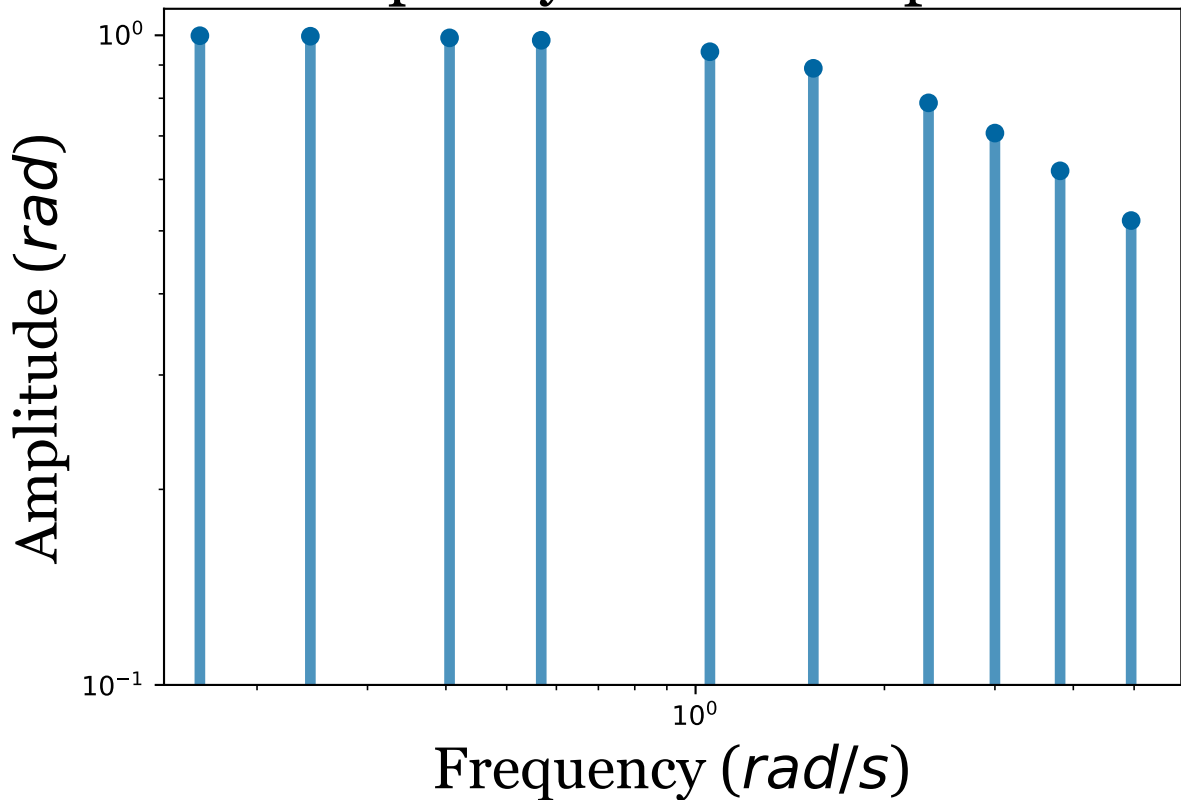
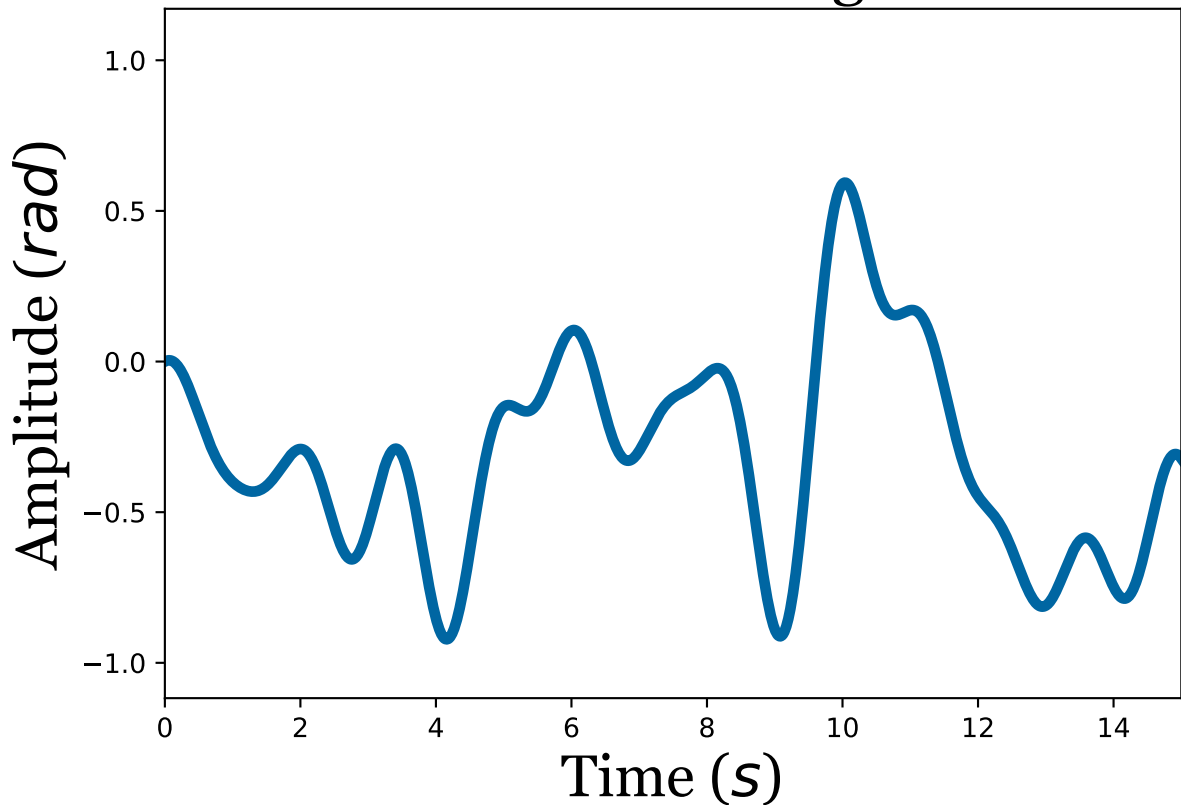


