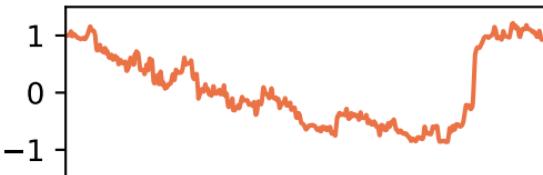
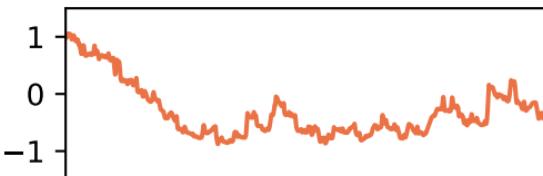
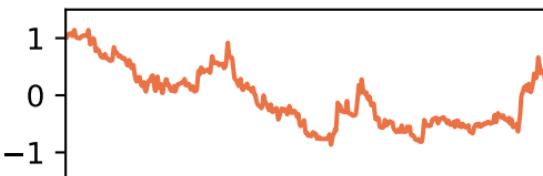
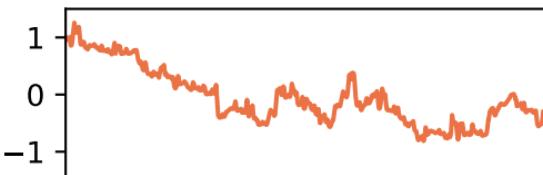
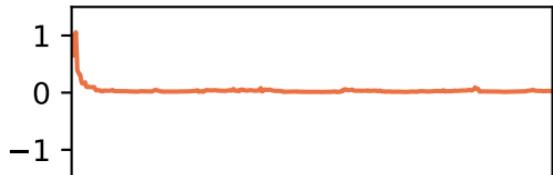
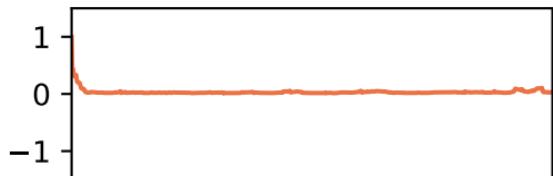
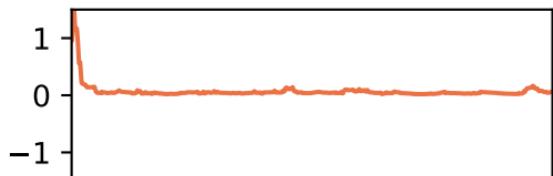


Estimated Control Authority

Positive Re.

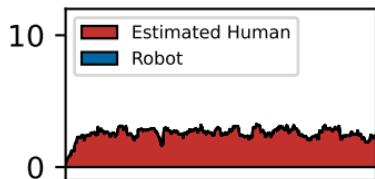
Negative Re.



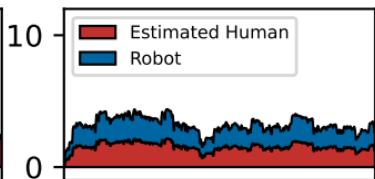
Time (s)

Time (s)

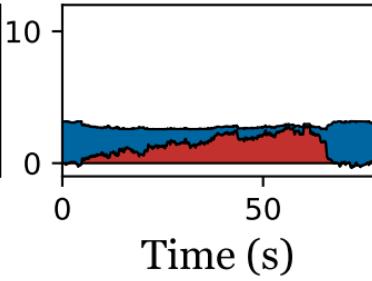
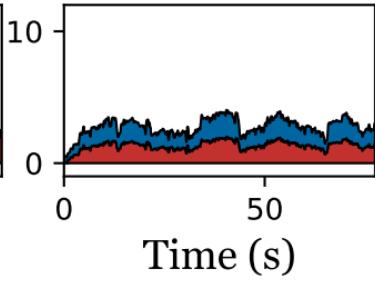
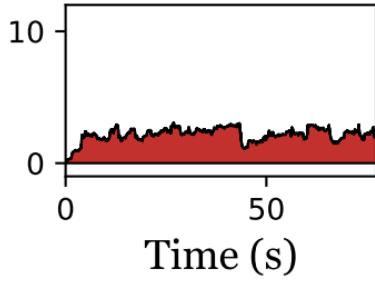
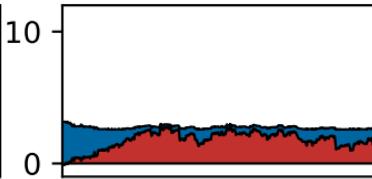
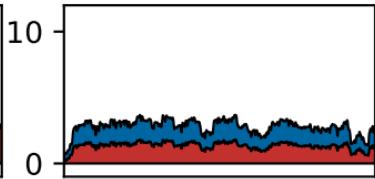
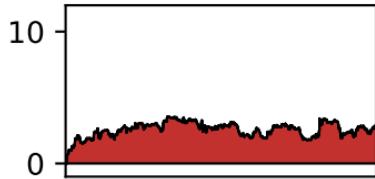
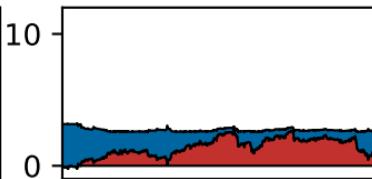
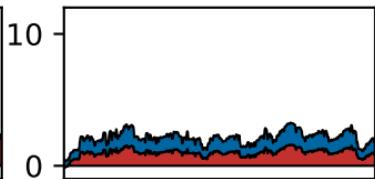
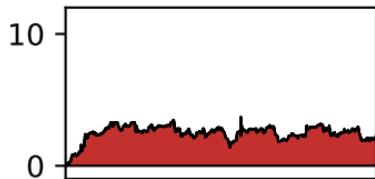
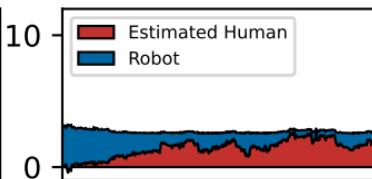
Manual
Control



Gains
Positive Re.



Negative Re.

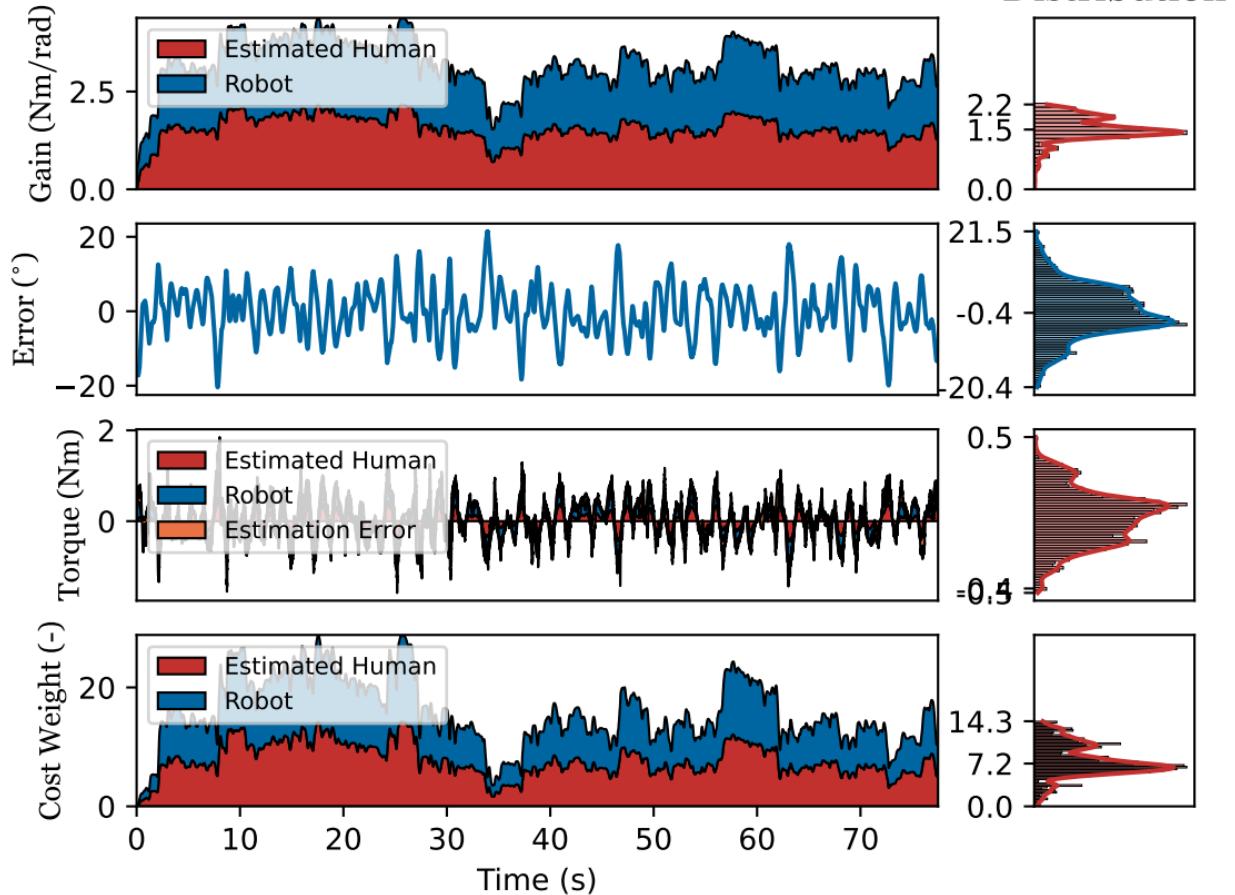


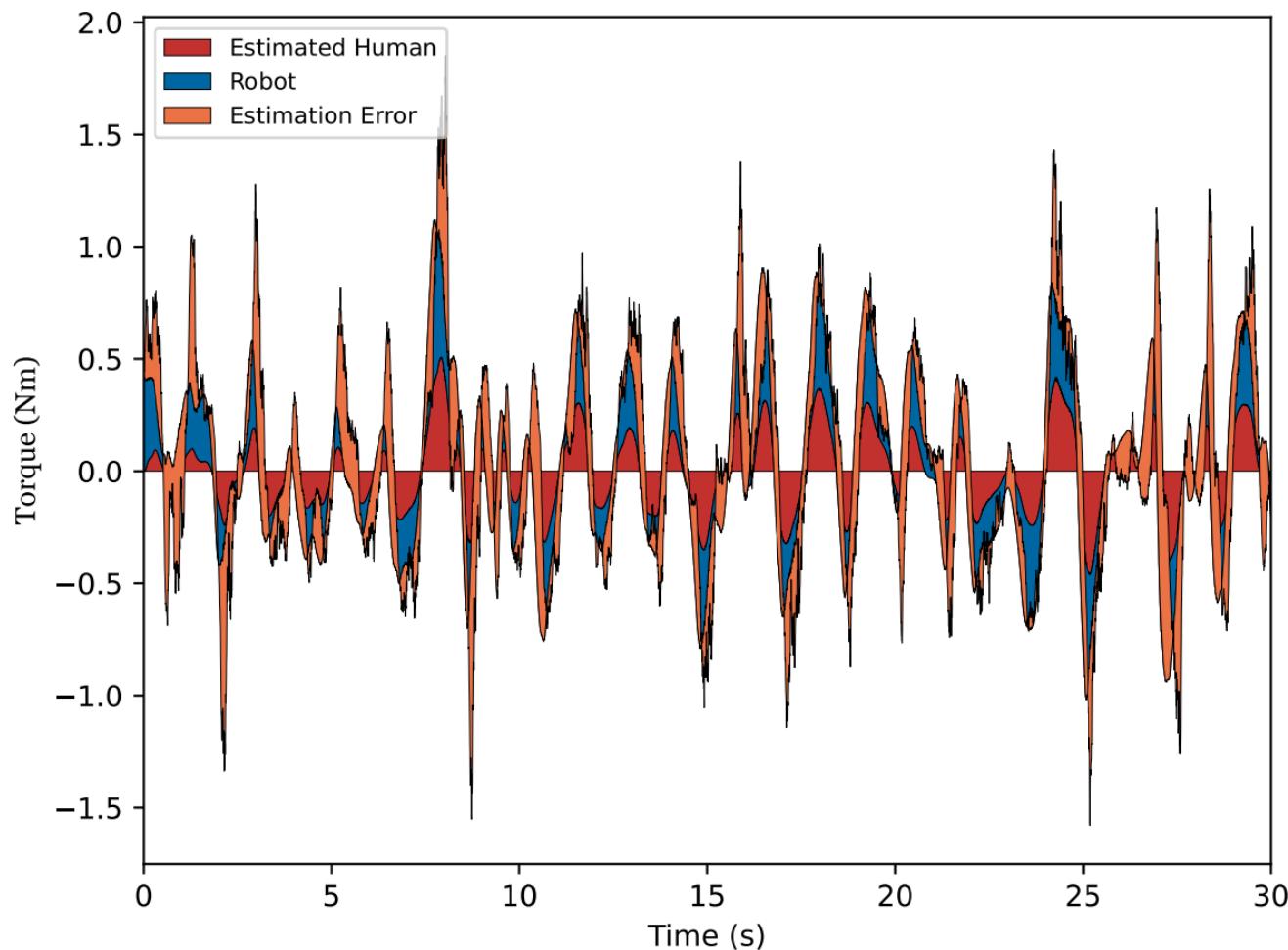
Time (s)

Time (s)

