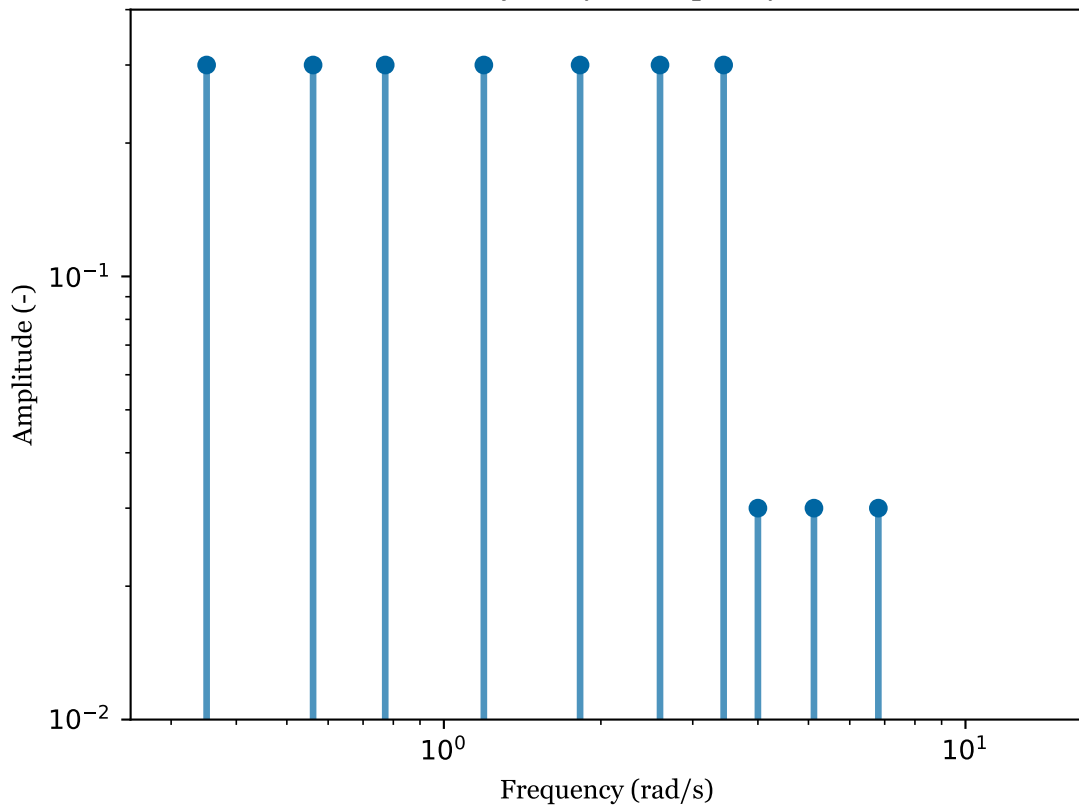
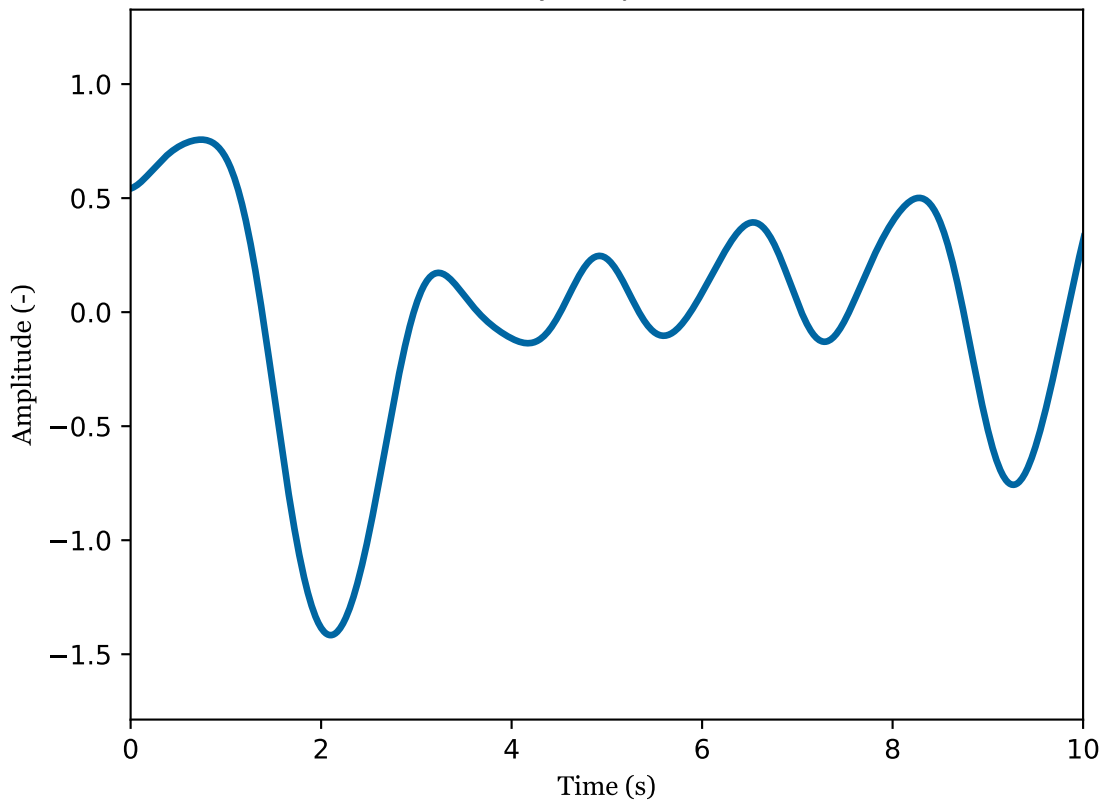