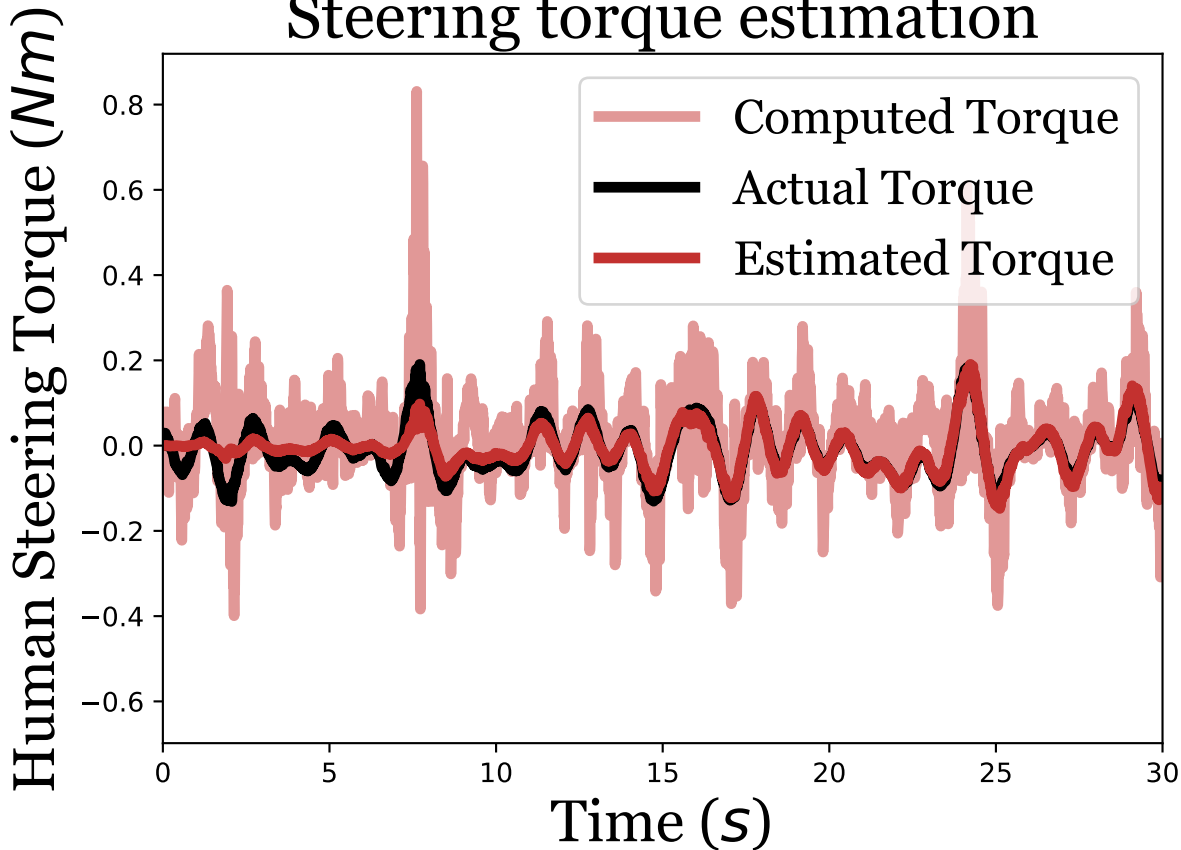
# Frequency domain response



# Time domain signal

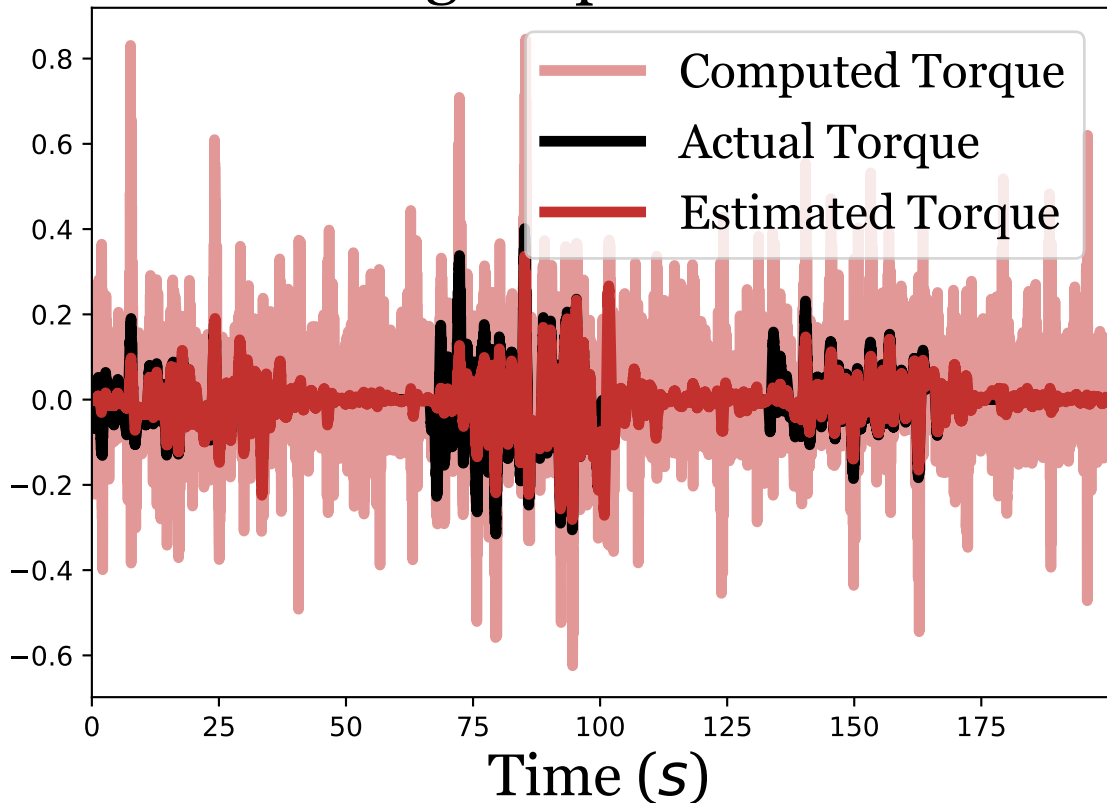


