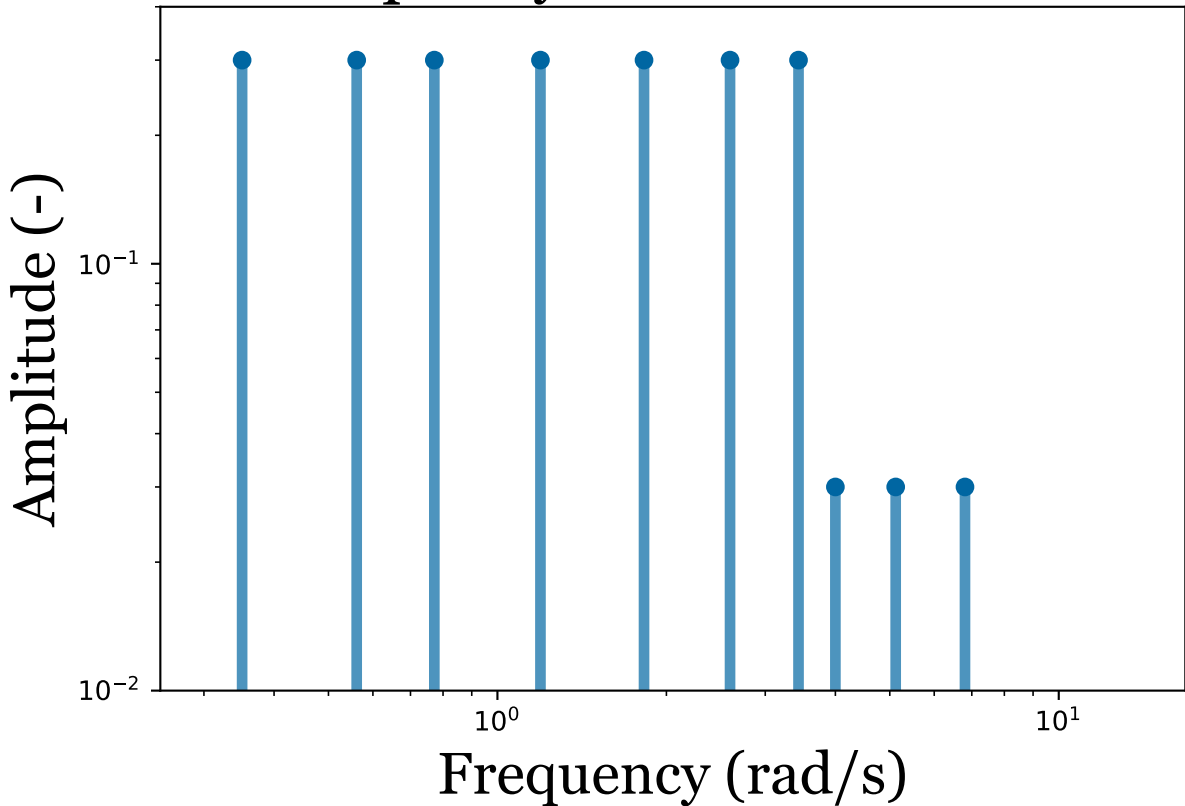
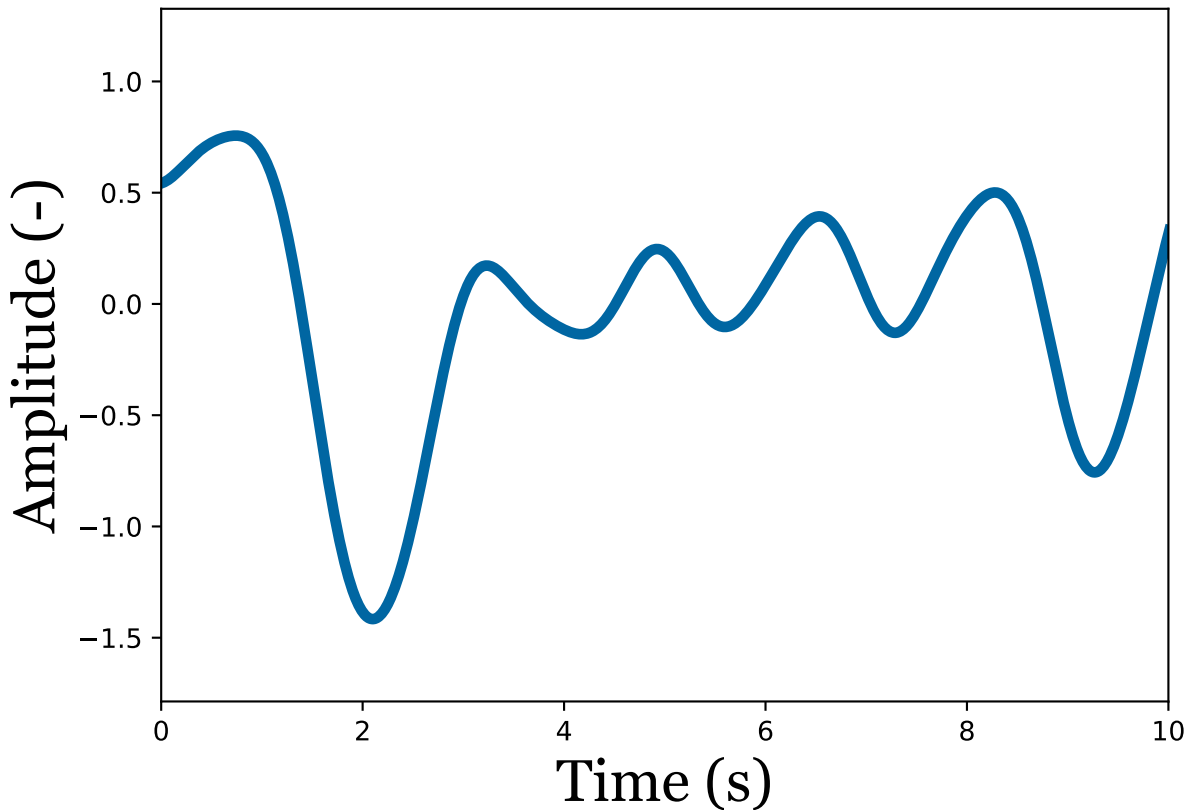