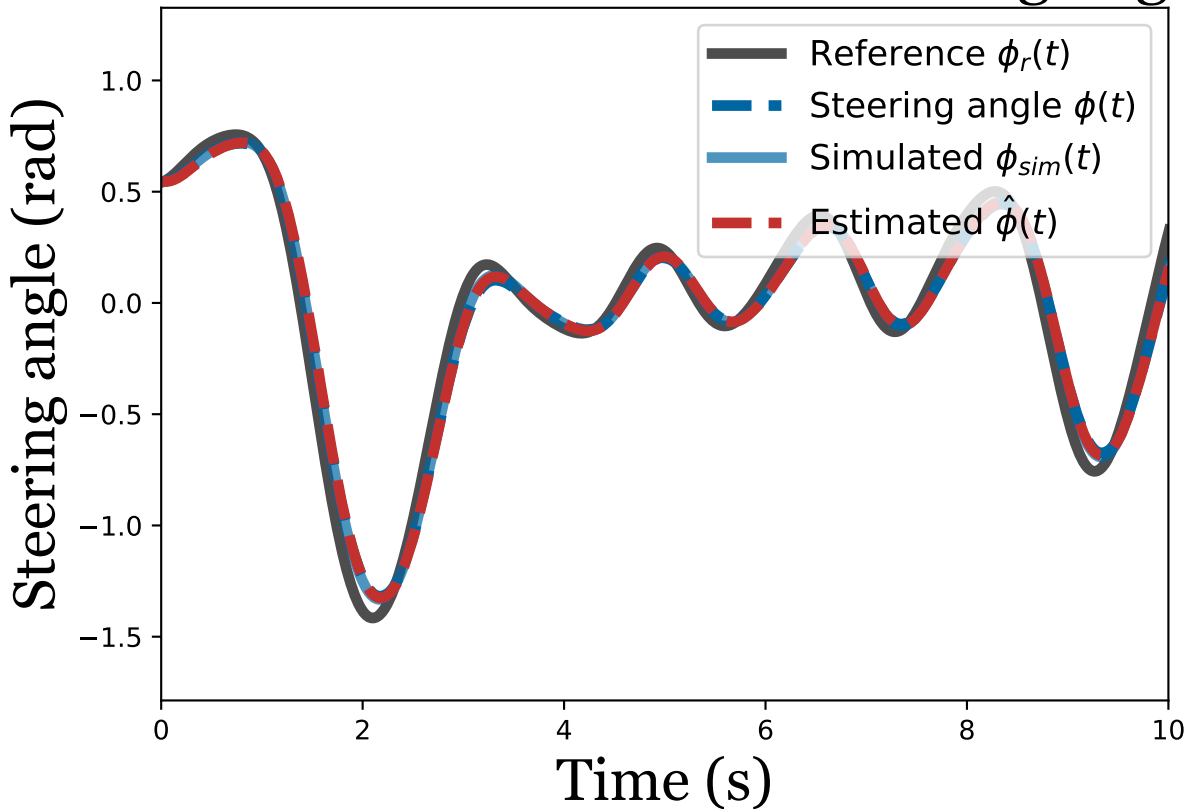
Reference trajectory in frequency domain



