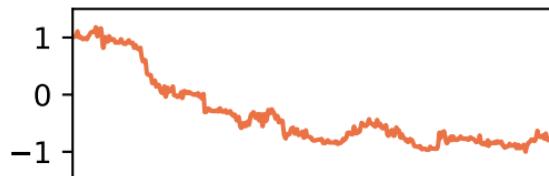
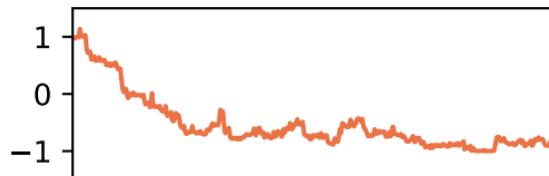
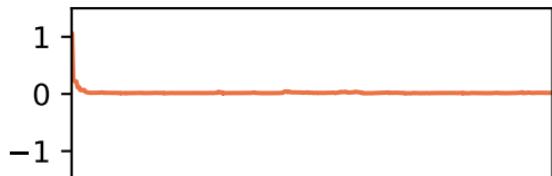
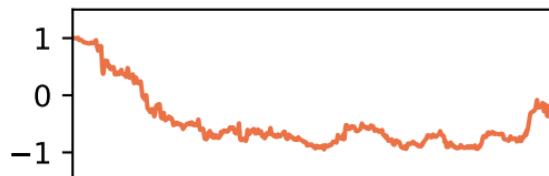
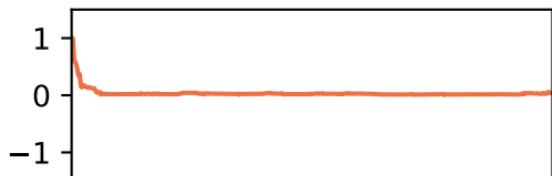
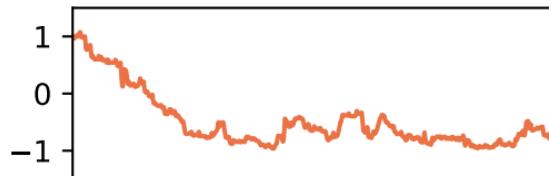


Estimated Control Share

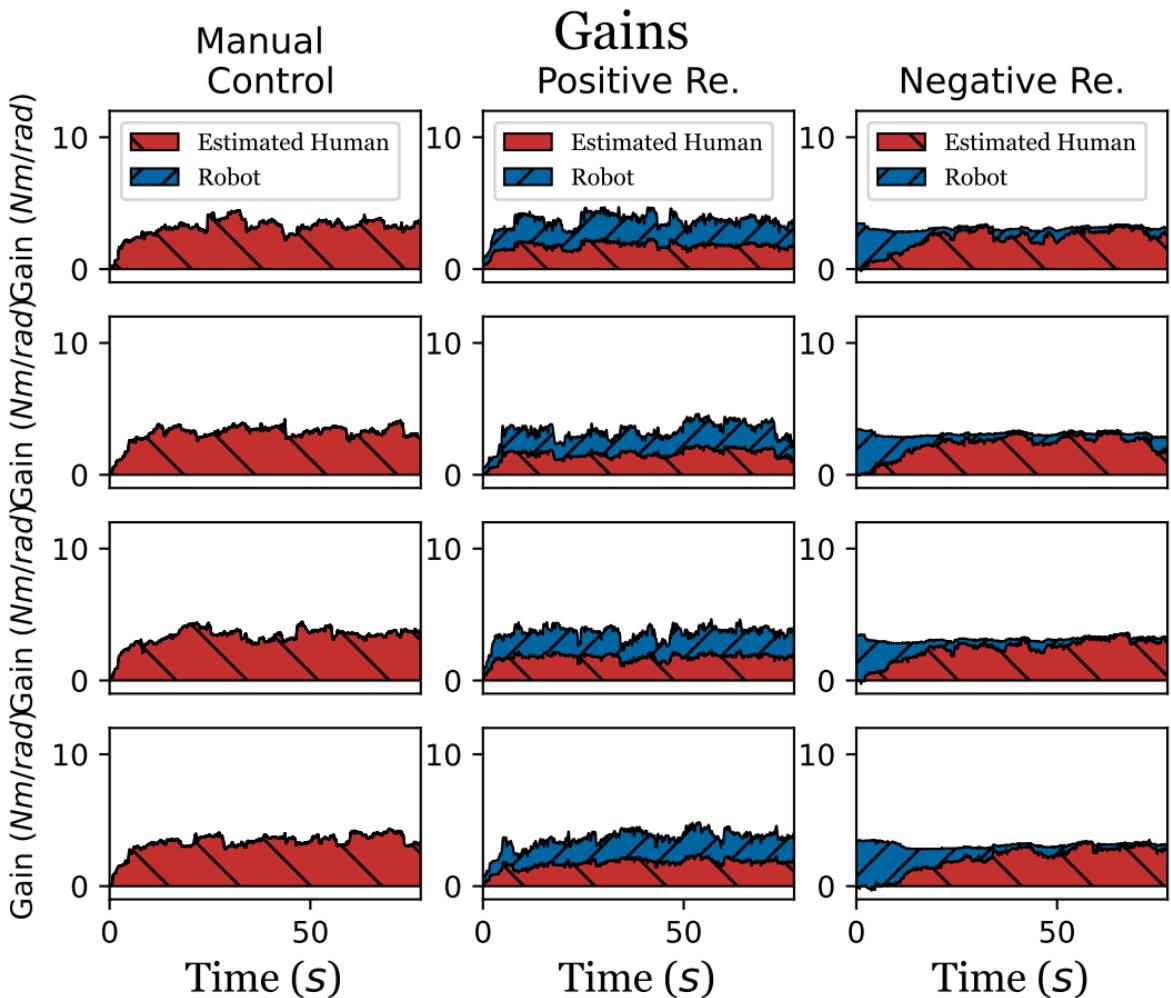
Positive Re.

Negative Re.

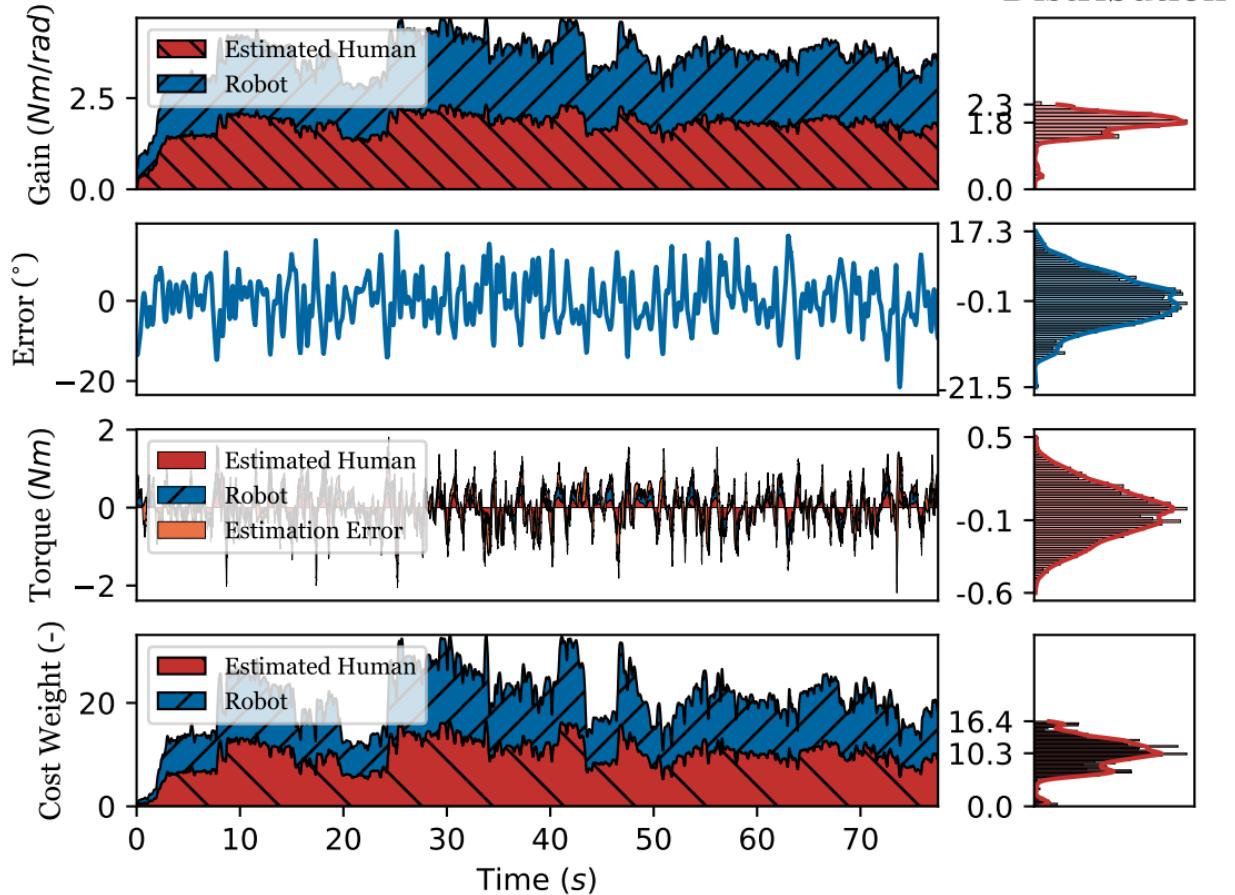


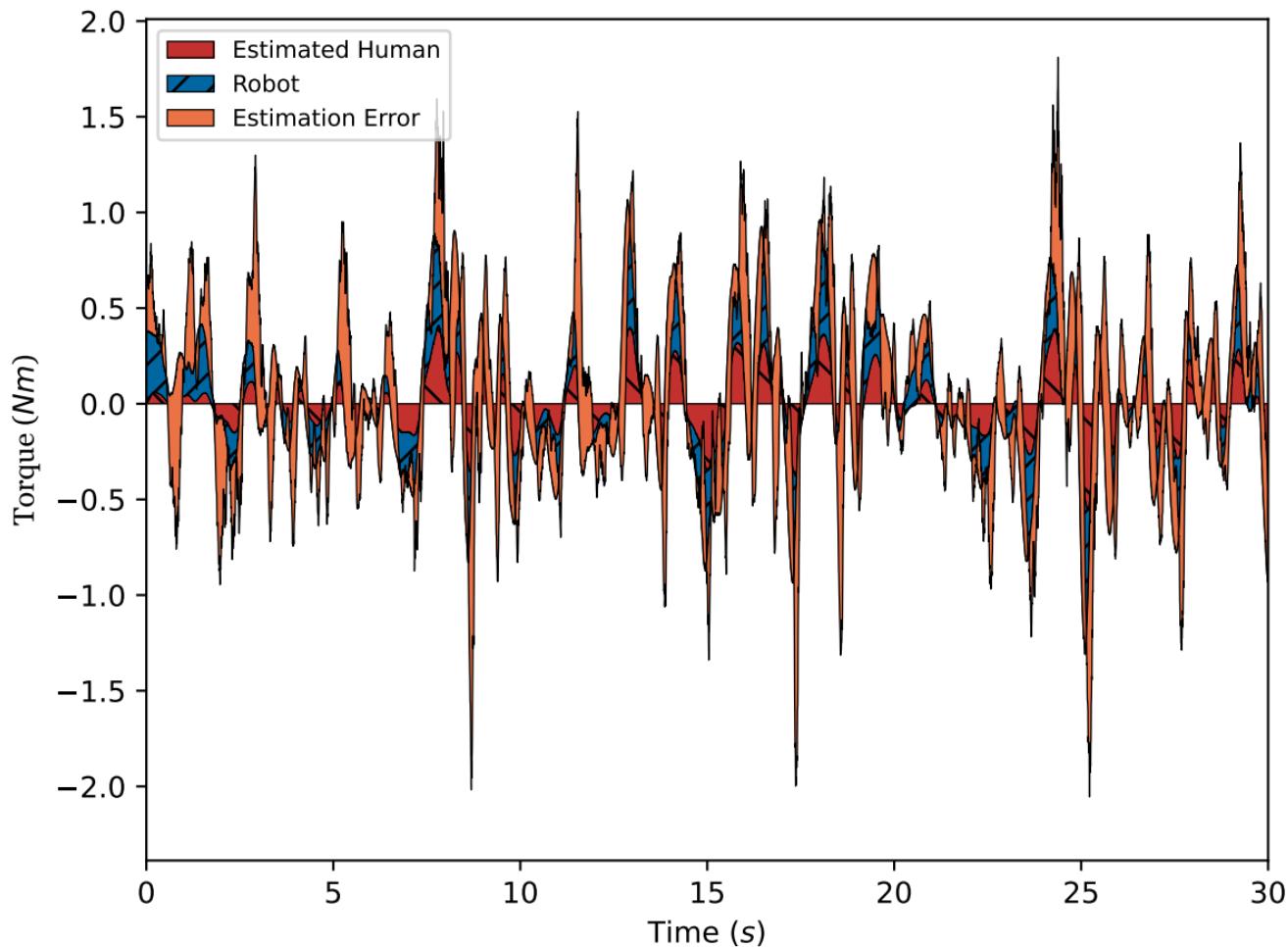
Time (s)

Time (s)