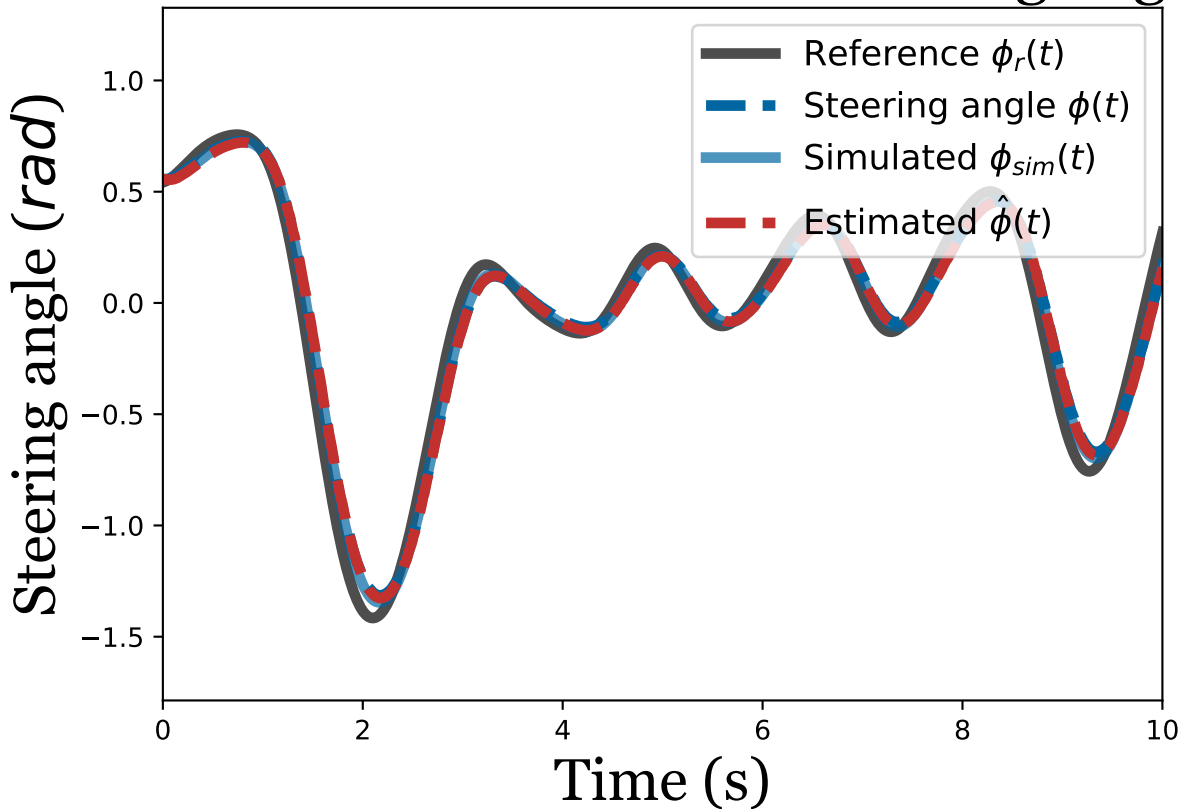
# Frequency domain reference



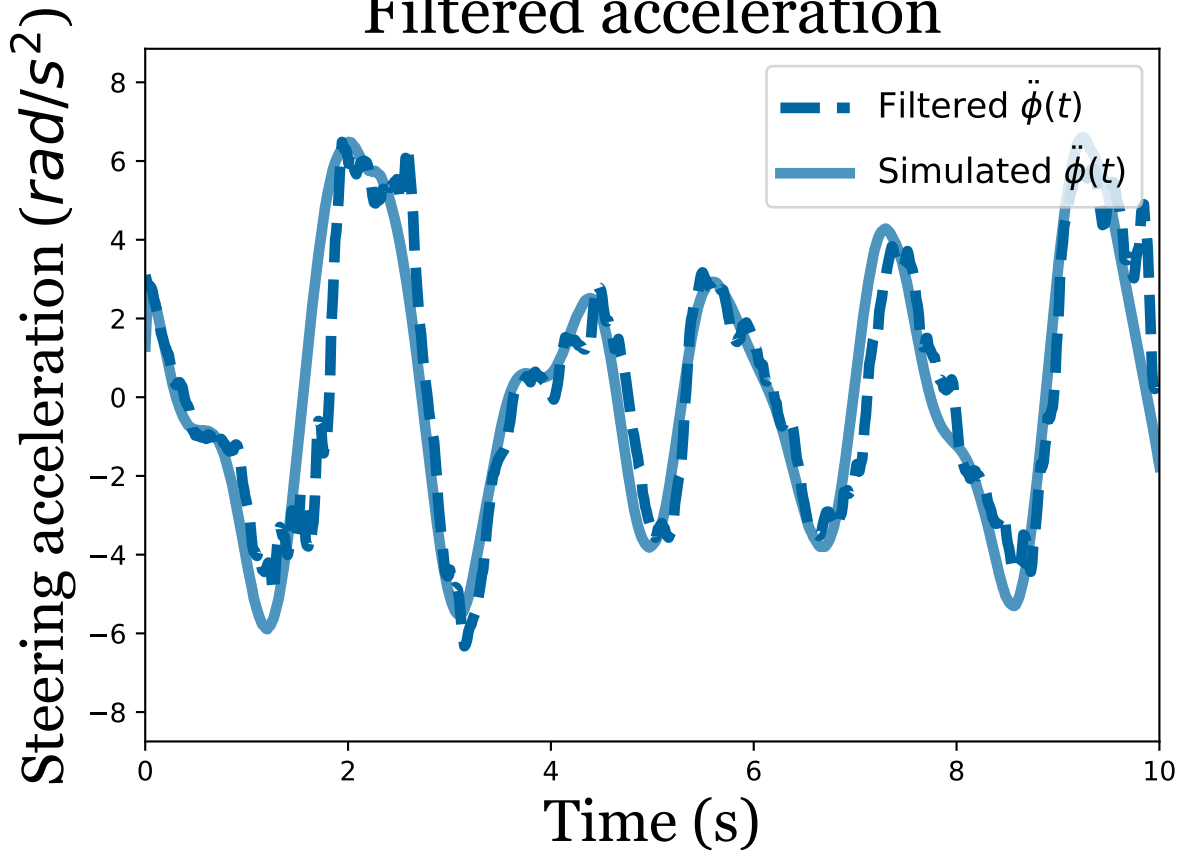
# Time domain reference



