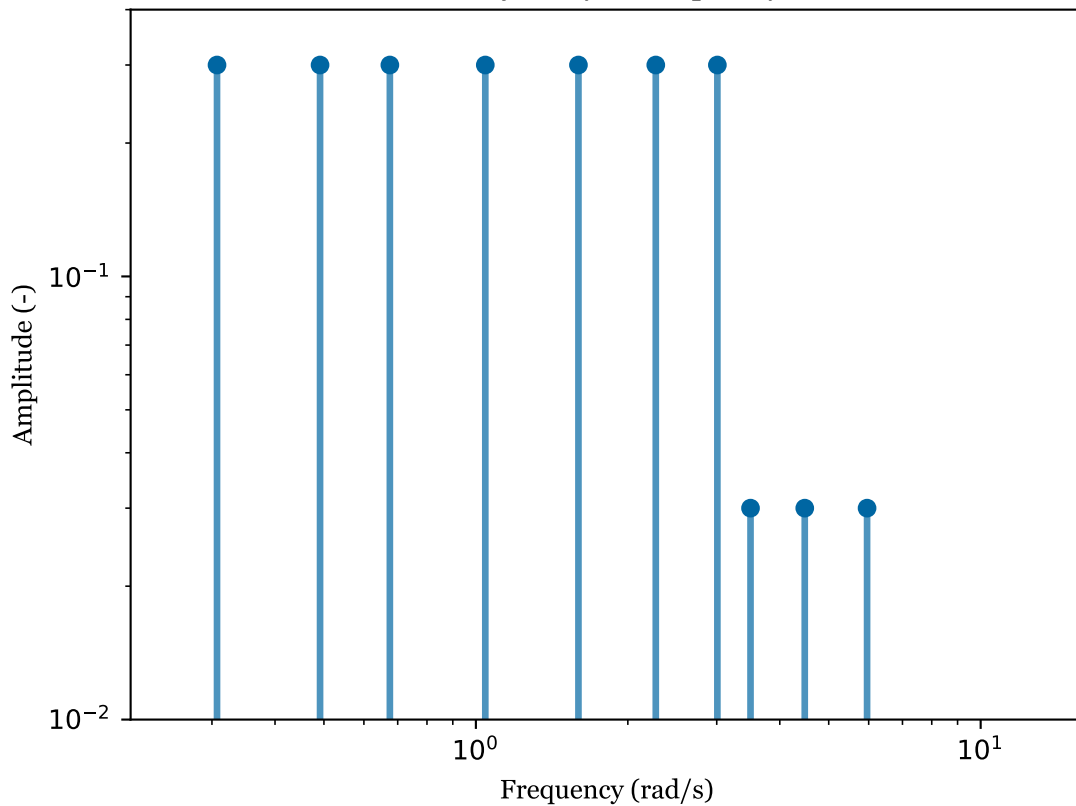
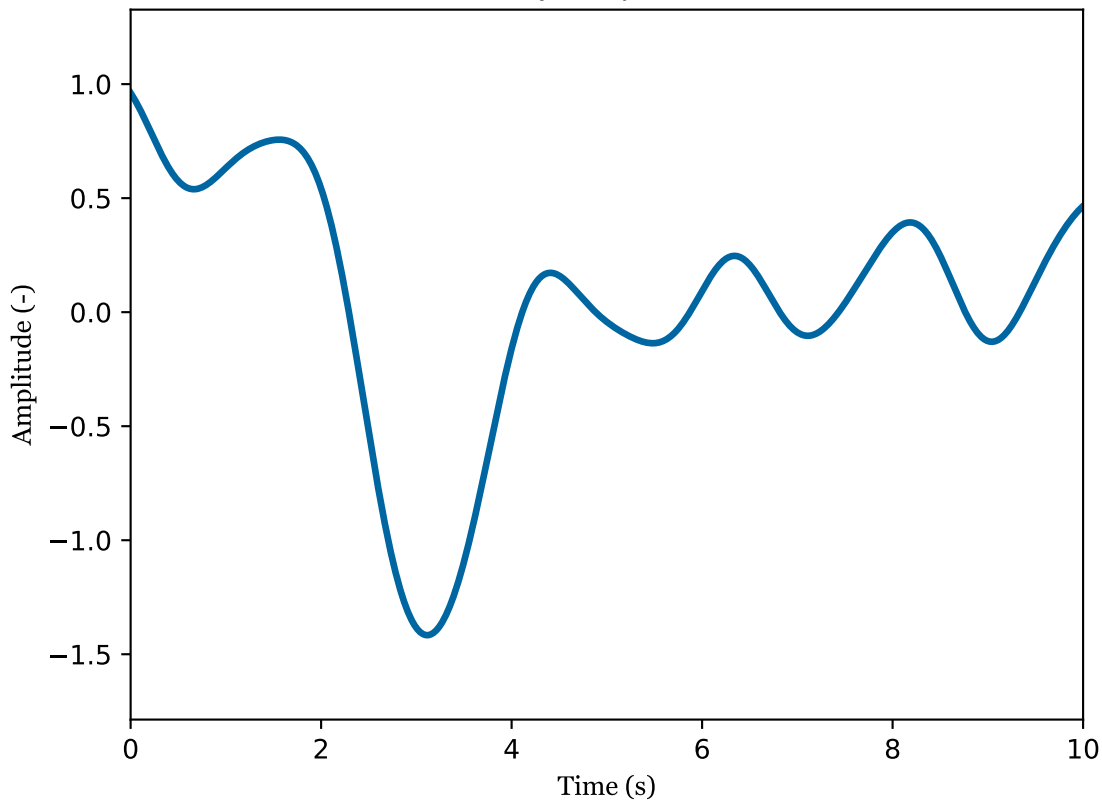