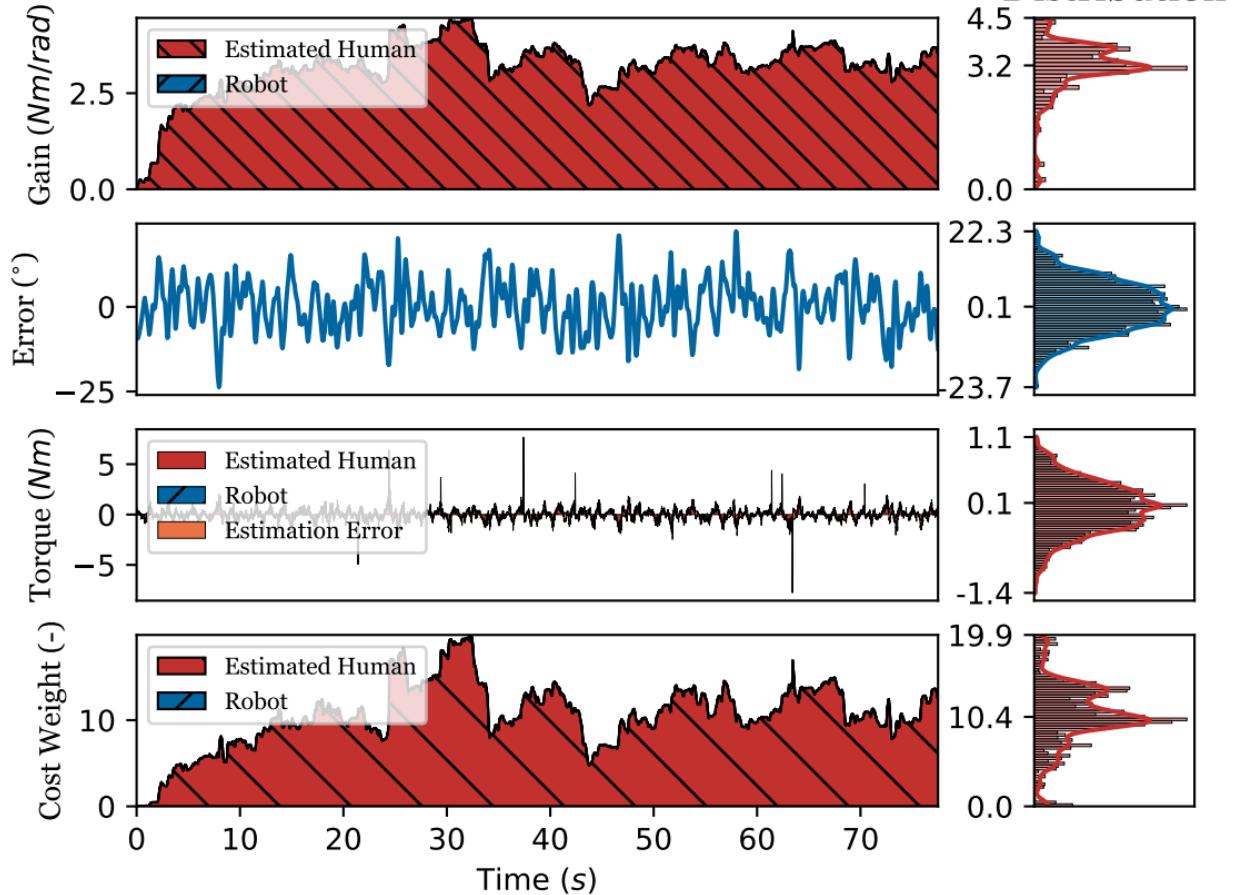


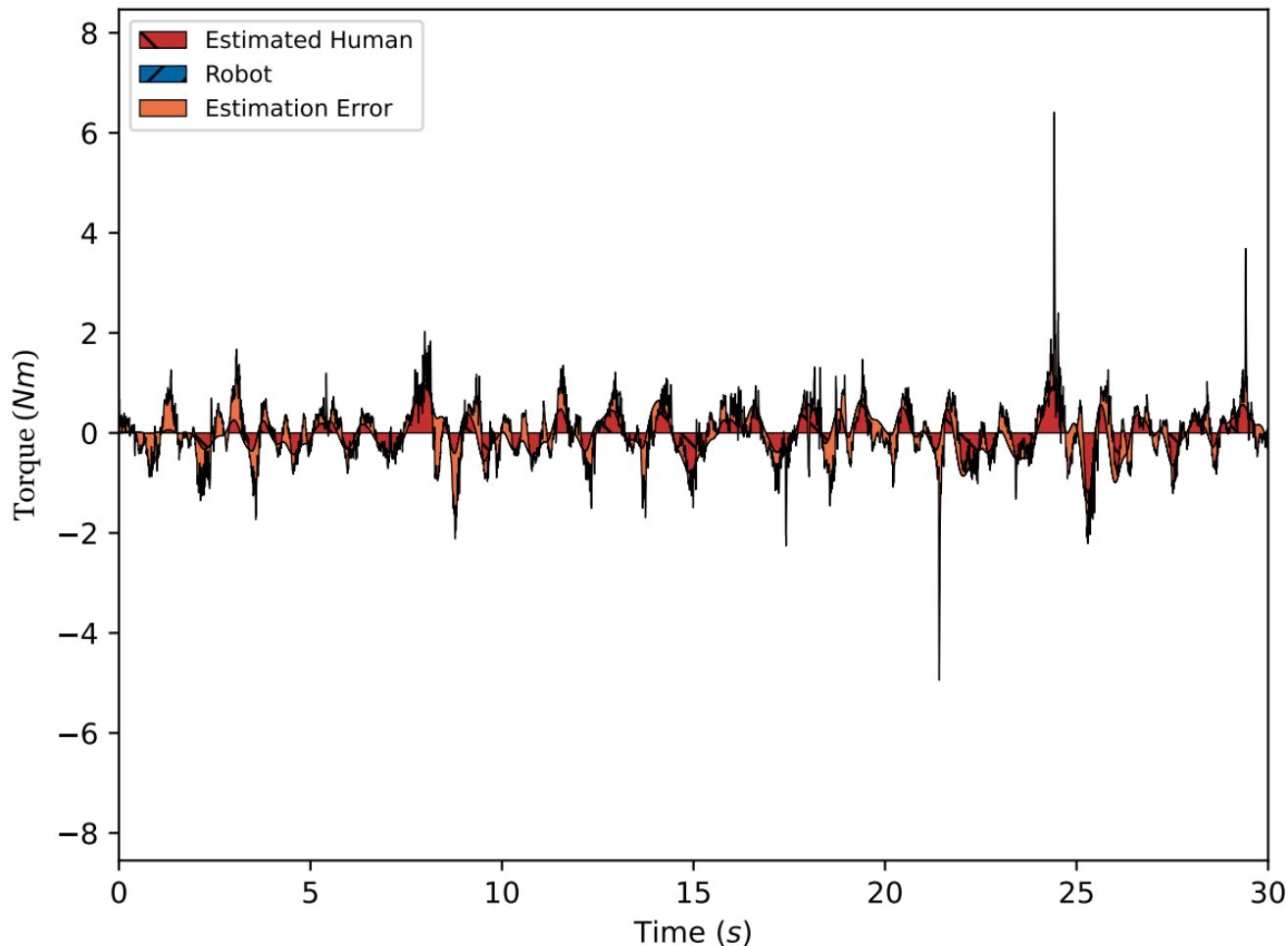
Positive Reinforcement



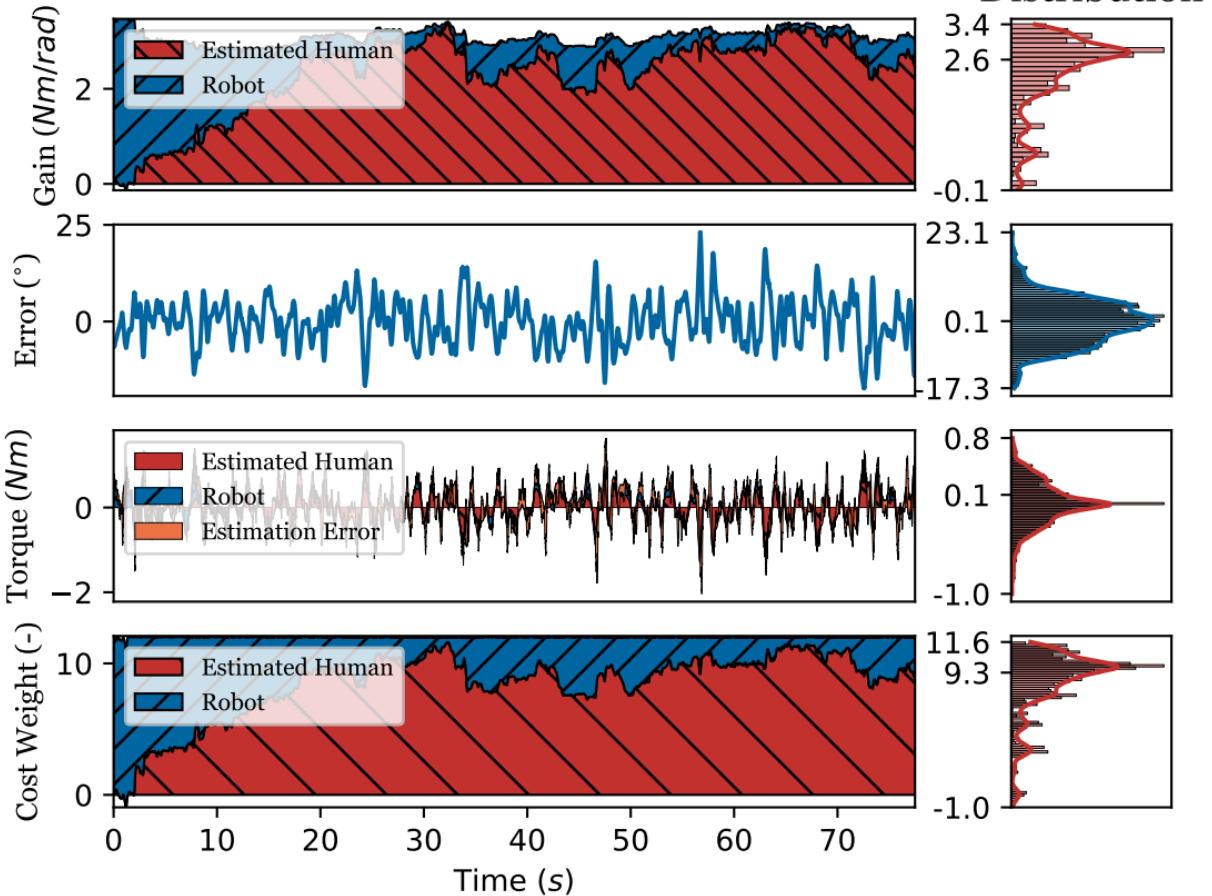


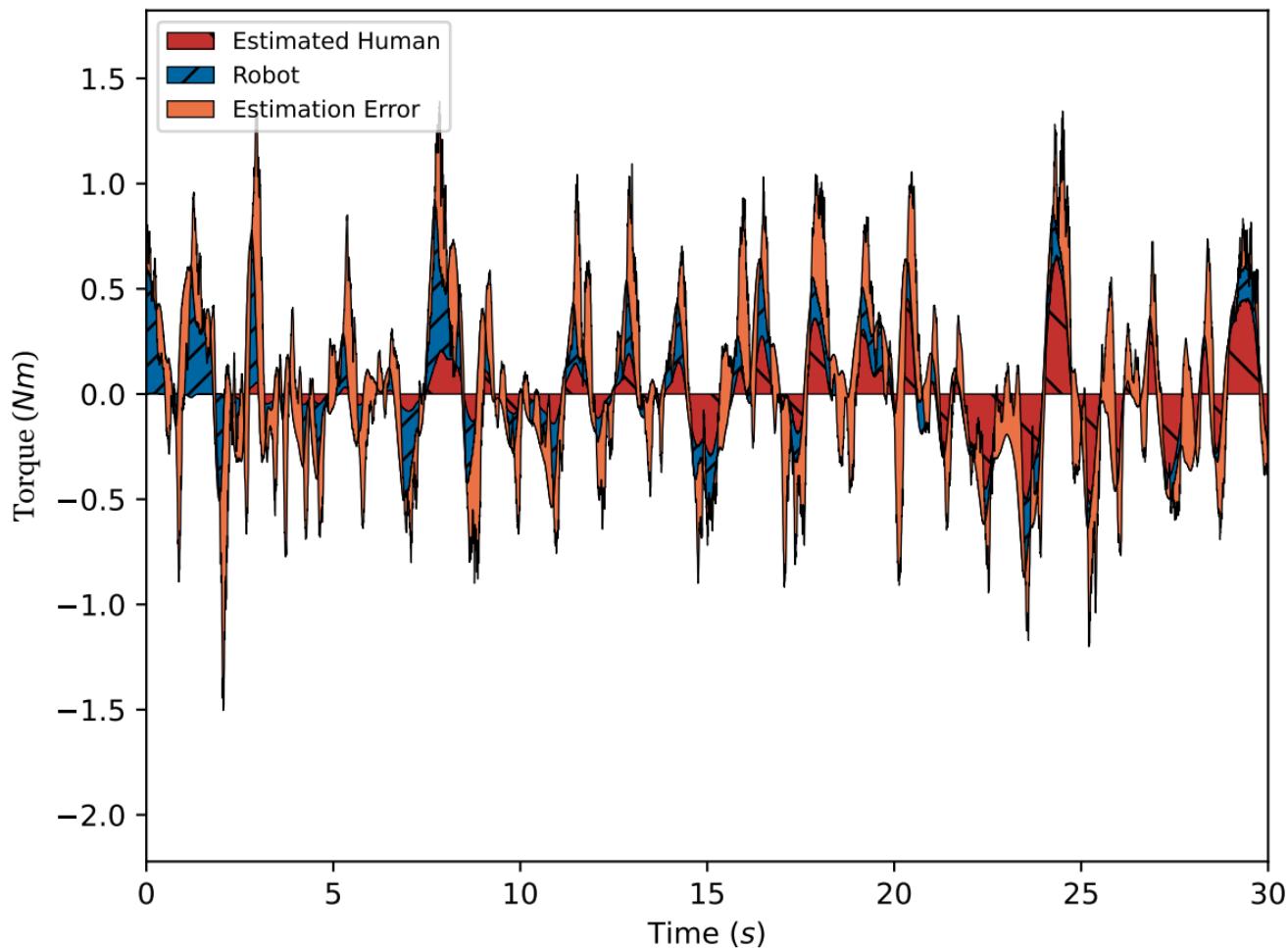
Manual Control





Negative Reinforcement

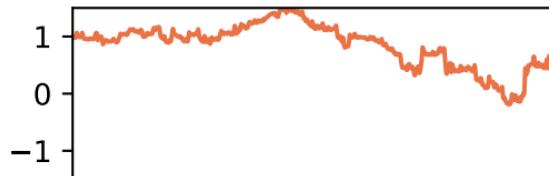
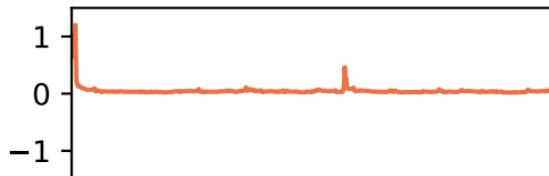
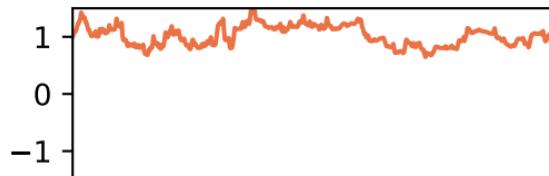
