09-Linear-Independence

January 6, 2017

```
In [2]: from latools import *
     from sympy import *
     init_printing(use_latex=True)
```

1 Linear Independence

1.1 First strategy:

To determine if the vectors $v_1, v_2, ..., v_k$ are linearly independent we proceed as follows:

• Solve the linear system:

$$c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + \dots + c_k\mathbf{v}_k = \mathbf{0}$$

• If the only solution of the system is $c_1 = c_2 = \cdots c_k = 0$, the vectors are linearly independent. Otherwise, they are linearly dependent.

1.2 Example 1

Determine if the vectors:

$$\mathbf{v}_1 = \begin{bmatrix} 1 \\ -2 \\ 3 \\ 3 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 0 \\ 2 \\ -4 \\ 1 \end{bmatrix}, \quad \mathbf{v}_3 = \begin{bmatrix} 1 \\ 1 \\ -3 \\ 2 \end{bmatrix}$$

1.2.1 Solution:

We write the system:

$$c_{1} \begin{bmatrix} 1 \\ -2 \\ 3 \\ 3 \end{bmatrix} + c_{2} \begin{bmatrix} 0 \\ 2 \\ -4 \\ 1 \end{bmatrix} + c_{3} \begin{bmatrix} 1 \\ 1 \\ -3 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

Equivalently:

$$\begin{bmatrix} 1 & 0 & 1 \\ -2 & 2 & 1 \\ 3 & -4 & -3 \\ 3 & 1 & 2 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

Since this is a homogeneous system, we don't need to keep track of the right-hand side vector, so we work with the matrix *A* itself, instead of the augmented matrix:

Α

Out[3]:

$$\begin{bmatrix} 1 & 0 & 1 \\ -2 & 2 & 1 \\ 3 & -4 & -3 \\ 3 & 1 & 2 \end{bmatrix}$$

We now use the function $reduced_row_echelon_form()$ to find the RREF matrix equivalent to A:

Out [4]:

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

The three columns in this matrix correspond to the variables c_1 , c_2 and c_3 (remember, this is *not* the augmented matrix). So, this matrix corresponds to the solution:

$$c_1 = 0$$
$$c_2 = 0$$

$$c_3 = 0$$

Notice that the last row consists only of zeros, and can be ignored. We conclude that, the only solution to:

$$c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + c_3\mathbf{v}_3 = \mathbf{0}$$

is

$$c_1 = 0, \quad c_2 = 0, \quad c_3 = 0$$

It follows that the vectors are *linearly independent*.

1.3 Example 2

Determine if the vectors:

$$\mathbf{v}_1 = \begin{bmatrix} -1 \\ 2 \\ 0 \\ 3 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 0 \\ 1 \\ 2 \\ 4 \end{bmatrix}, \quad \mathbf{v}_3 = \begin{bmatrix} 1 \\ 2 \\ 1 \\ 3 \end{bmatrix}, \quad \mathbf{v}_4 = \begin{bmatrix} 2 \\ 9 \\ -2 \\ -6 \end{bmatrix}$$

are linearly independent.

1.3.1 Solution:

We need to solve the linear system:

$$c_{1} \begin{bmatrix} -1\\2\\0\\3 \end{bmatrix} + c_{2} \begin{bmatrix} 0\\1\\2\\4 \end{bmatrix} + c_{3} \begin{bmatrix} 1\\2\\1\\3 \end{bmatrix} + c_{4} \begin{bmatrix} 2\\9\\-2\\-6 \end{bmatrix} = \begin{bmatrix} 0\\0\\0\\0 \end{bmatrix}$$

In matrix form:

$$\begin{bmatrix} -1 & 0 & 1 & 2 \\ 2 & 1 & 2 & 9 \\ 0 & 2 & 1 & -2 \\ 3 & 4 & 3 & 6 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \\ c_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

The matrix of the system is (ignoring the right-hand side, since the system is homogeneous):