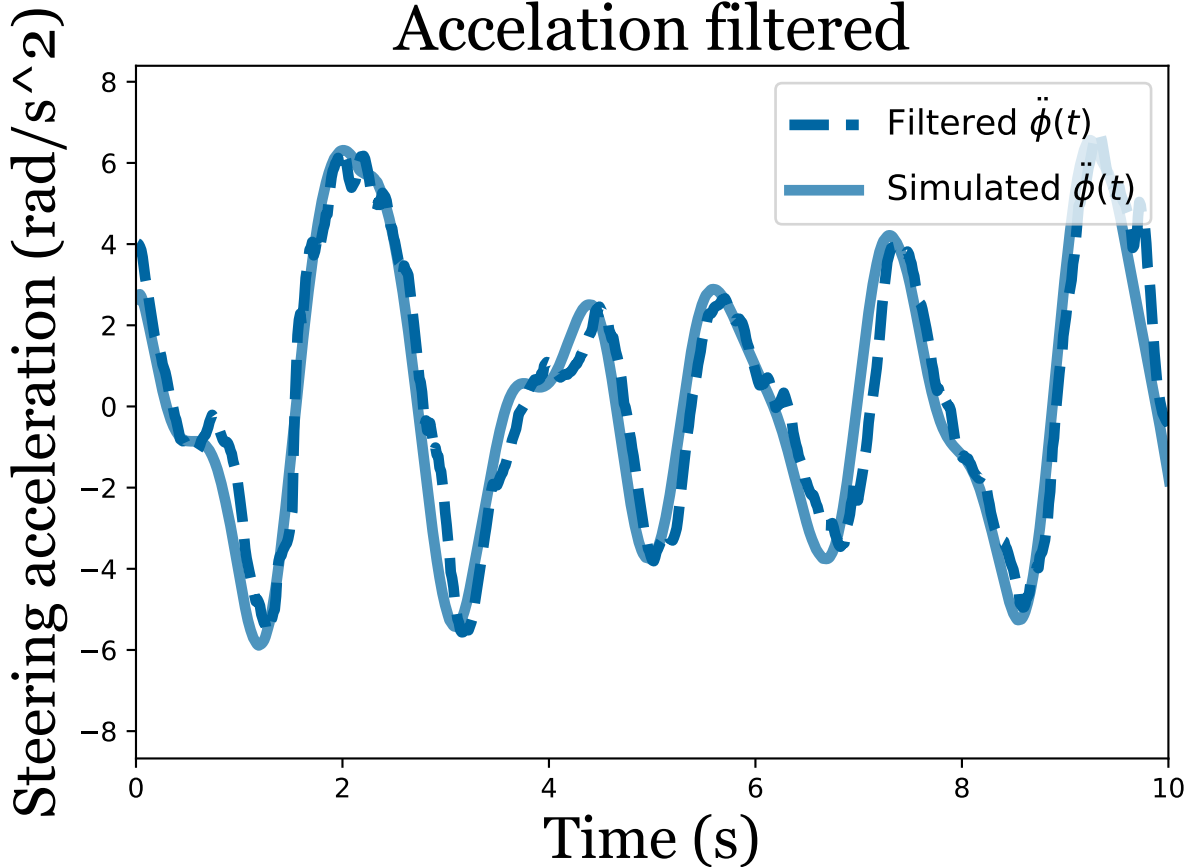
Reference trajectory in time domain



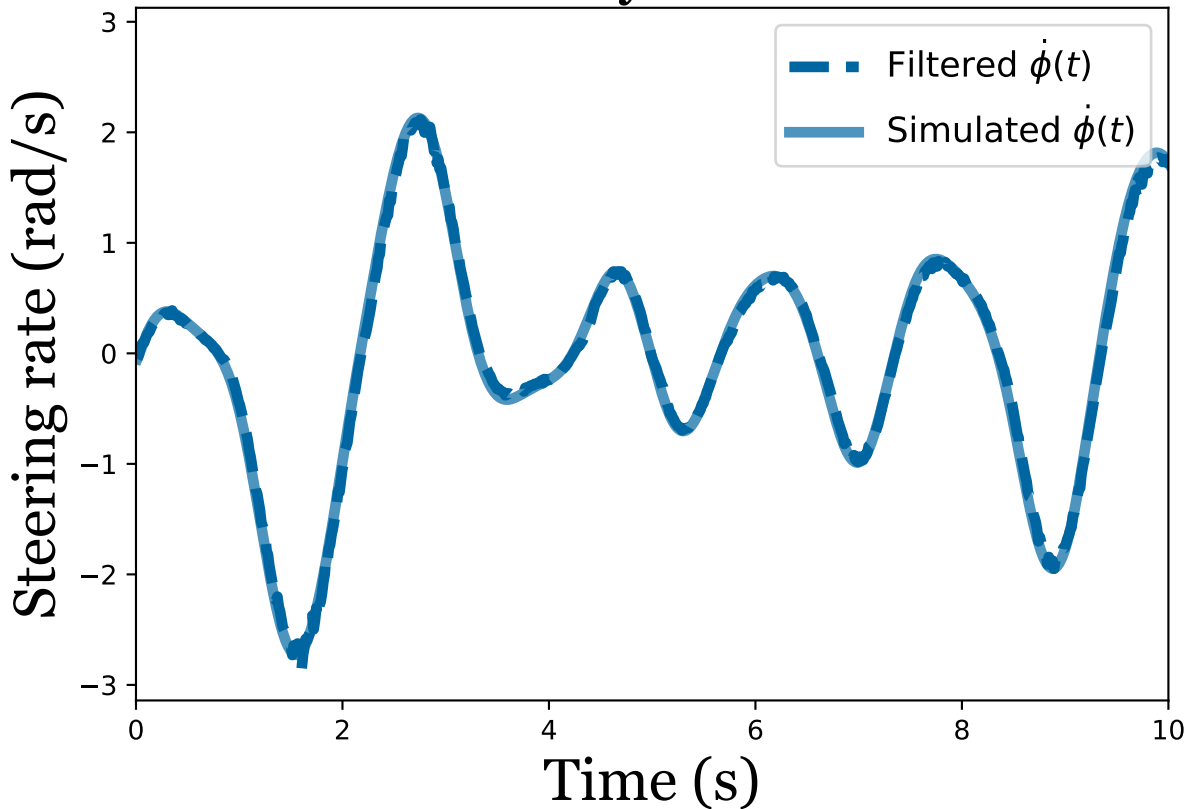
Measured and estimated steering angle

