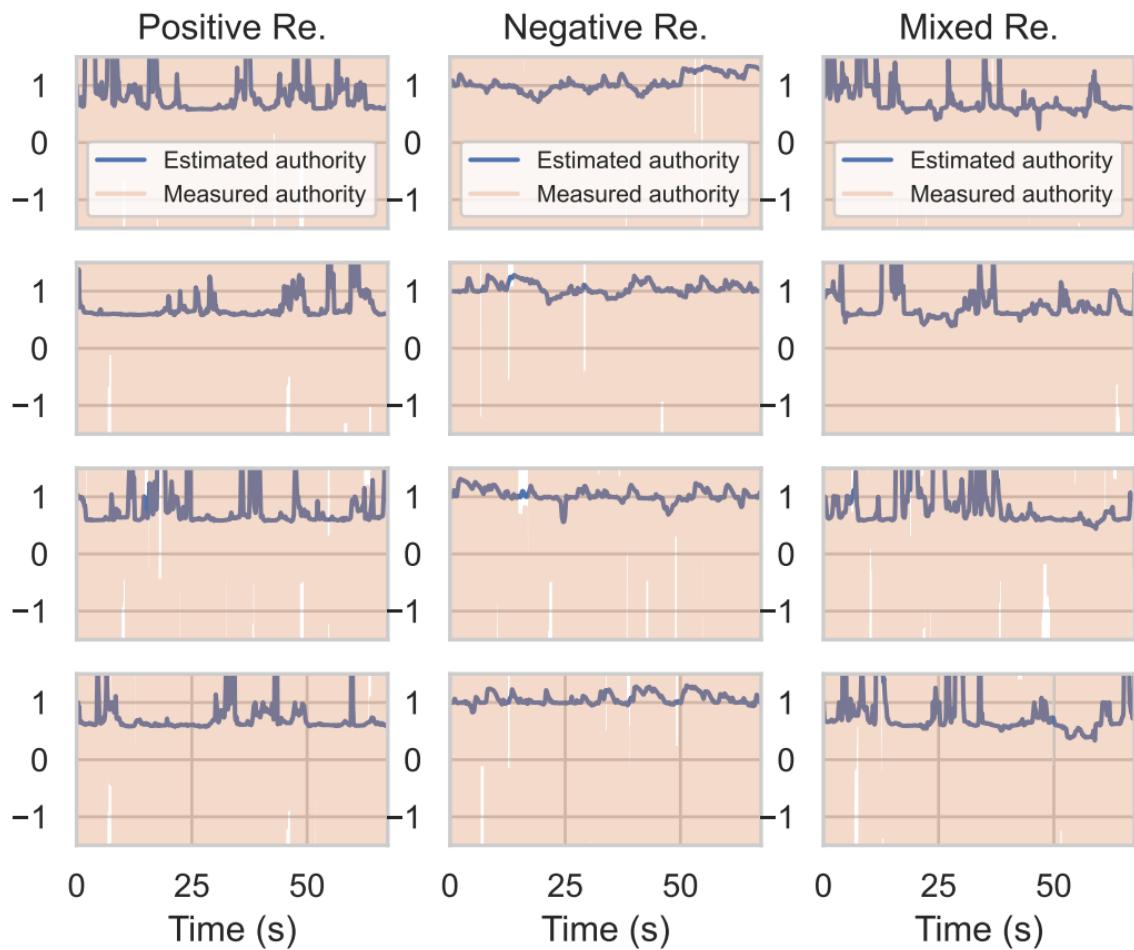
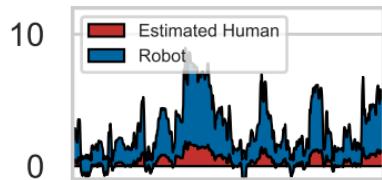


