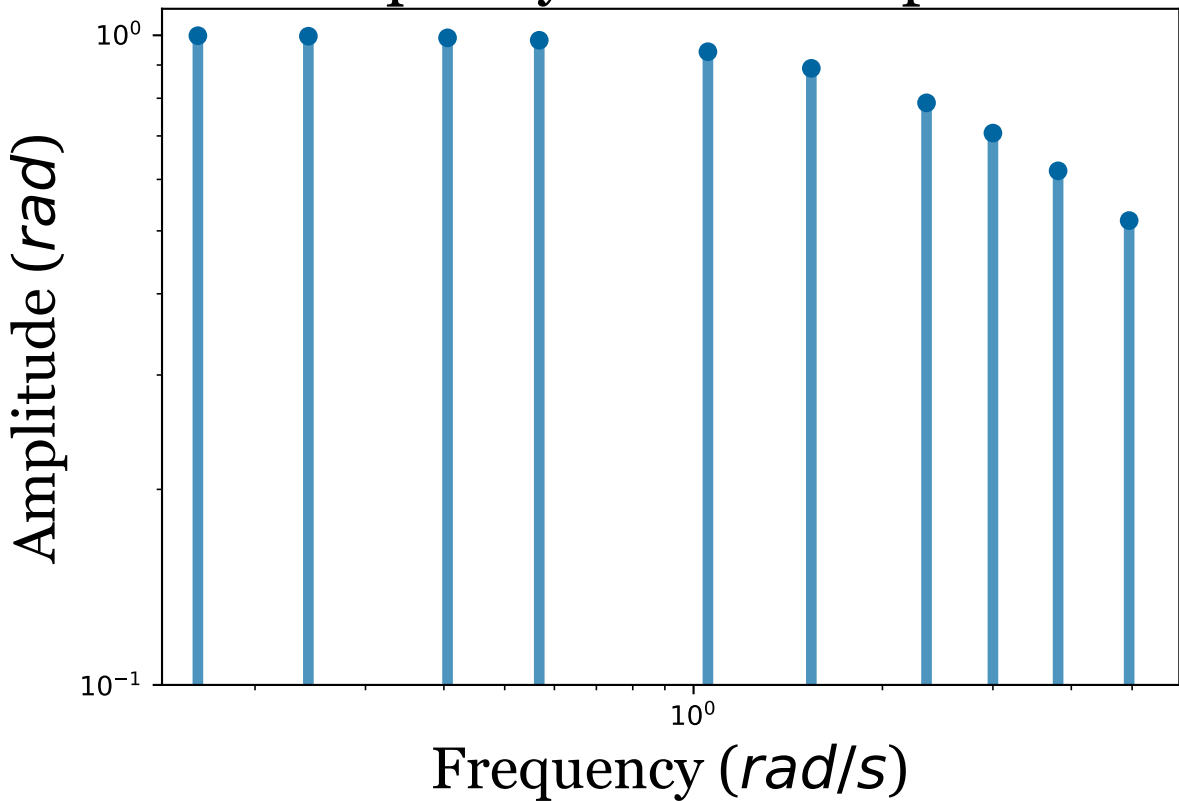
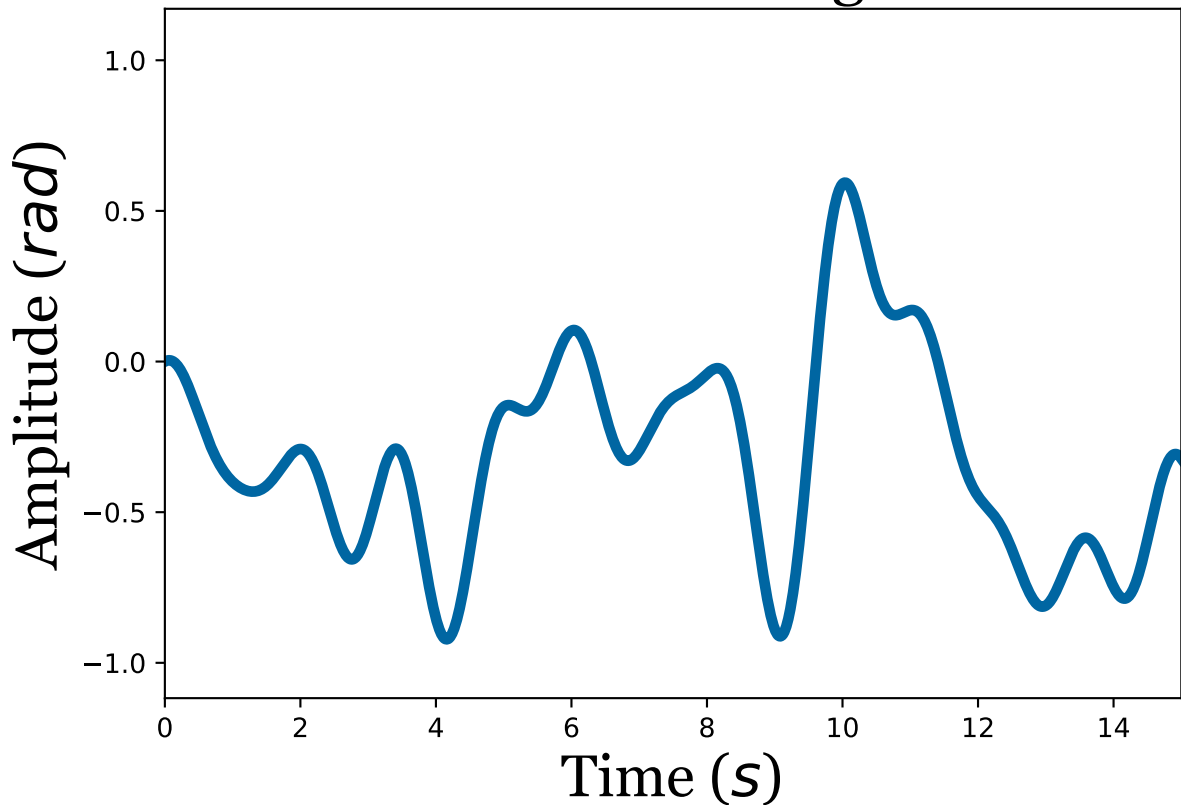


