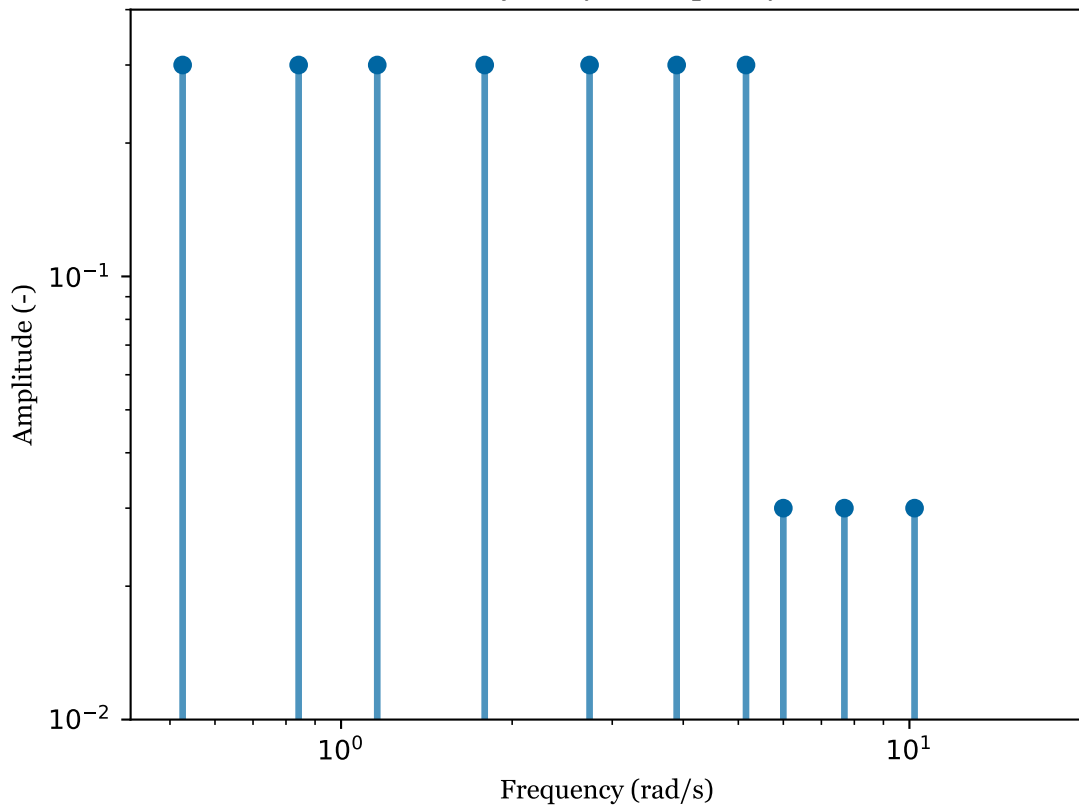
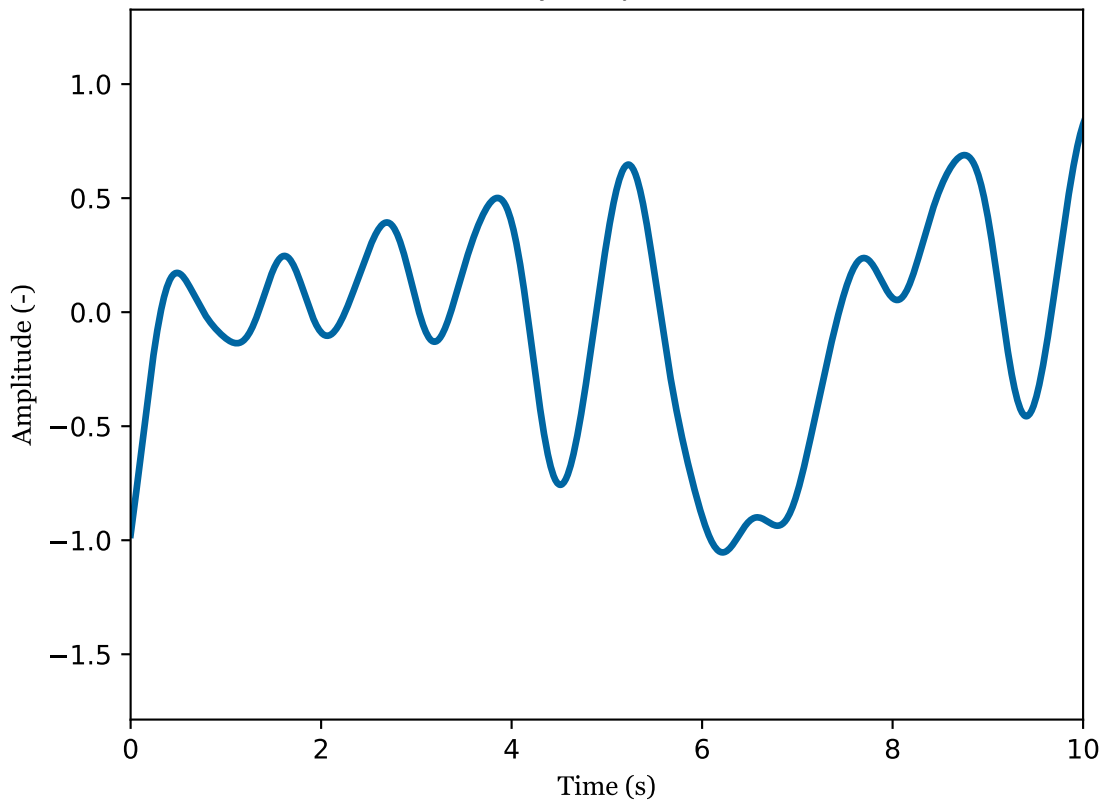