# Estimated Control Authority

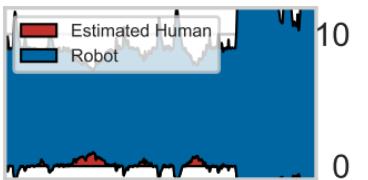


# Gains

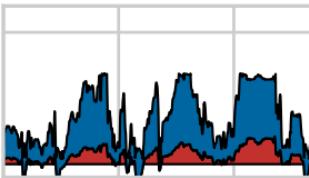
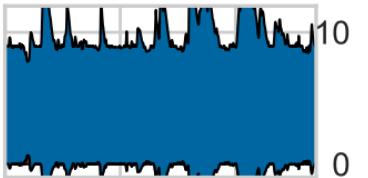
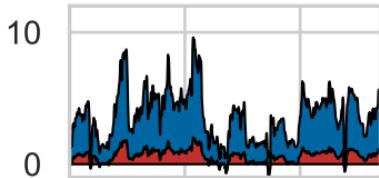
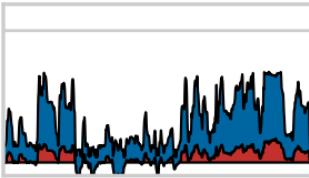
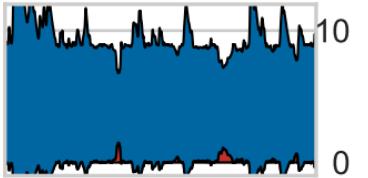
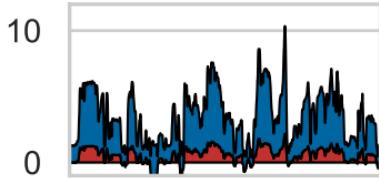
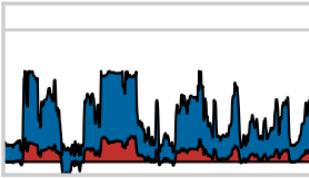
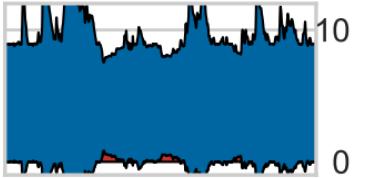
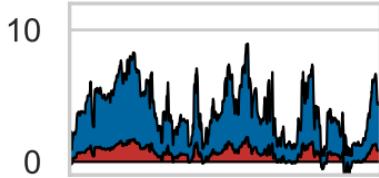
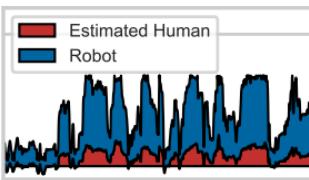
Positive Re.



Negative Re.



Mixed Re.

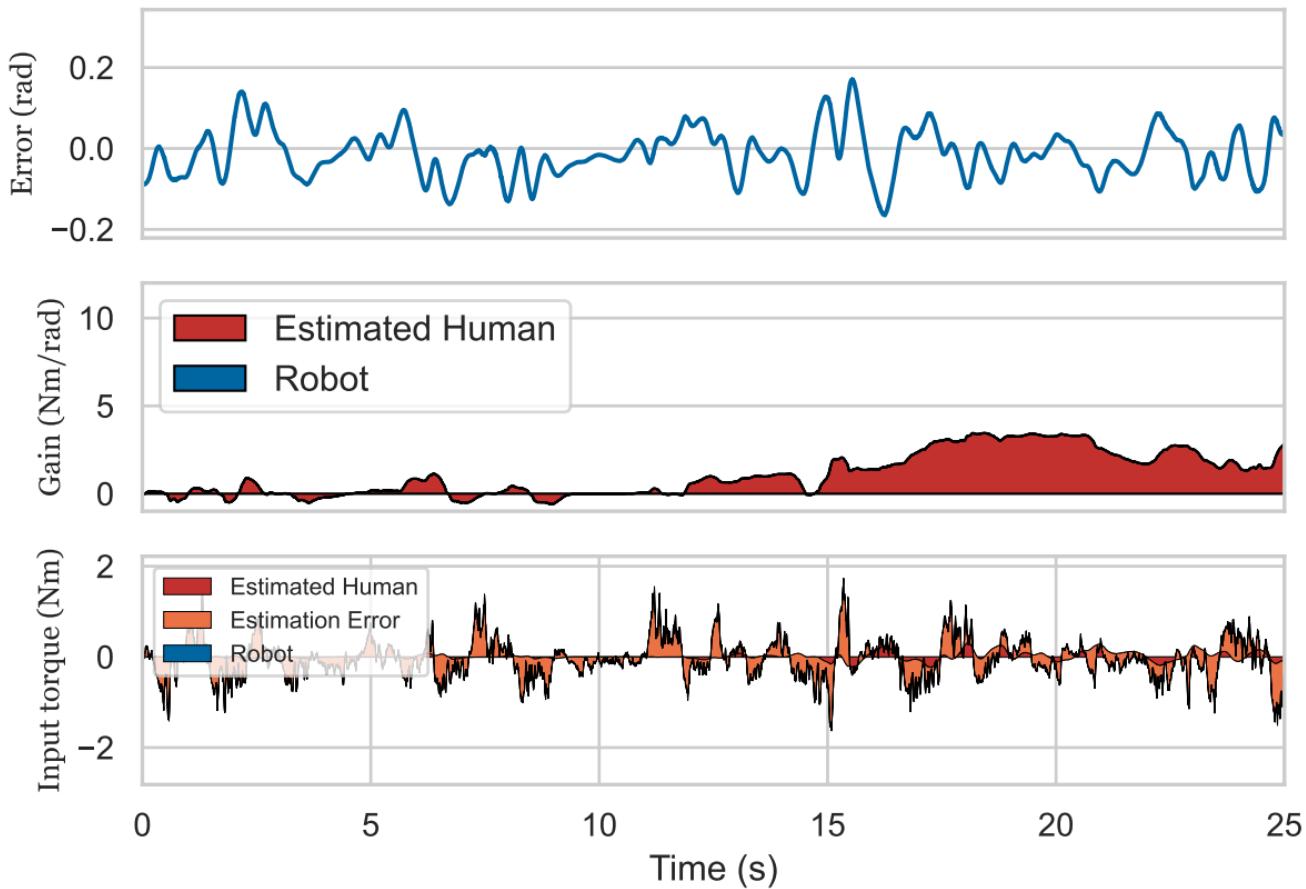


Time (s)