# Steering torque estimation

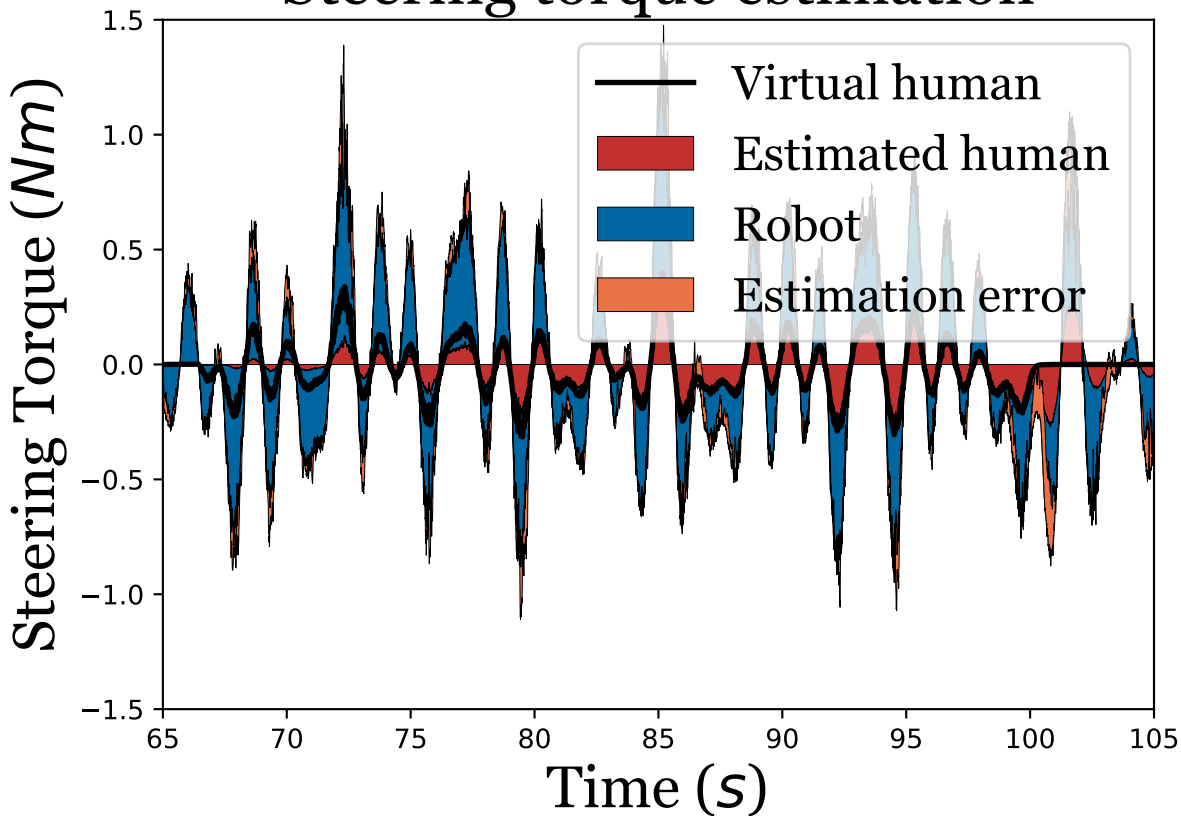


# Steering torque estimation

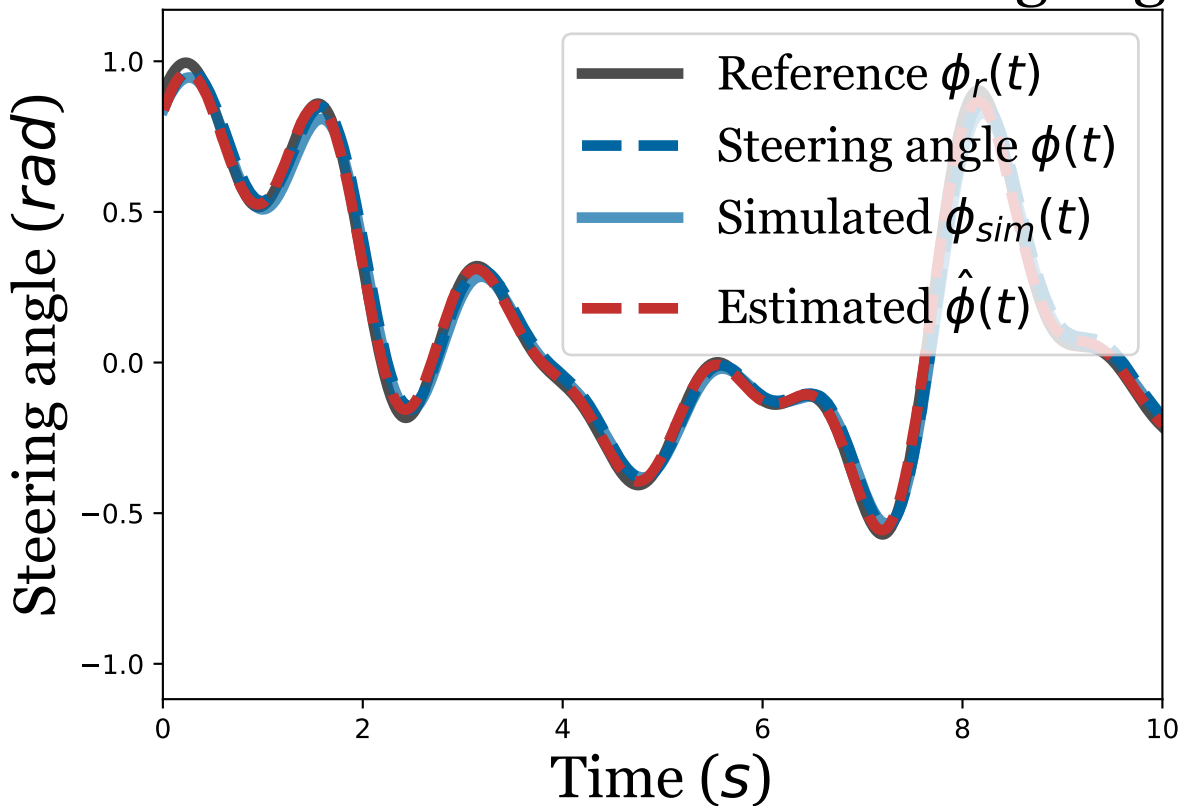
Human Steering Torque (Nm)



