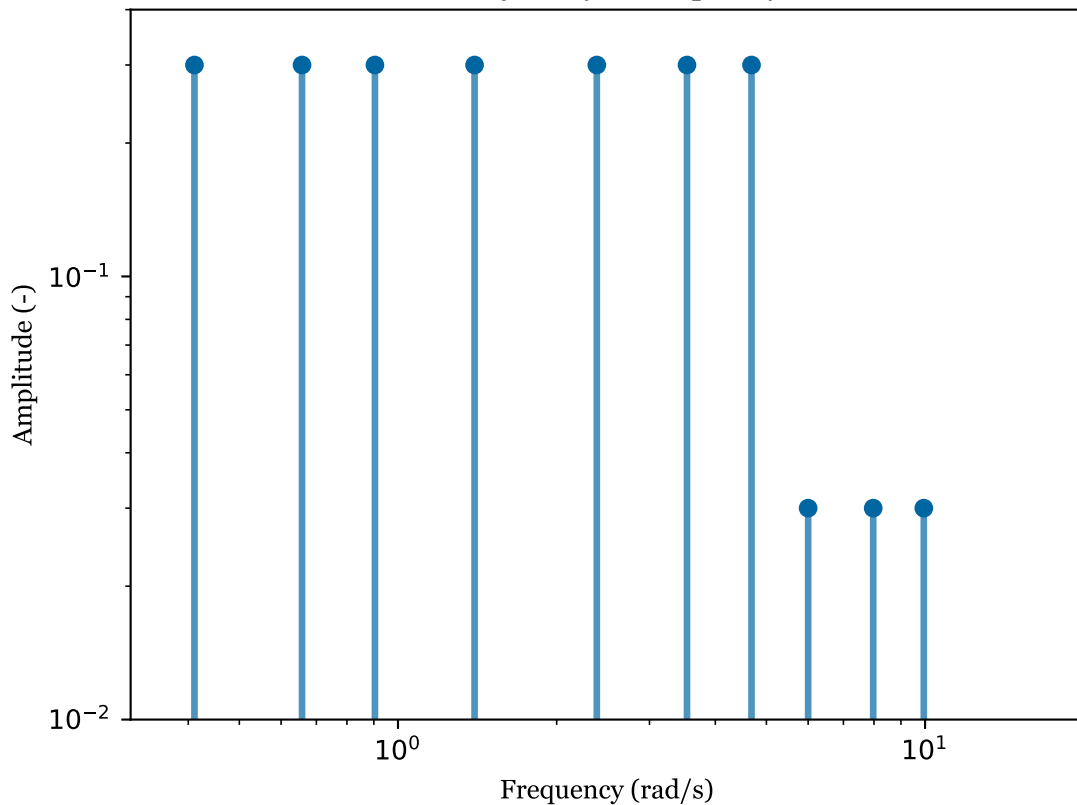
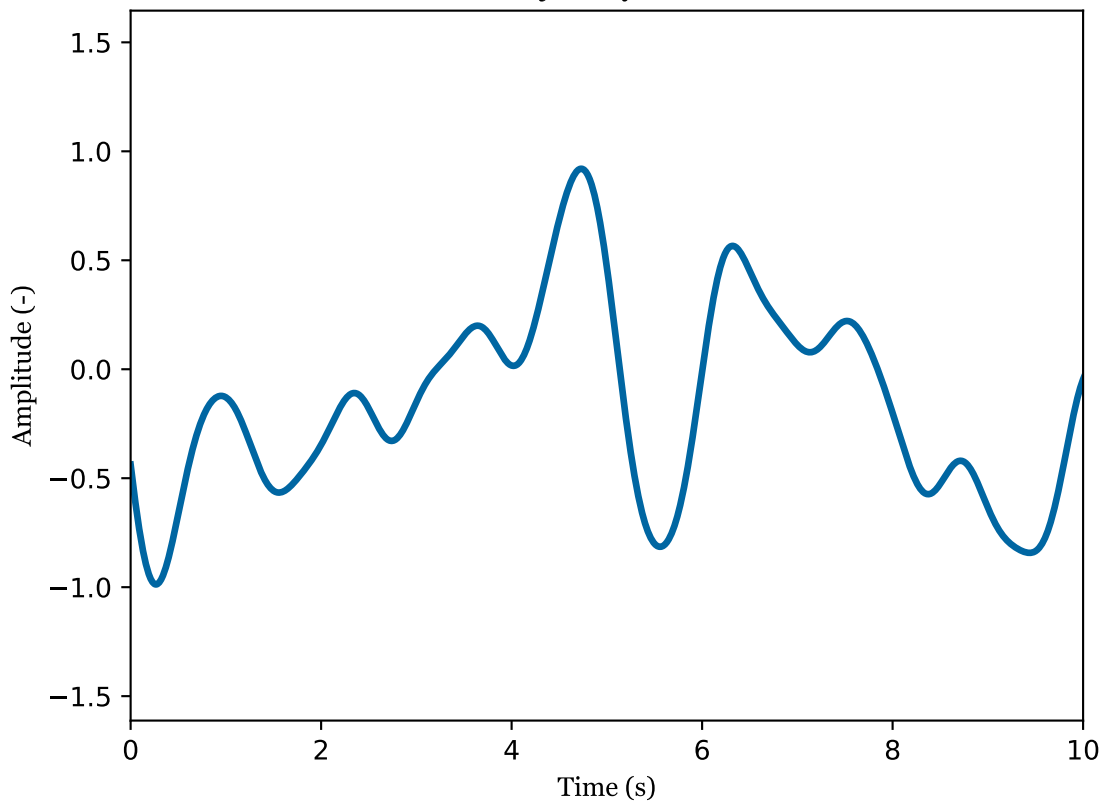