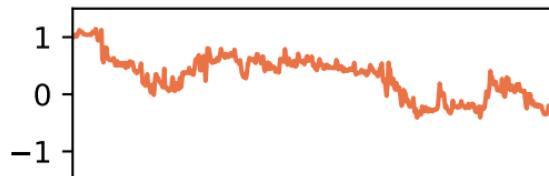
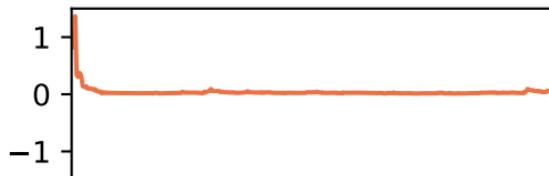
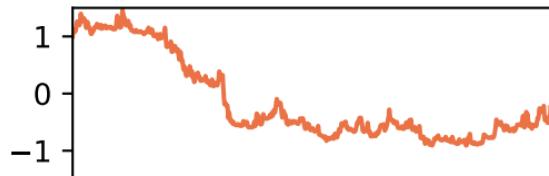




Estimated Control Share

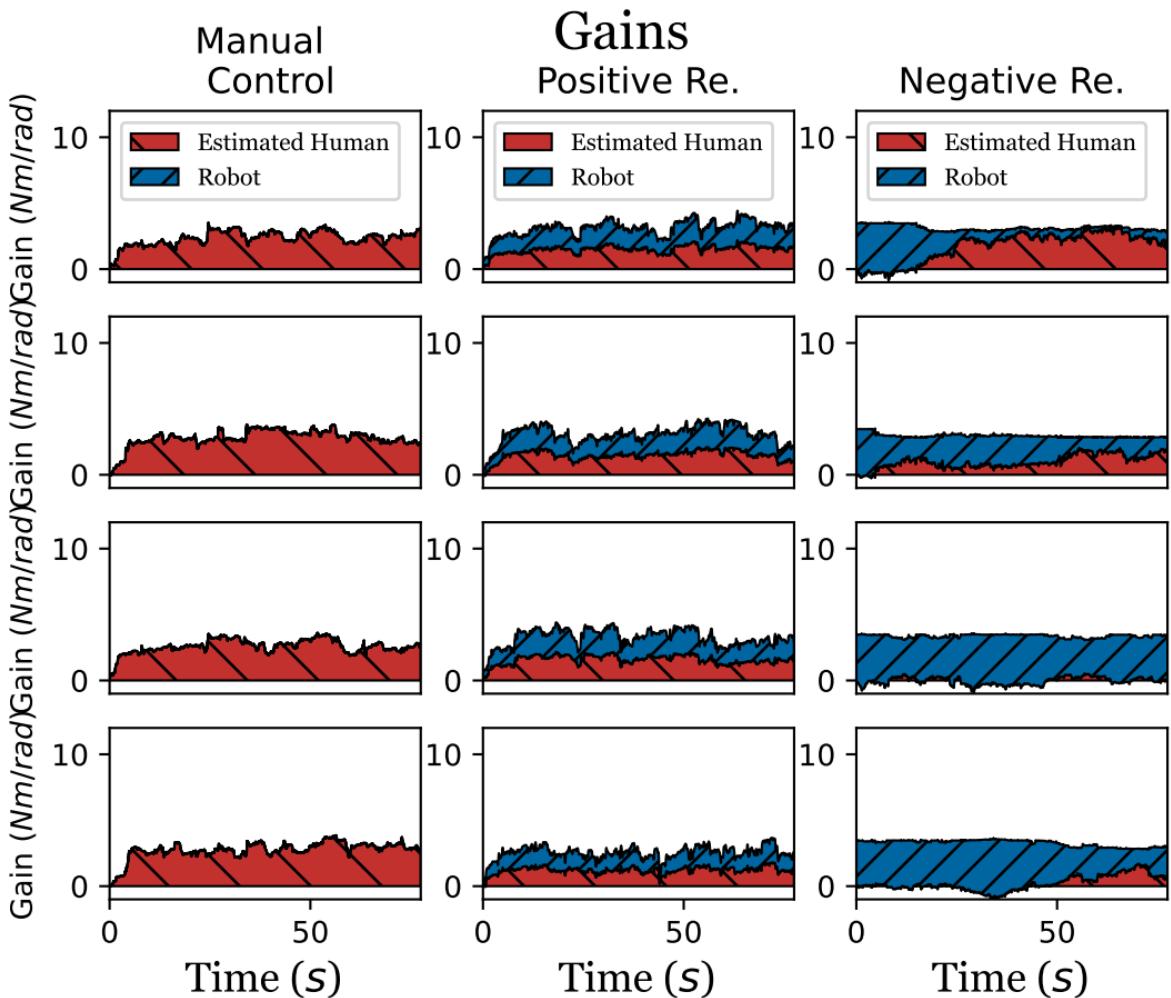
Positive Re.

Negative Re.

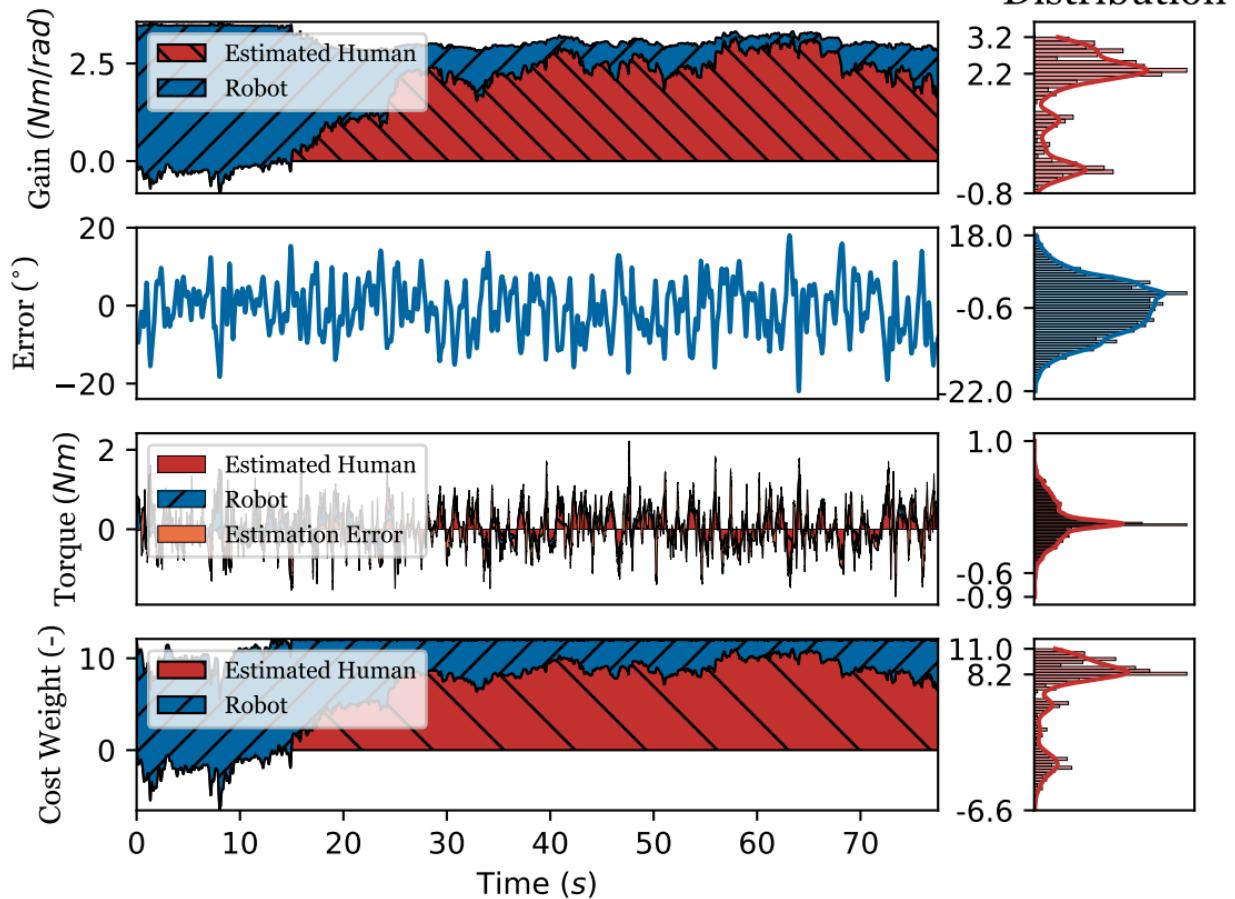


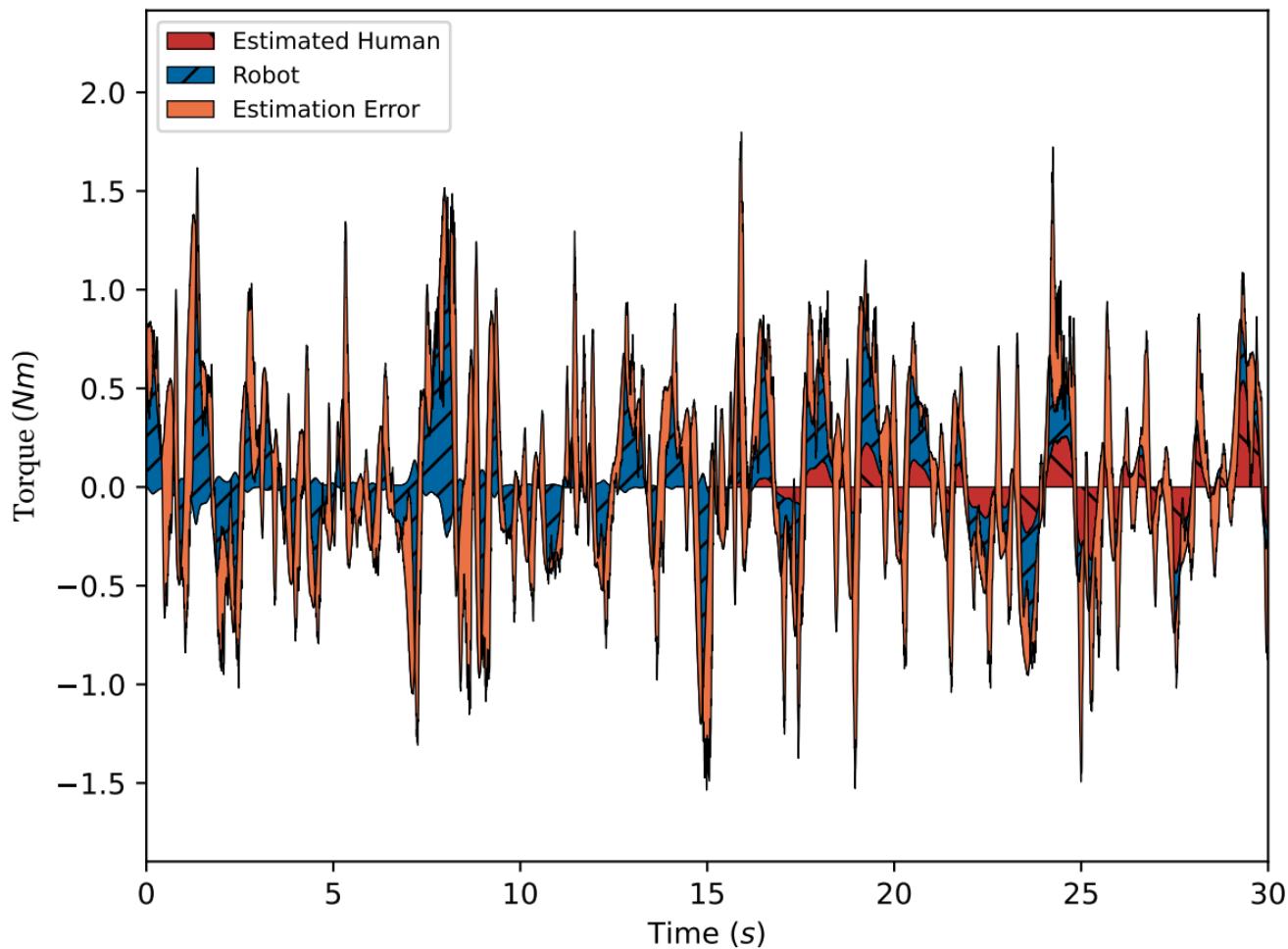
Time (s)

Time (s)

