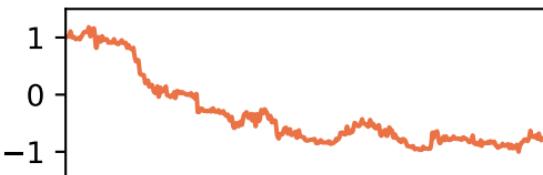
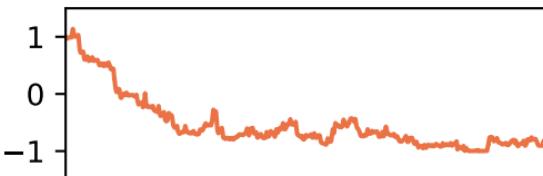
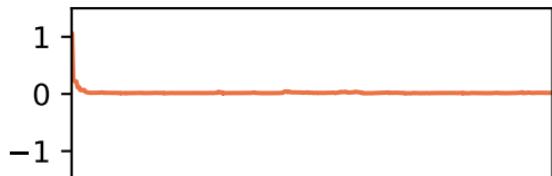
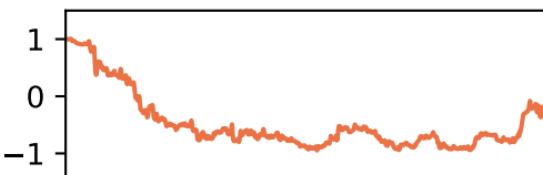
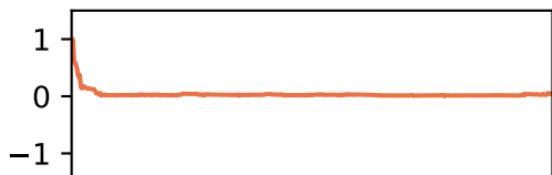
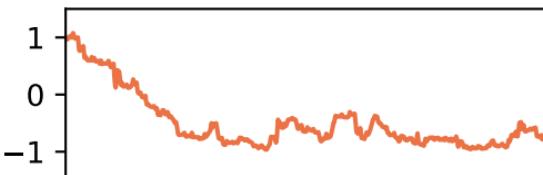


Estimated Control Authority

Positive Re.

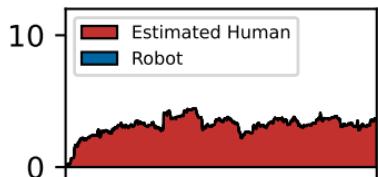
Negative Re.



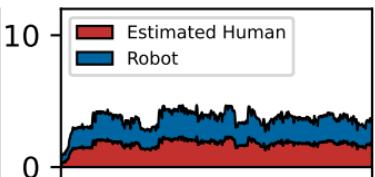
Time (s)

Time (s)

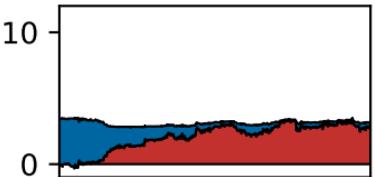
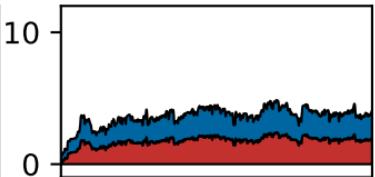
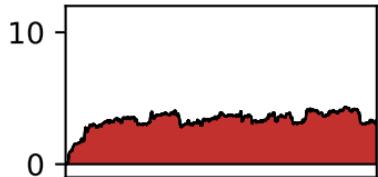
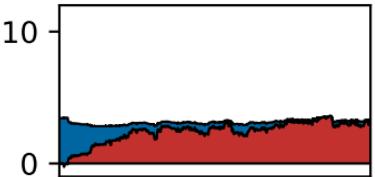
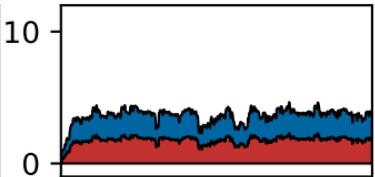
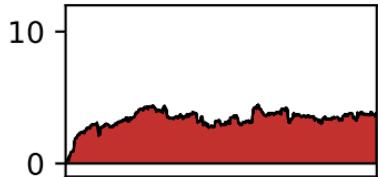
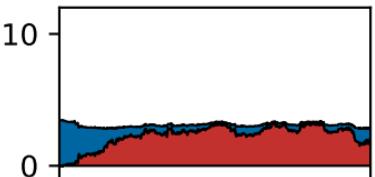
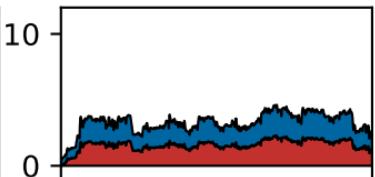
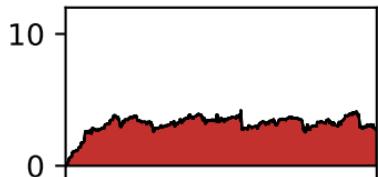
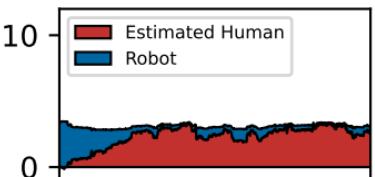
Manual
Control



Gains
Positive Re.



Negative Re.

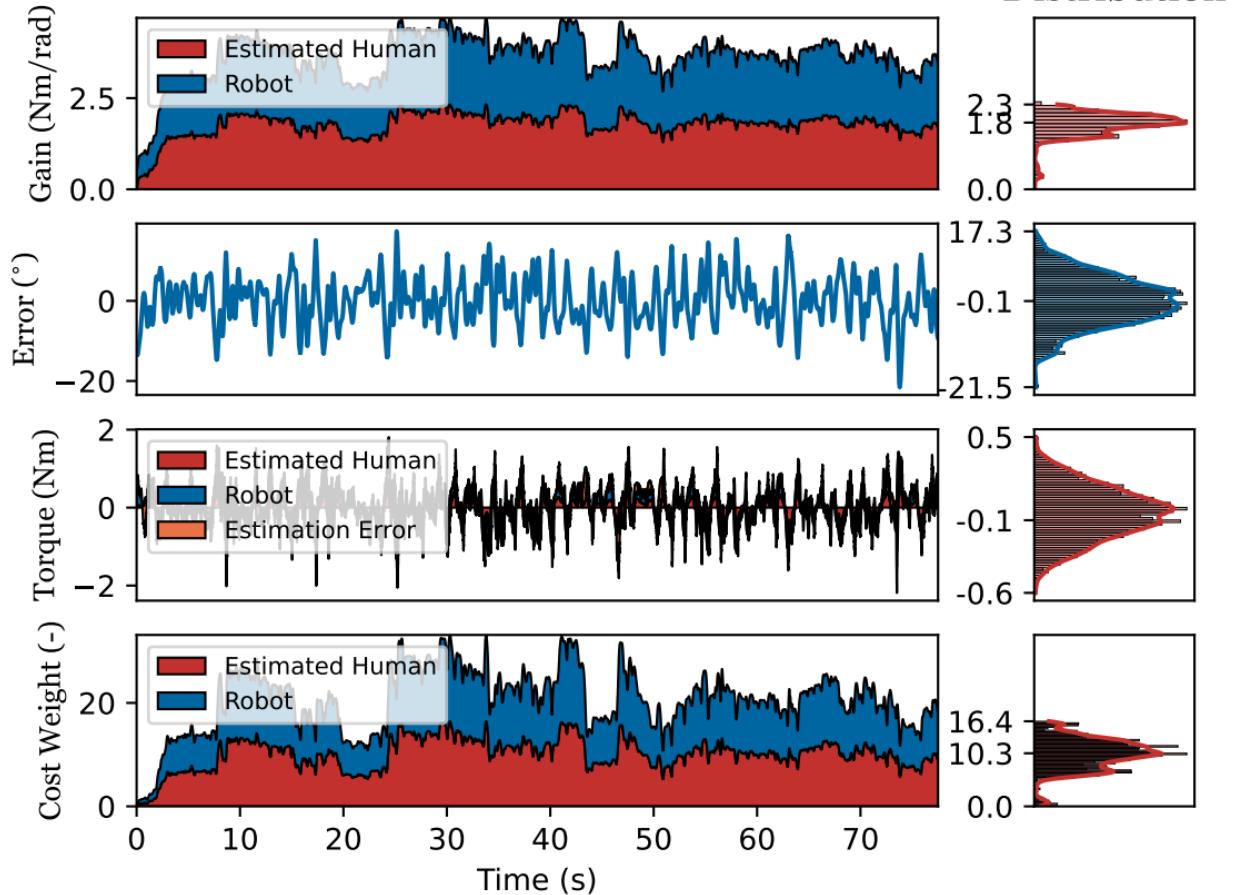


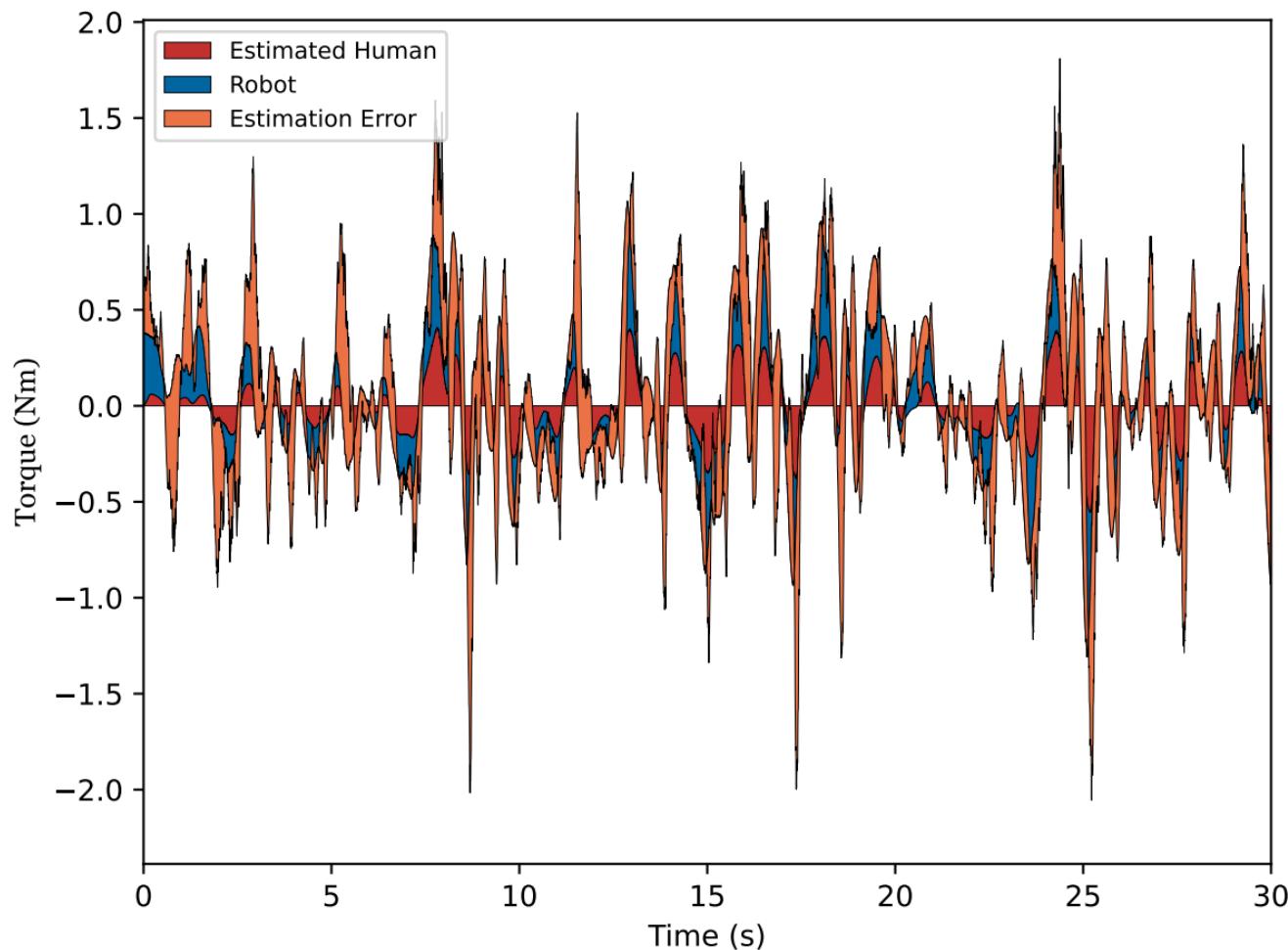
Time (s)

Time (s)

