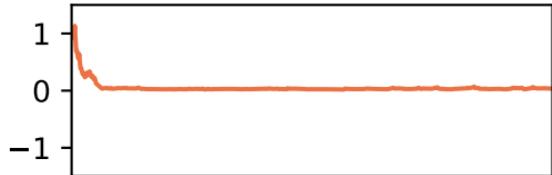
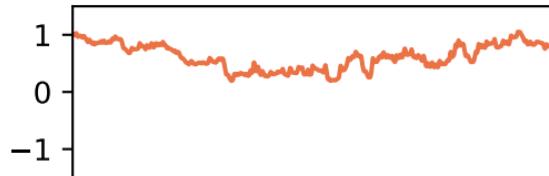
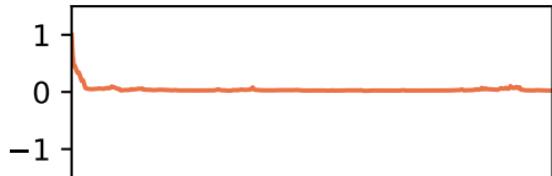
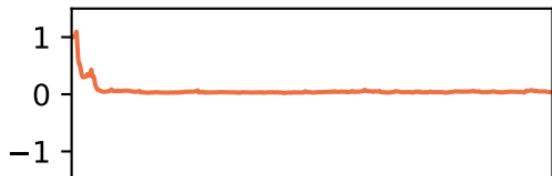
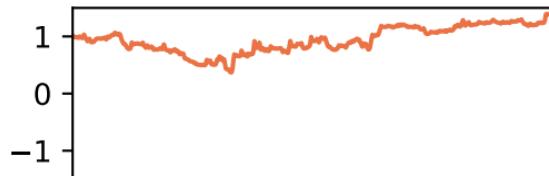
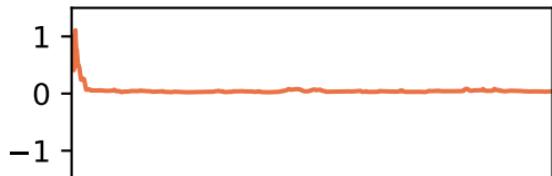


Estimated Control Authority

Positive Re.

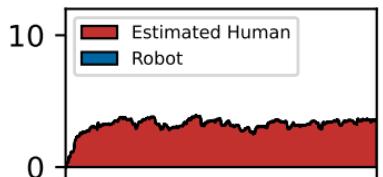
Negative Re.



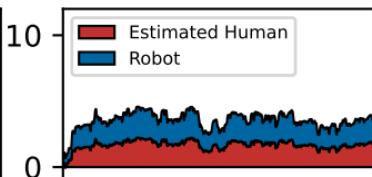
Time (s)

Time (s)

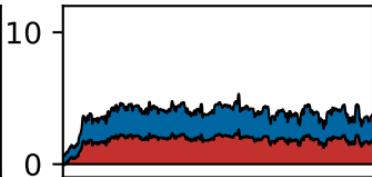
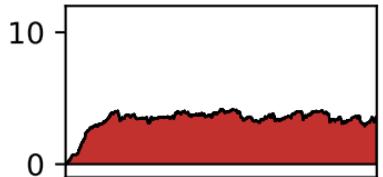
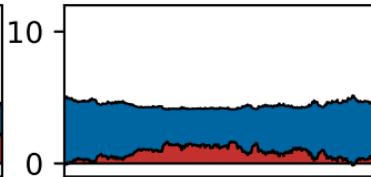
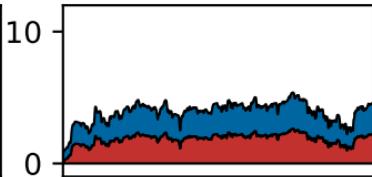
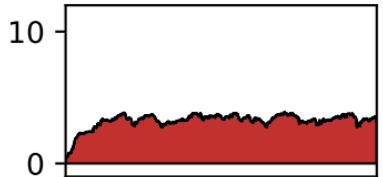
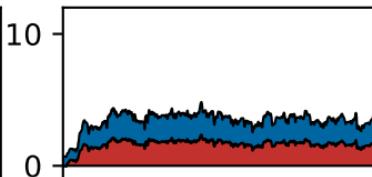
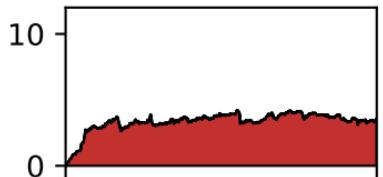
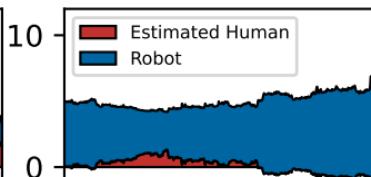
Manual
Control



Gains
Positive Re.



Negative Re.

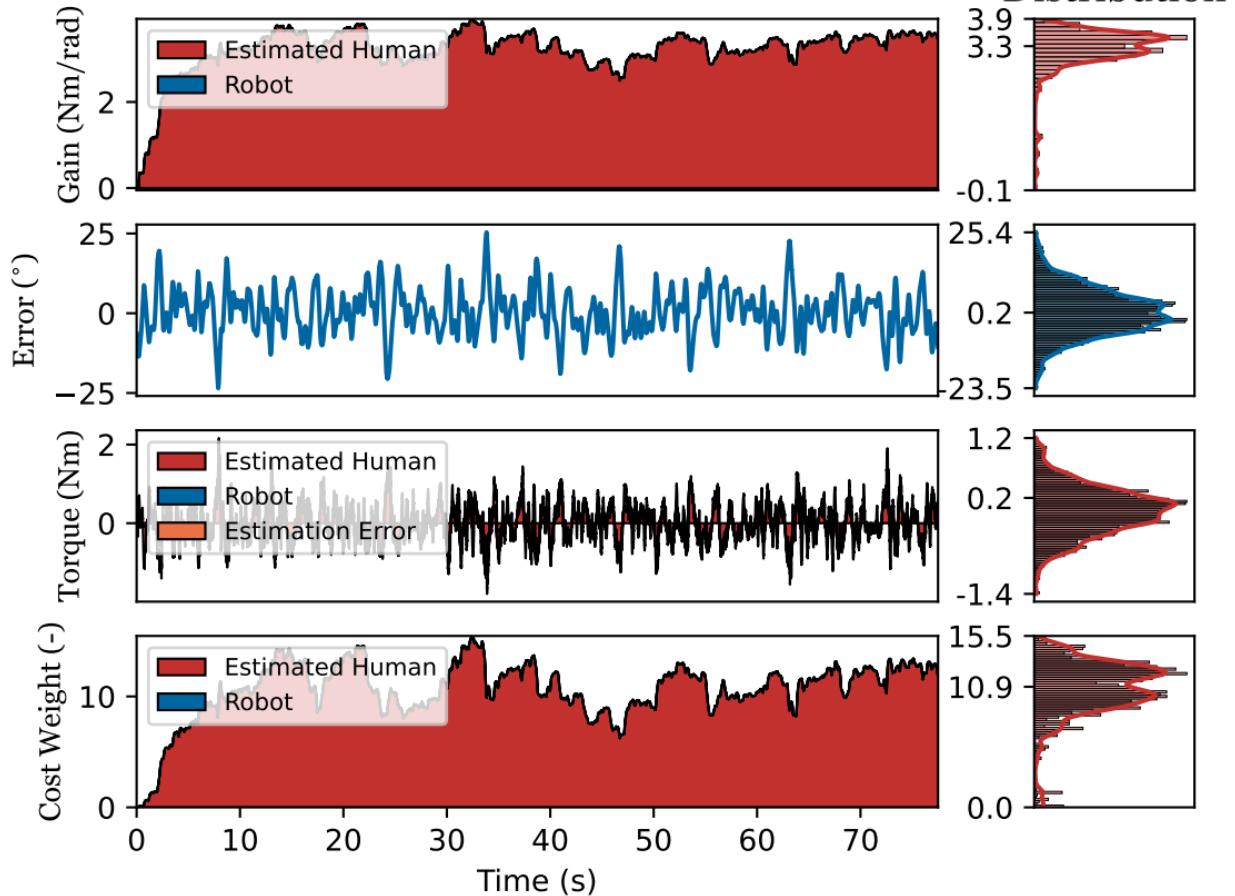


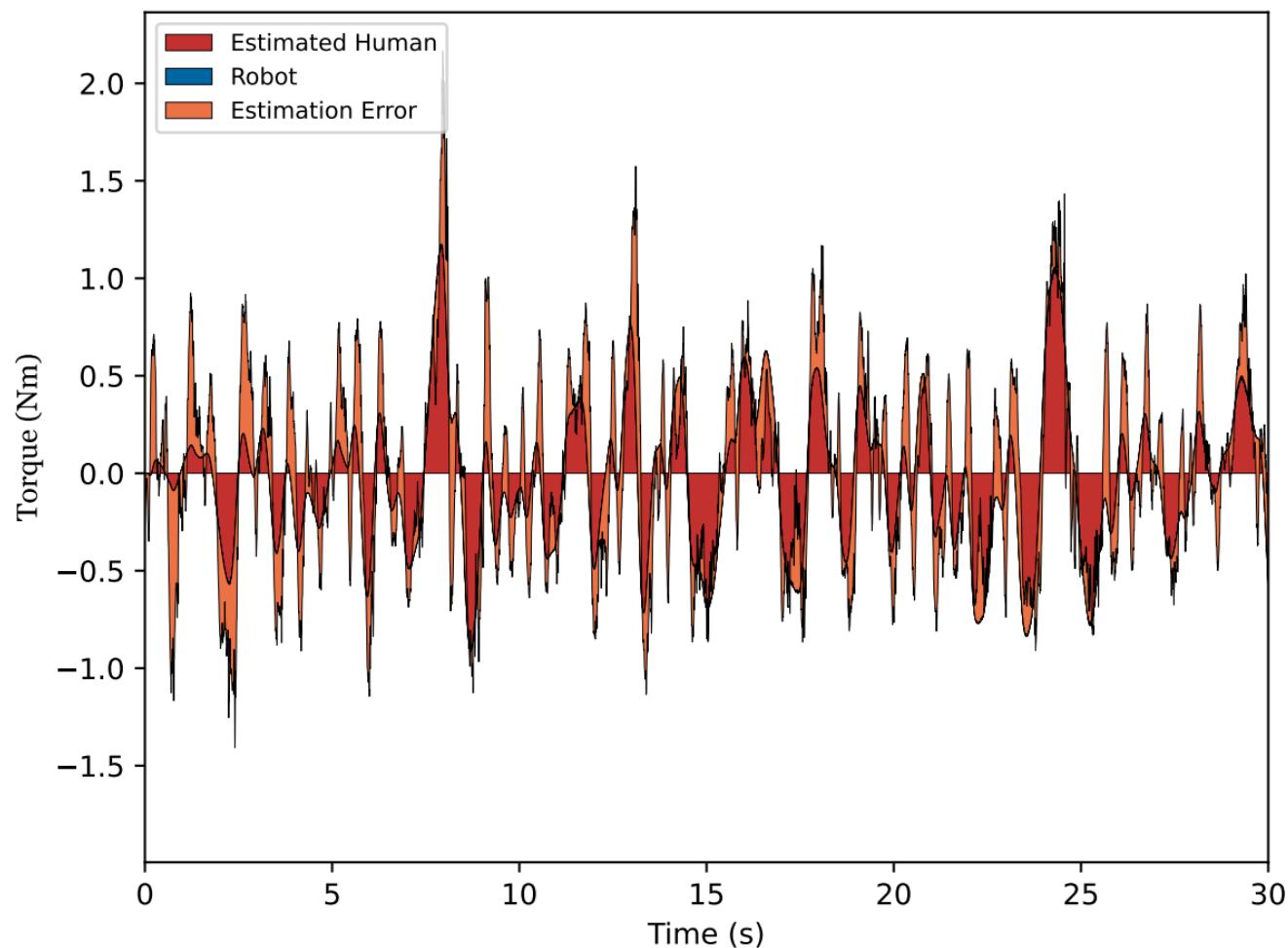
Time (s)