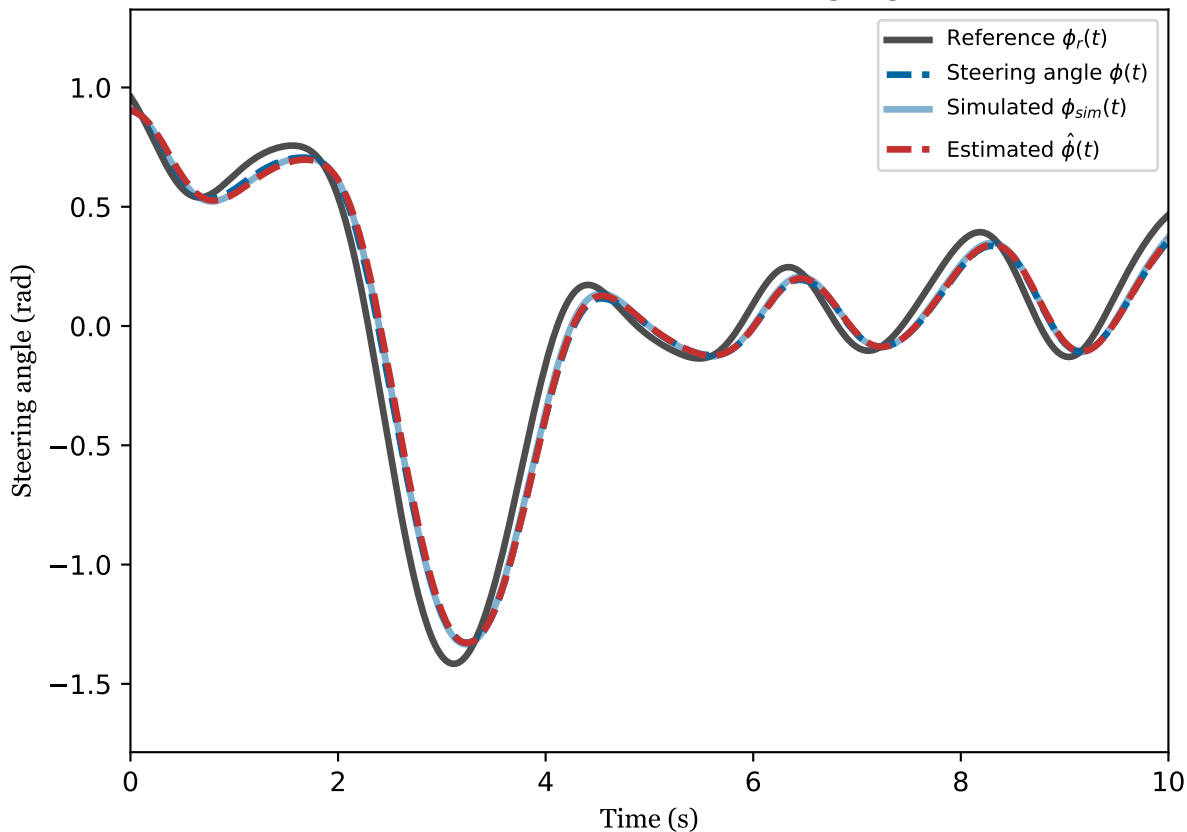
Reference trajectory in frequency domain