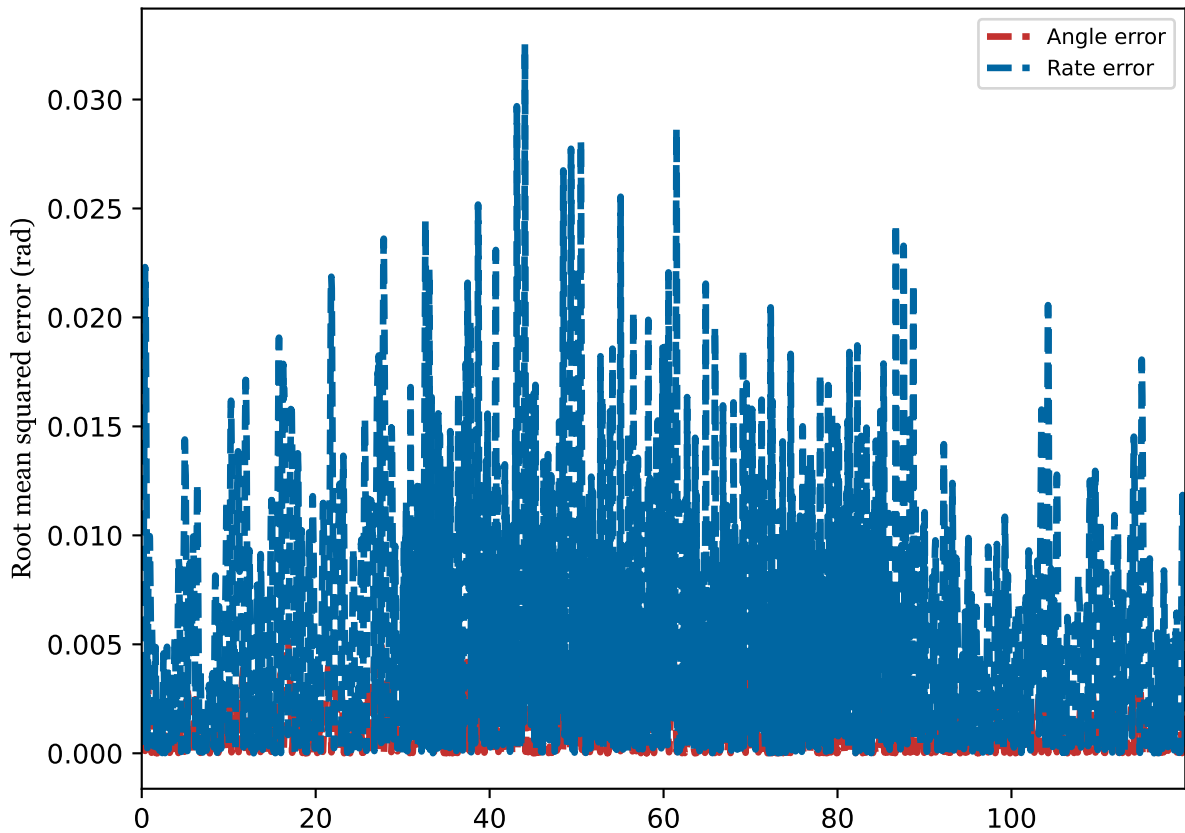
Reference trajectory in frequency domain