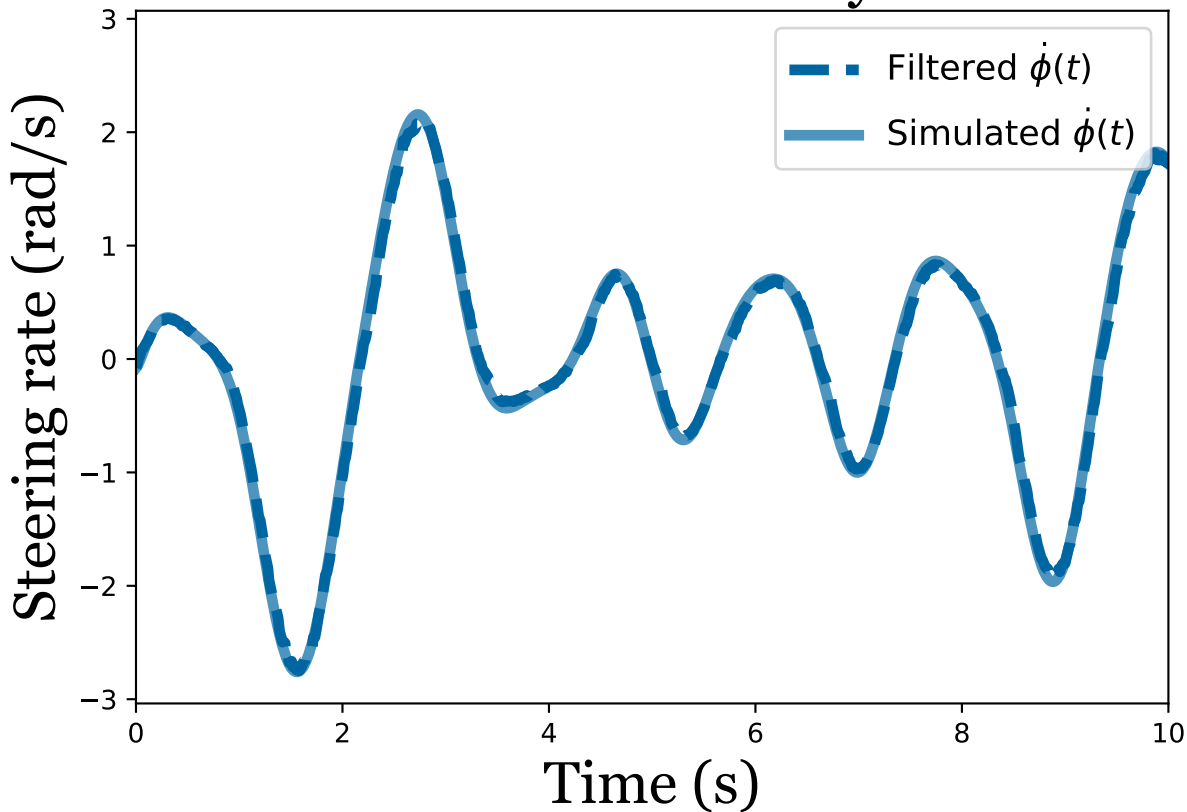
# Measured and estimated steering angle



# Filtered acceleration

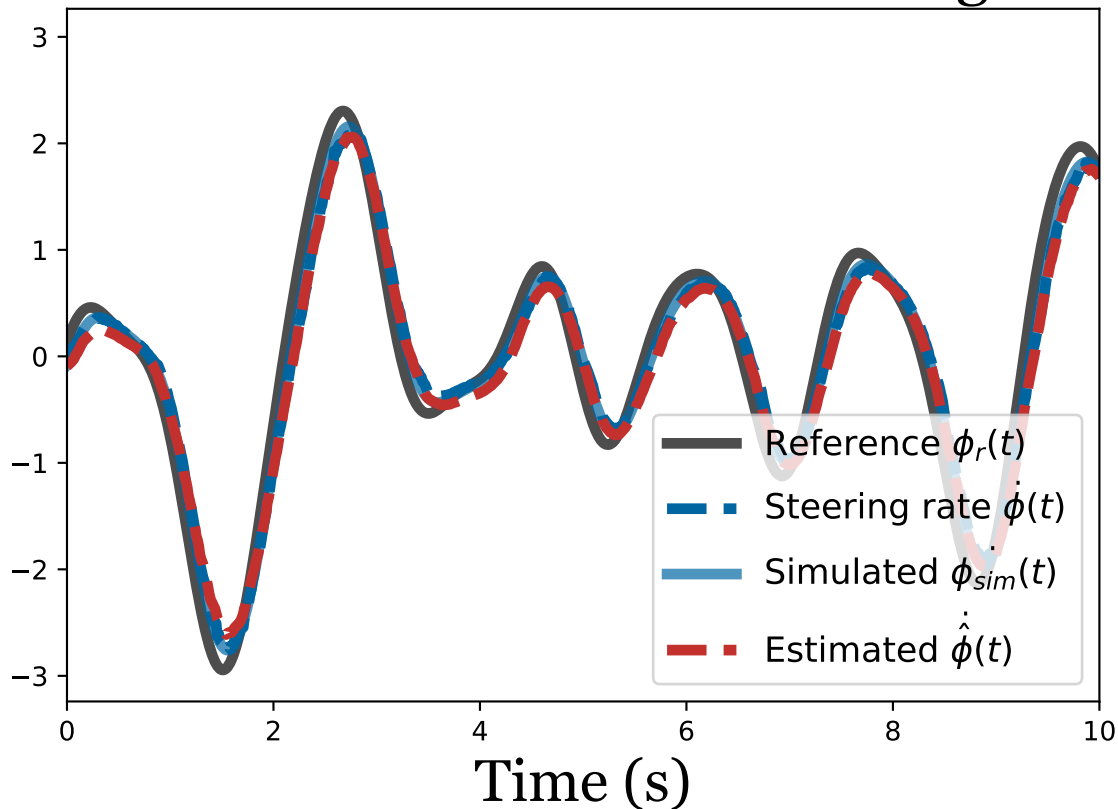