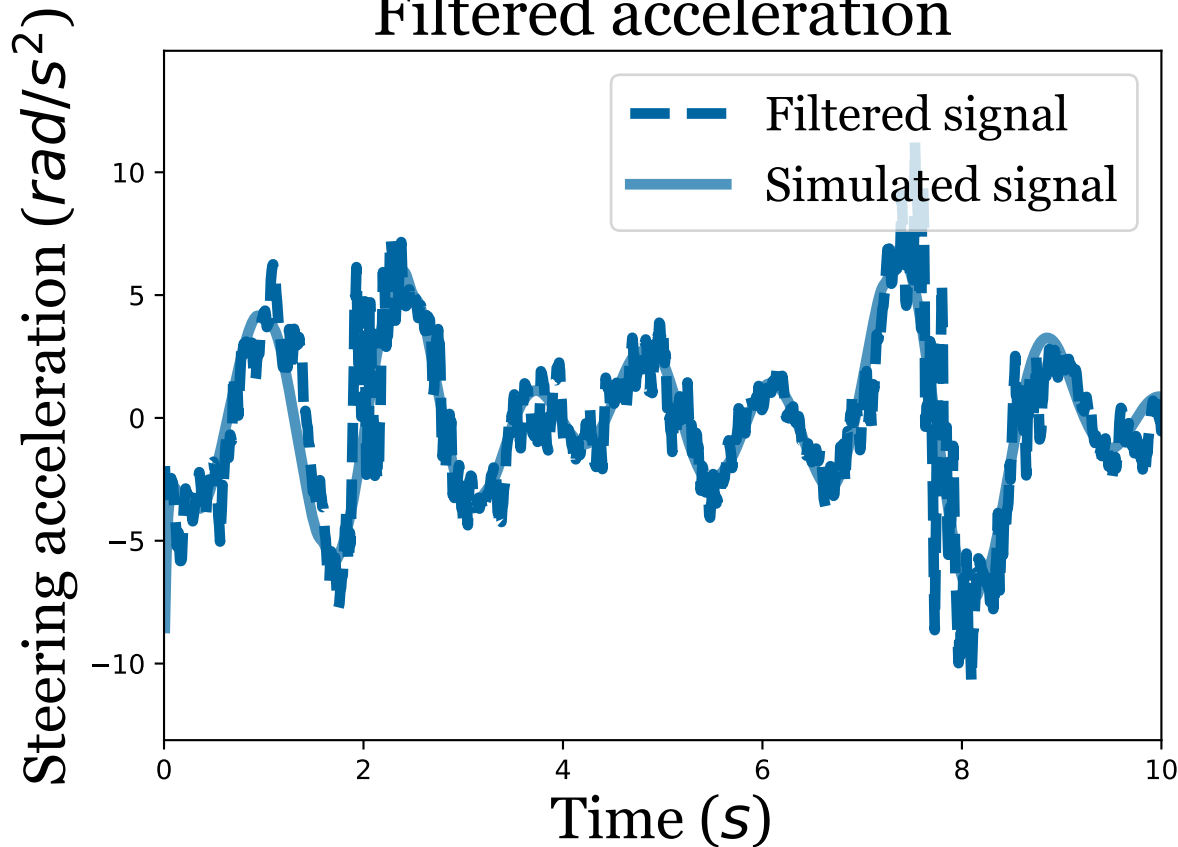
# Steering torque estimation



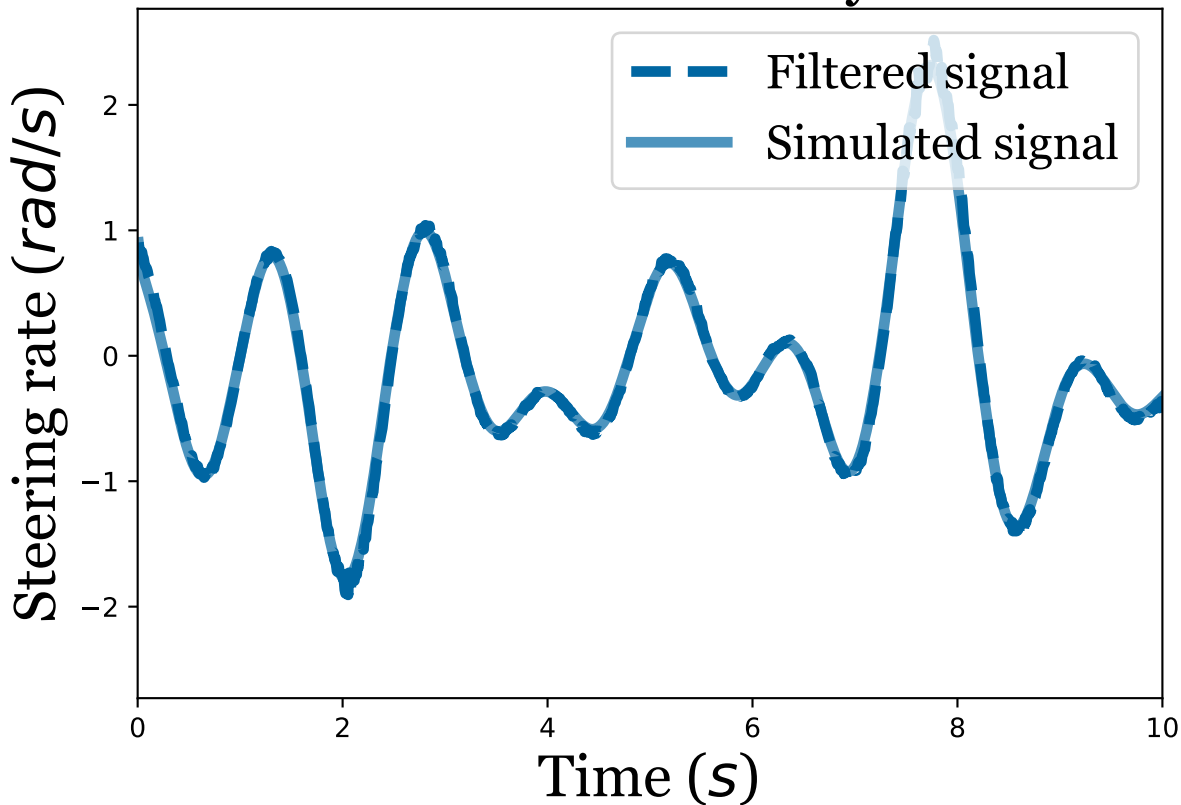
# Measured and estimated steering angle



# Filtered acceleration

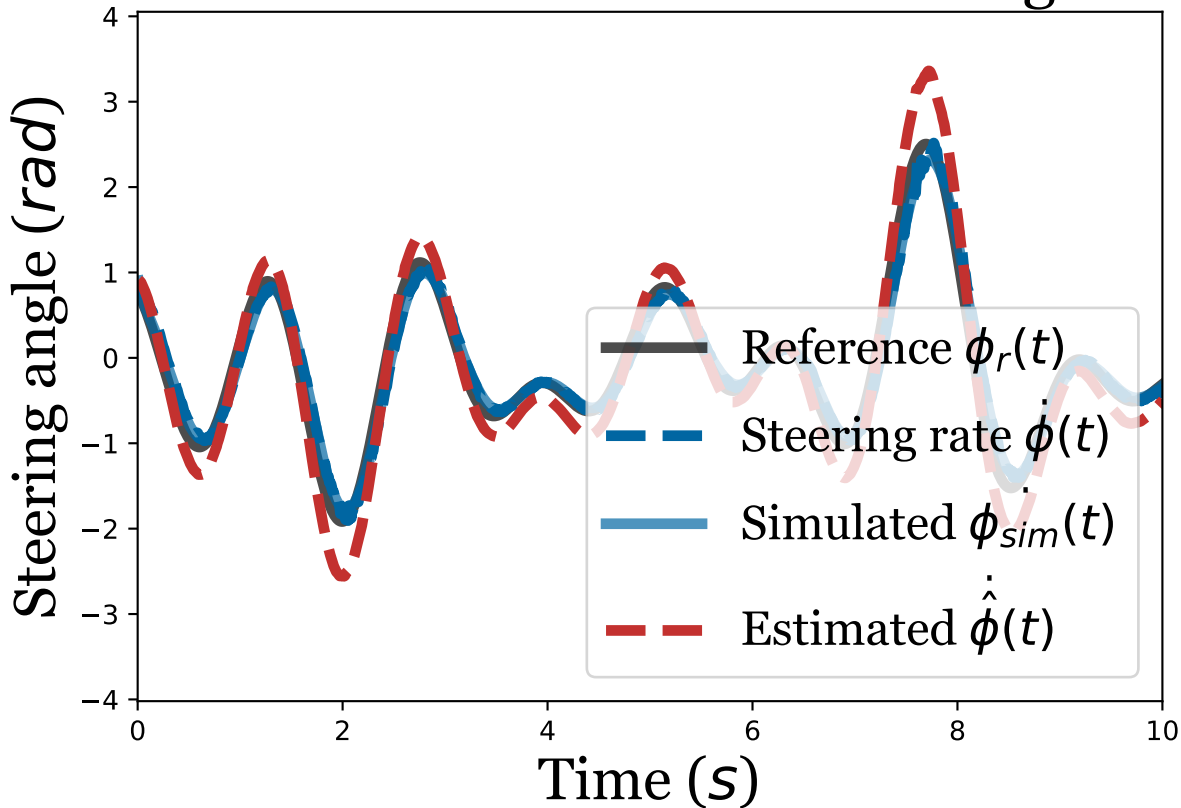


