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## PUBLICATION LIST

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(Note: highlighted publications are marked with a ★)

### Preprints

- [1] V. Moro and **L. F. O. Chamon**. Solving differential equations with constrained learning, 2024. URL: <https://arxiv.org/abs/2410.22796>.
- [2] **L. F. O. Chamon**, S. Paternain, and A. Ribeiro. Trust but verify: Assigning prediction credibility by counterfactual constrained learning, 2020. URL: <https://arxiv.org/abs/2011.12344>.
- [3] **L. F. O. Chamon** and C. G. Lopes. Combination of LMS adaptive filters with coefficients feedback, 2016. URL: <https://arxiv.org/abs/1608.03248>.

### Patents

- [1] D. Lamb, **L. F. O. Chamon**, V. H. Nascimento, and A. Spirer. Sparse cascaded-integrator-comb filters, 2019. URL: <https://patents.google.com/patent/US10367477B2>. US10367477B2.

### Journals

- ★ [1] M. Calvo-Fullana, S. Paternain, **L. F. O. Chamon**, and A. Ribeiro. State augmented constrained reinforcement learning: Overcoming the limitations of learning with rewards. *IEEE Trans. on Autom. Control.*, 69[7]:4275–4290, 2024. URL: <https://arxiv.org/abs/2102.11941>.
- [2] C. G. Lopes, V. H. Nascimento, and **L. F. O. Chamon**. Distributed universal adaptive networks. *IEEE Trans. on Signal Process.*, 71:1817–1832, 2023. DOI: [10.1109/TSP.2023.3275812](https://arxiv.org/abs/2307.05746). URL: <https://arxiv.org/abs/2307.05746>.
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- ★ [4] L. Ruiz, **L. F. O. Chamon**, and A. Ribeiro. Transferability properties of graph neural networks. *IEEE Trans. on Signal Process.*, 71:3474–3489, 2023. DOI: [10.1109/TSP.2023.3297848](https://arxiv.org/abs/2112.04629). URL: <https://arxiv.org/abs/2112.04629>.
- ★ [5] **L. F. O. Chamon**, S. Paternain, M. Calvo-Fullana, and A. Ribeiro. Constrained learning with non-convex losses. *IEEE Trans. on Inf. Theory*, 69[3]:1739–1760, 2023. DOI: [10.1109/TIT.2022.3187948](https://arxiv.org/abs/2103.05134). URL: <https://arxiv.org/abs/2103.05134>.
- [6] **L. F. O. Chamon**, A. Amice, and A. Ribeiro. Approximately supermodular scheduling subject to matroid constraints. *IEEE Trans. on Autom. Control.*, 67[3]:1384–1396, 2022. DOI: [10.1109/TAC.2021.3071024](https://arxiv.org/abs/2003.08841). URL: <https://arxiv.org/abs/2003.08841>.
- [7] L. Ruiz, **L. F. O. Chamon**, and A. Ribeiro. Graphon signal processing. *IEEE Trans. on Signal Process.*, 69:4961–4976, 2021. DOI: [10.1109/TSP.2021.3106857](https://arxiv.org/abs/2003.05030). URL: <https://arxiv.org/abs/2003.05030>.
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## ML & Systems Conferences

- [1] J. Elenter, **L. F. O. Chamon**, and A. Ribeiro. Near-optimal solutions of constrained learning problems. In *International Conference on Learning Representations (ICLR)*, 2024. URL: <https://arxiv.org/abs/2403.11844>.
- ★ [2] **L. F. O. Chamon**, M. R. K. Jaghargh, and A. Korba. Constrained sampling with primal-dual Langevin Monte Carlo. In *Conference on Neural Information Processing Systems (NeurIPS)*, 2024. URL: <https://arxiv.org/abs/2411.00568>.
- [3] J. Cervino, **L. F. O. Chamon**, B. D. Haeffele, R. Vidal, and A. Ribeiro. Learning globally smooth functions on manifolds. In *International Conference on Machine Learning (ICML)*, 2023. URL: <https://arxiv.org/abs/2210.00301>.
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- ★ [10] S. Paternain, **L. F. O. Chamon**, M. Calvo-Fullana, and A. Ribeiro. Constrained reinforcement learning has zero duality gap. In *Conference on Neural Information Processing Systems (NeurIPS)*, pages 7555–7565, 2019. URL: <https://arxiv.org/abs/1910.13393>.
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## Control Conferences

- [1] B. A. Angélico, **L. F. O. Chamon**, S. Paternain, A. Ribeiro, and G. J. Pappas. Source seeking in unknown environments with convex obstacles. In *American Control Conference*, 2021. URL: <https://arxiv.org/abs/1909.07496>.
- [2] M. Calvo-Fullana, **L. F. O. Chamon**, and S. Paternain. Towards safe continuing task reinforcement learning. In *American Control Conference*, 2021. URL: <https://arxiv.org/abs/2102.12585>.
- [3] **L. F. O. Chamon**, A. Amice, S. Paternain, and A. Ribeiro. Resilient control: Compromising to adapt. In *IEEE Control and Decision Conference*, 2020. URL: <https://arxiv.org/abs/2004.03726>.
- [4] **L. F. O. Chamon**, S. Paternain, and A. Ribeiro. Counterfactual programming for optimal control. In *Learning for Dynamics & Control (L4DC)*, 2020.
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