# Filtered velocity

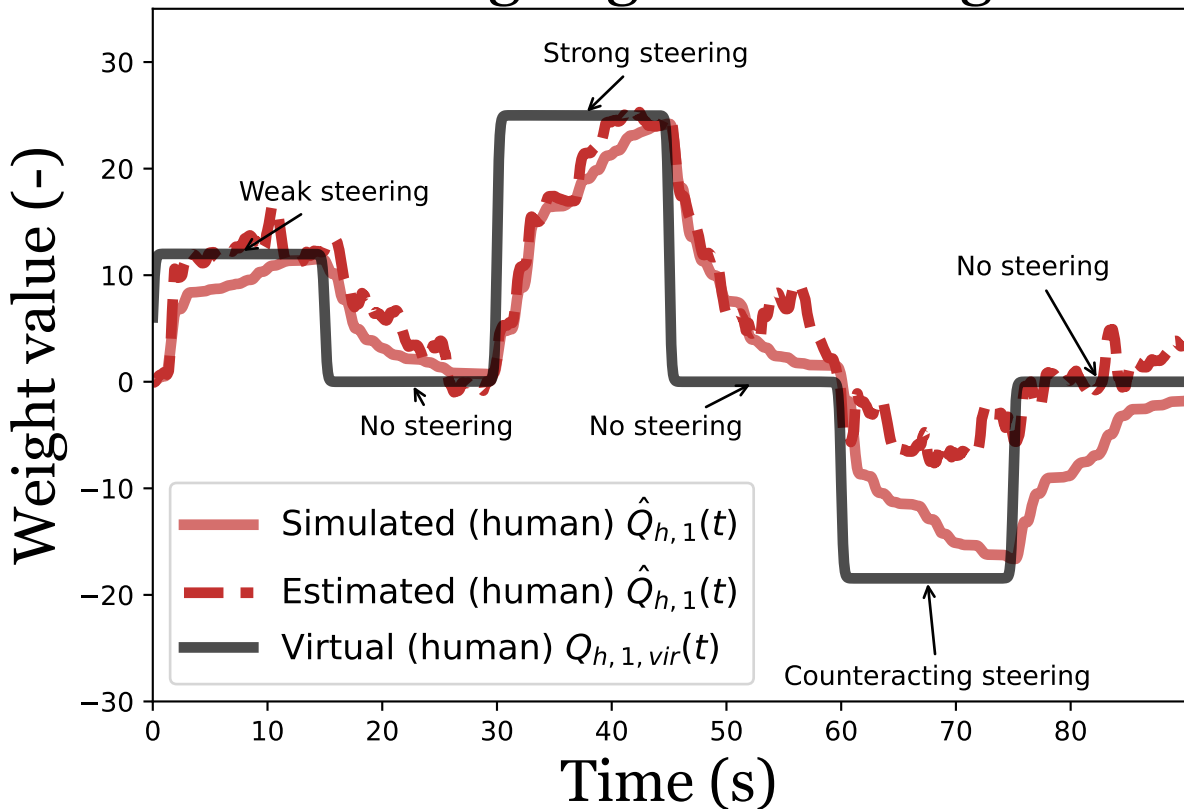


# Measured and estimated steering rate

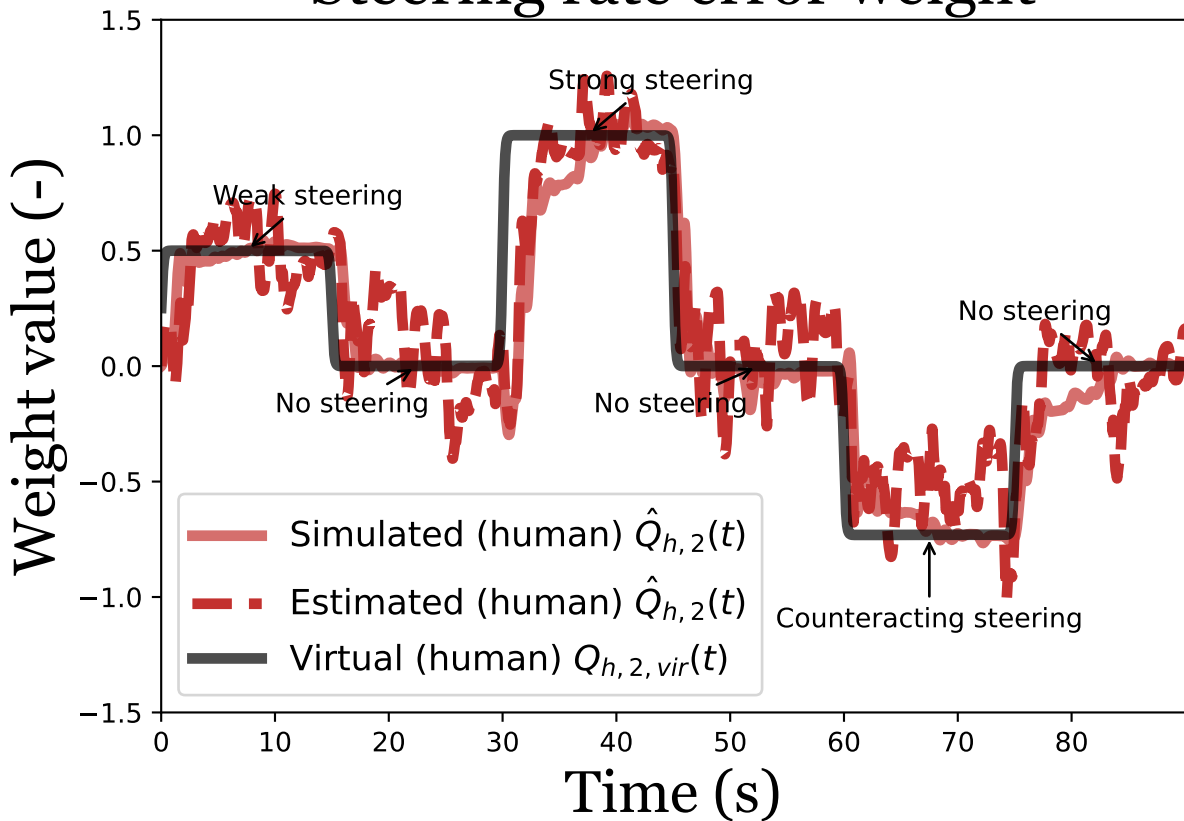
Steering angle (rad)