# Filtered velocity

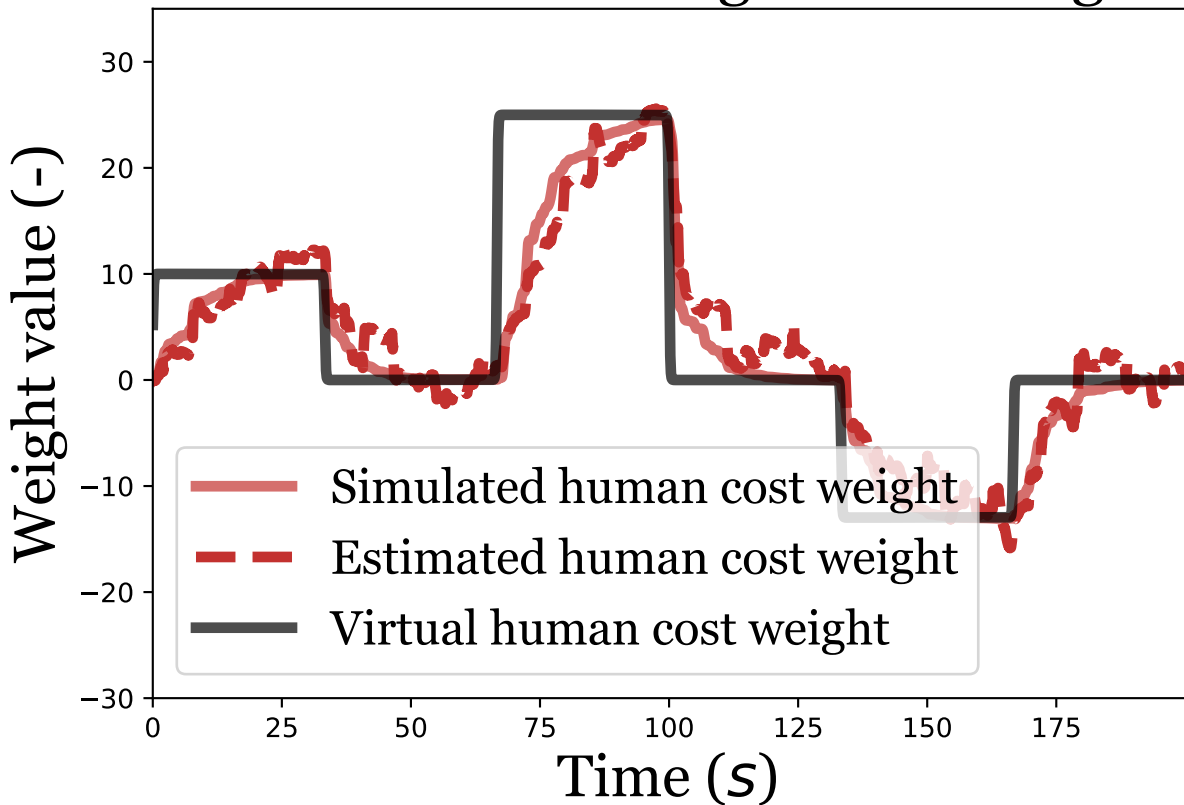




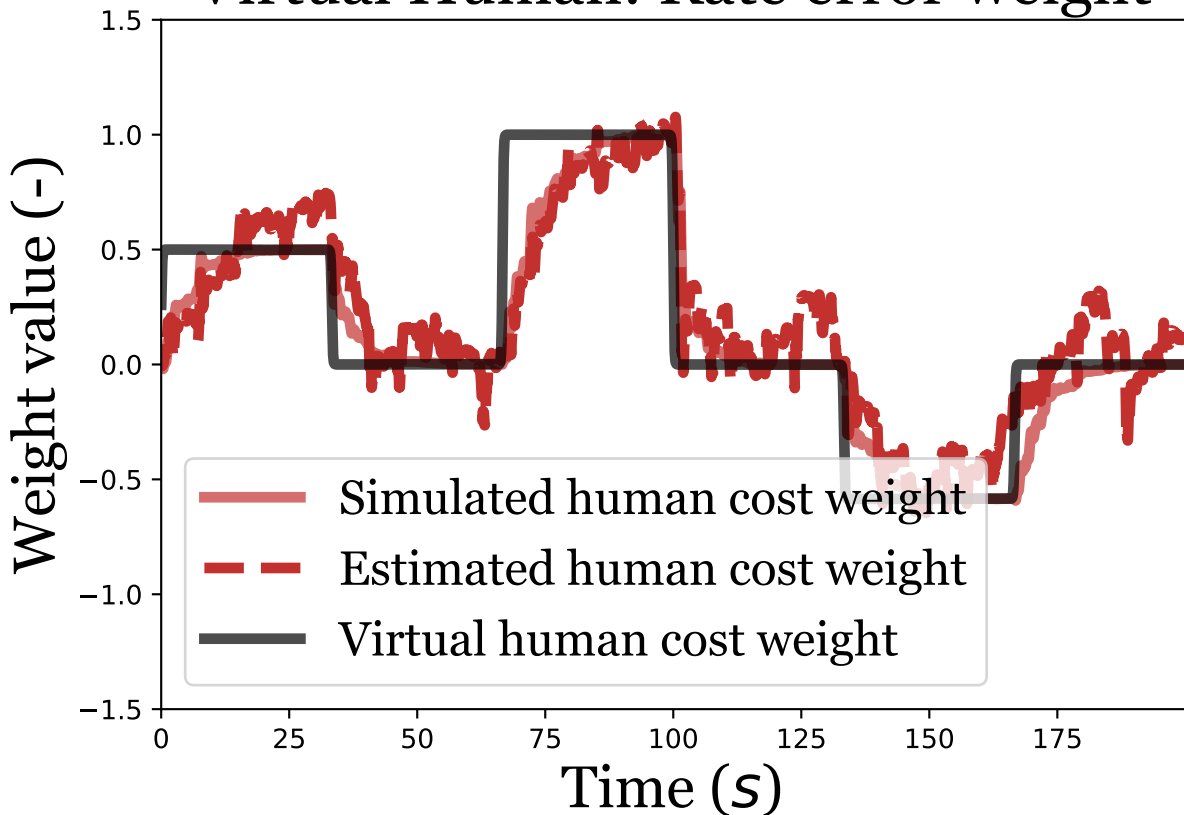
# Measured and estimated steering rate



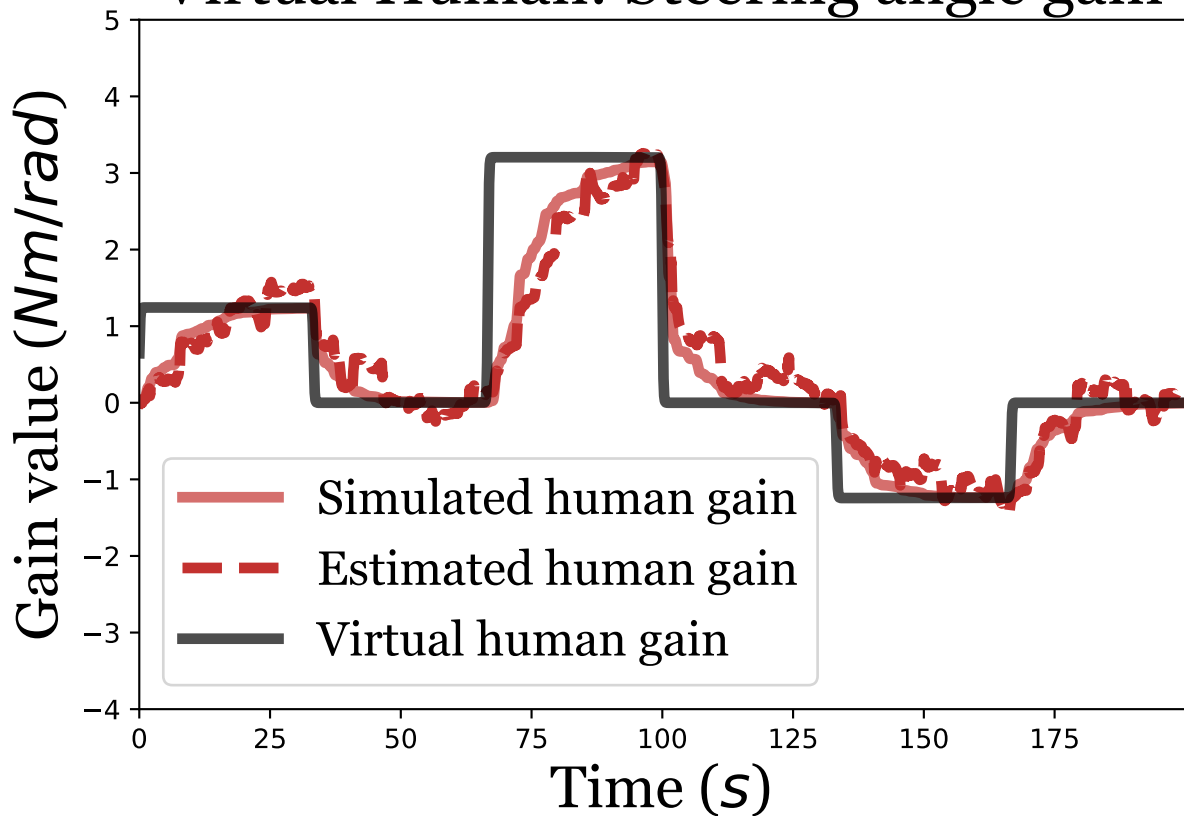