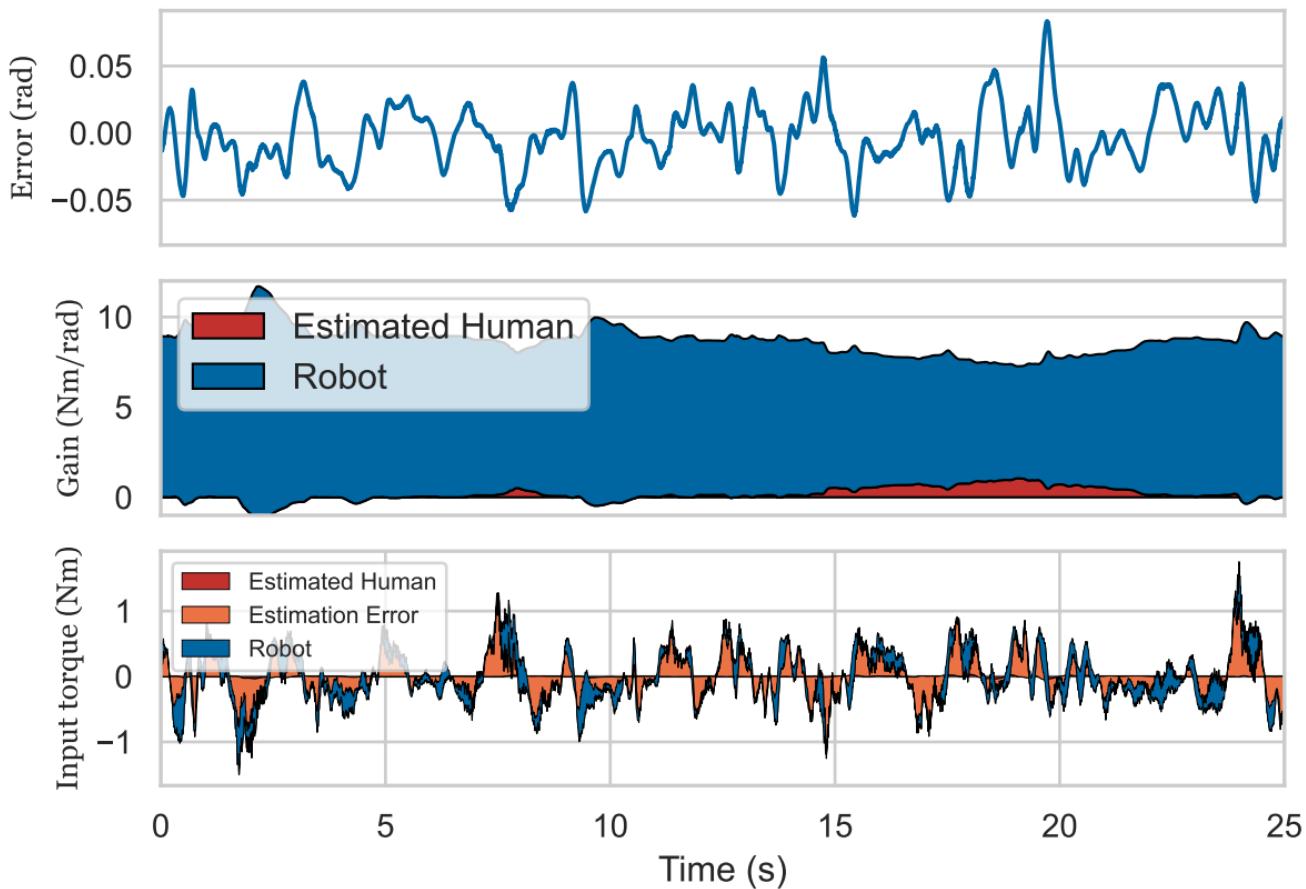
Time (s)

Time (s)