Out [5]:

$$\begin{bmatrix} -1 & 0 & 1 & 2 \\ 2 & 1 & 2 & 9 \\ 0 & 2 & 1 & -2 \\ 3 & 4 & 3 & 6 \end{bmatrix}$$

The RREF equivalent matrix is:

Out [6]:

$$\begin{bmatrix} 1 & 0 & 0 & 2 \\ 0 & 1 & 0 & -3 \\ 0 & 0 & 1 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Thus, the original system is equivalent to:

$$c_1 + 2c_4 = 0$$
$$c_2 - 3c_4 = 0$$
$$c_3 + 4c_4 = 0$$

Since there are free variables, this system has infinitely many solutions. For example, we can let $c_4 = 1$, so that $c_1 = -2$, $c_2 = 3$ and $c_3 = -4$, and we get the relation:

$$-2\mathbf{v}_1 + 3\mathbf{v}_2 - 4\mathbf{v}_3 + \mathbf{v}_4 = \mathbf{0}$$

We conclude that the vectors are *linearly dependent*.

Notice that, from the formula above, we can express any of the vectors that appears with a nonzero coefficient in terms of the other. For example:

$$-4\mathbf{v}_3 = 2\mathbf{v}_1 - 3\mathbf{v}_2 - \mathbf{v}_4$$

Thus:

$$\mathbf{v}_3 = -\frac{1}{2}\mathbf{v}_1 - \frac{3}{4}\mathbf{v}_2 + \frac{1}{4}\mathbf{v}_4$$

So, if we remove the vector \mathbf{v}_3 from the set, we are removing a "dependency", and we may ask if the set of remaining vectors:

$$\mathbf{v}_1 = \begin{bmatrix} -1\\2\\0\\3 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 0\\1\\2\\4 \end{bmatrix}, \quad \mathbf{v}_4 = \begin{bmatrix} 2\\9\\-2\\-6 \end{bmatrix}$$

is linearly independent. Again, we can use this using the definition of linear independence and some algebra. We need to solve the system:

$$c_{1} \begin{bmatrix} -1\\2\\0\\3 \end{bmatrix} + c_{2} \begin{bmatrix} 0\\1\\2\\4 \end{bmatrix} + c_{3} \begin{bmatrix} 2\\9\\-2\\-6 \end{bmatrix} = \begin{bmatrix} 0\\0\\0\\0 \end{bmatrix}$$

In matrix form:

$$\begin{bmatrix} -1 & 0 & 2 \\ 2 & 1 & 9 \\ 0 & 2 & -2 \\ 3 & 4 & 6 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

The solution to the system is as follows:

Out [7]:

Α

$$\begin{bmatrix} -1 & 0 & 2 \\ 2 & 1 & 9 \\ 0 & 2 & -2 \\ 3 & 4 & 6 \end{bmatrix}$$

Out[8]:

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

The system now only has the trivial solution, $c_1 = 0$, $c_2 = 0$ $c_3 = 0$. We conclude that \mathbf{v}_1 , \mathbf{v}_2 and \mathbf{v}_4 are *linearly independent*.

The next example demonstrates a streamlined method to obtain a linearly independent subset from a given set of vectors.

1.4 Example 3

Find a subset of $\{v_1, v_2, v_3, v_4, v_5\}$ that is linearly independent, where:

$$\mathbf{v}_{1} = \begin{bmatrix} 1 \\ -2 \\ 0 \\ -3 \\ -6 \end{bmatrix}, \quad \mathbf{v}_{2} = \begin{bmatrix} -2 \\ 4 \\ 0 \\ 6 \\ 12 \end{bmatrix}, \quad \mathbf{v}_{3} = \begin{bmatrix} 2 \\ -3 \\ 1 \\ -2 \\ -5 \end{bmatrix}, \quad \mathbf{v}_{4} = \begin{bmatrix} 7 \\ -11 \\ 3 \\ -9 \\ -21 \end{bmatrix}, \quad \mathbf{v}_{5} = \begin{bmatrix} -2 \\ 2 \\ -1 \\ 0 \\ 1 \end{bmatrix}$$