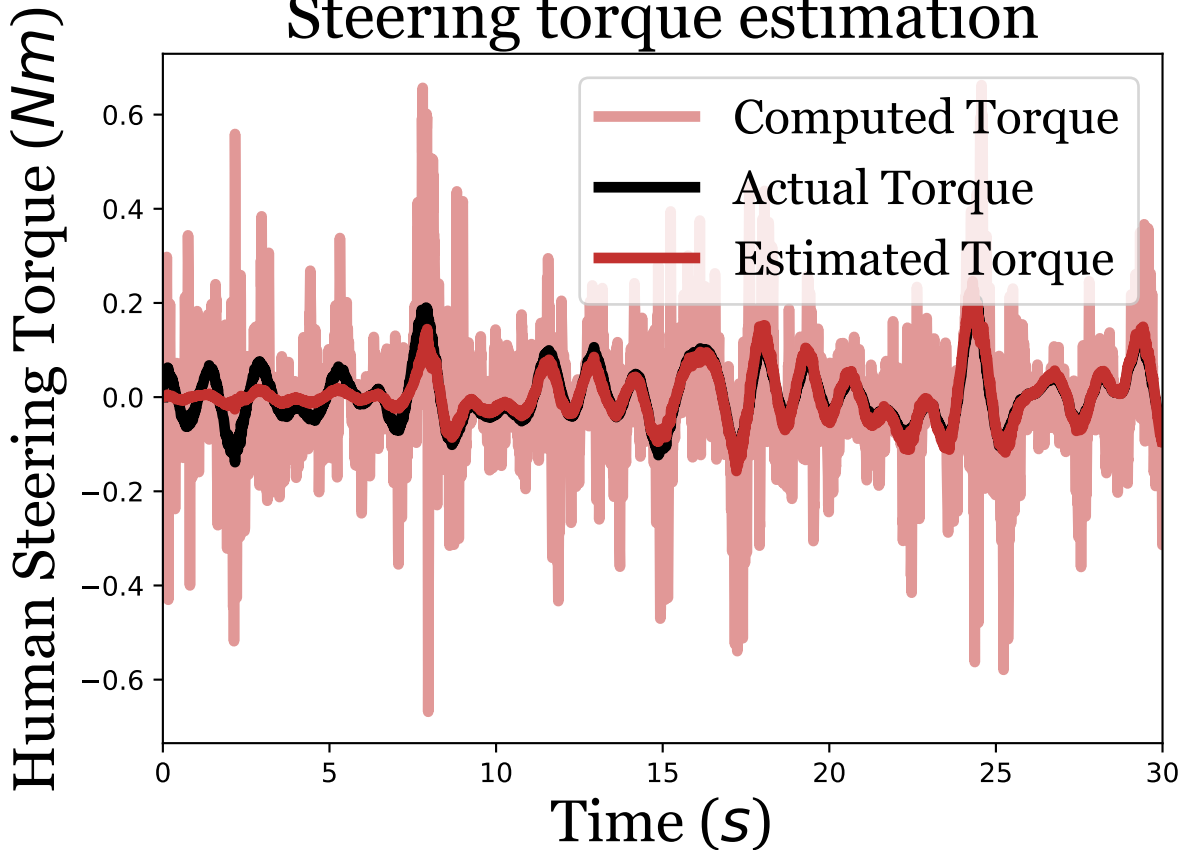
Frequency domain response



Time domain signal

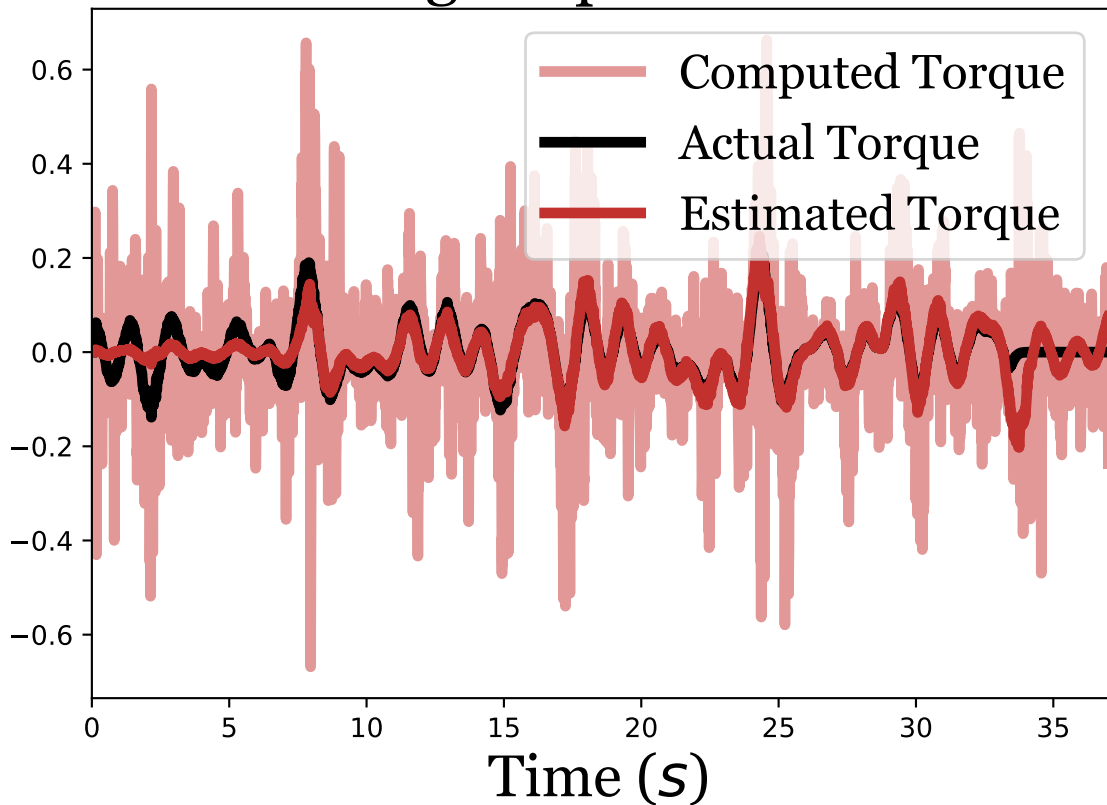


Steering torque estimation