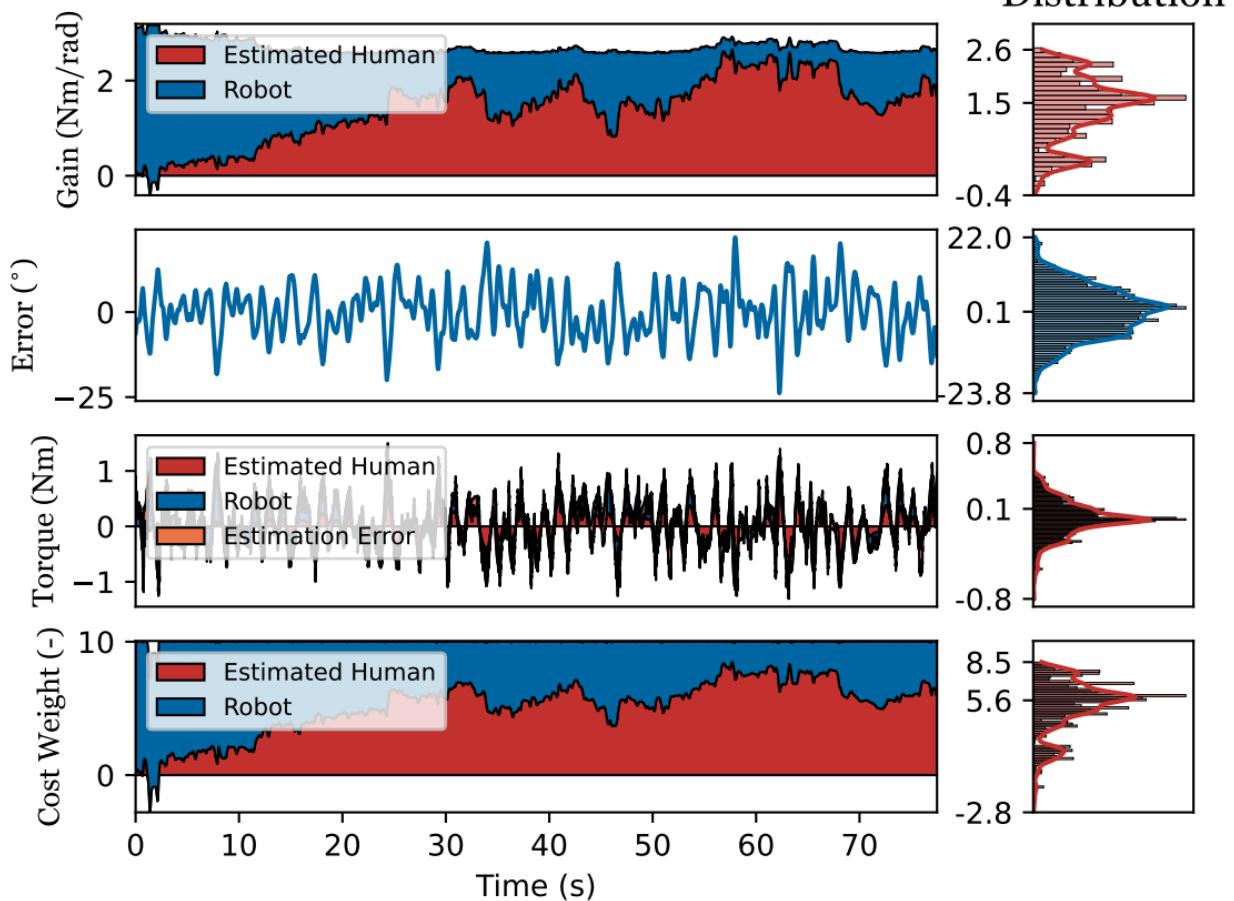
Time (s)