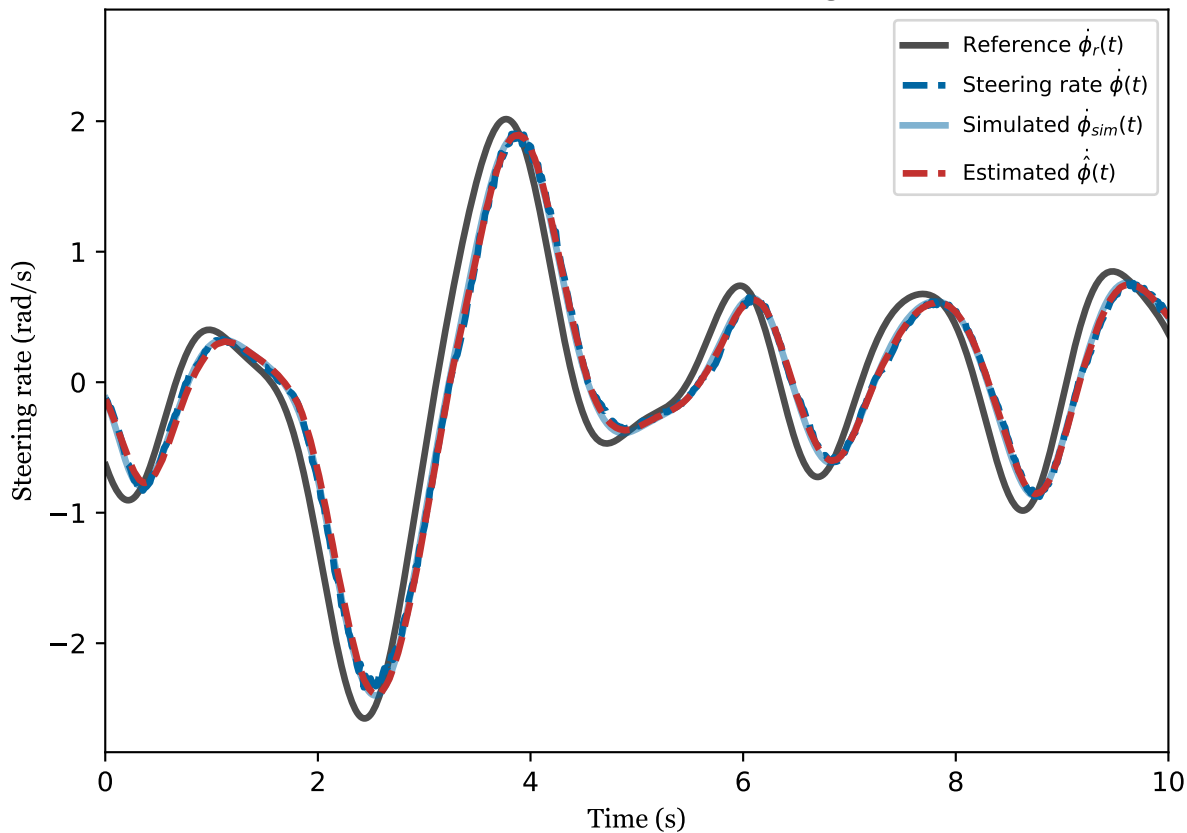
Reference trajectory in time domain



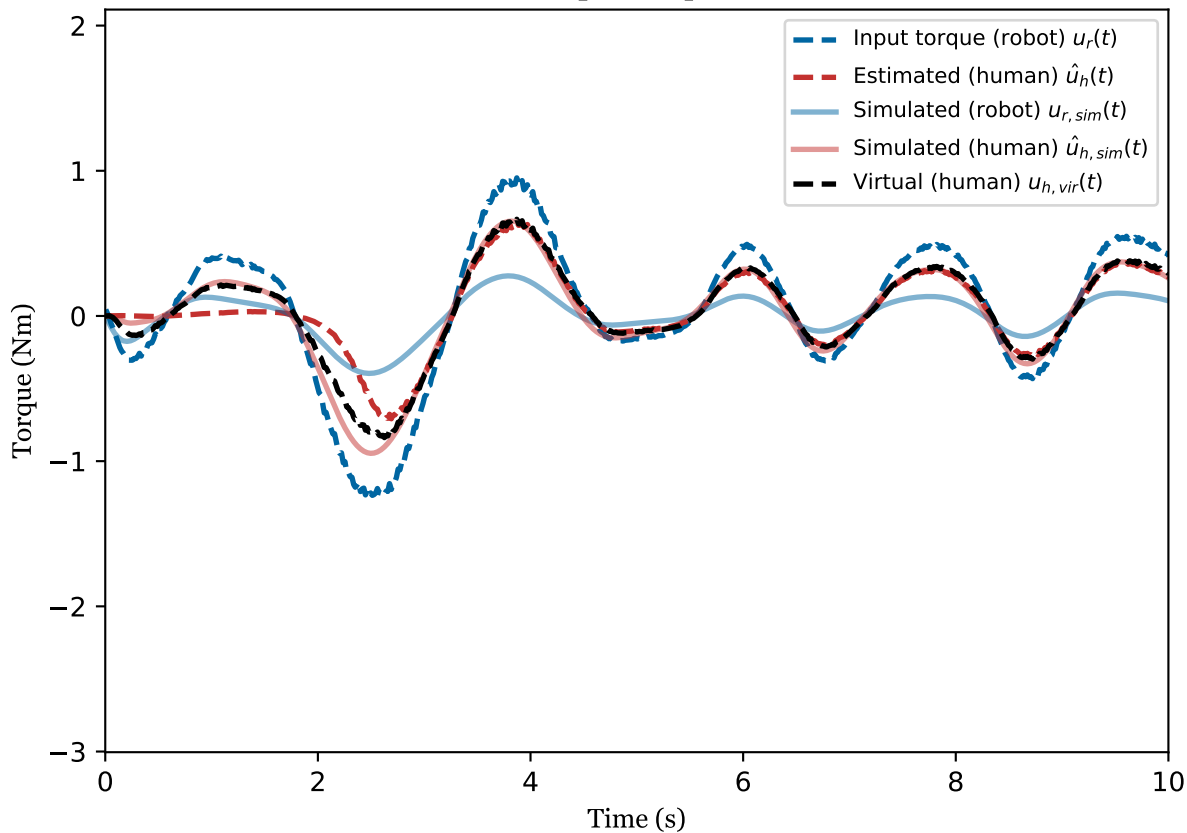