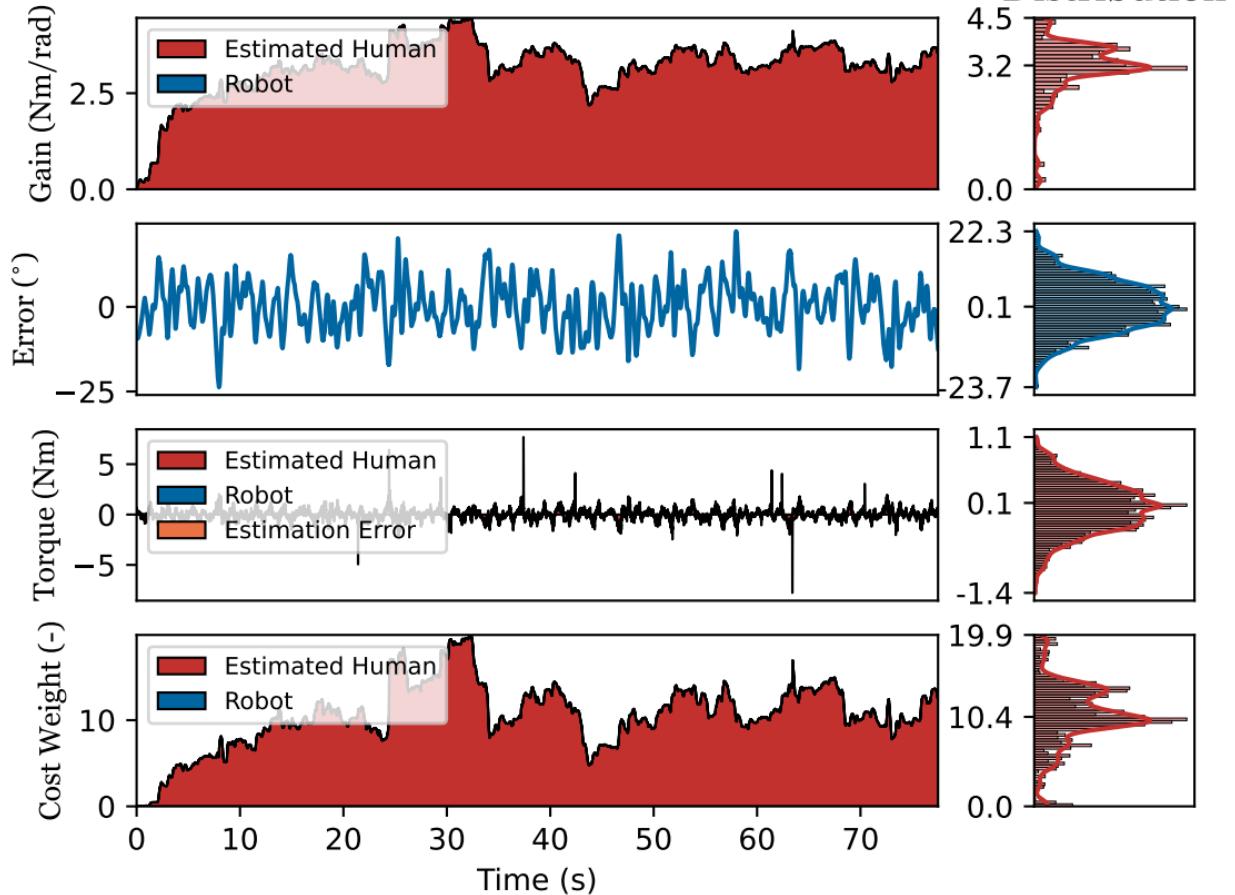
Time (s)

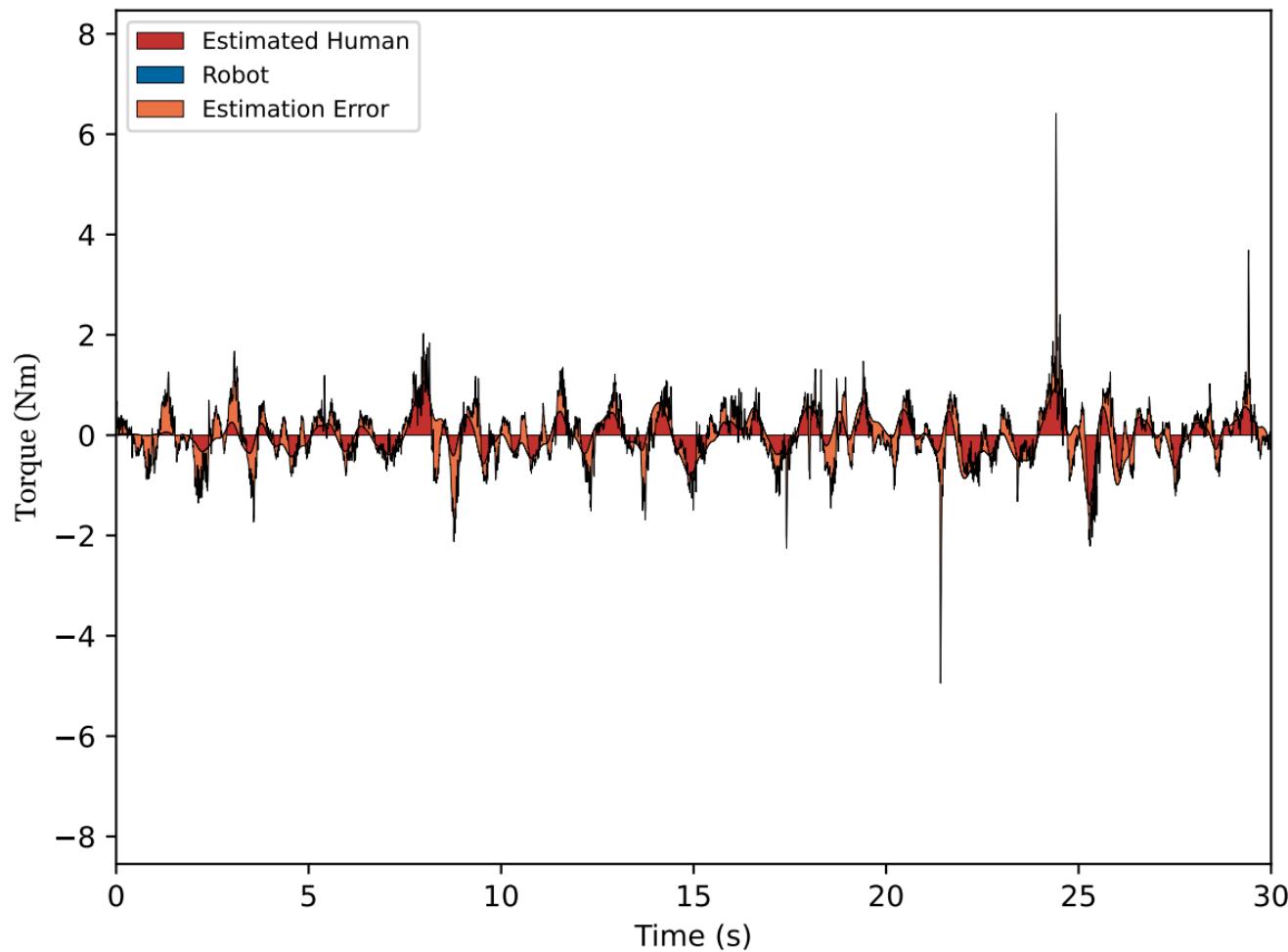
Positive Reinforcement



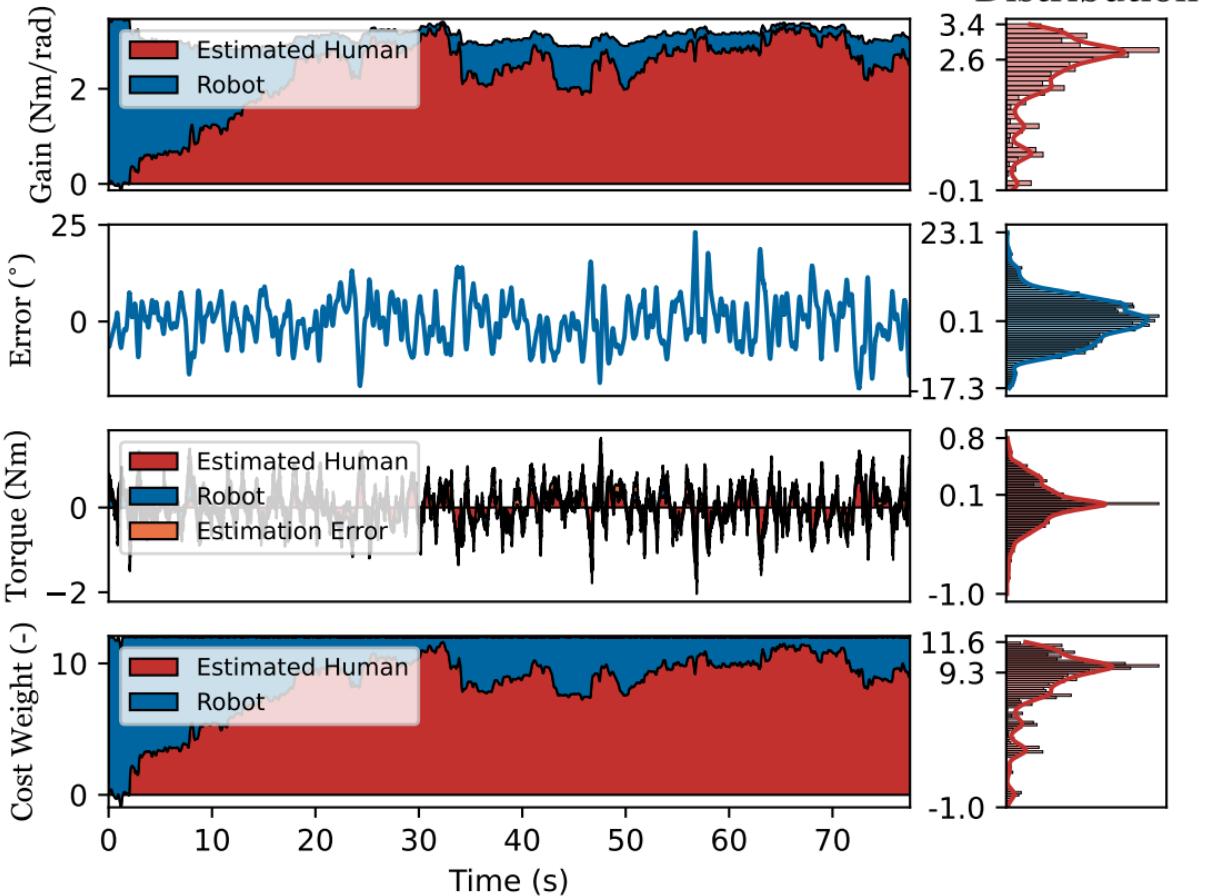


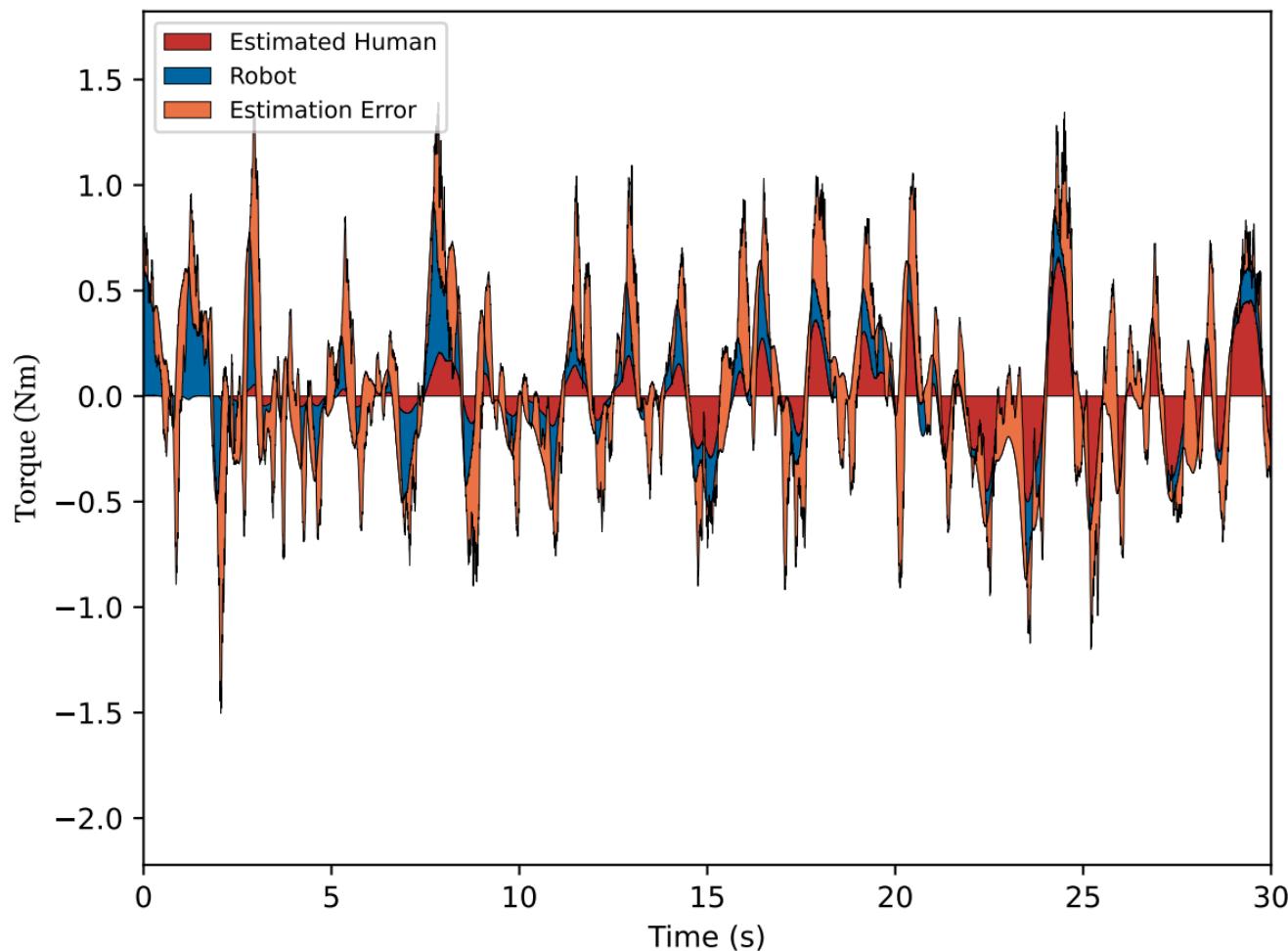
Manual Control





Negative Reinforcement

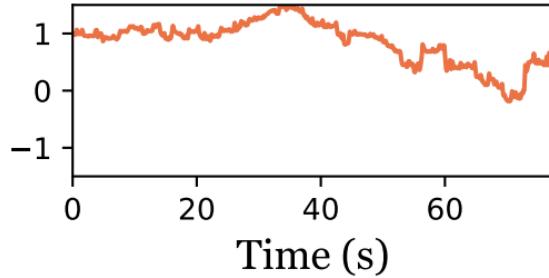
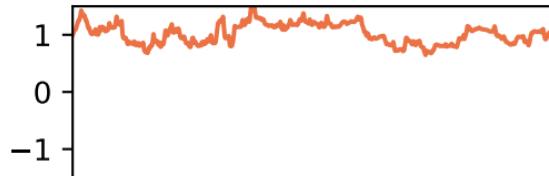
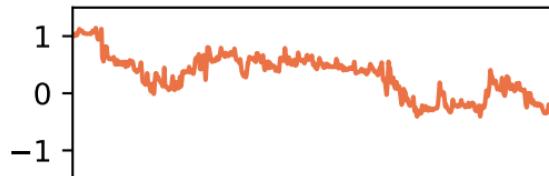
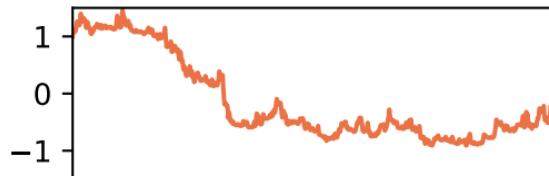
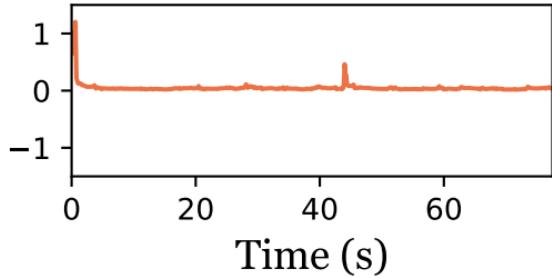
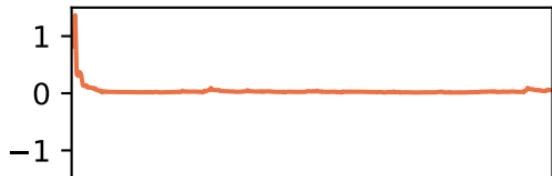
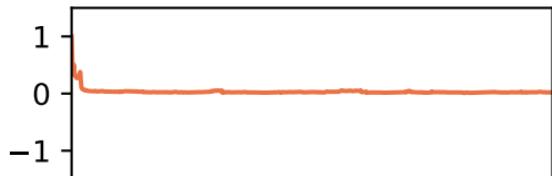




Estimated Control Authority

Positive Re.