Time (s)

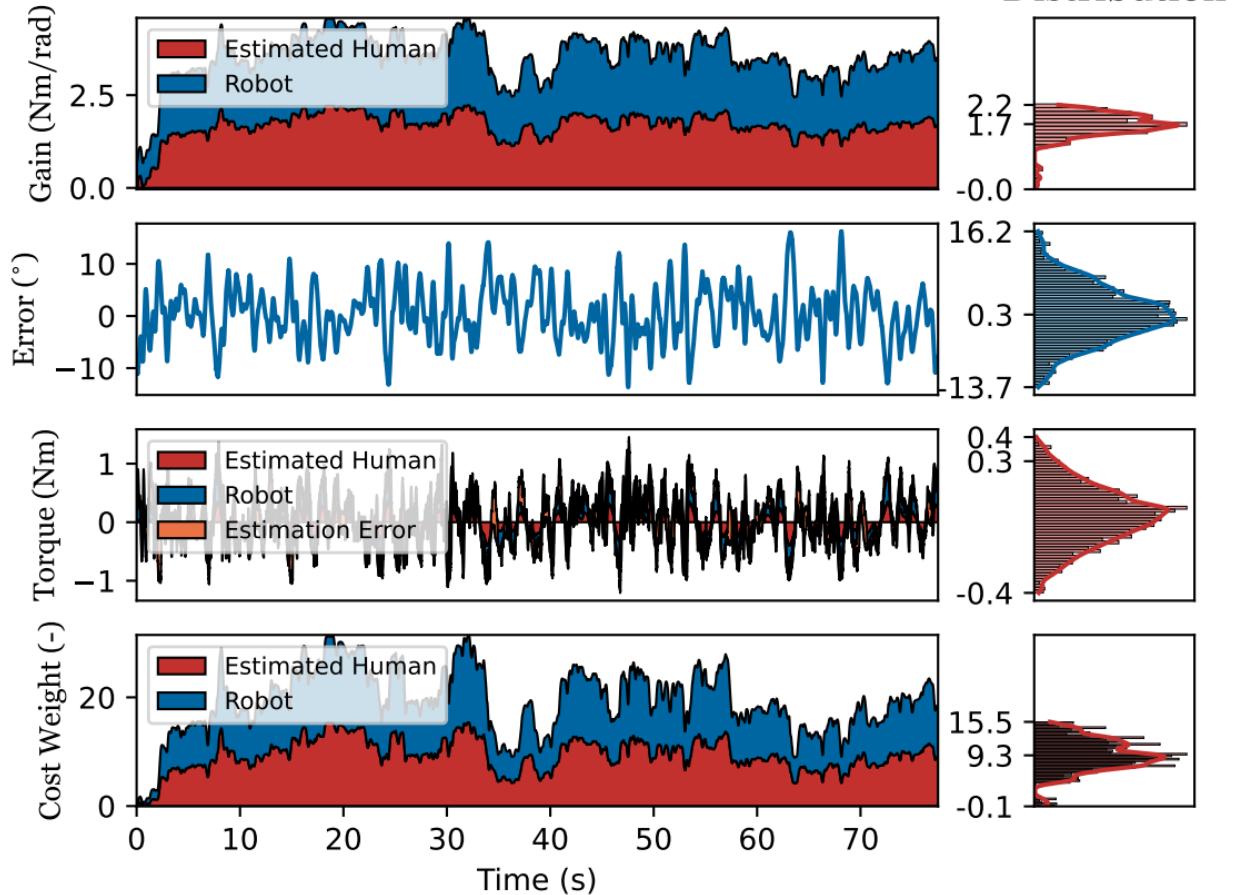
Time (s)