Measured and estimated steering angle



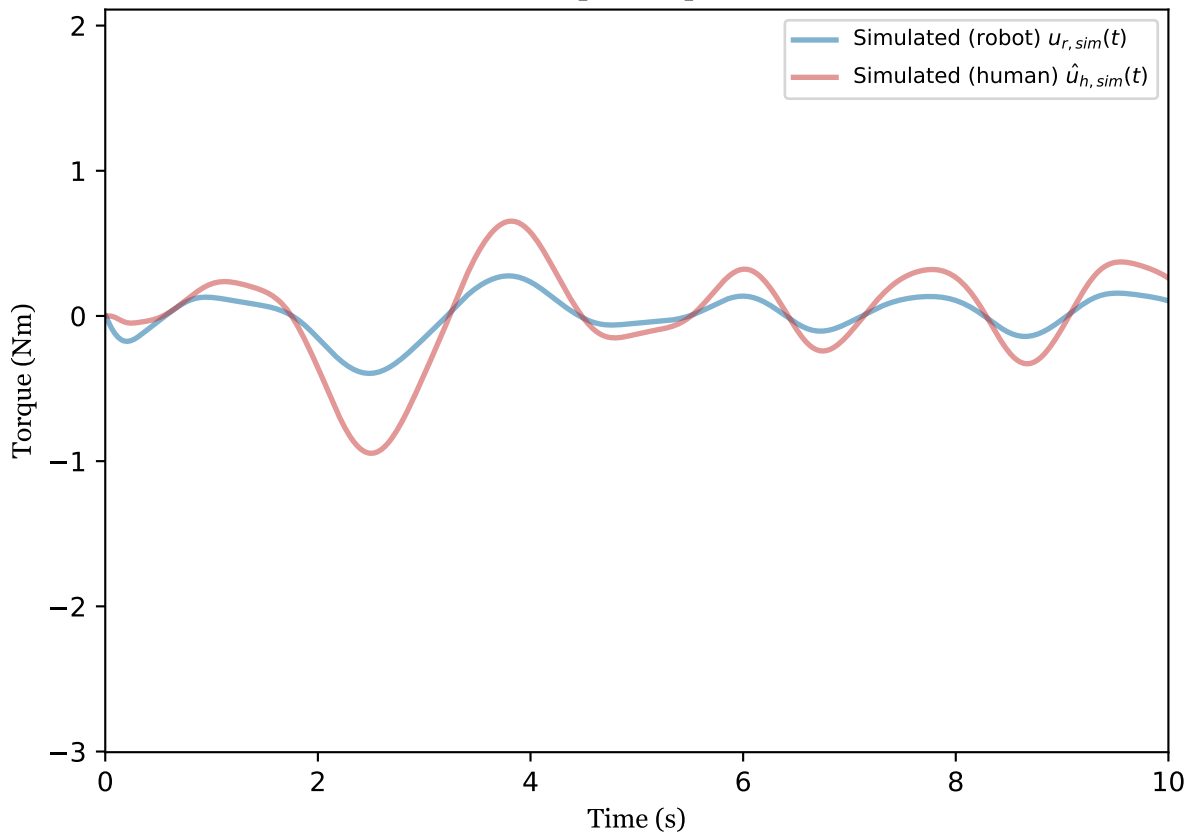