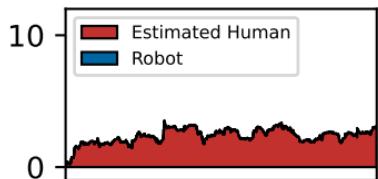
Negative Re.



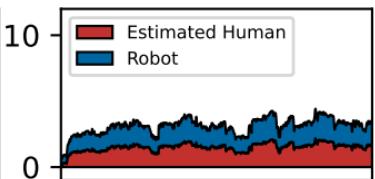
Time (s)

Time (s)

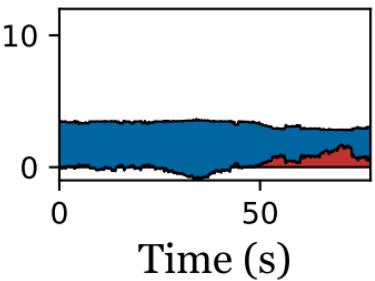
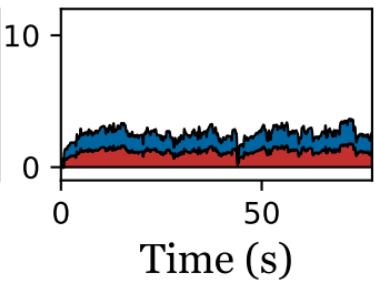
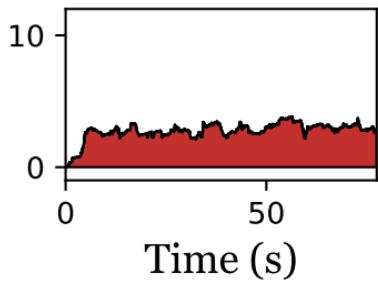
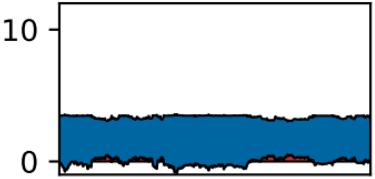
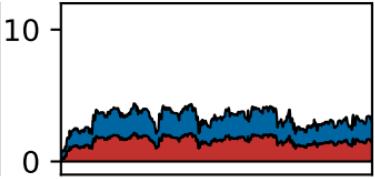
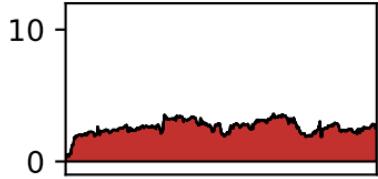
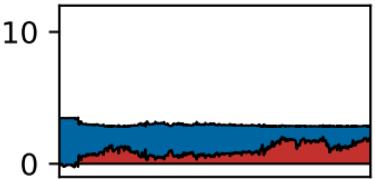
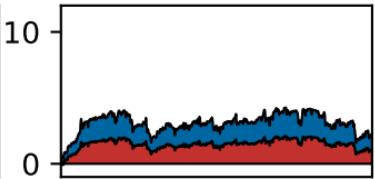
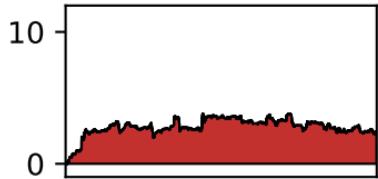
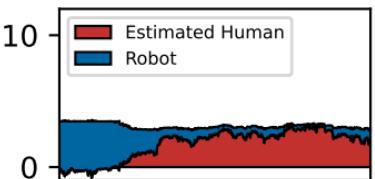
Manual
Control



Gains
Positive Re.



Negative Re.

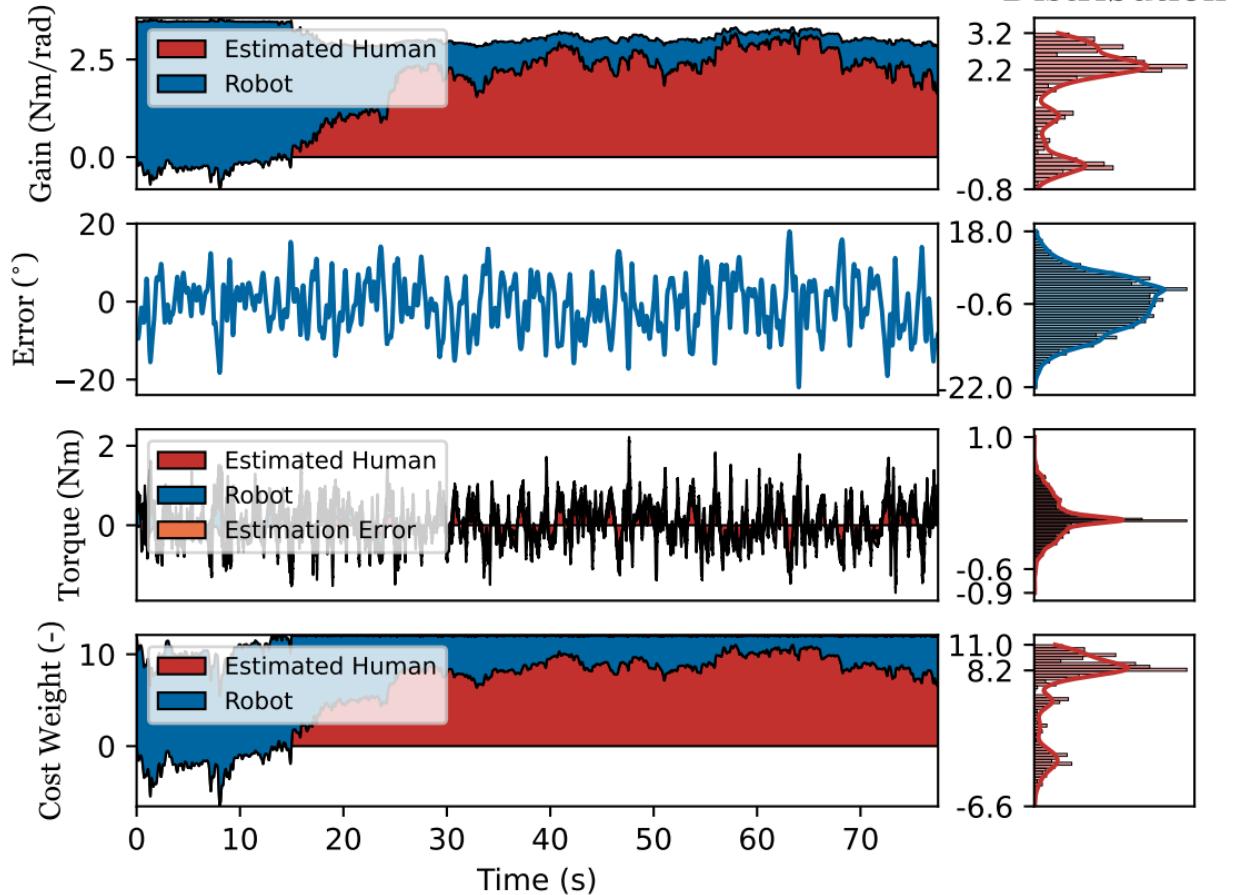


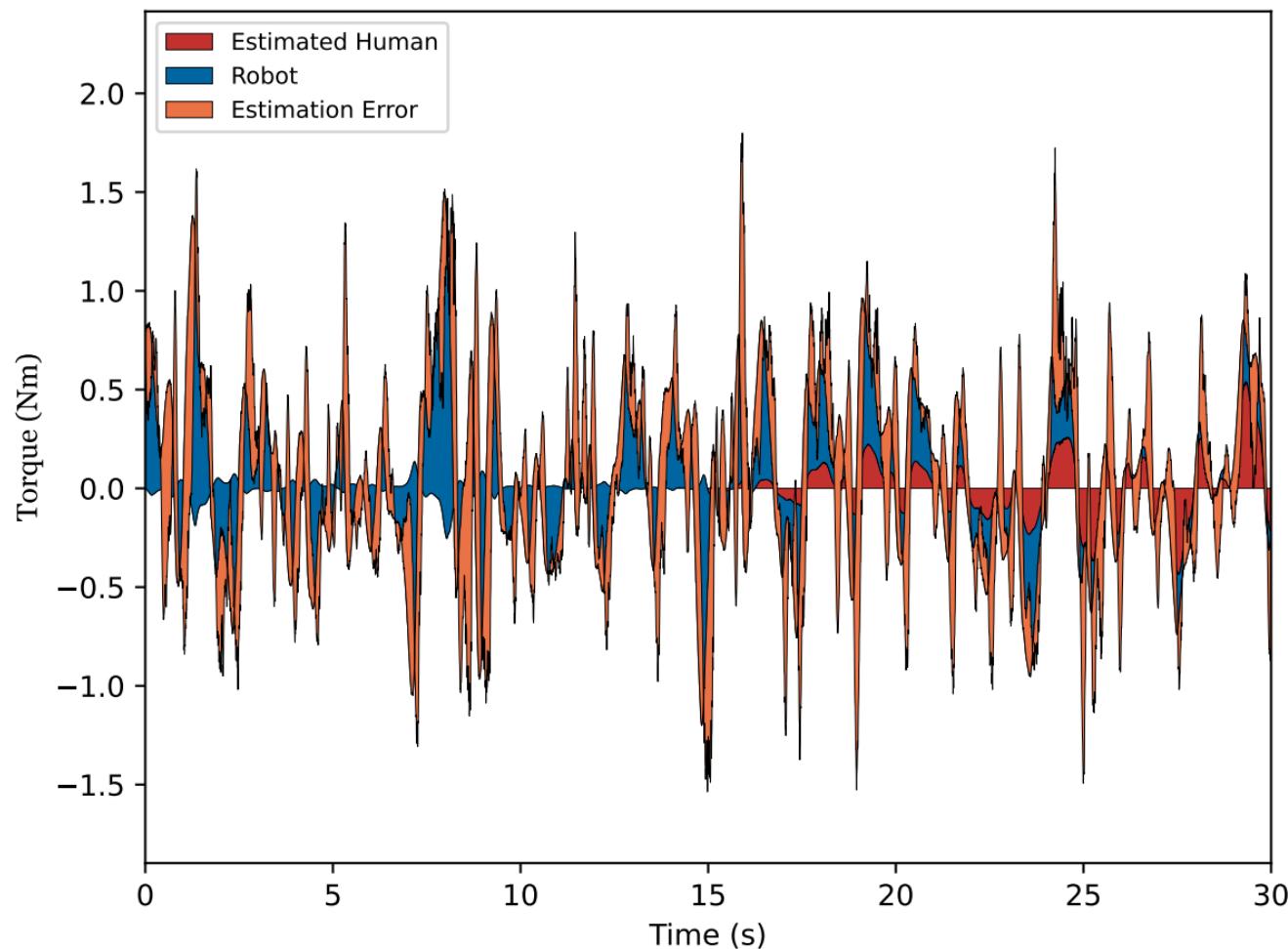
Time (s)

Time (s)