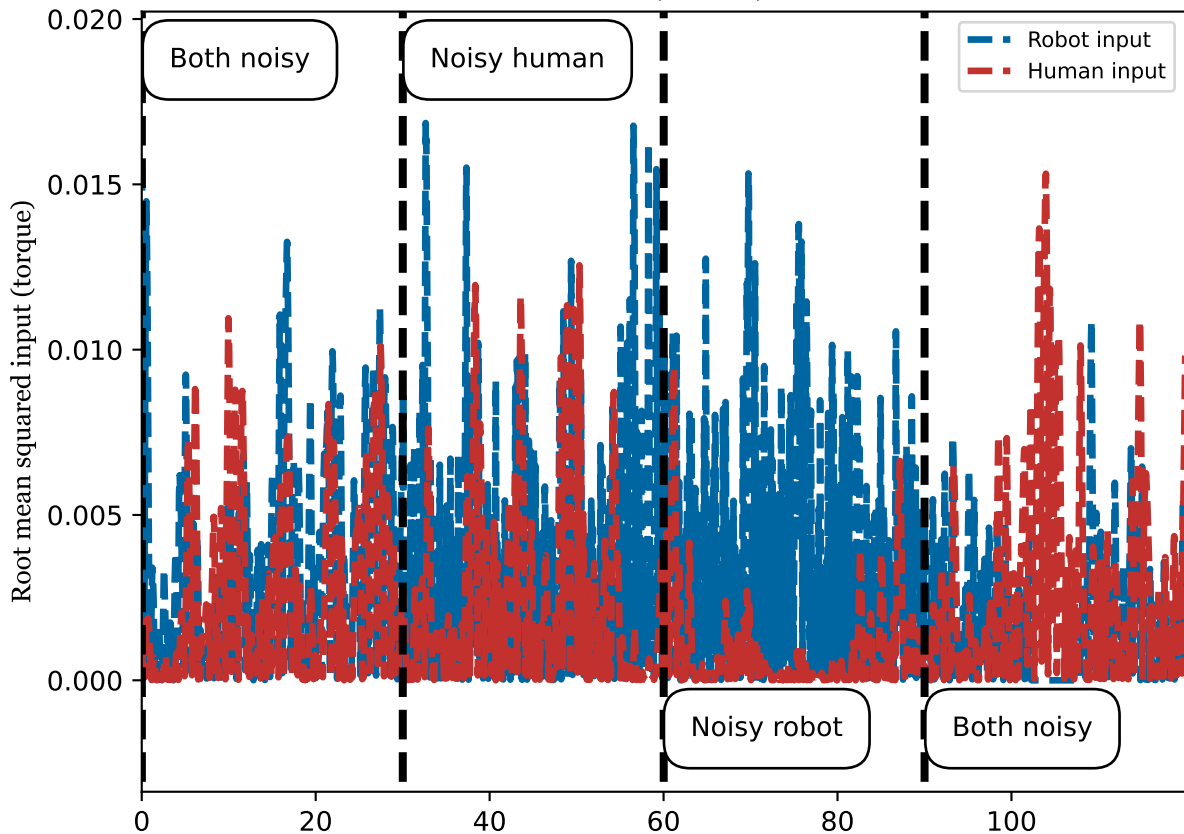
Reference trajectory in time domain



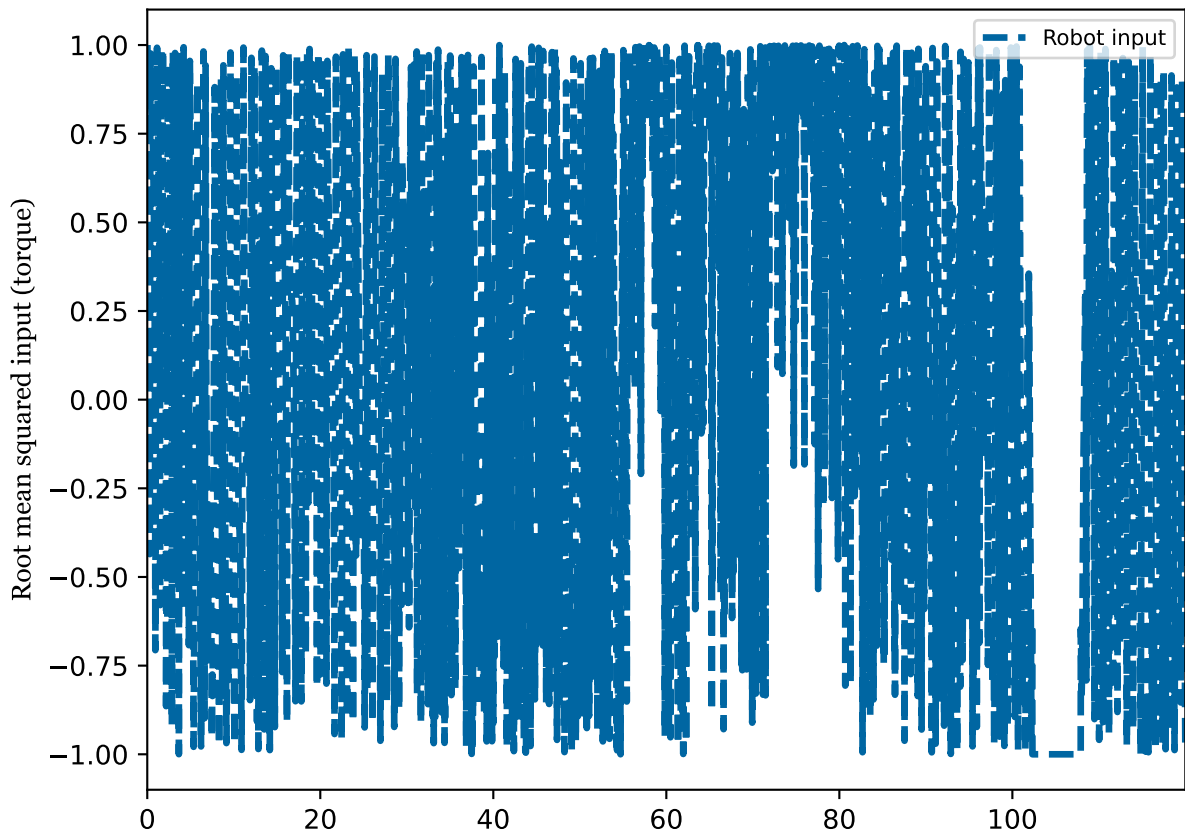
Performance (RMSE)