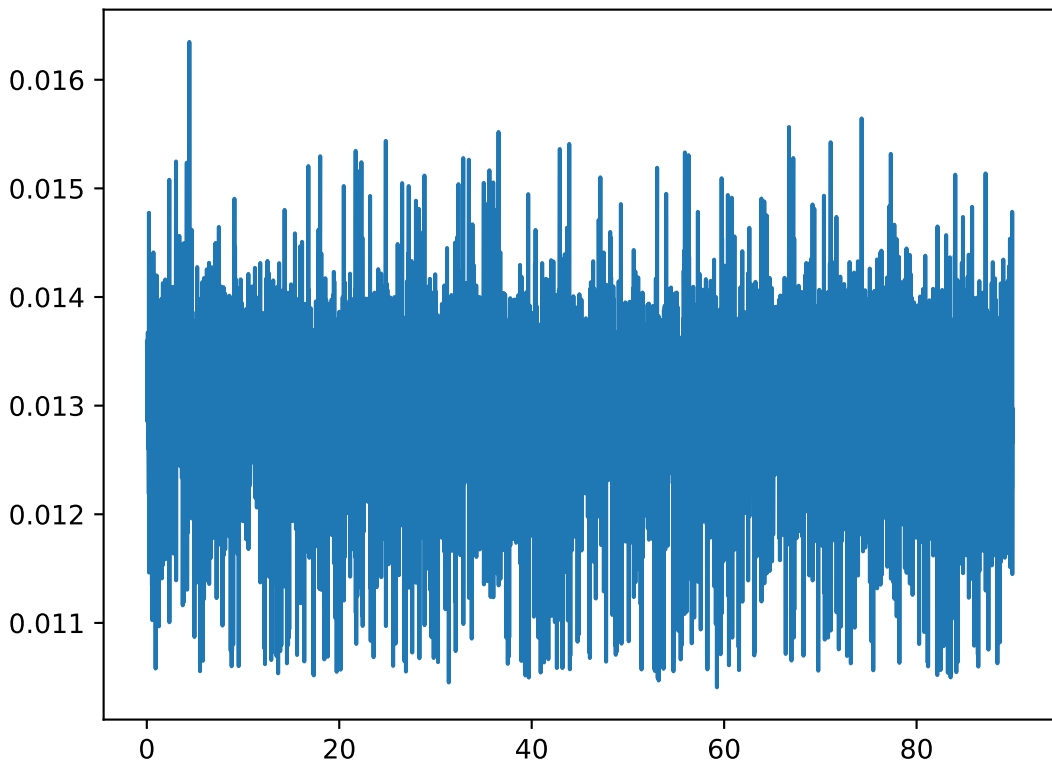


Acceleration filtered



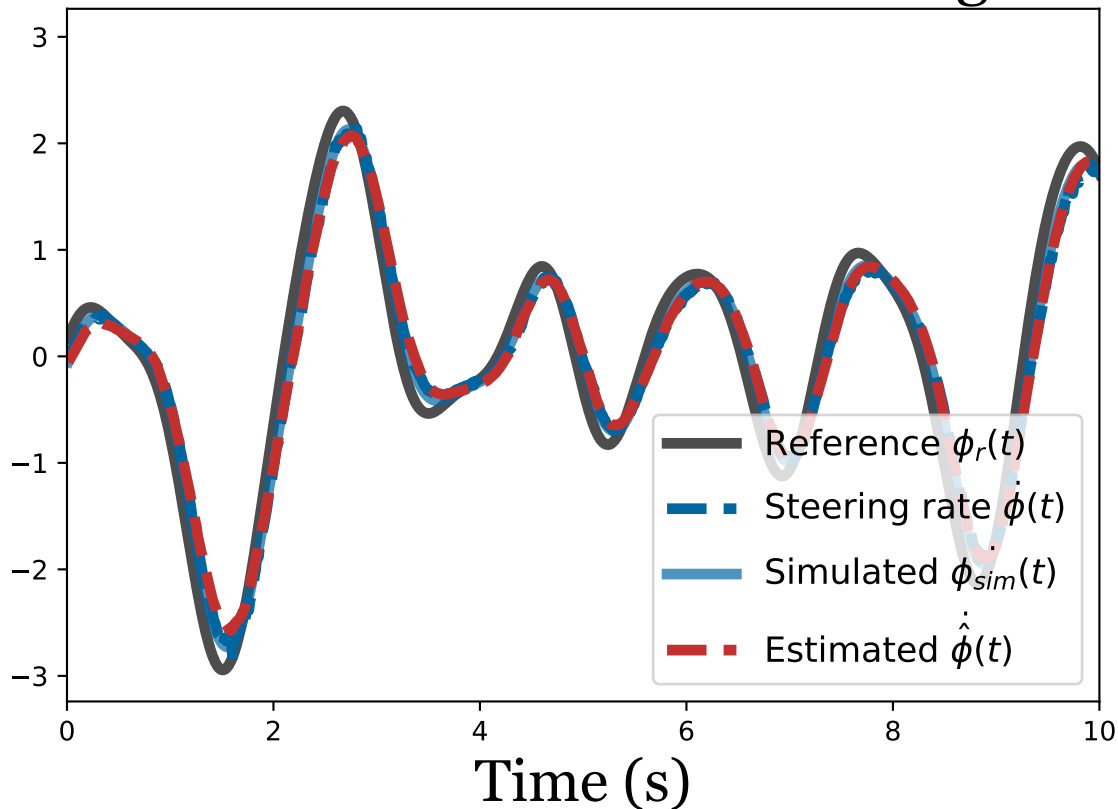
velocity filtered