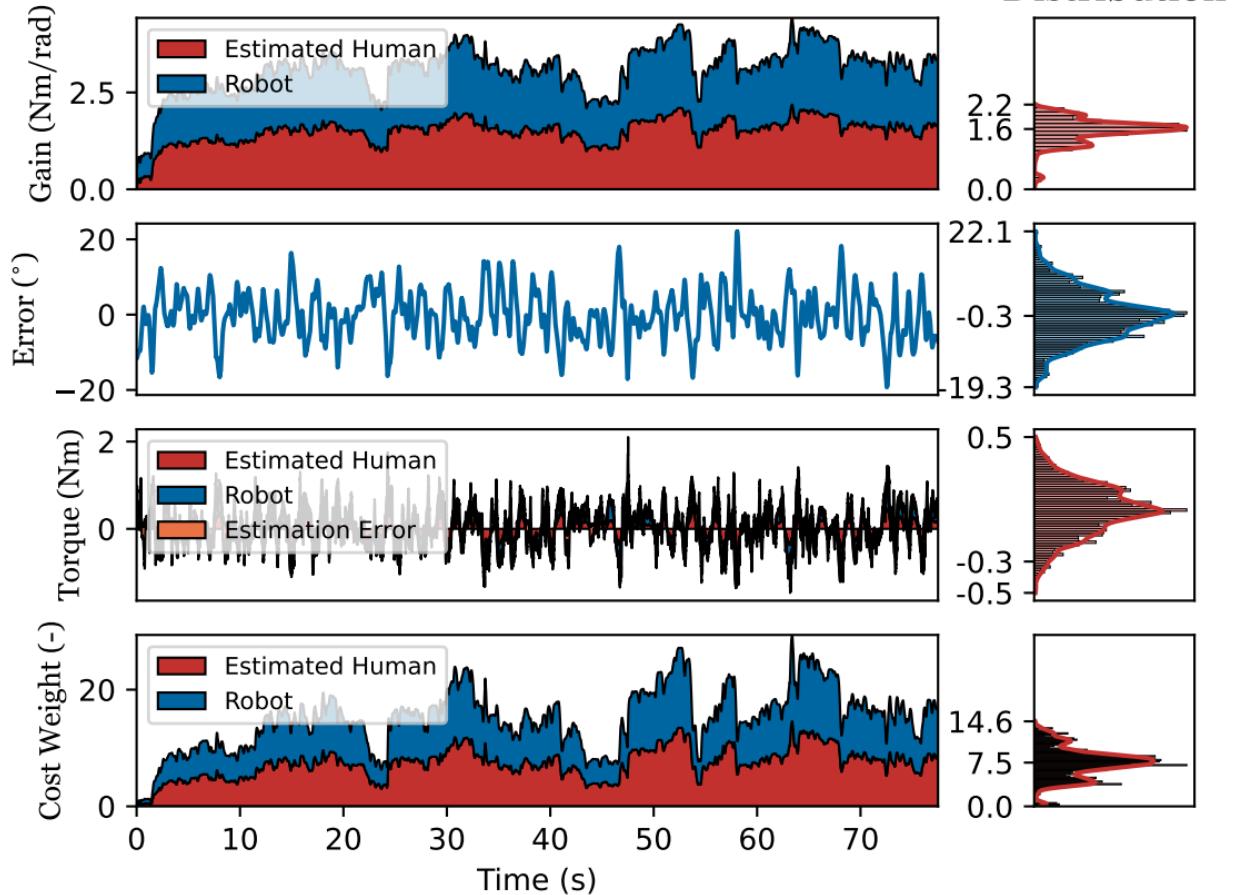
Time (s)

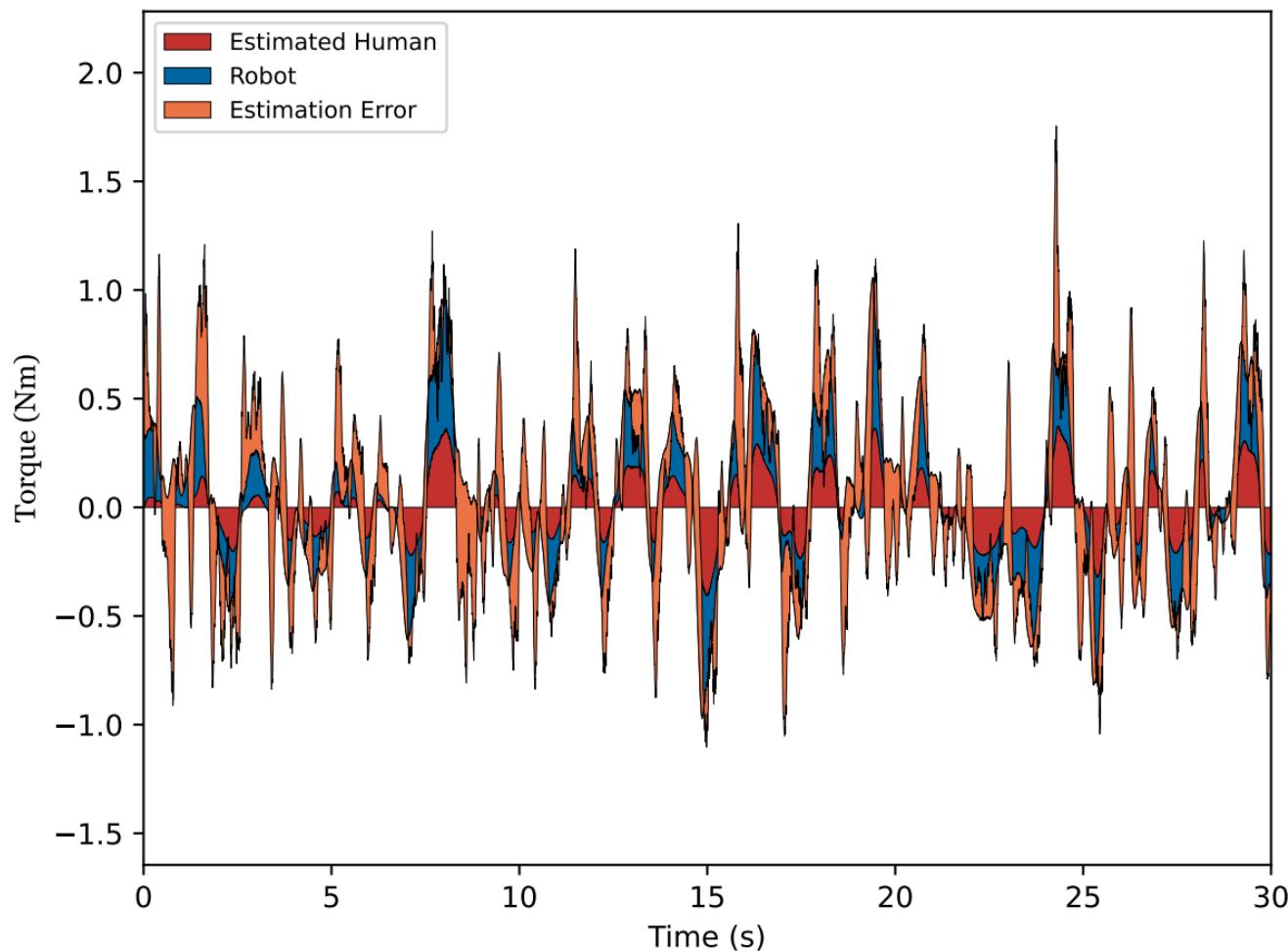
Negative Reinforcement



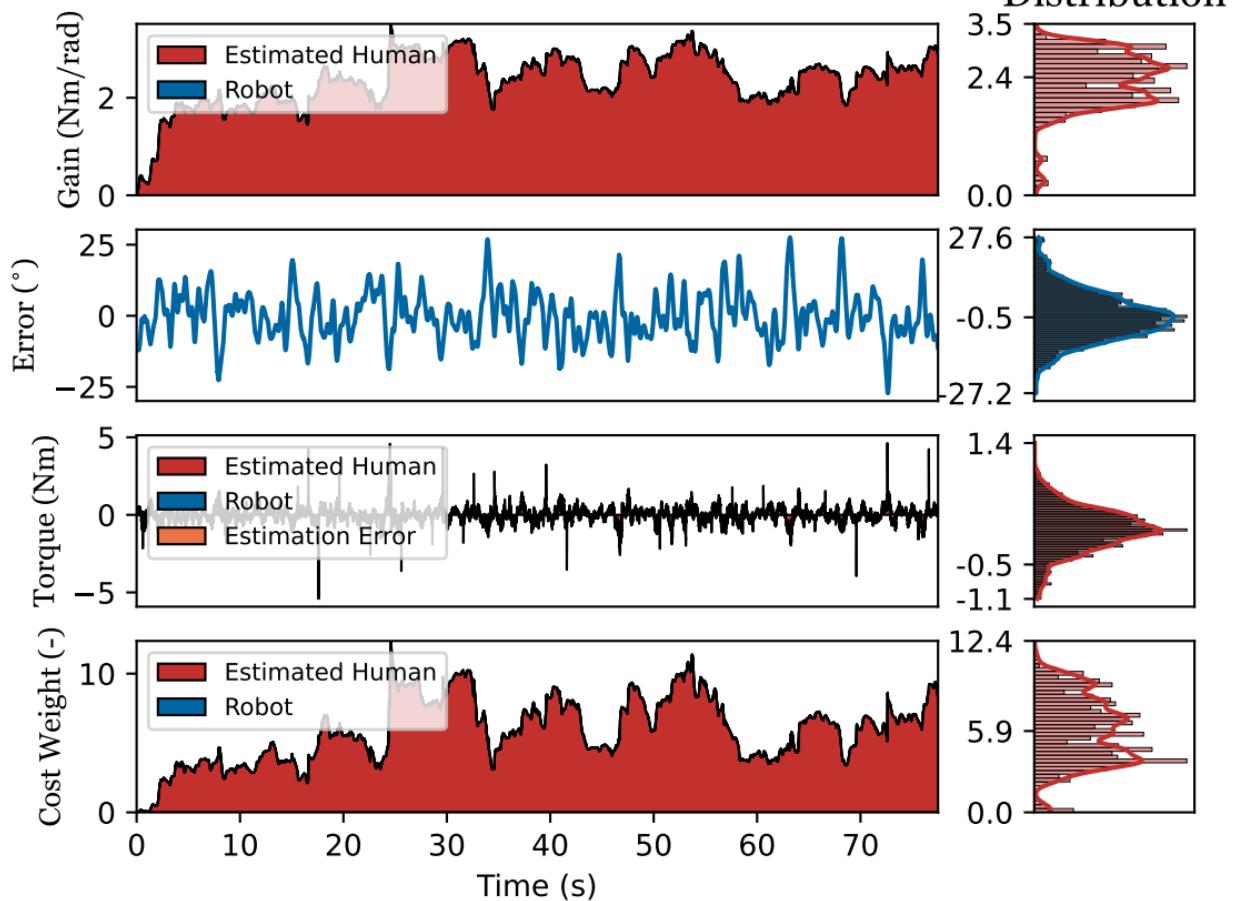


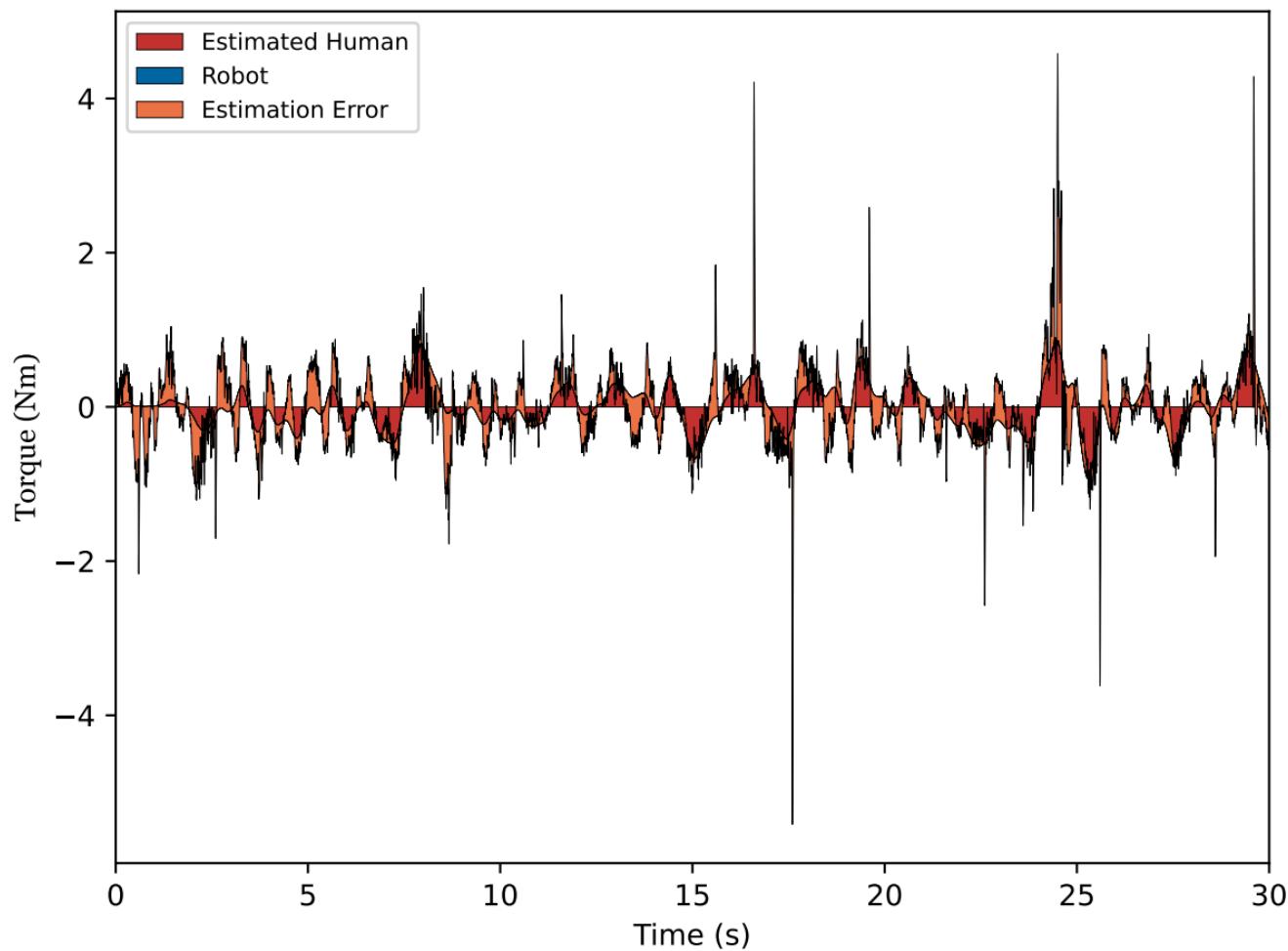
Positive Reinforcement





Manual Control

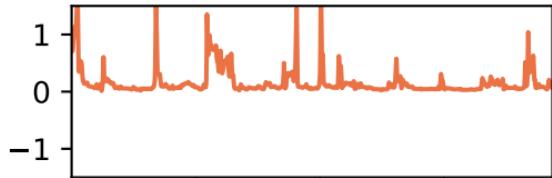
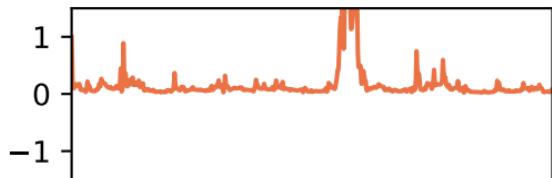
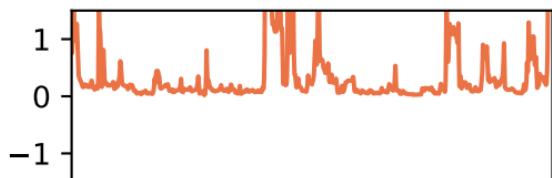
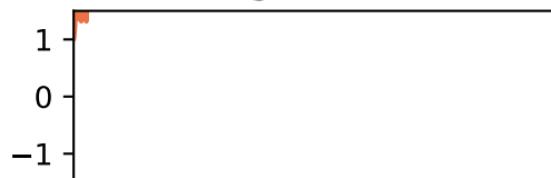
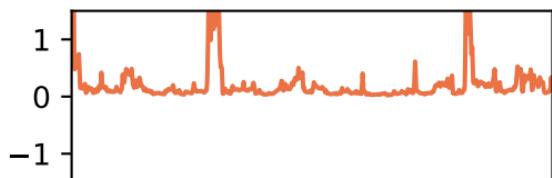




Estimated Control Authority

Positive Re.