# Steering angle error weight

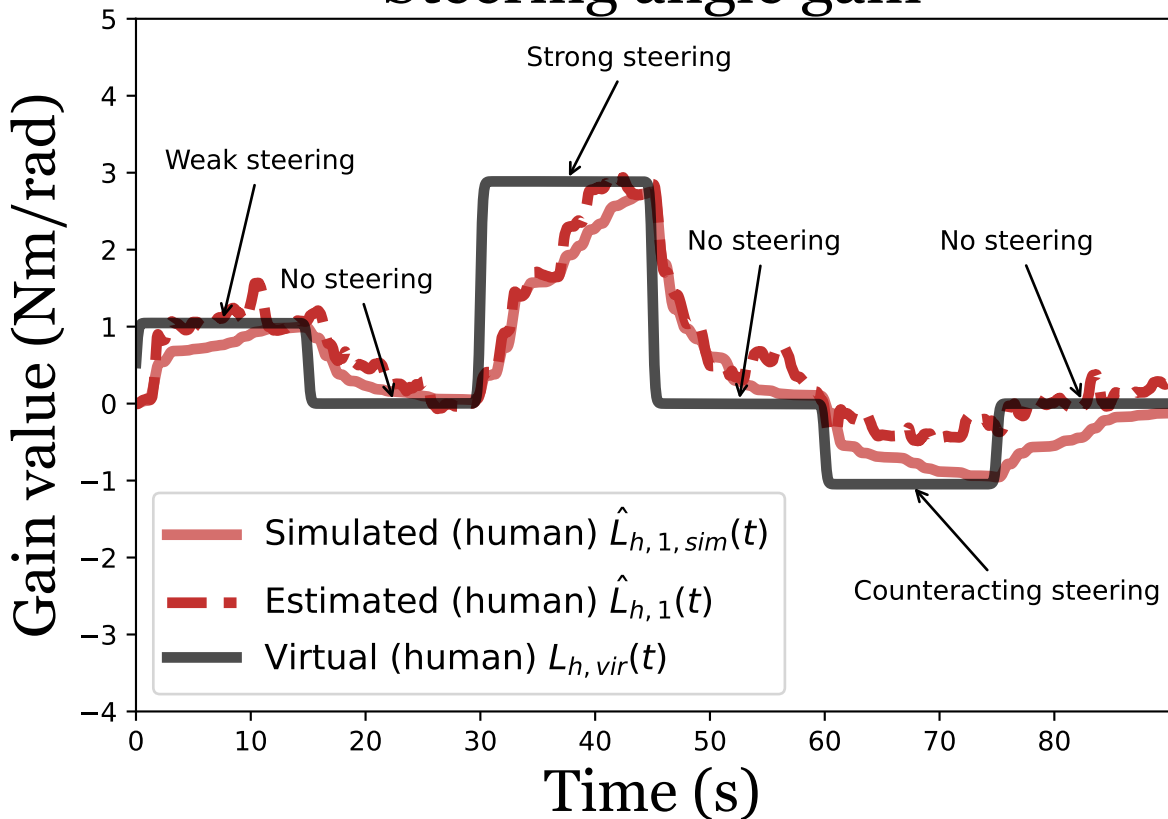


# Steering rate error weight



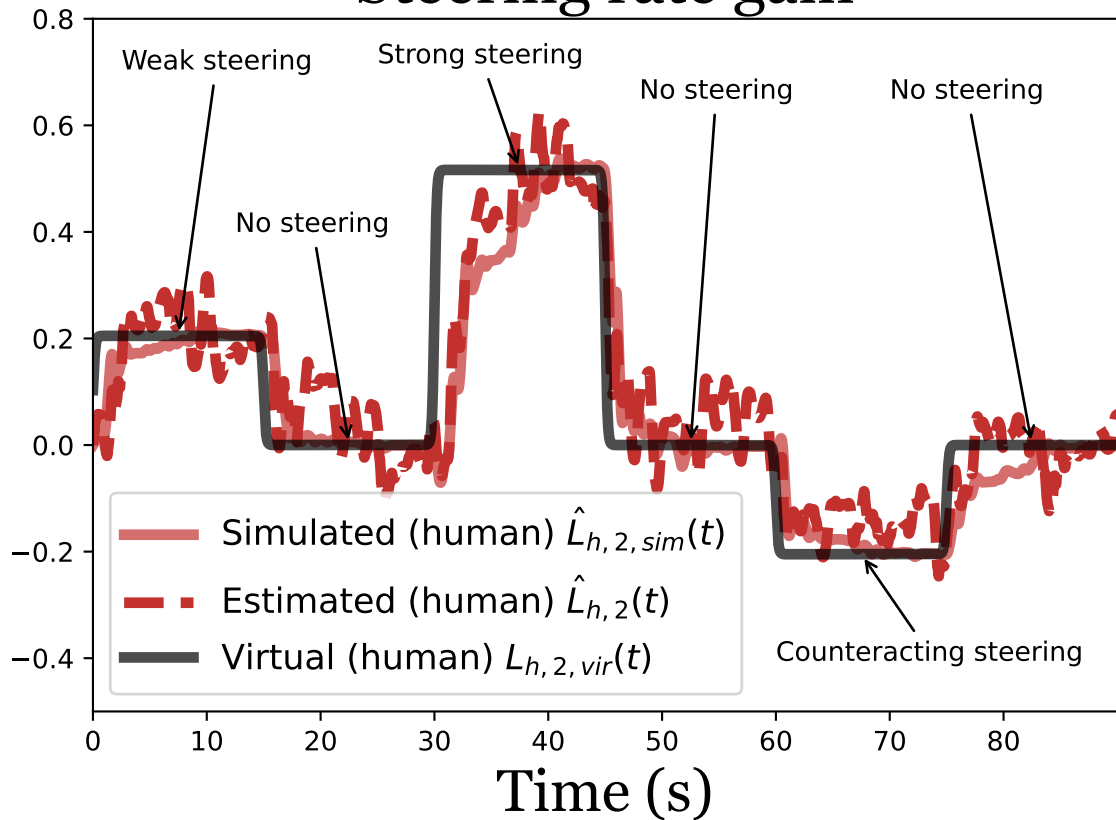


