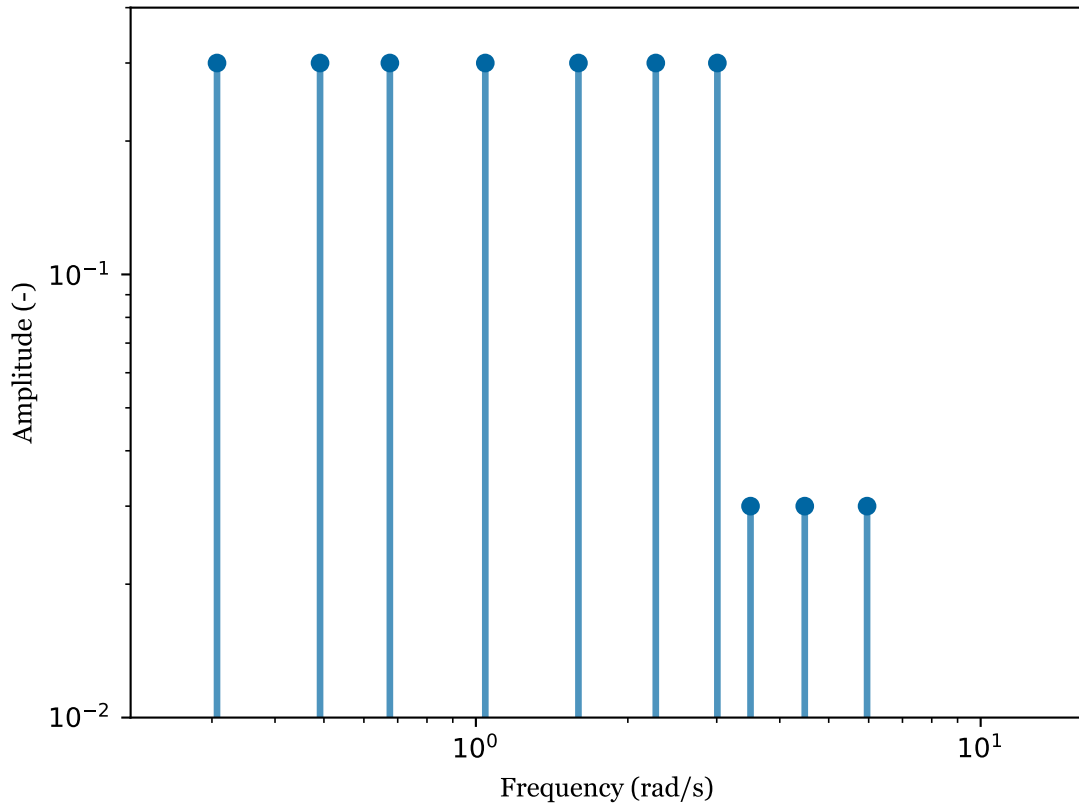
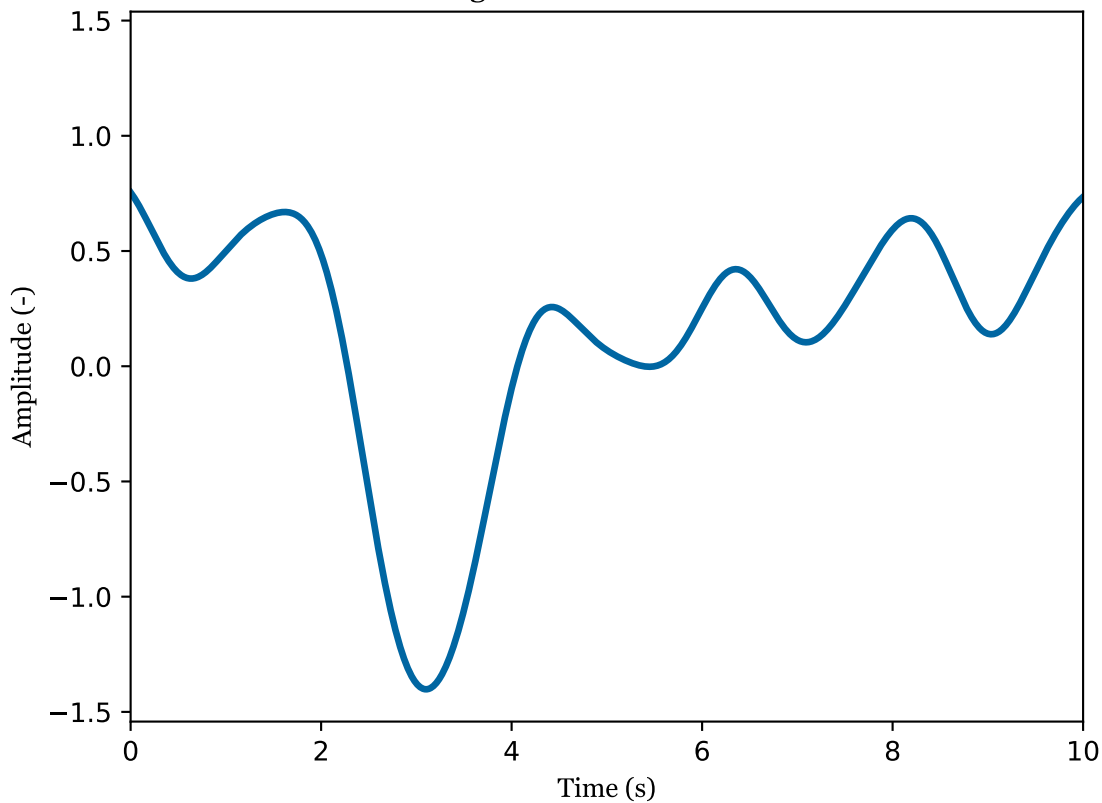