Measured and estimated steering rate



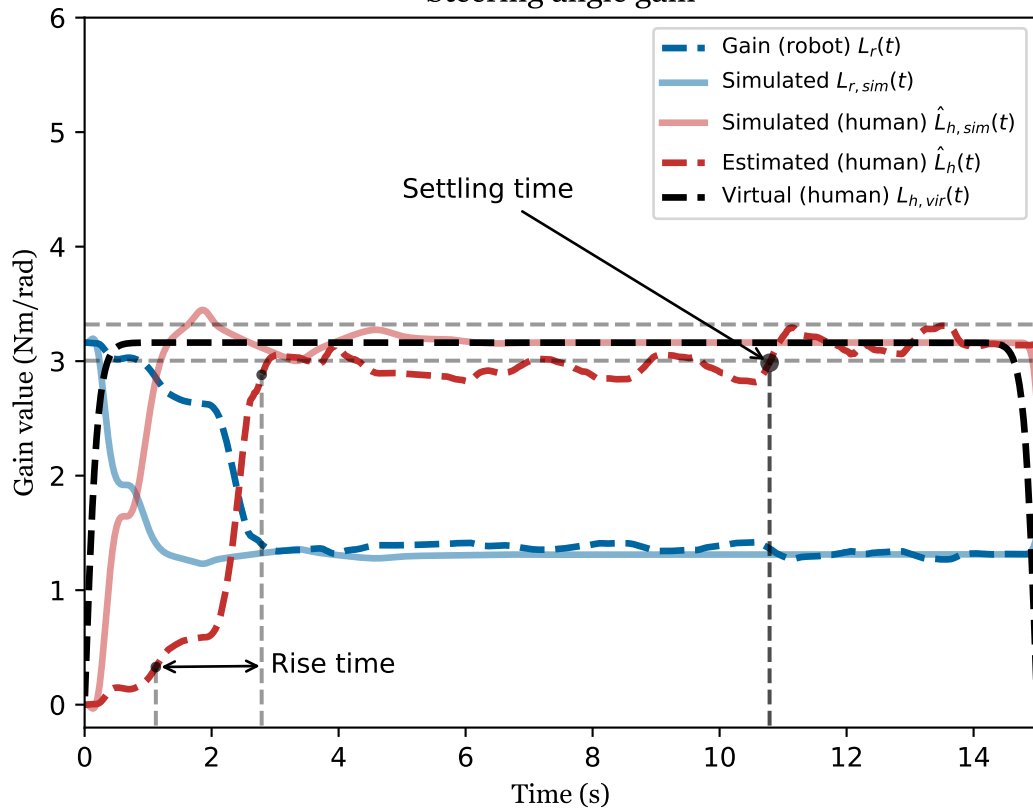
Input torque