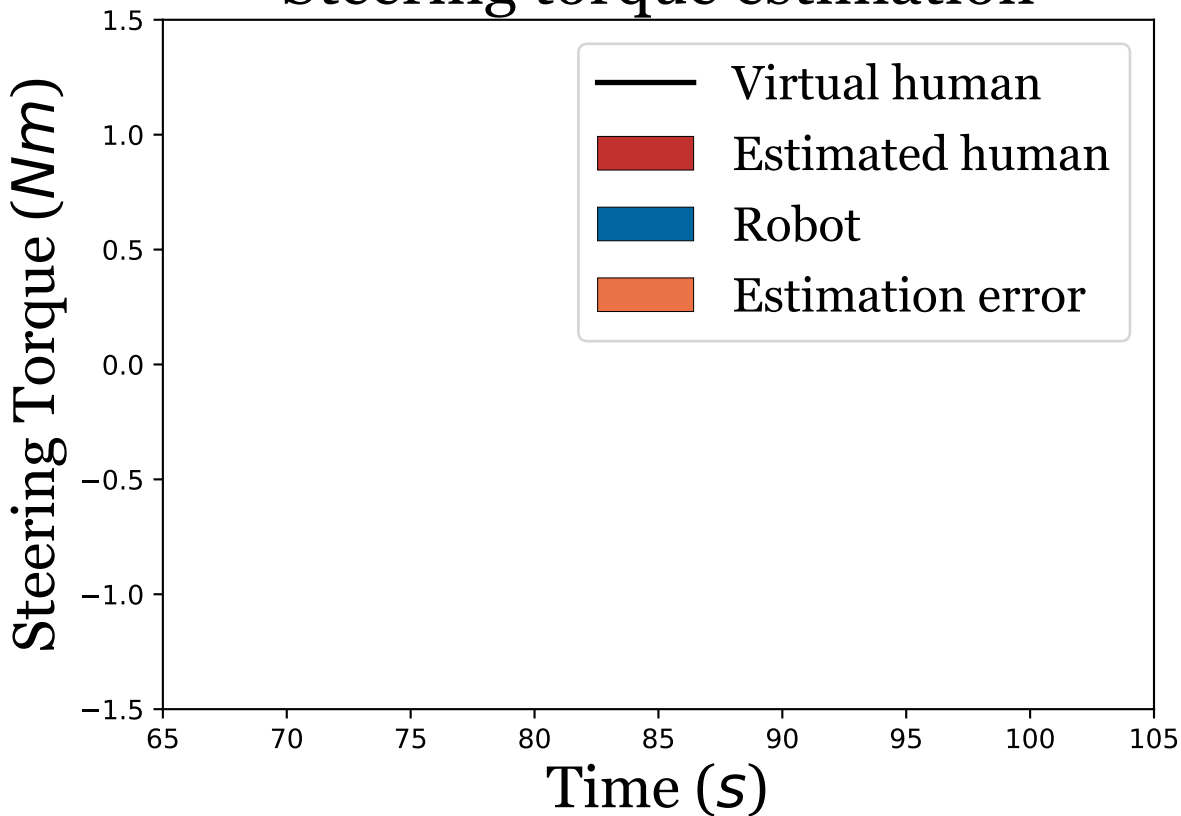


Steering torque estimation

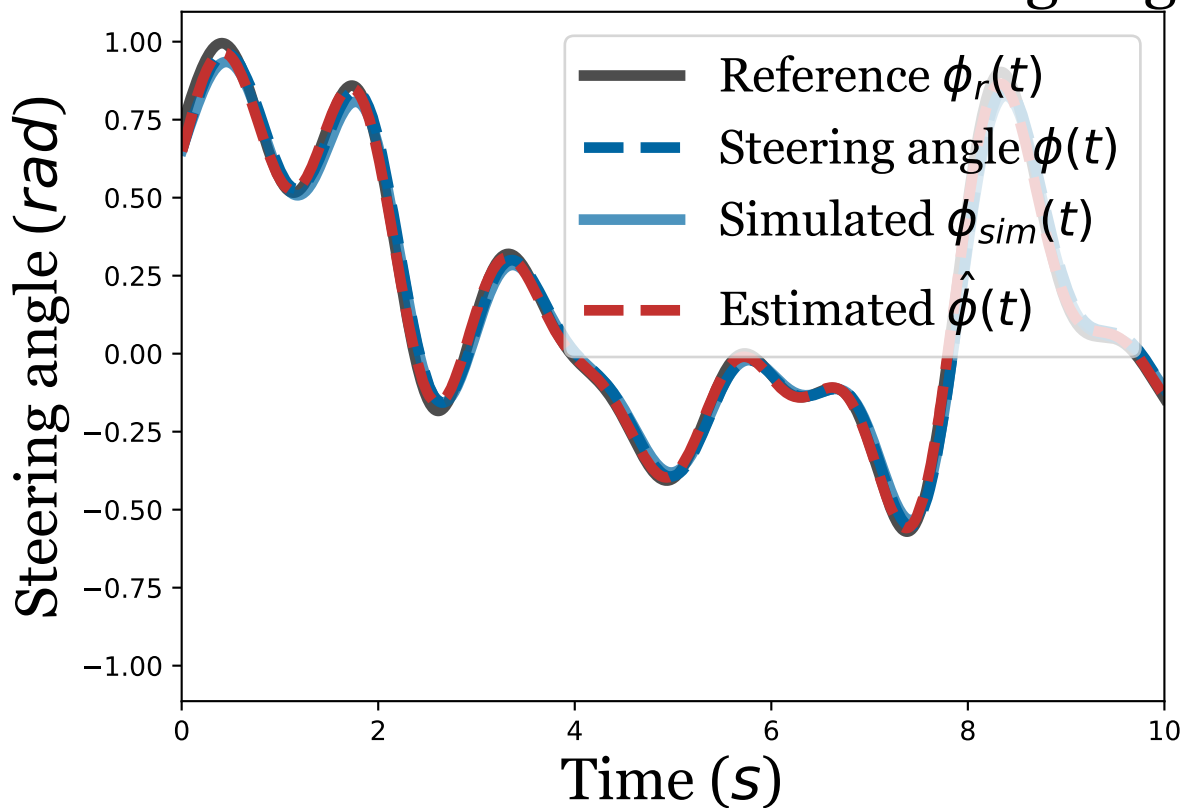
Human Steering Torque (Nm)