# Steering angle gain

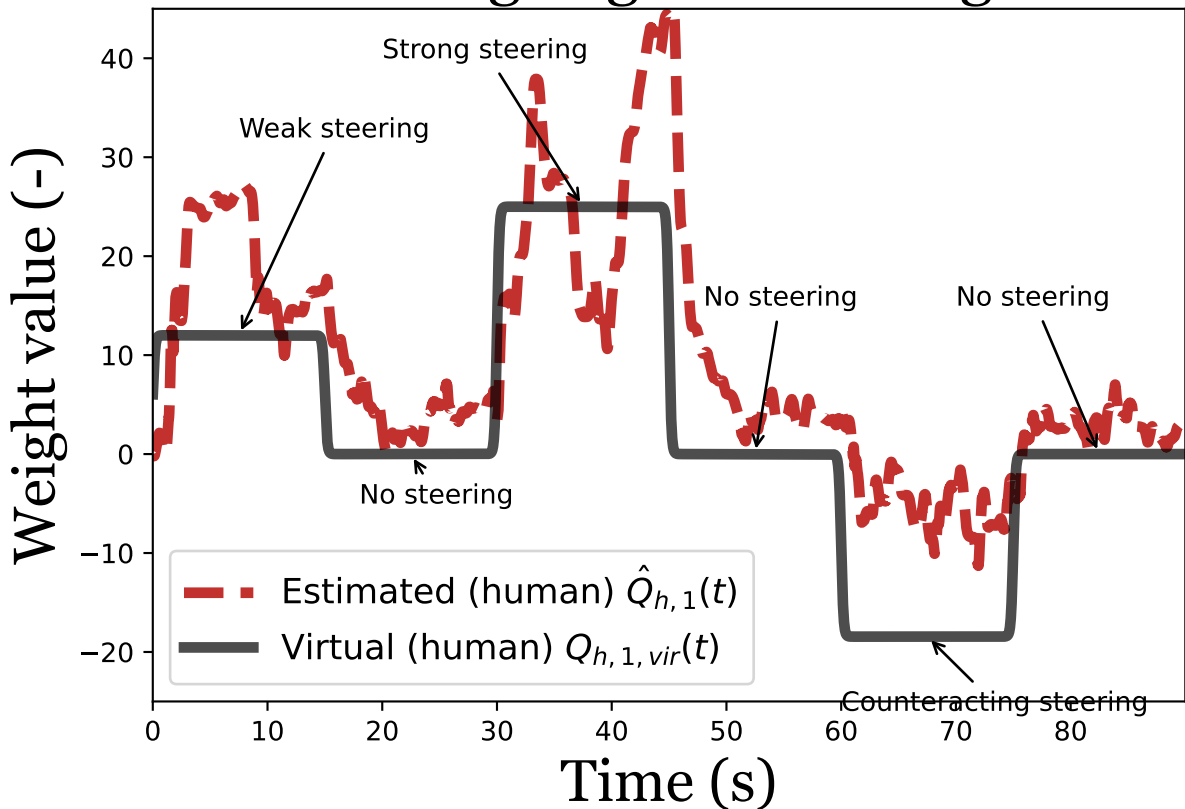


# Steering rate gain

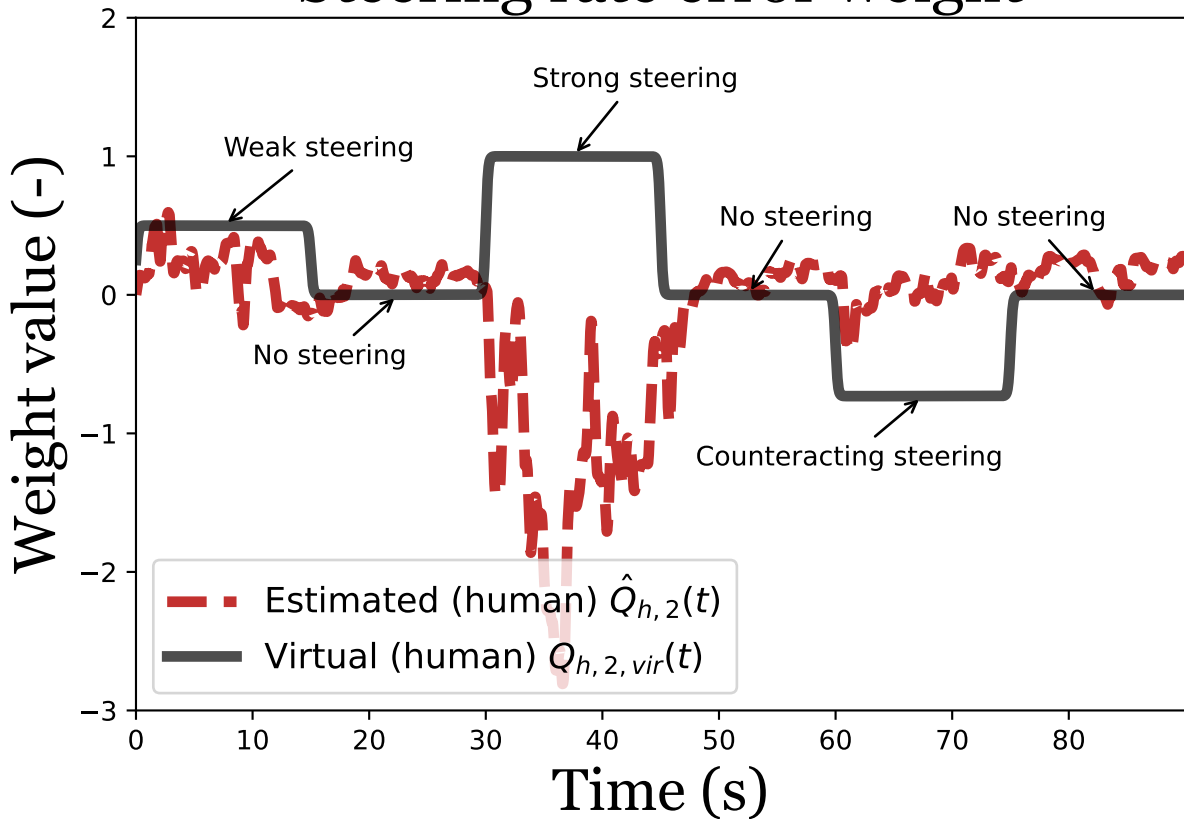
Gain value (Nms/rad)