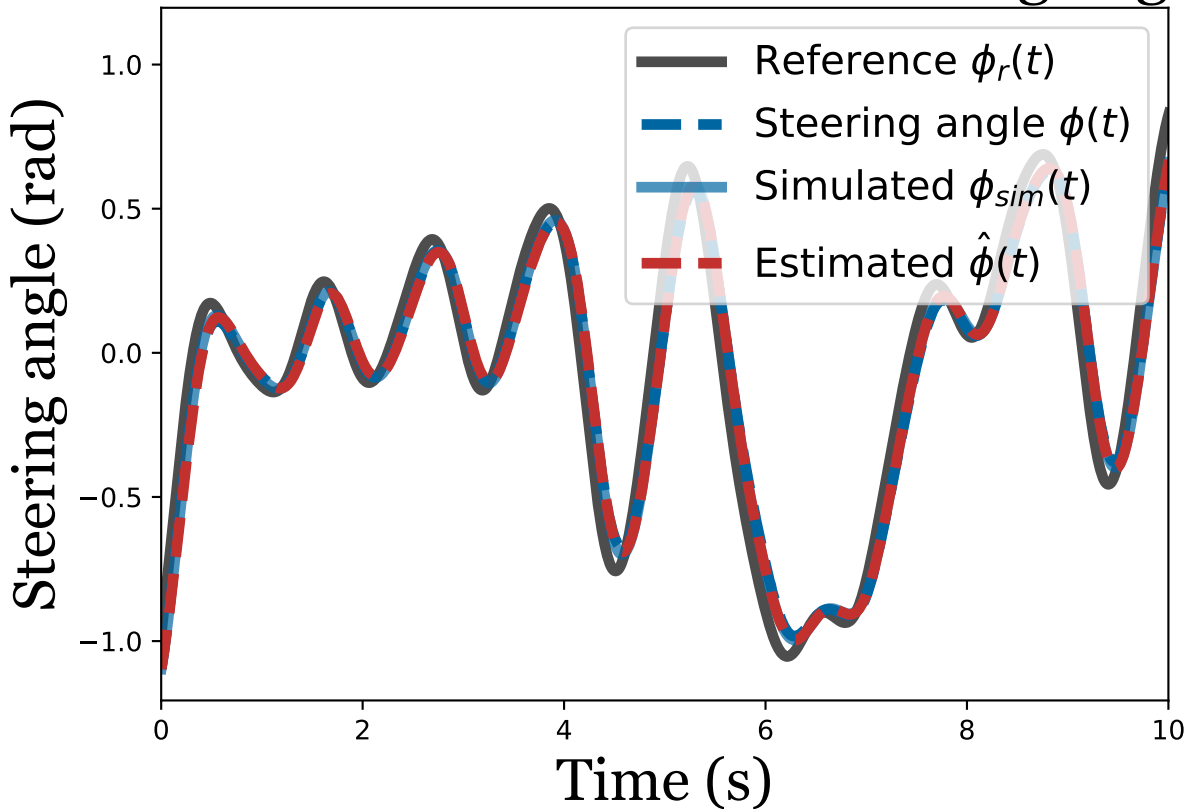
Reference trajectory in frequency domain