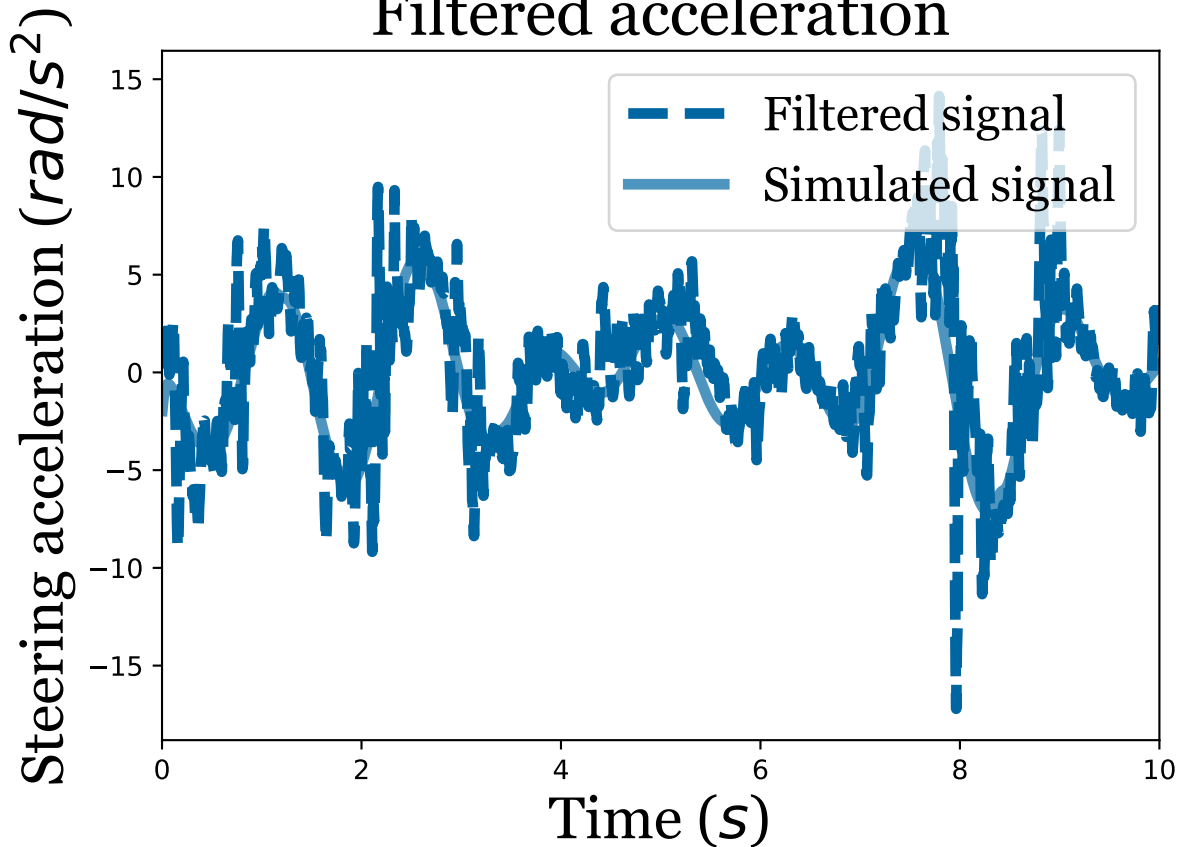
Steering torque estimation



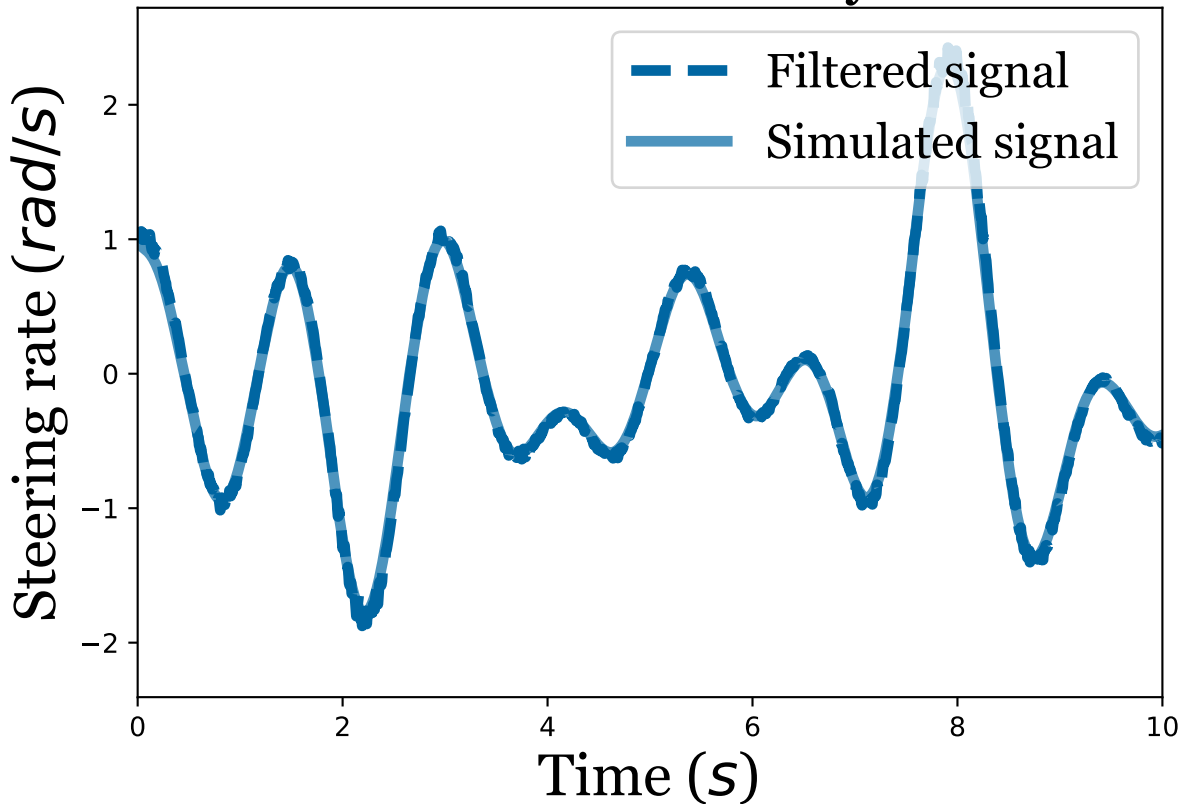
Measured and estimated steering angle



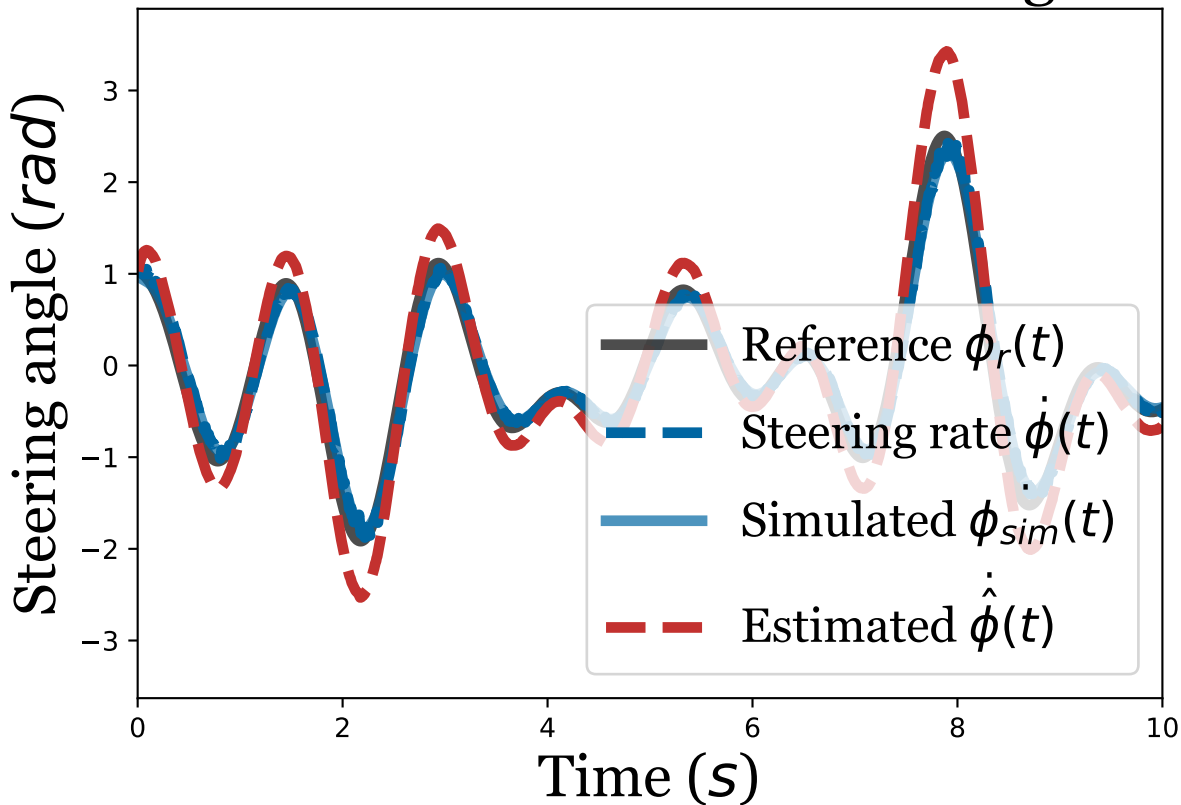