# Virtual Human: Angle error weight



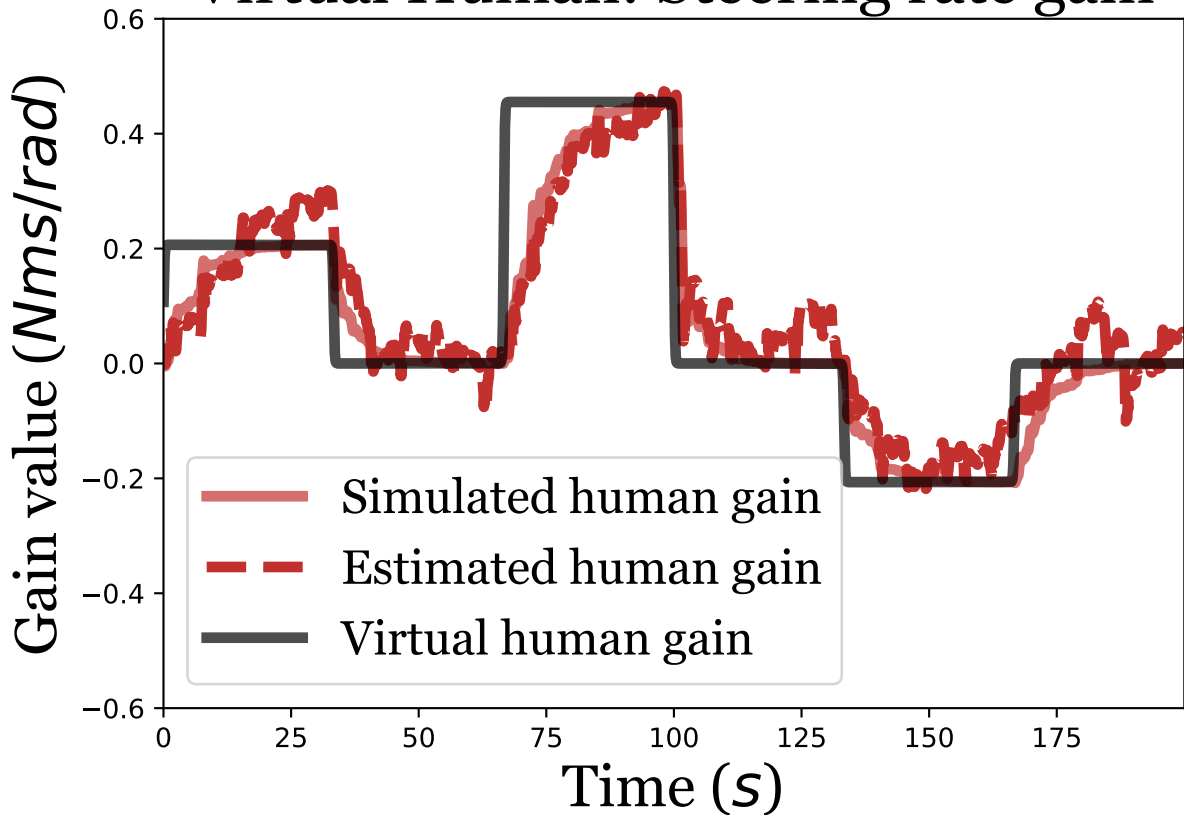
# Virtual Human: Rate error weight



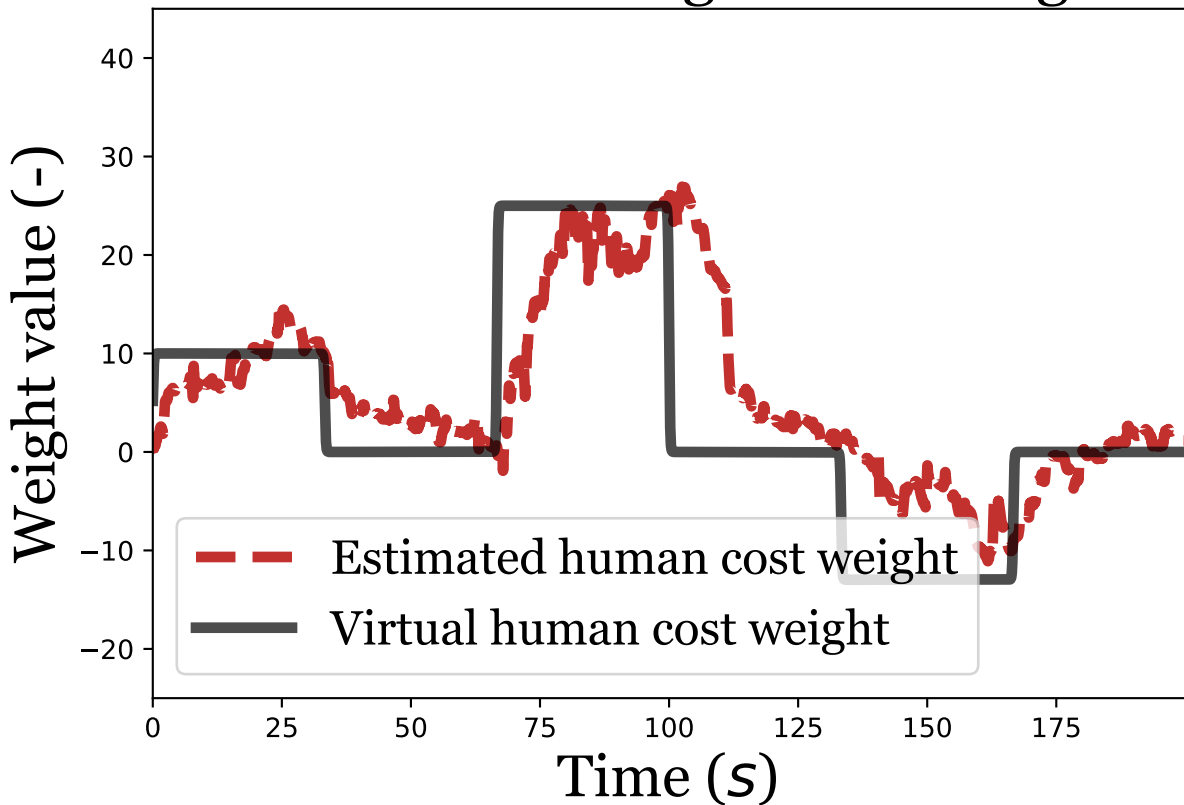
# Virtual Human: Steering angle gain



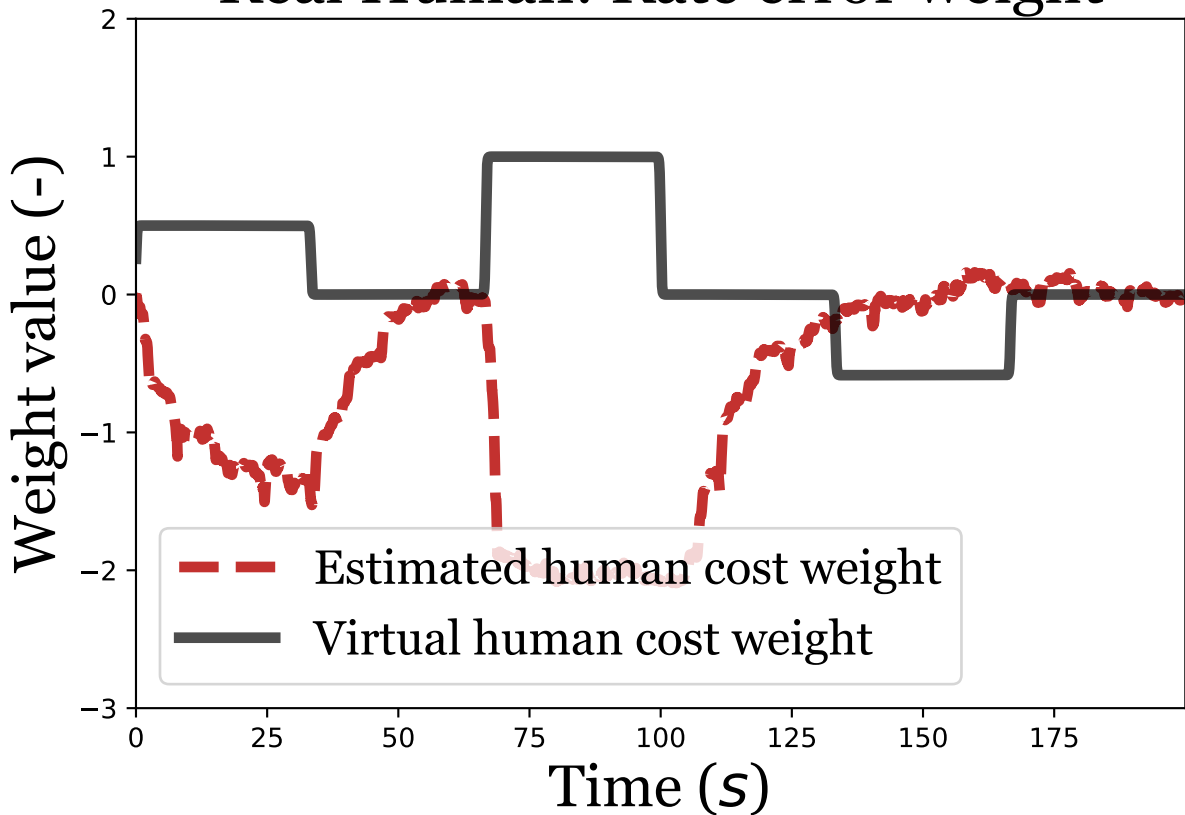