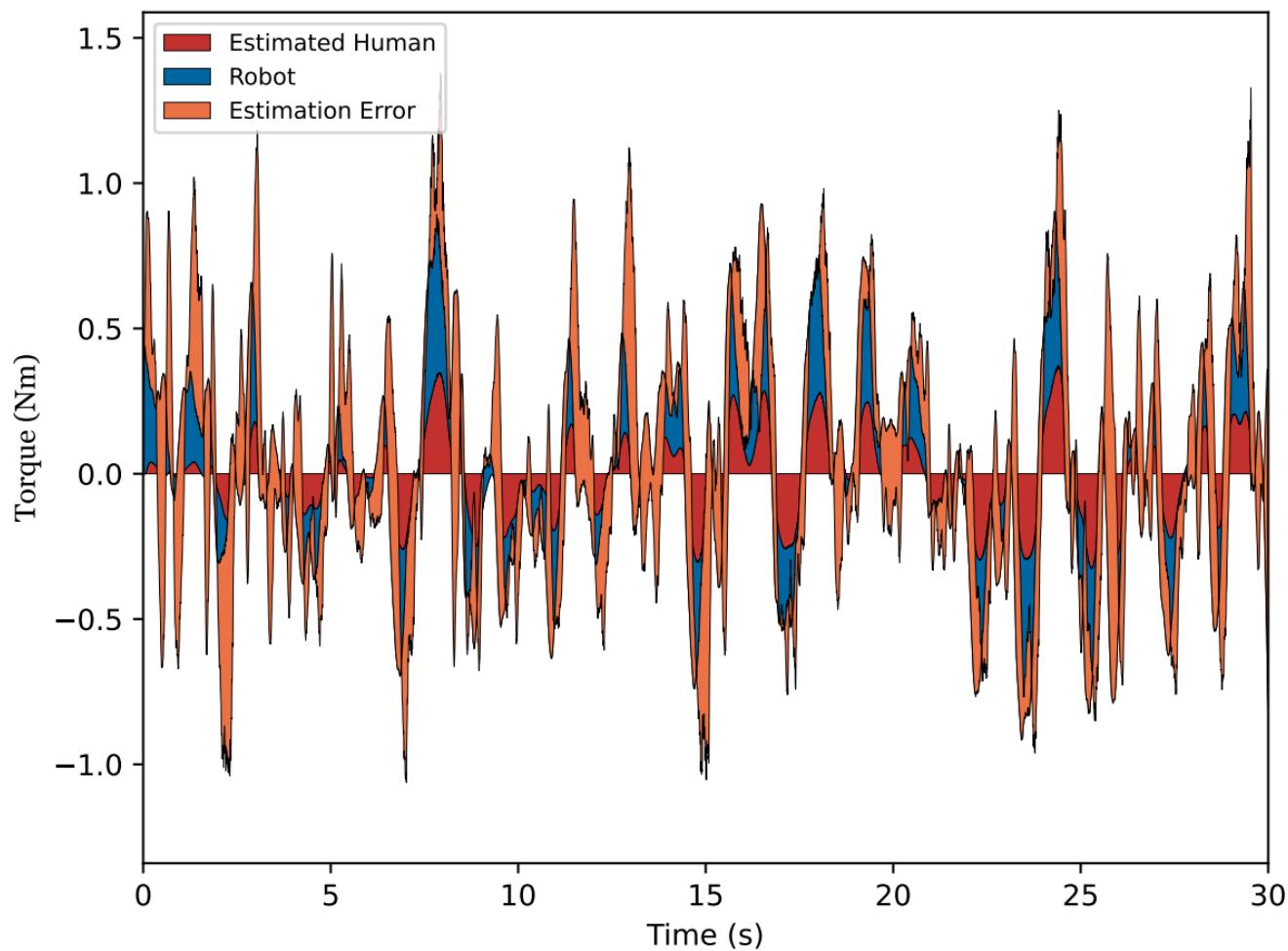
Manual Control



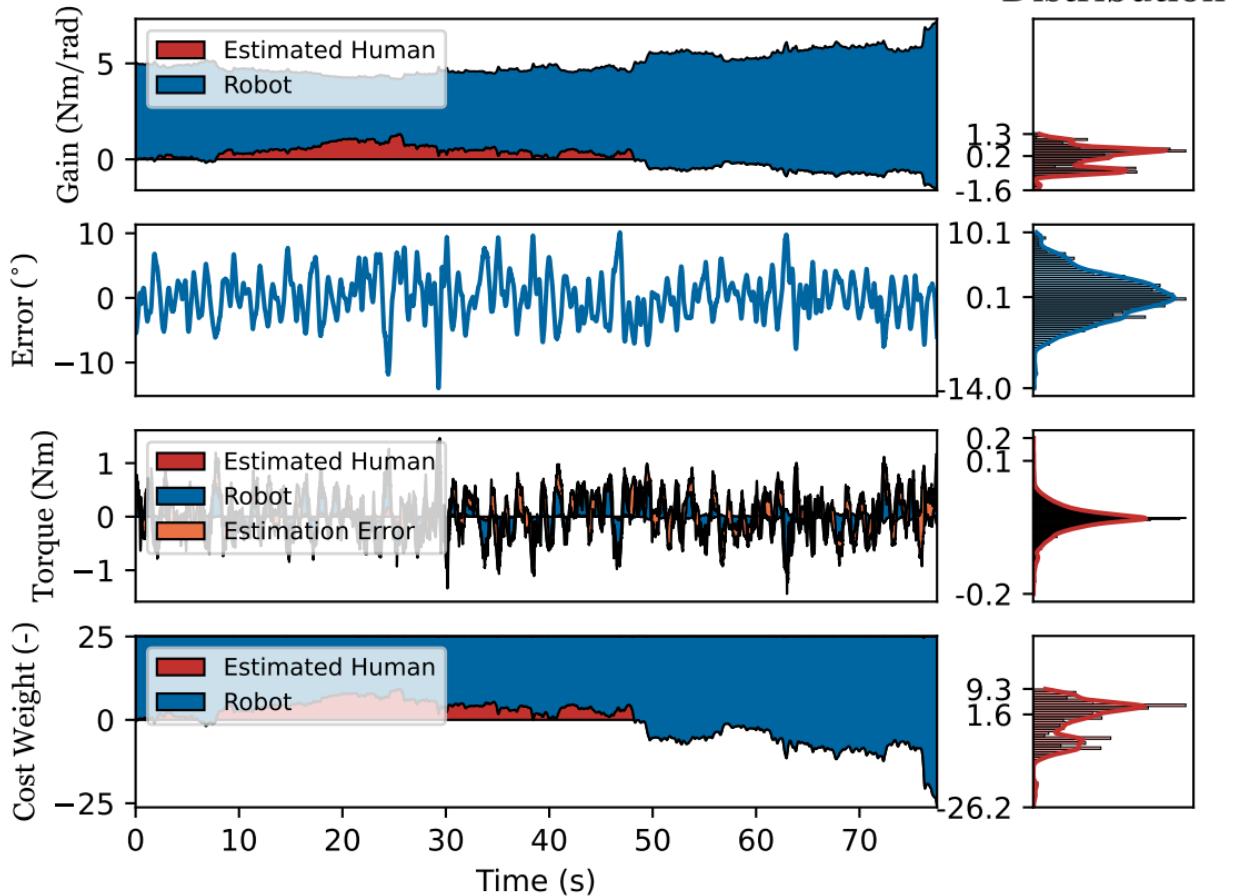


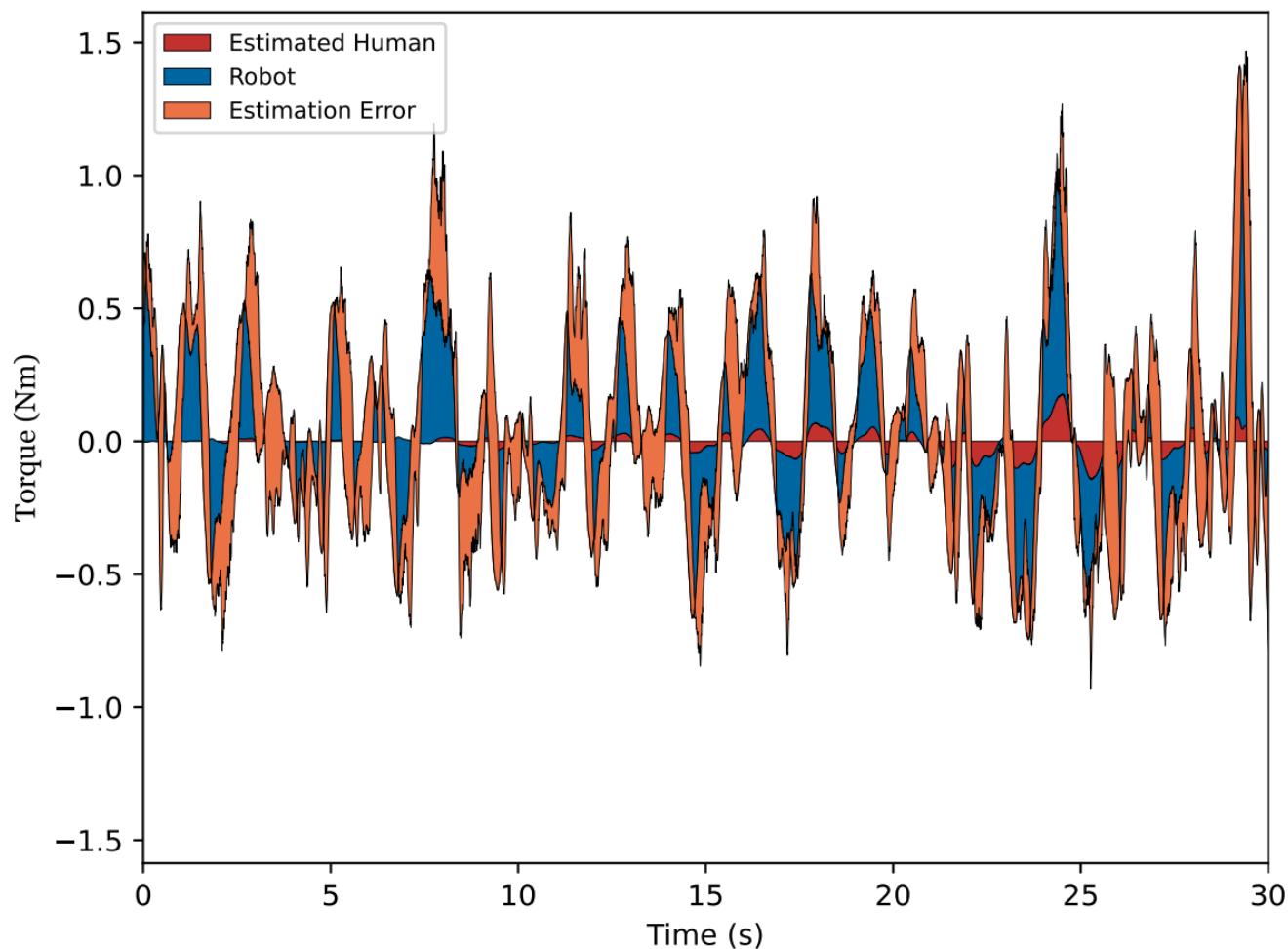
Positive Reinforcement



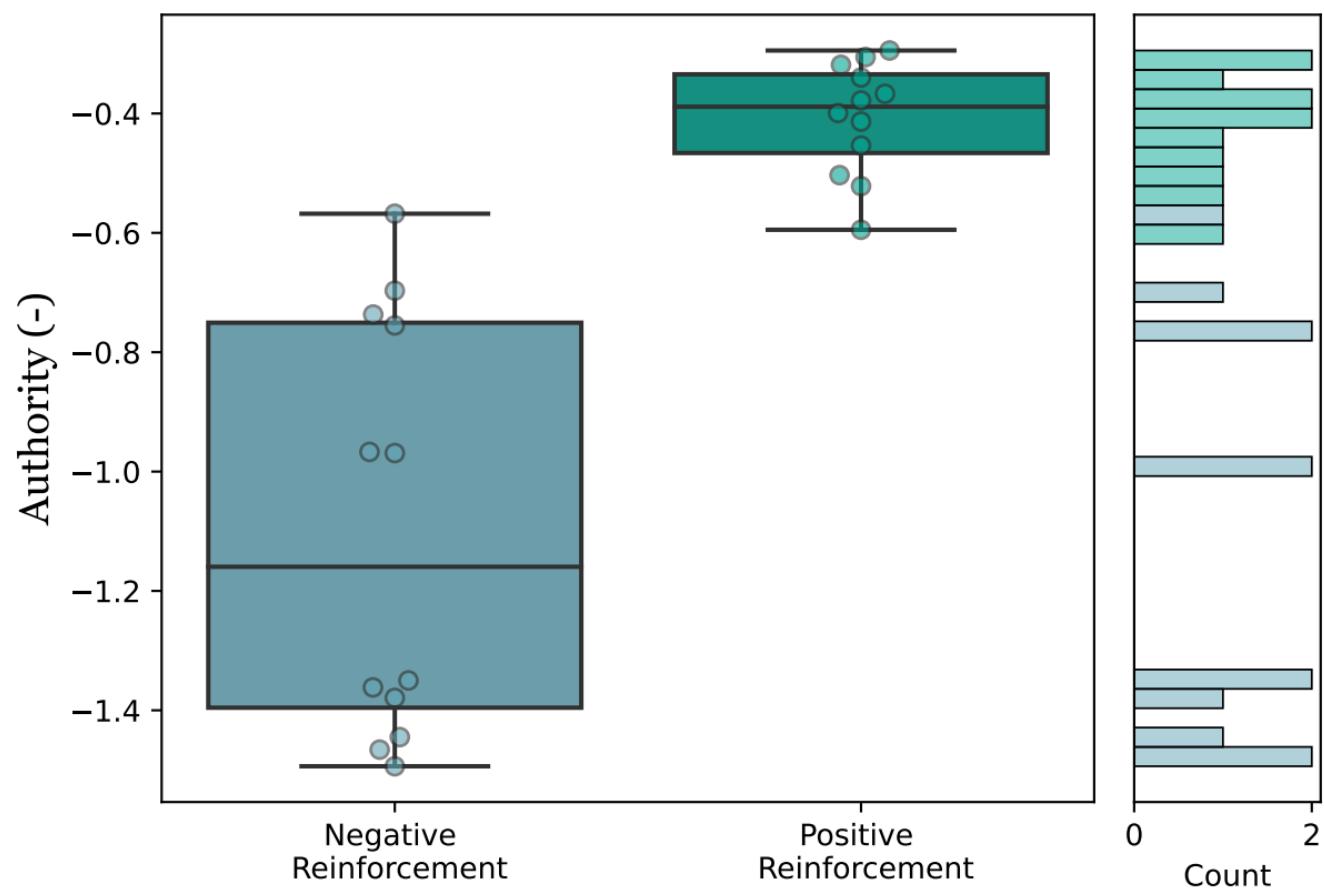


Negative Reinforcement