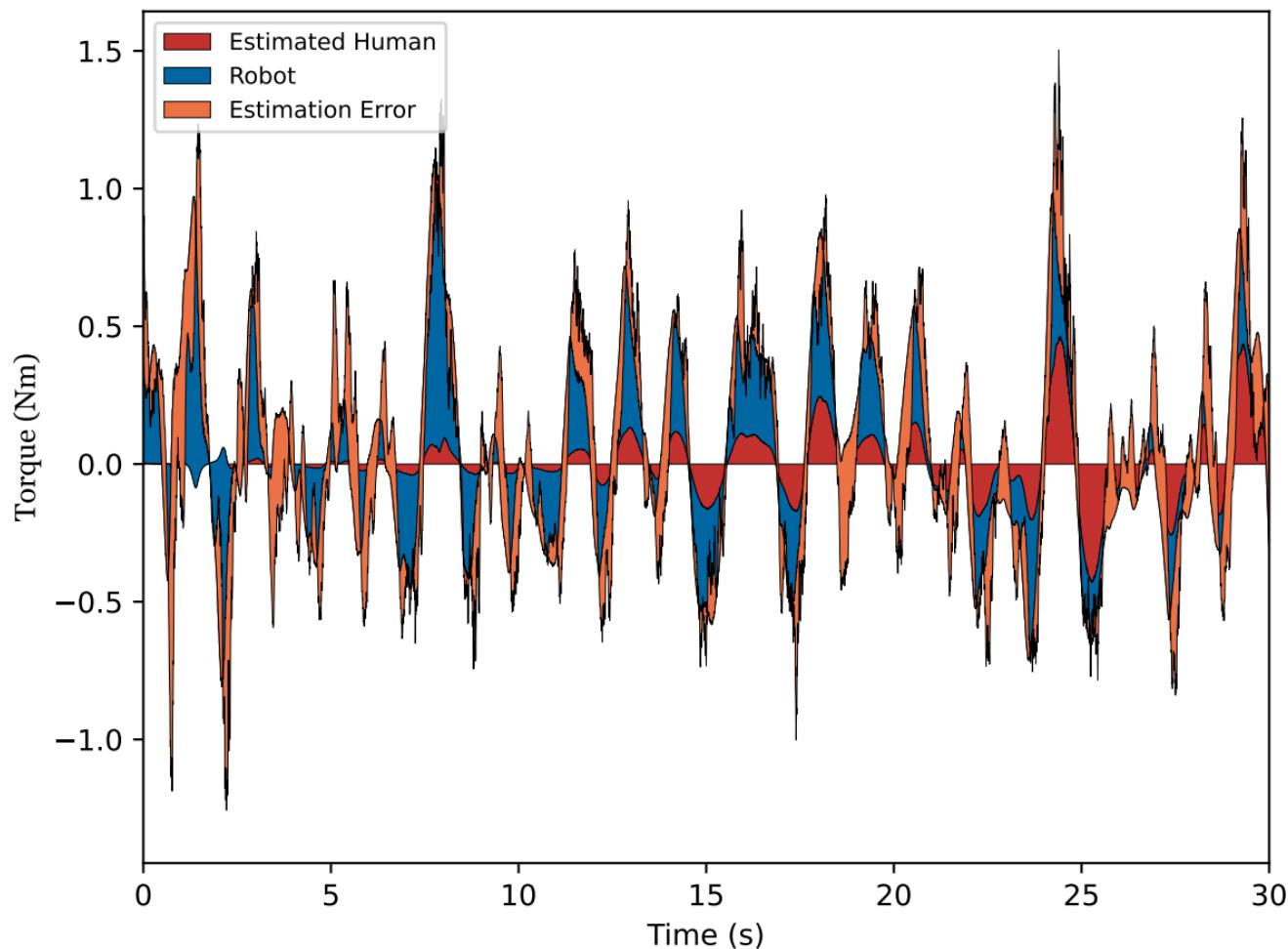
Positive Reinforcement



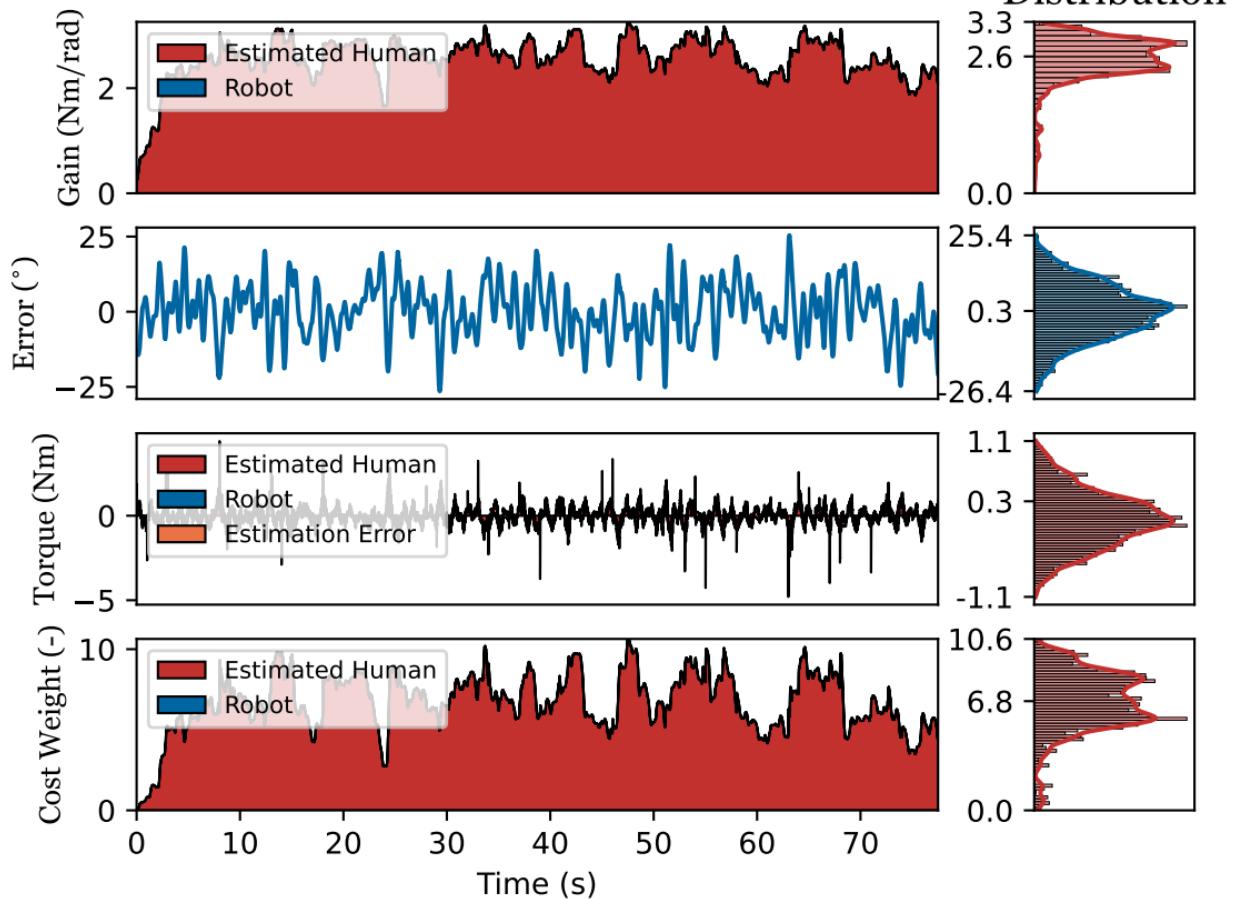


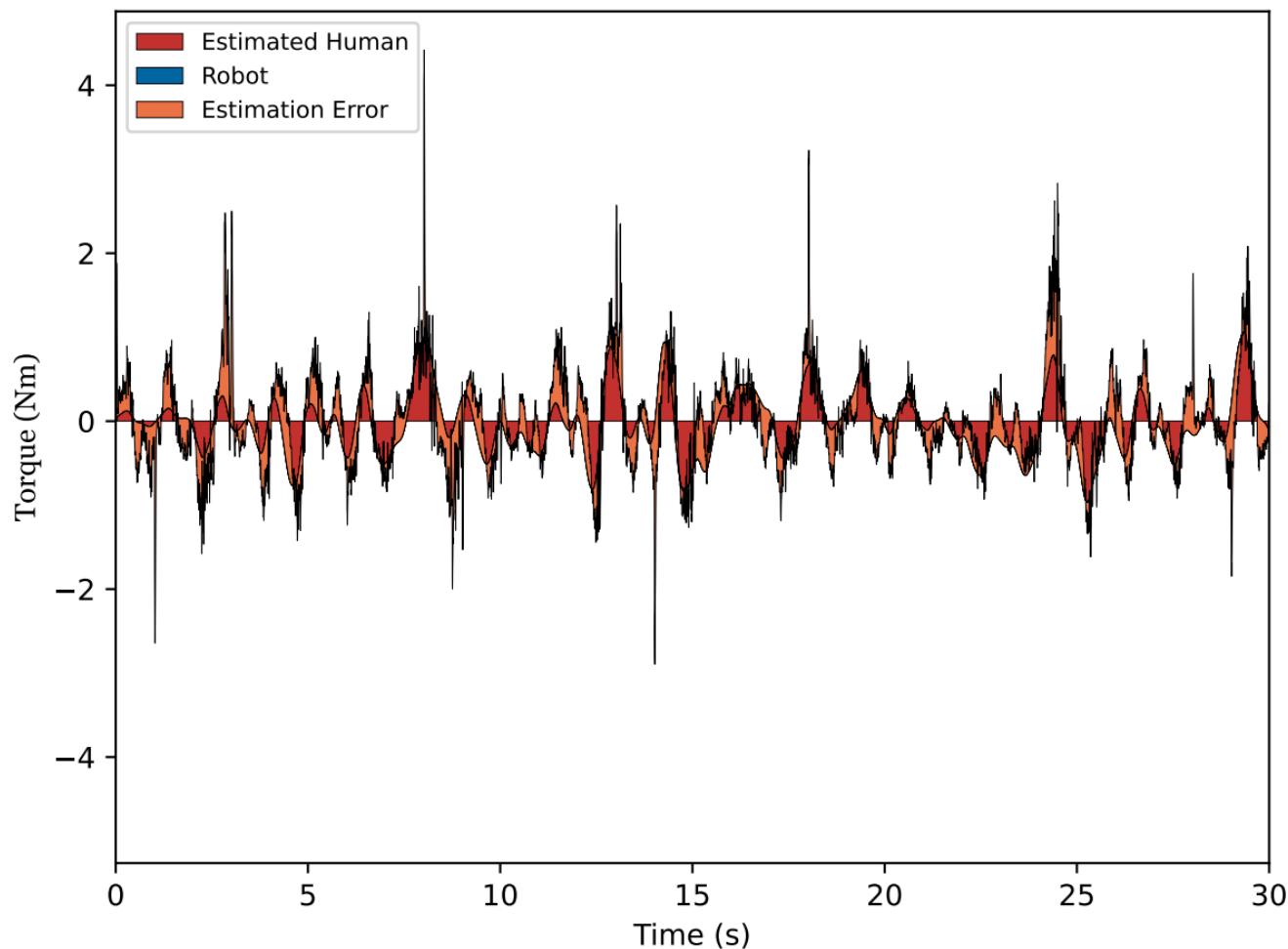
Negative Reinforcement



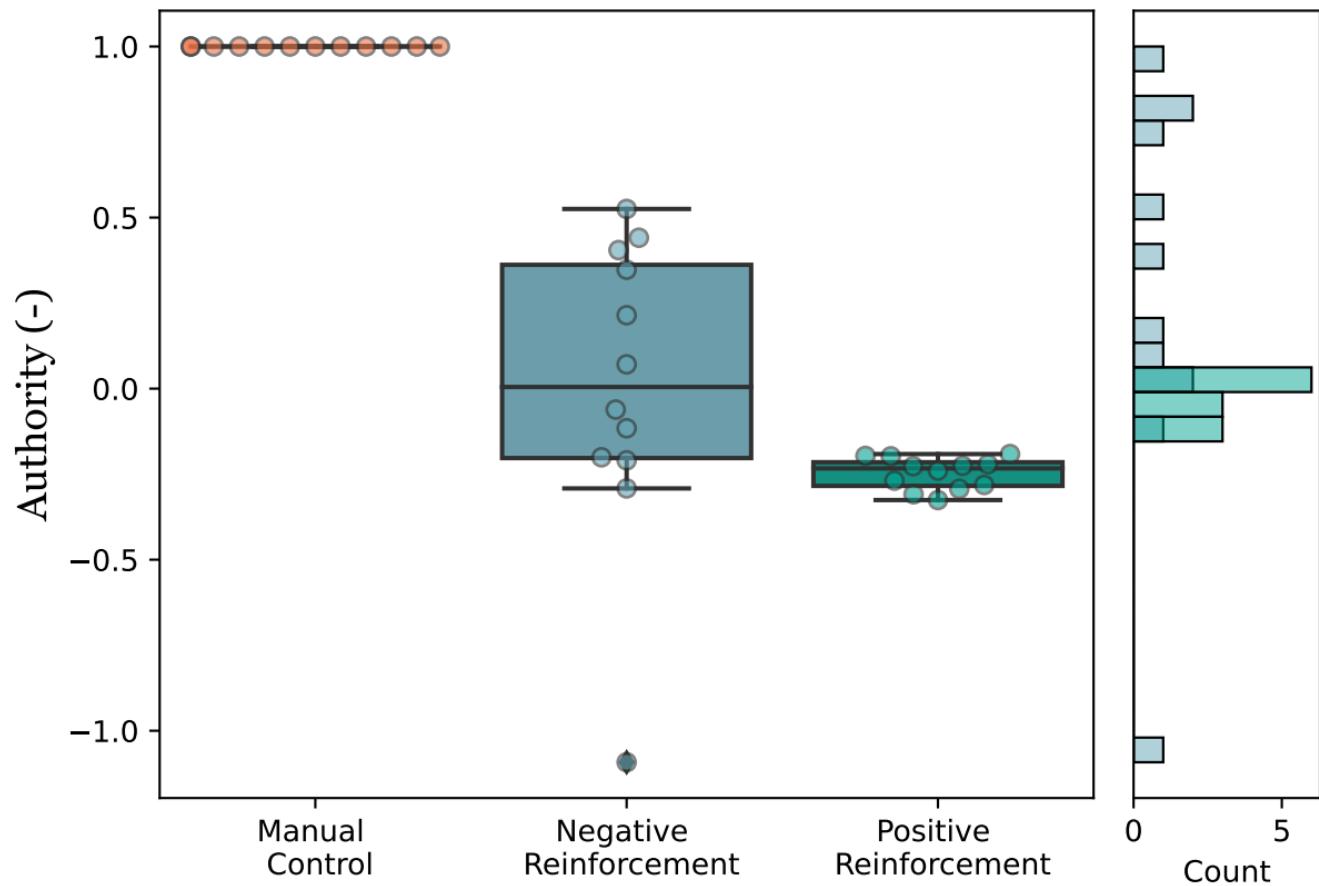


Manual Control

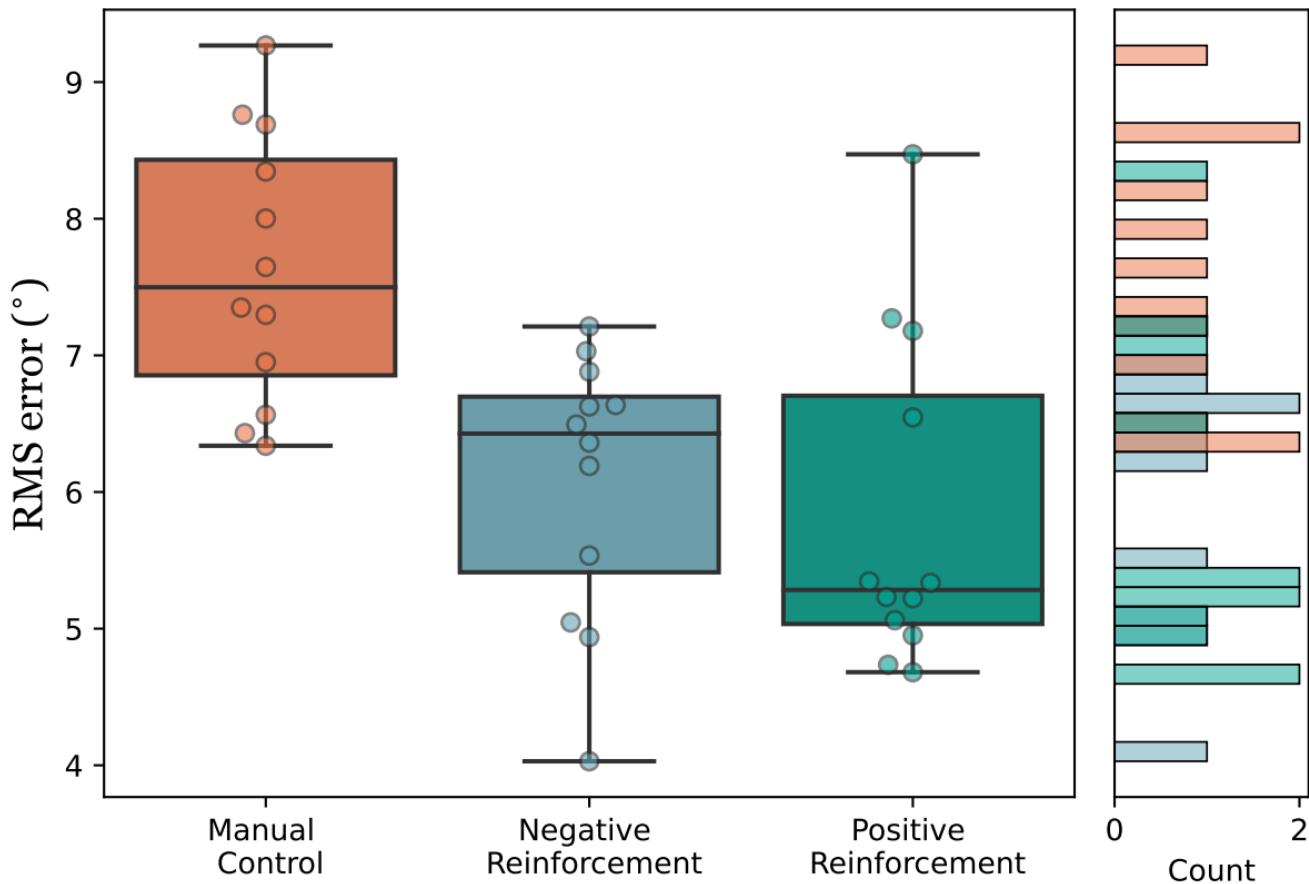