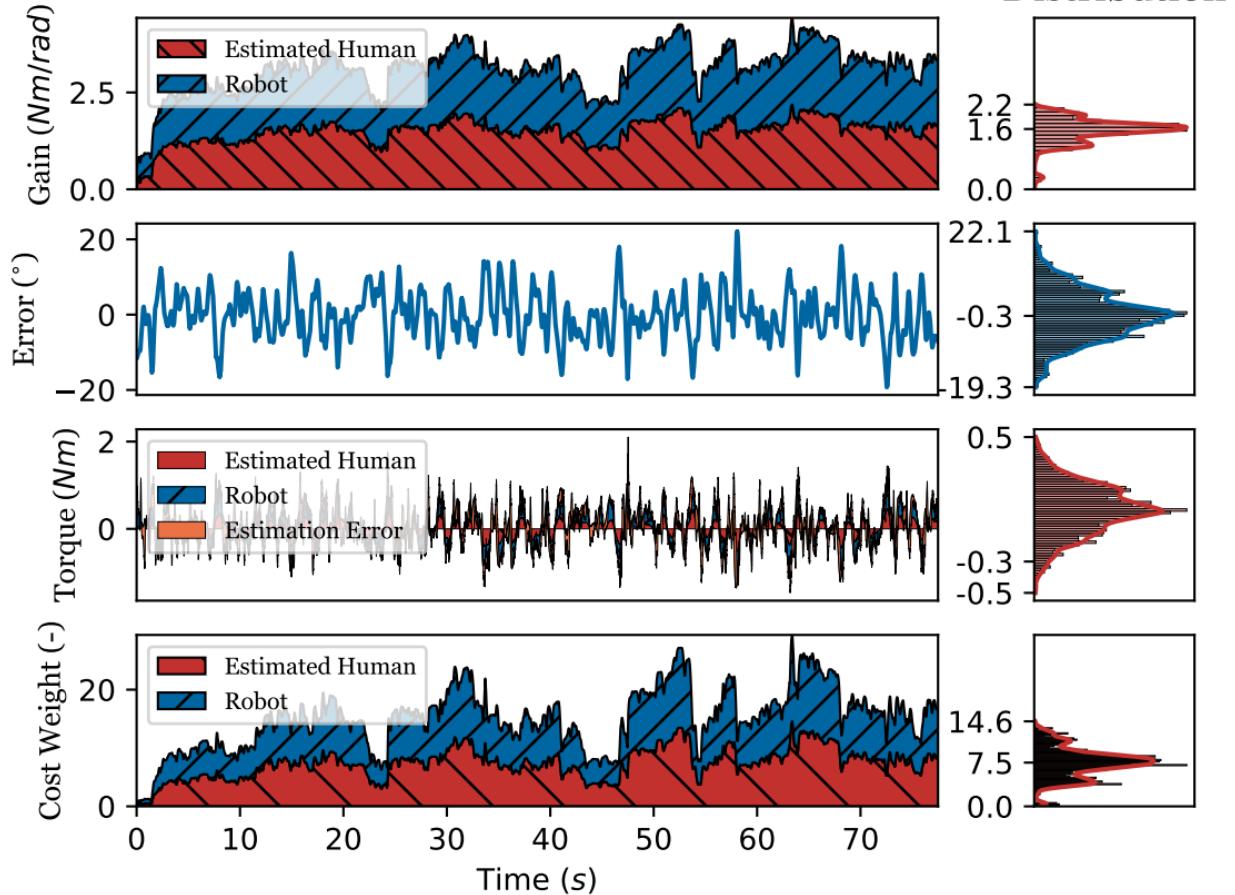


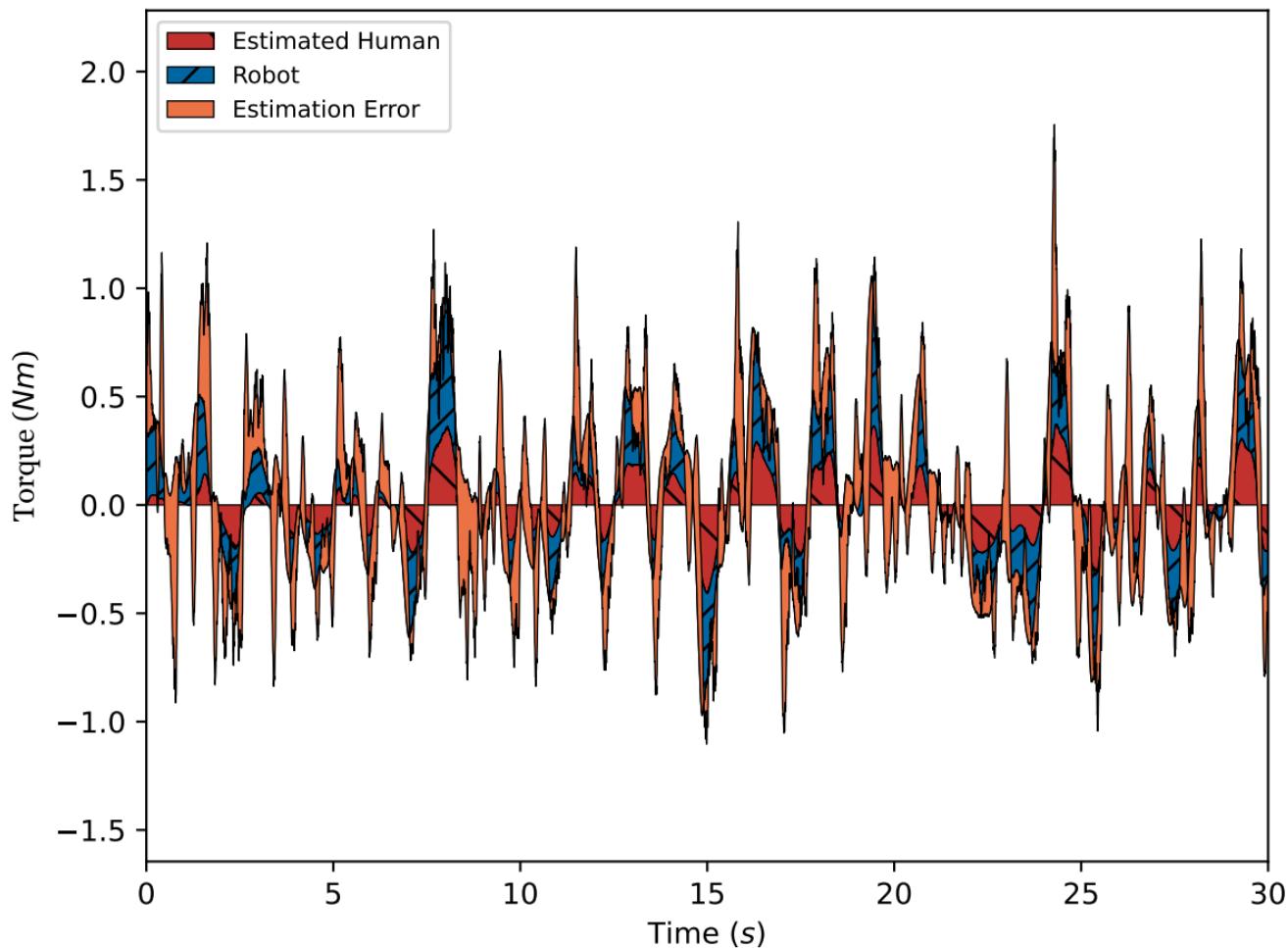
Negative Reinforcement



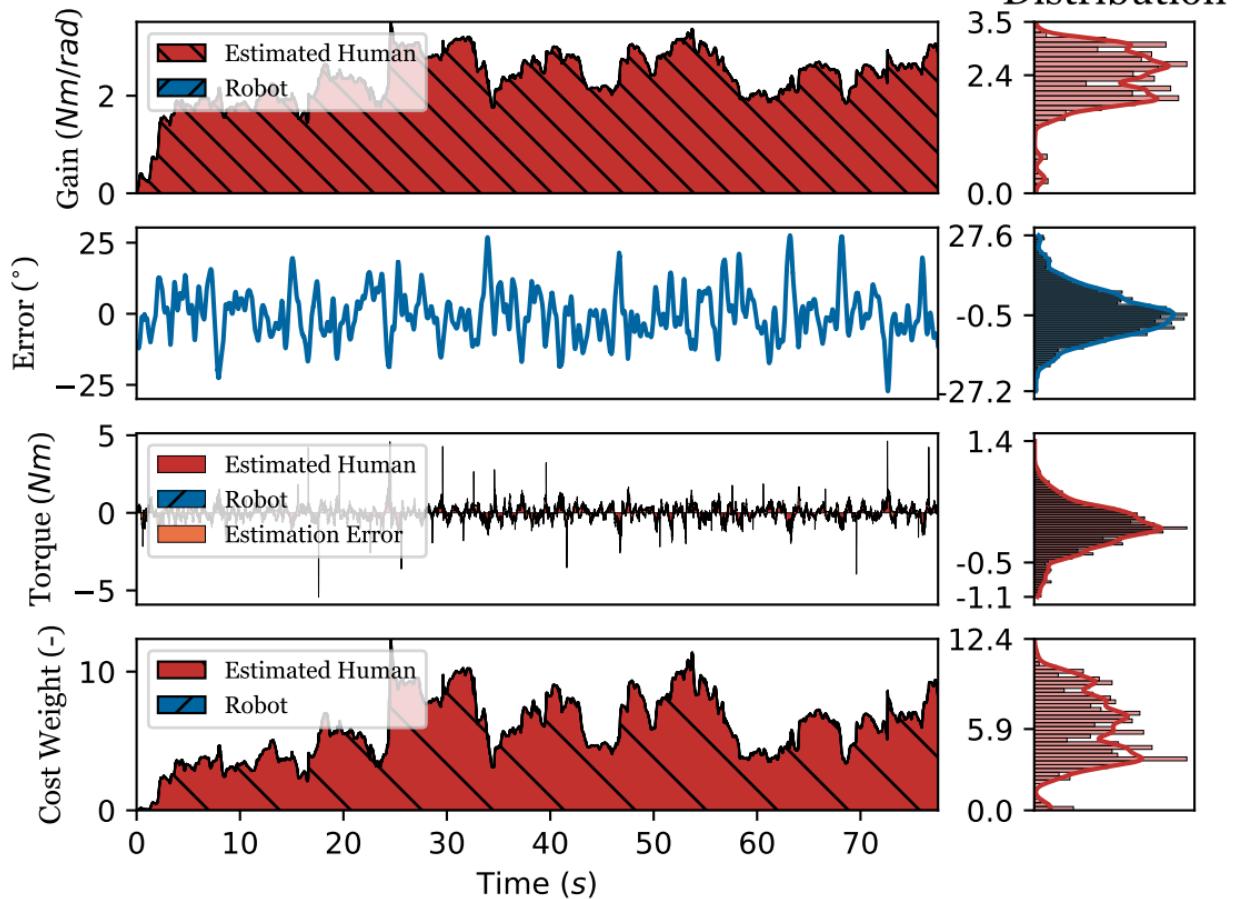


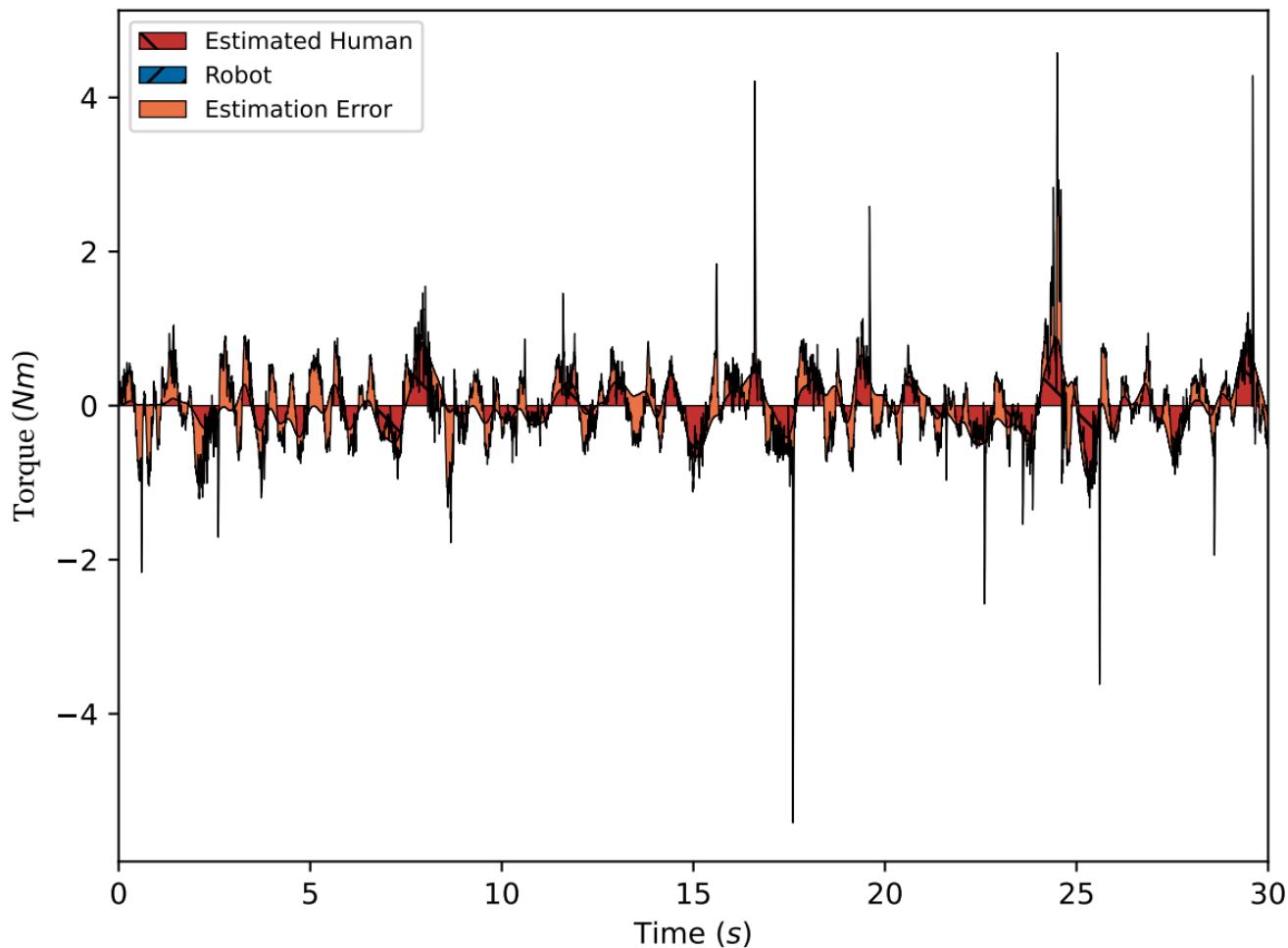
Positive Reinforcement





Manual Control

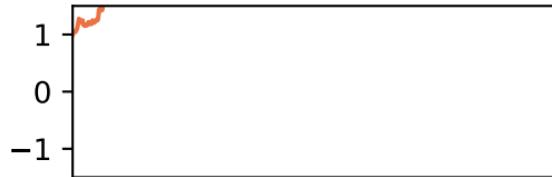
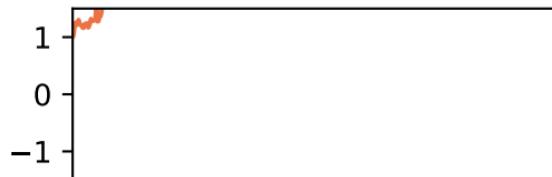
