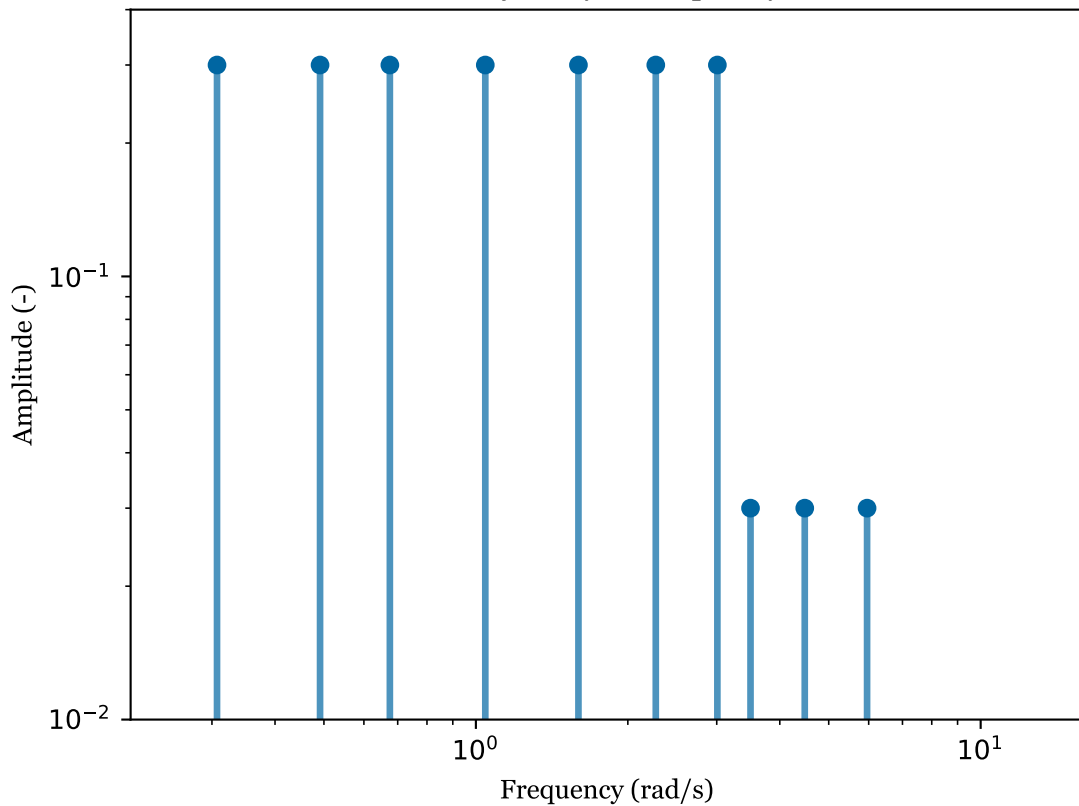
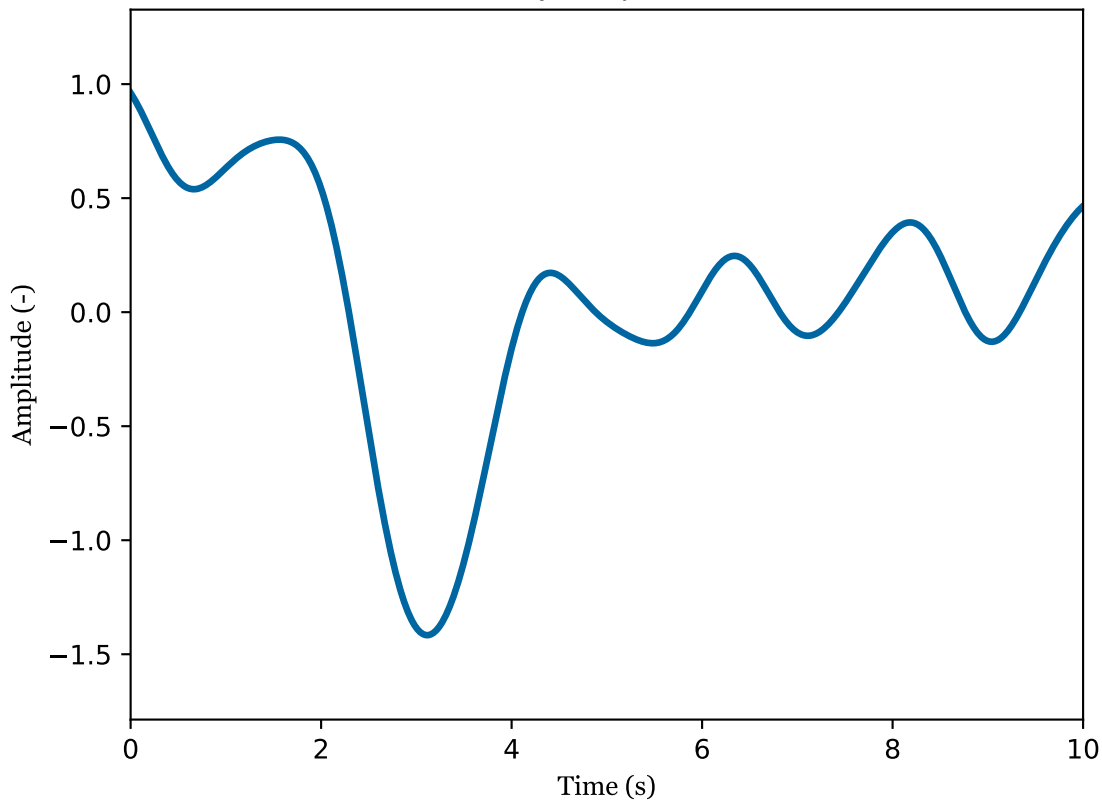


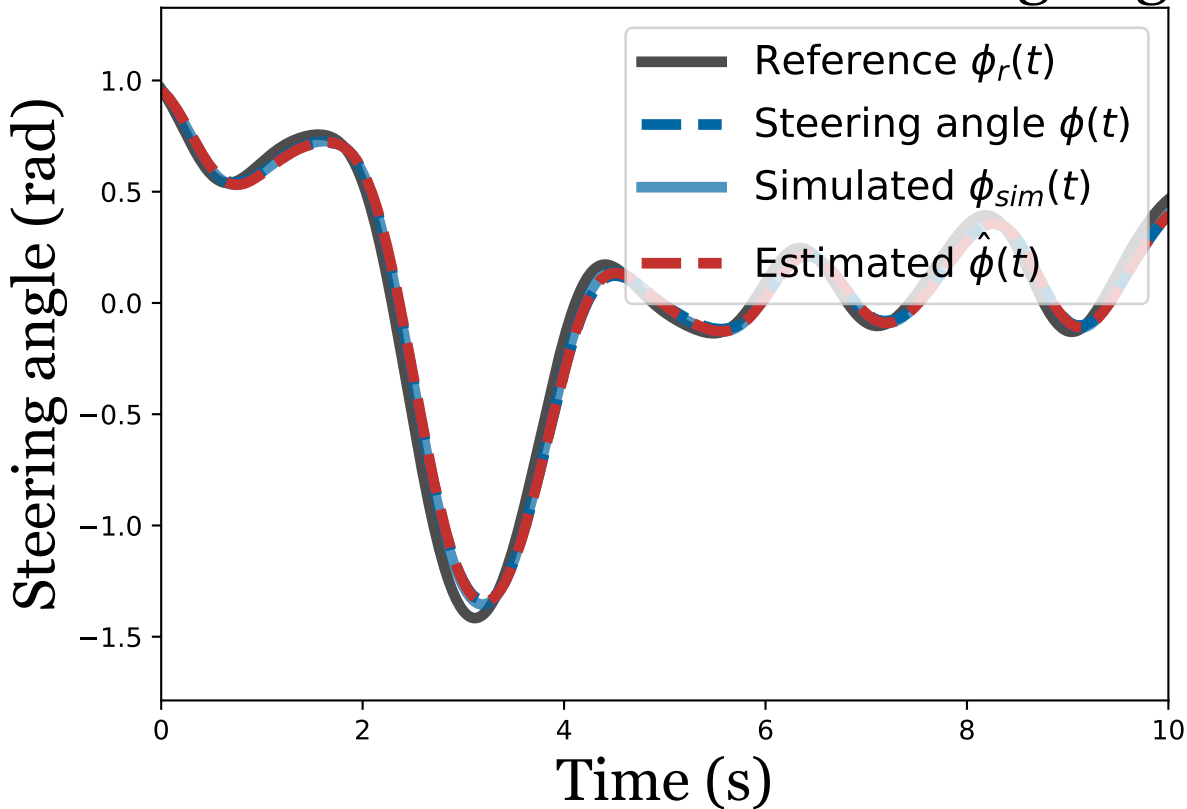
Reference trajectory in frequency domain

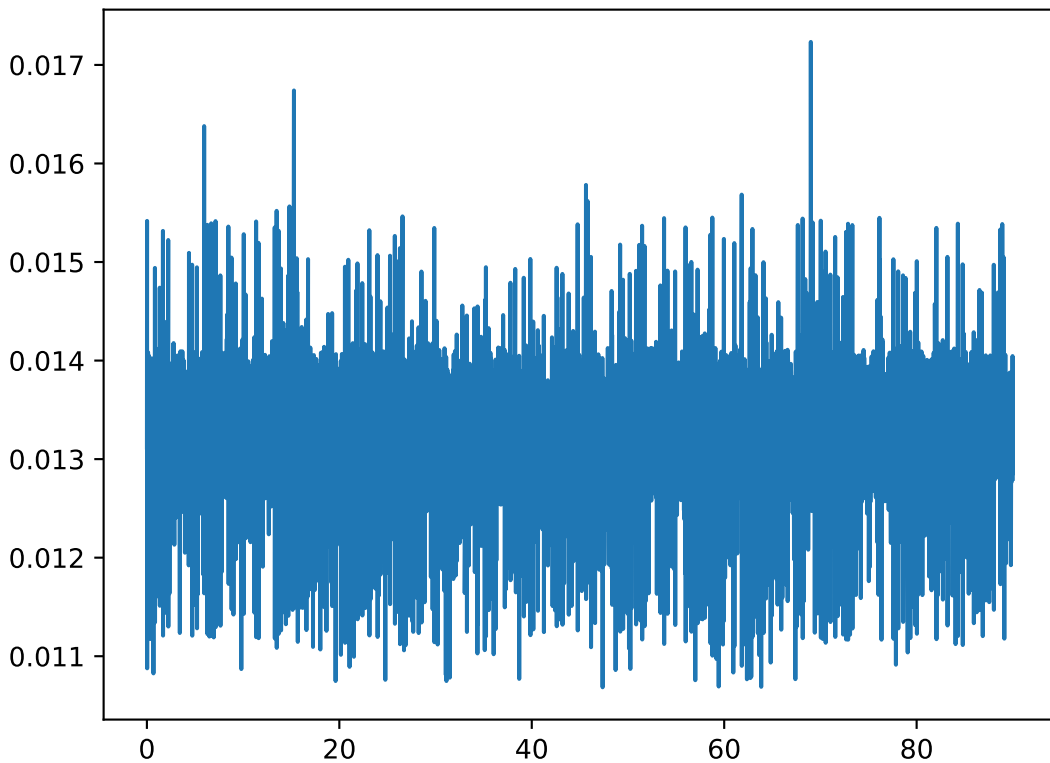


Reference trajectory in time domain



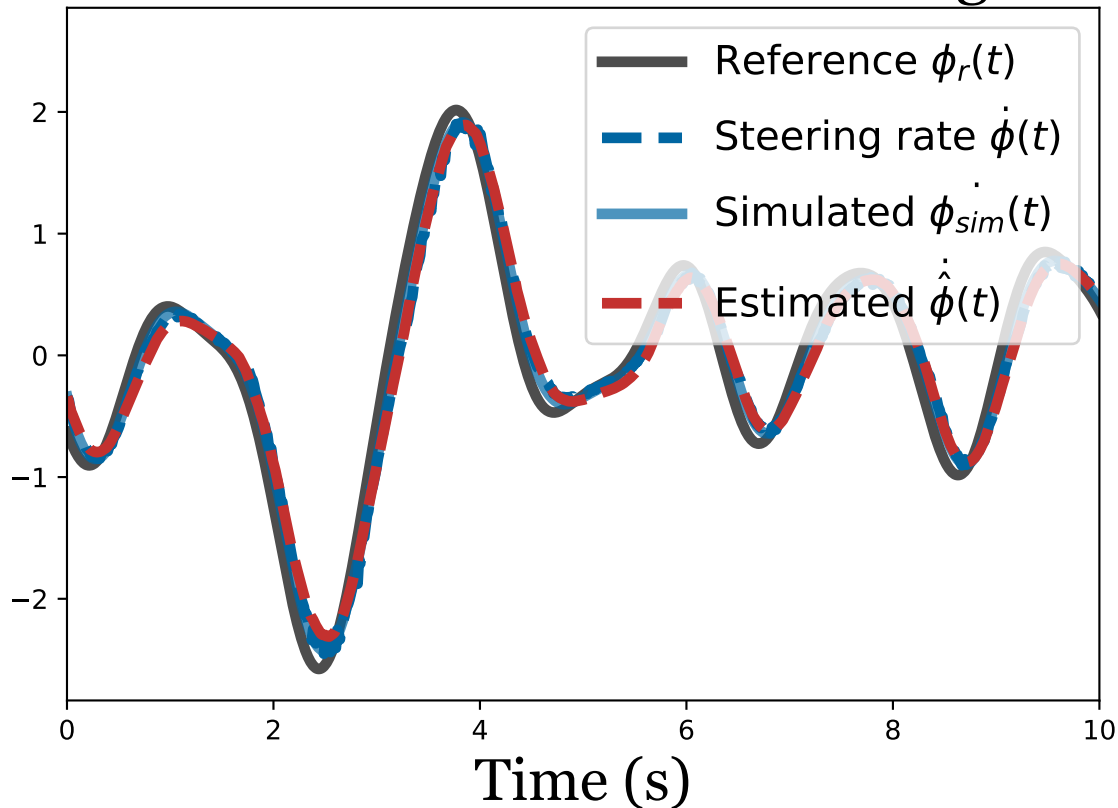
# Measured and estimated steering angle



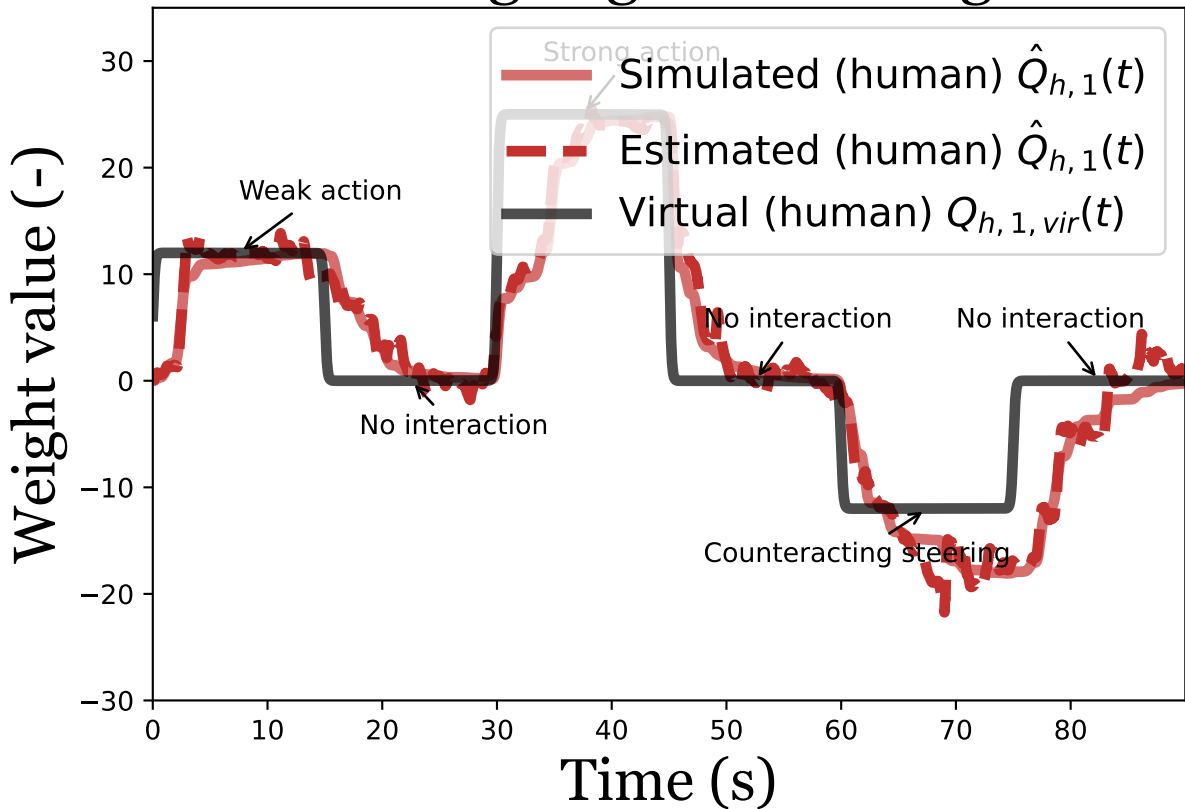


# Measured and estimated steering rate

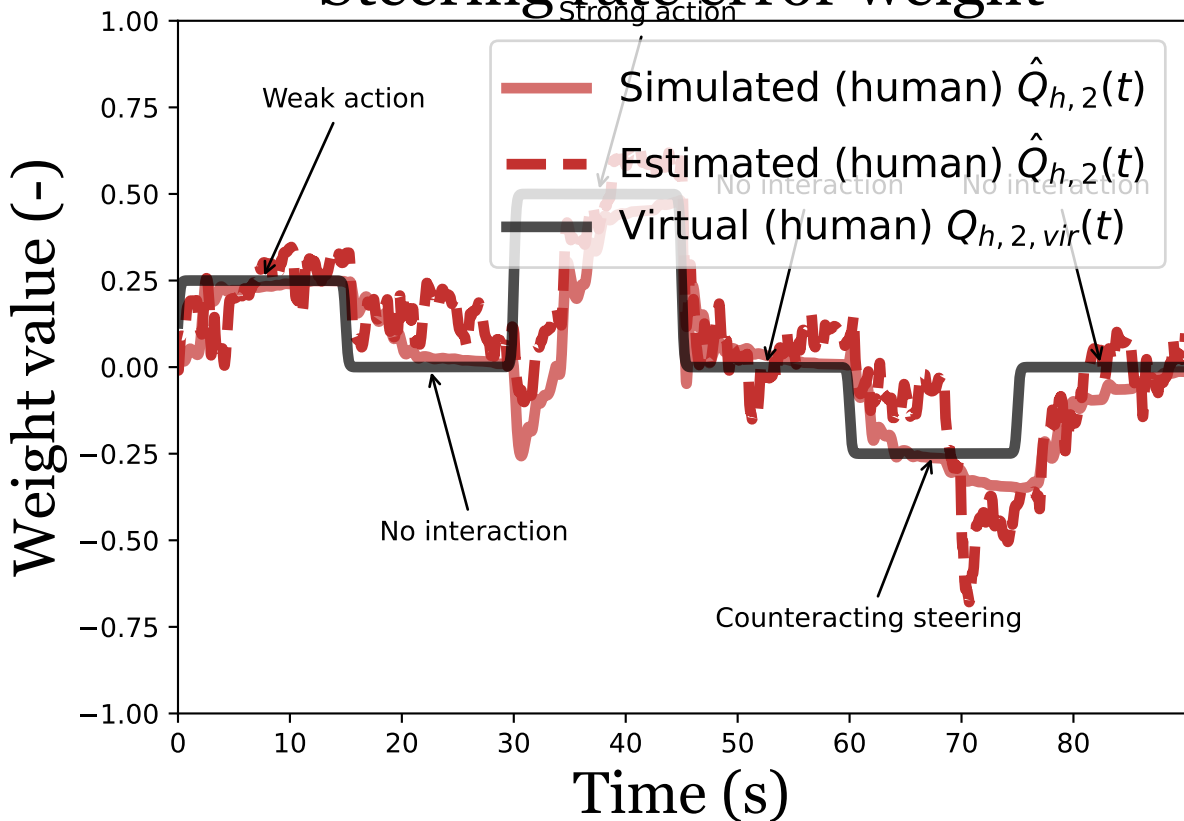
Steering angle (rad)



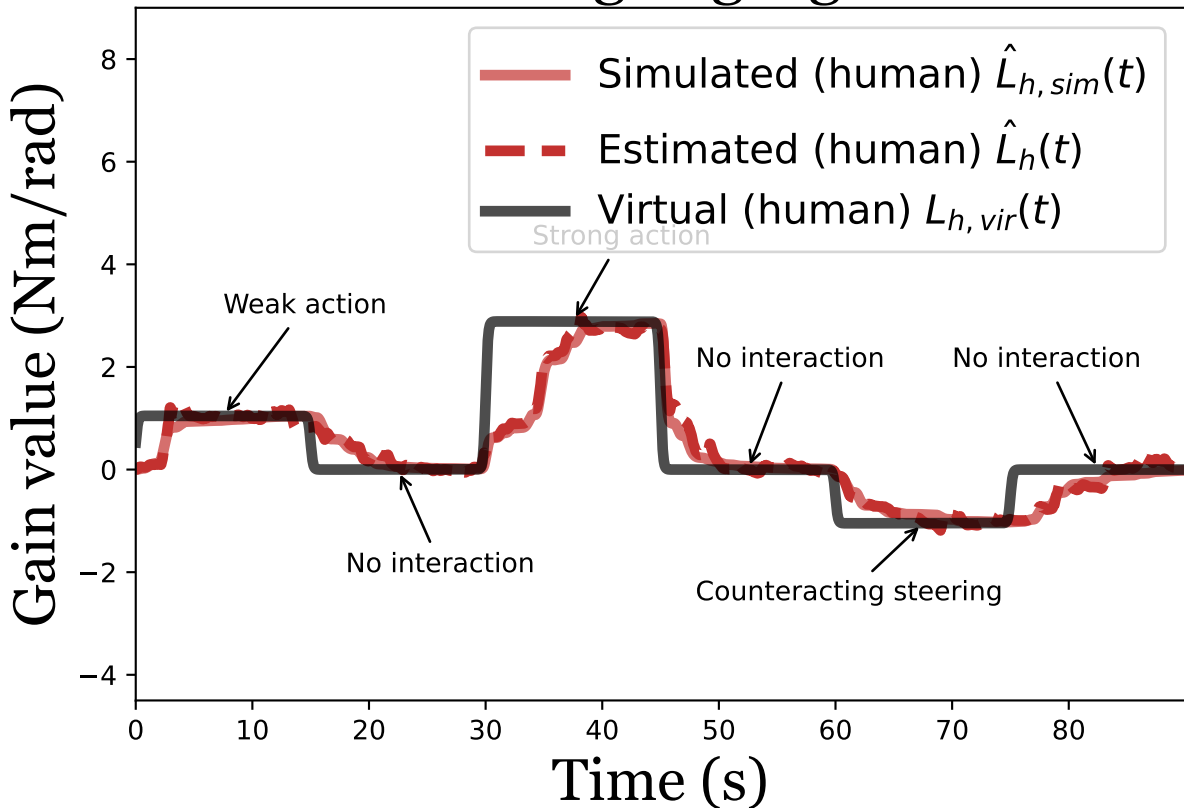
# Steering angle error weight



# Steering rate error weight



# Steering angle gain





# Steering rate gain