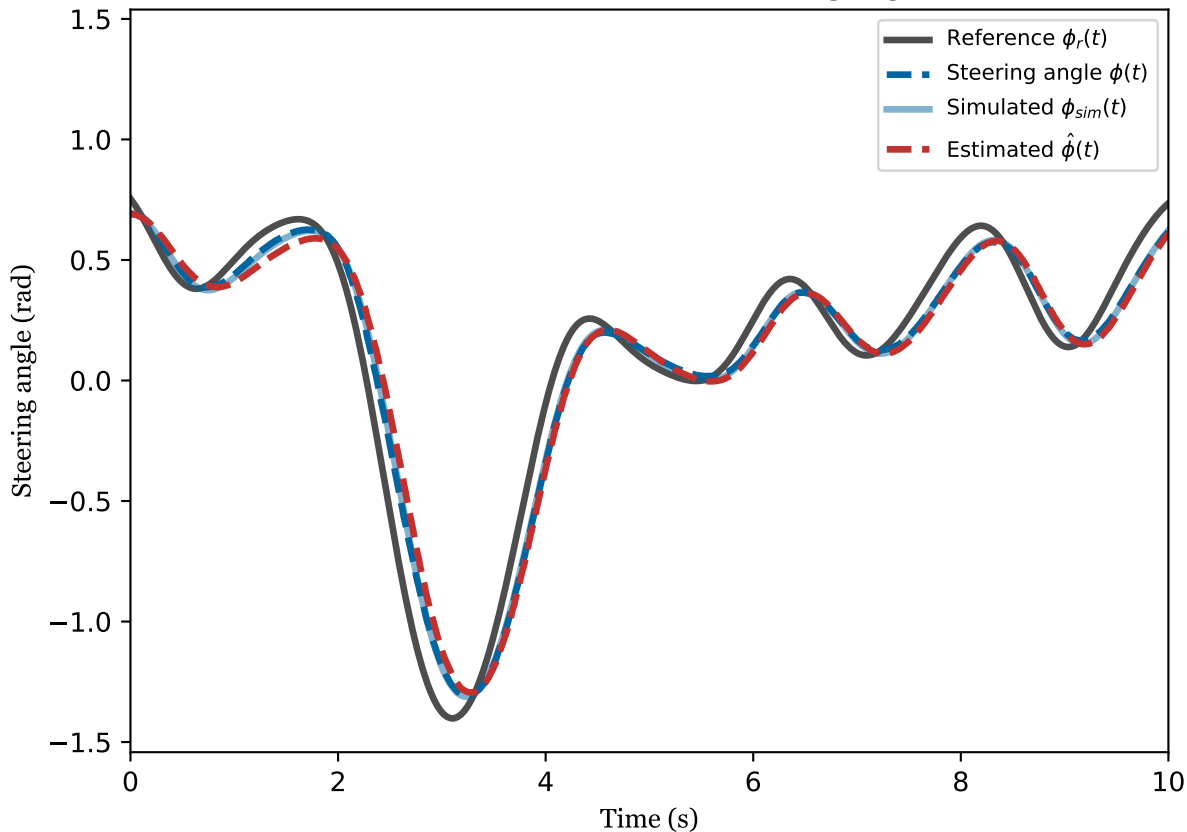
Forcing function in frequency domain



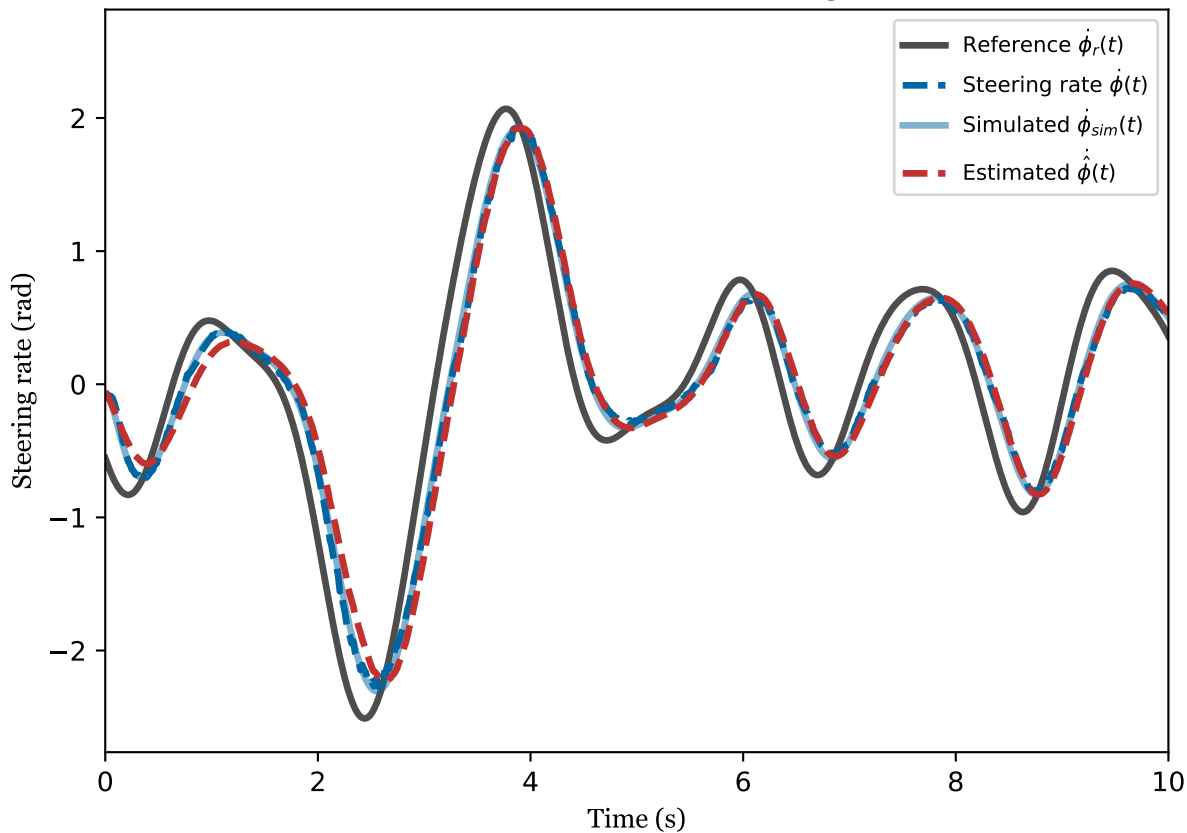