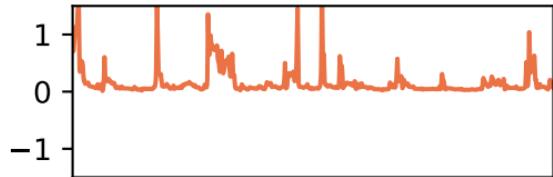
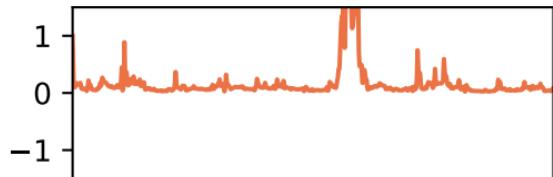
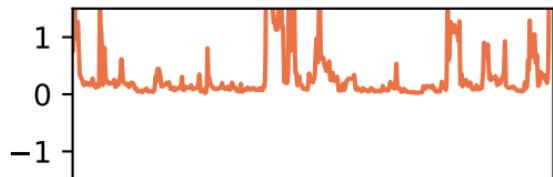
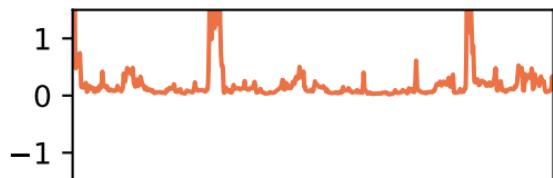




Estimated Control Share

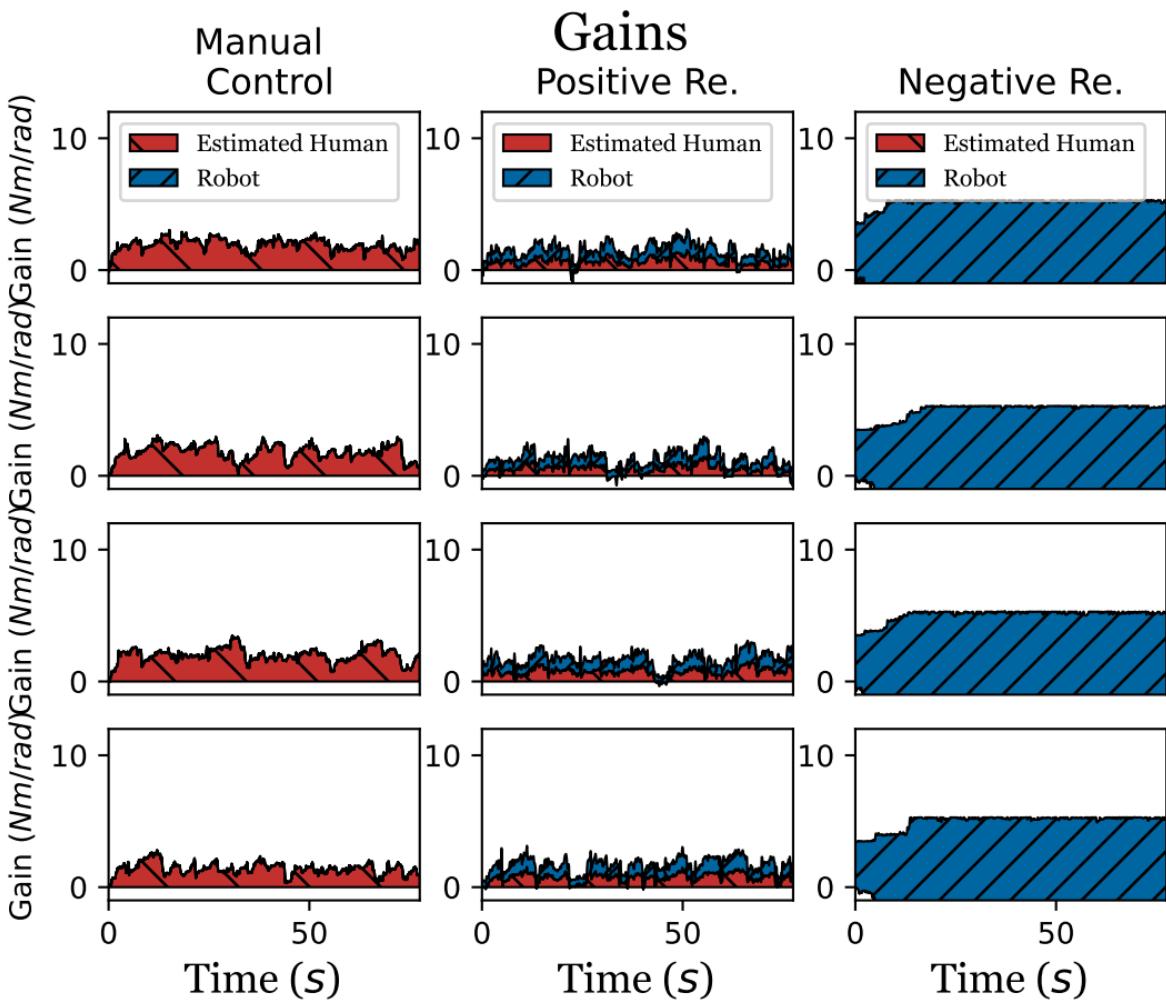
Positive Re.

Negative Re.

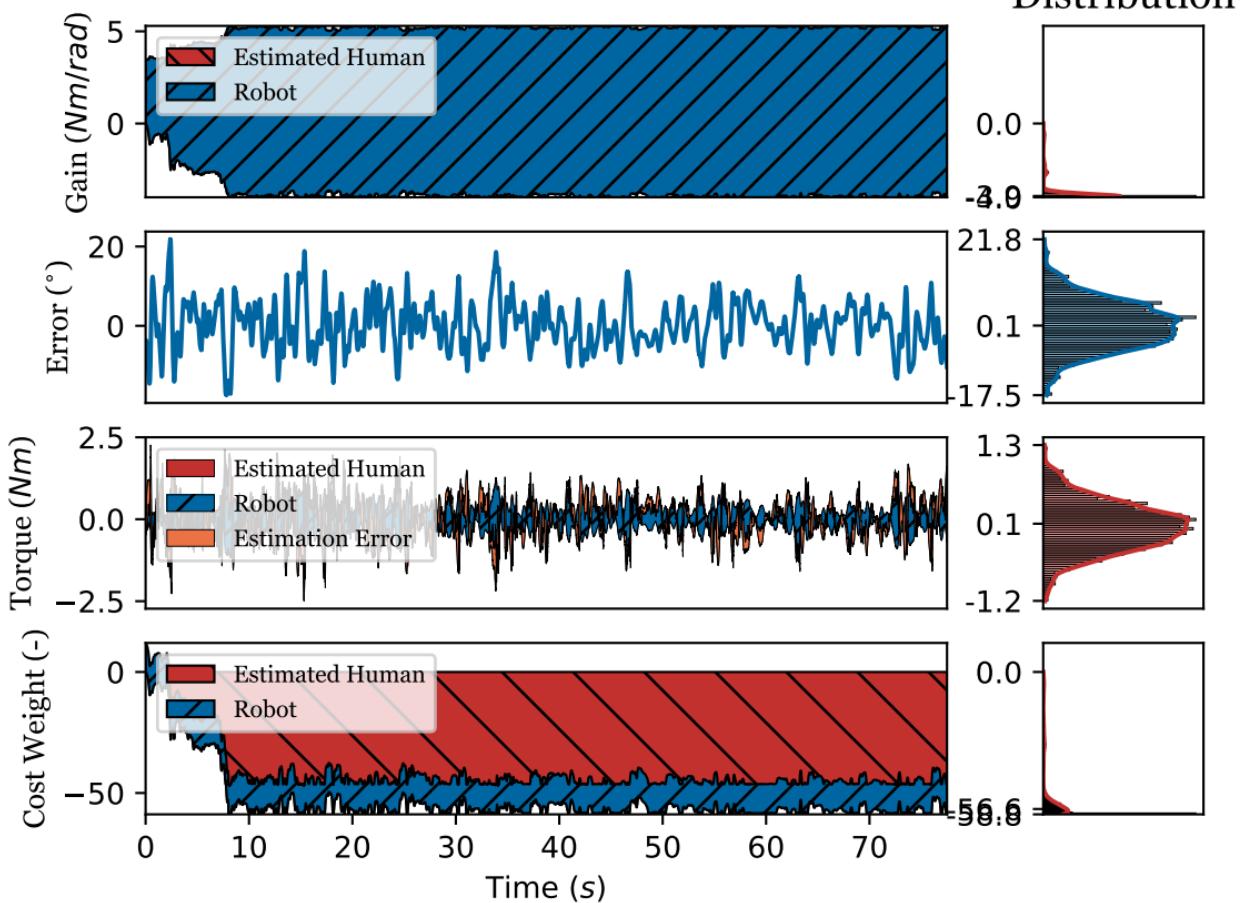


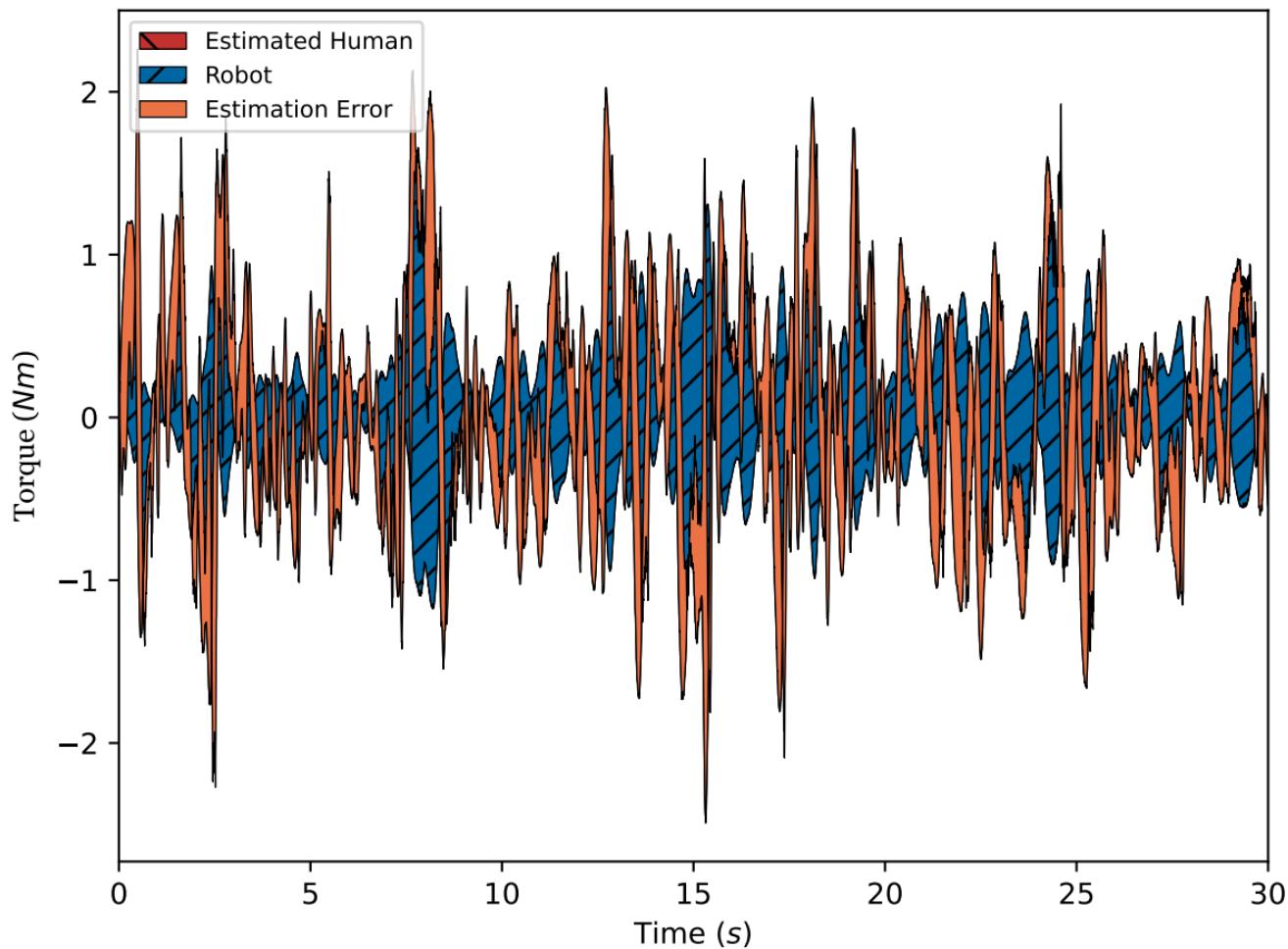
Time (s)