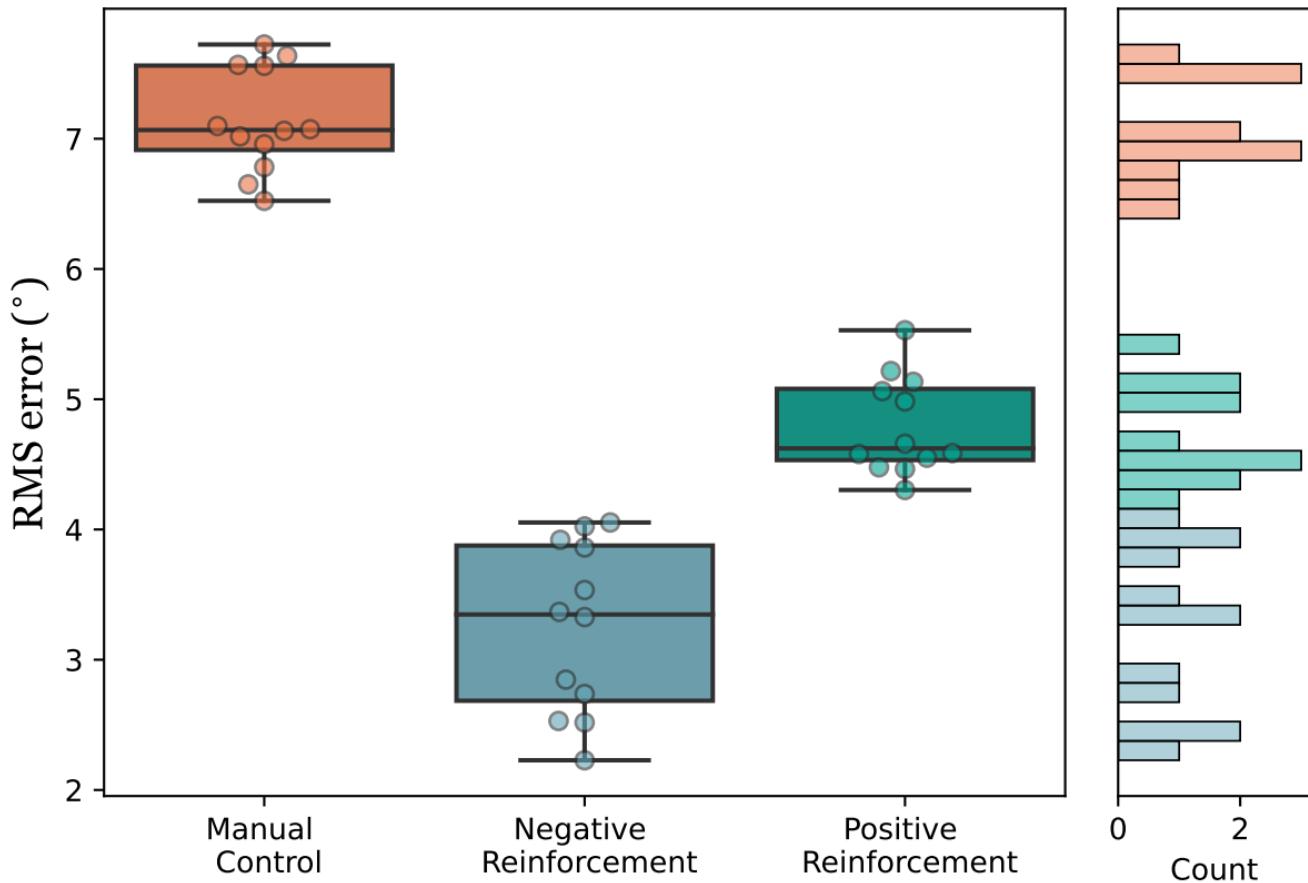




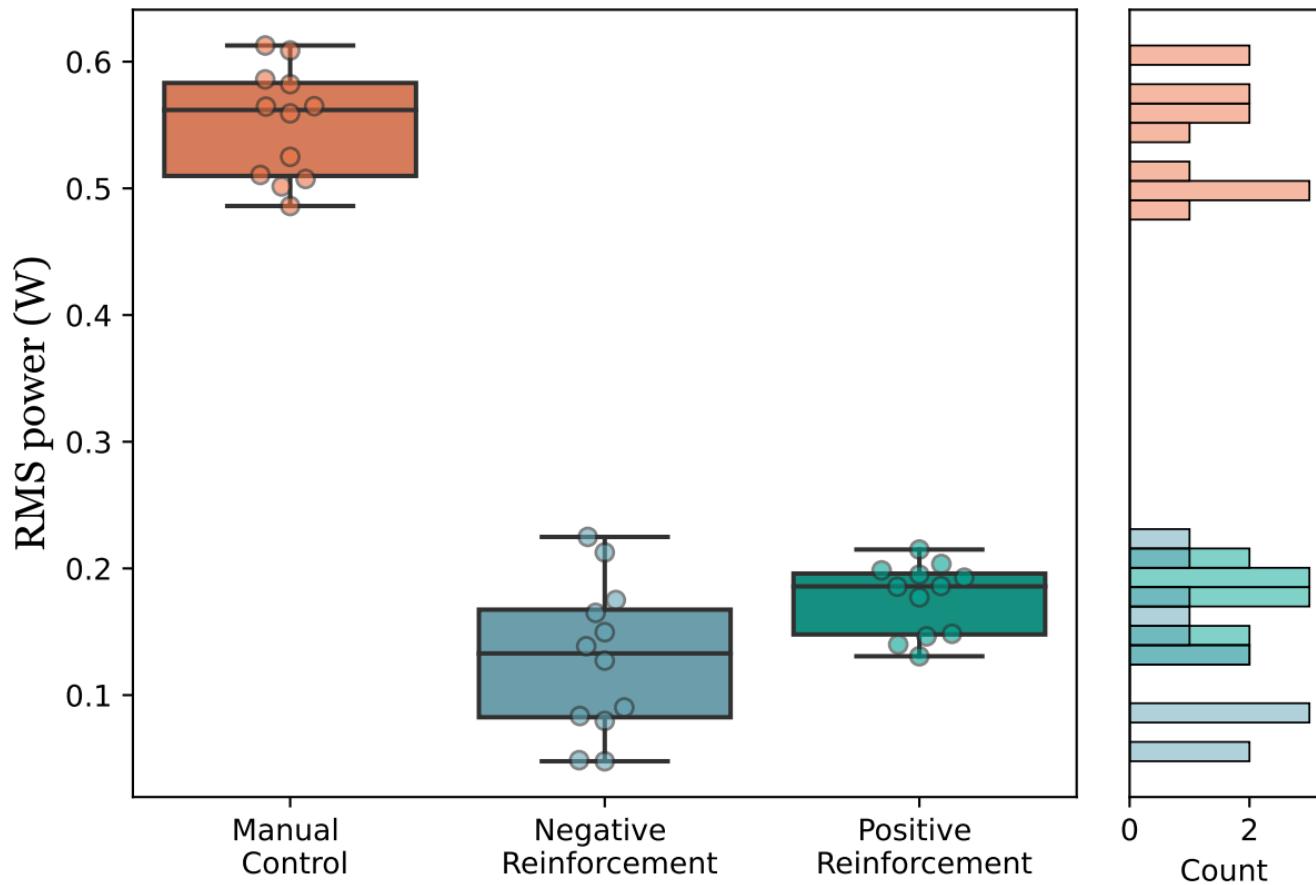
Control Authority



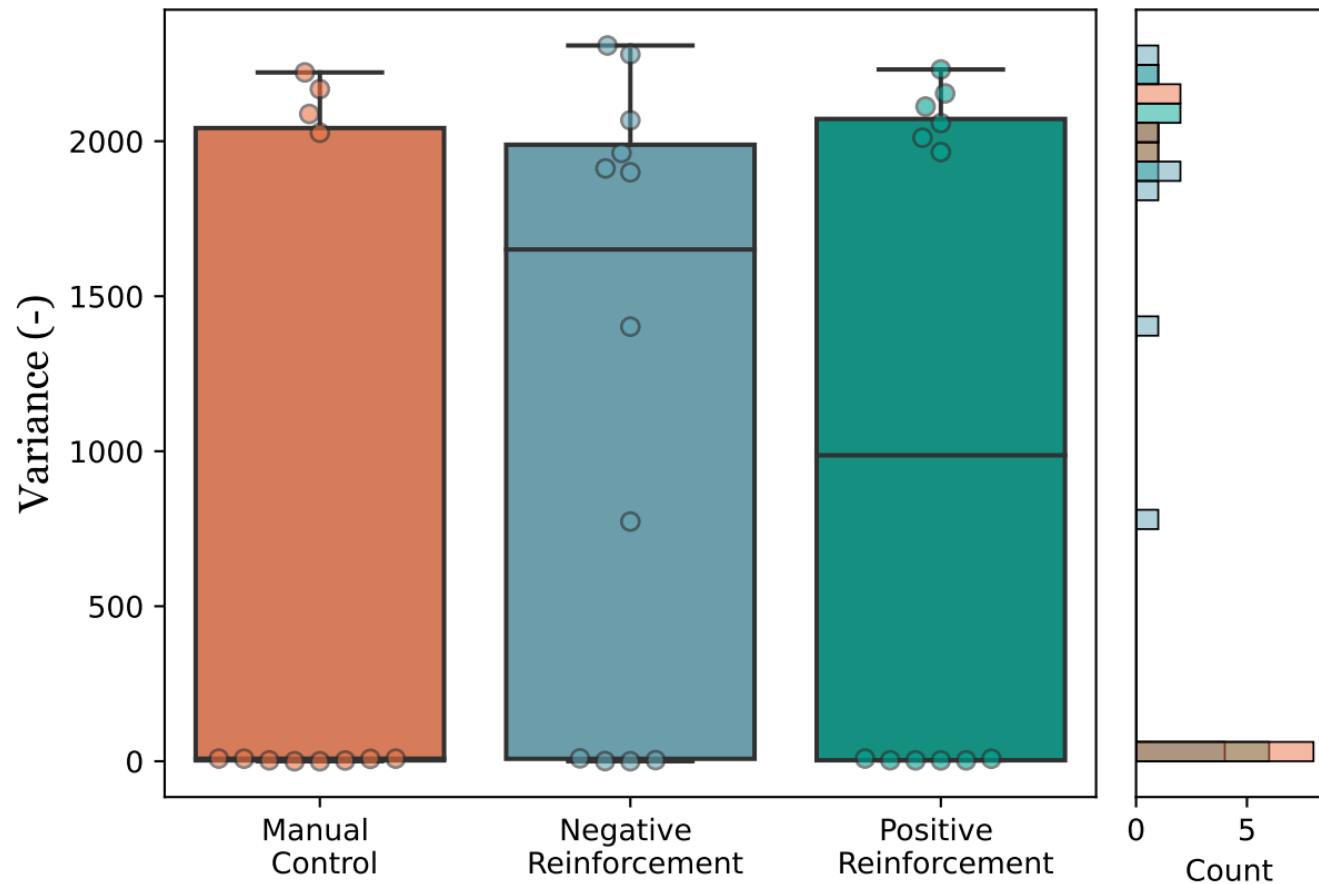
Steering Angle Error



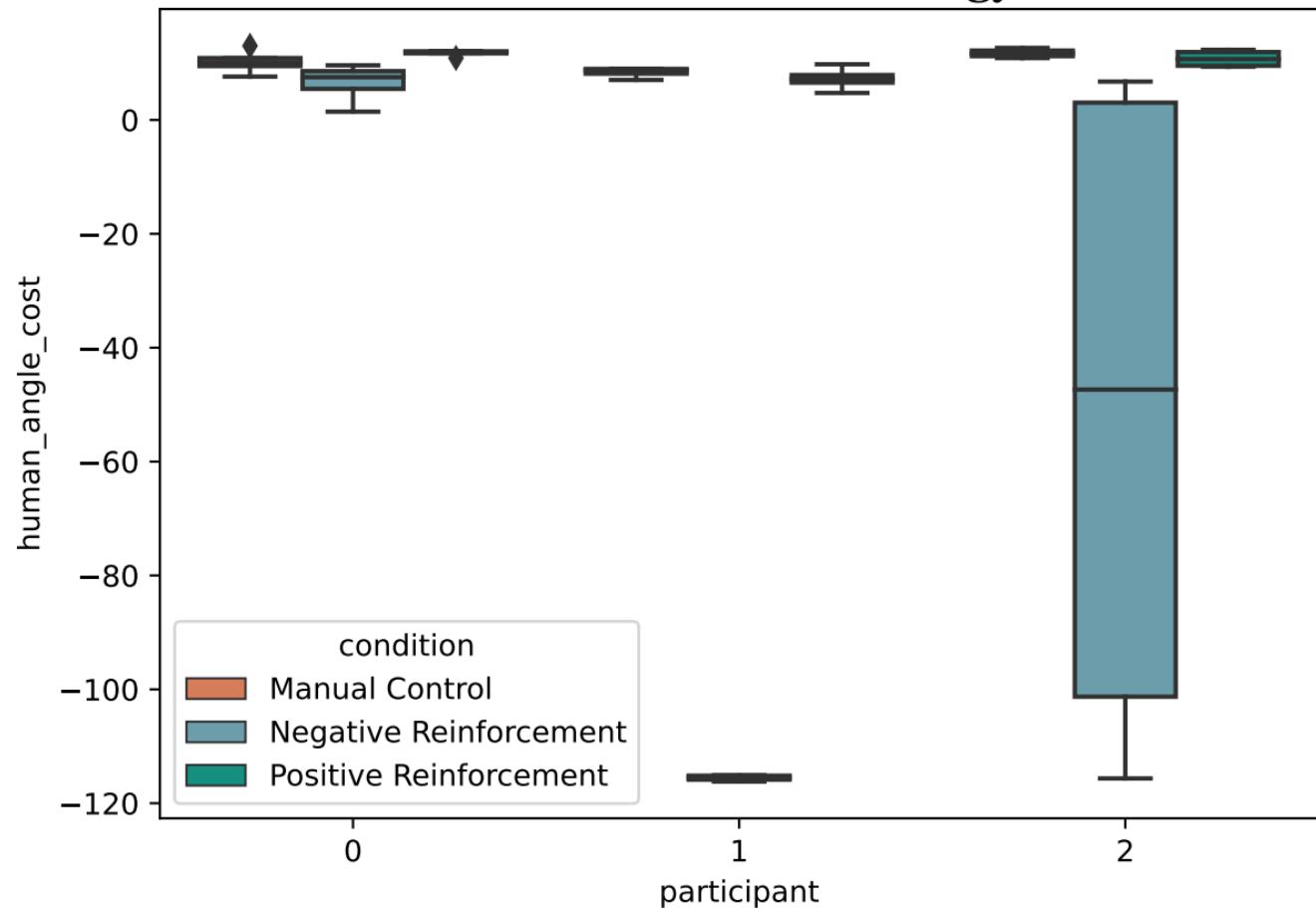
Human Input Power