Forcing function in time domain



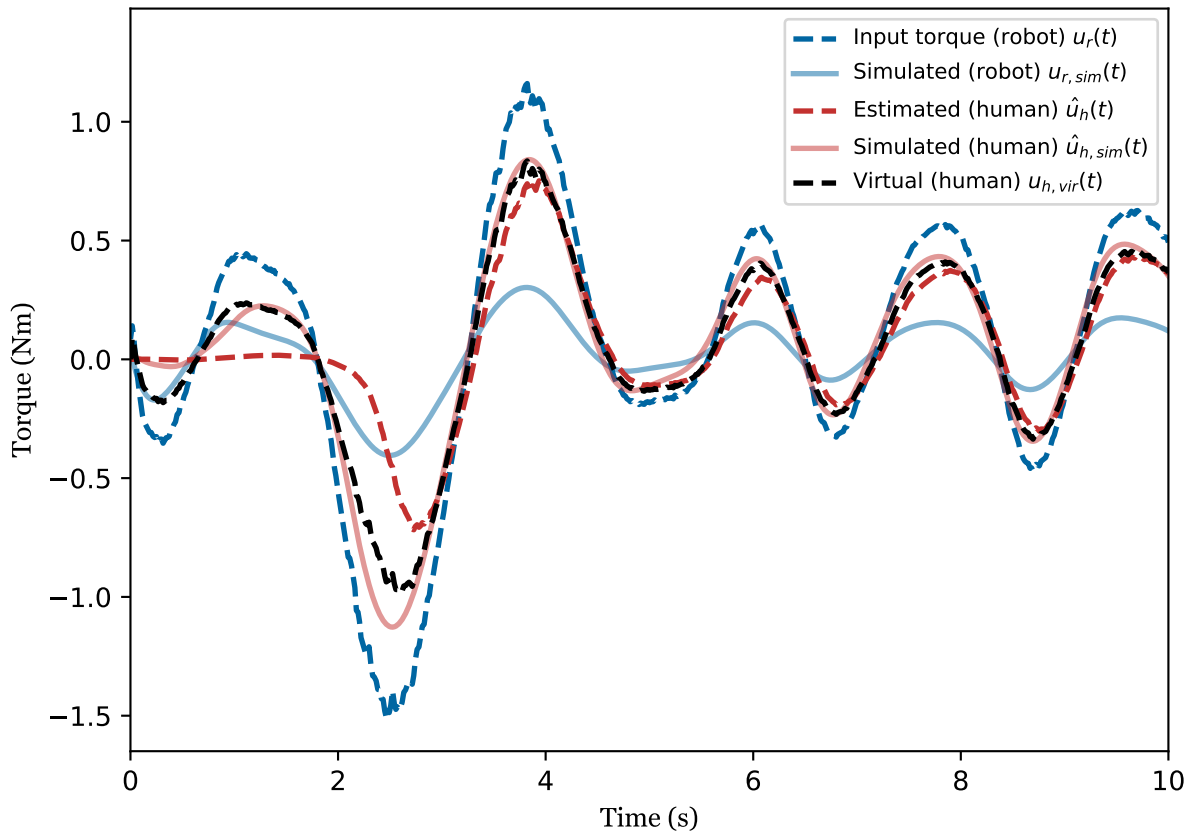
Measured and estimated steering angle