Time (s)

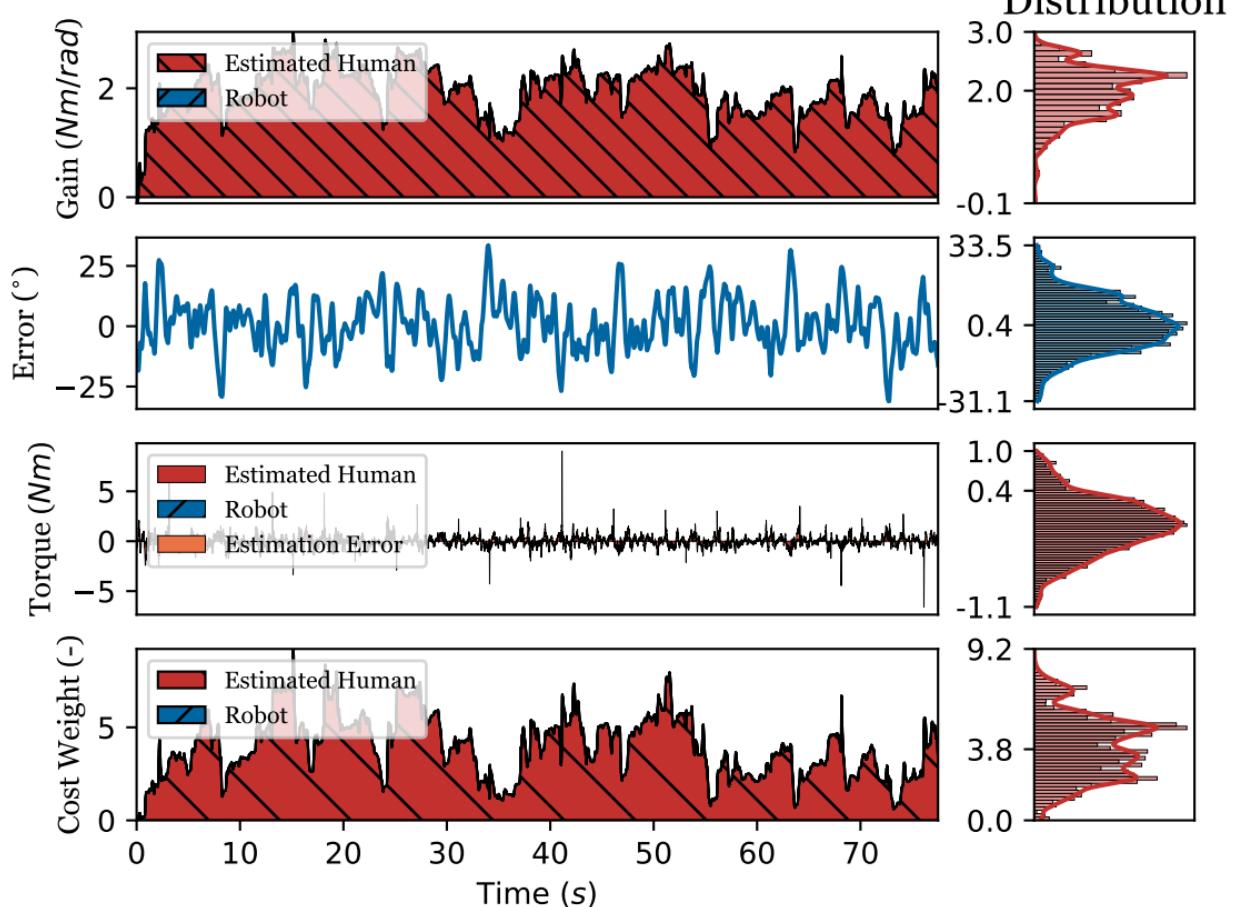


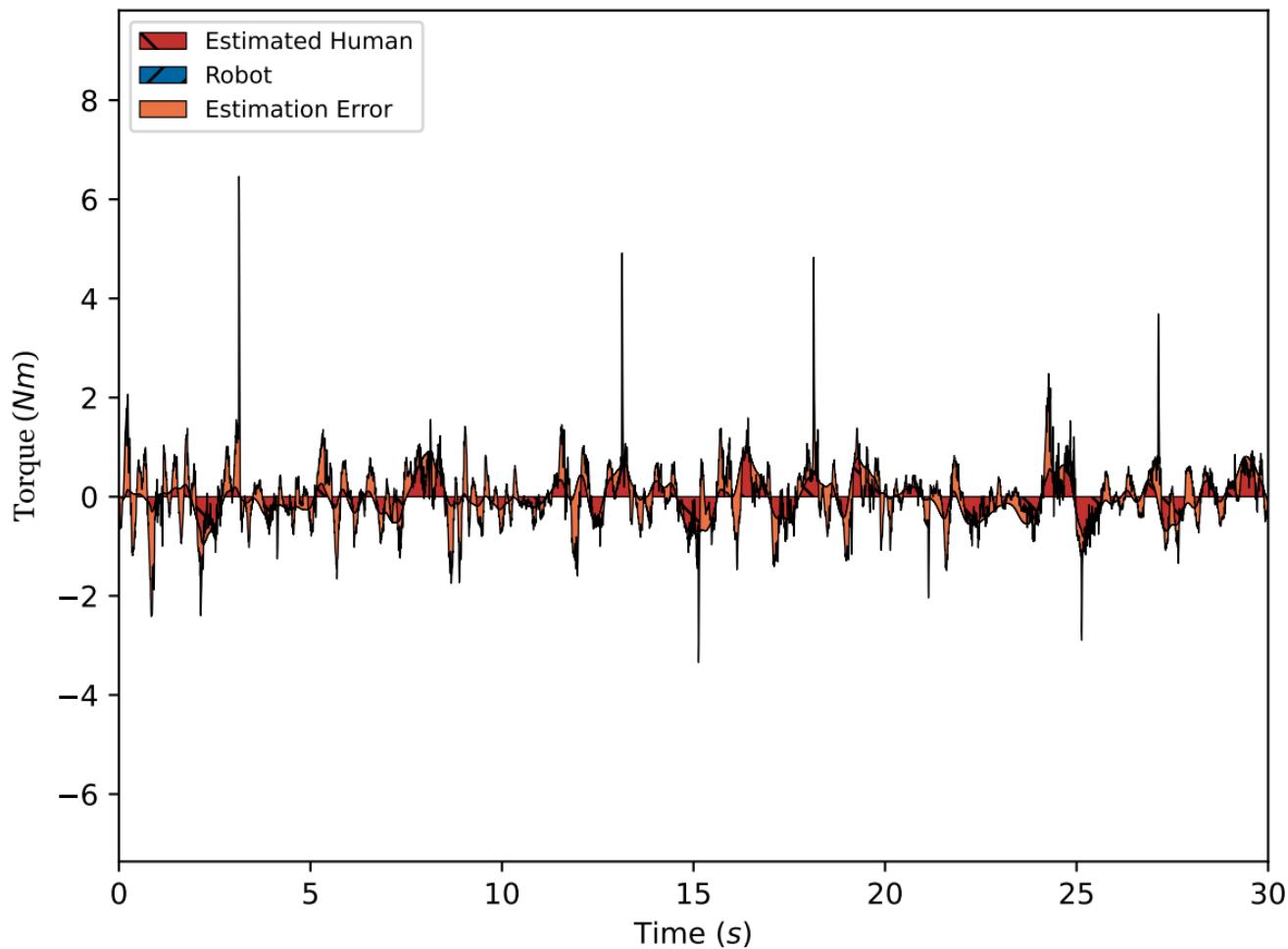
Negative Reinforcement



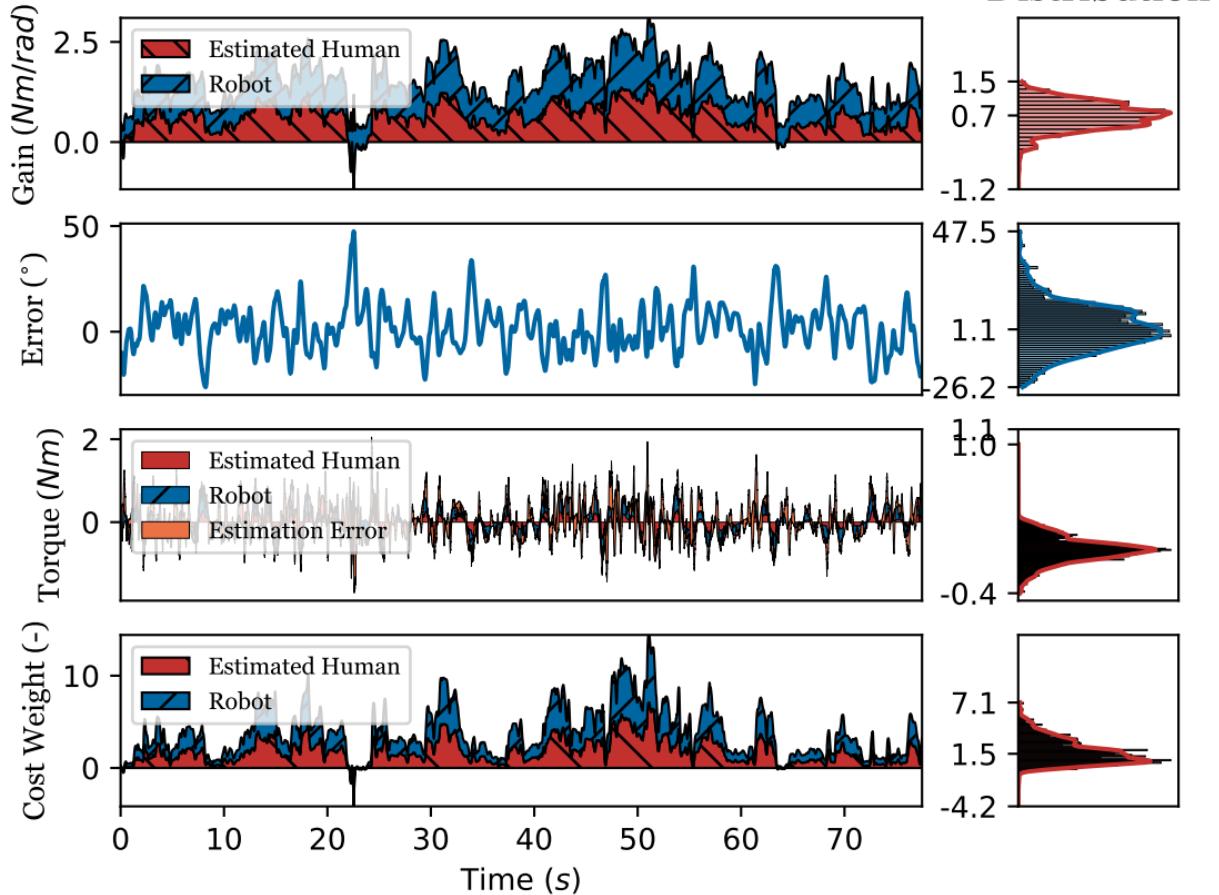


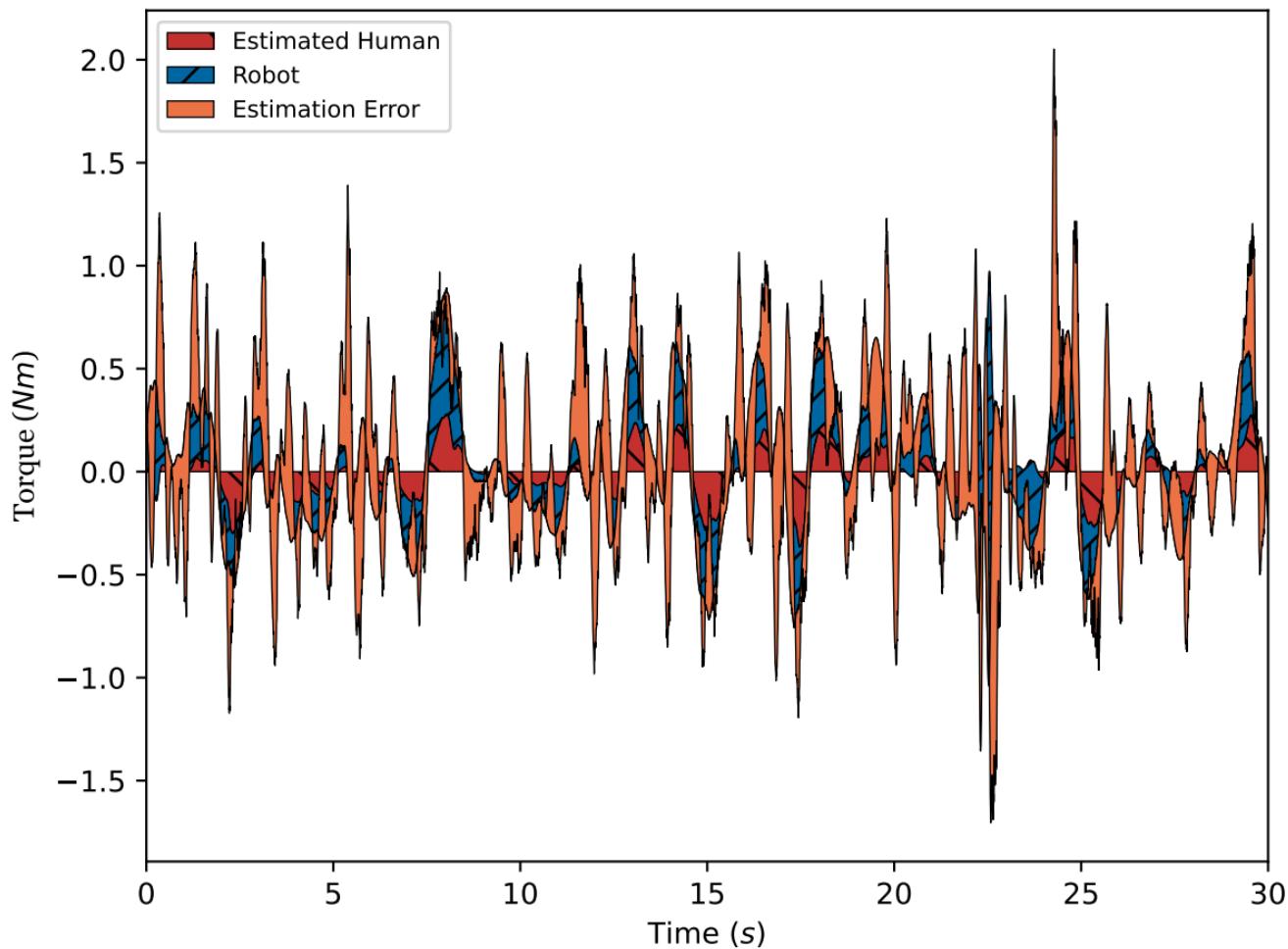
Manual Control