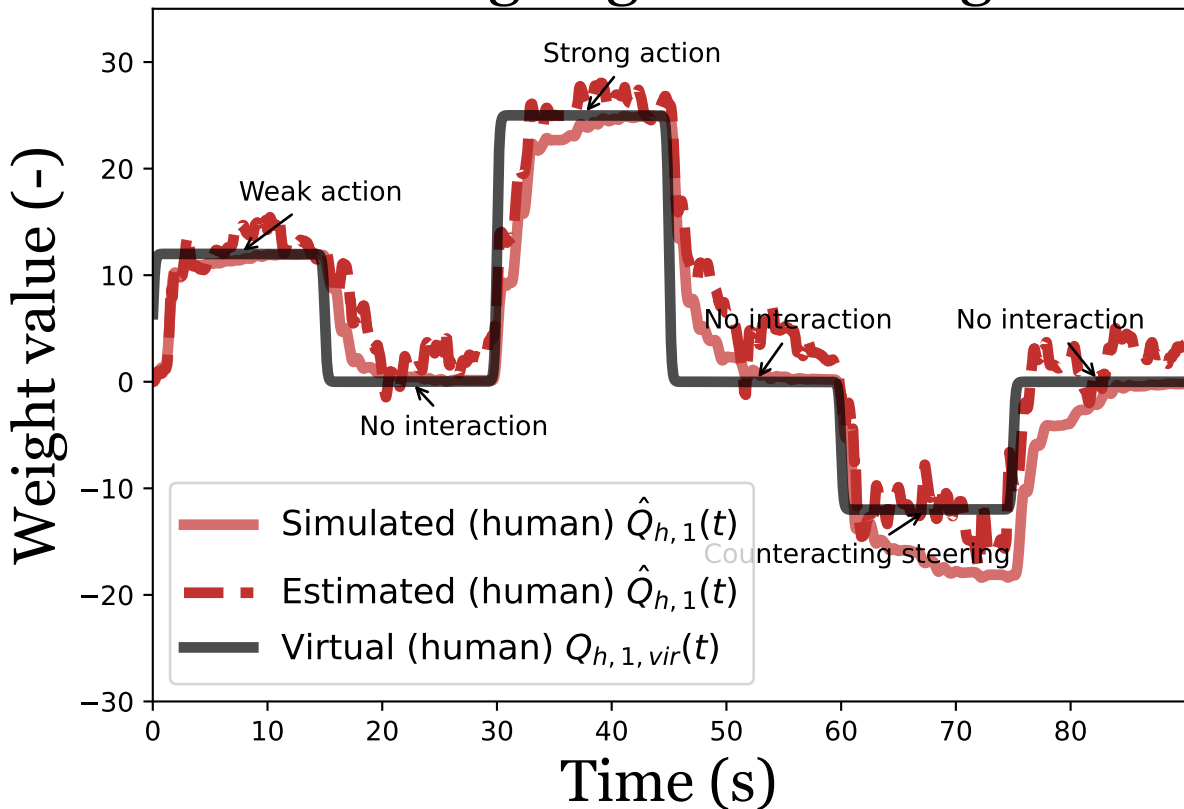


Measured and estimated steering rate

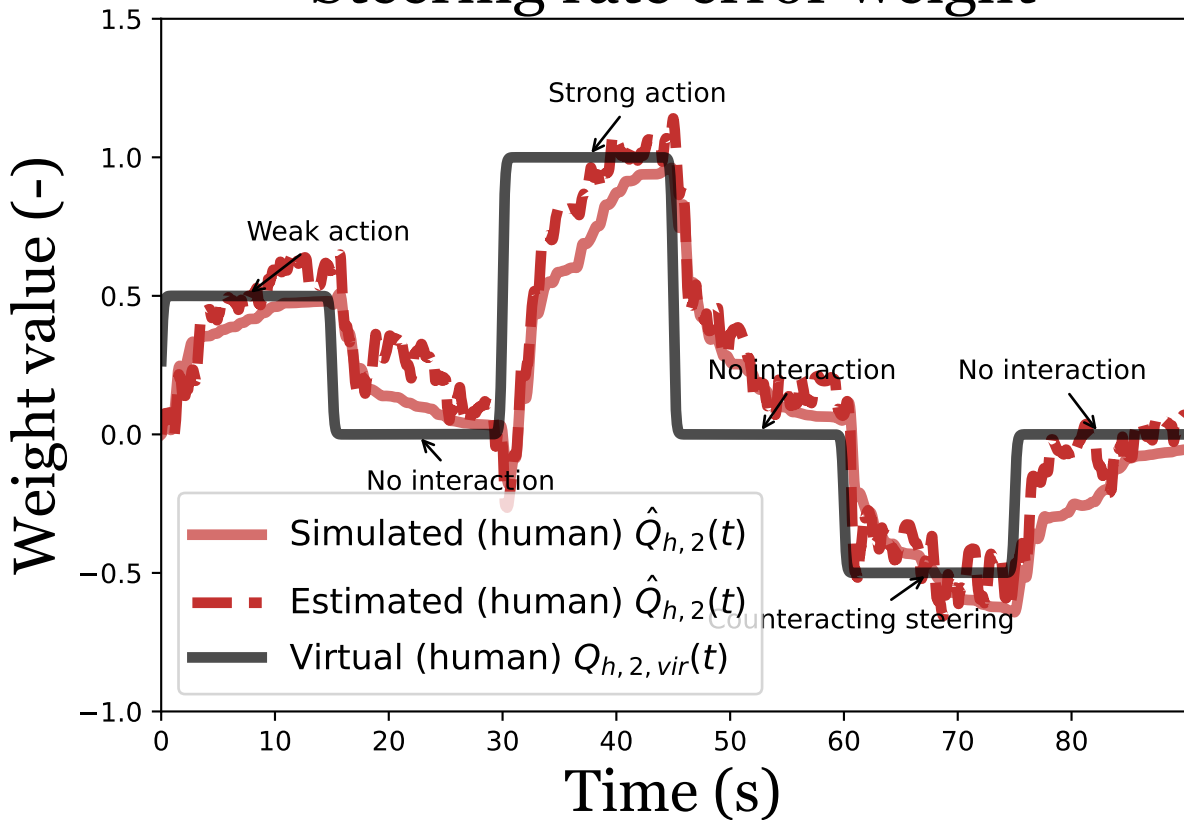
Steering angle (rad)