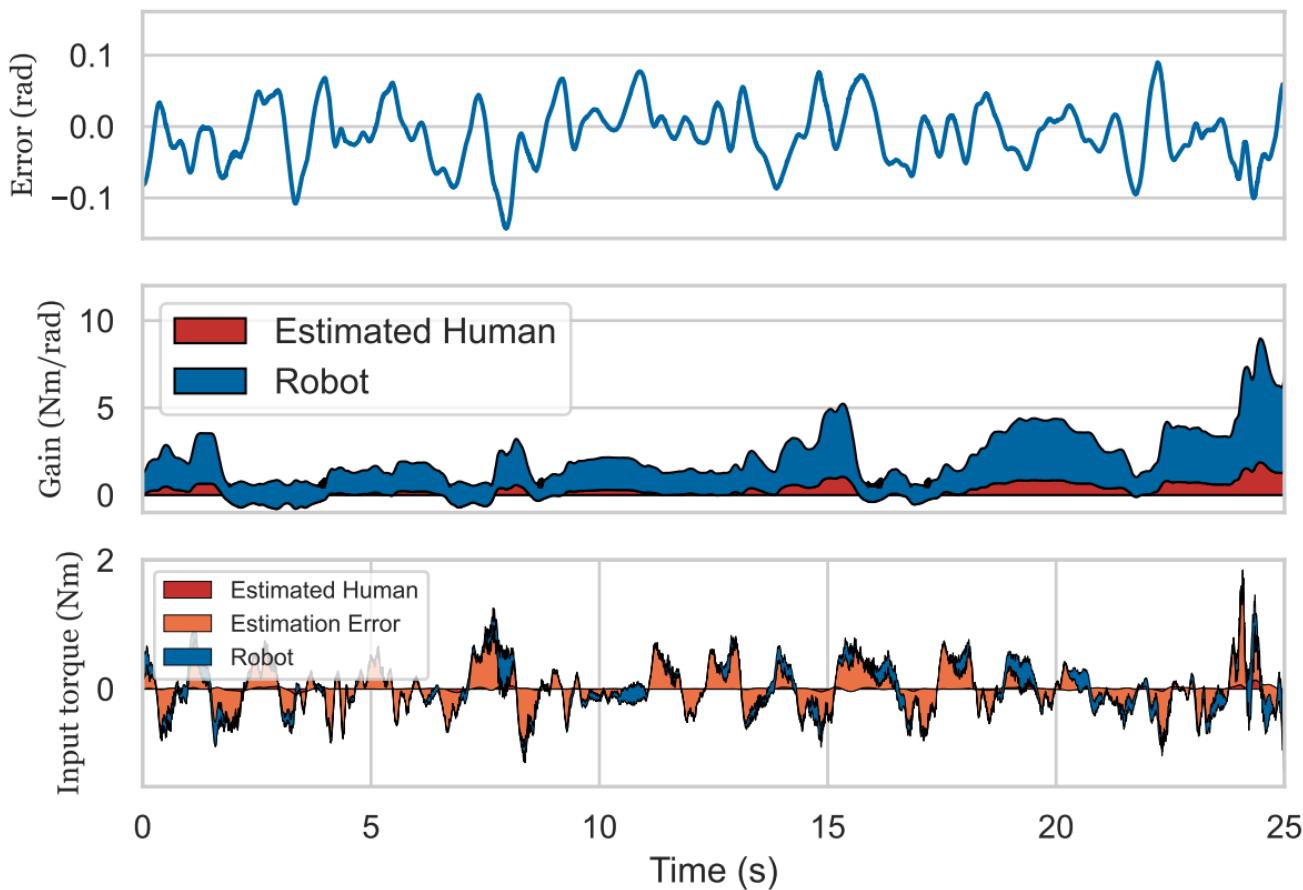
# Manual Control



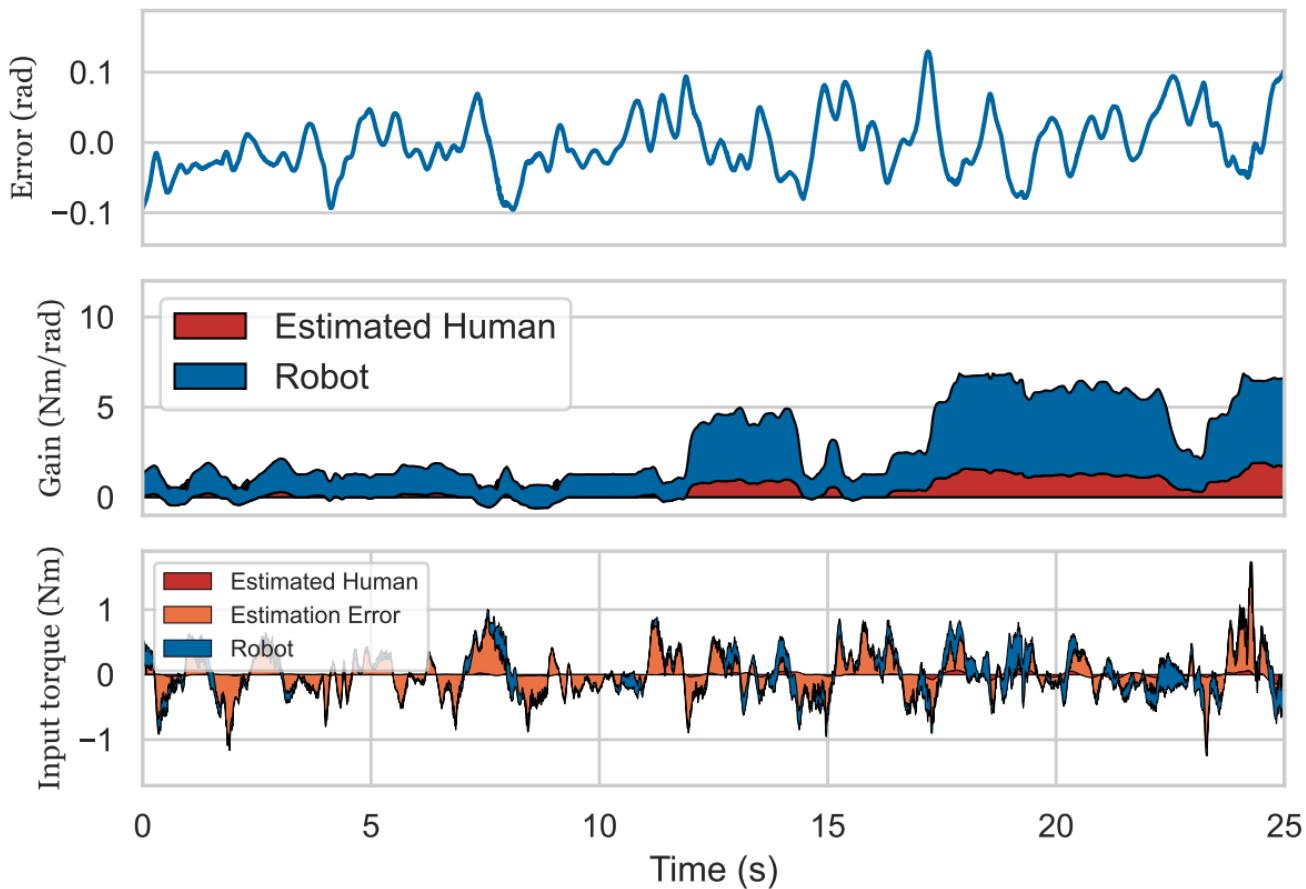
# Negative Reinforcement



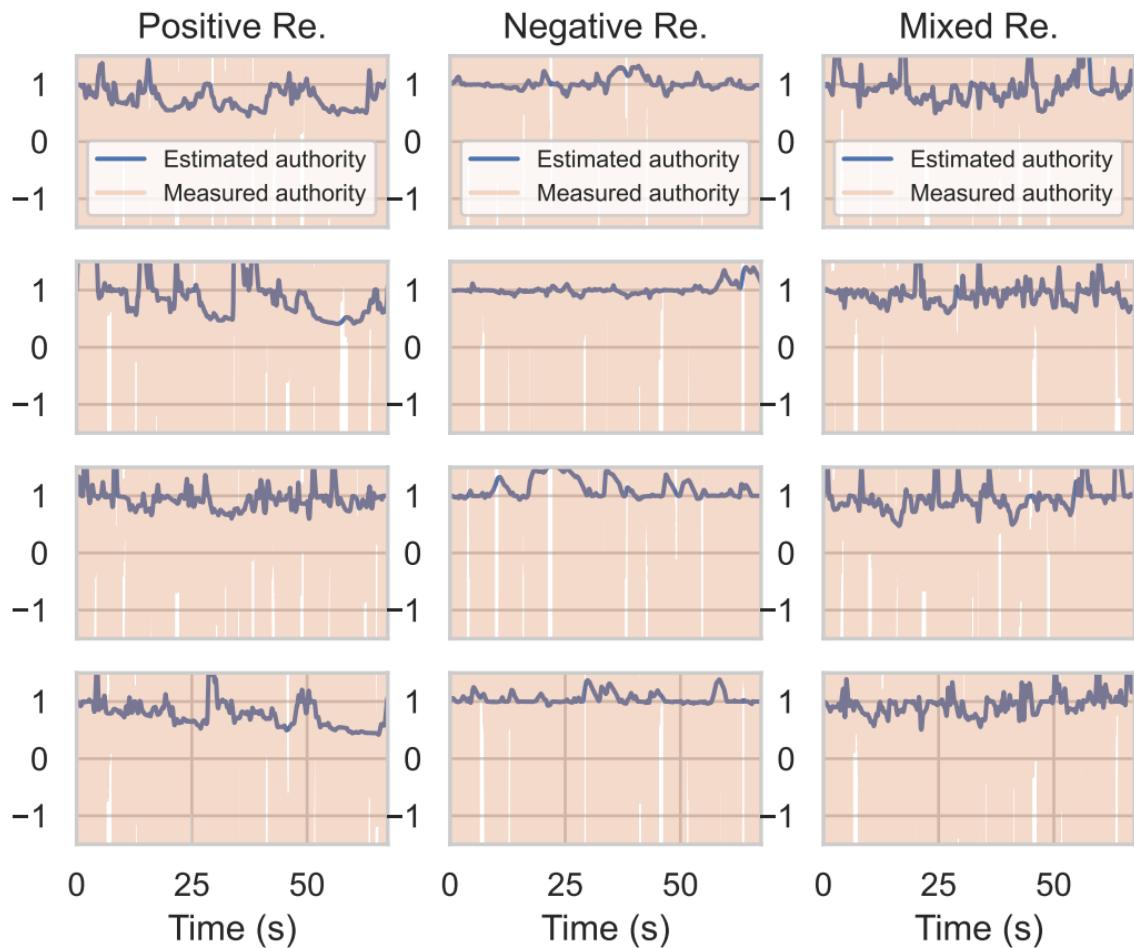
# Positive Reinforcement



# Mixed Reinforcement

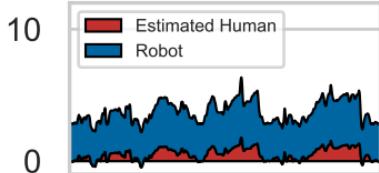