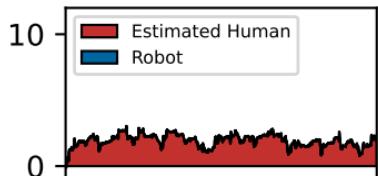
Negative Re.



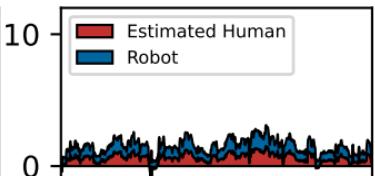
Time (s)

Time (s)

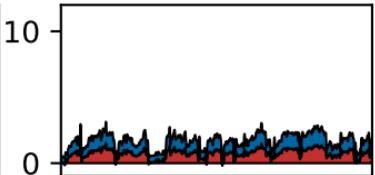
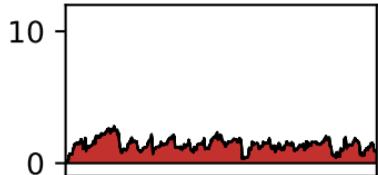
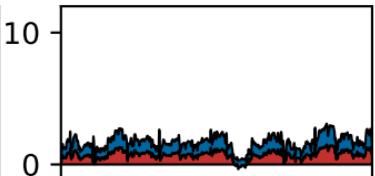
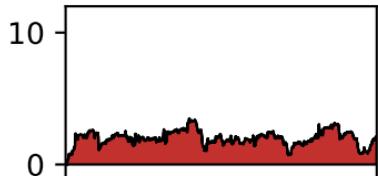
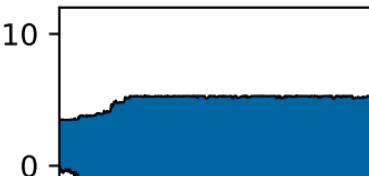
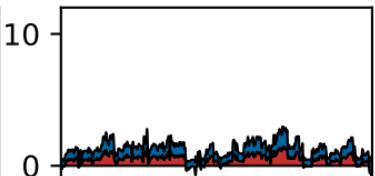
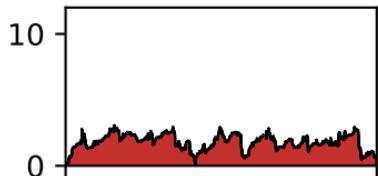
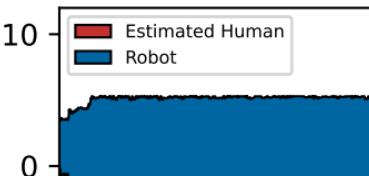
Manual
Control



Gains
Positive Re.



Negative Re.

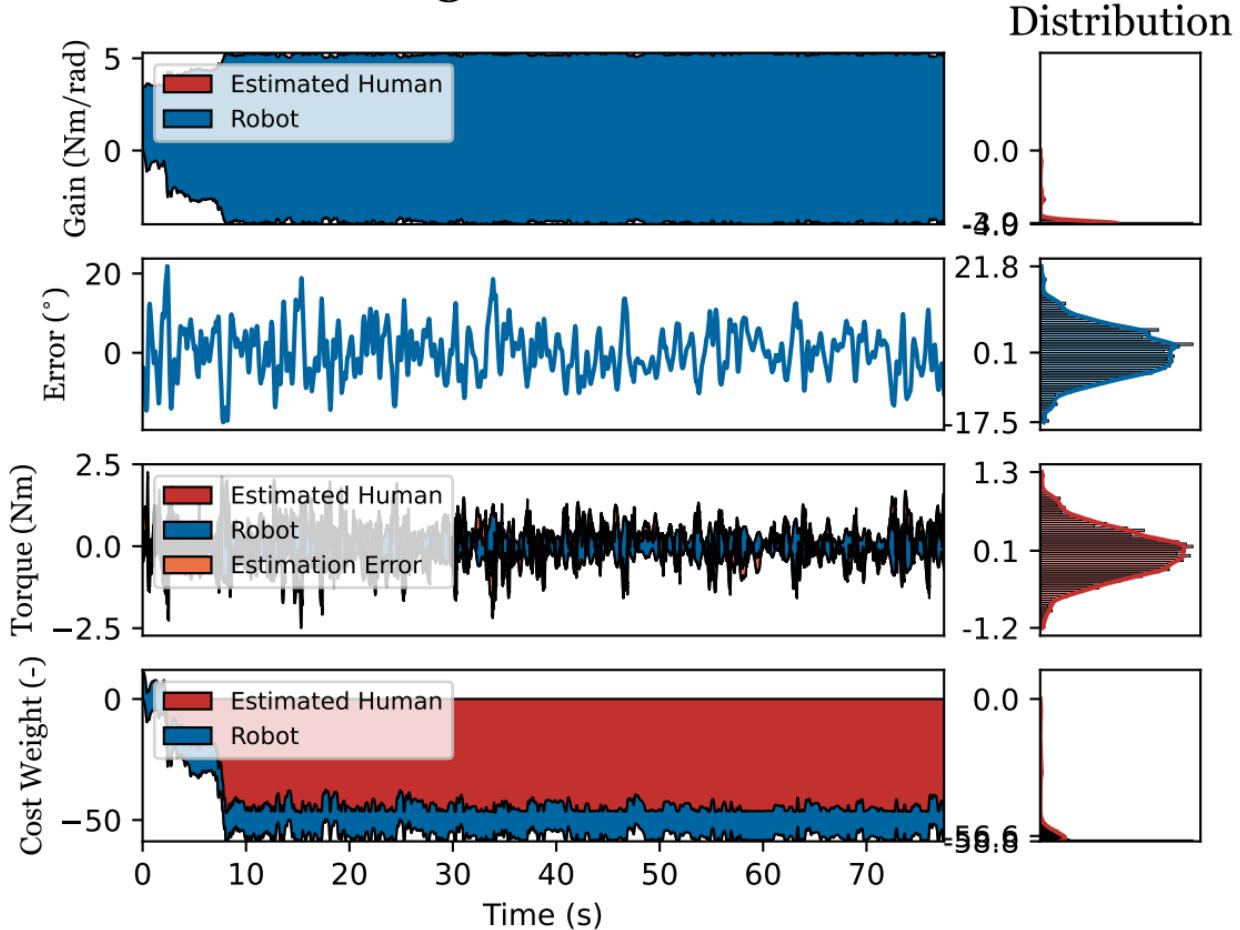


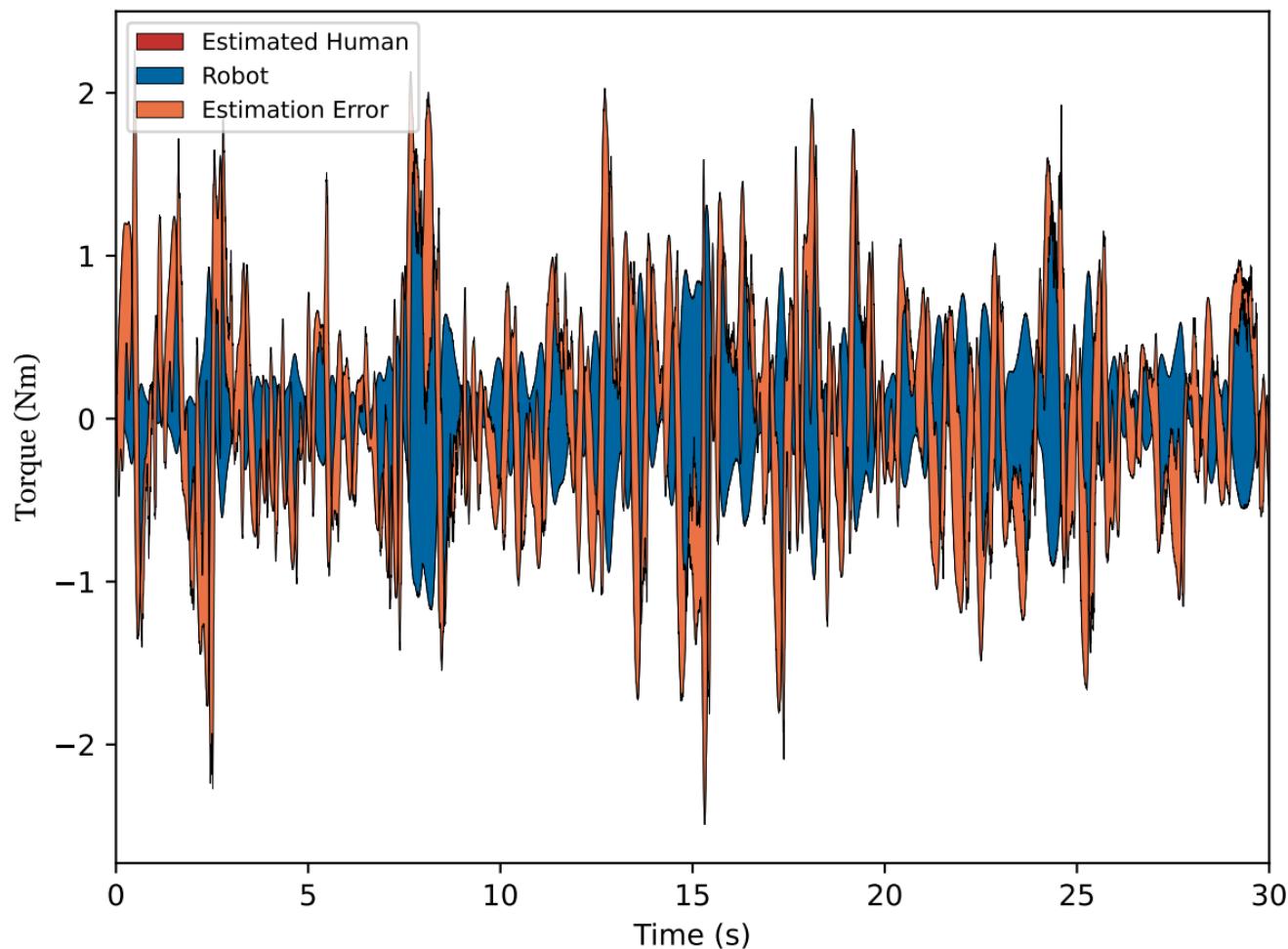
Time (s)

Time (s)

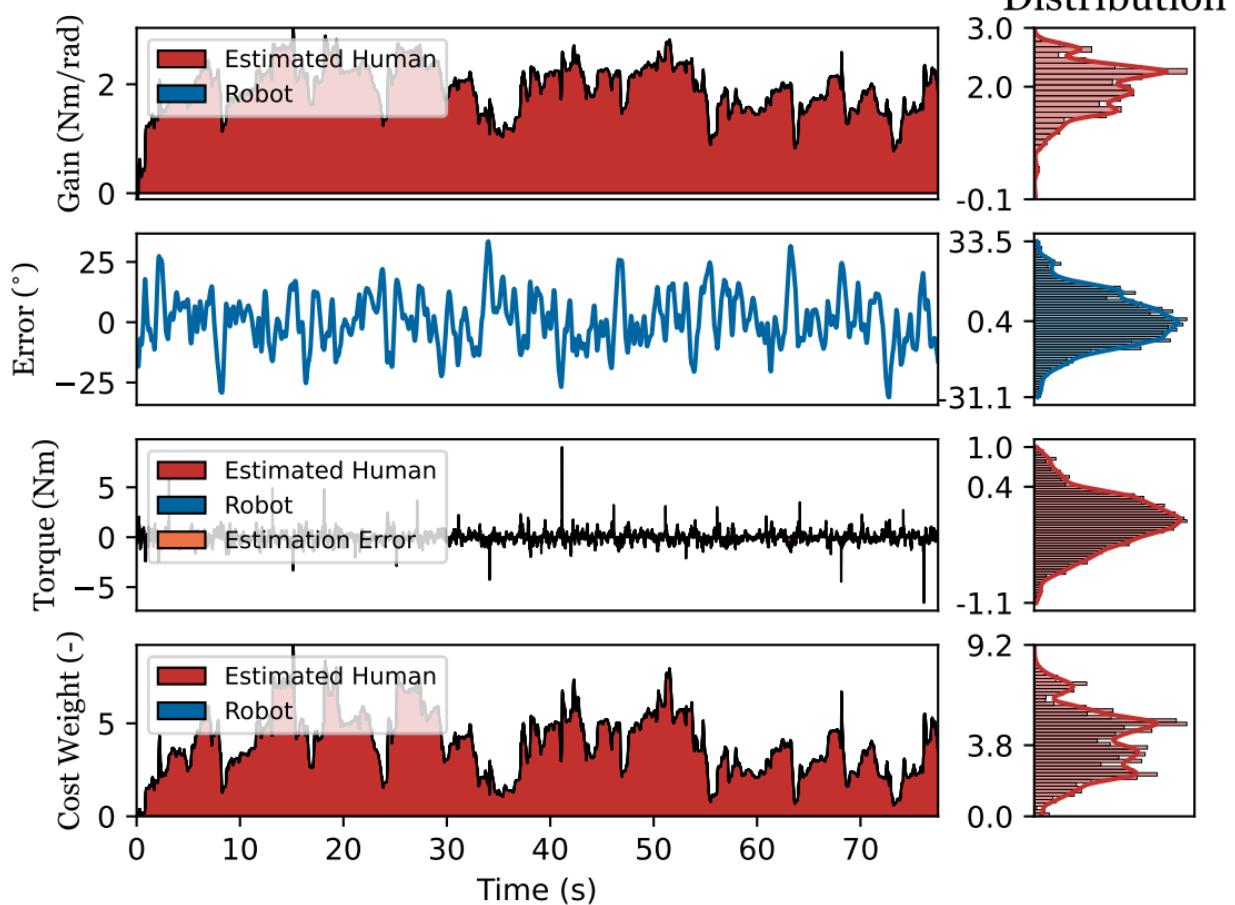
Time (s)