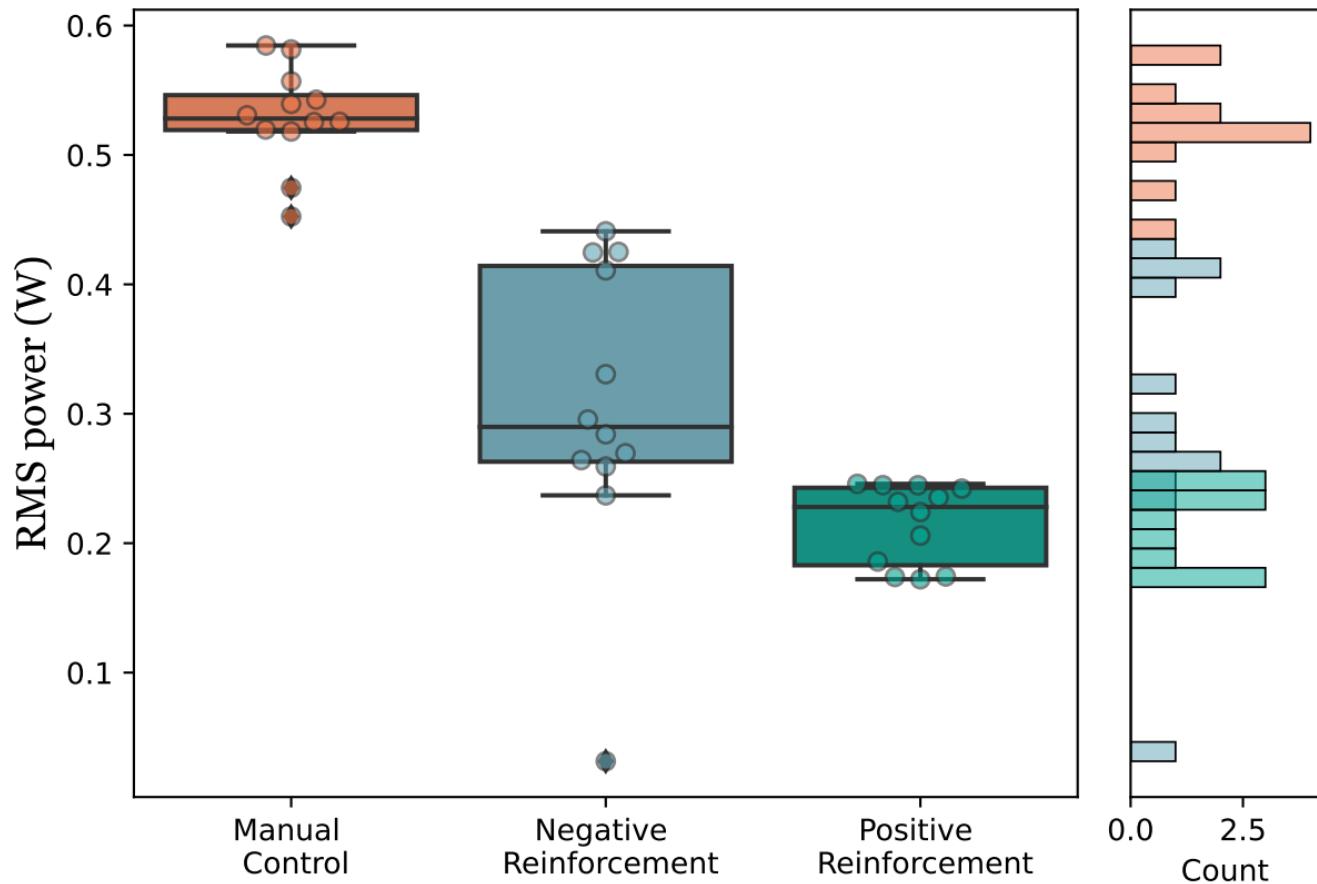
Control Authority



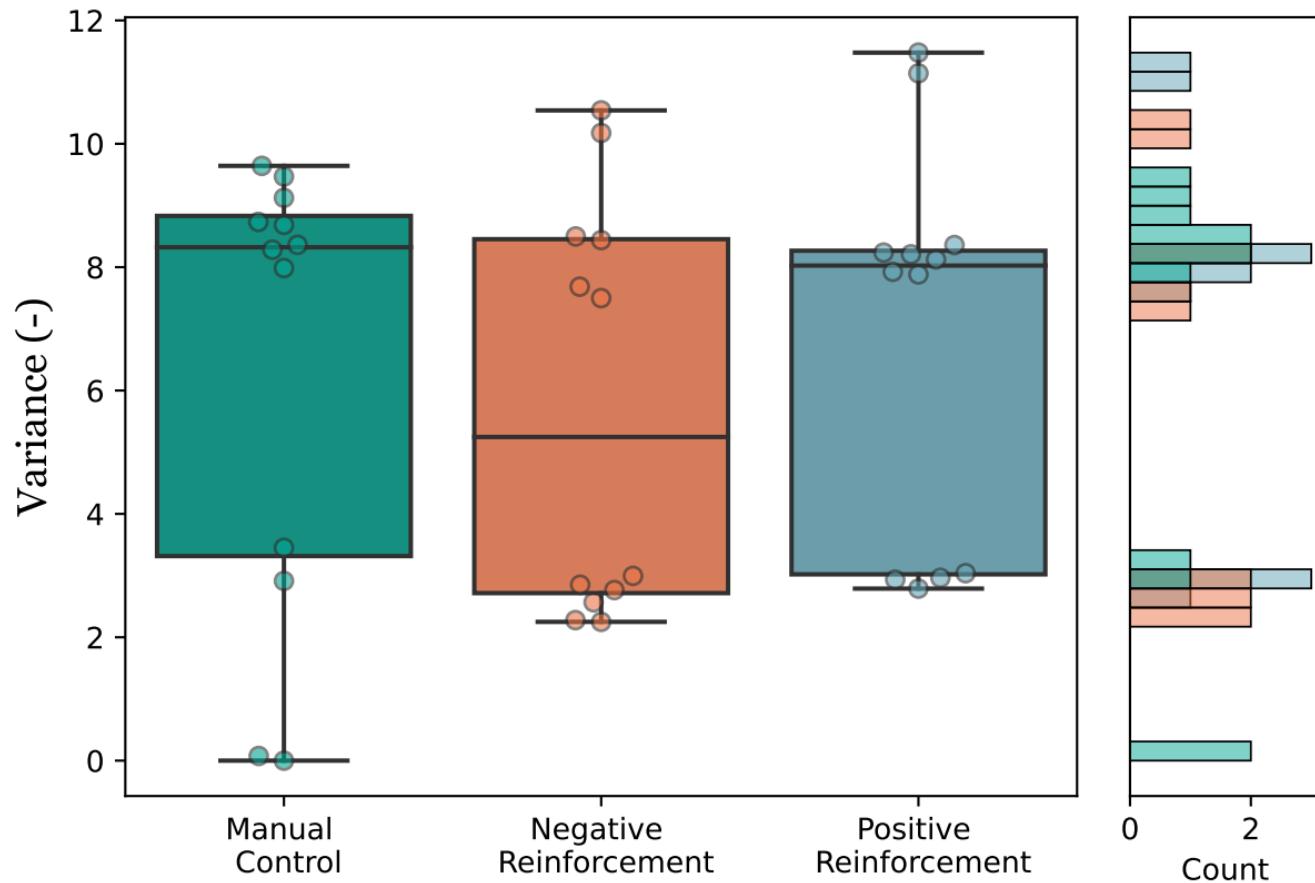
Steering Angle Error



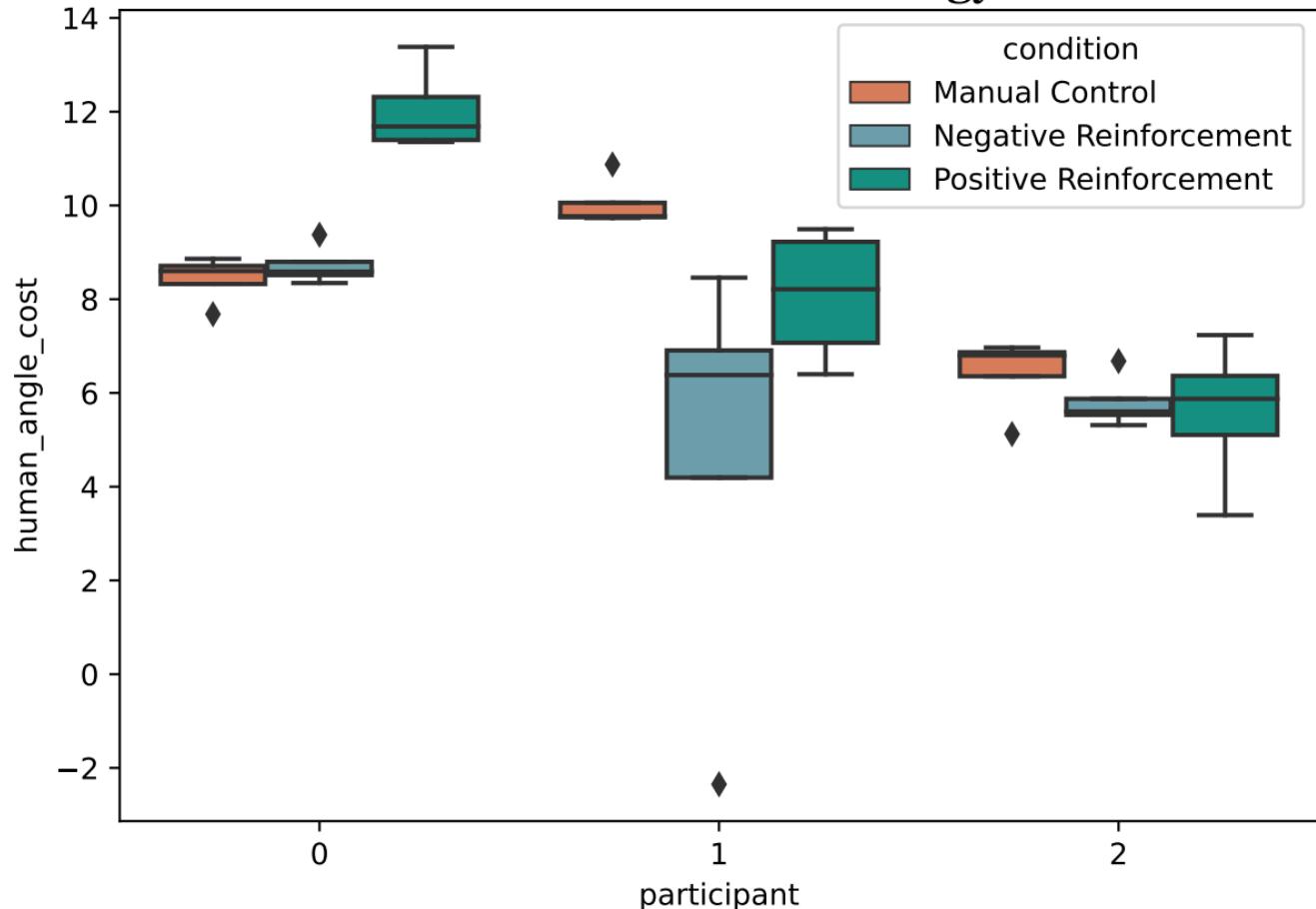
Human Input Power



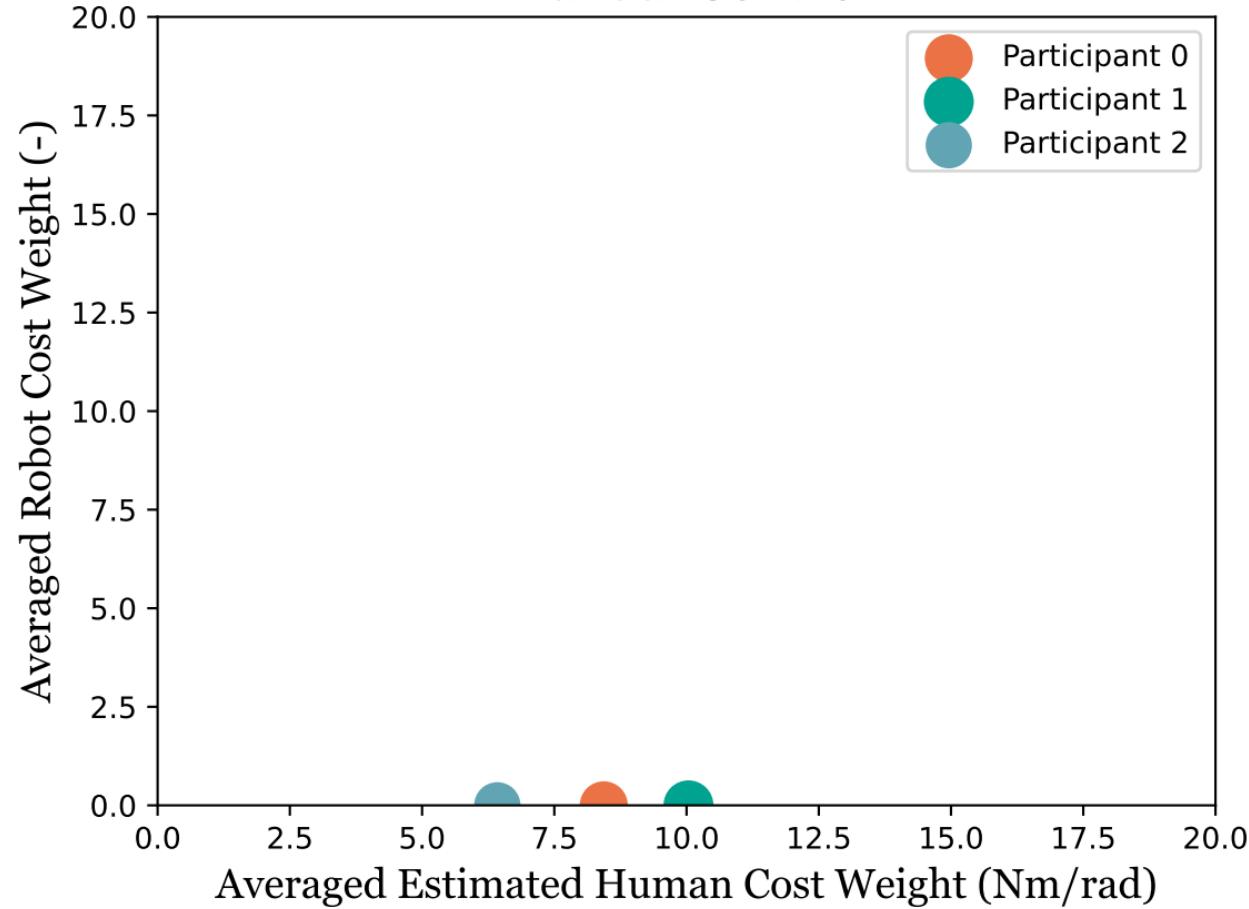
Cost function variability



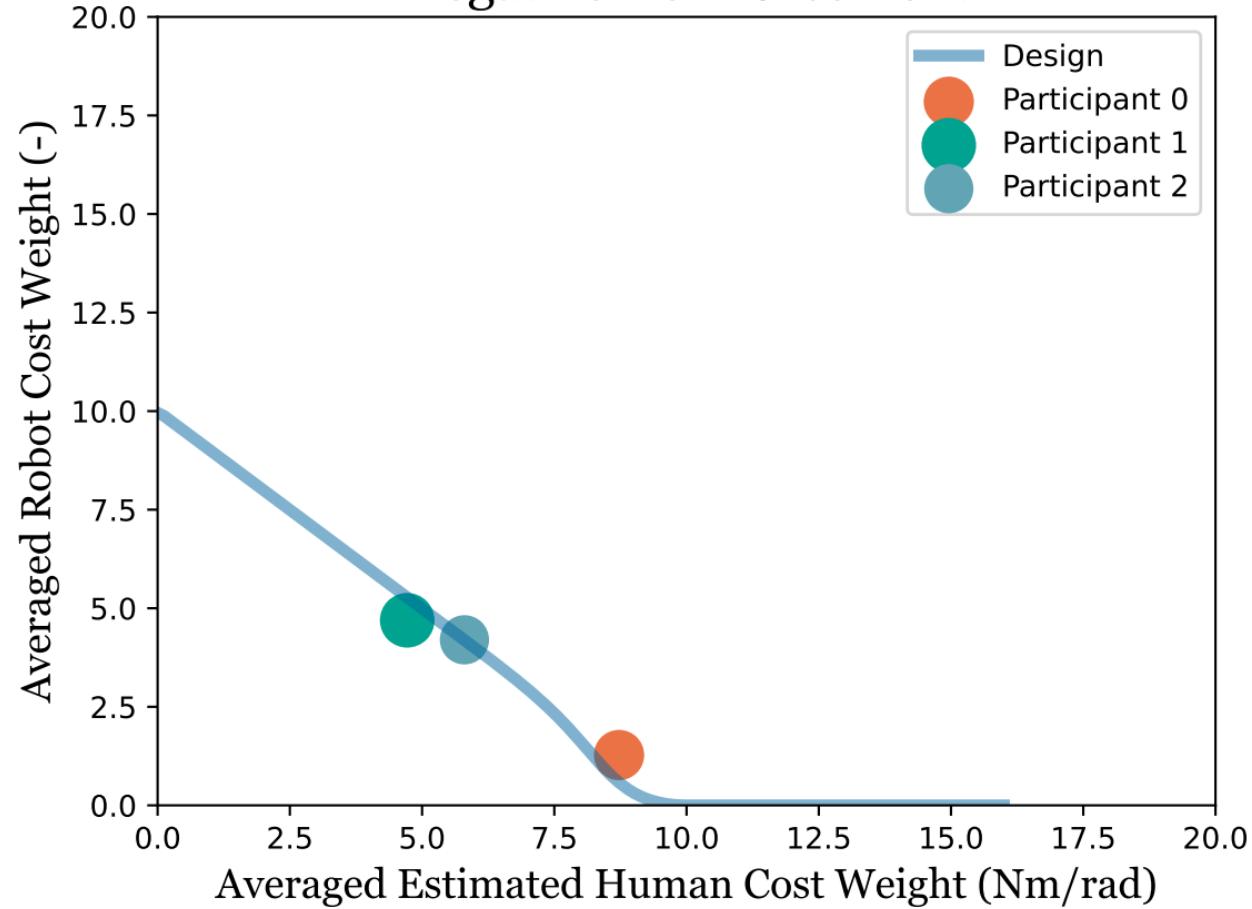