Filtered acceleration



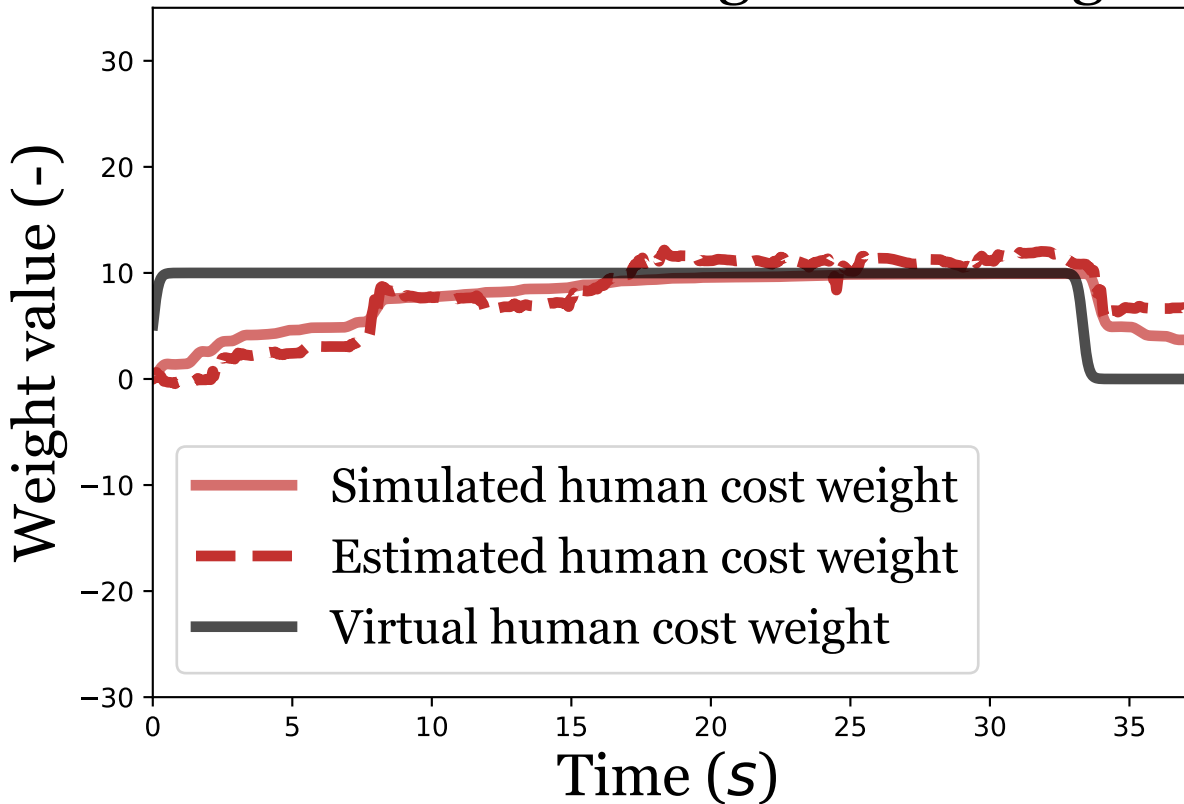
Filtered velocity



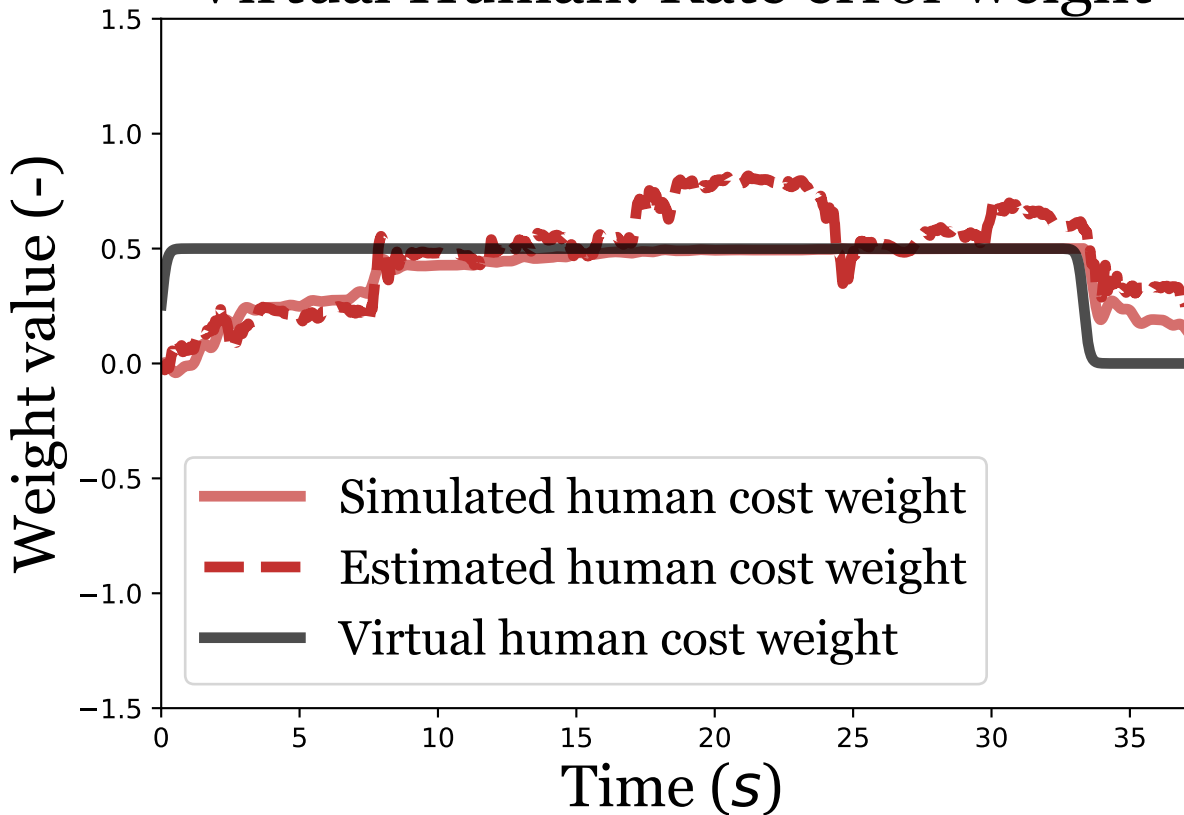
Measured and estimated steering rate



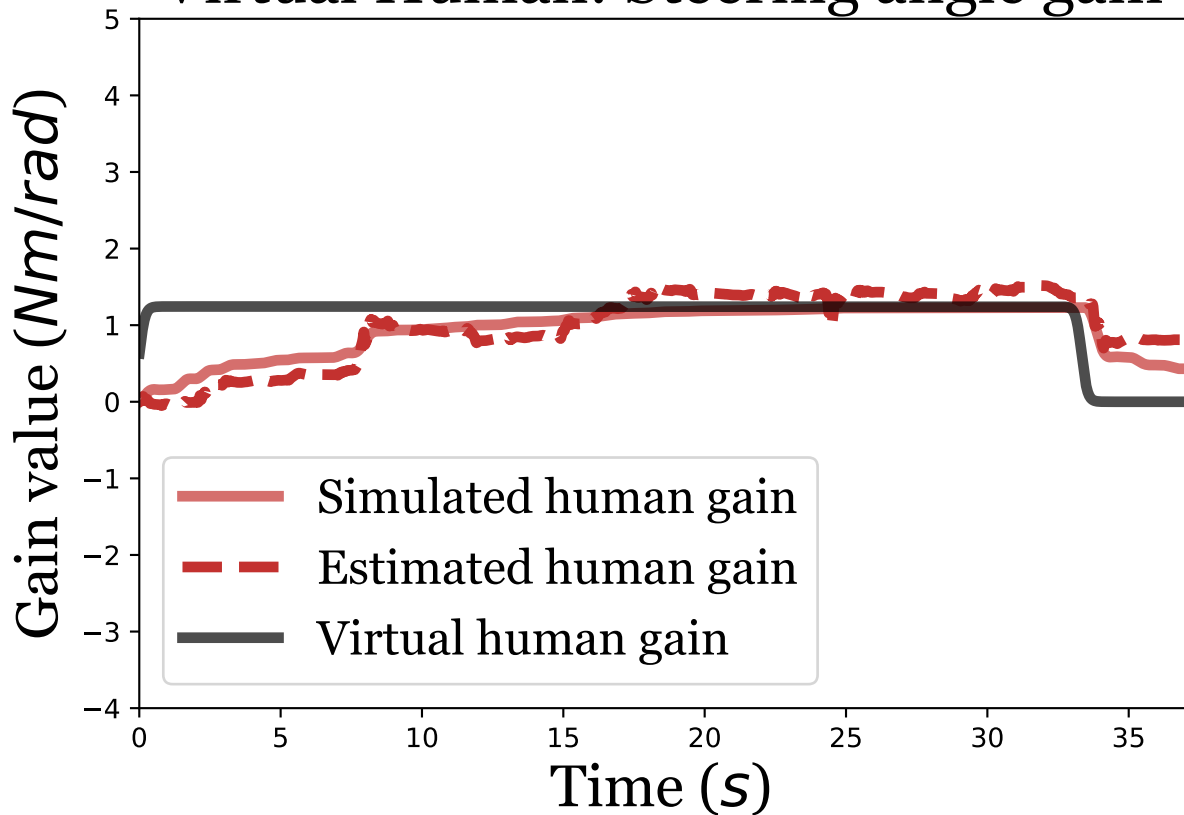