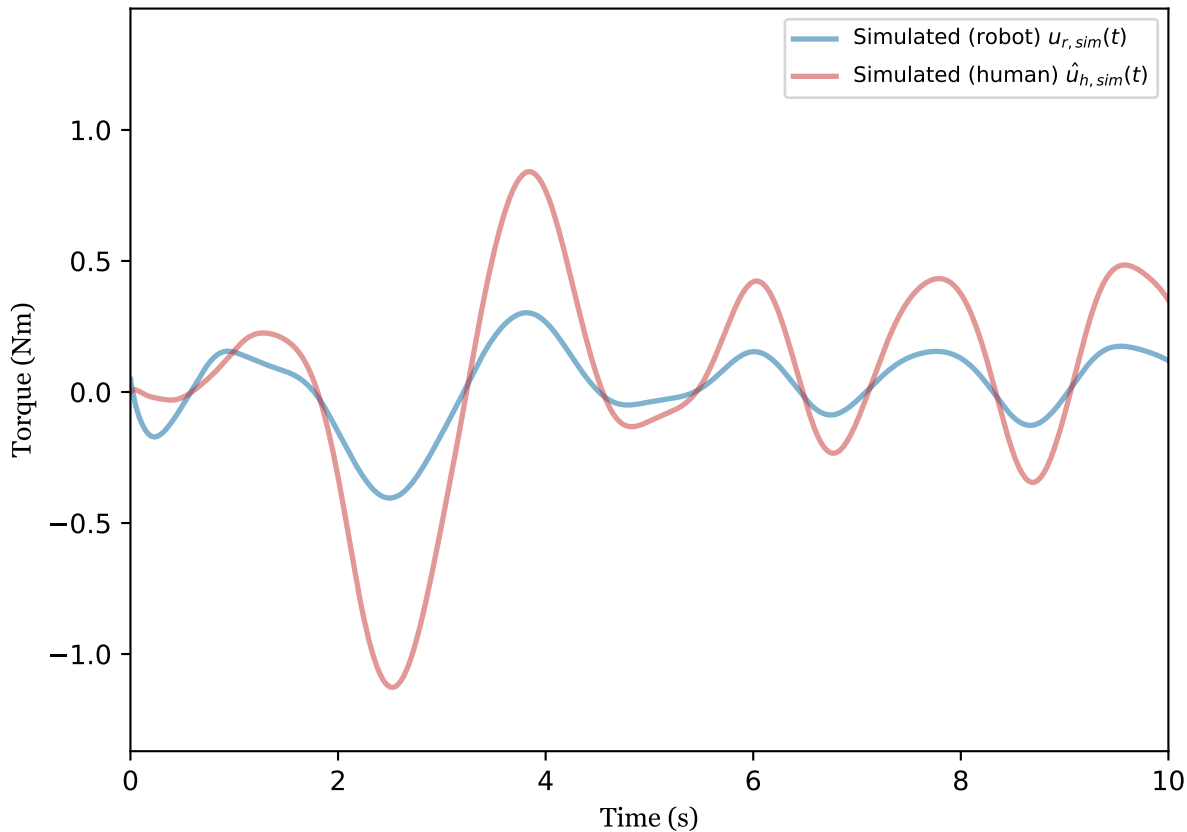
Measured and estimated steering rate