Human control strategy



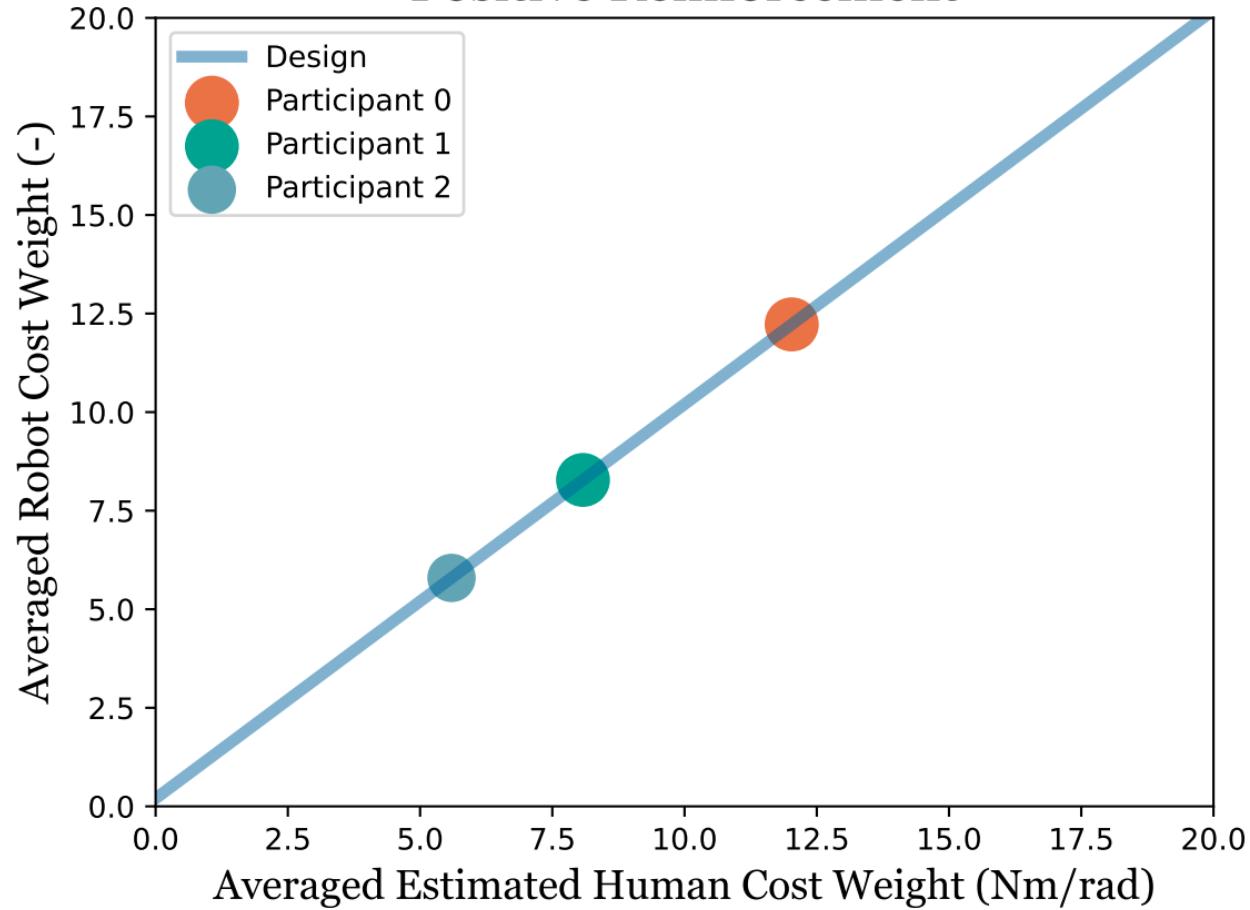
Manual Control



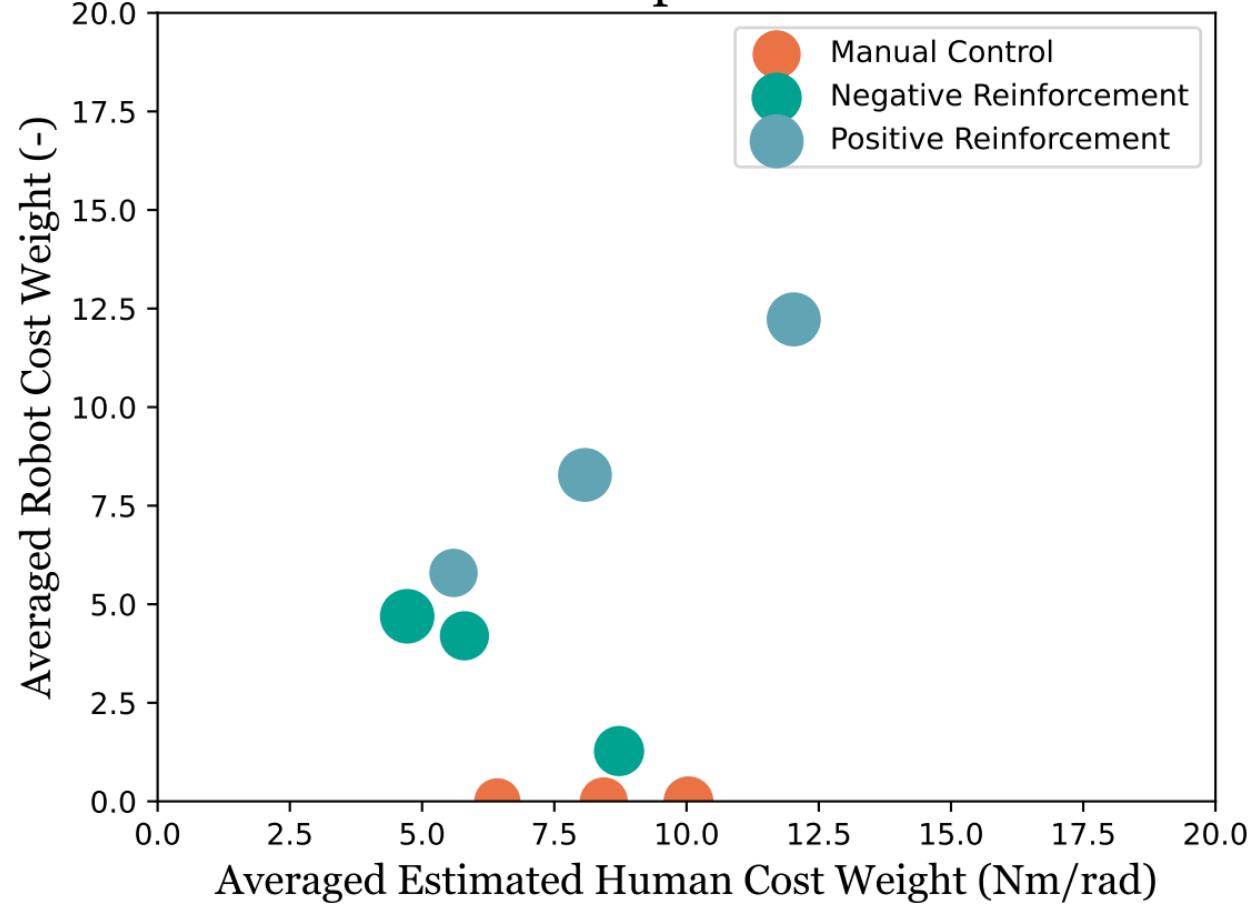
Negative Reinforcement



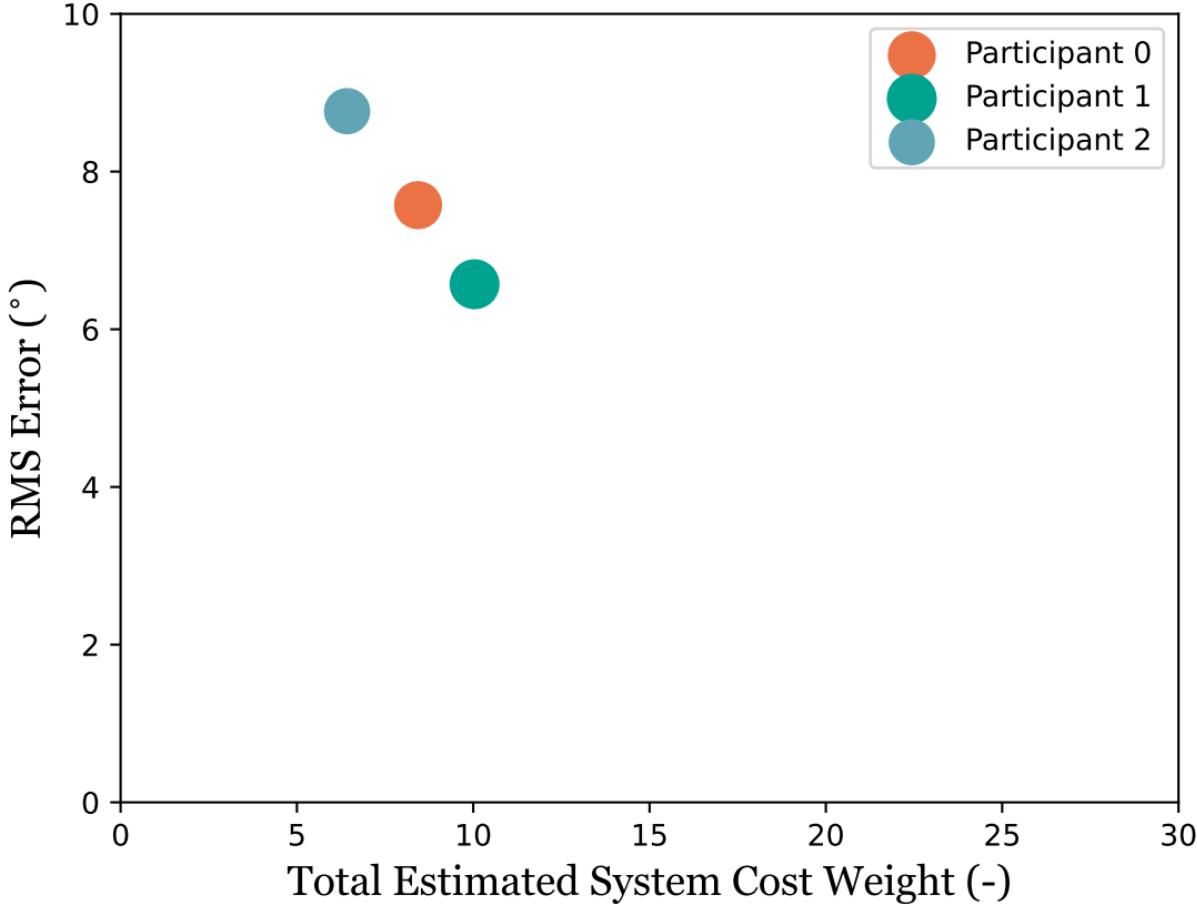
Positive Reinforcement



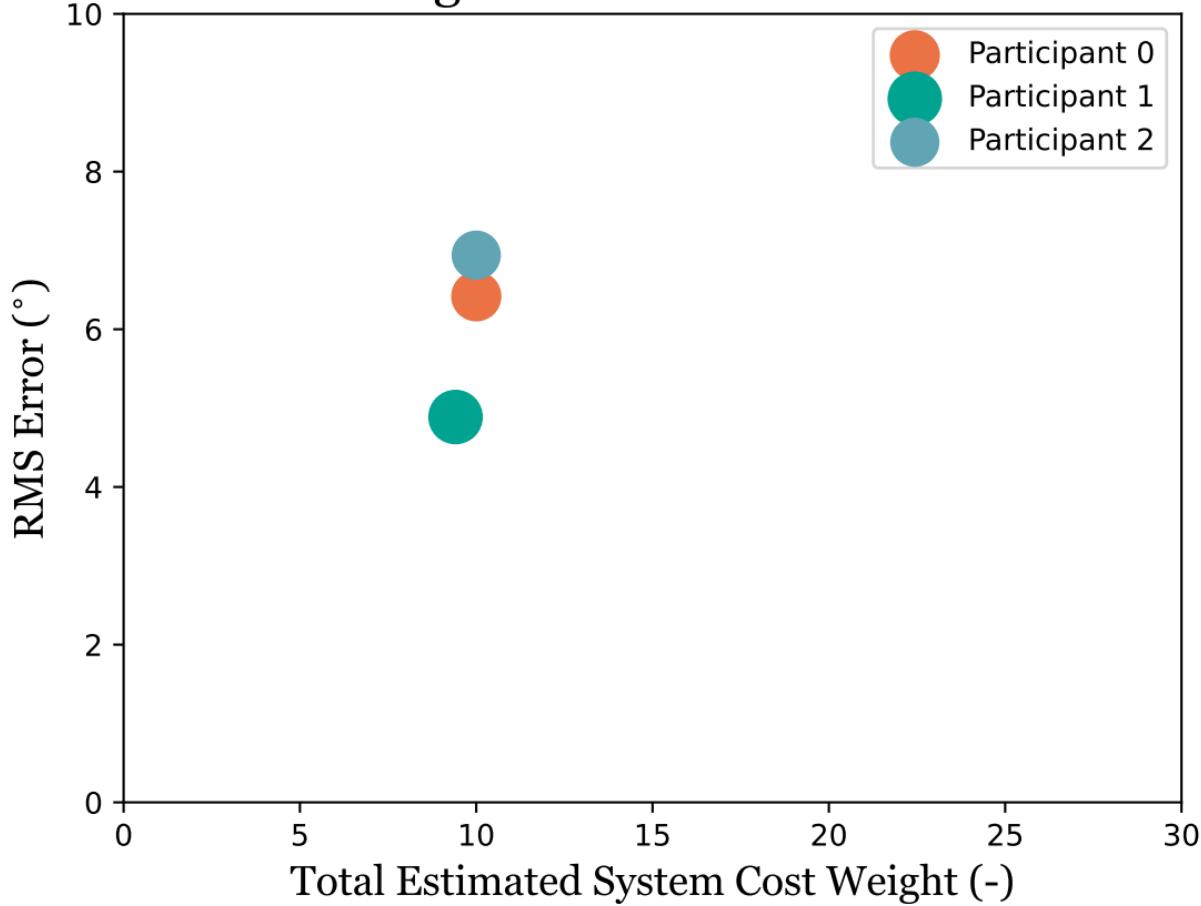
Comparison