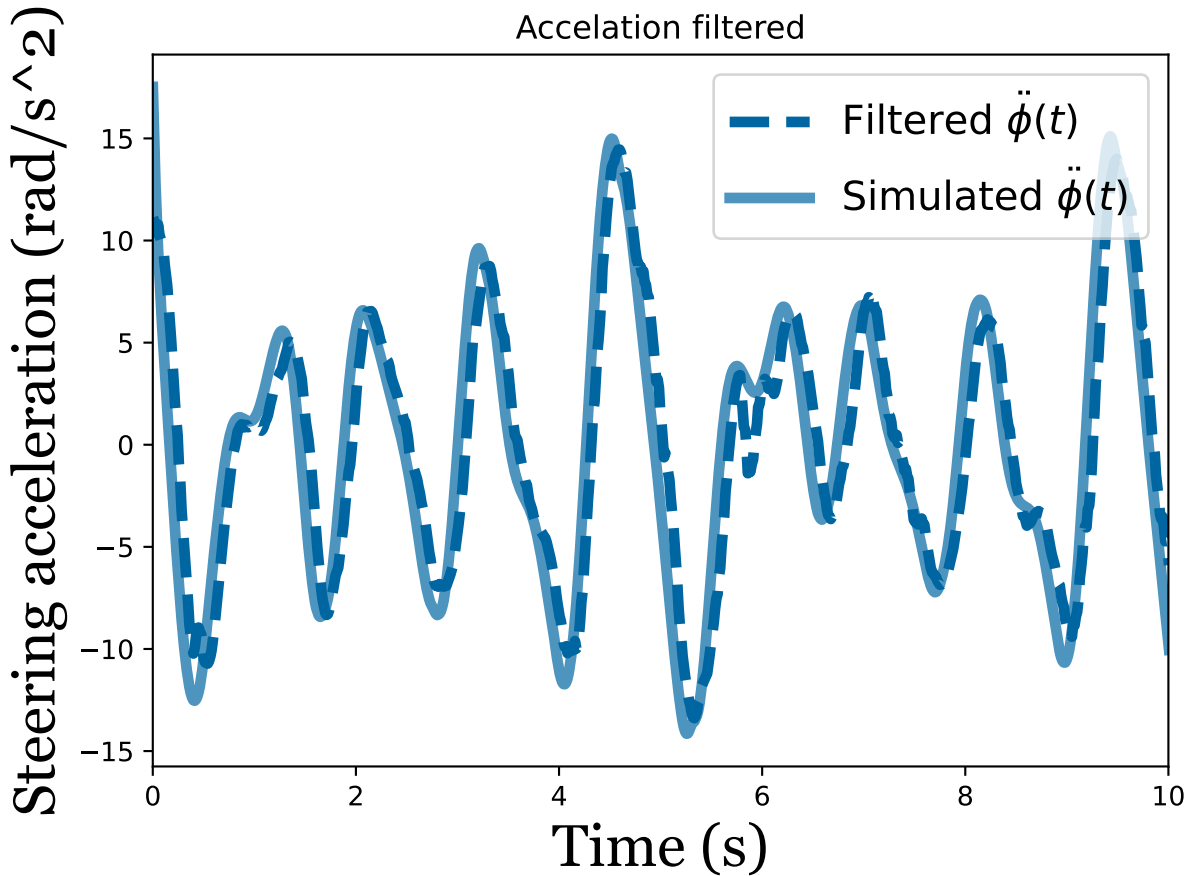


Reference trajectory in time domain