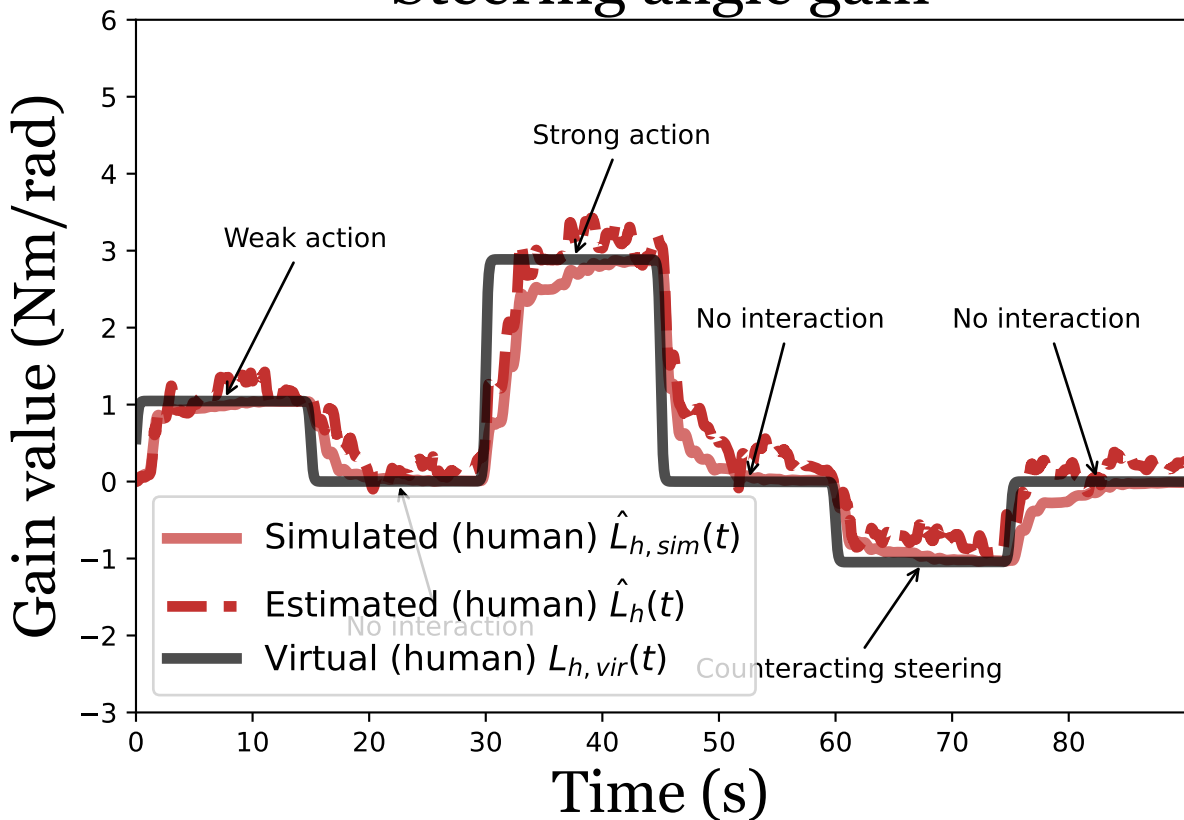
Steering angle error weight



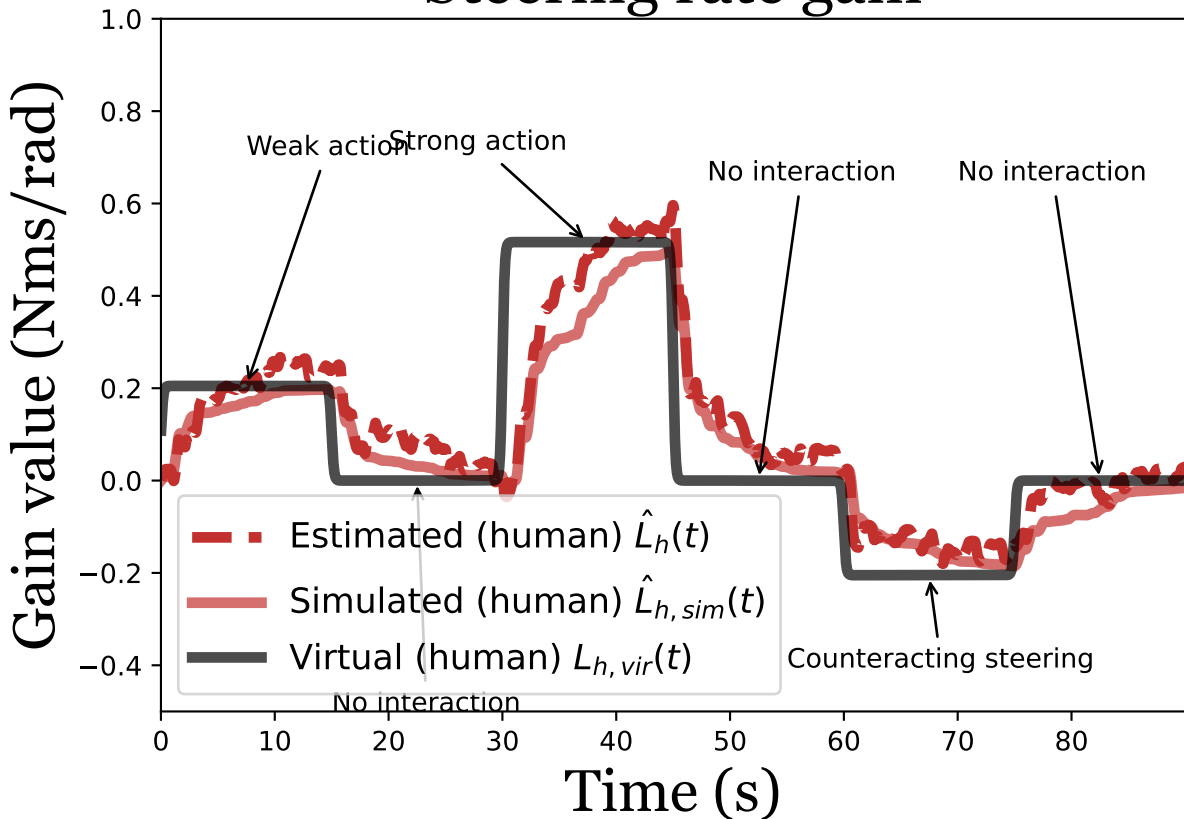
Steering rate error weight