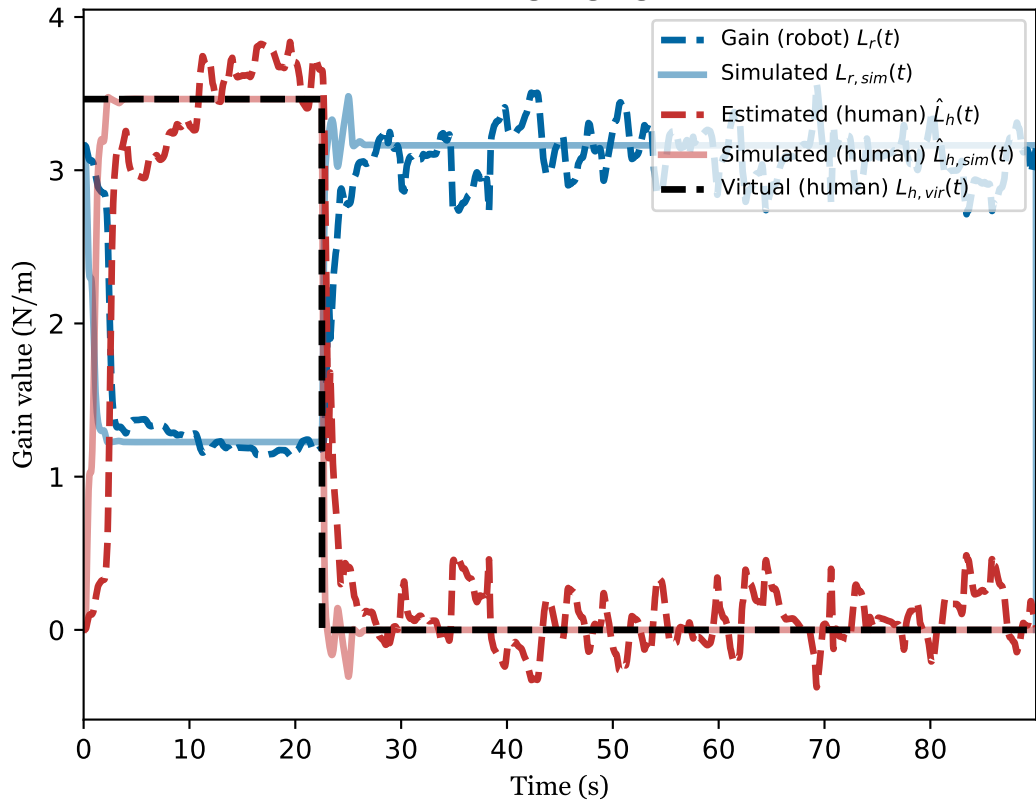
Input torque



Input torque



Steering angle gain



Steering rate gain