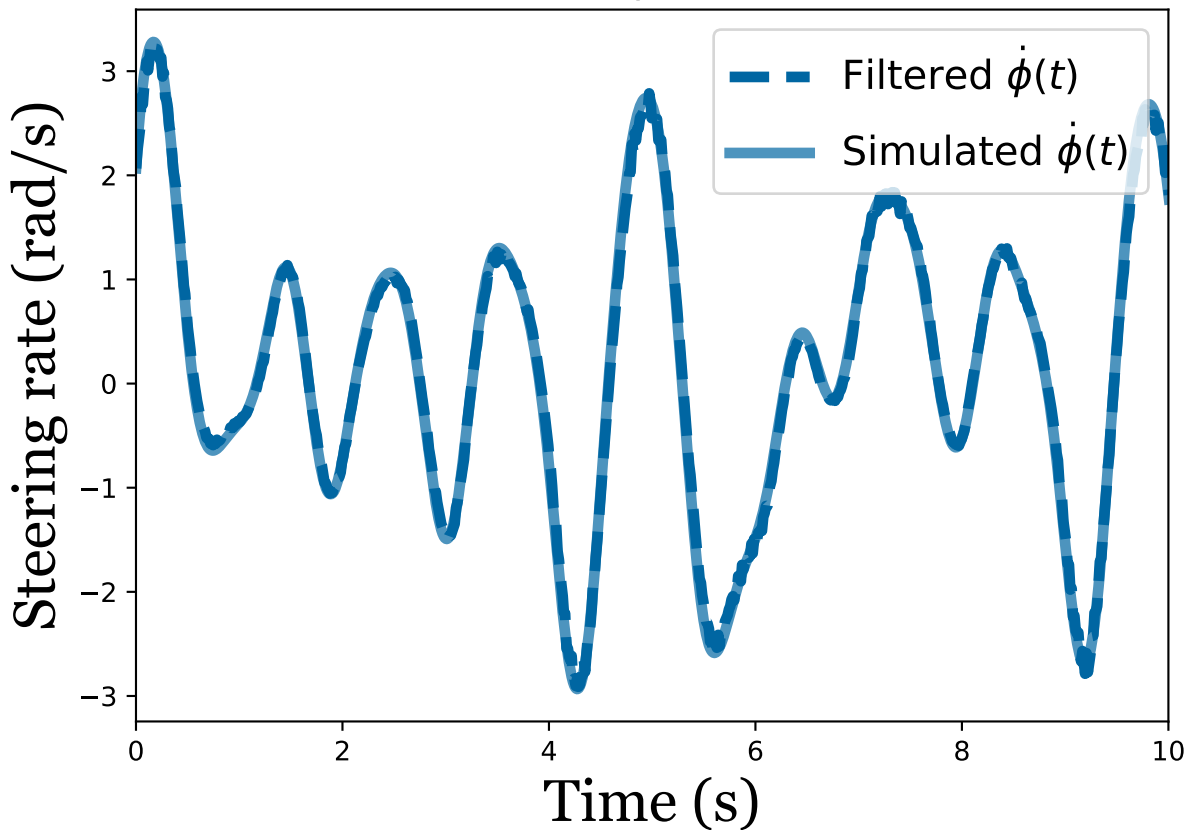


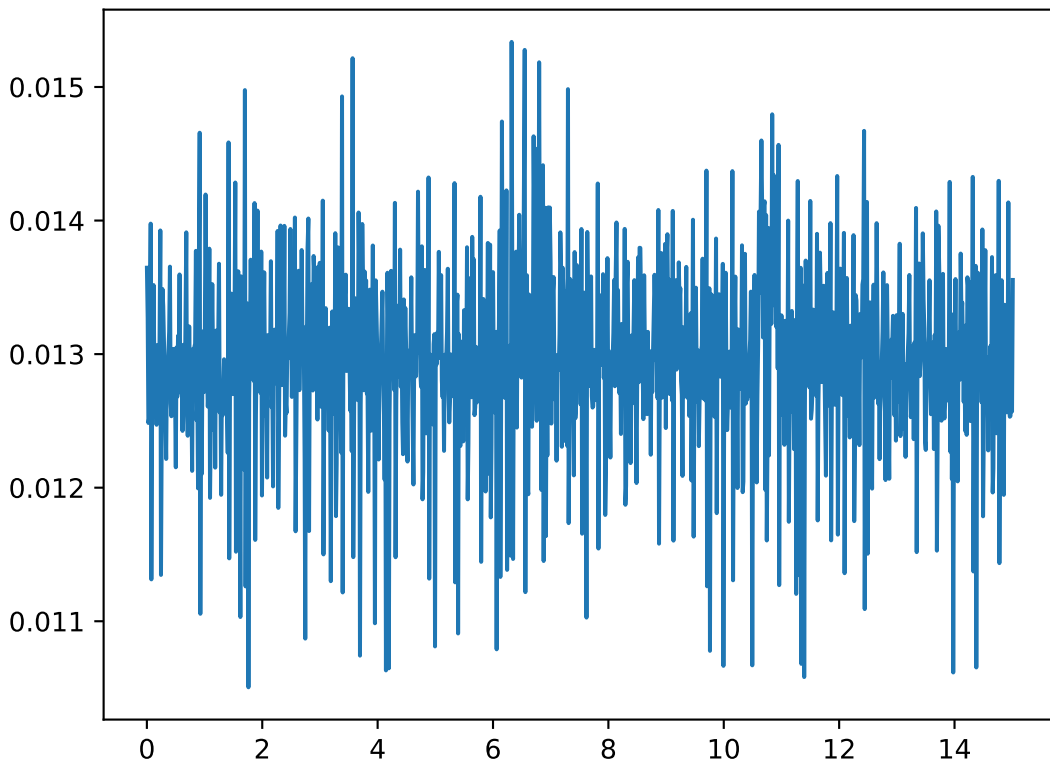
Measured and estimated steering angle



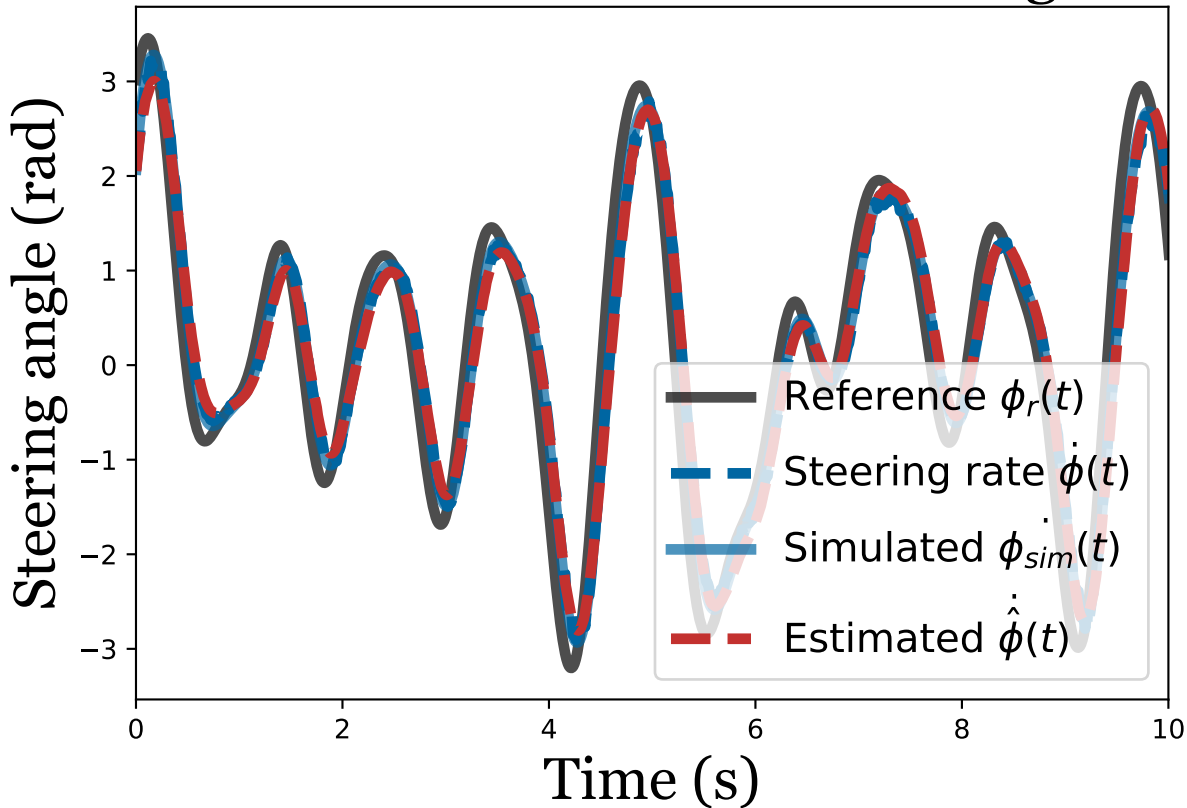


velocity filtered

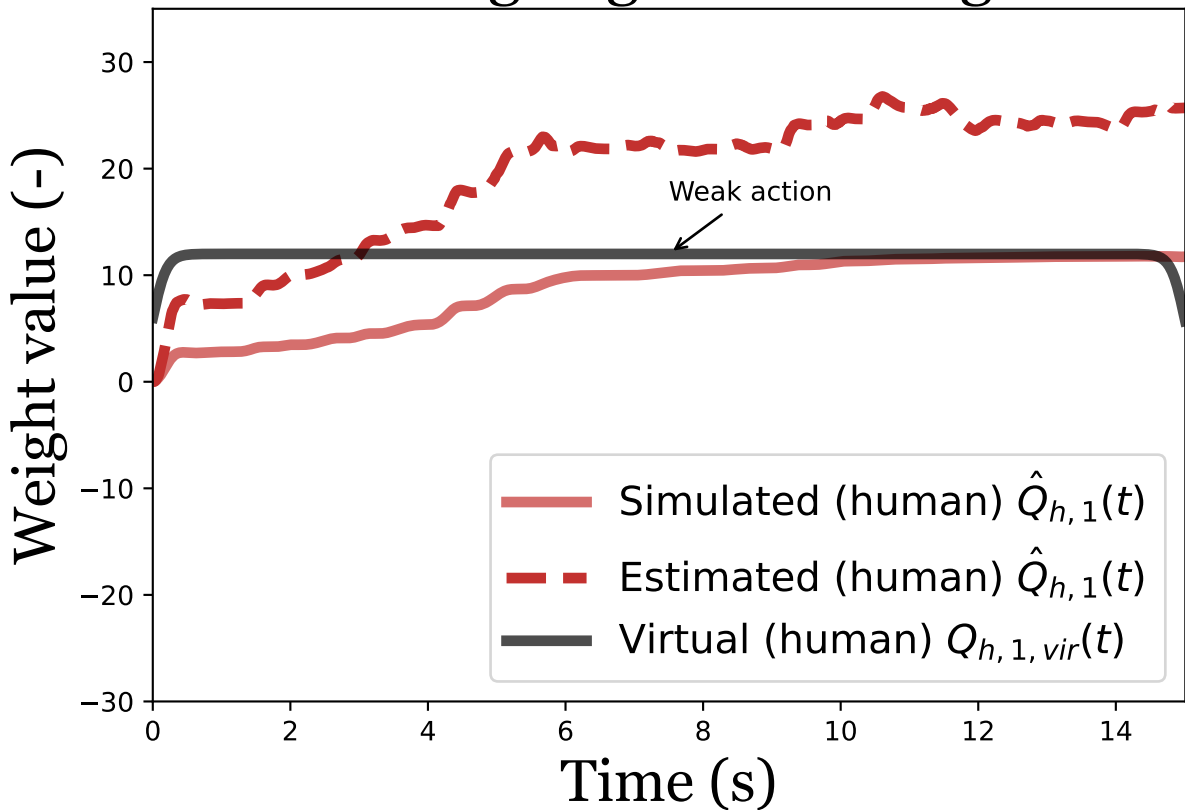




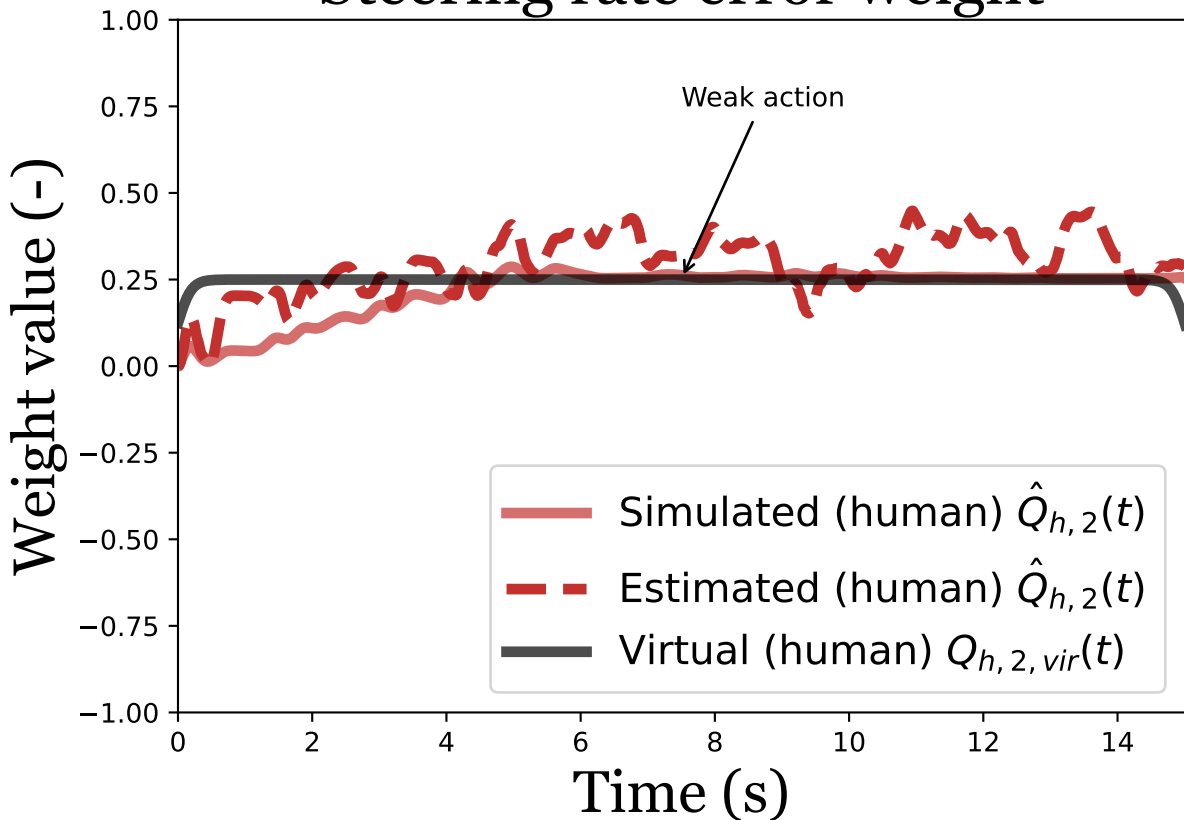
Measured and estimated steering rate



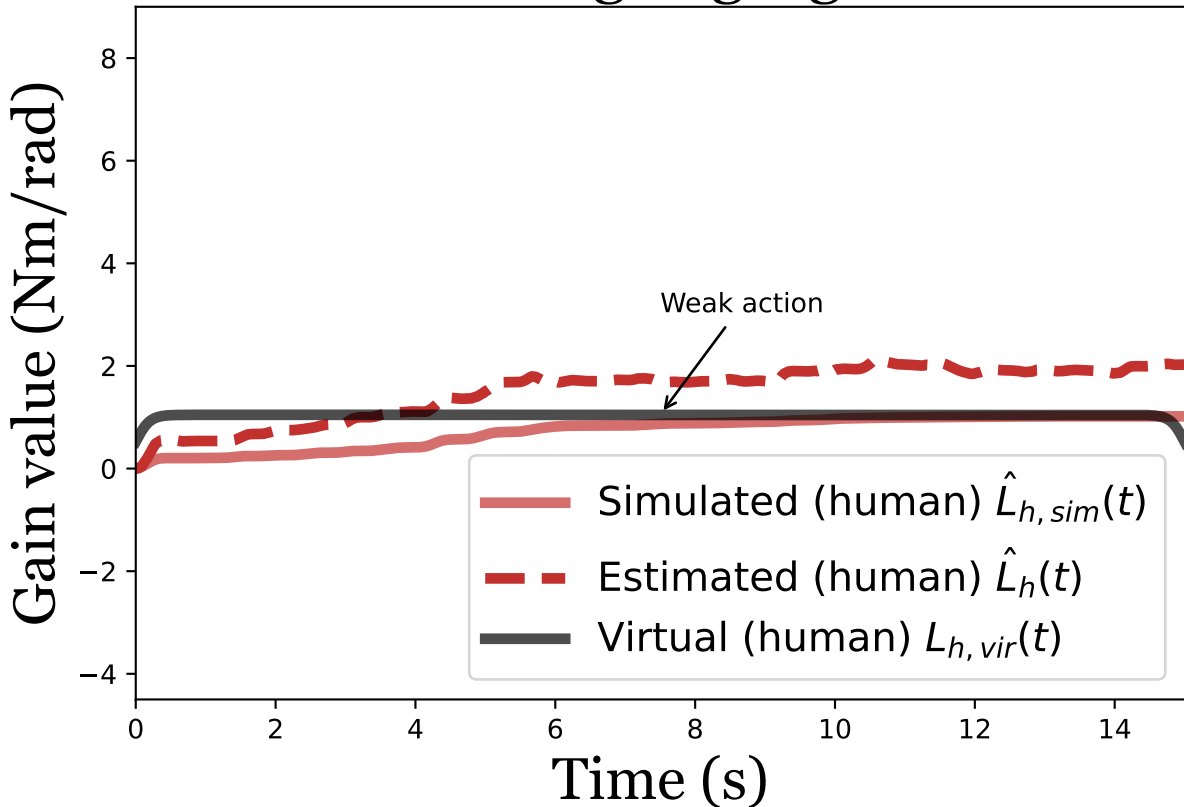
Steering angle error weight



Steering rate error weight



Steering angle gain



Steering rate gain