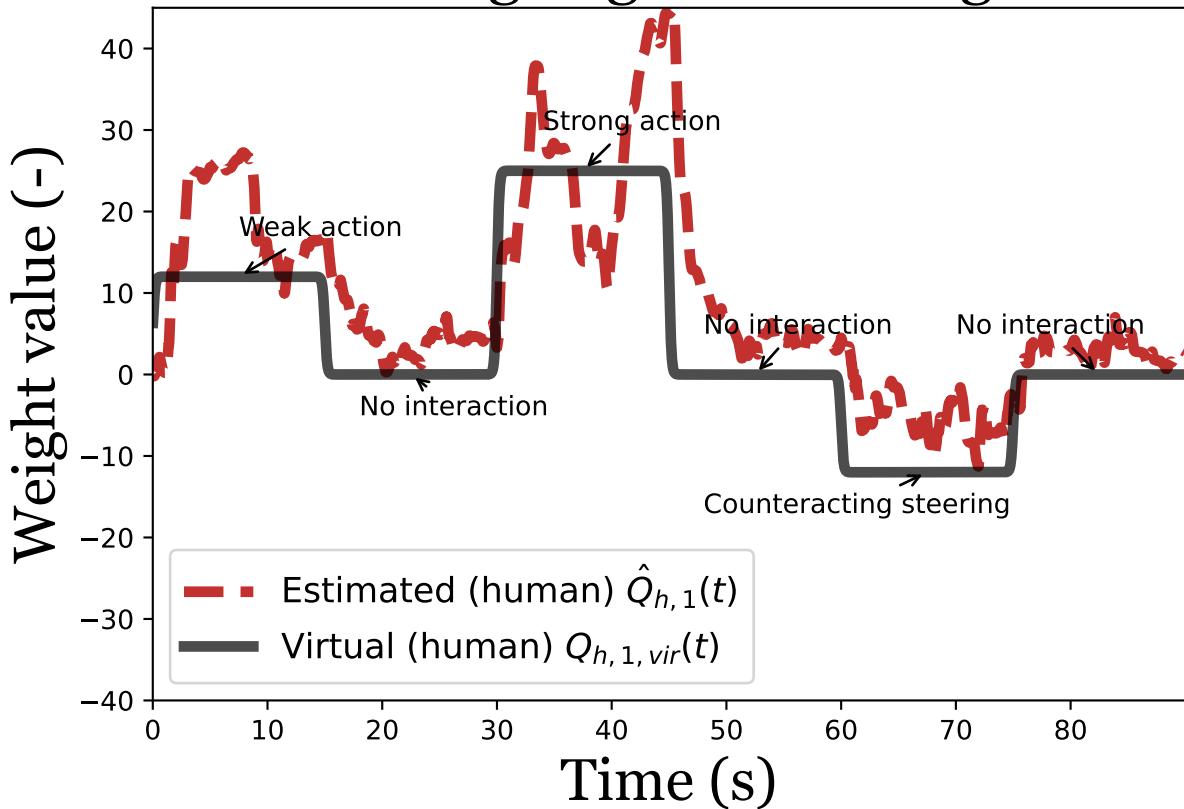
Steering angle gain



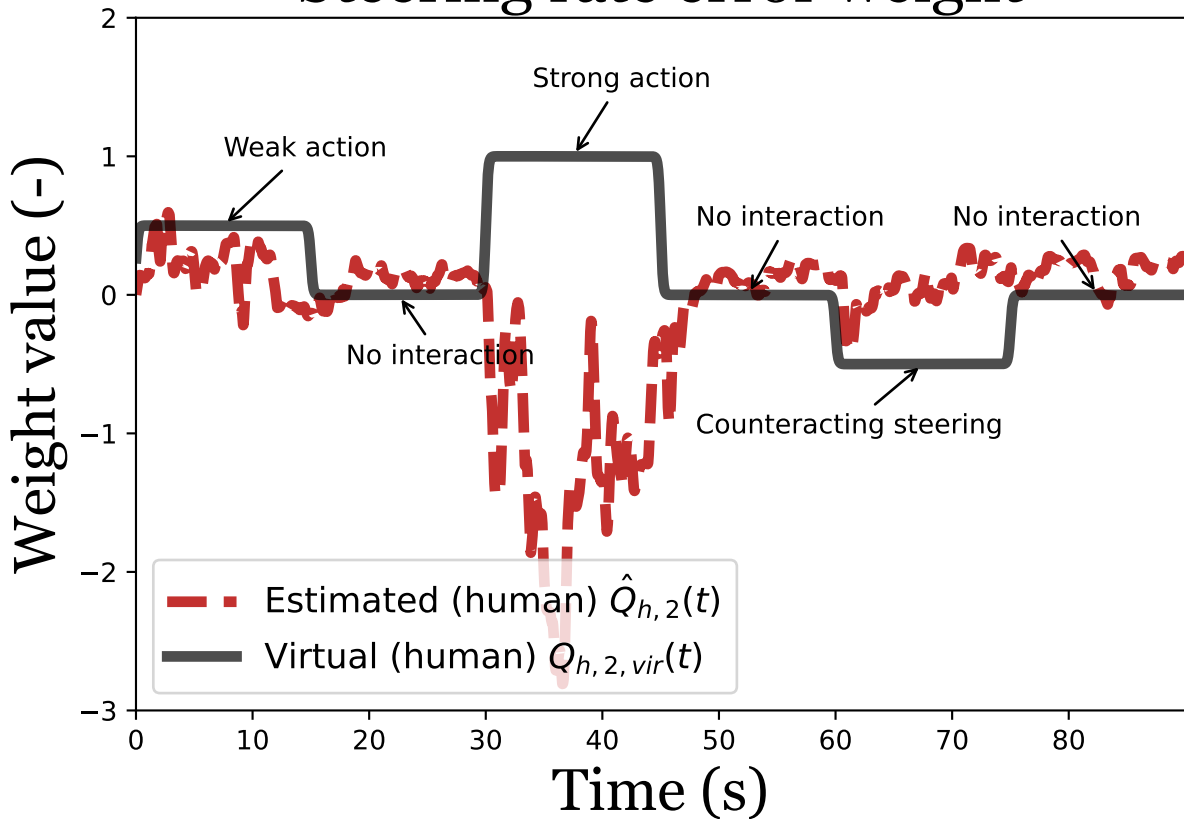
Steering rate gain