# Estimated Control Authority

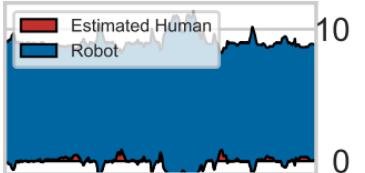


# Gains

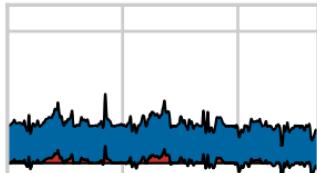
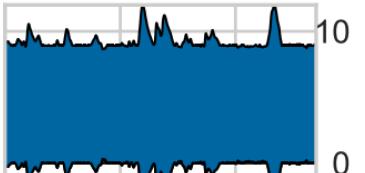
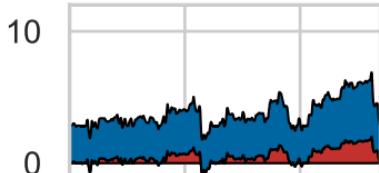
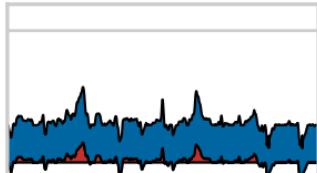
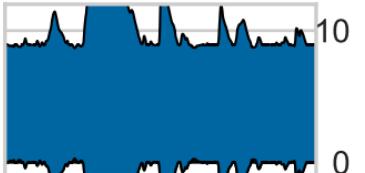
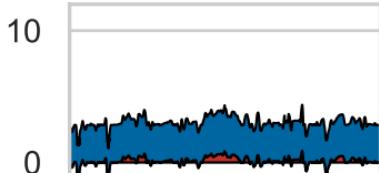
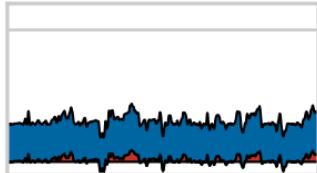
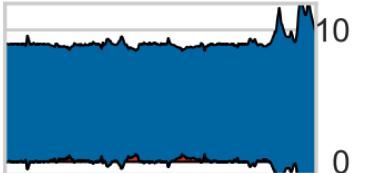
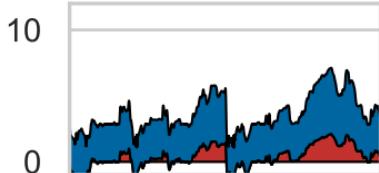
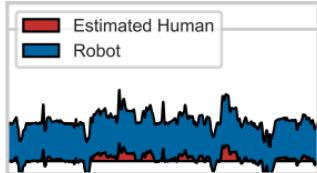
Positive Re.



Negative Re.