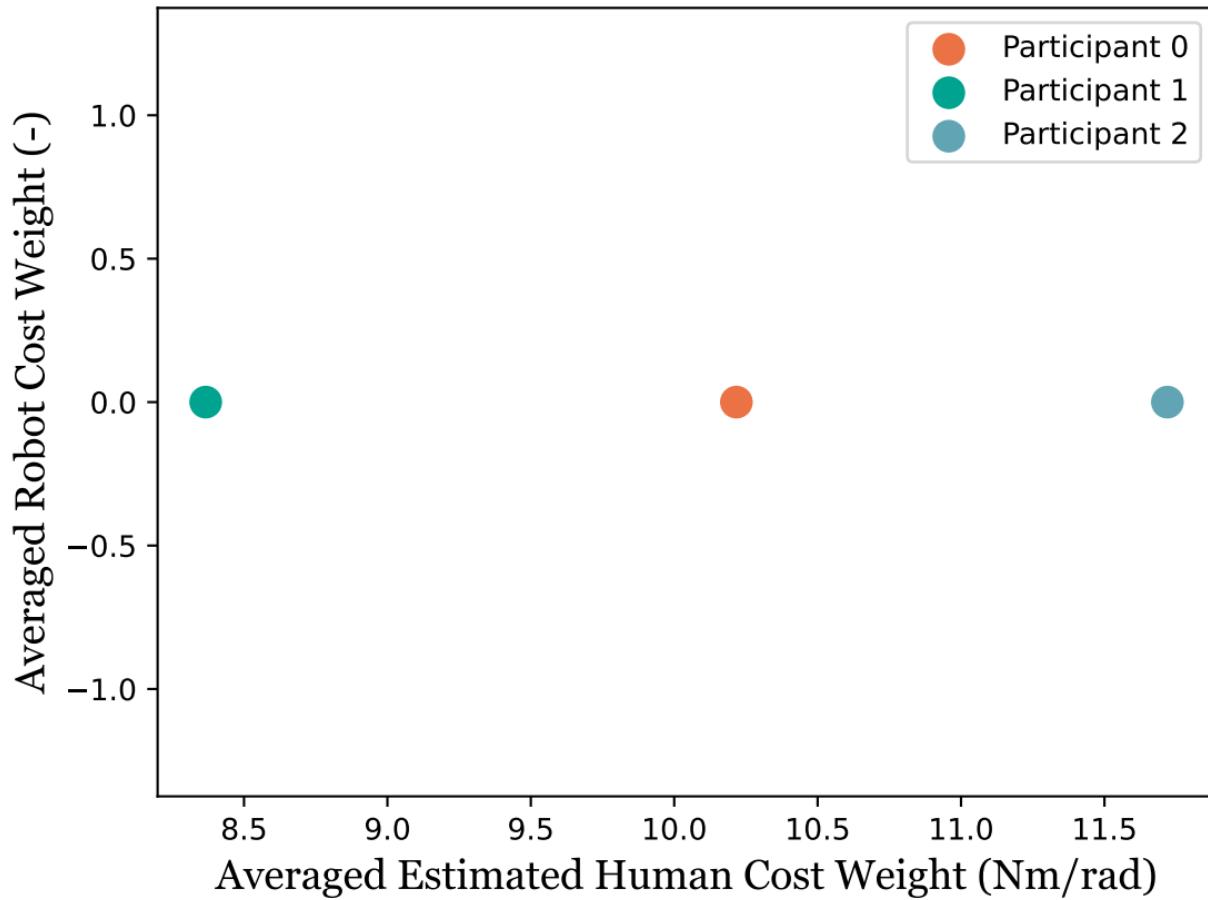
Cost function variability



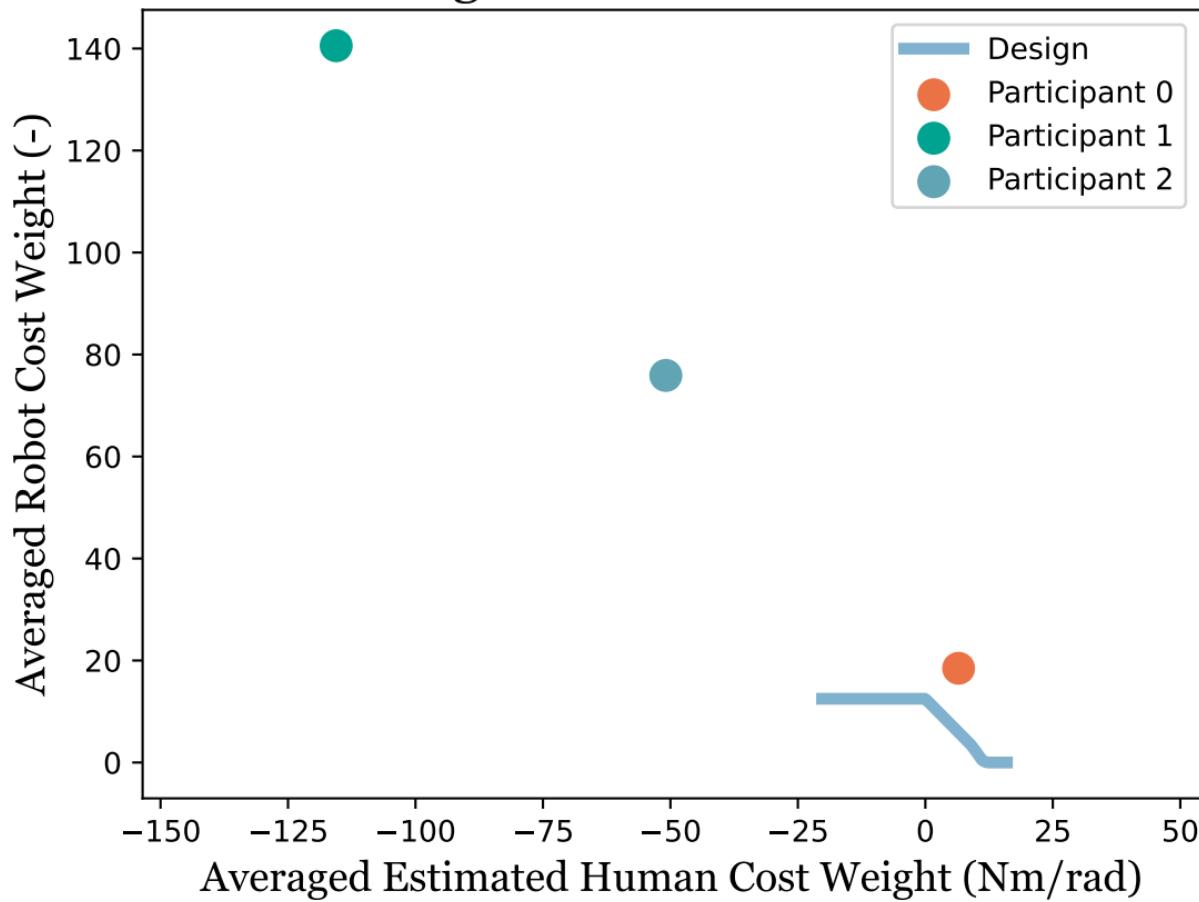
Human control strategy



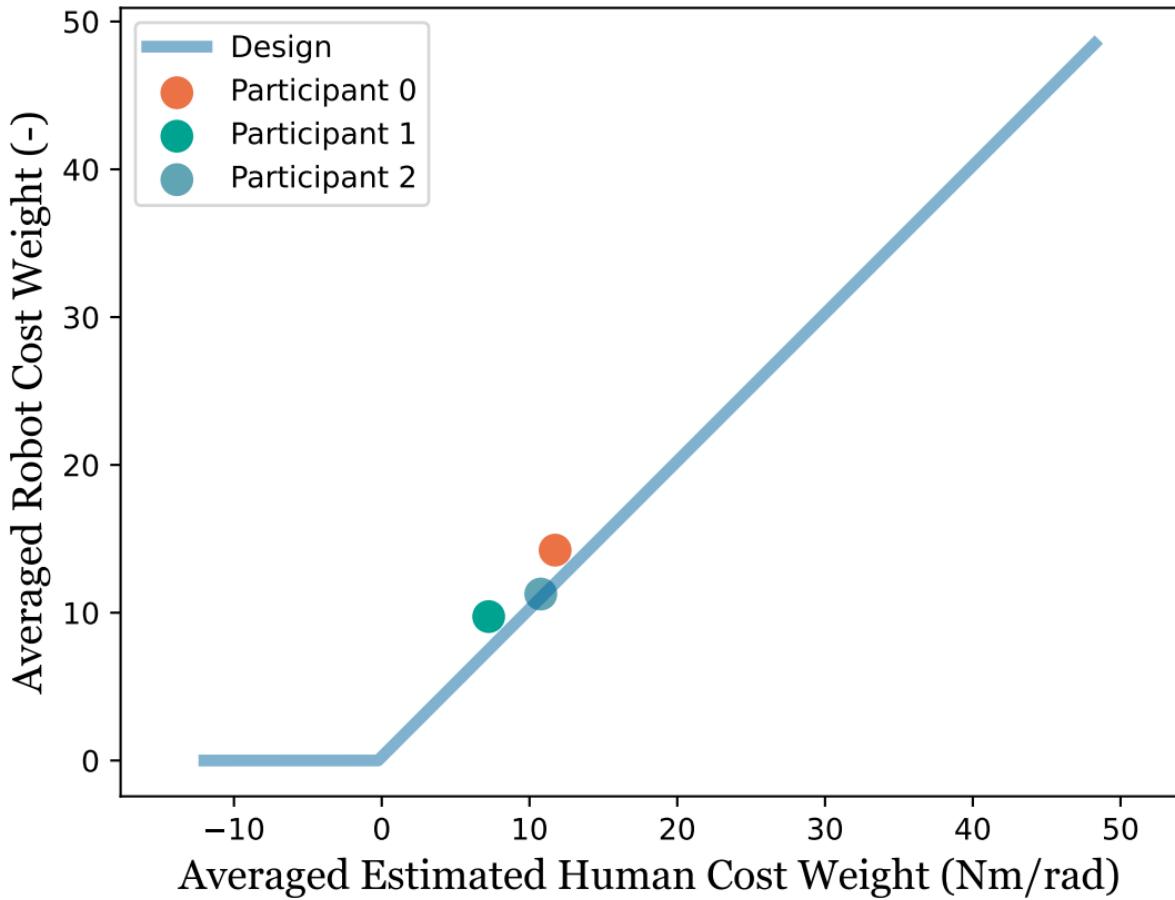
Manual Control



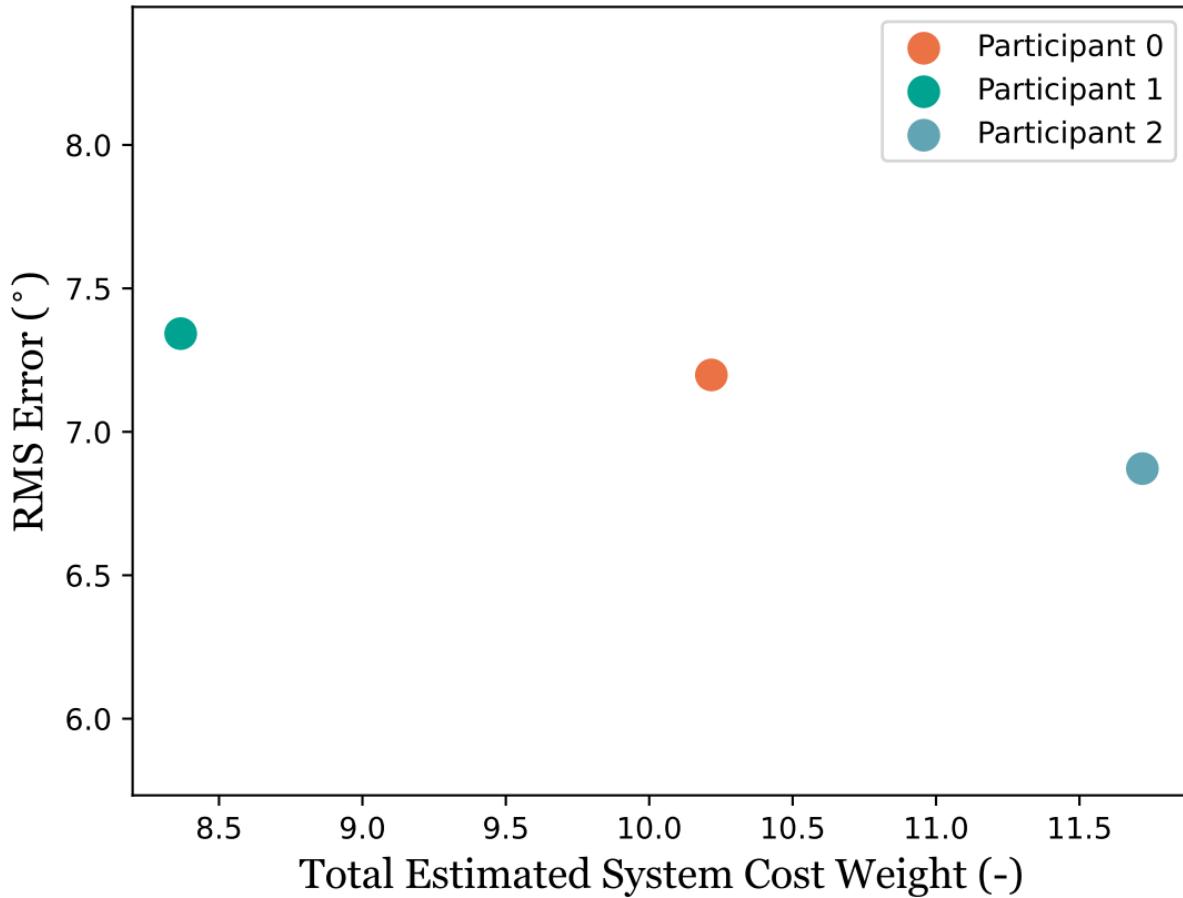
Negative Reinforcement