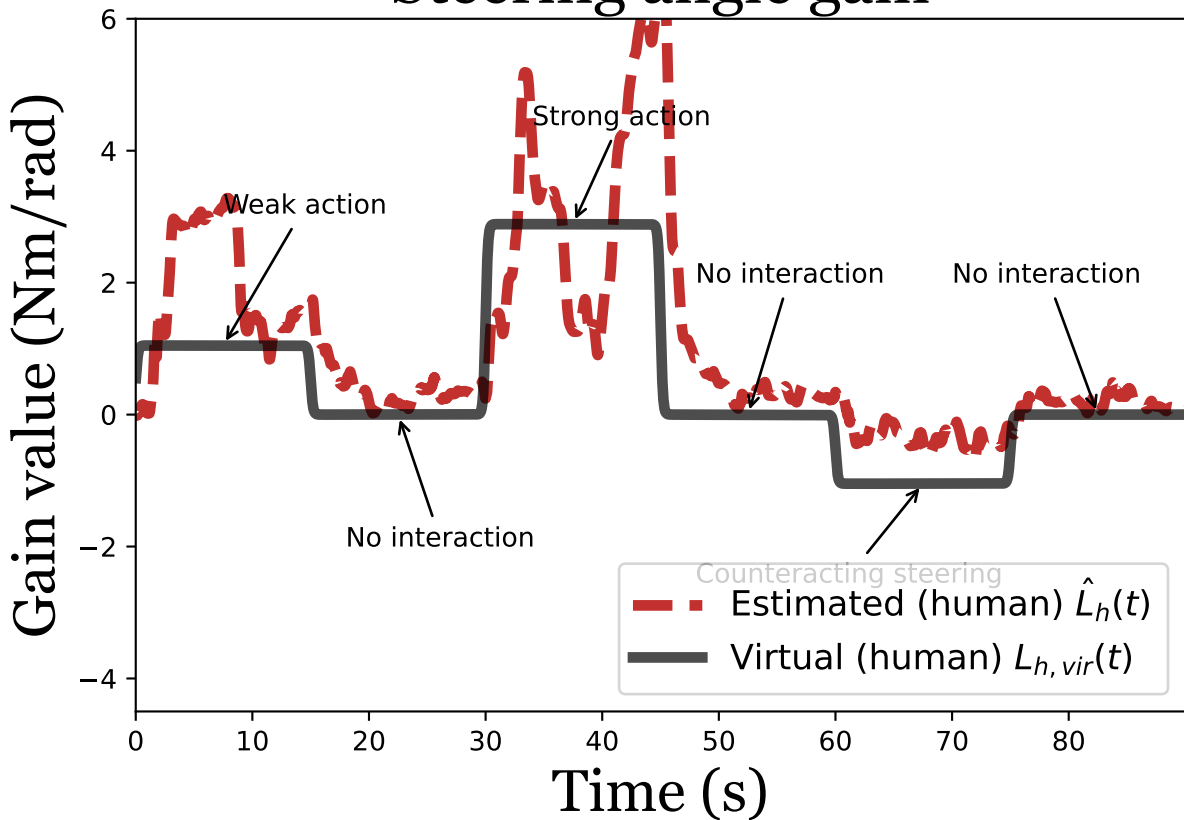
Steering angle error weight



Steering rate error weight



Steering angle gain



Steering rate gain