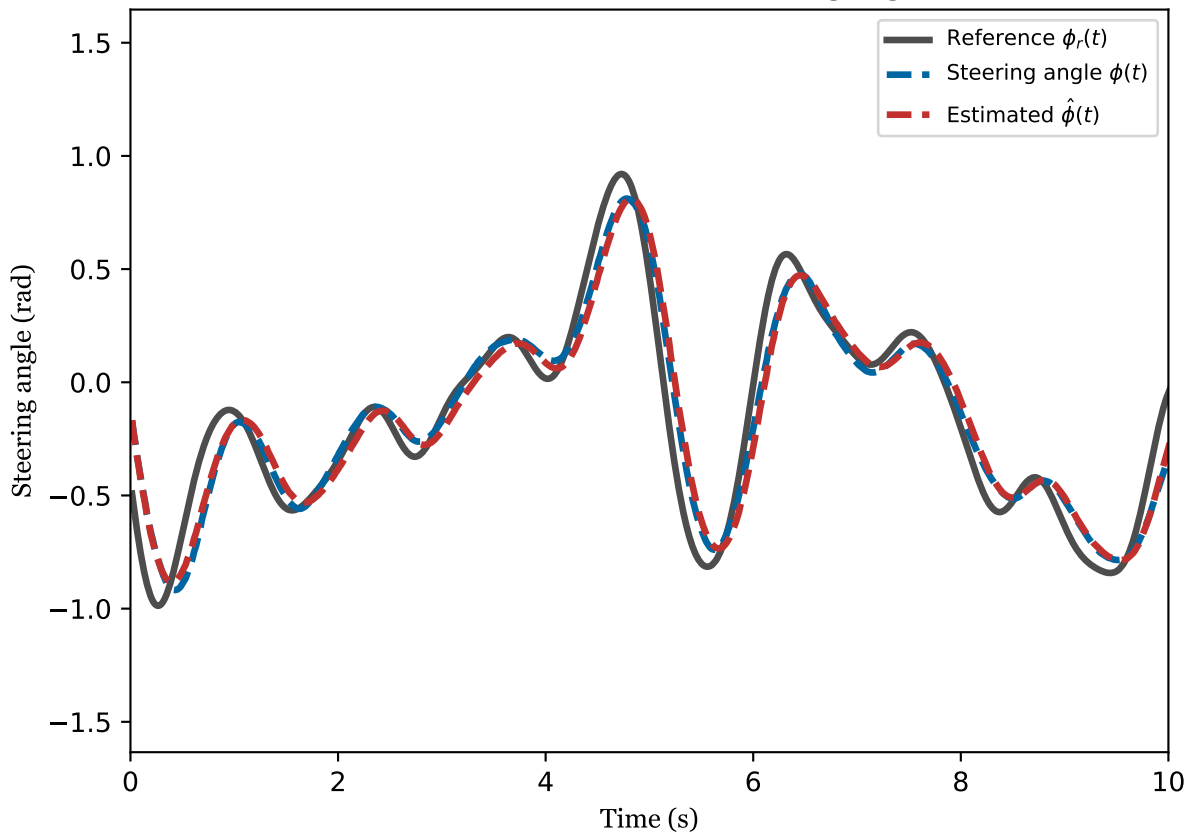
Effort (RMSU)