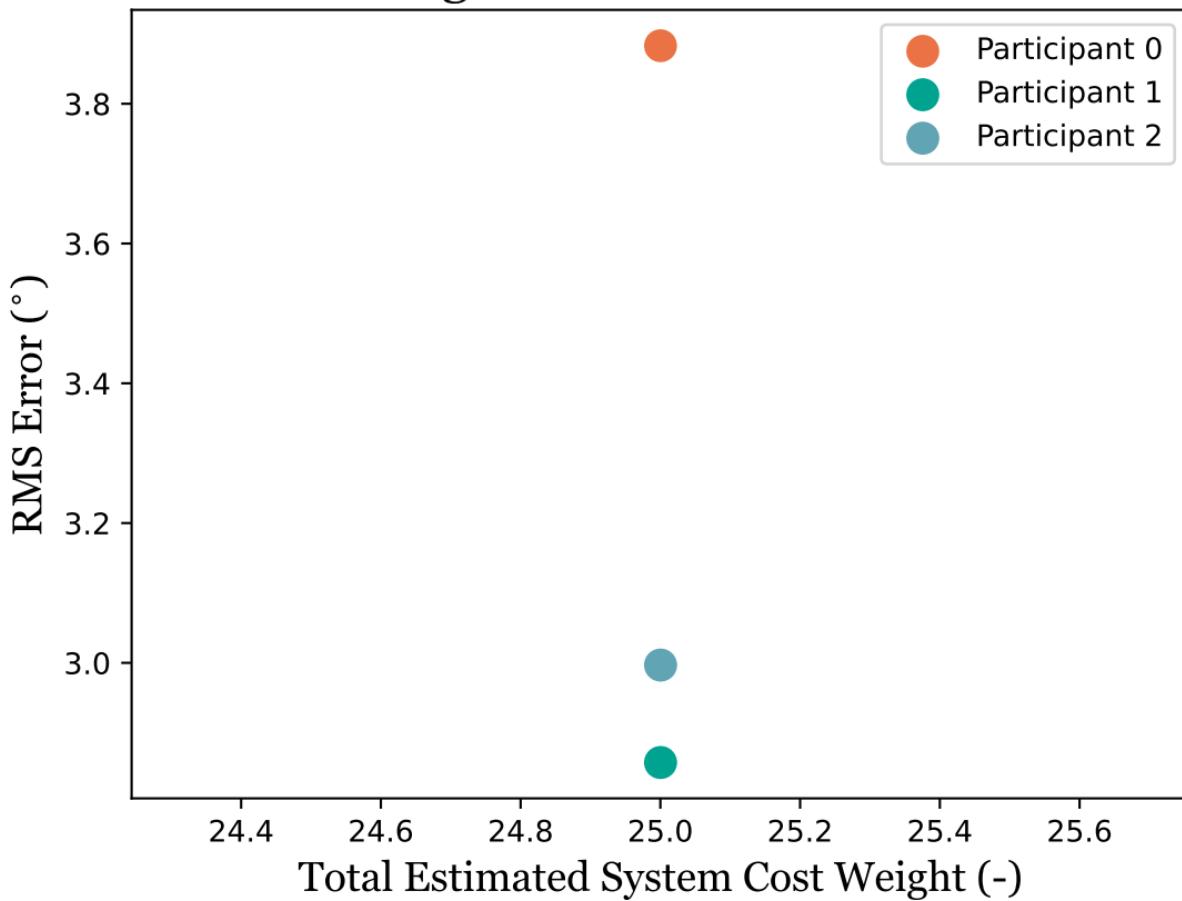
Positive Reinforcement



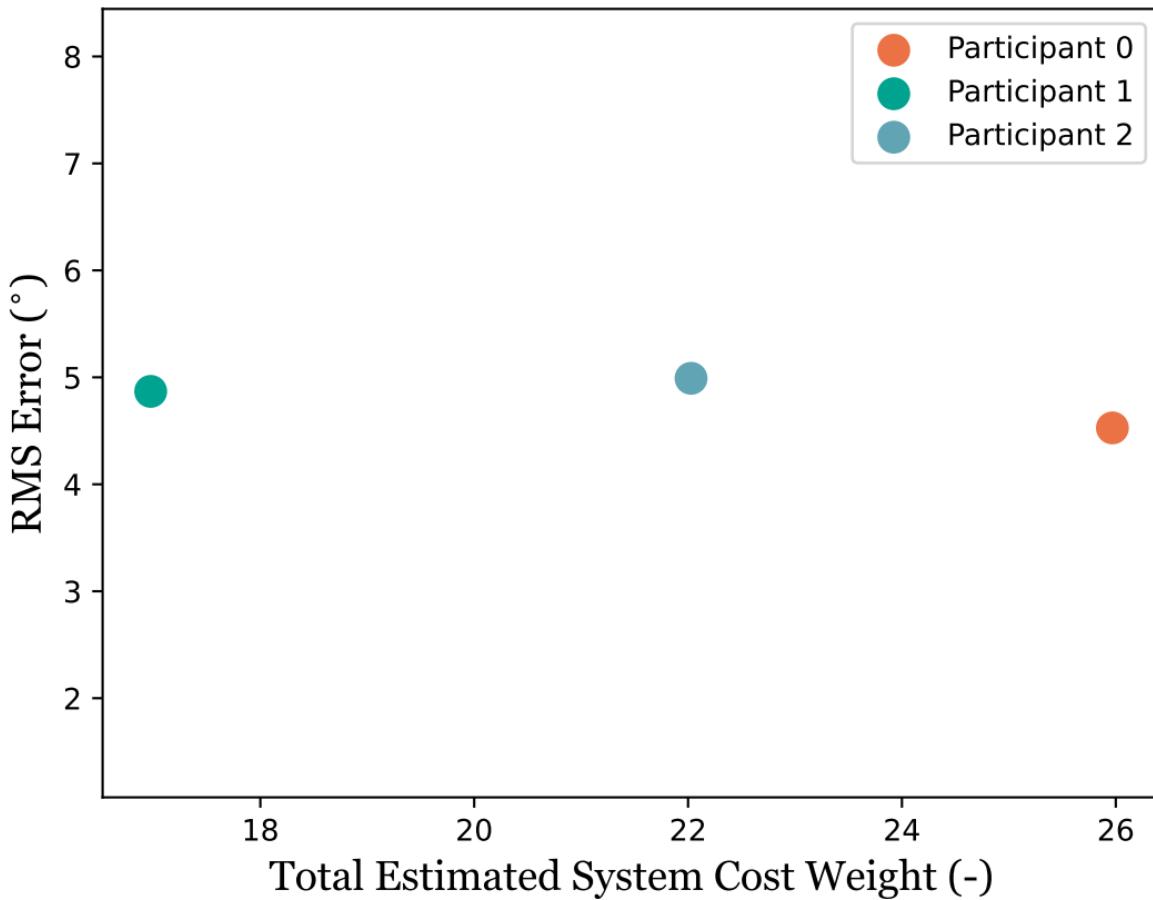
Manual Control



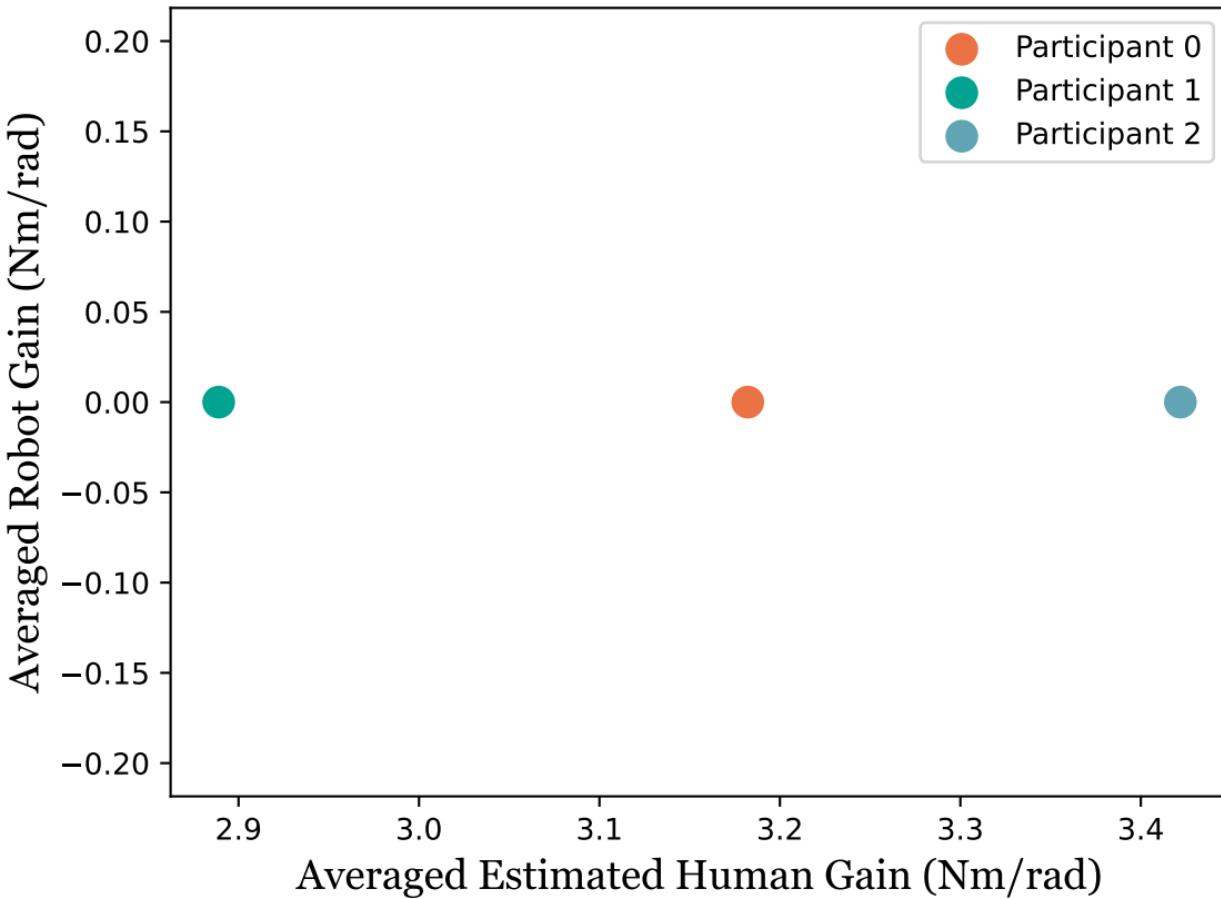
Negative Reinforcement



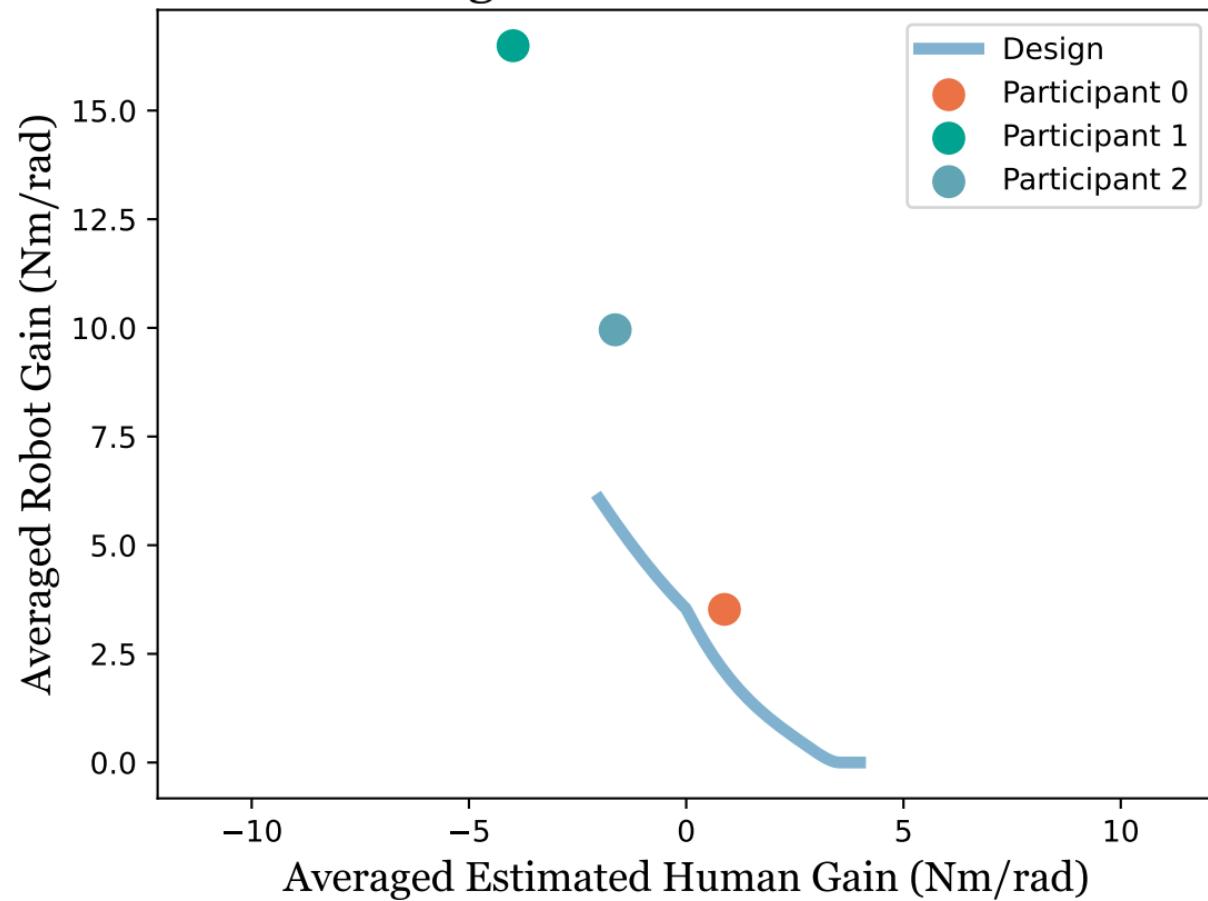