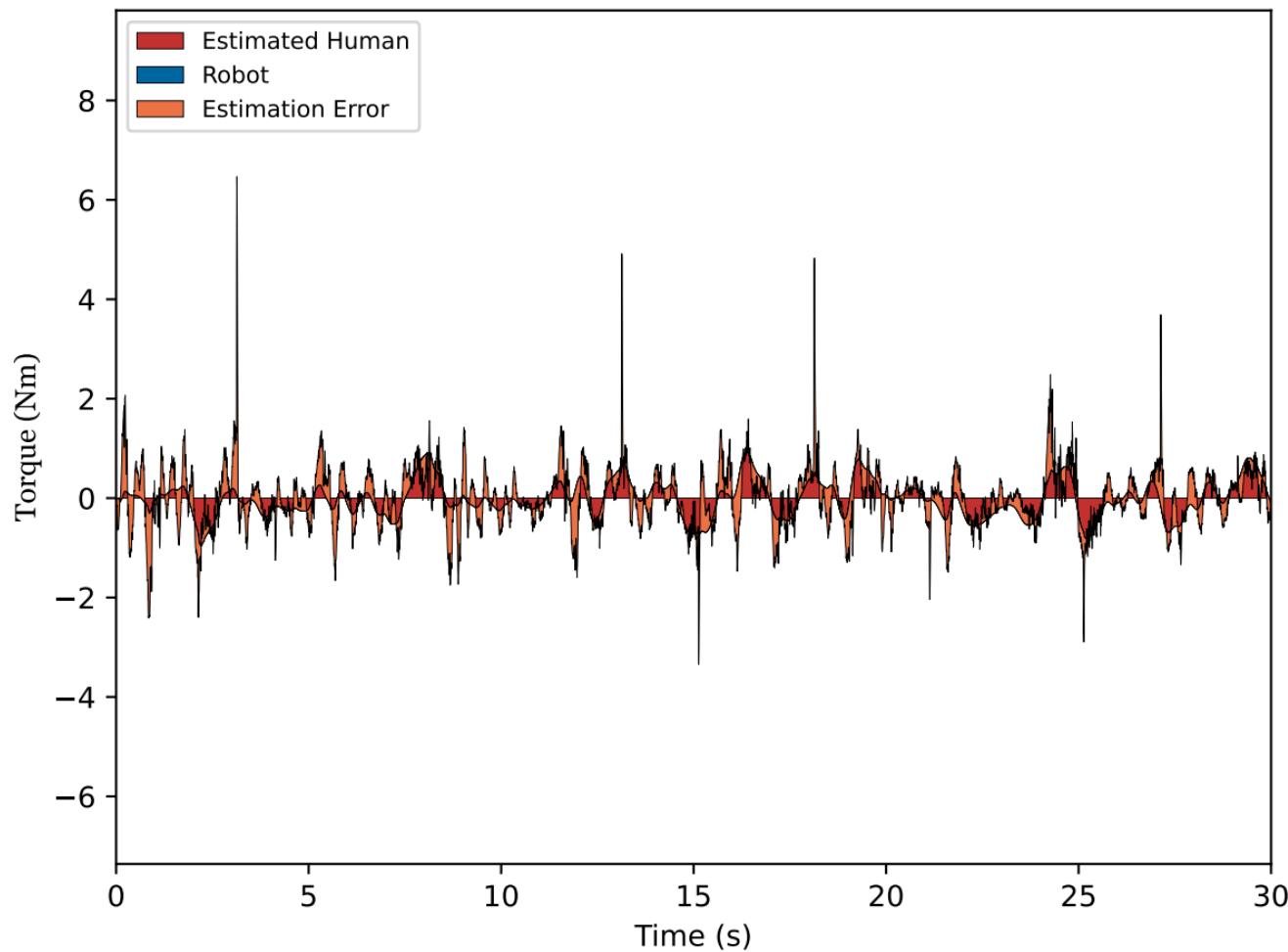
Negative Reinforcement



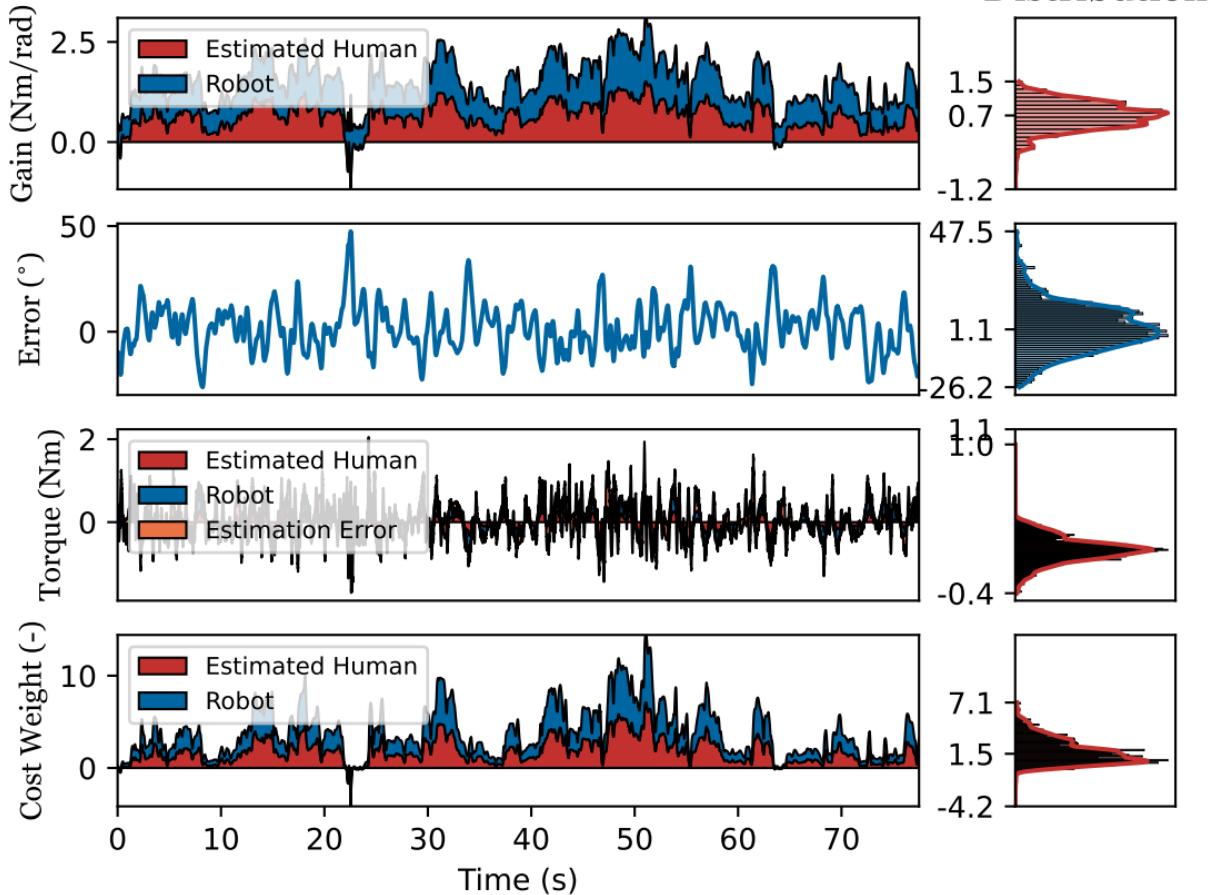


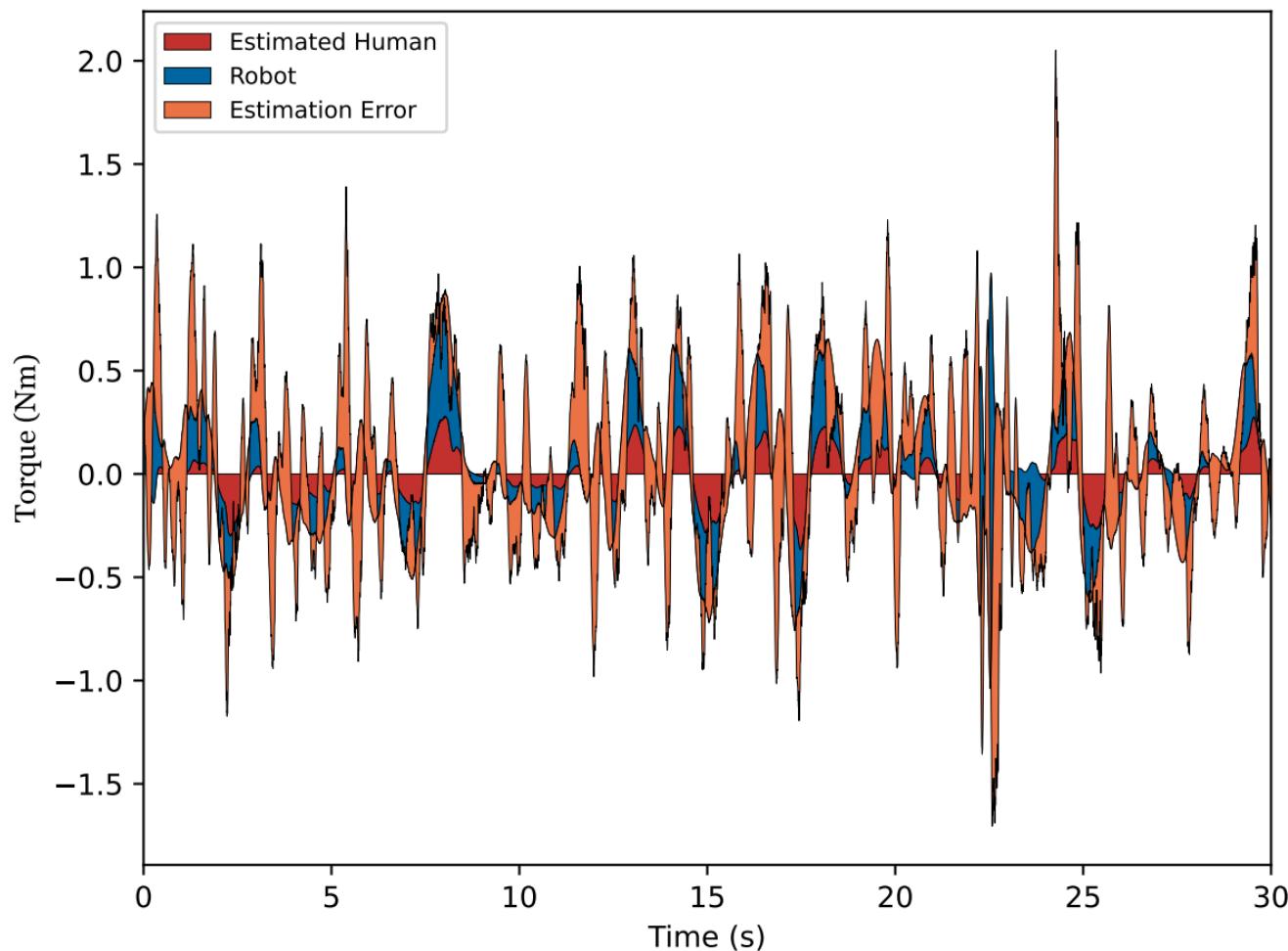
Manual Control



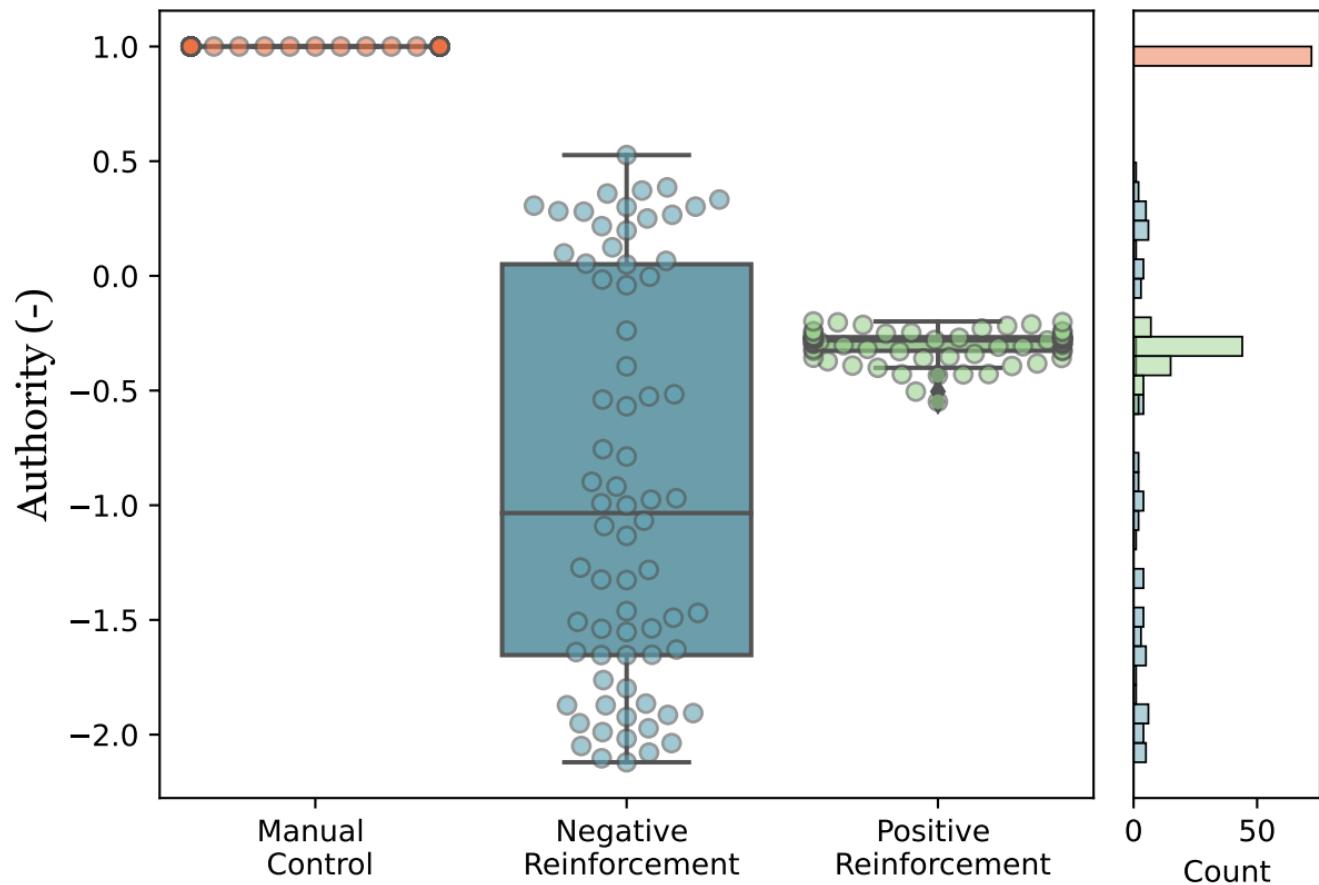


Positive Reinforcement