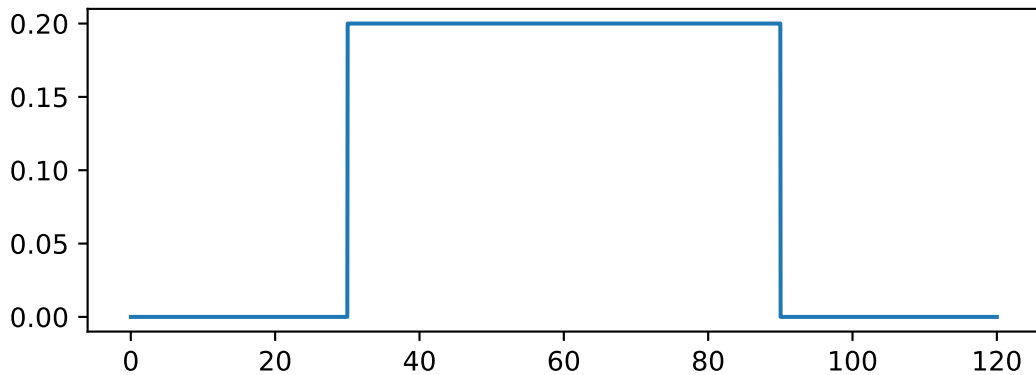
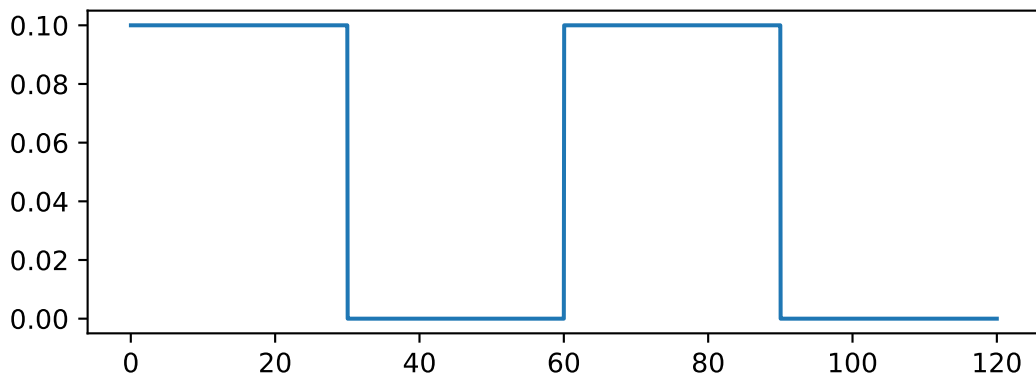
# Dominance