Virtual Human: Angle error weight



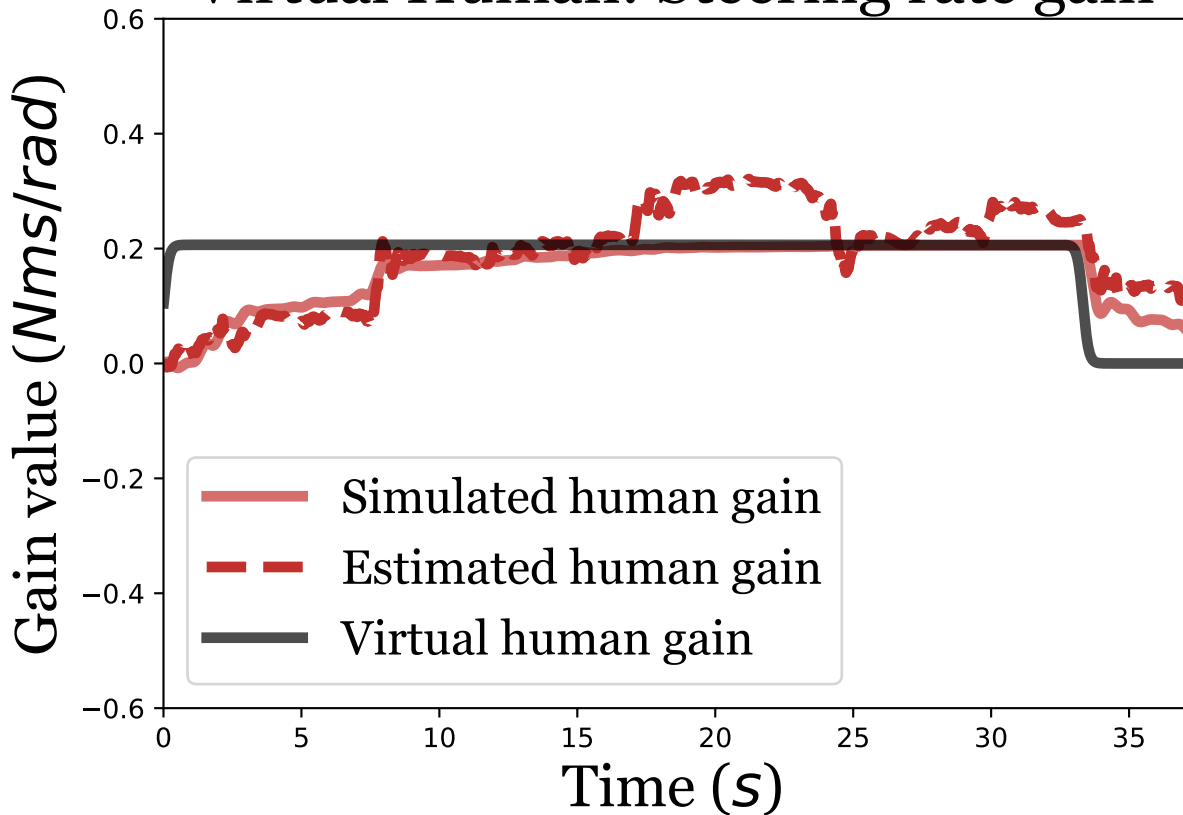
Virtual Human: Rate error weight



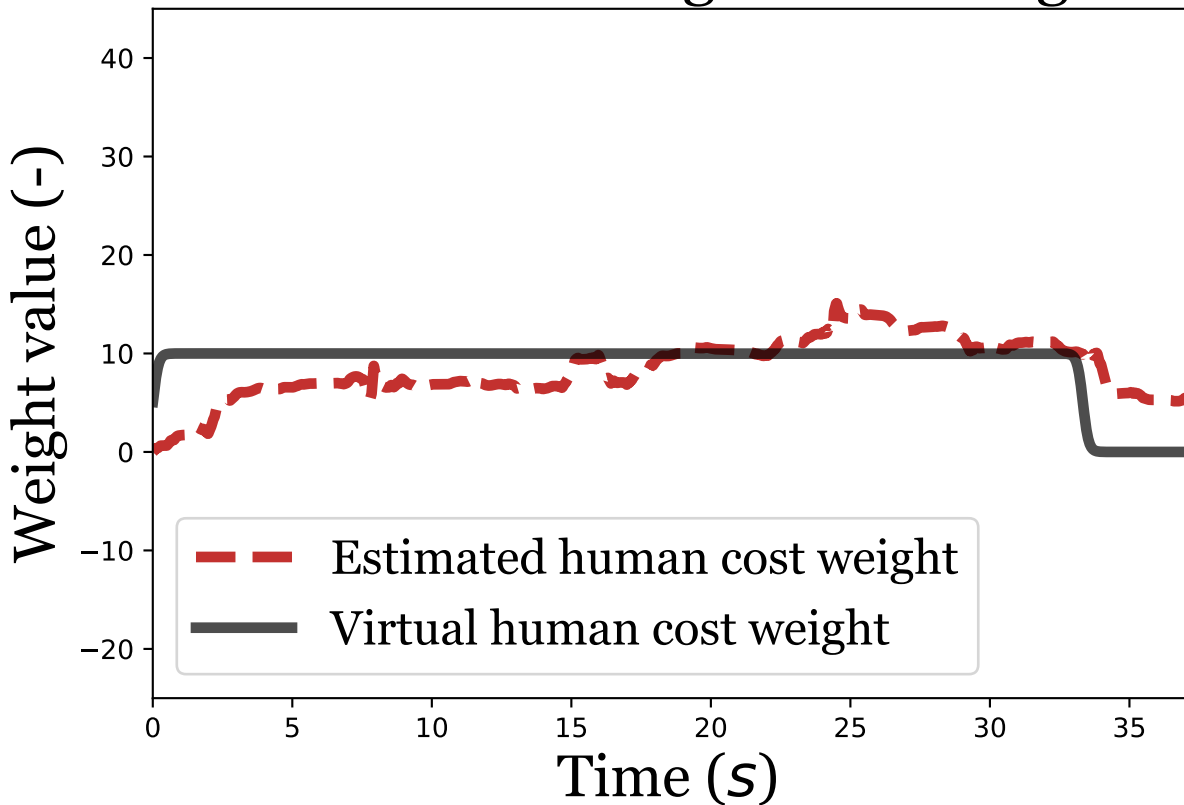
Virtual Human: Steering angle gain



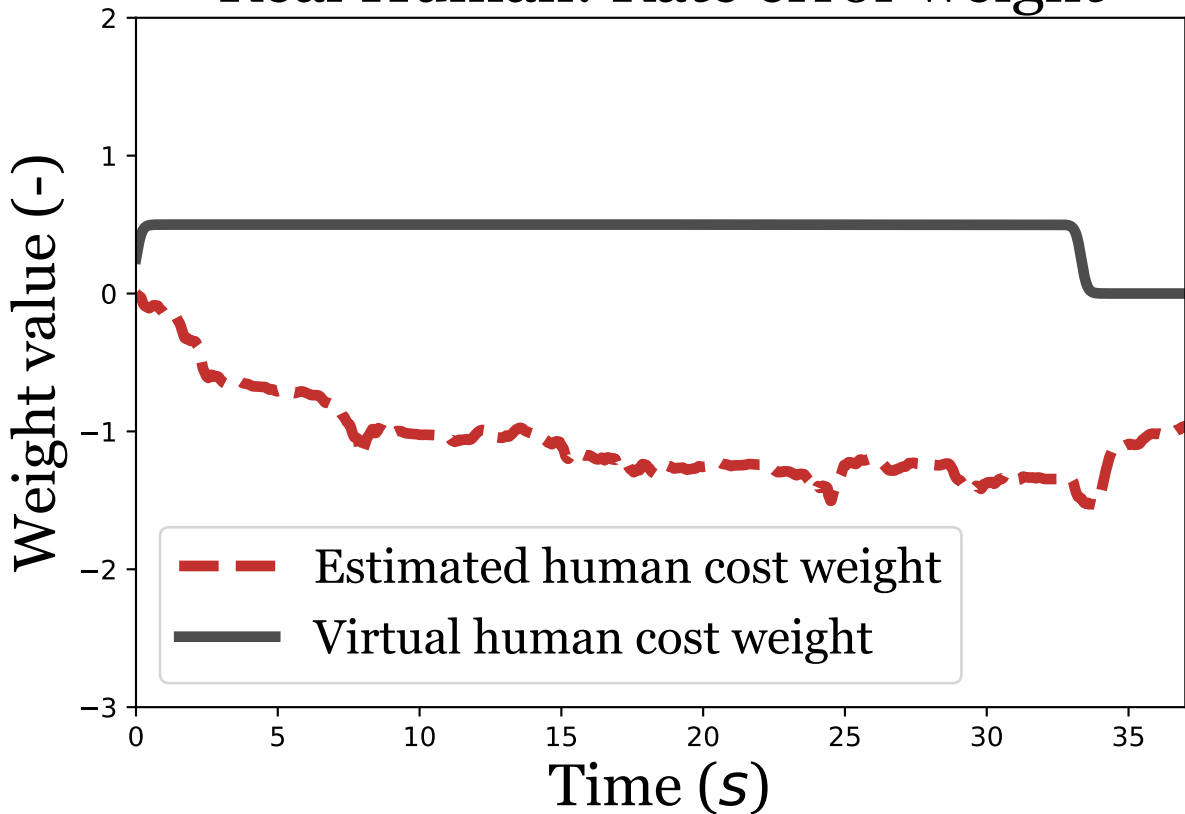