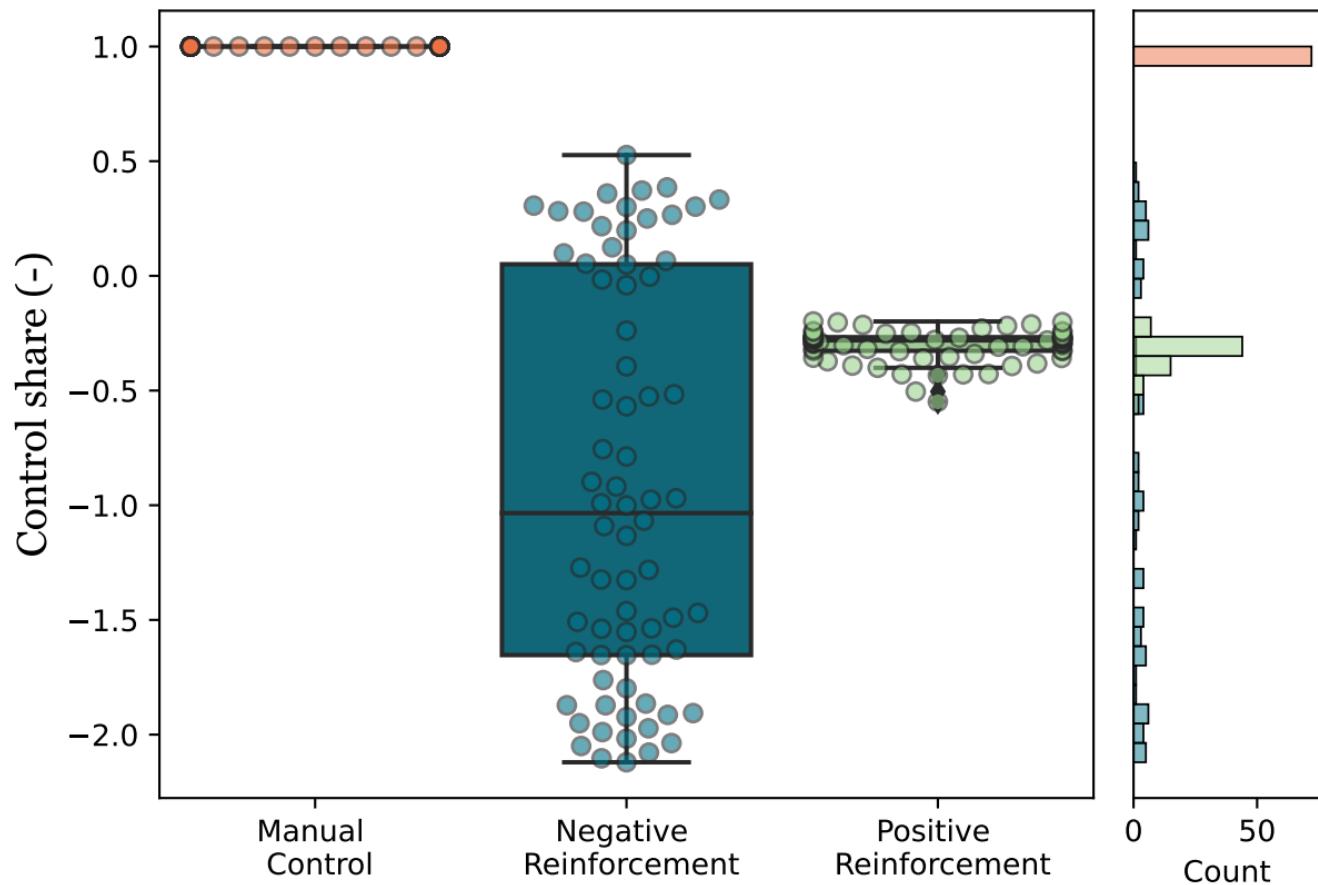


Positive Reinforcement

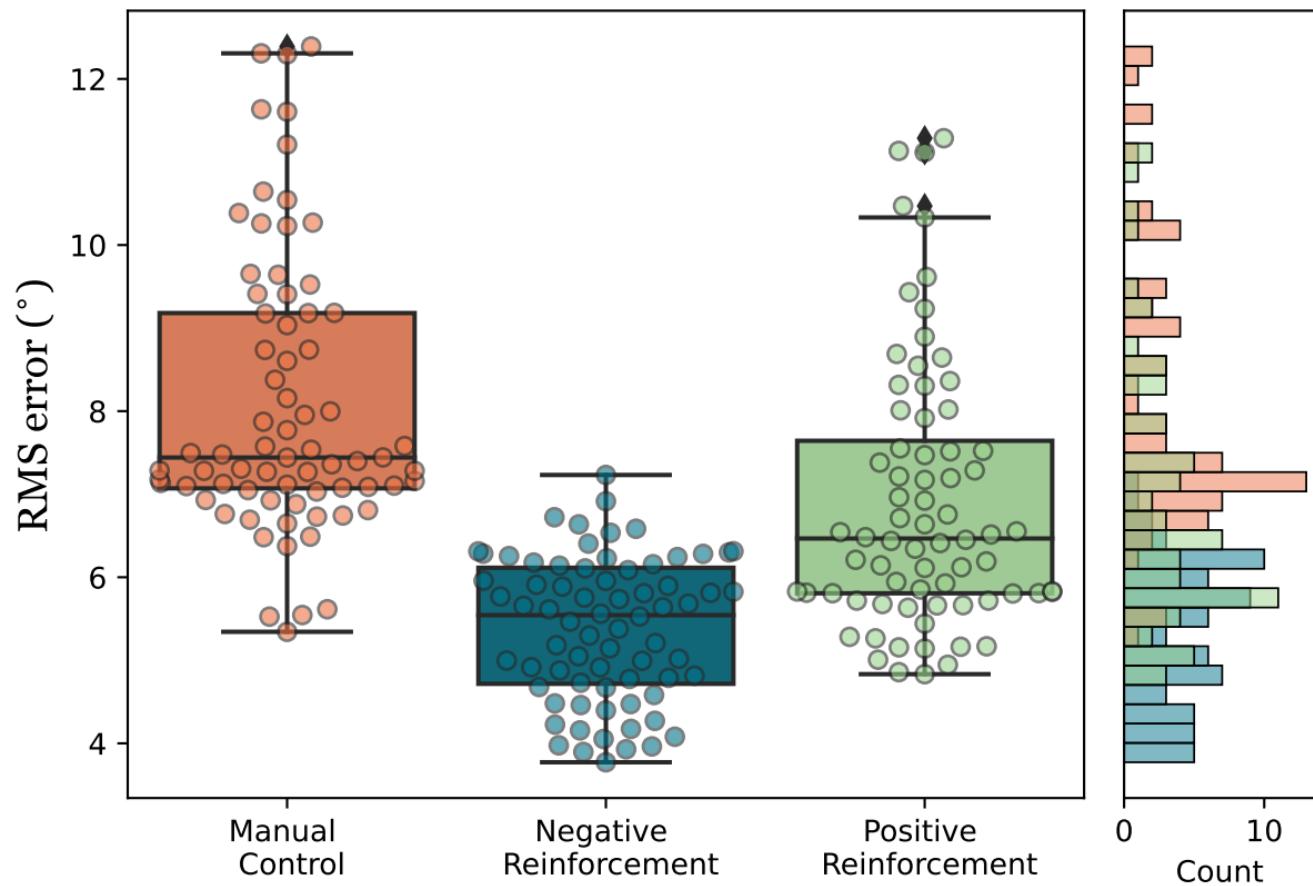




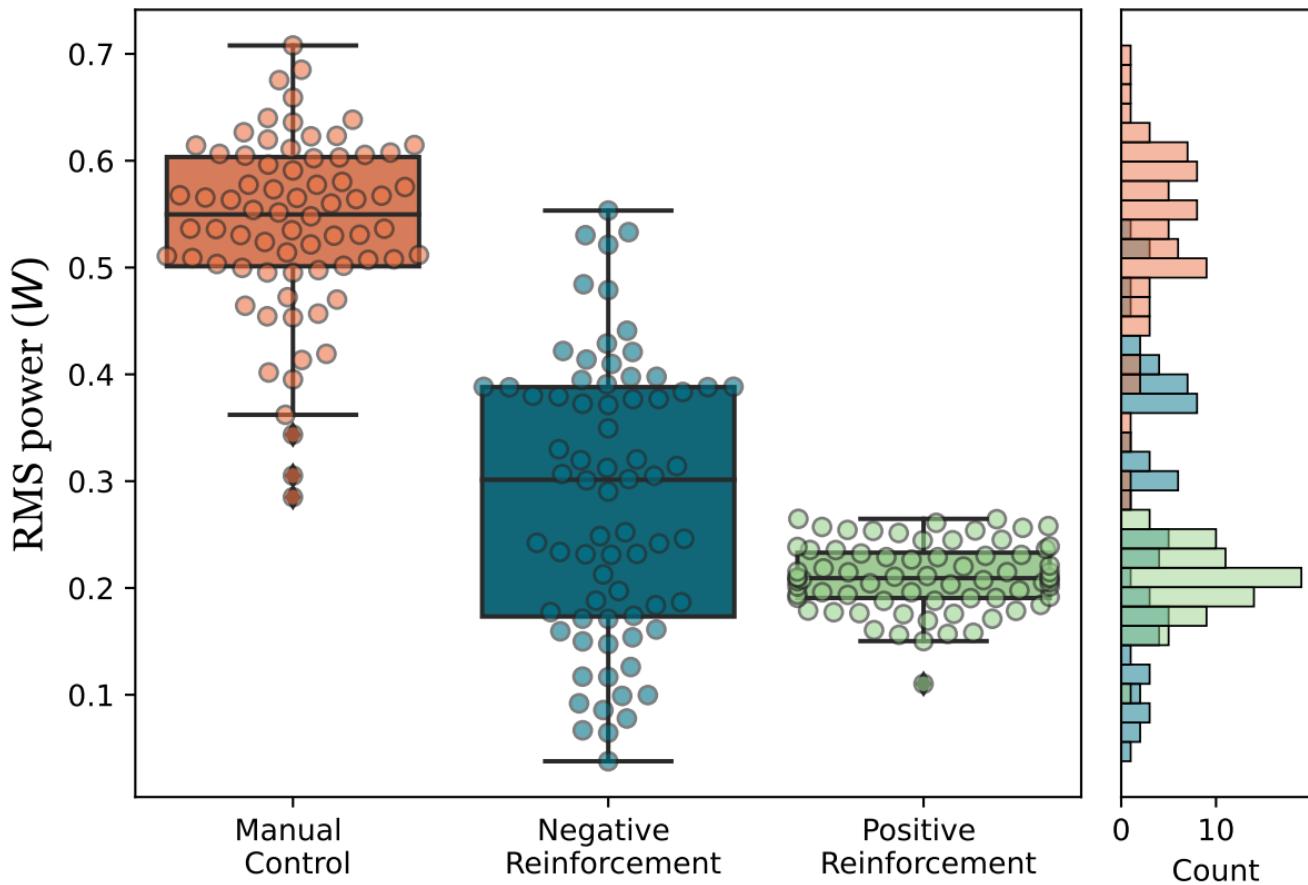
Control Share



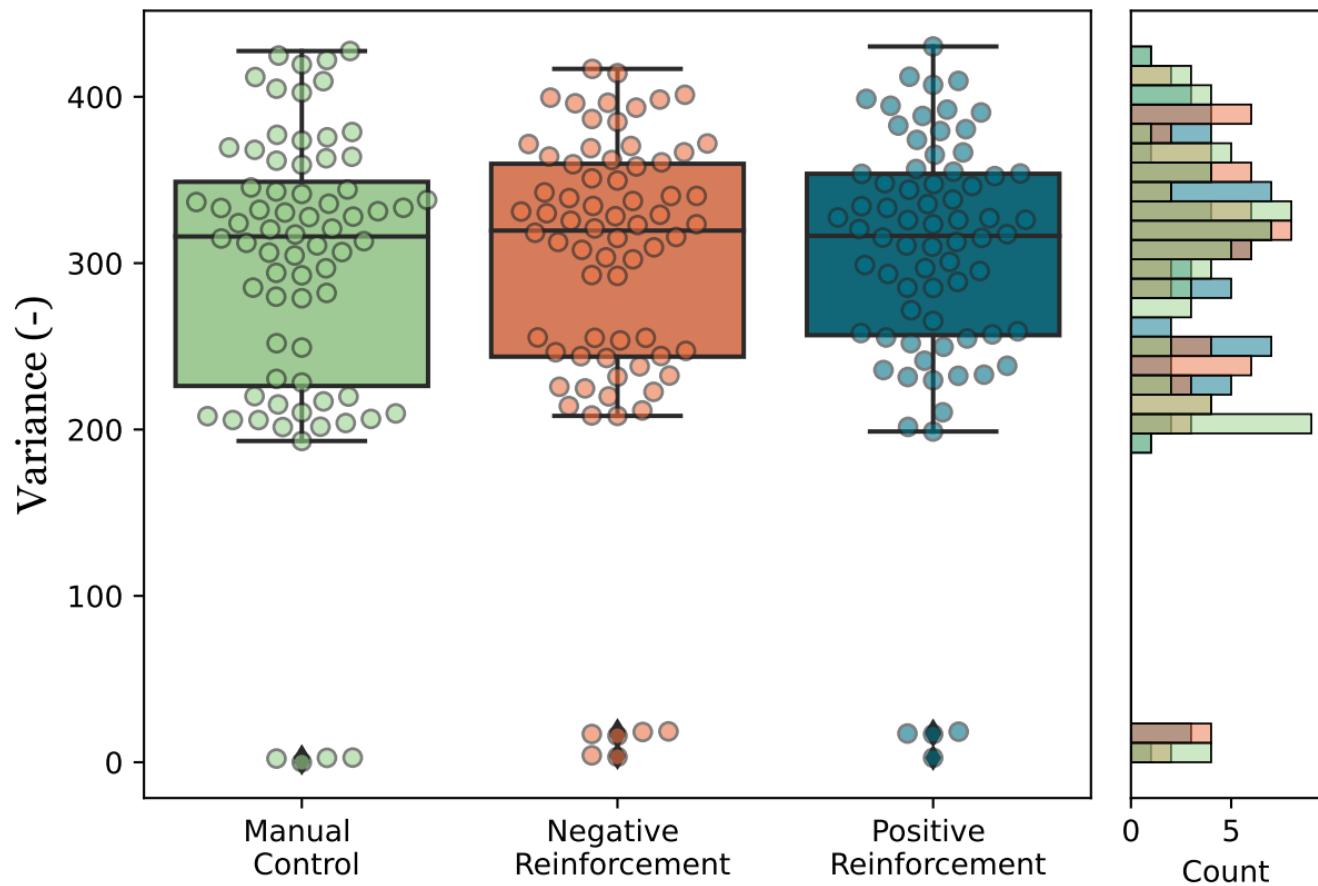
Steering Angle Error



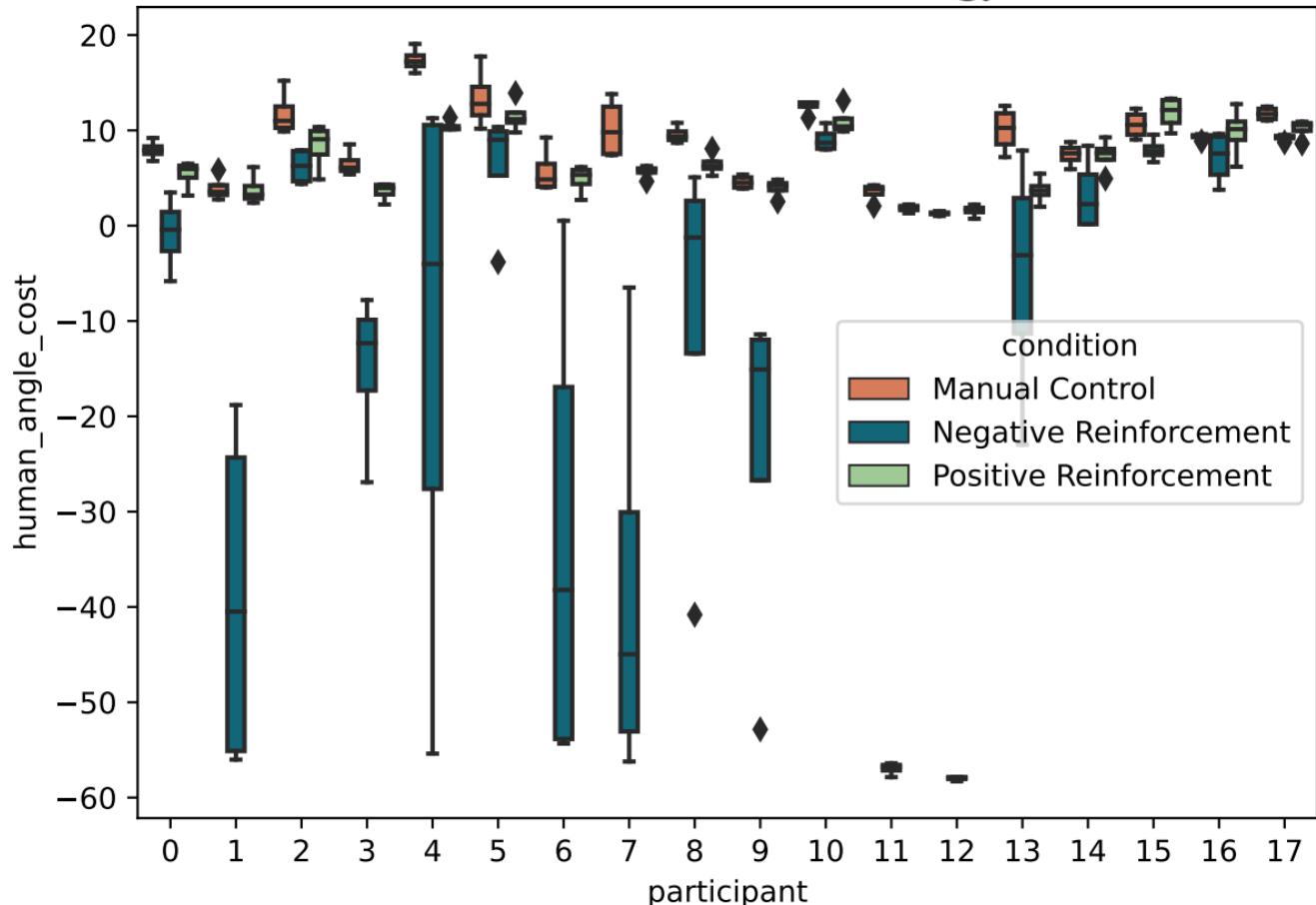