Solution:

We first solve the system:

$$c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + c_3\mathbf{v}_3 + c_4\mathbf{v}_4 + c_5\mathbf{v}_5 = \mathbf{0}$$

In matrix form this becomes:

$$\begin{bmatrix} 1 & -2 & 2 & 7 & -2 \\ -2 & 4 & -3 & -11 & 2 \\ 0 & 0 & 1 & 3 & -1 \\ -3 & 6 & -2 & -9 & 0 \\ -6 & 12 & -5 & -21 & 1 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \\ c_4 \\ c_5 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

The solution is in the following cells:

Α

Out[9]:

$$\begin{bmatrix} 1 & -2 & 2 & 7 & -2 \\ -2 & 4 & -3 & -11 & 2 \\ 0 & 0 & 1 & 3 & -1 \\ -3 & 6 & -2 & -9 & 0 \\ -6 & 12 & -5 & -21 & 1 \end{bmatrix}$$

The RREF is:

Out [10]:

The original system is equivalent to:

$$c_1 - 2c_2 + c_4 = 0$$
$$c_3 + 3c_4 = 0$$
$$c_5 = 0$$

The free variables are c_2 and c_4 , and the privot variables are c_1 , c_3 and c_5 .

Now, notice that *if we set the free variables equal to* 0, *then the pivot variables will also be zero*. This means that the only solution of:

$$c_1\mathbf{v}_1 + c_3\mathbf{v}_3 + c_5\mathbf{v}_5 = \mathbf{0}$$

is $c_1 = c_3 = c_5 = 0$, and the vectors \mathbf{v}_1 , \mathbf{v}_3 , \mathbf{v}_5 are linearly independent. In fact, this is a *maximal* linearly independent subset of the given vectors, because the solution of the system above shows that v_2 and v_4 can be expressed in terms of v_1 , v_3 , v_5 .

This principle can be used in general to solve this kind of problem:

Suppose that a finite set of vectors $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k\}$, and we want to find a *maximal linearly independent subset* of this set. Proceed as follows:

- Let A be the matrix that has the given vectors in its columns: $A = \begin{bmatrix} \mathbf{v}_1 & \mathbf{v}_2 & \dots & \mathbf{v}_k \end{bmatrix}$
- Find the RREF of *A*.
- A minimal set of linearly independent vectors is formed by the vectors that correspond to the *pivot columns* of the RREF.

1.5 Example 4

Find a subset of the vectors that is maximally linearly independent:

$$\mathbf{v}_1 = \begin{bmatrix} 2 \\ 4 \\ -1 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 4 \\ -8 \\ 2 \end{bmatrix}, \quad \mathbf{v}_3 = \begin{bmatrix} 0 \\ 2 \\ 0 \end{bmatrix}, \quad \mathbf{v}_4 = \begin{bmatrix} 2 \\ 6 \\ -1 \end{bmatrix},$$

Solution:

Form a matrix with the vectors on its columns:

Α

$$\begin{bmatrix} 2 & -4 & 0 & 2 \\ 4 & -8 & 2 & 6 \\ -1 & 2 & 0 & -1 \end{bmatrix}$$

Find the RREF equivalent matrix:

Out[12]:

$$\begin{bmatrix}
1 & -2 & 0 & 1 \\
0 & 0 & 1 & 1 \\
0 & 0 & 0 & 0
\end{bmatrix}$$

Columns 1 and 3 are pivot columns, so a maximal linearly independent set is given by:

$$\mathbf{v}_1 = \begin{bmatrix} 2\\4\\-1 \end{bmatrix}, \quad \mathbf{v}_3 = \begin{bmatrix} 0\\2\\0 \end{bmatrix},$$

In []: