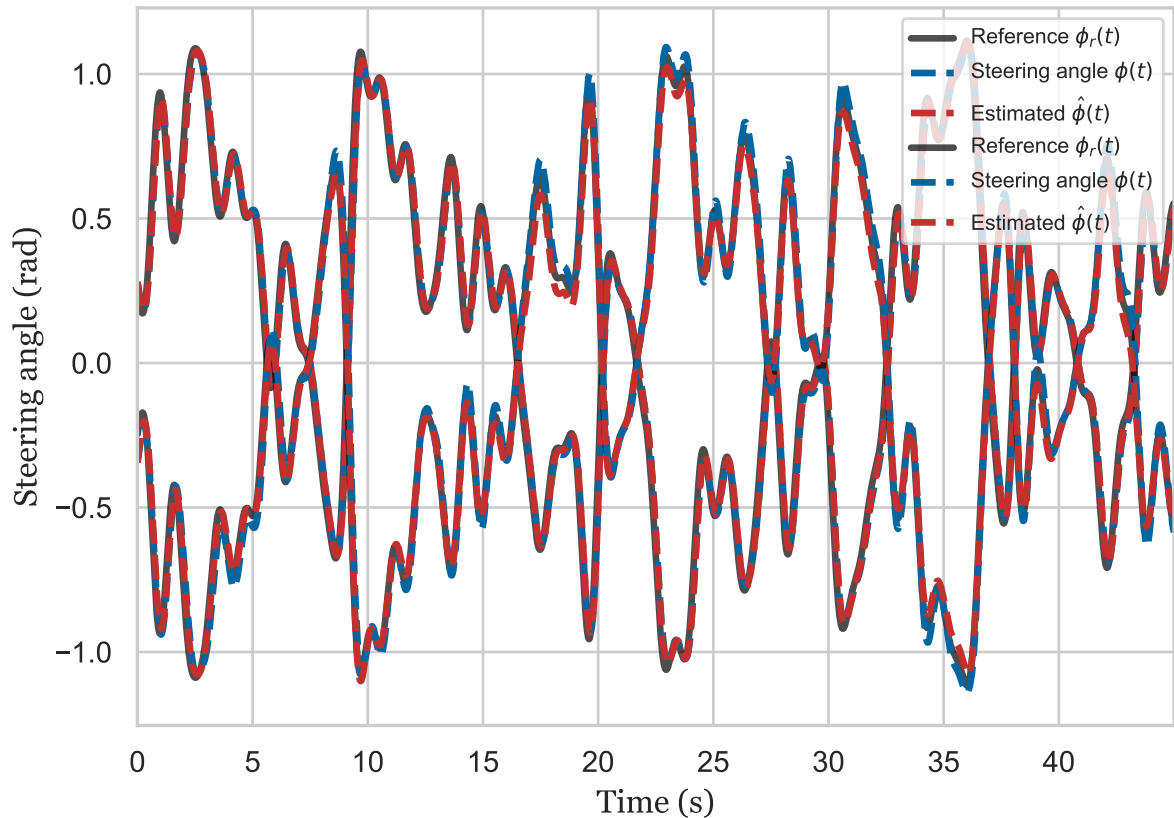
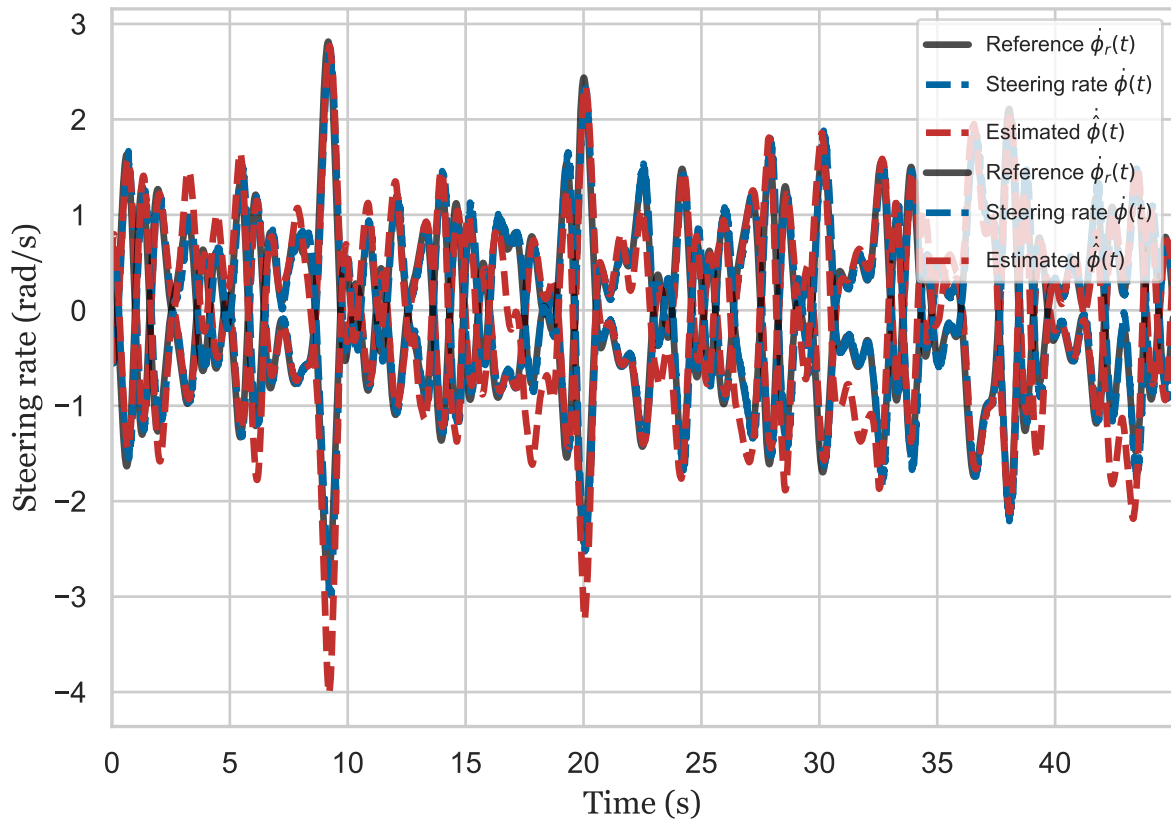


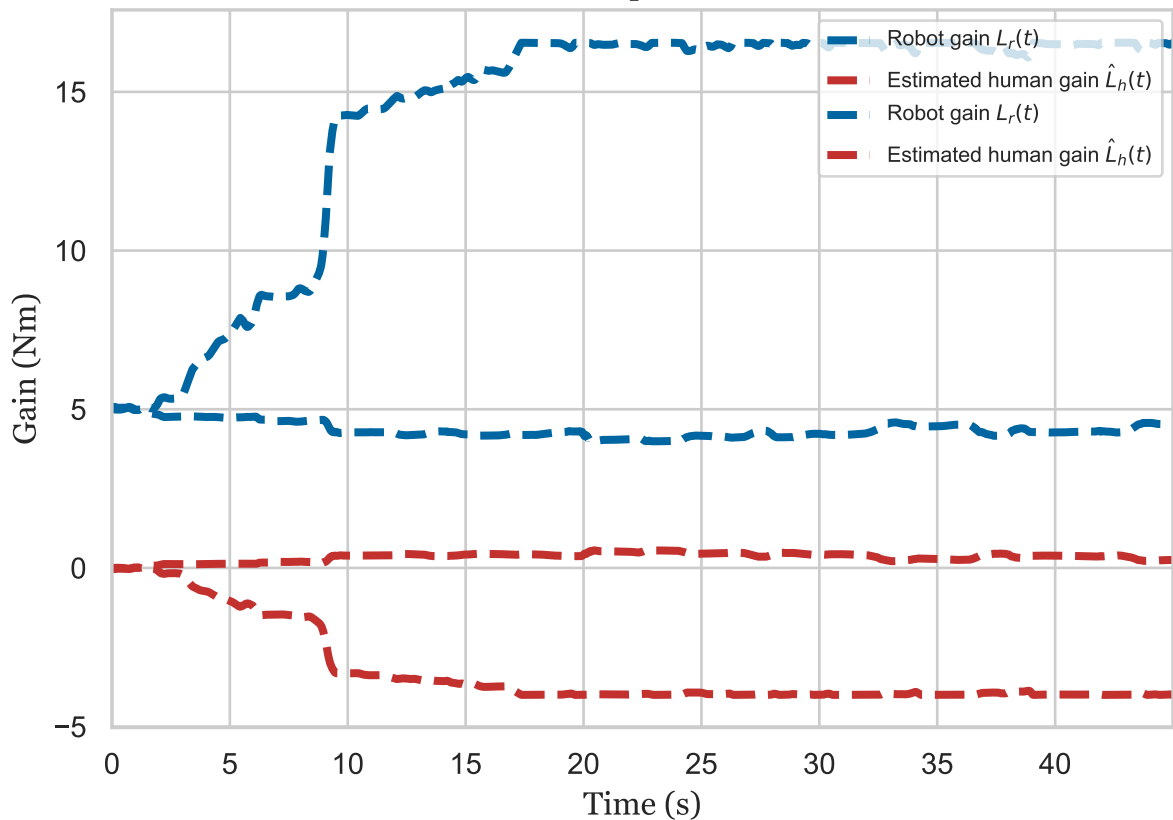
Measured and estimated steering angle



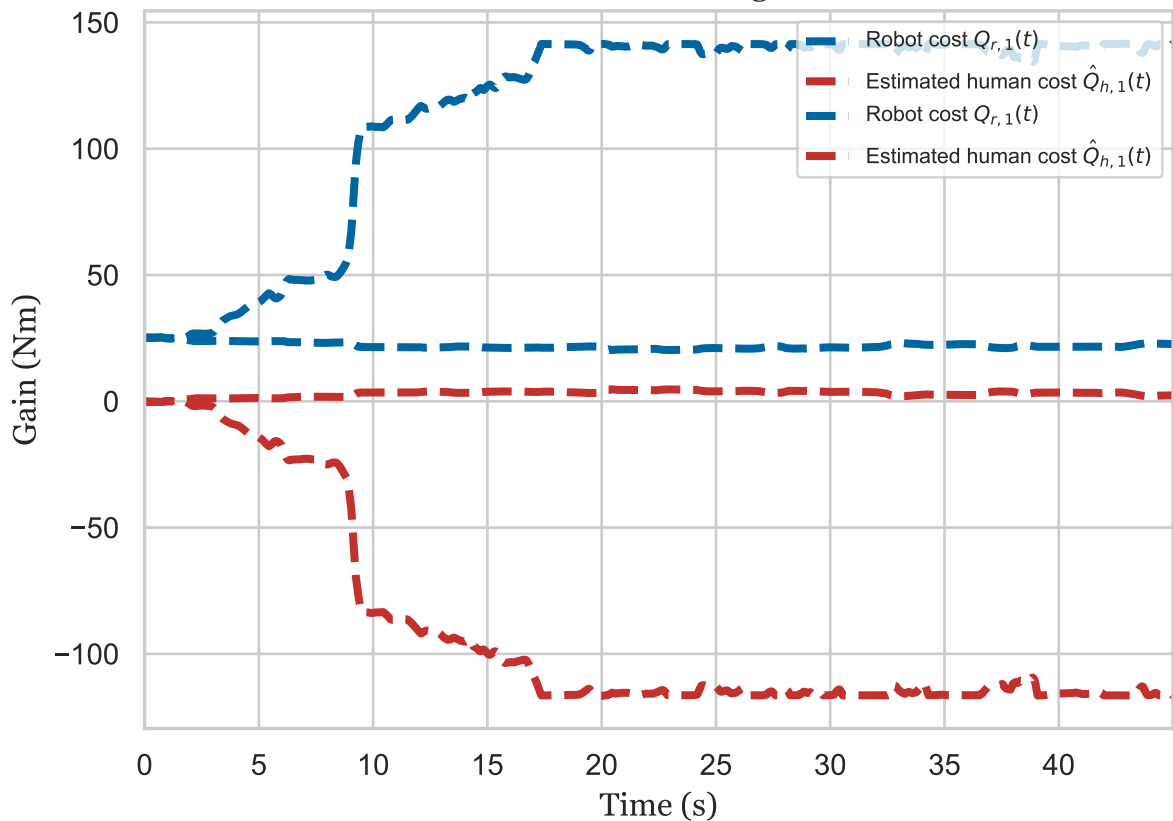
Measured and estimated steering rate



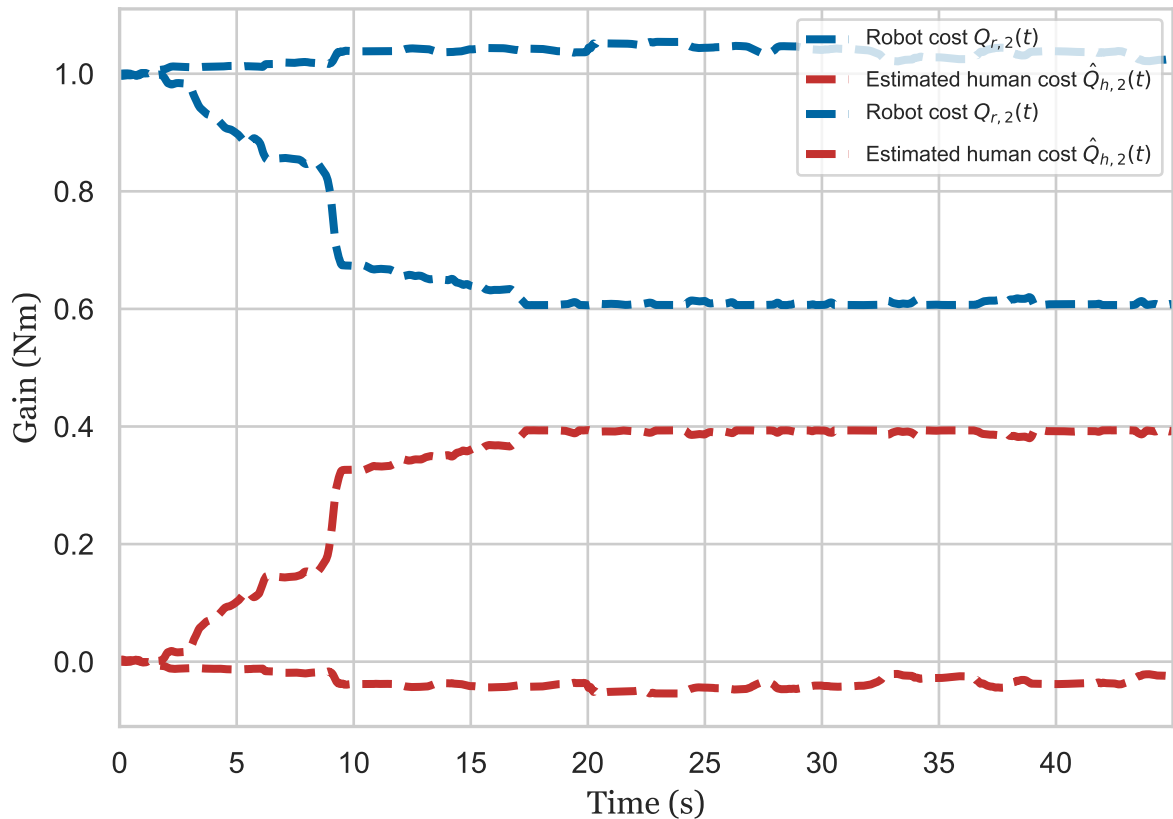
Gains position



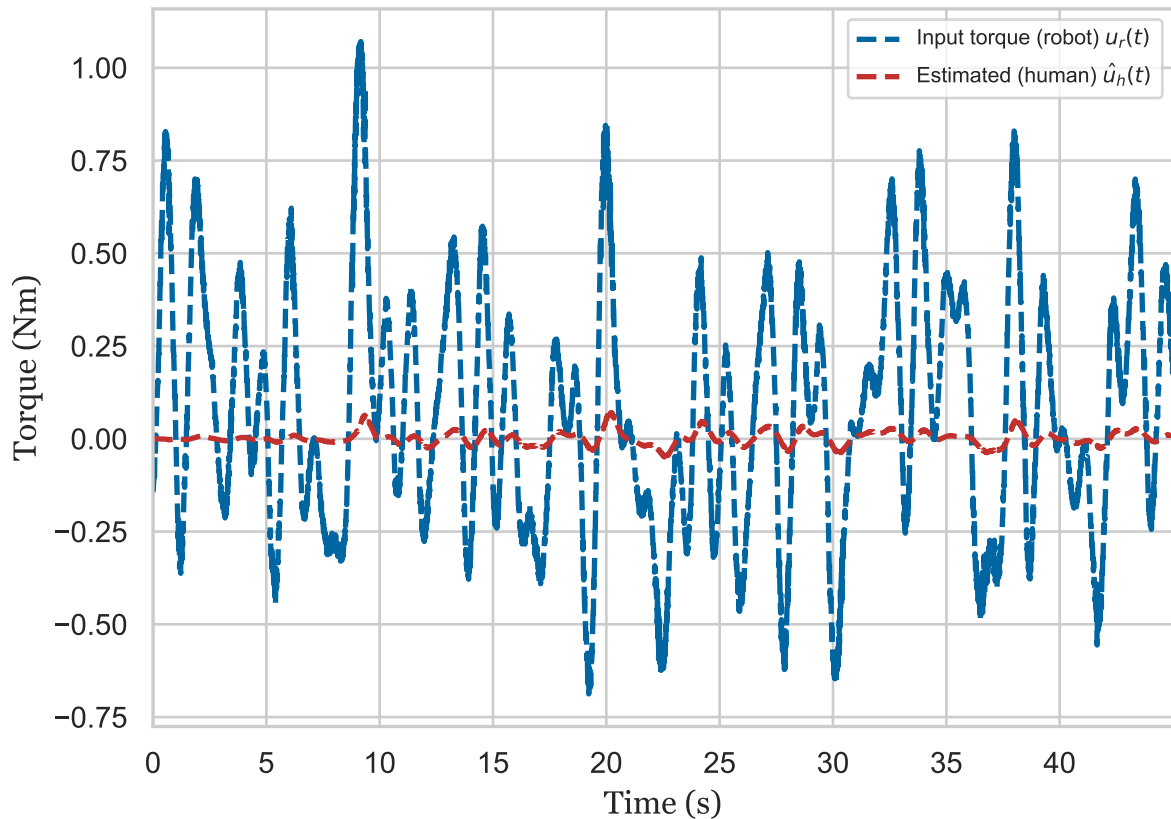
Cost function weights



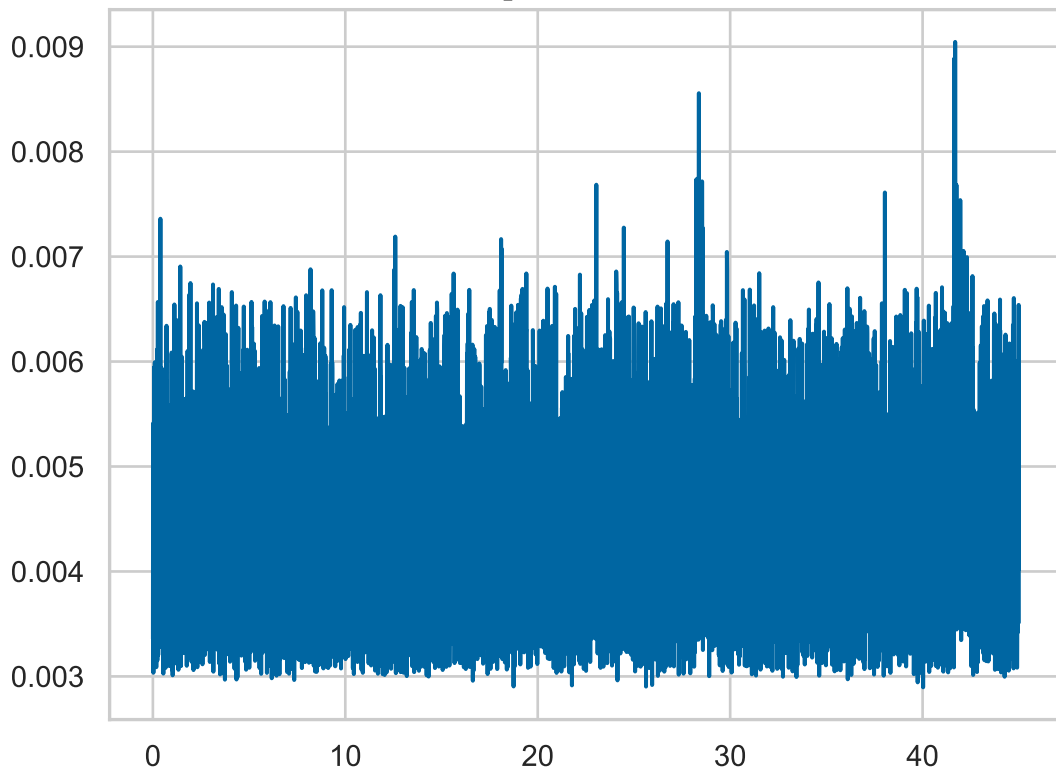
Cost function weights

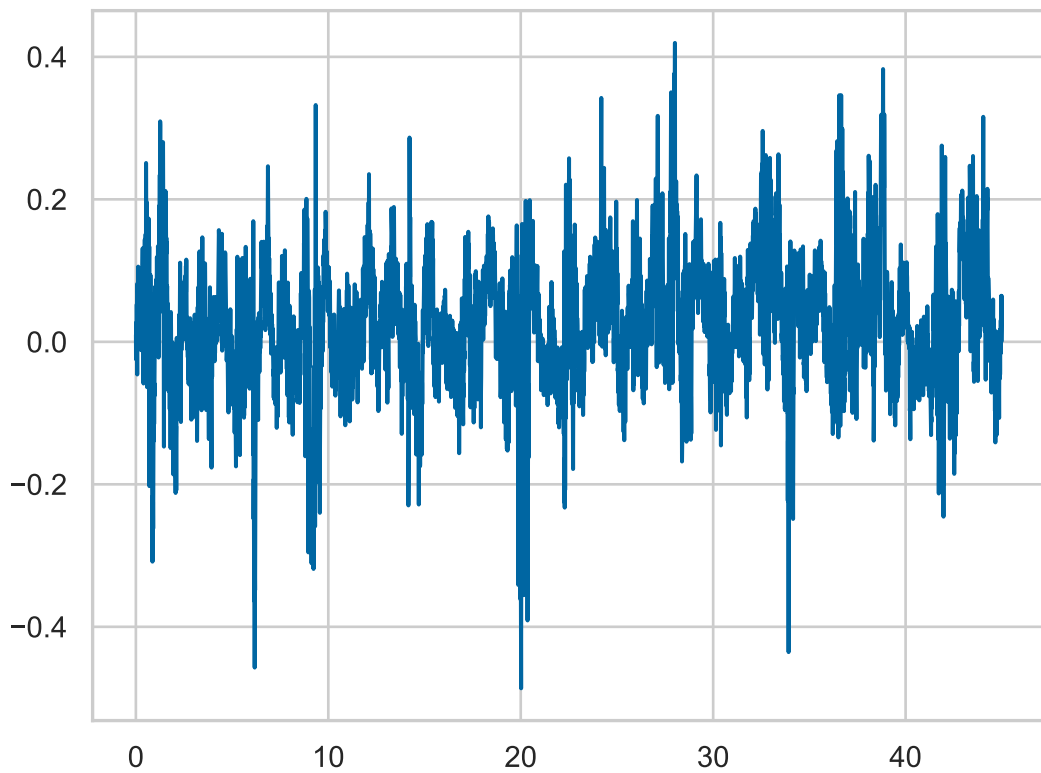


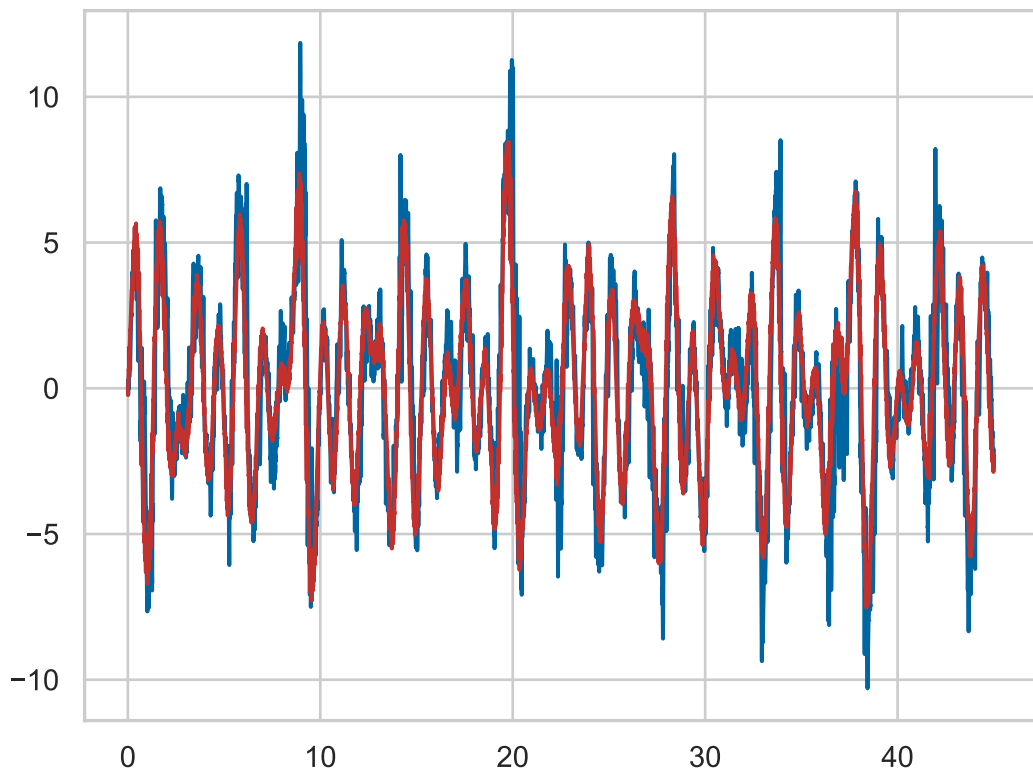
Input torque



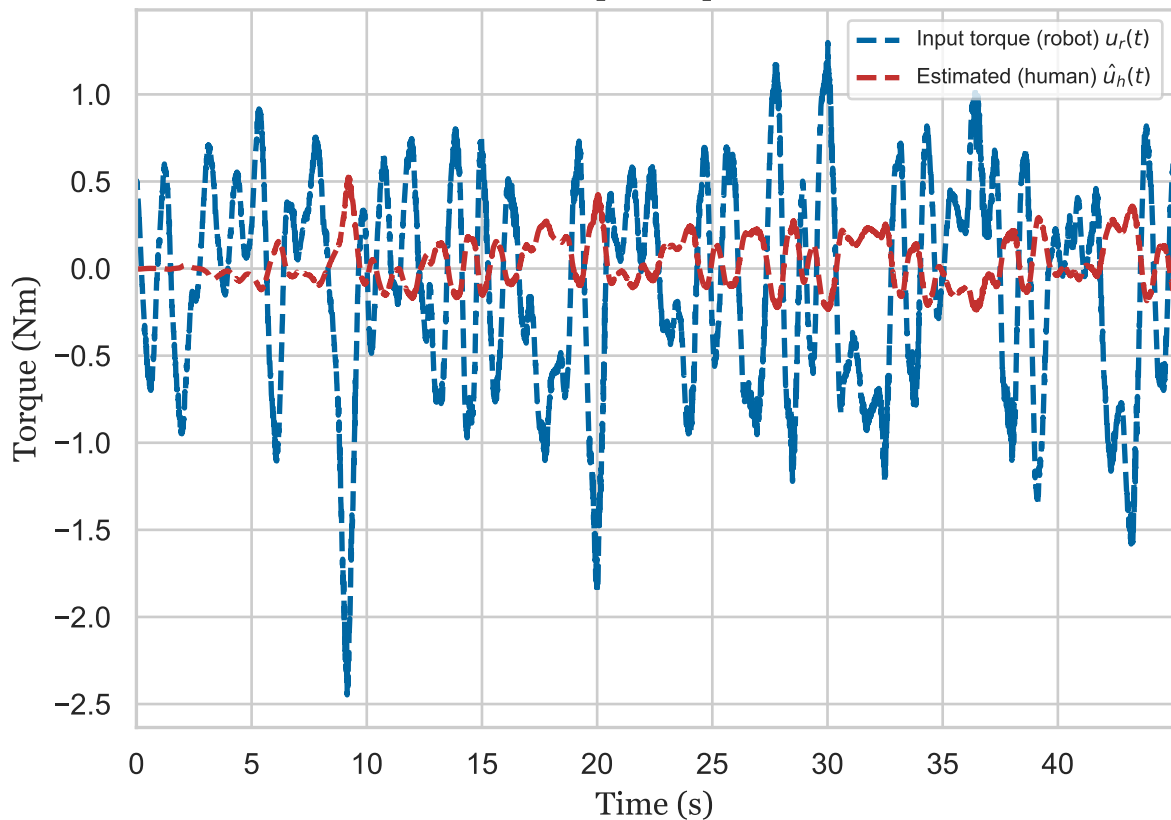
Computational times



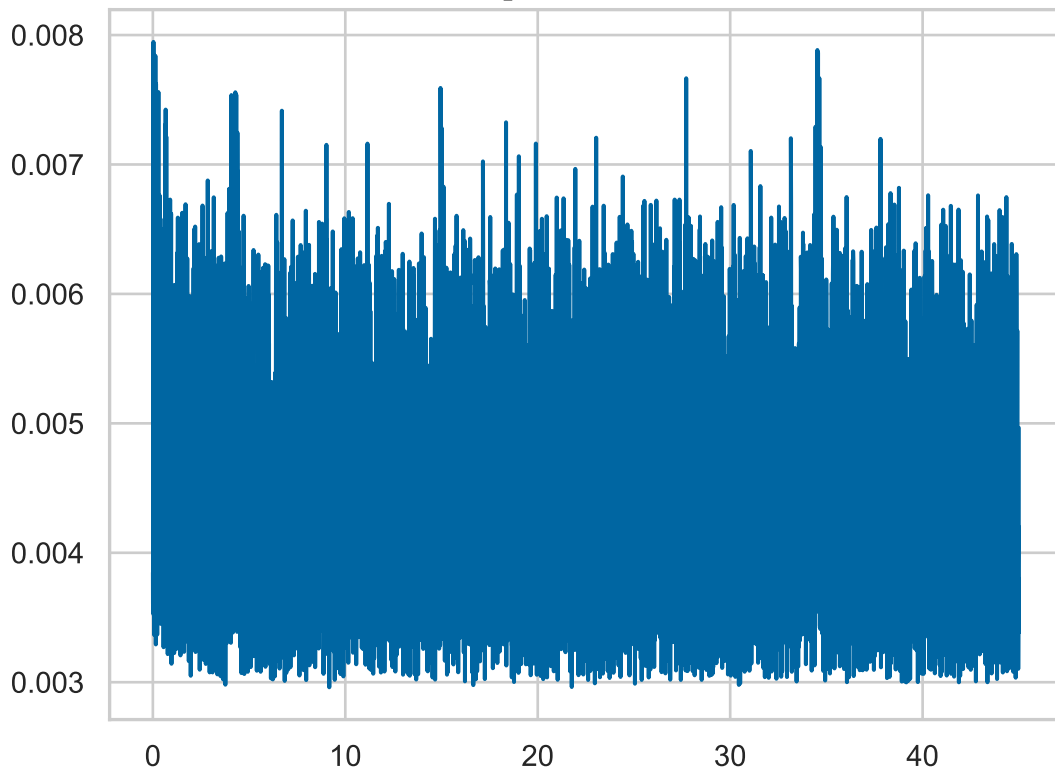


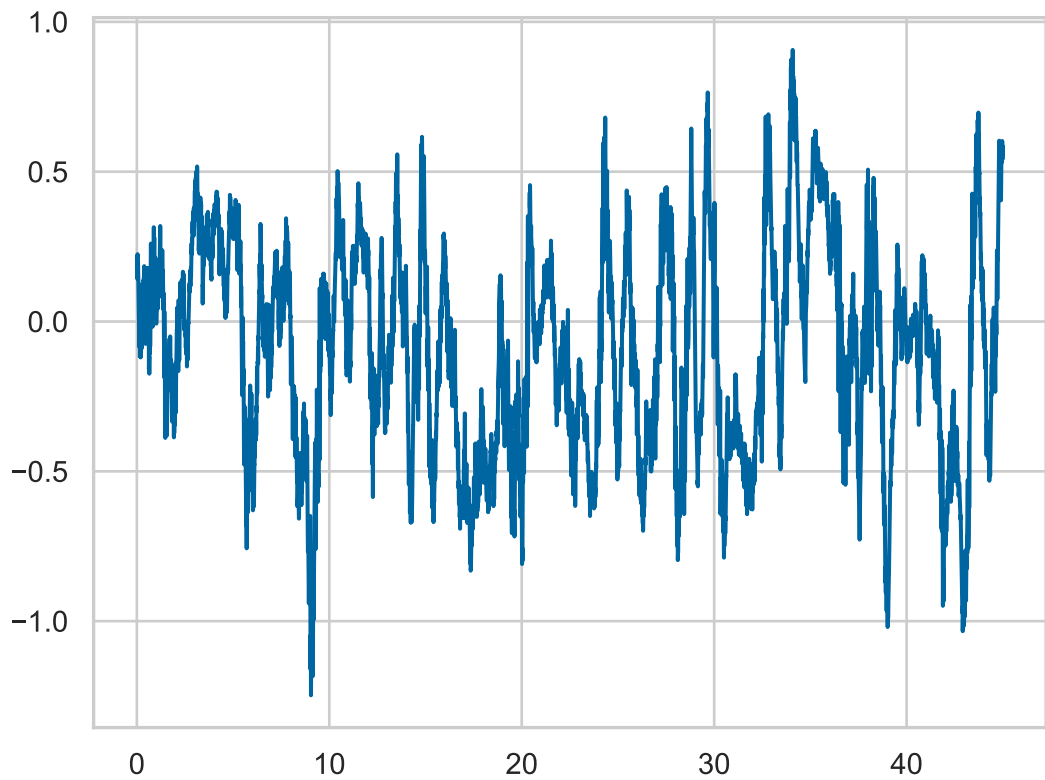


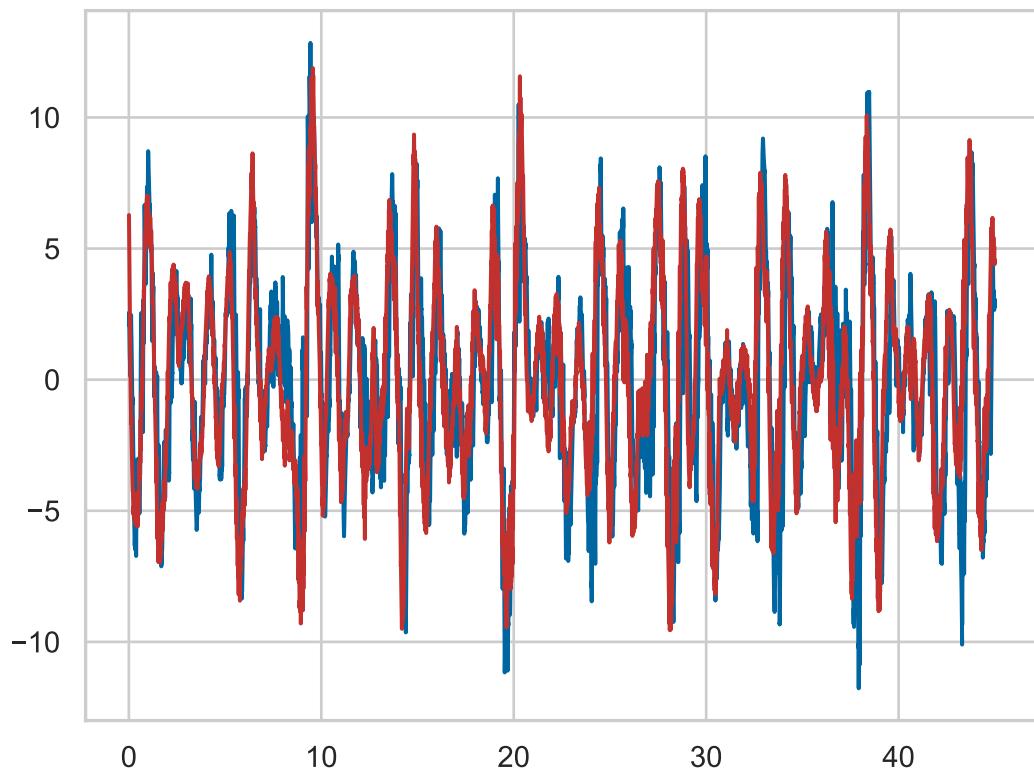
Input torque



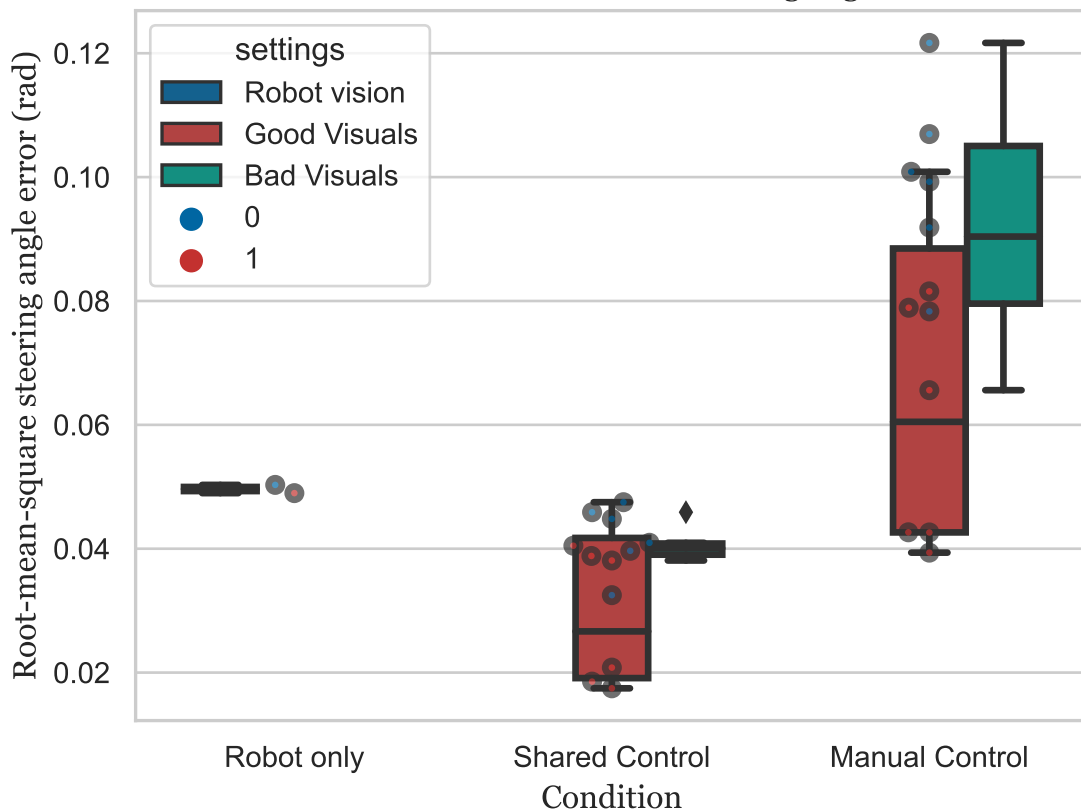
Computational times



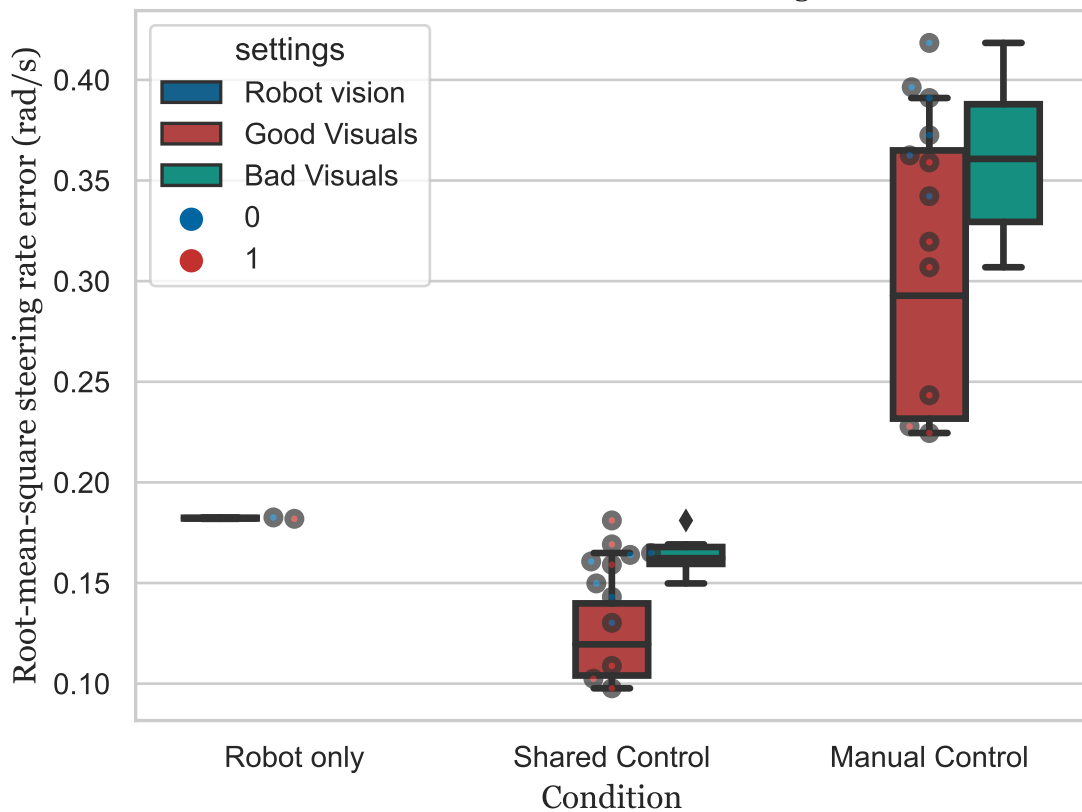




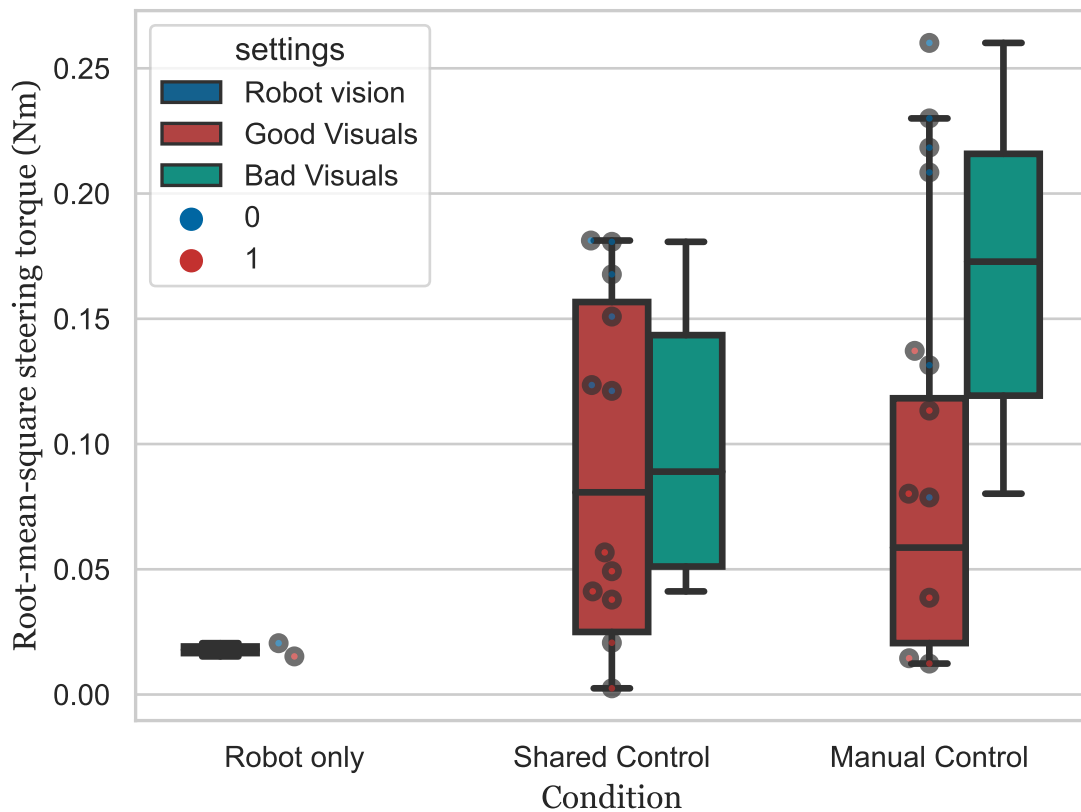
Controller Performance (Steering angle)



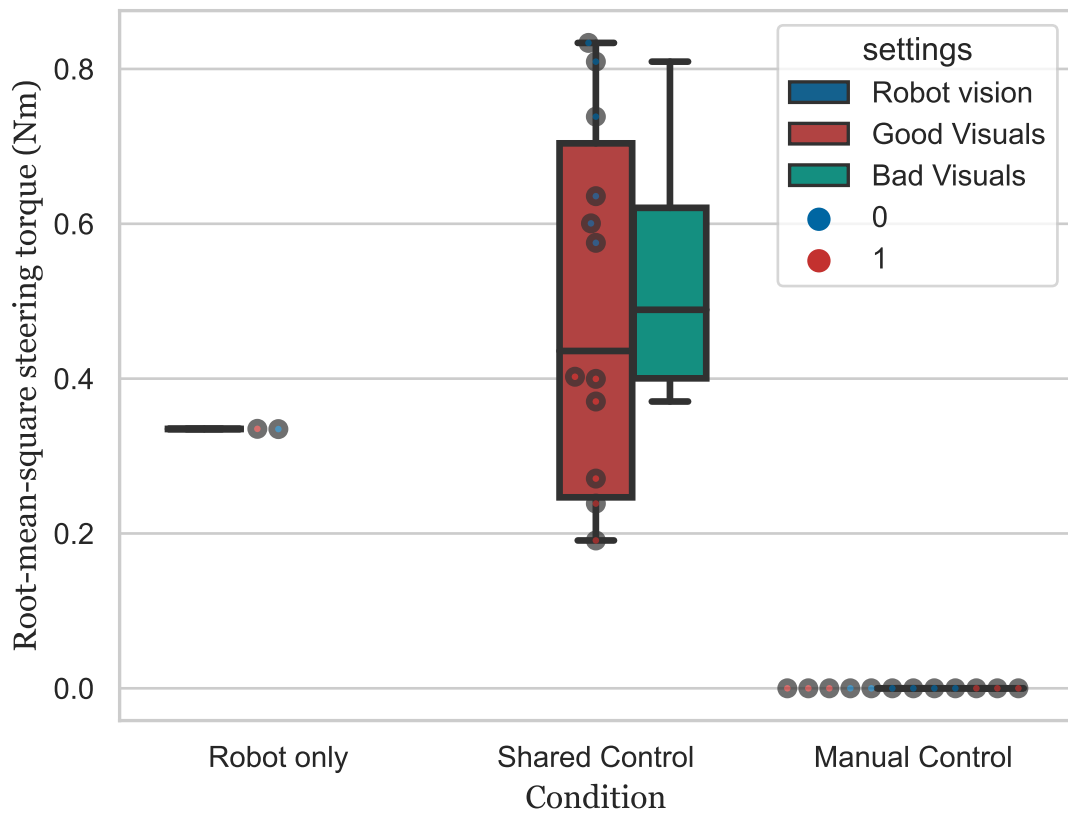
Controller Performance (Steering rate)



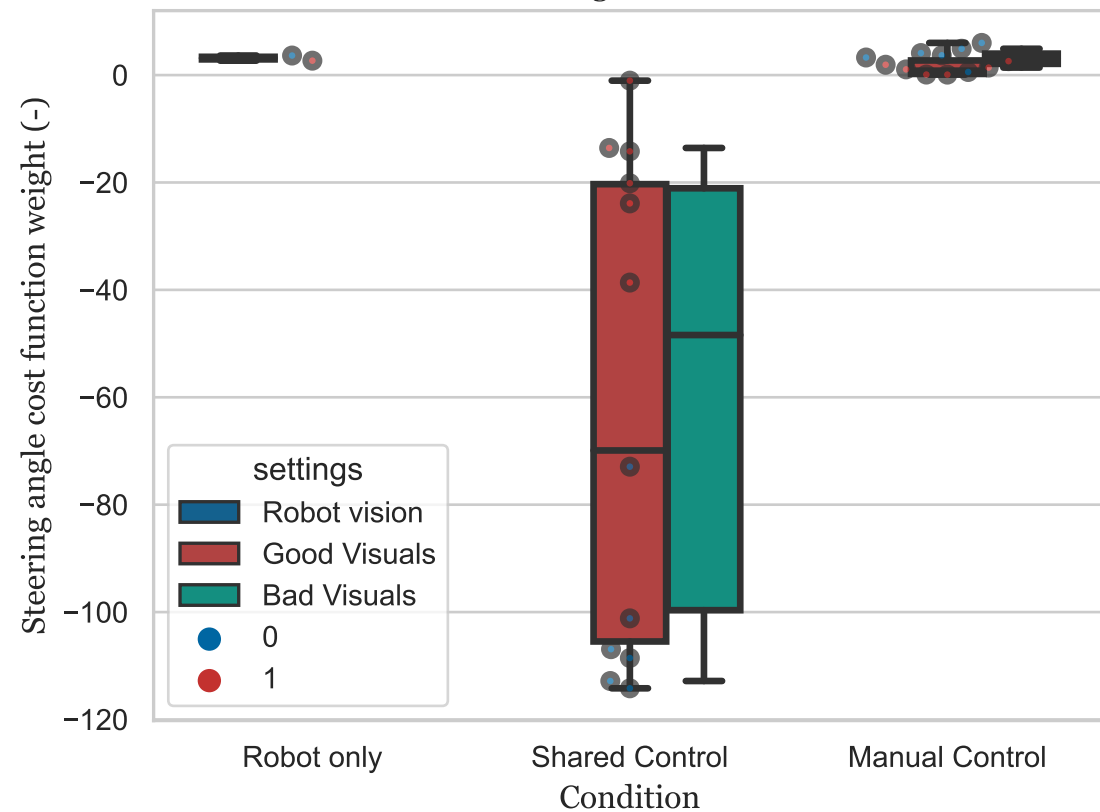
Control Effort (Estimated human)



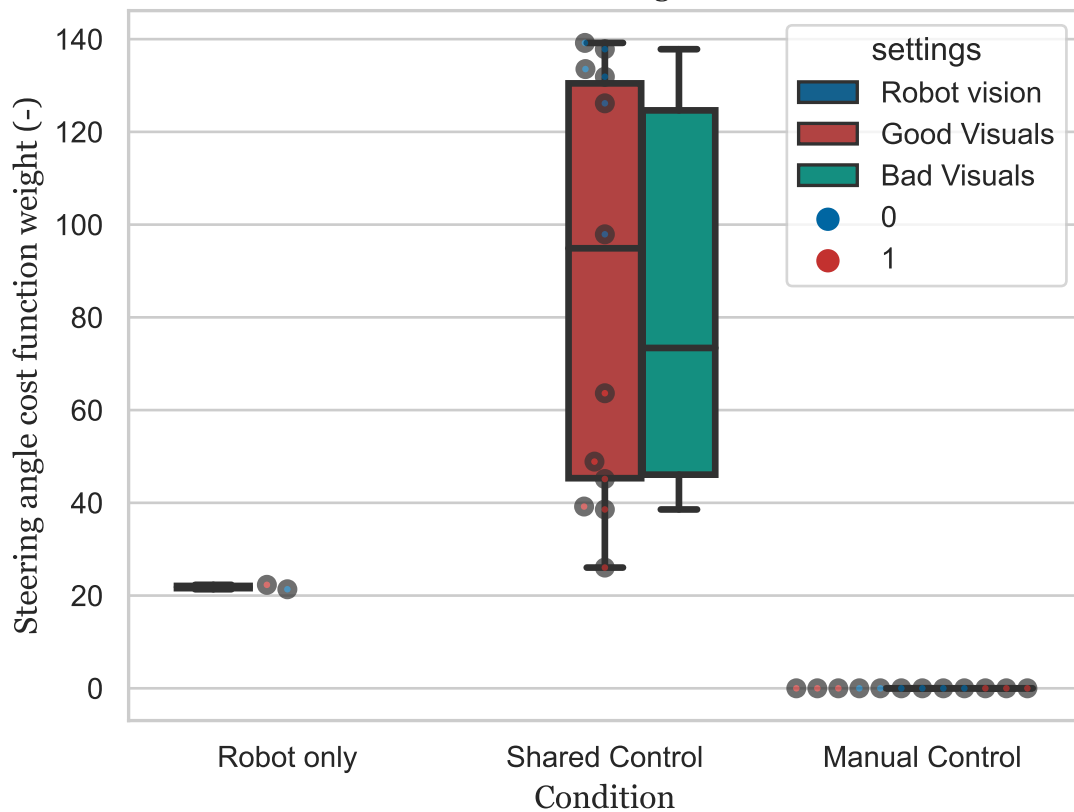
Control Effort (Robot)



Cost Function Weight (Estimated Human)



Cost Function Weight (Robot)



Performance