Virtual Human: Steering rate gain



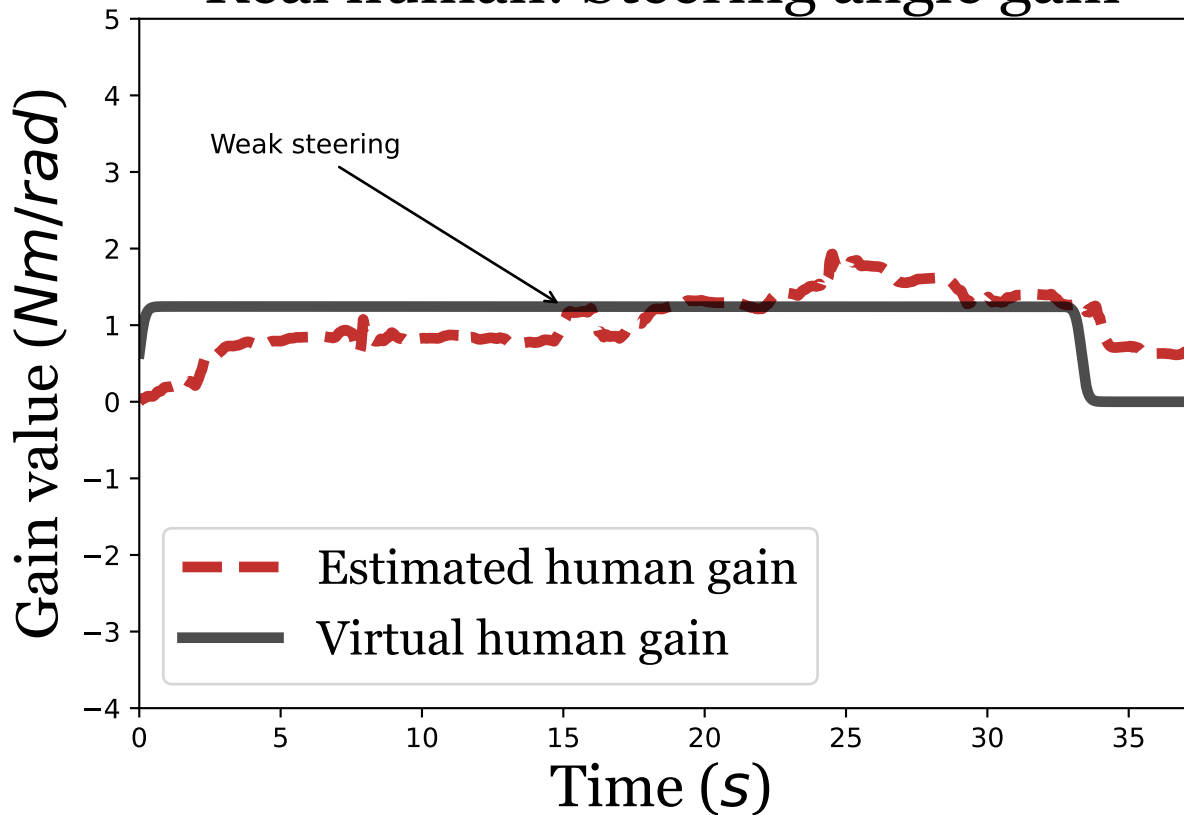
Real Human: Angle error weight



Real Human: Rate error weight

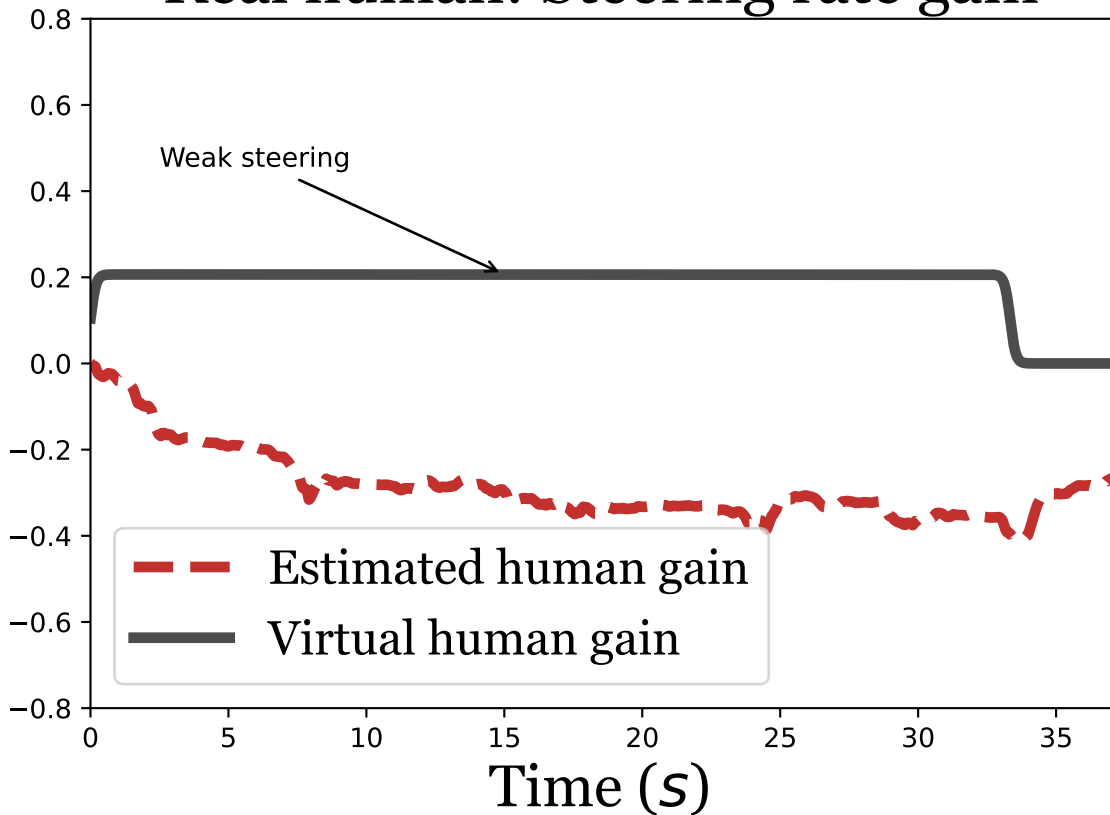