Positive Reinforcement



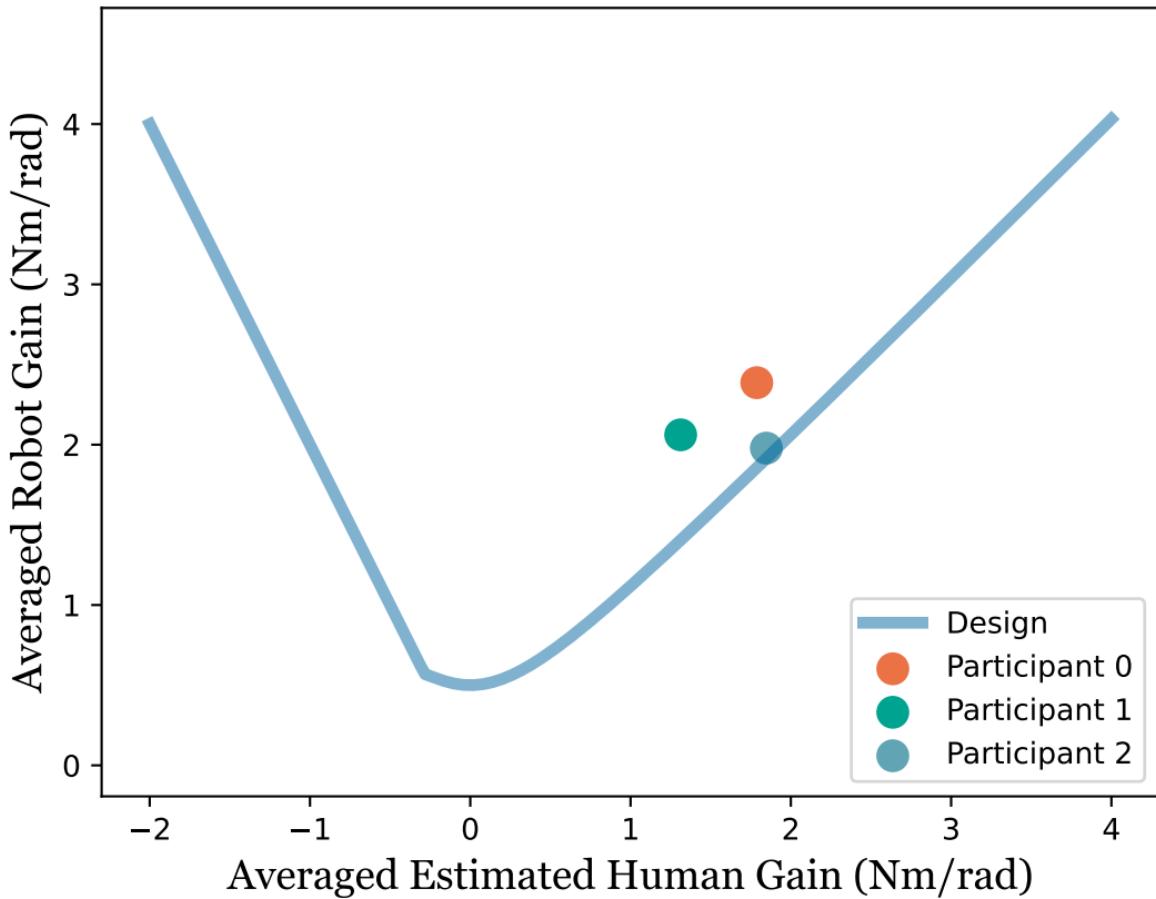
Manual Control



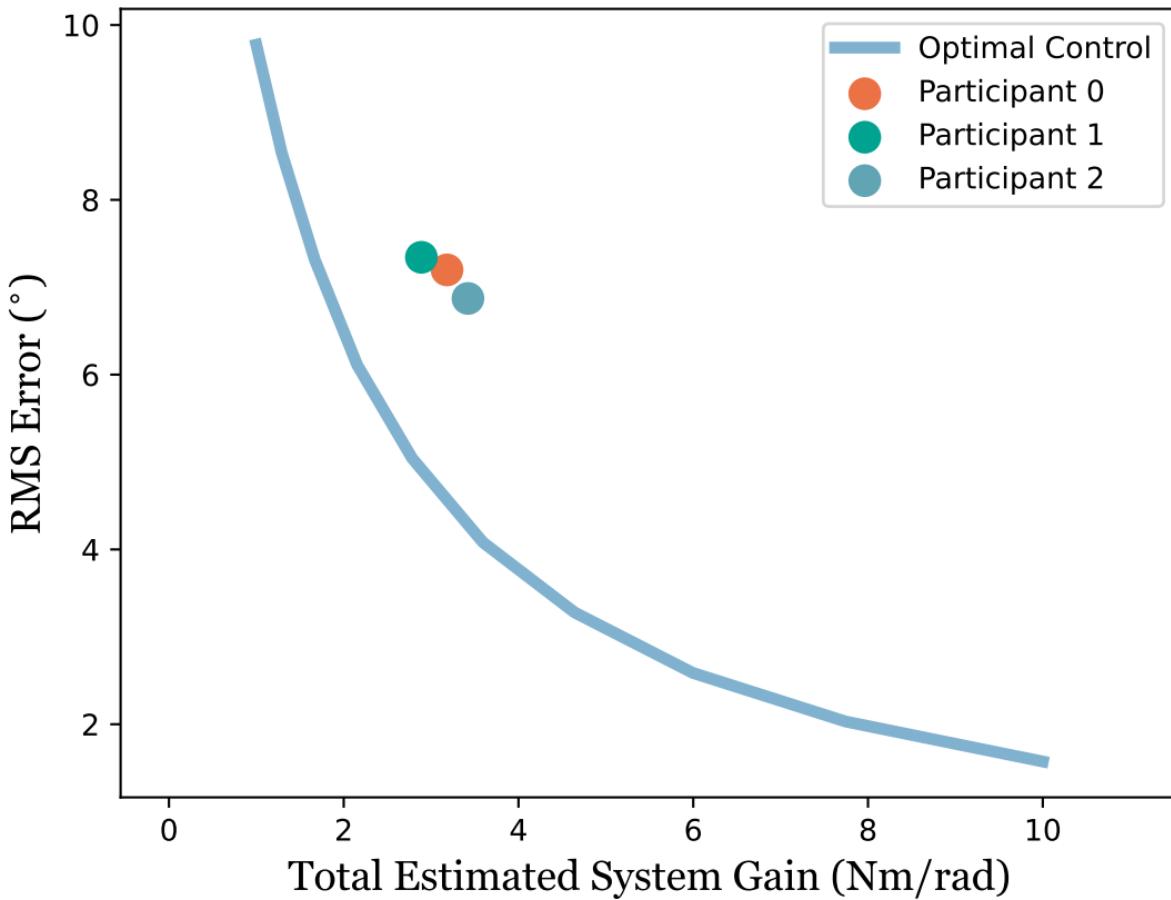
Negative Reinforcement



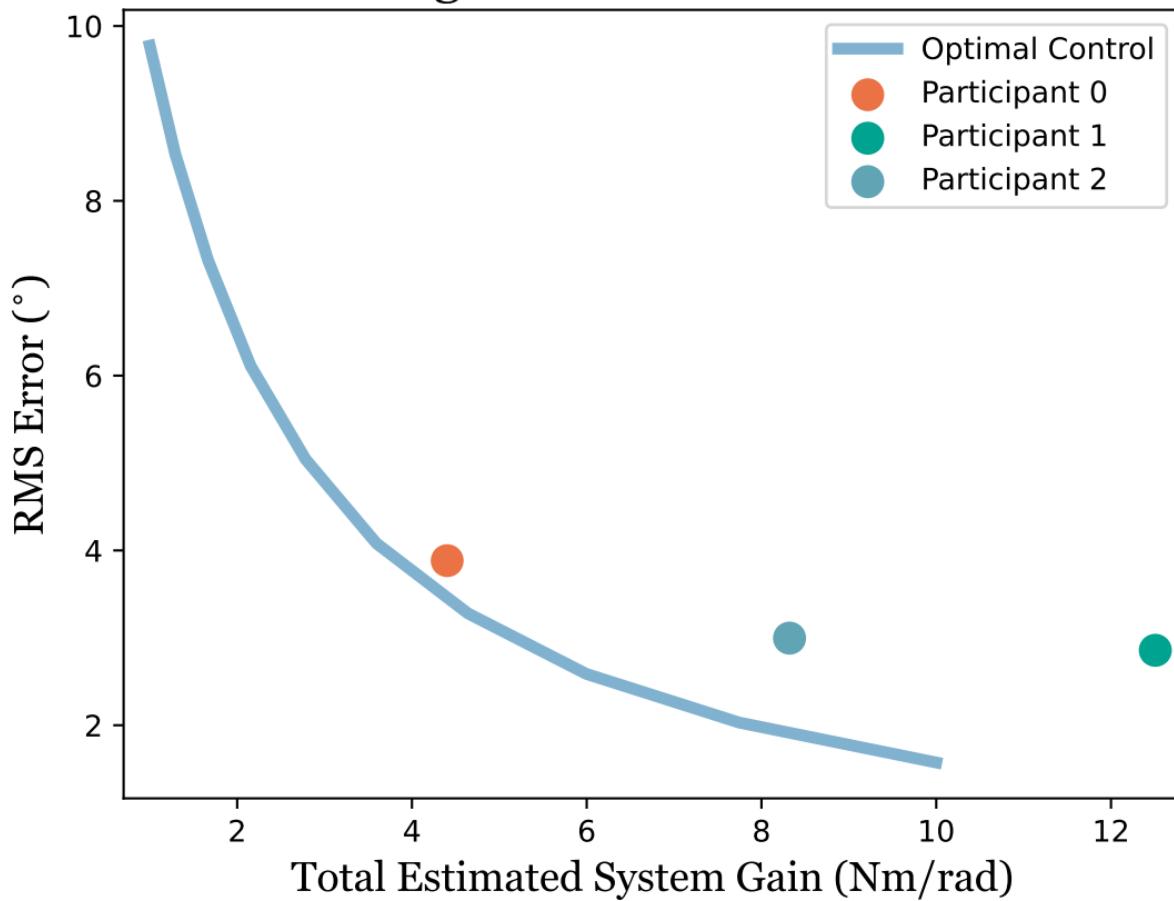
Positive Reinforcement