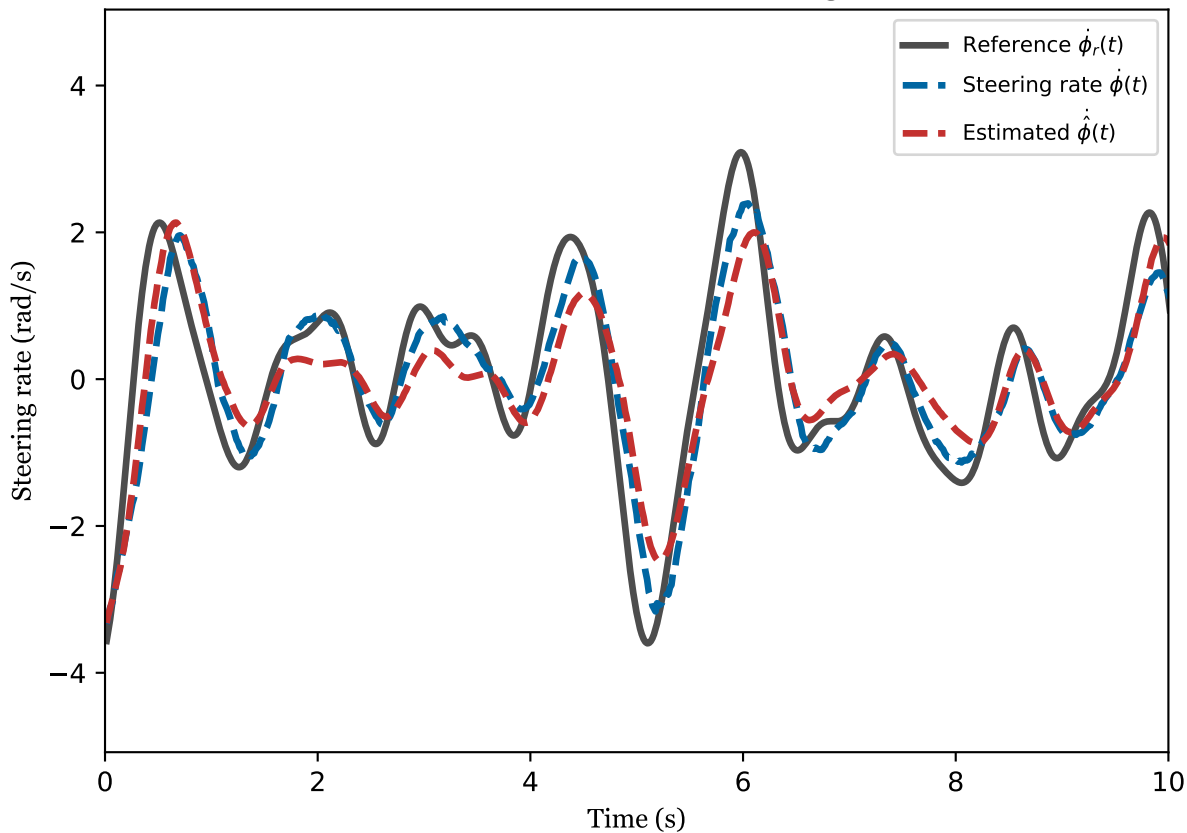
Measured and estimated steering angle



Vertically stacked subplots

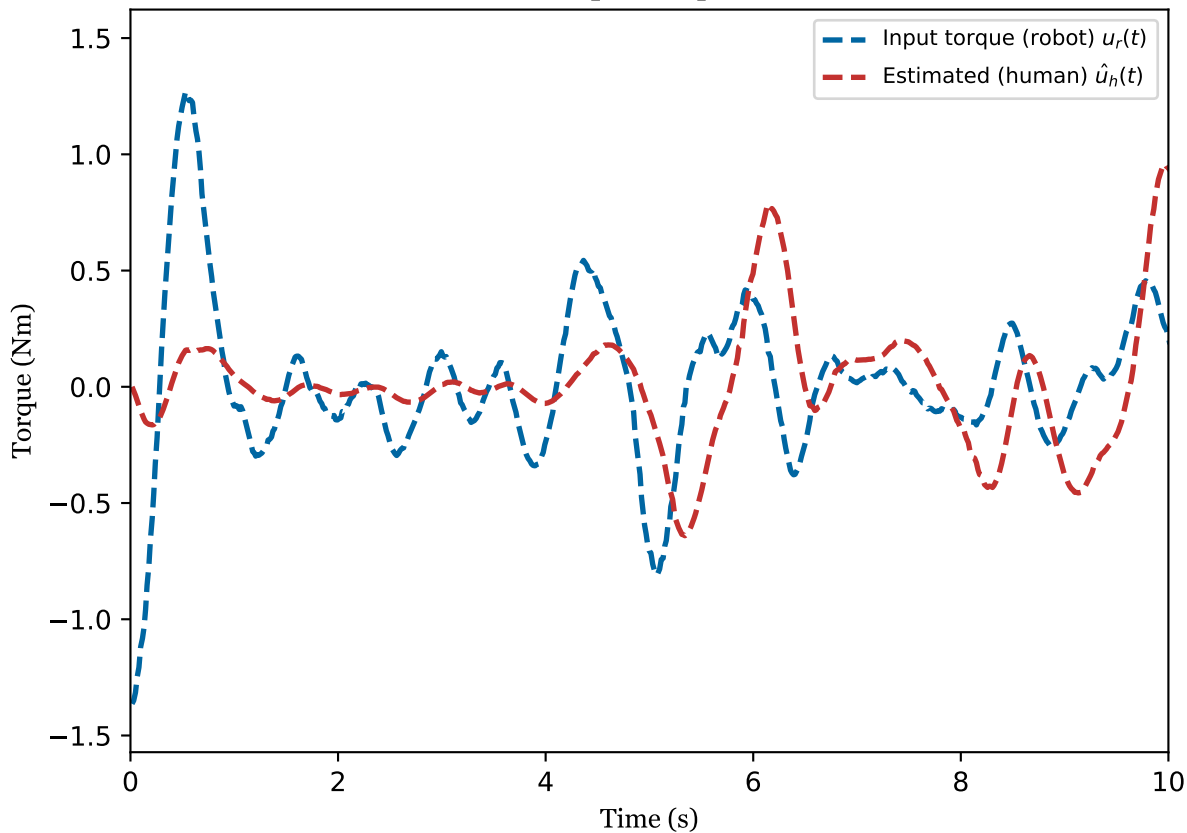