Real human: Steering angle gain

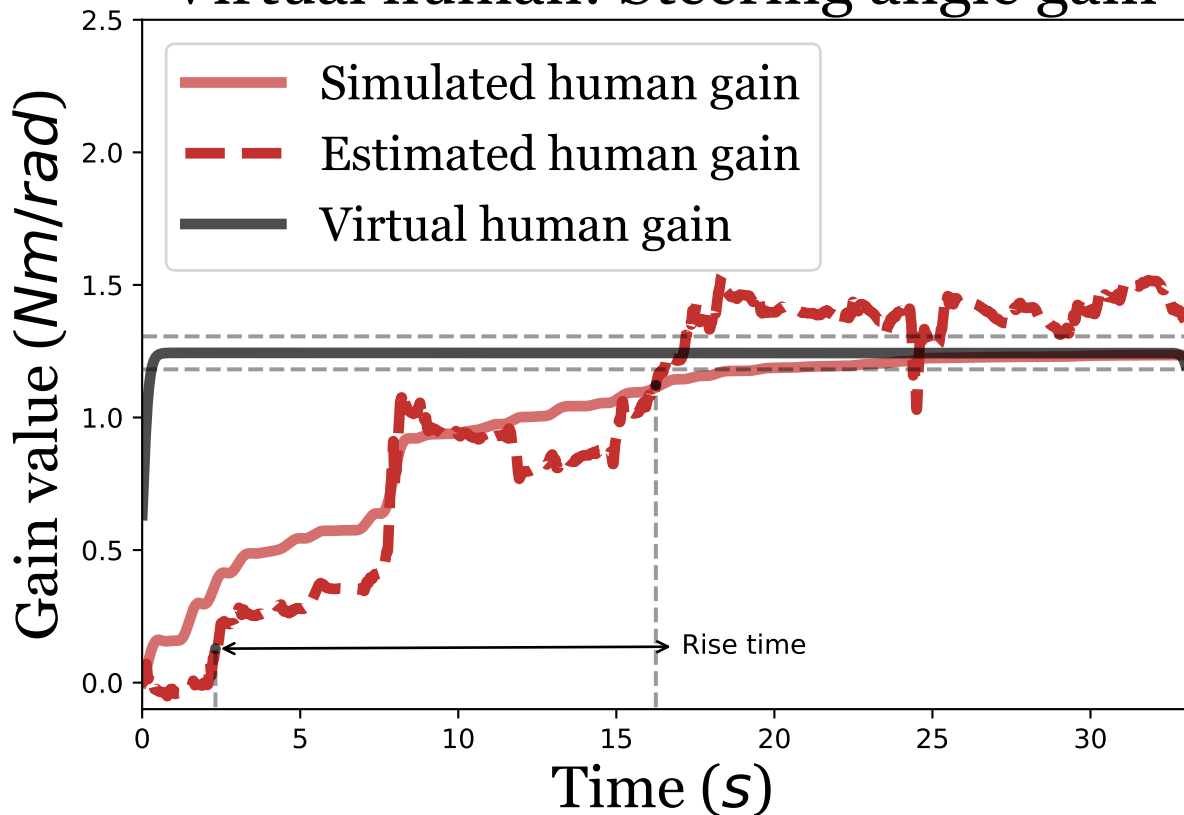


Real human: Steering rate gain

Gain value (Nms/rad)



Virtual human: Steering angle gain



Virtual human: Steering rate gain