Human Input Power



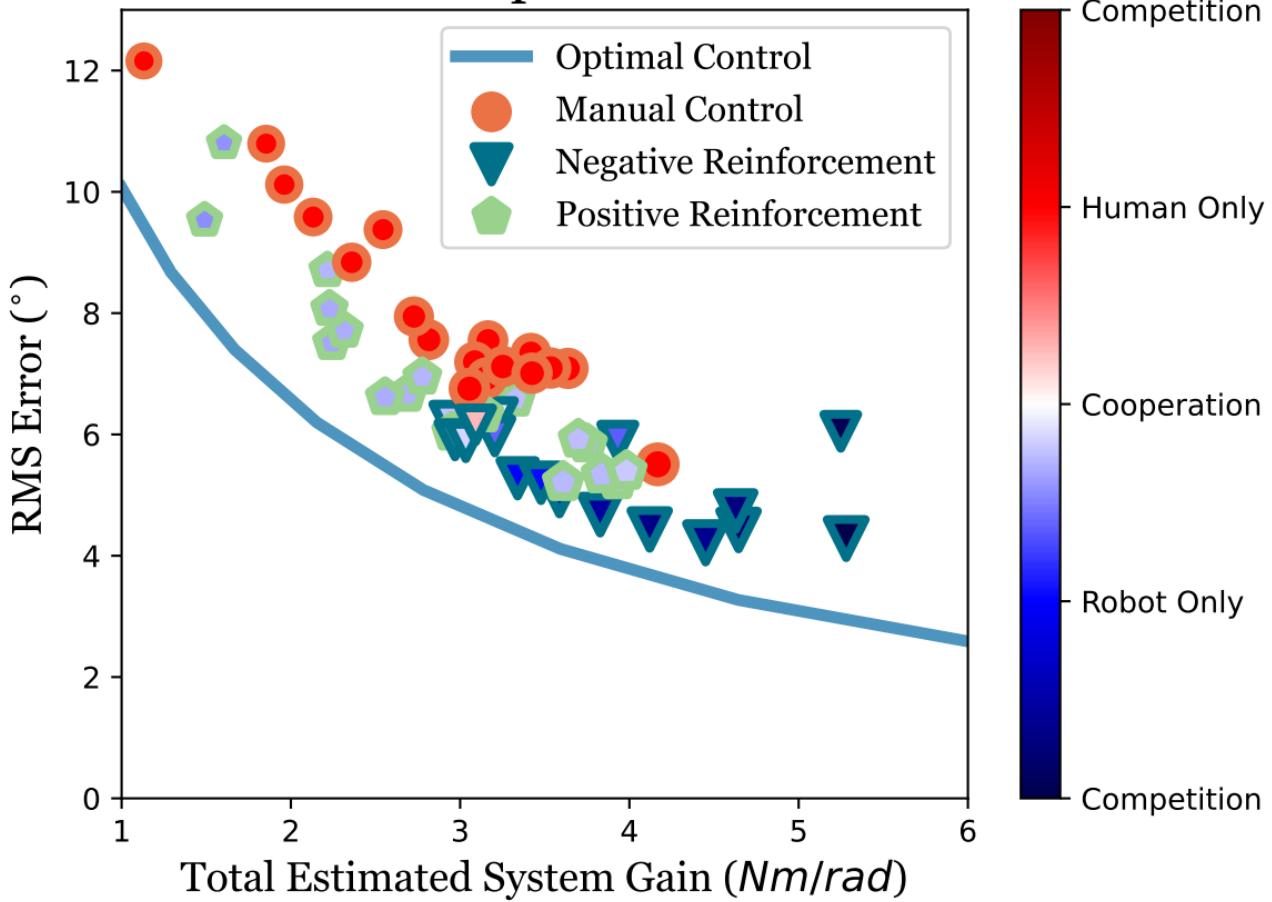
Cost function variability



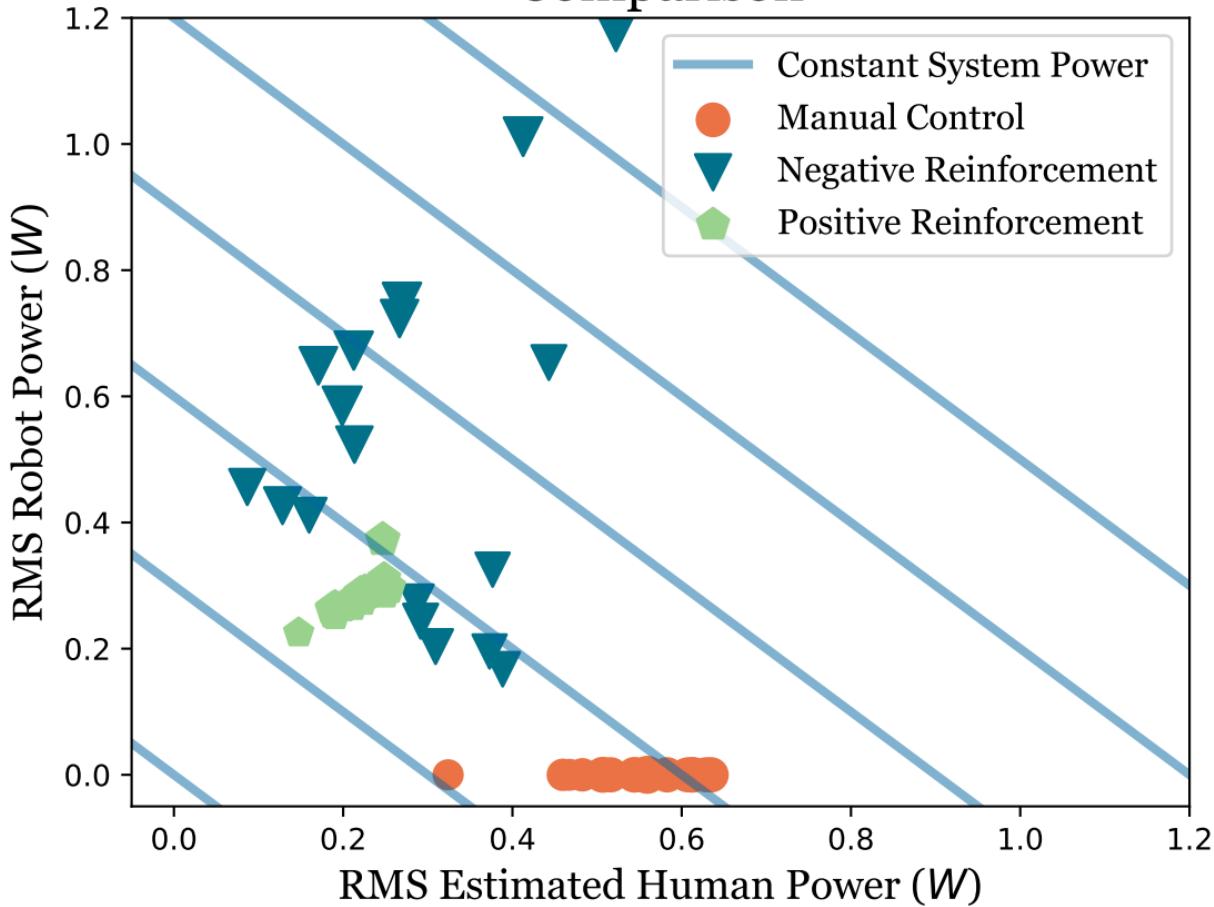
Human control strategy



Comparison



Comparison



Subjective and objective control share