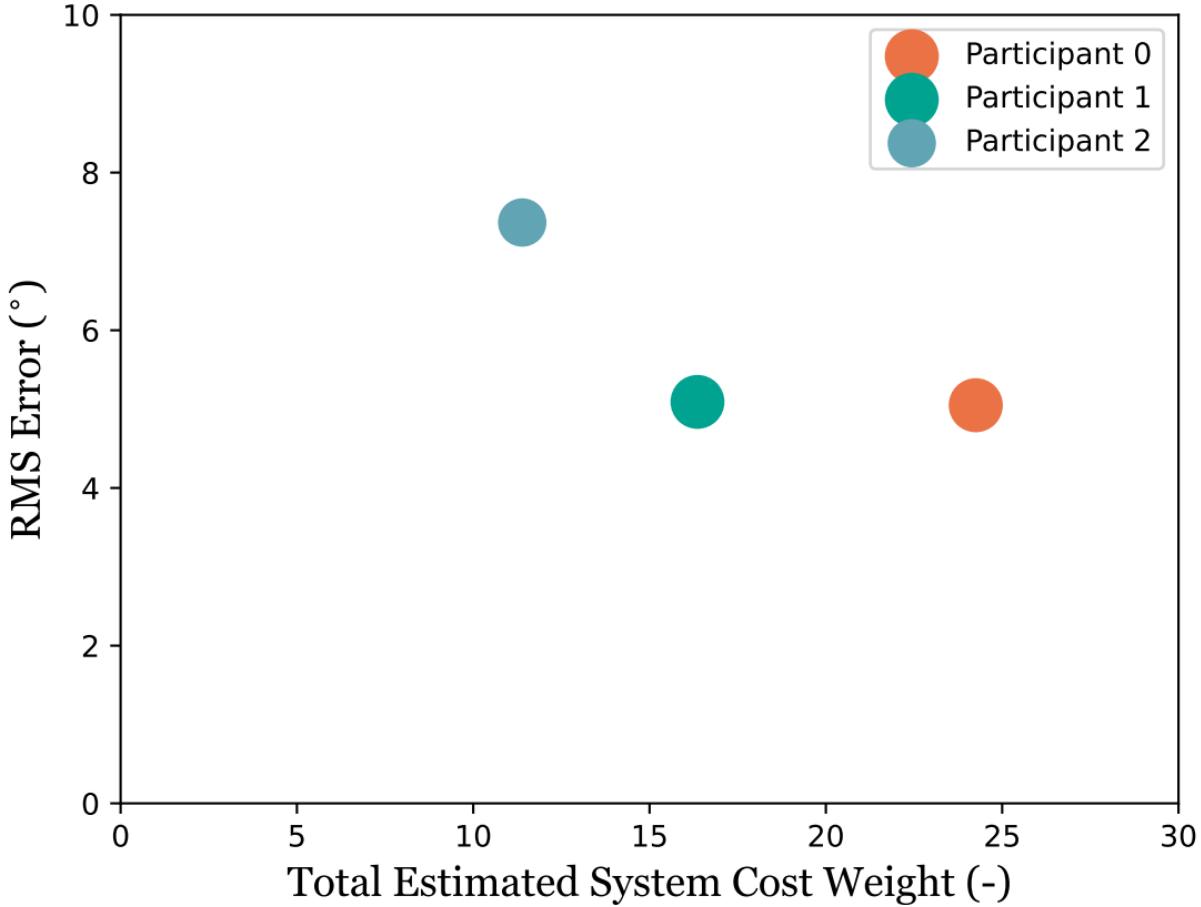
Manual Control



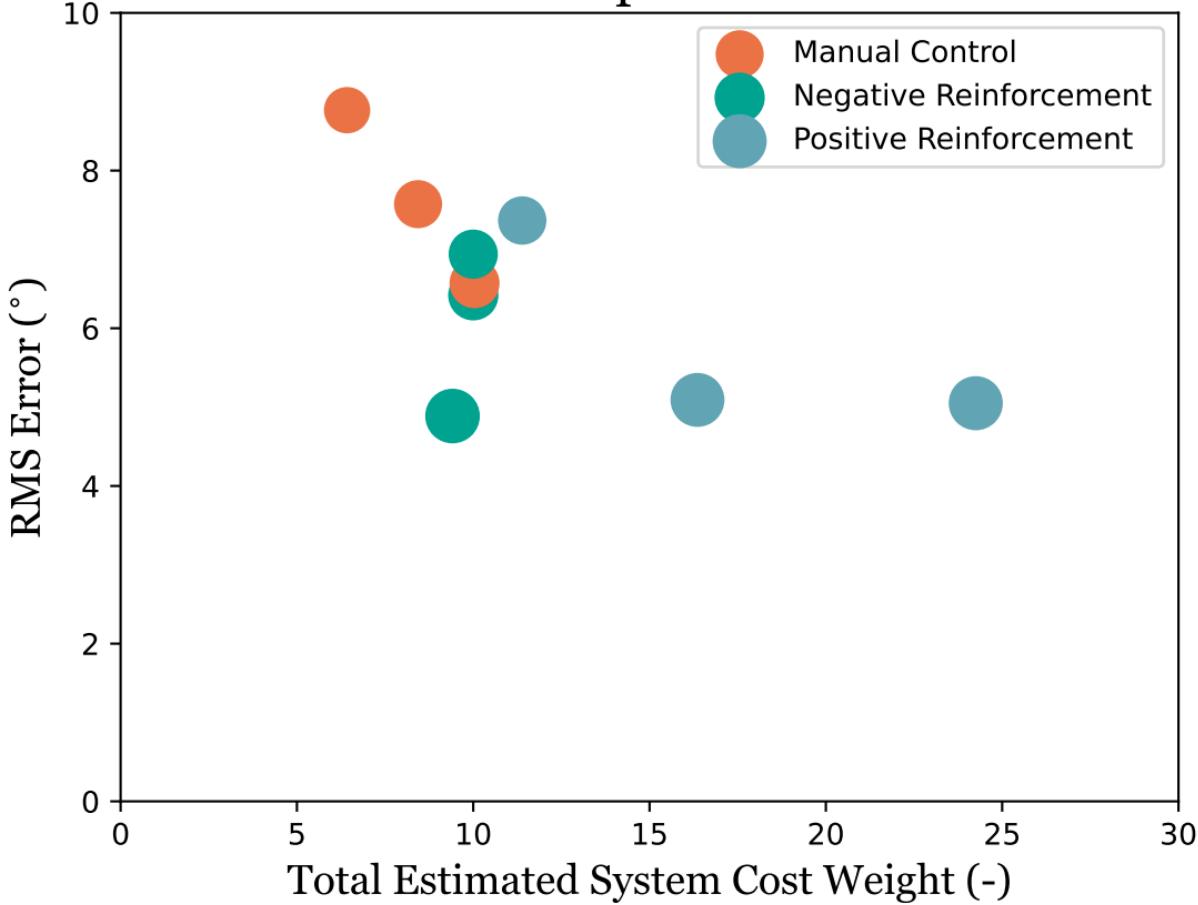
Negative Reinforcement



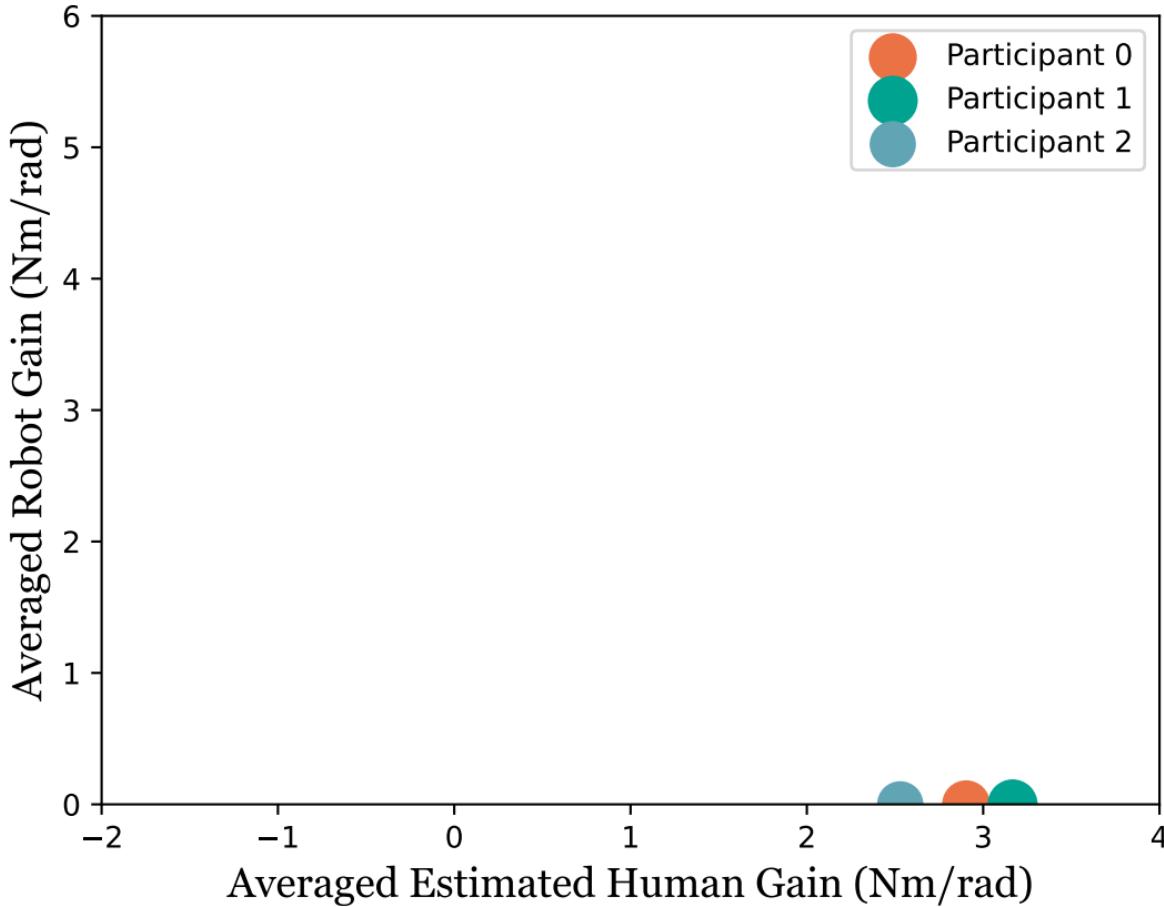
Positive Reinforcement



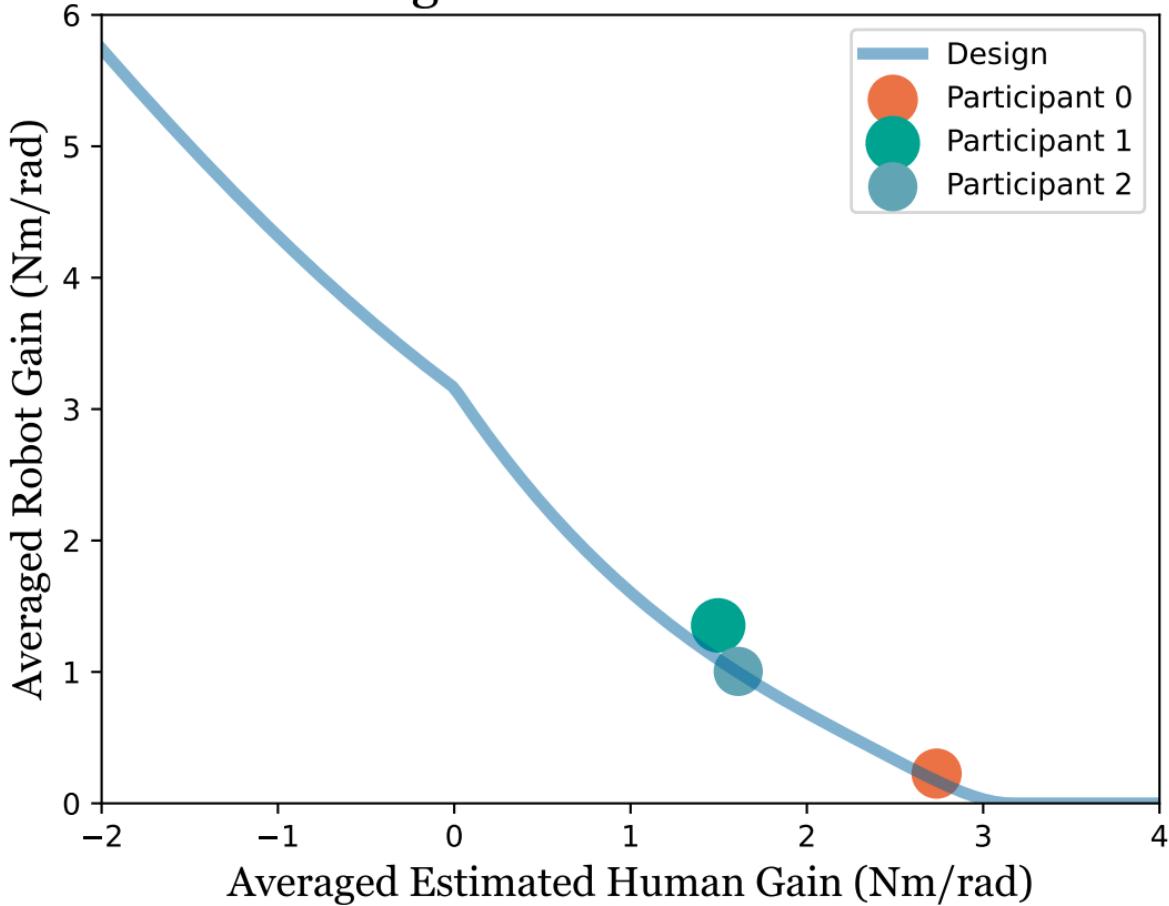
Comparison



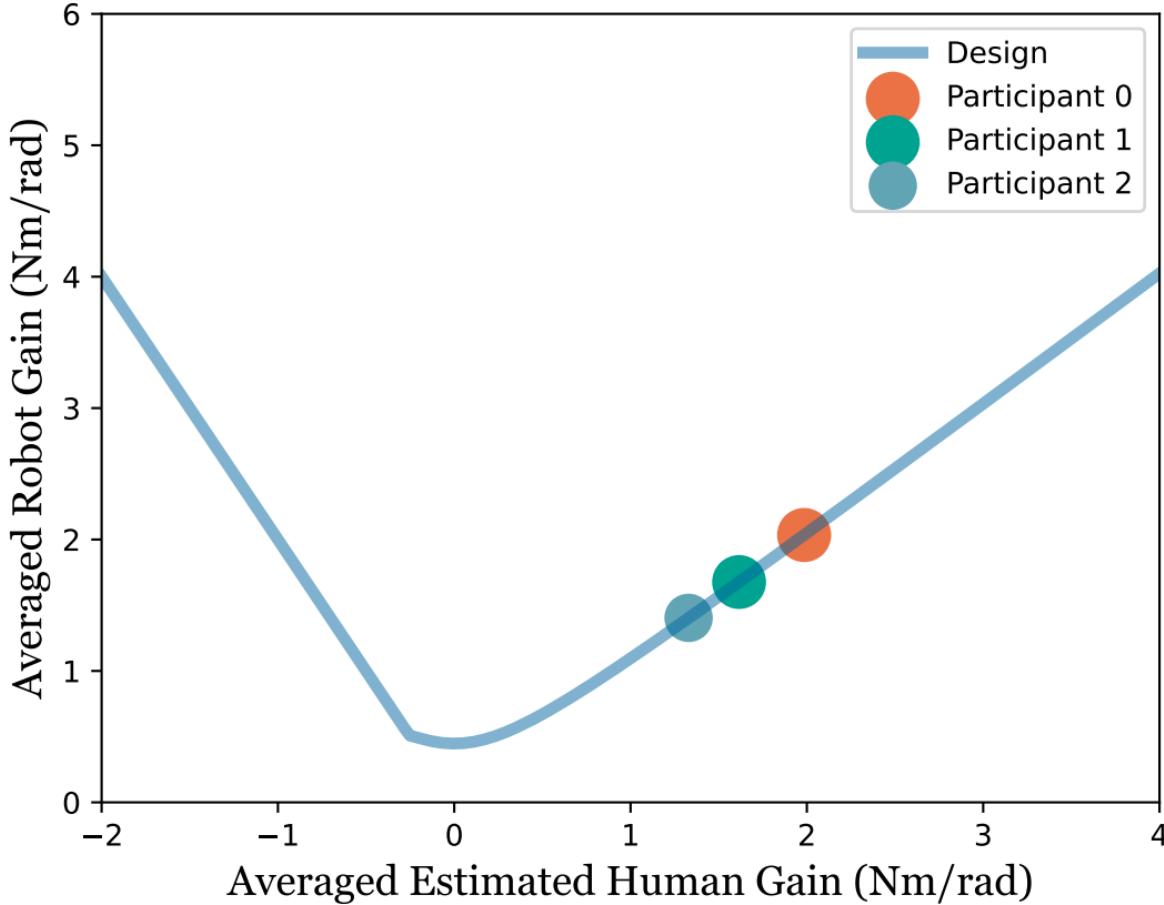