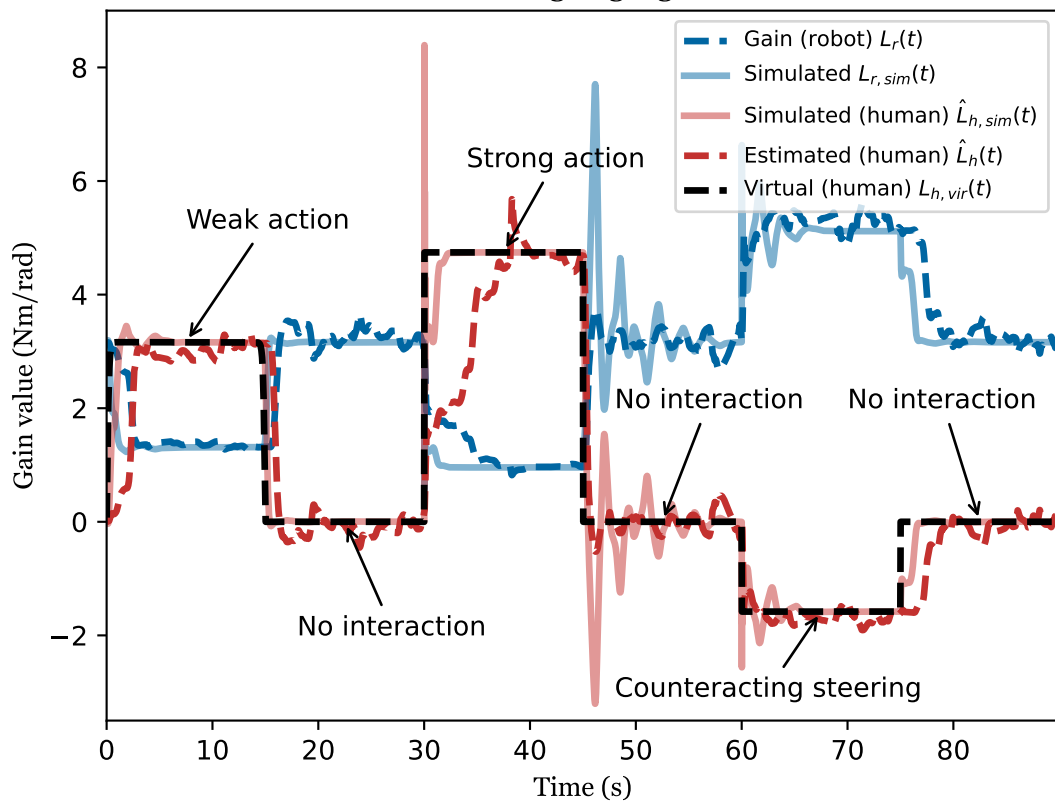
Input torque



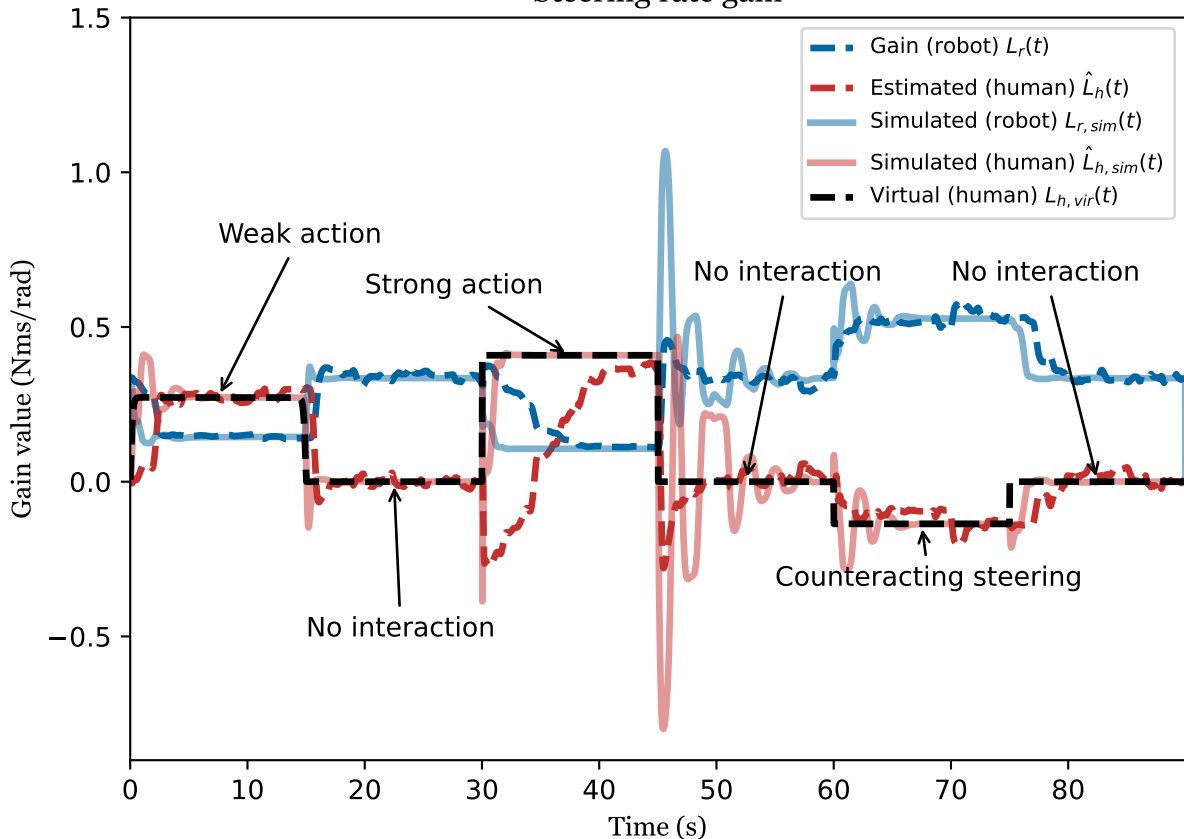
Steering angle gain



Steering angle gain



Steering rate gain



Steering rate gain