Measured and estimated steering rate

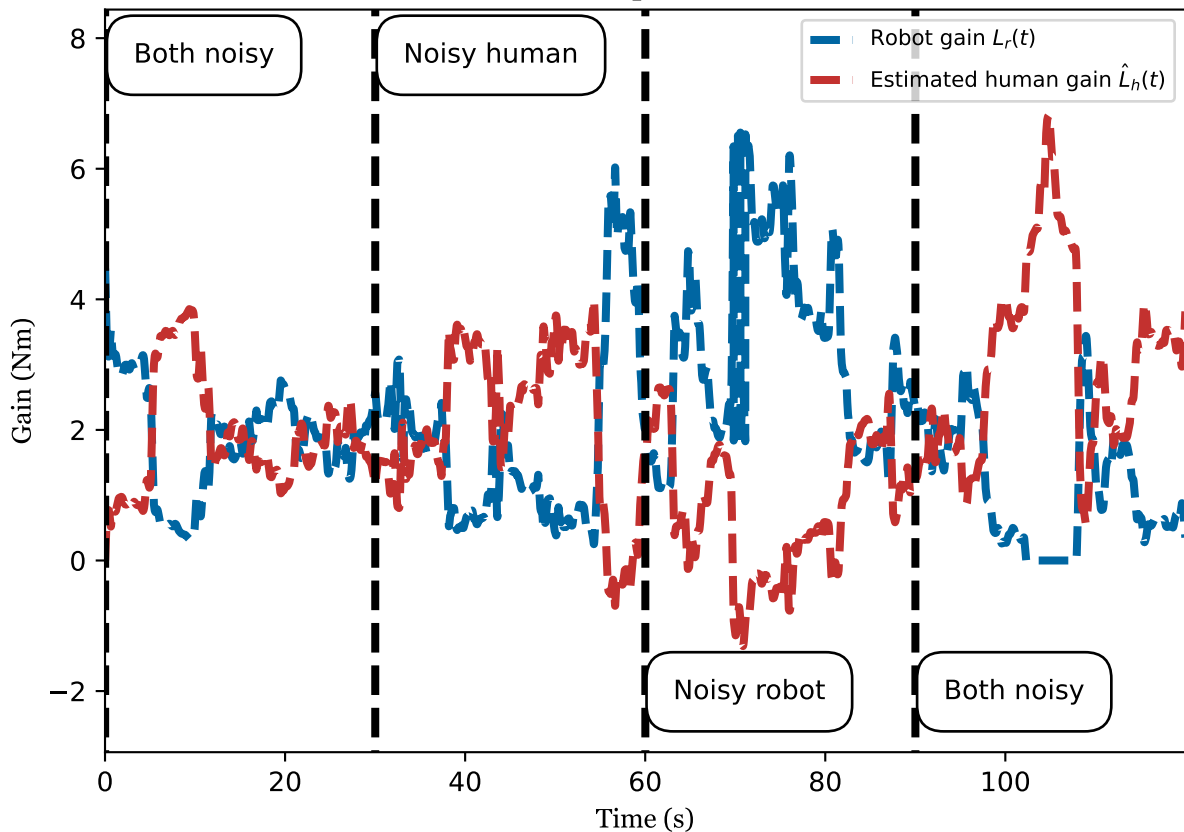




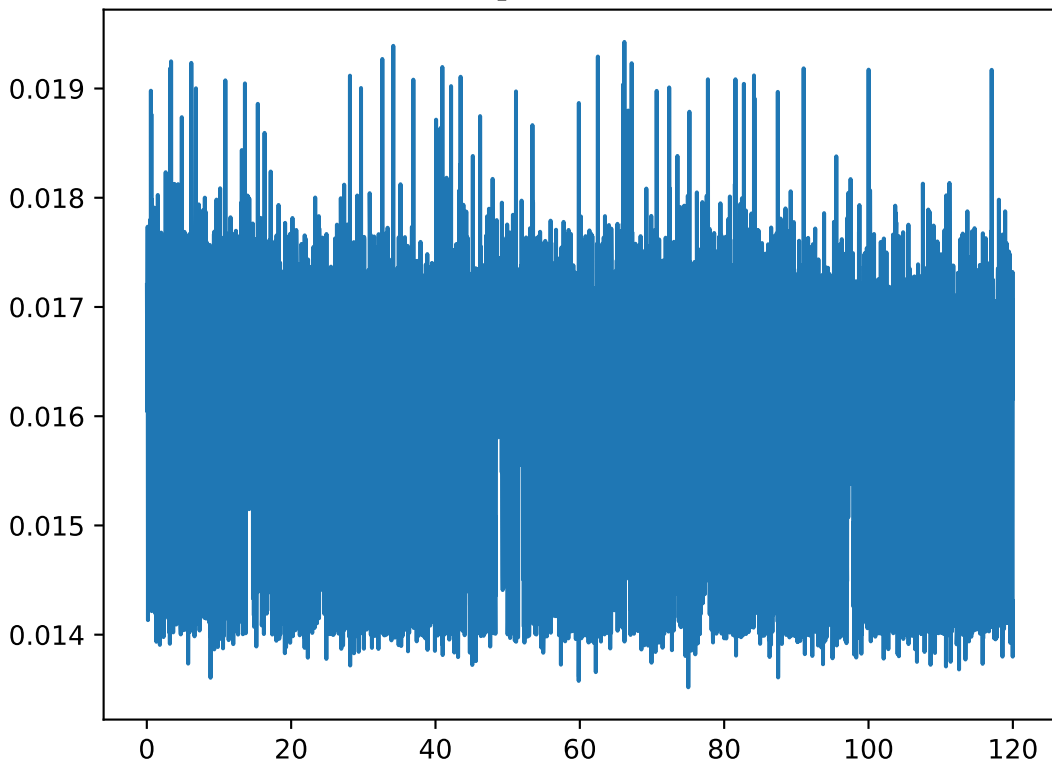