Manual Control



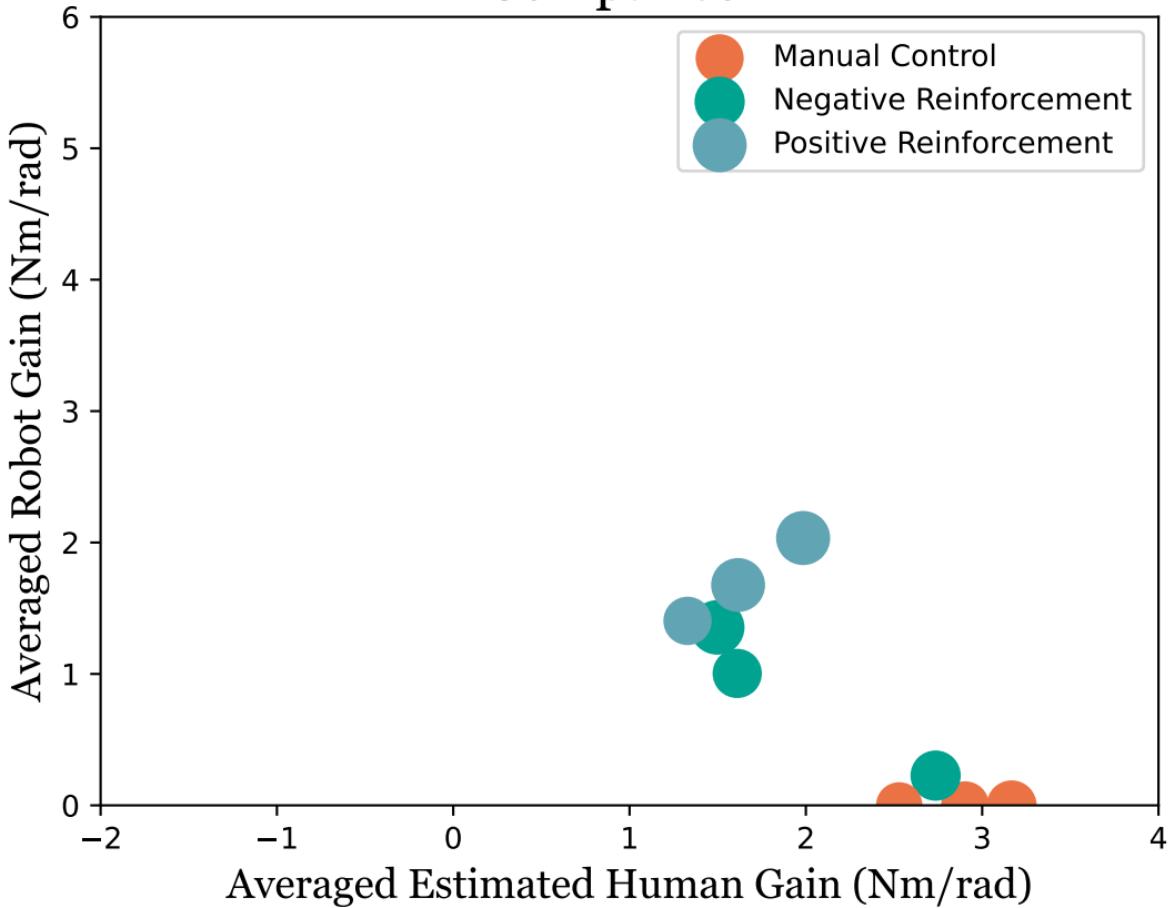
Negative Reinforcement



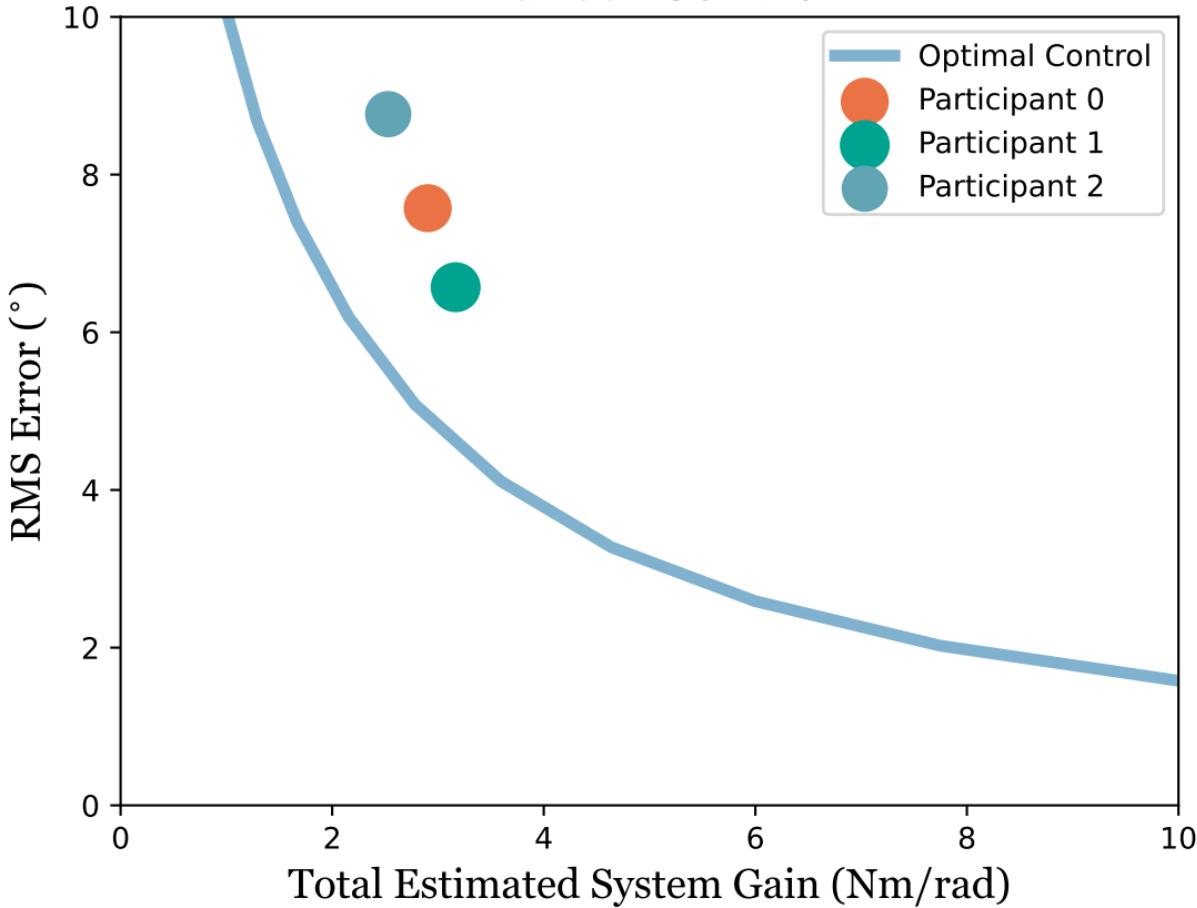
Positive Reinforcement



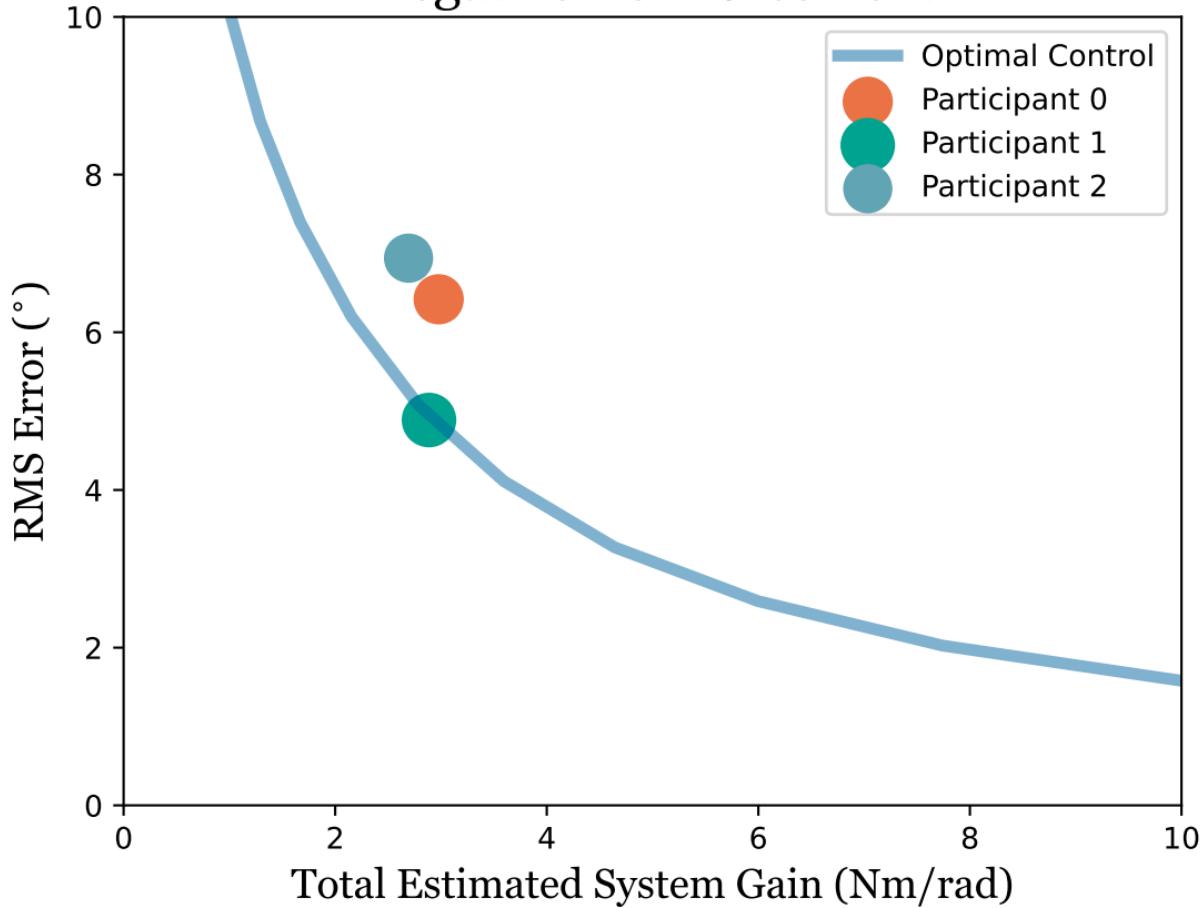
Comparison



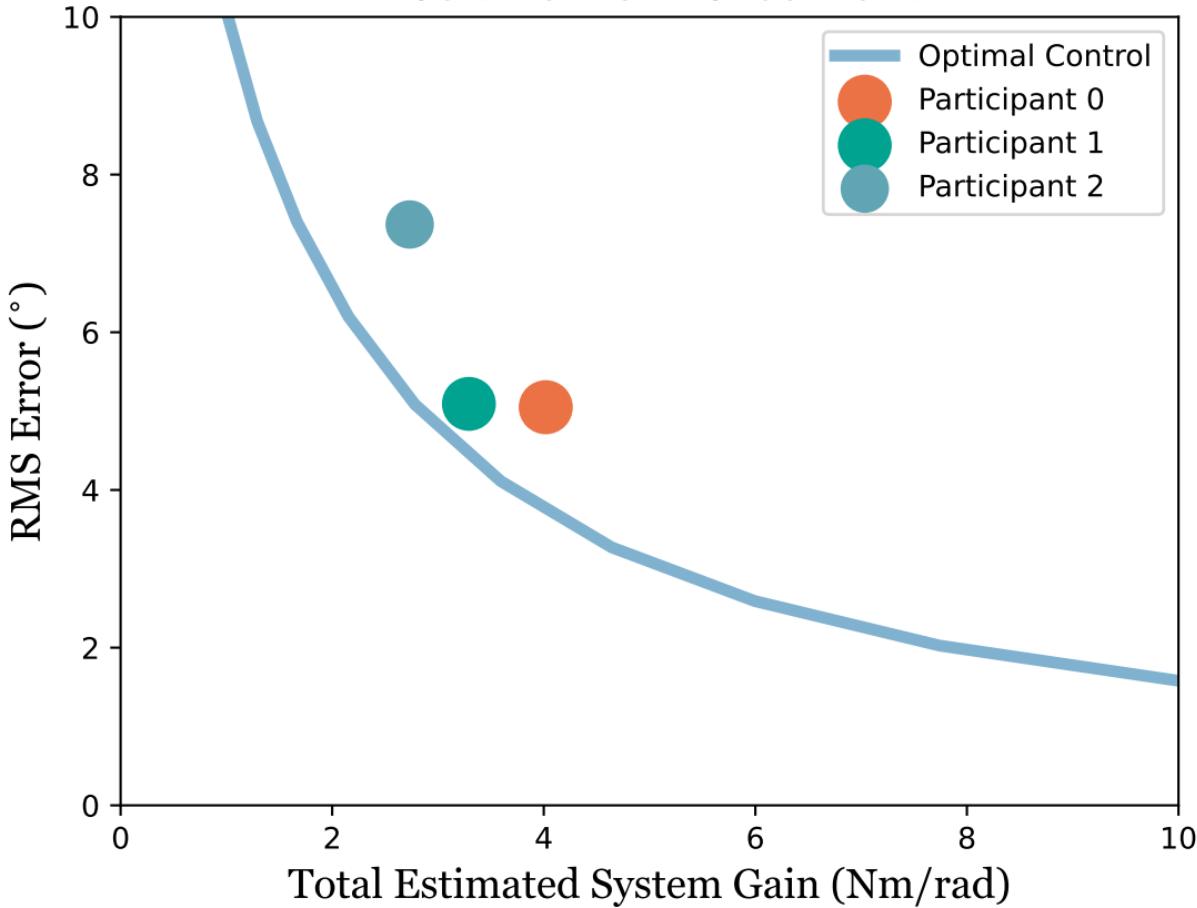
Manual Control



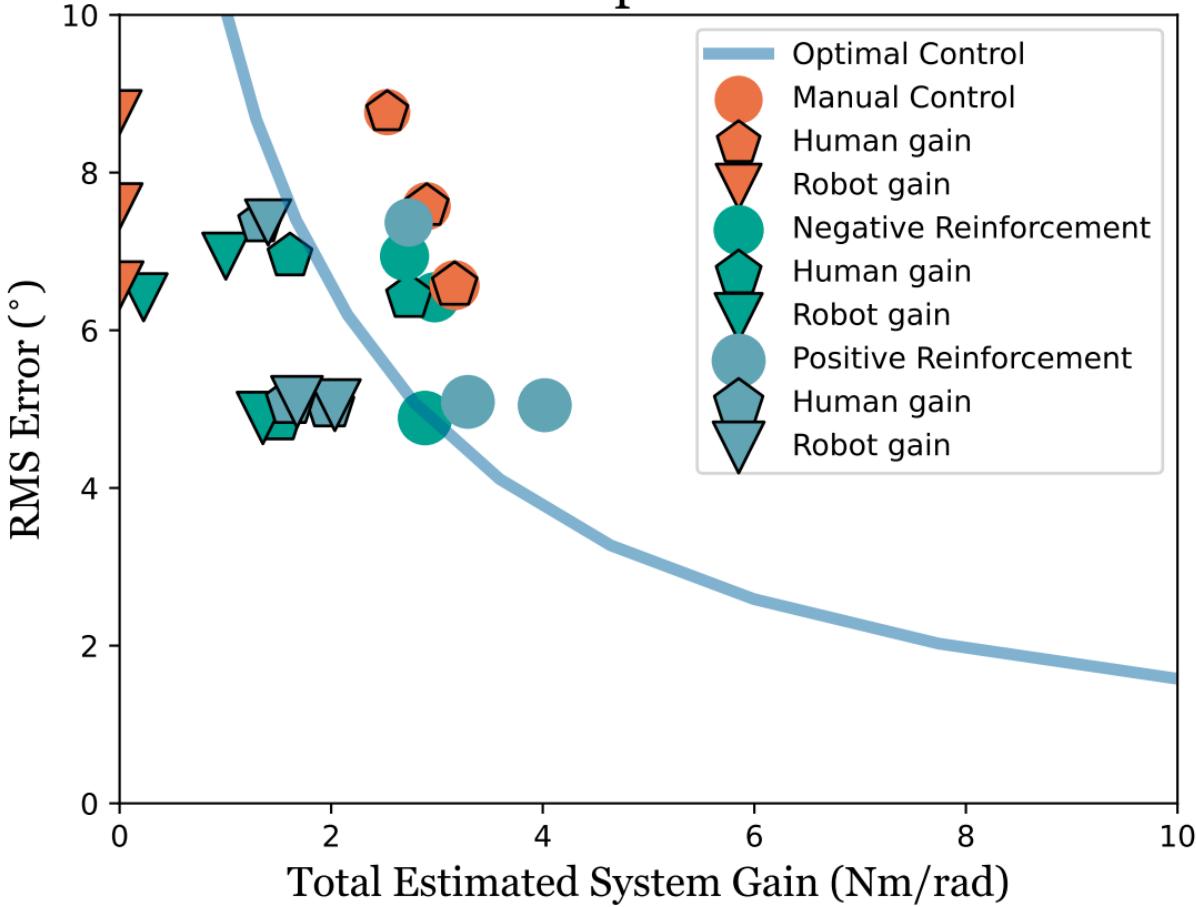