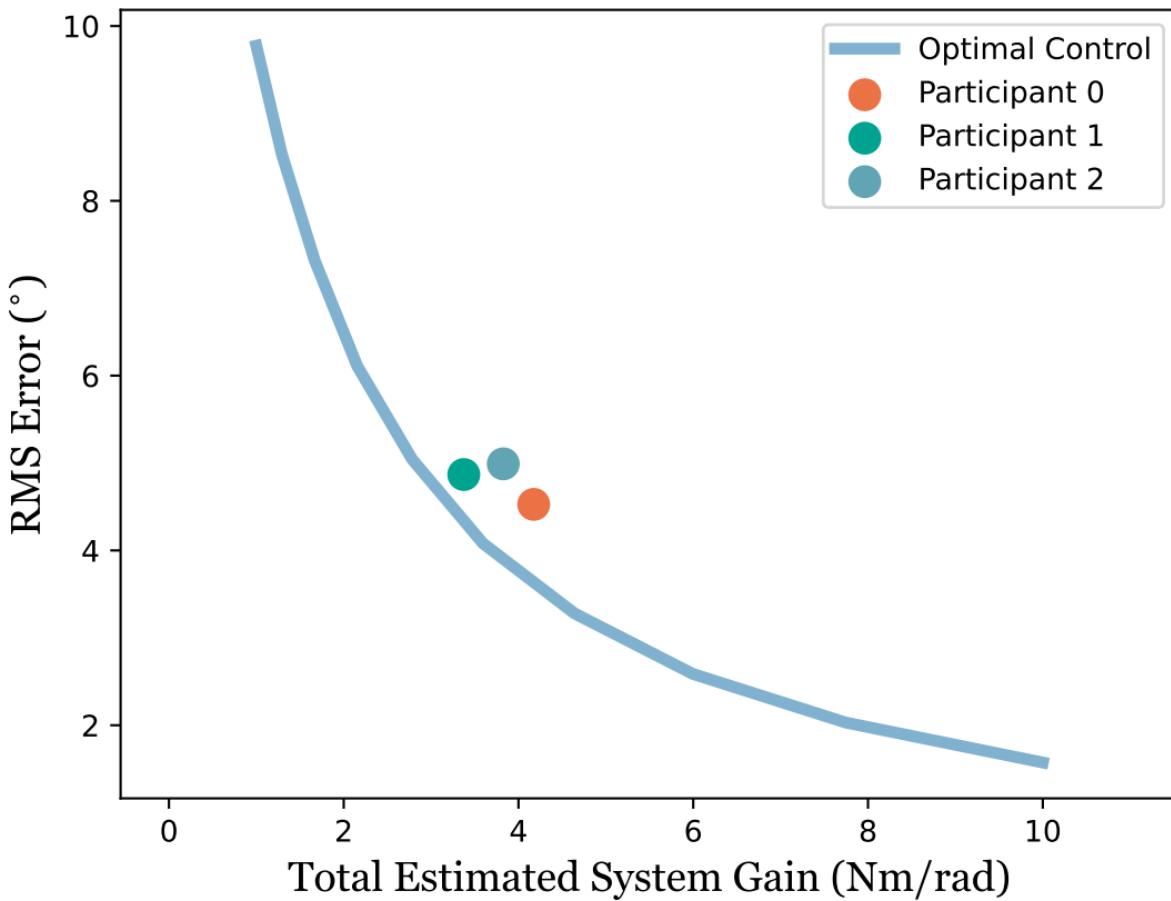
Manual Control



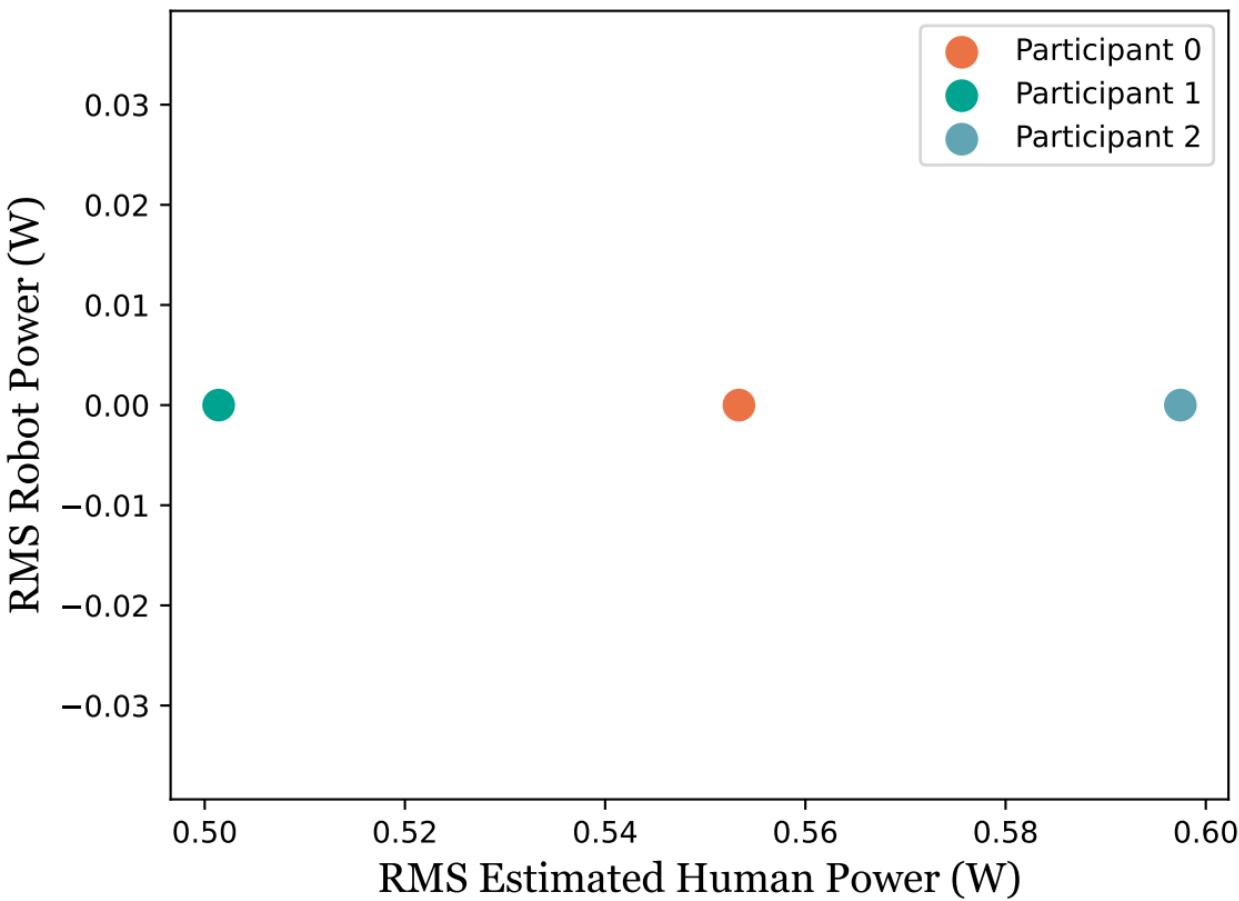
Negative Reinforcement



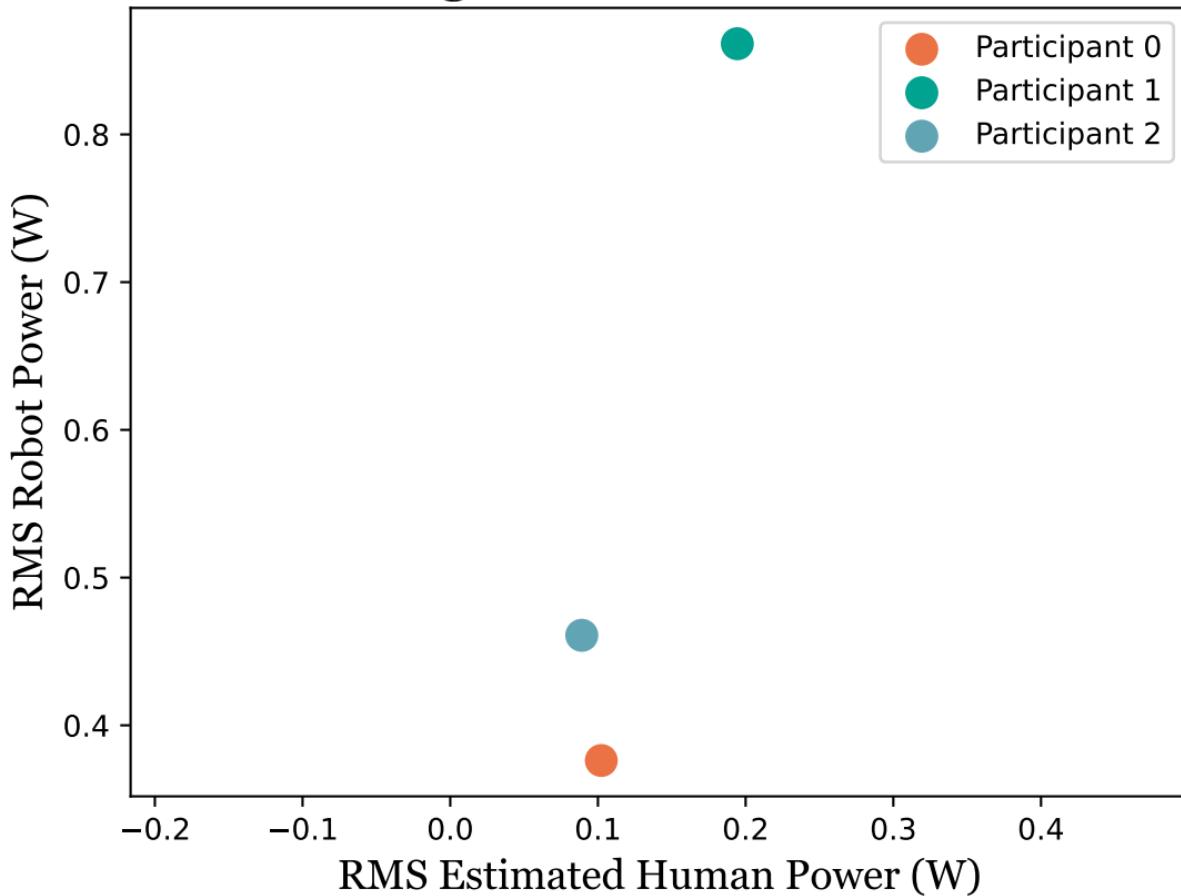
Positive Reinforcement



Manual Control



Negative Reinforcement



Positive Reinforcement