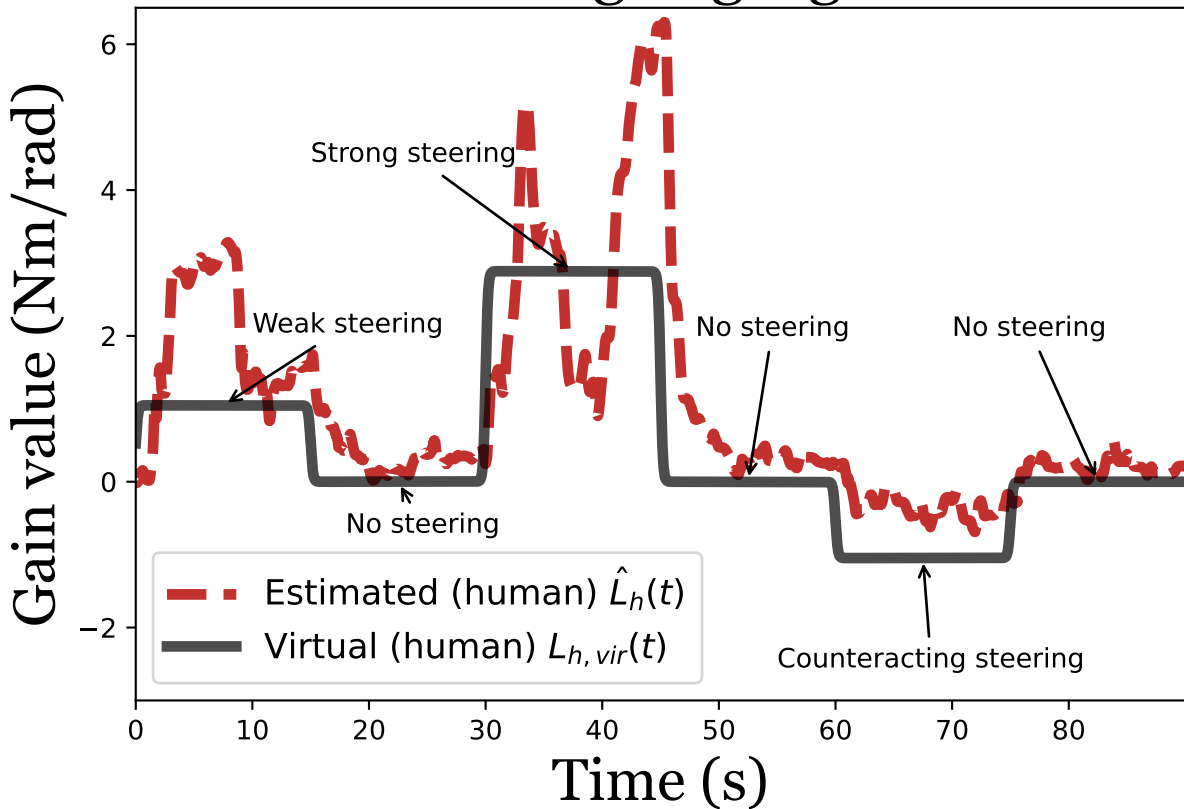
# Steering angle error weight



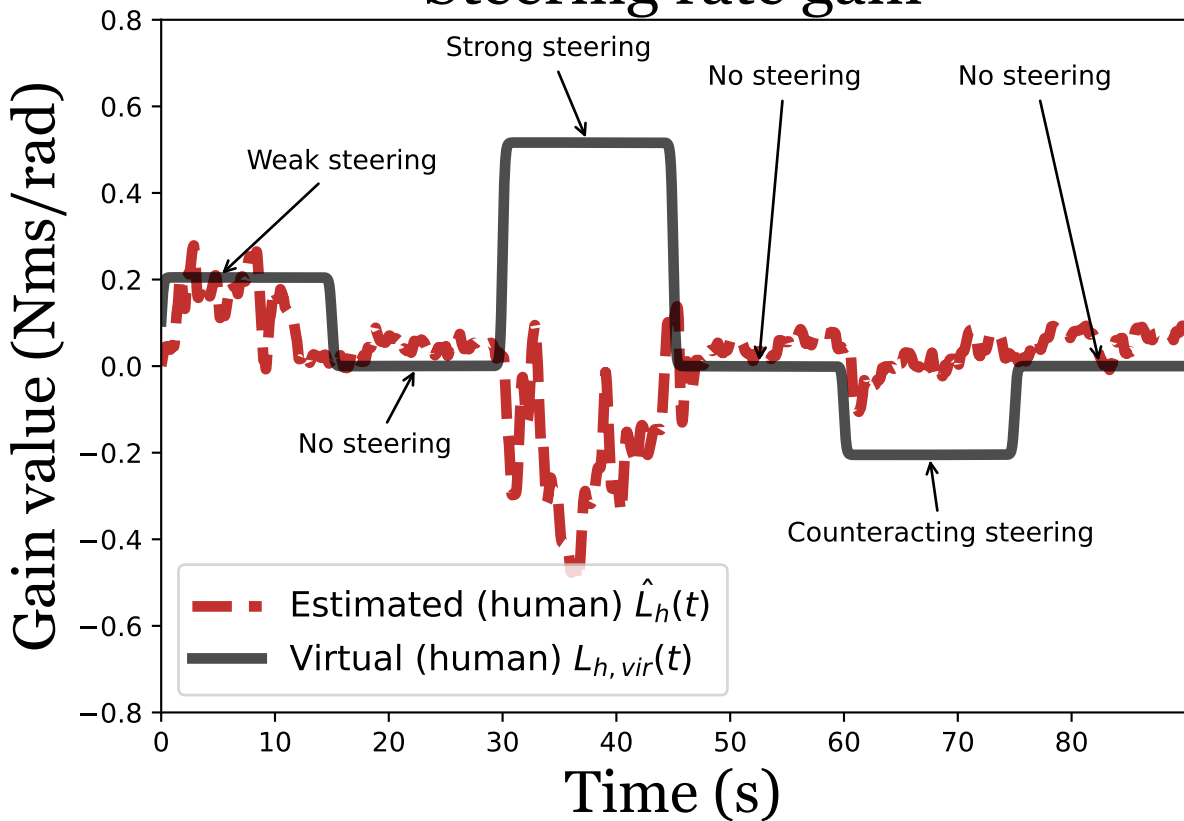
# Steering rate error