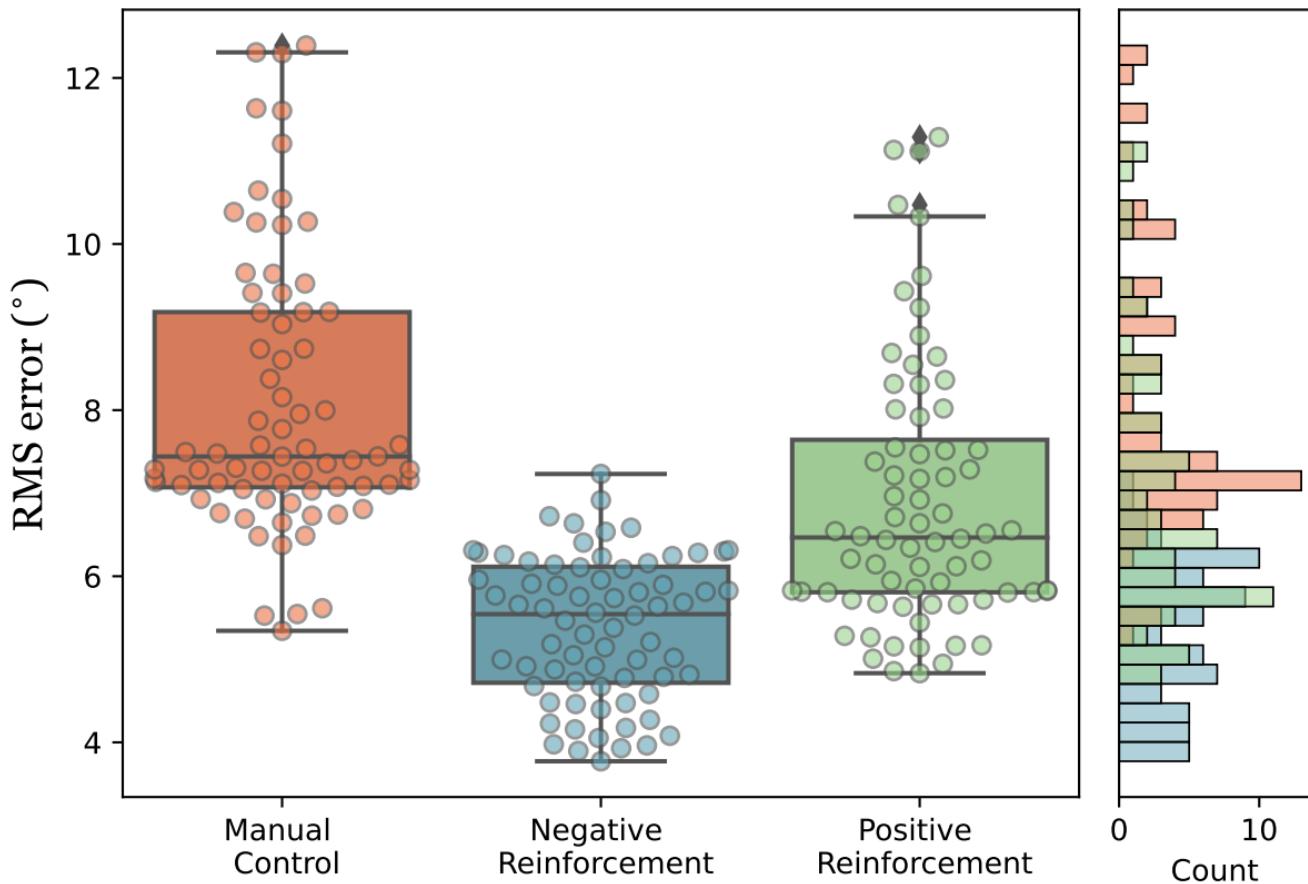




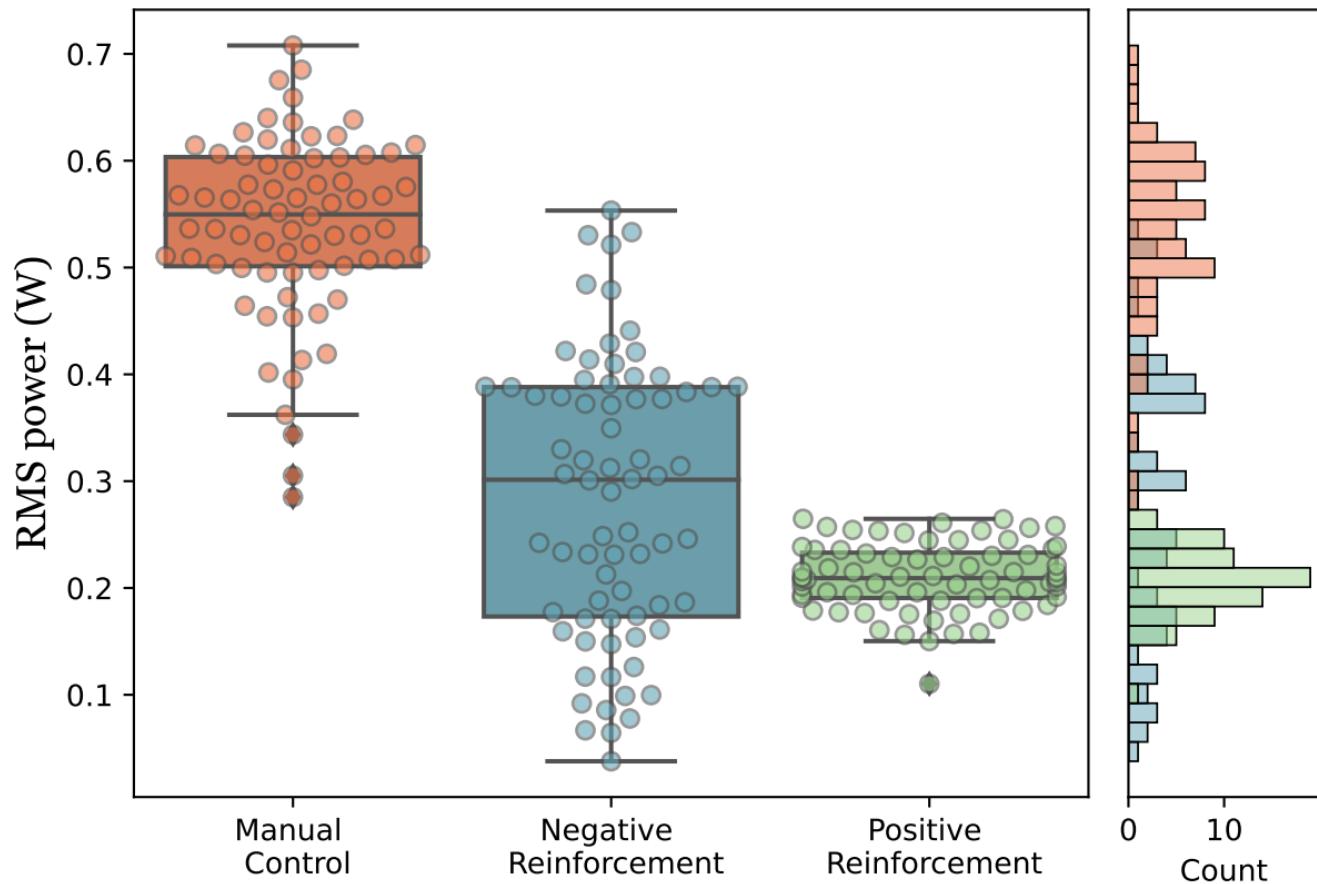
Control Authority



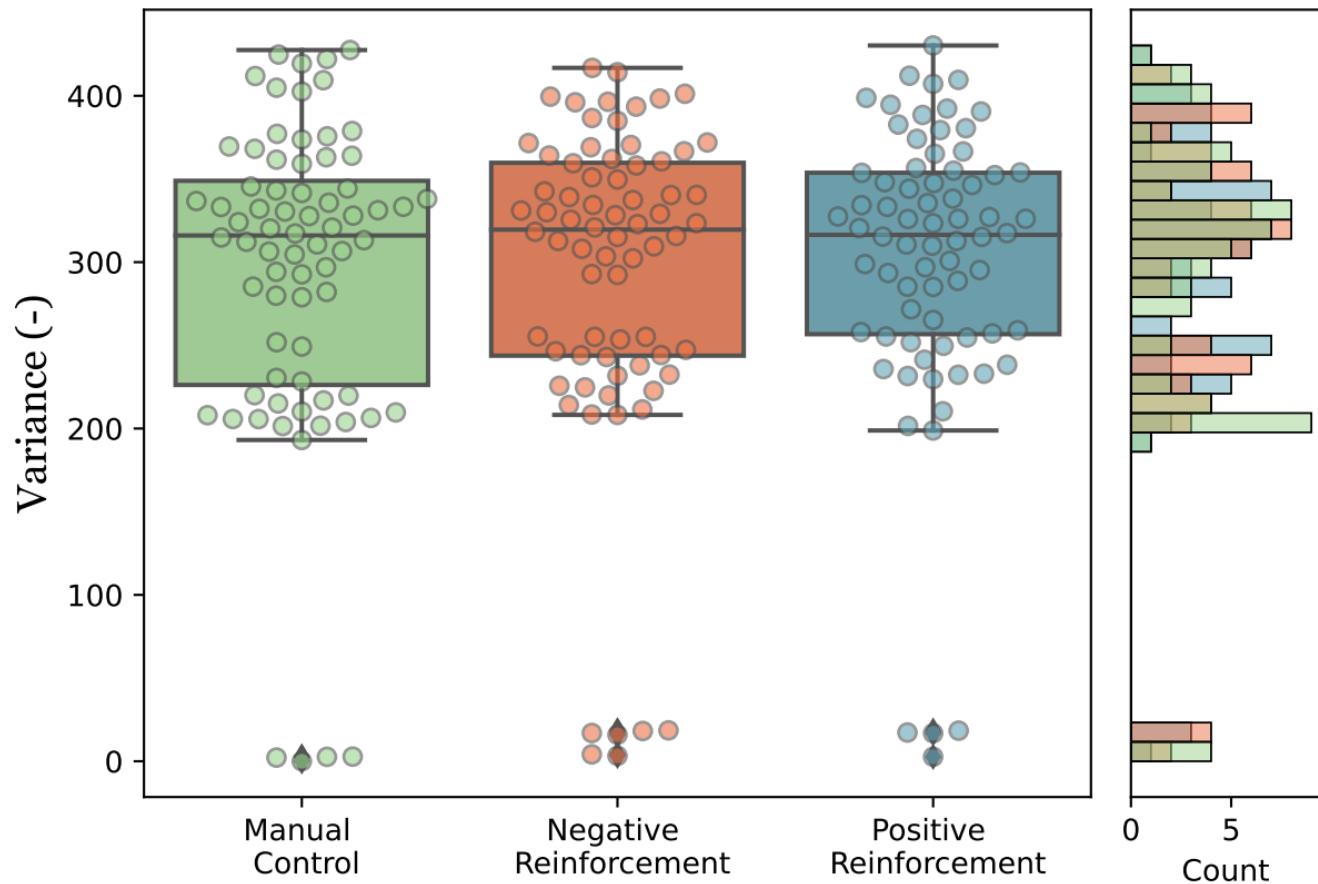
Steering Angle Error



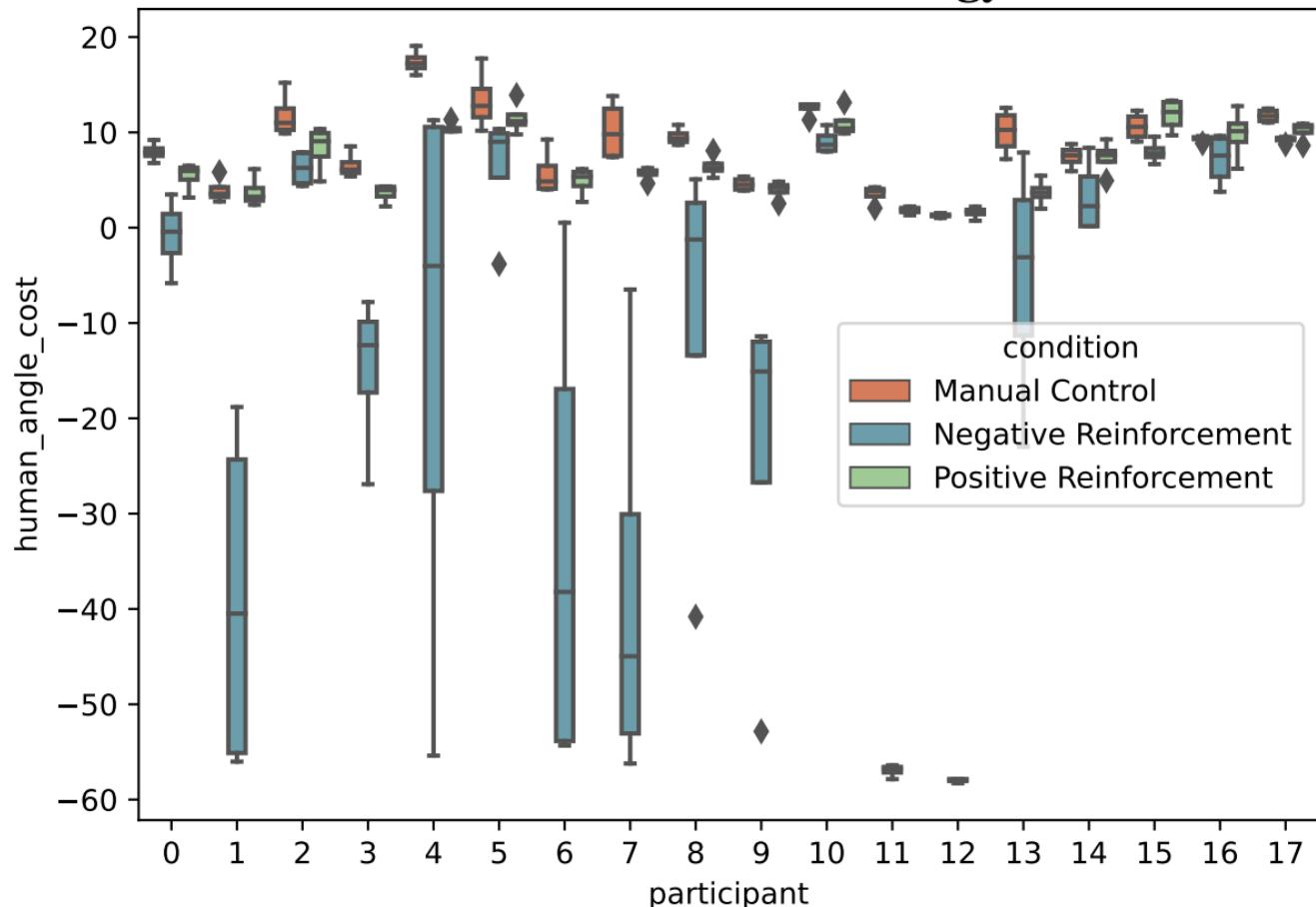
Human Input Power