# Virtual Human: Steering rate gain



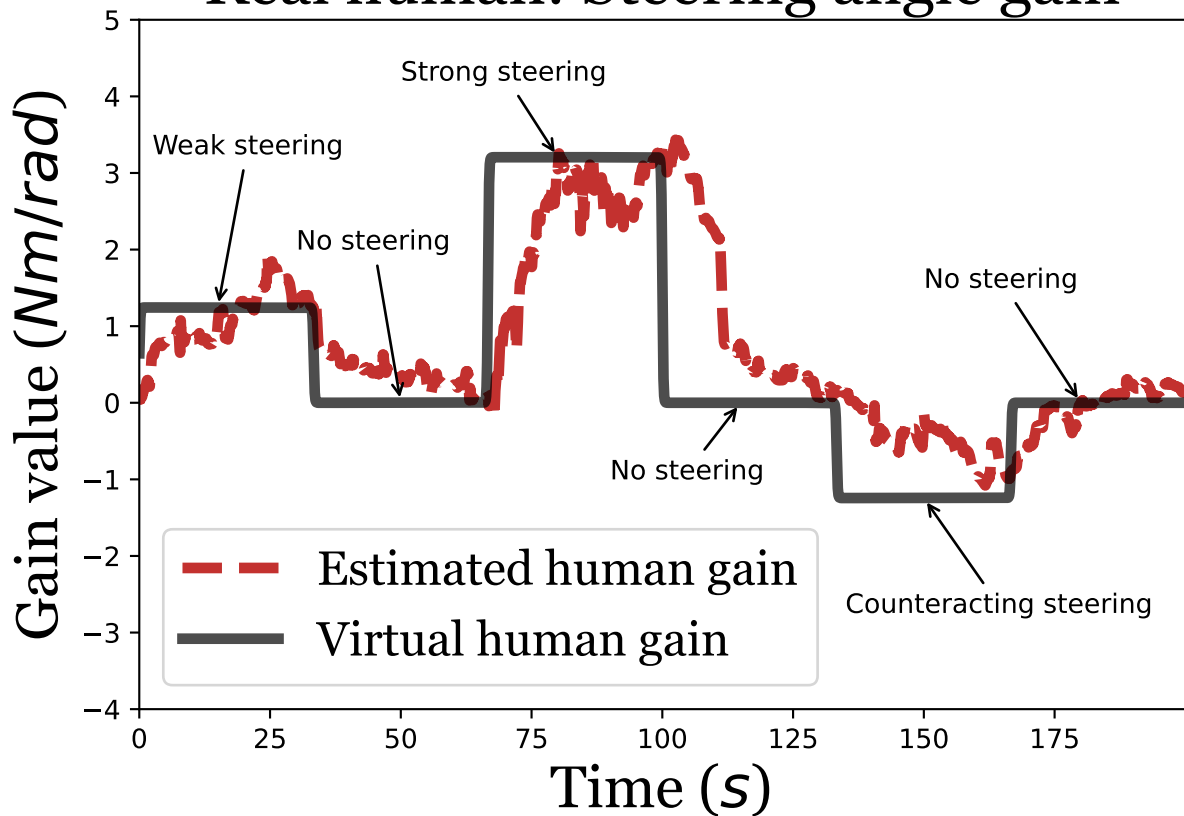
# Real Human: Angle error weight



# Real Human: Rate error weight

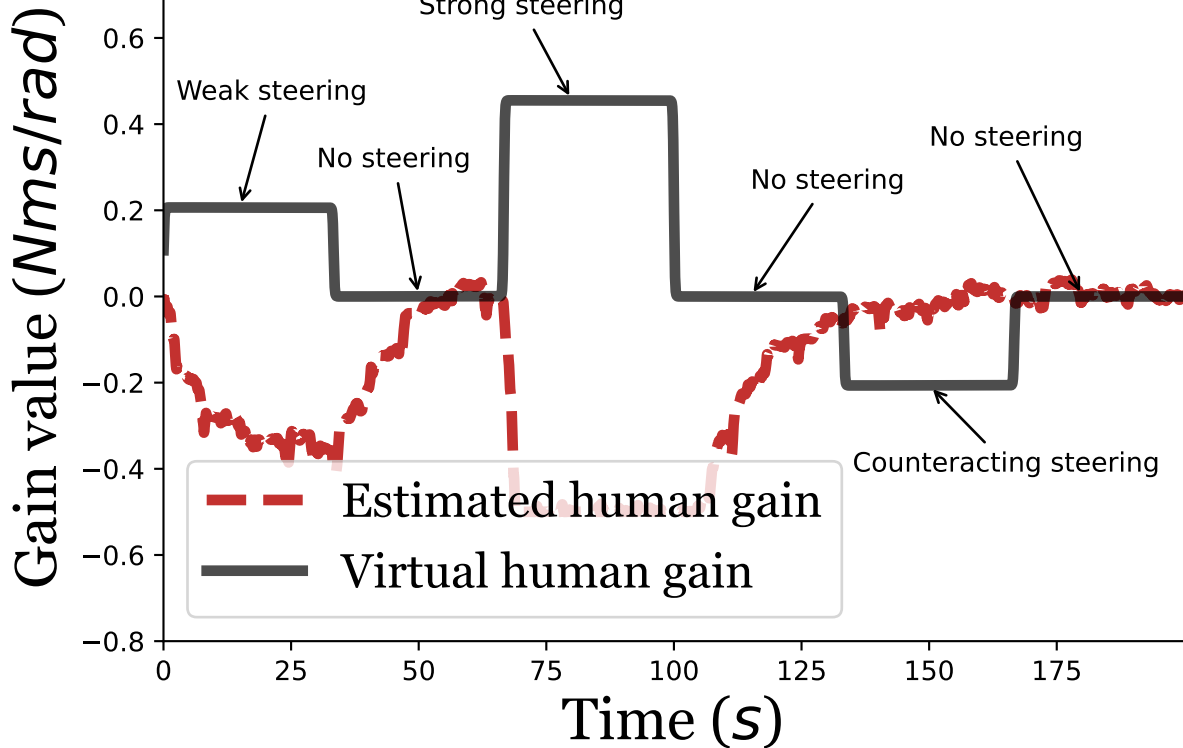