weight



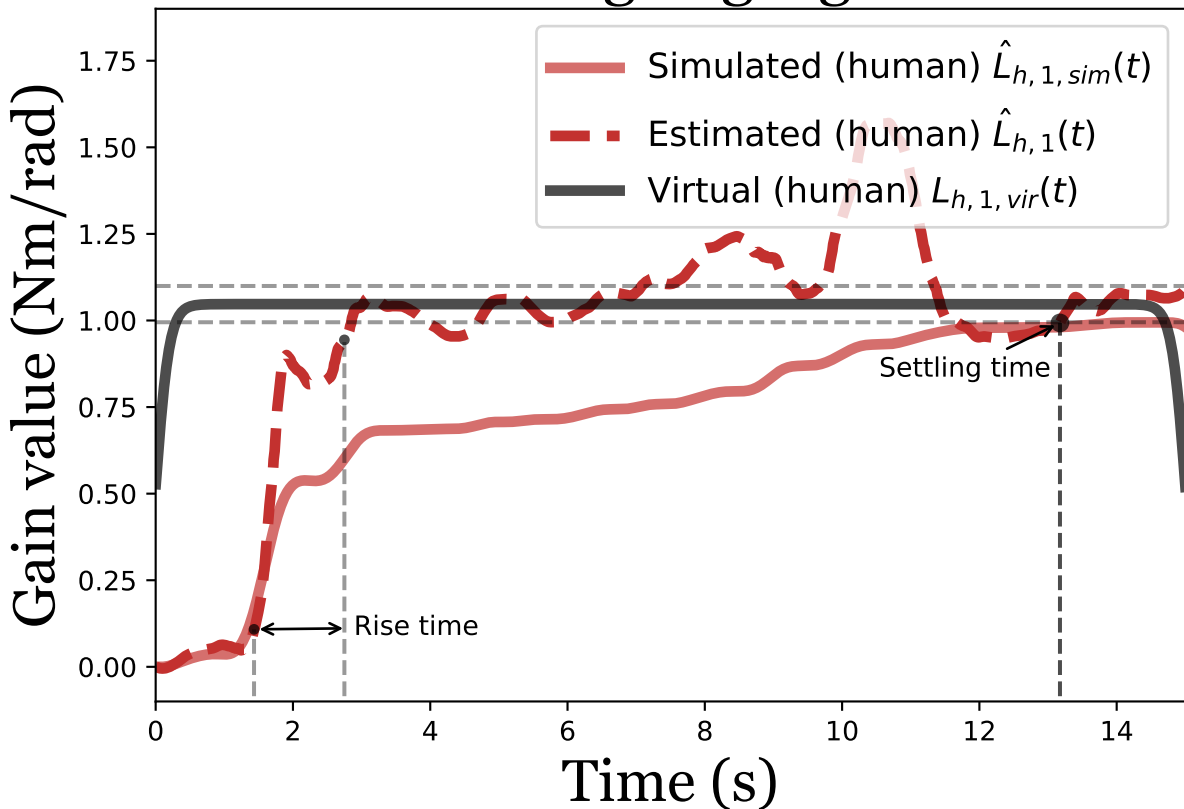
# Steering angle gain



# Steering rate gain



# Steering angle gain



# Steering rate gain