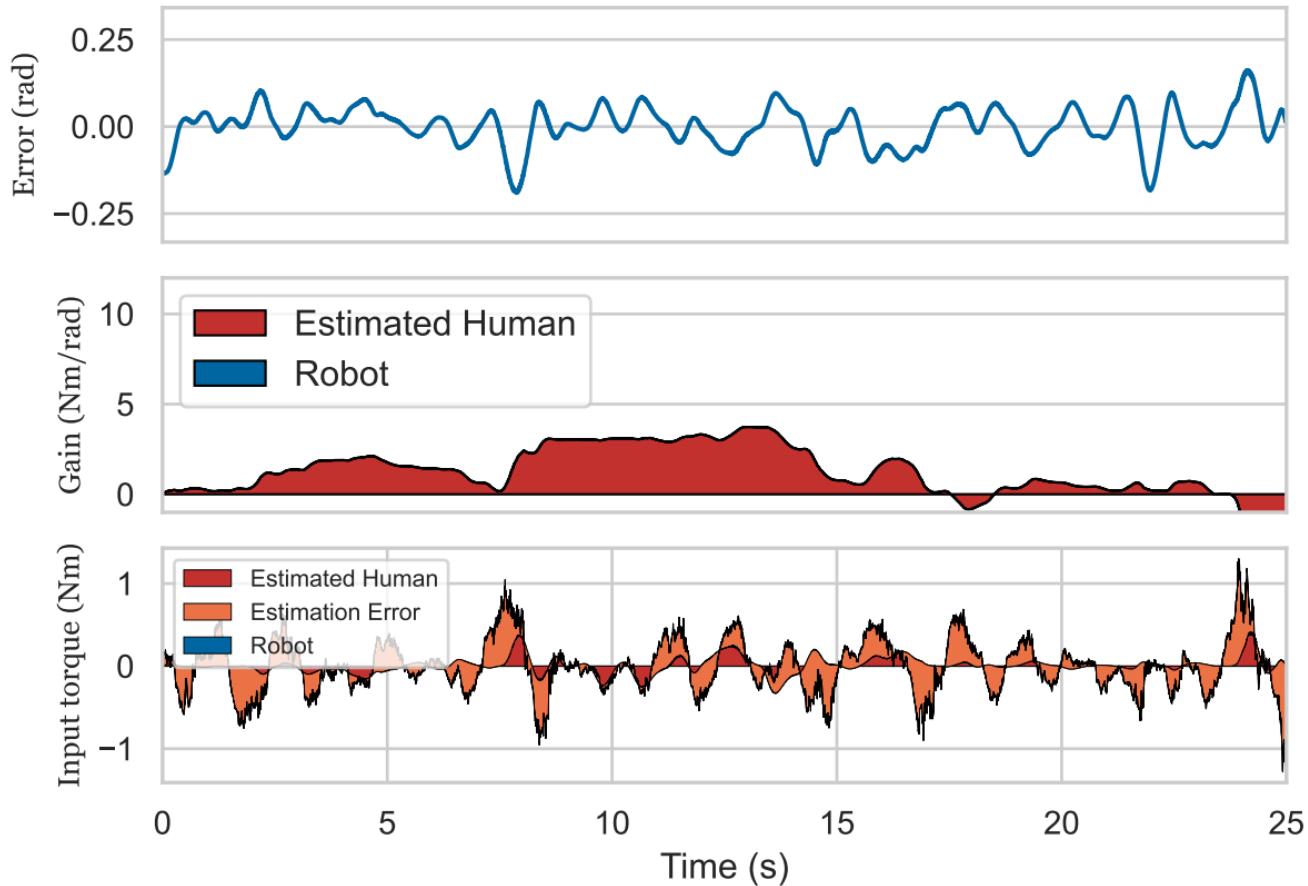


Mixed Re.