Input torque



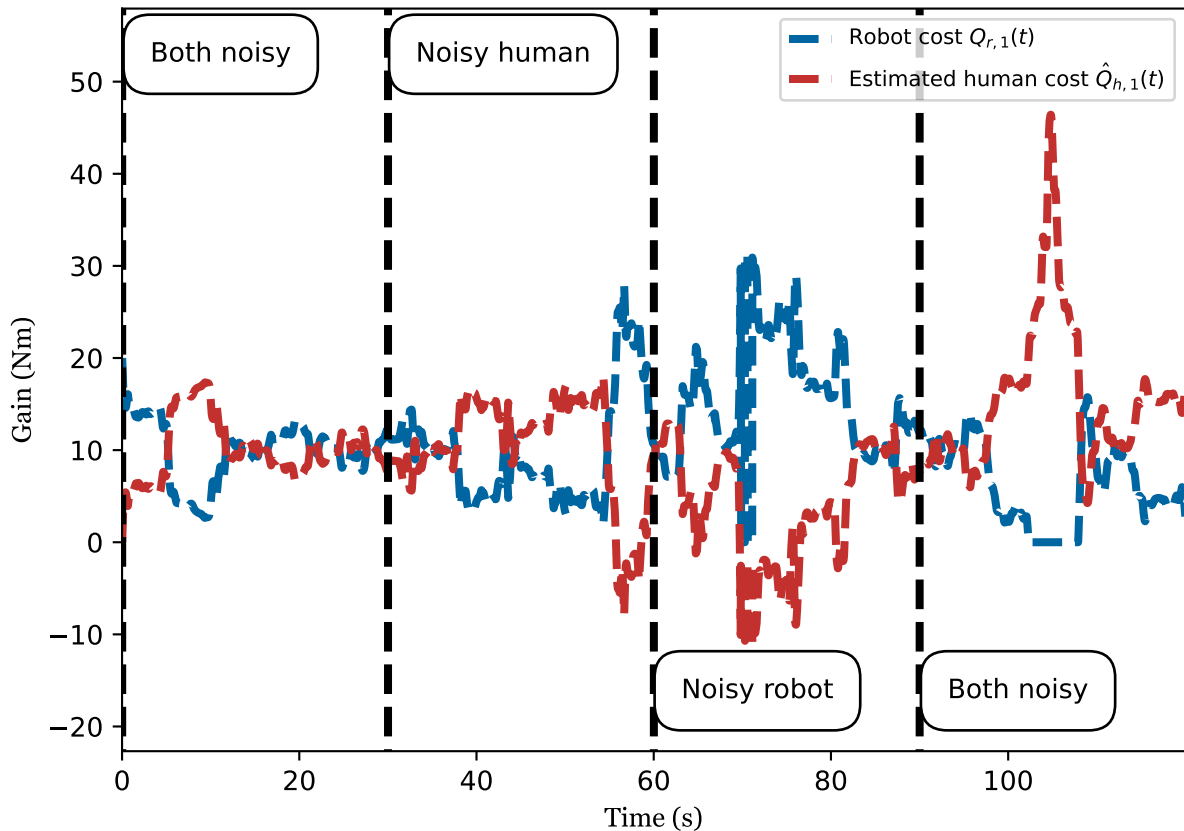
Gains position



Computational times



Cost function weights



Cost function weights

