

00-Useful-Commands

January 6, 2017

```
In [1]: from latools import *
        from sympy import *
        init_printing(use_latex=True)
```

1 Gram-Schmidt

Input: $\{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k\}$ a linearly independent set of vectors in \mathbb{R}^n

Output: $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k\}$, and orthogonal basis of $\text{span}\{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k\}$.

Algorithm:

- Let $\mathbf{v}_1 = \mathbf{u}_1$
- Let $\mathbf{v}_j = \mathbf{u}_j - \frac{\mathbf{u}_j \cdot \mathbf{v}_1}{\mathbf{v}_1 \cdot \mathbf{v}_1} \mathbf{v}_1 - \frac{\mathbf{u}_j \cdot \mathbf{v}_2}{\mathbf{v}_2 \cdot \mathbf{v}_2} \mathbf{v}_2 - \dots - \frac{\mathbf{u}_j \cdot \mathbf{v}_{j-1}}{\mathbf{v}_{j-1} \cdot \mathbf{v}_{j-1}} \mathbf{v}_{j-1}$ for $j = 2, \dots, k$

The first three steps are, more explicitly:

$$\mathbf{v}_1 = \mathbf{u}_1$$

$$\mathbf{v}_2 = \mathbf{u}_2 - \frac{\mathbf{u}_2 \cdot \mathbf{v}_1}{\mathbf{v}_1 \cdot \mathbf{v}_1} \mathbf{v}_1$$

$$\mathbf{v}_3 = \mathbf{u}_3 - \frac{\mathbf{u}_3 \cdot \mathbf{v}_1}{\mathbf{v}_1 \cdot \mathbf{v}_1} \mathbf{v}_1 - \frac{\mathbf{u}_3 \cdot \mathbf{v}_2}{\mathbf{v}_2 \cdot \mathbf{v}_2} \mathbf{v}_2$$

2 Matrices

2.1 Matrix Input

```
In [2]: A = matrix_to_rational([[1, 2, 3],
                                [4, 5, 6],
                                [7, 8, 9]])
```

A

Out [2]:

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix}$$

2.2 Row Operations

```
In [3]: A = matrix_to_rational([[1,2,3],[4,5,6],[7,8,9]])  
A
```

Out[3]:

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix}$$

2.2.1 Add a multiple of a row to another row:

Notice that you can put more than one row operation in a single command.

```
In [4]: A1 = rop(A, 'R1*(-4)+R2=>R2', 'R1*(-7)+R3=>R3')  
A1
```

Out[4]:

$$\begin{bmatrix} 1 & 2 & 3 \\ 0 & -3 & -6 \\ 0 & -6 & -12 \end{bmatrix}$$

2.2.2 Multiply a row by a scalar

```
In [5]: A2 = rop(A1, 'R2*(-1/3)=>R2')  
A2
```

Out[5]:

$$\begin{bmatrix} 1 & 2 & 3 \\ 0 & 1 & 2 \\ 0 & -6 & -12 \end{bmatrix}$$

2.2.3 Swap rows

```
In [6]: A = matrix_to_rational([[0,2,1],[-1,0,3],[2,4,-2]])  
A
```

Out[6]:

$$\begin{bmatrix} 0 & 2 & 1 \\ -1 & 0 & 3 \\ 2 & 4 & -2 \end{bmatrix}$$

Since the entry a_{11} is zero, to get a pivot on row 1 we need to swap rows:

```
In [7]: A1 = rop(A, 'R1<=>R2')  
A1
```

Out [7]:

$$\begin{bmatrix} -1 & 0 & 3 \\ 0 & 2 & 1 \\ 2 & 4 & -2 \end{bmatrix}$$

2.3 Identity Matrix

```
In [8]: eye(5) # Identity matrix, 5x5
```

Out [8]:

$$\begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

2.4 Reduced row echelon form

```
In [9]: R = reduced_row_echelon_form(A)
        R
```

Out [9]:

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

```
In [10]: x,y,z = symbols('x,y,z')
        B = matrix_to_rational([[1,2,3,x],
                                [4,5,6,y],
                                [7,8,9,z]])
        # Ignore last column of augmented matrix
        R = reduced_row_echelon_form(B, extra_cols=1)
        R
```

Out [10]:

$$\begin{bmatrix} 1 & 0 & -1 & -\frac{5x}{3} + \frac{2y}{3} \\ 0 & 1 & 2 & \frac{4x}{3} - \frac{y}{3} \\ 0 & 0 & 0 & x - 2y + z \end{bmatrix}$$

2.5 Vector input

```
In [11]: v1 = Matrix([1,-1,1])
        v1
```

Out [11]:

$$\begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$$

2.6 Vector with fractional entries

```
In [12]: v2 = Matrix([sympify('1/2'), sympify('-2/3'), 4])
          v2
```

Out [12]:

$$\begin{bmatrix} \frac{1}{2} \\ -\frac{2}{3} \\ 4 \end{bmatrix}$$

2.7 Matrices with Symbolic variables

```
In [13]: x, y, z, t = symbols('x,y,z,t')
          A = matrix_to_rational([[1,-1,2,5,x],
                                  [0,1,-2,4,y],
                                  [1,-1,1,-3,z],
                                  [1,1,1,2,t]])
          A
```

Out [13]:

$$\begin{bmatrix} 1 & -1 & 2 & 5 & x \\ 0 & 1 & -2 & 4 & y \\ 1 & -1 & 1 & -3 & z \\ 1 & 1 & 1 & 2 & t \end{bmatrix}$$

```
In [14]: k = symbols('k') # Use "symbols" even if there is only one symbol
          A = matrix_to_rational([[1,k,2],
                                  [2,0,k],
                                  [1,1,5]])
          A
```

Out [14]:

$$\begin{bmatrix} 1 & k & 2 \\ 2 & 0 & k \\ 1 & 1 & 5 \end{bmatrix}$$

2.8 Characteristic polynomial

```
In [15]: A = matrix_to_rational([[1,1,1],[-1,-1,1],[2,2,3]])
          A
```

Out [15]:

$$\begin{bmatrix} 1 & 1 & 1 \\ -1 & -1 & 1 \\ 2 & 2 & 3 \end{bmatrix}$$

```
In [16]: lbd = symbols('lambda')
p = det(A - lbd*eye(3)) # eye(3) is the 3x3 identity
p
```

Out [16]:

$$-\lambda^3 + 3\lambda^2 + 4\lambda$$

```
In [17]: factor(p)
```

Out [17]:

$$-\lambda(\lambda - 4)(\lambda + 1)$$

3 Matrix and vector operations

```
In [18]: # Multiplication
A * v1
```

Out [18]:

$$\begin{bmatrix} 1 \\ 1 \\ 3 \end{bmatrix}$$

```
In [19]: A * v2
```

Out [19]:

$$\begin{bmatrix} \frac{23}{6} \\ \frac{29}{6} \\ \frac{6}{35} \\ \frac{6}{3} \end{bmatrix}$$

```
In [20]: # Determinant
det(A)
```

Out [20]:

$$0$$

```
In [21]: # Inversion
P = matrix_to_rational([[1, 0, -1],
                        [2, 1, 3],
                        [2, 1, 1]])

P**(-1)
```

Out [21]:

$$\begin{bmatrix} 1 & \frac{1}{2} & -\frac{1}{2} \\ -2 & -\frac{3}{2} & \frac{5}{2} \\ 0 & \frac{1}{2} & -\frac{1}{2} \end{bmatrix}$$

```
In [22]: # Transposition  
P.T
```

Out [22]:

$$\begin{bmatrix} 1 & 2 & 2 \\ 0 & 1 & 1 \\ -1 & 3 & 1 \end{bmatrix}$$

```
In [23]: # Dot product  
v1.dot(v2)
```

Out [23]:

$$\frac{31}{6}$$

```
In [24]: # Length (norm)  
v1.norm()
```

Out [24]:

$$\sqrt{3}$$

```
In [ ]:
```