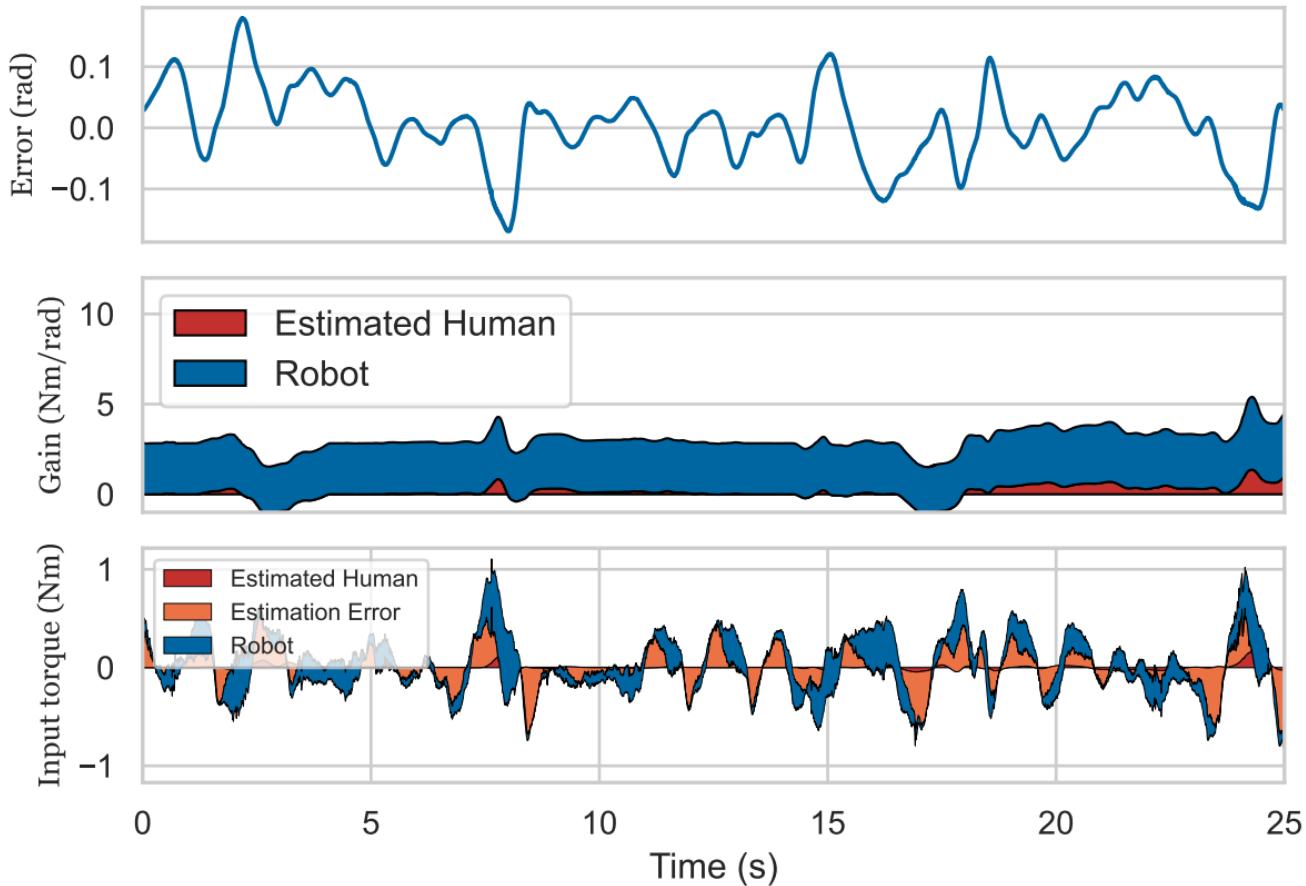


0 25 50 Time (s)

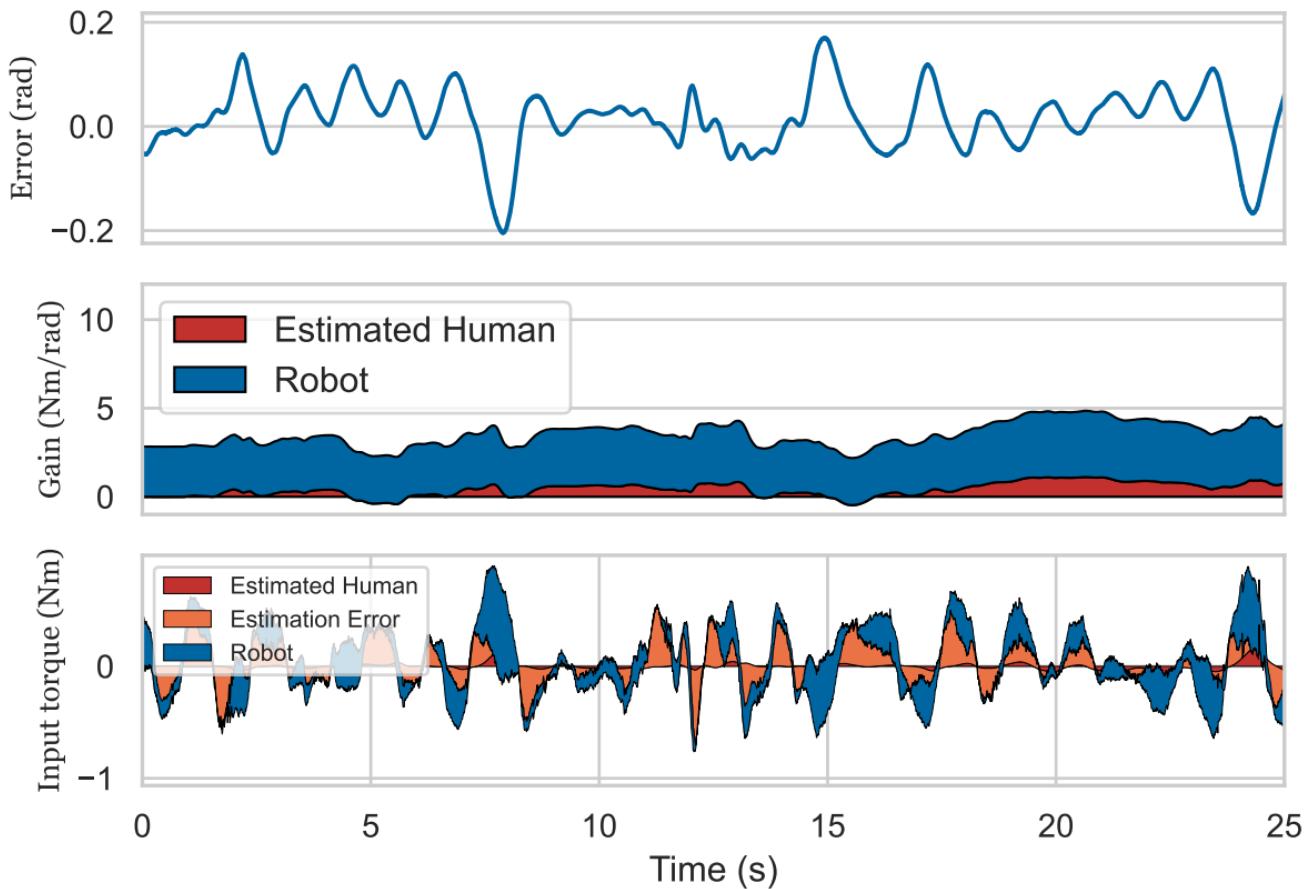
# Manual Control



# Mixed Reinforcement



# Positive Reinforcement



# Negative Reinforcement