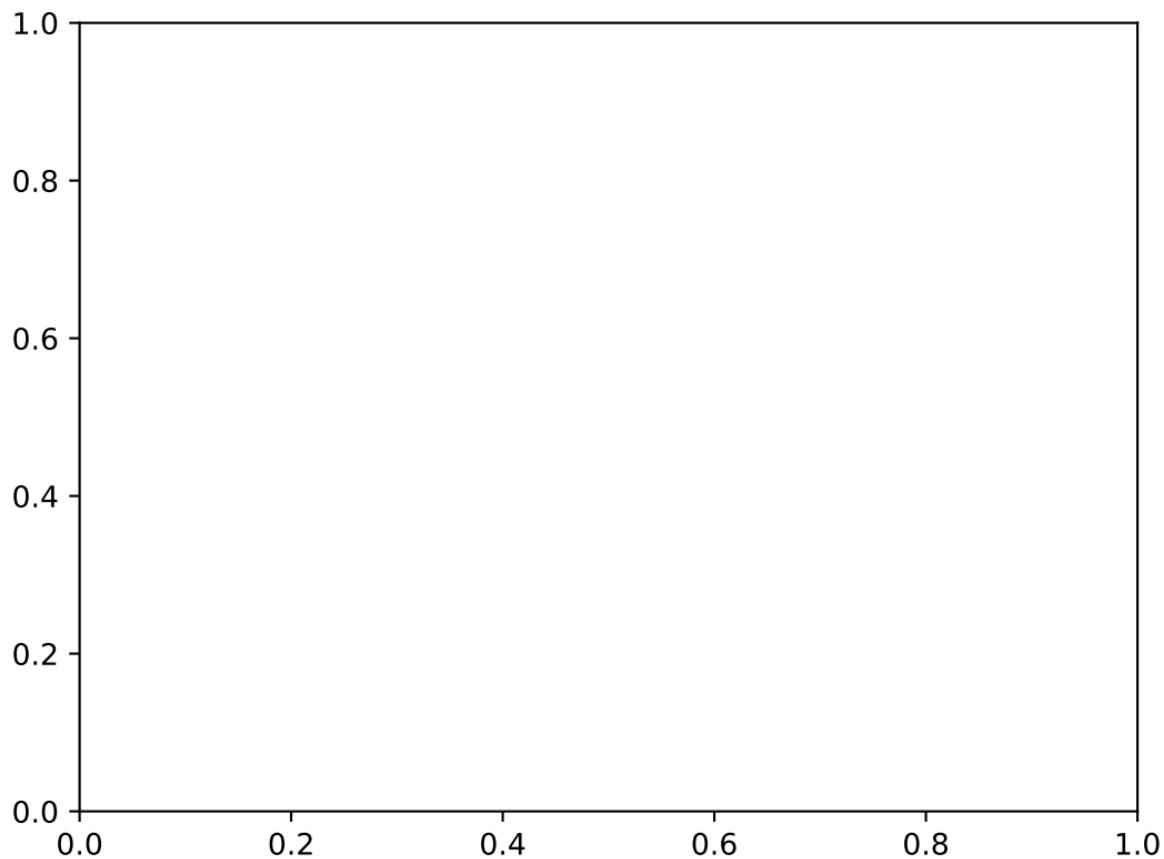


Cost function variability

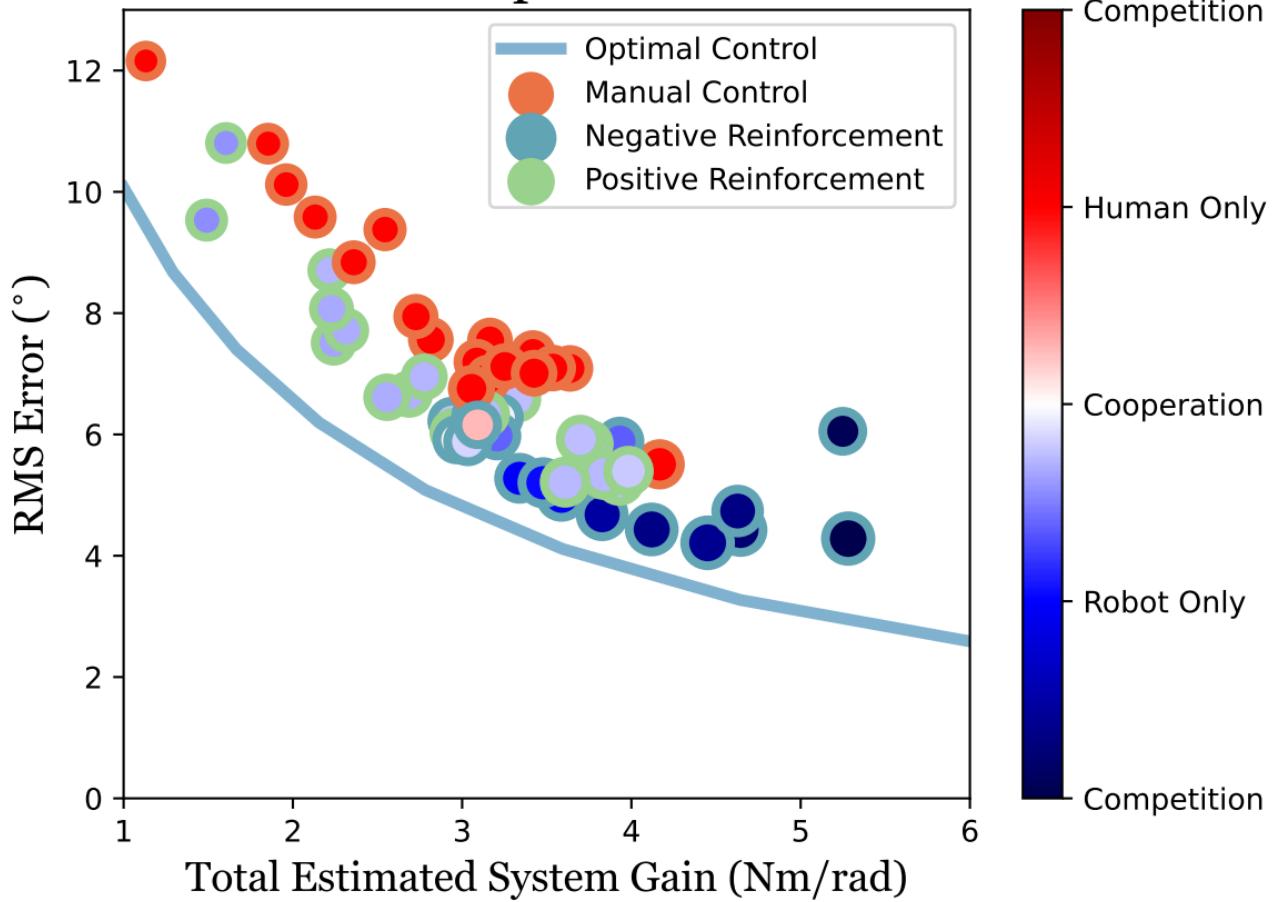


Human control strategy

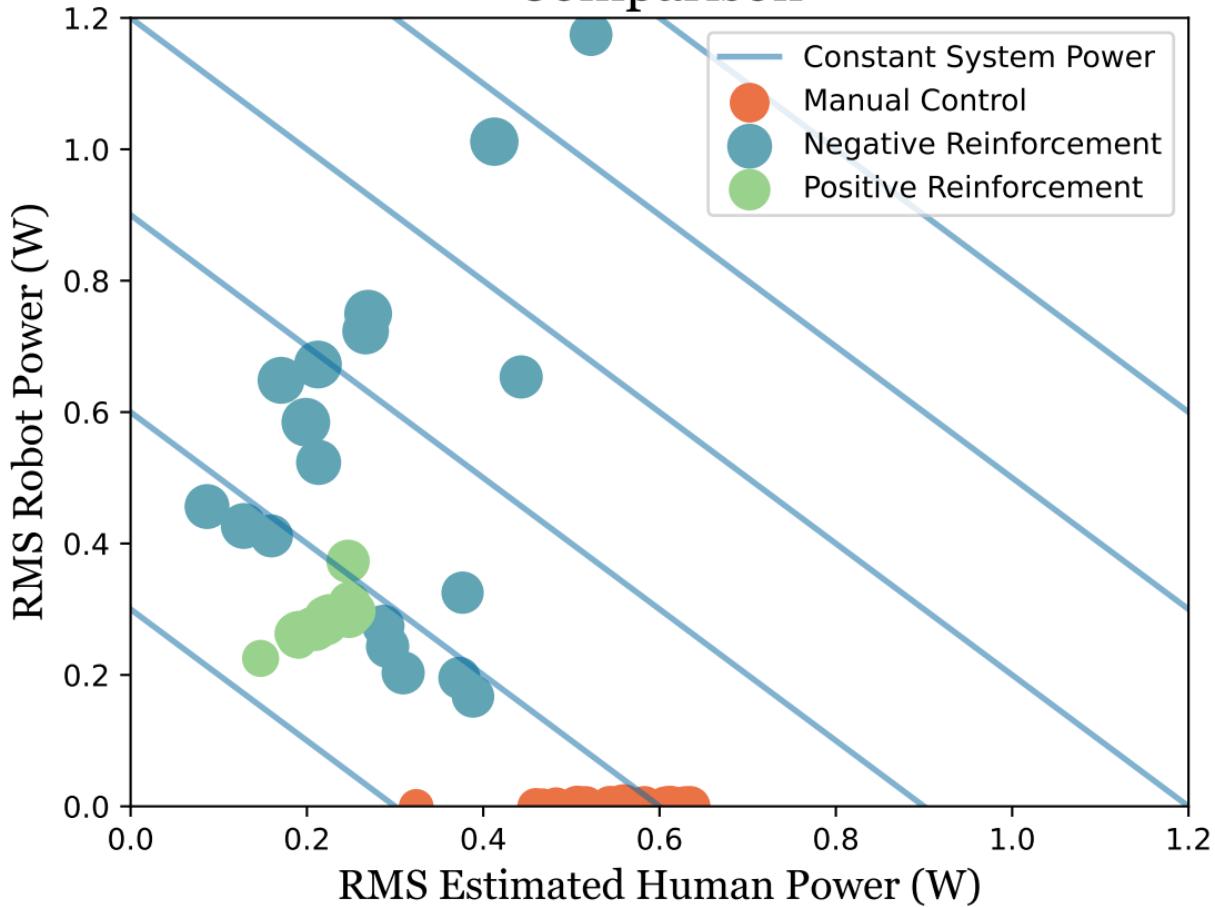




Comparison



Comparison



Subjective and objective control share