# Real human: Steering angle gain

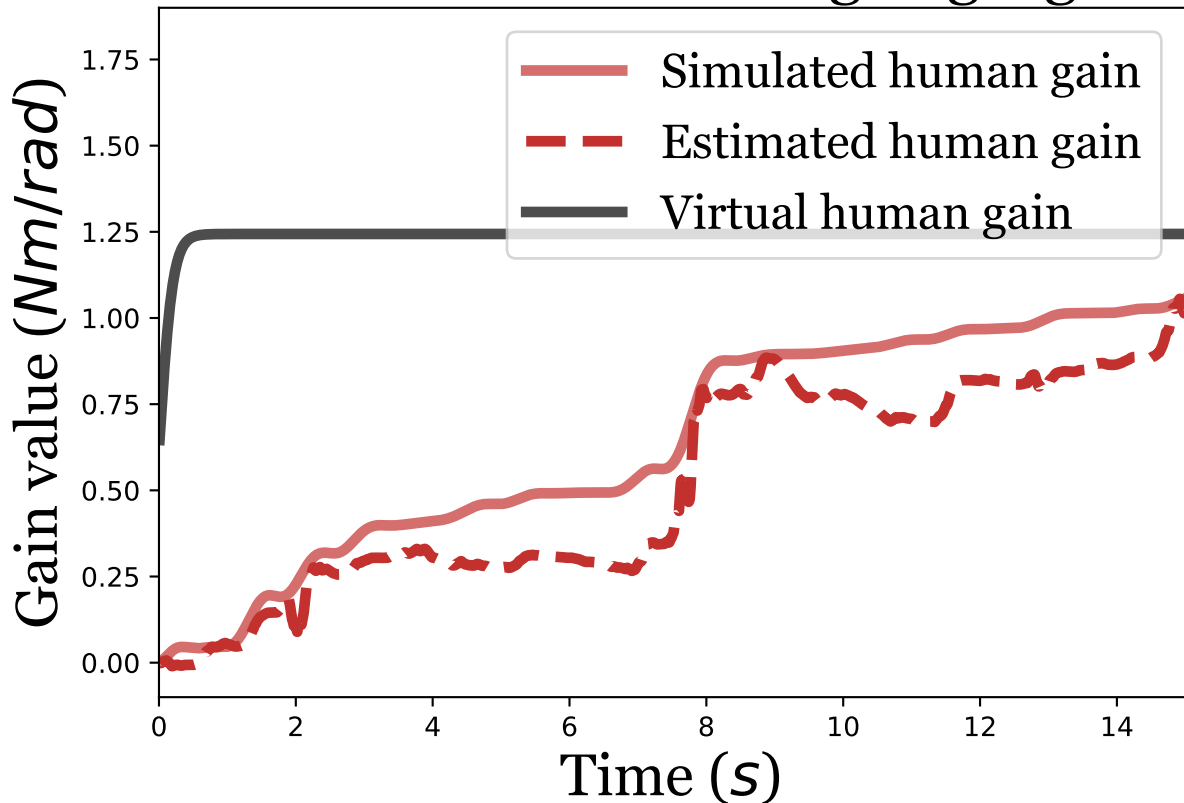




# Real human: Steering rate gain



# Virtual human: Steering angle gain



# Virtual human: Steering rate gain