Negative Reinforcement



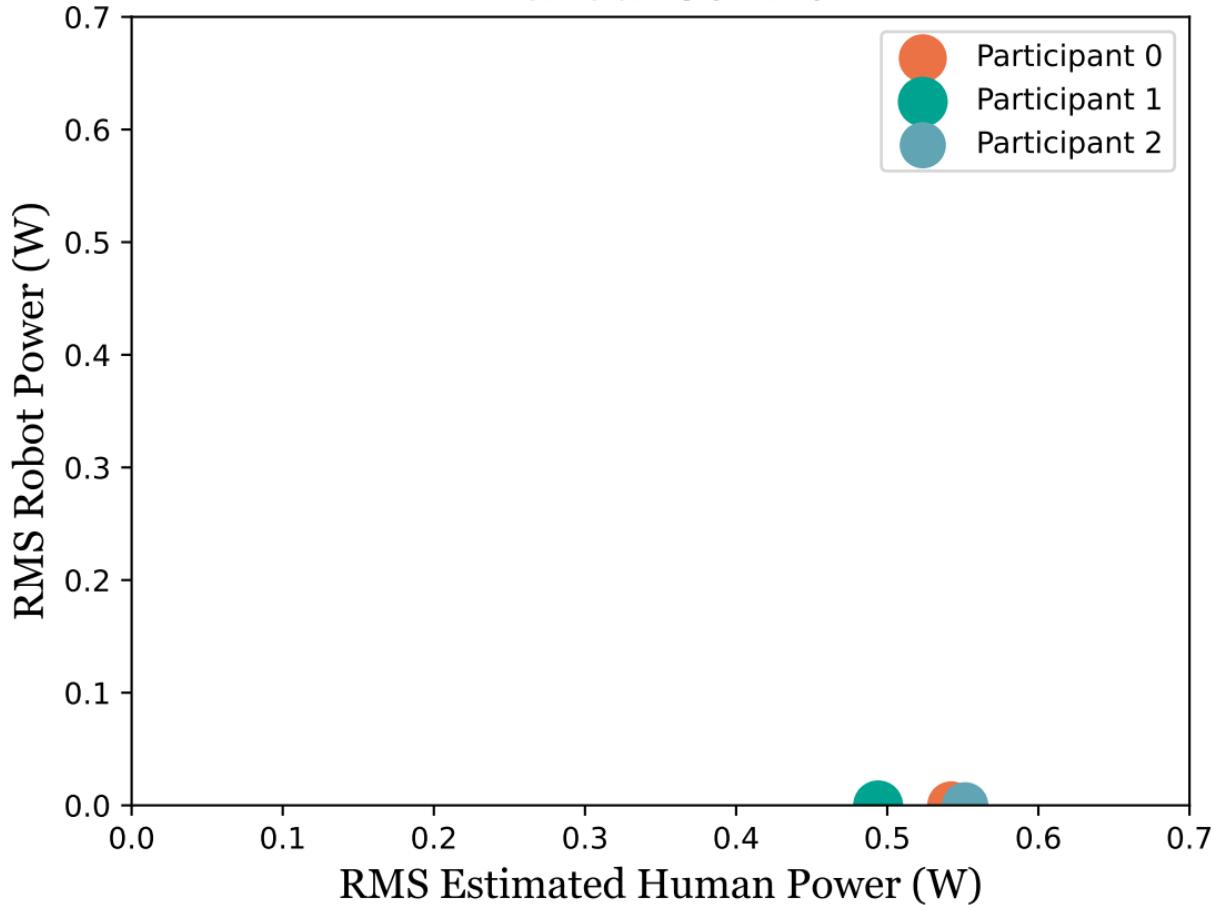
Positive Reinforcement



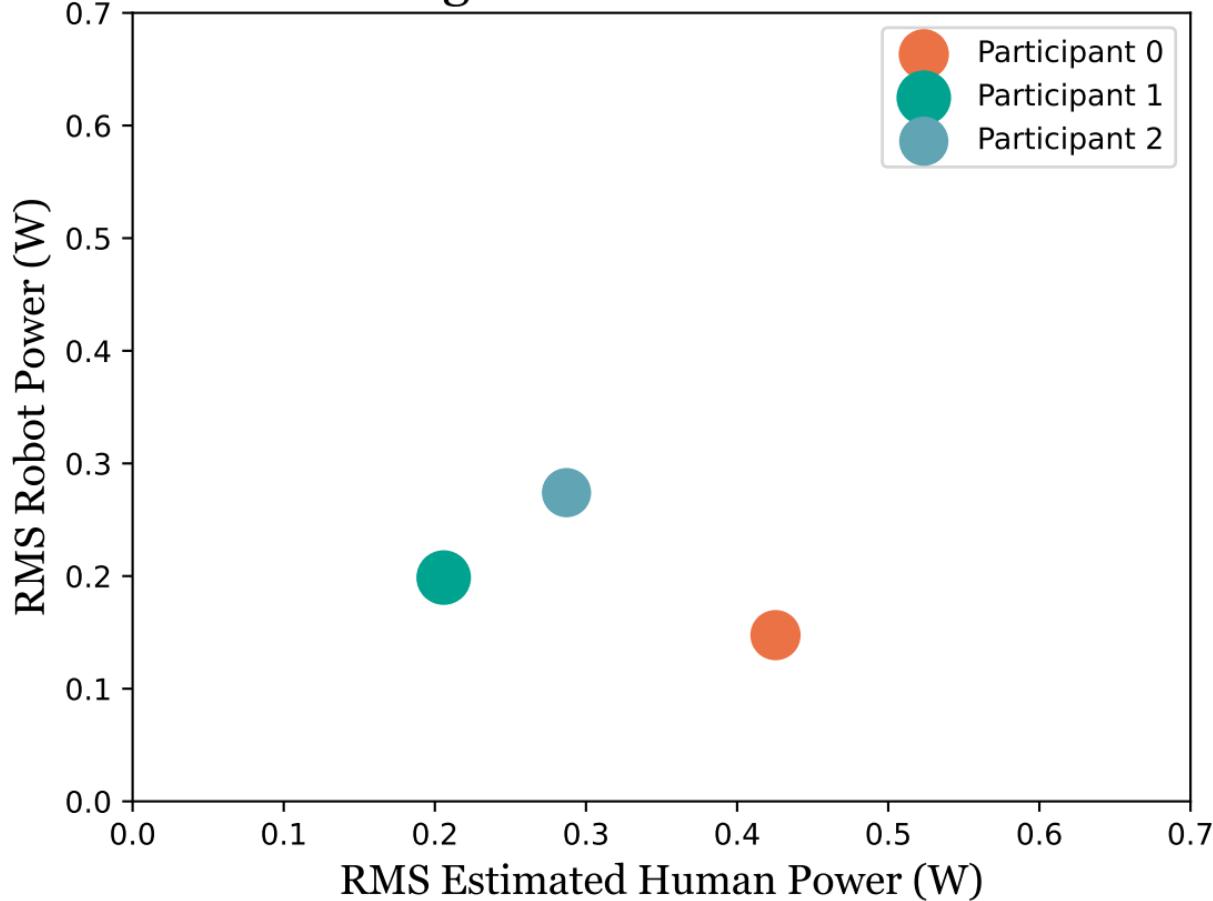
Comparison



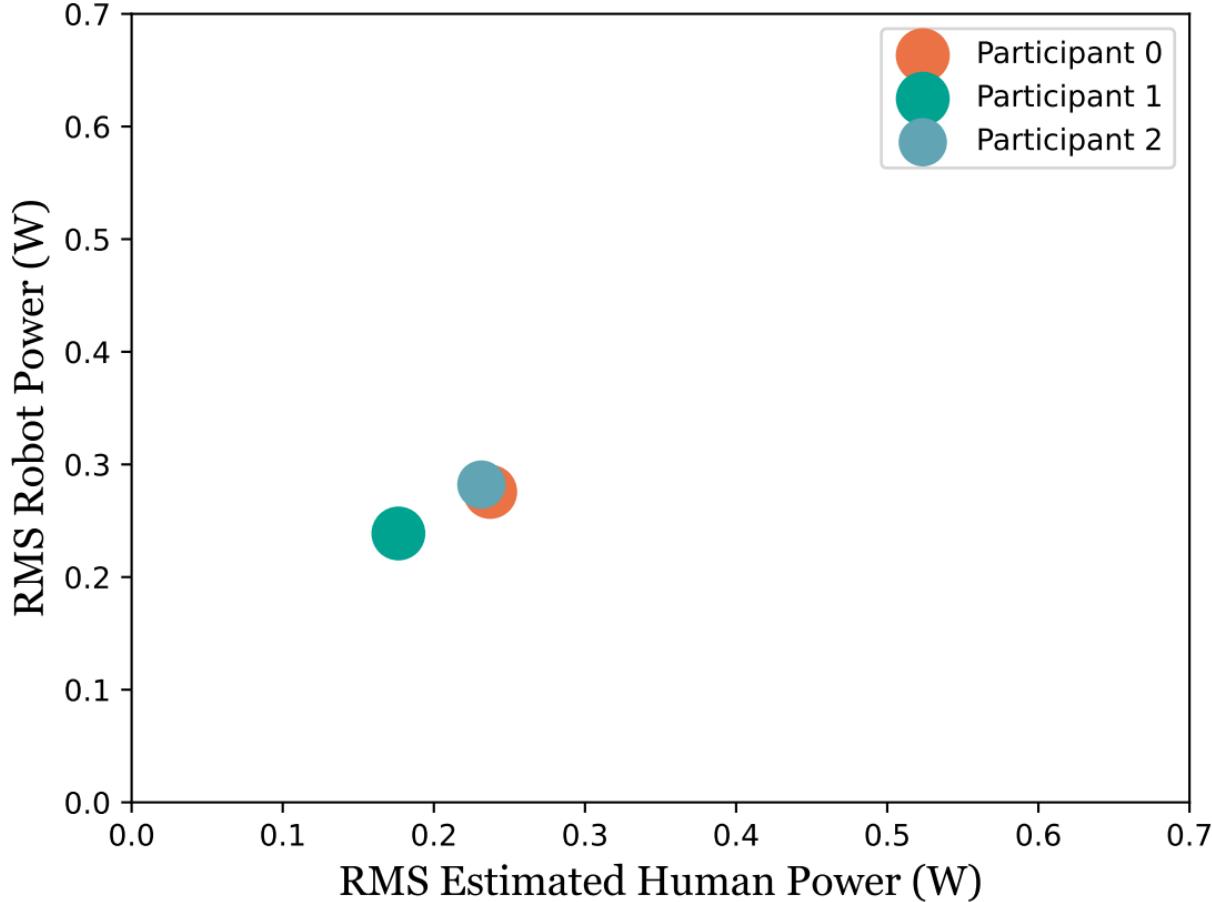
Manual Control



Negative Reinforcement



Positive Reinforcement



Comparison

