

Computer Technology I

Lab. 1: How to use the PORTs, Digital input/output, Subroutine call



Authors: LEONARDO PEDRO,

Loïc GALLAND

Supervisor:

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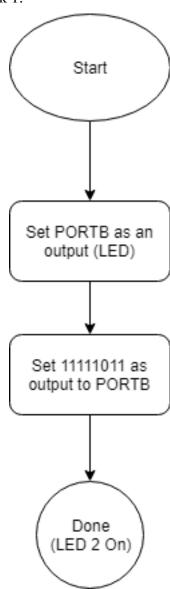
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Write a program in Assembly language to light LED 2. You can use any of the four ports, but start with PORTB. The program should be very short! How many instructions is minimum number?

```
; 1DT301, Computer Technology I
; Date: 2019-09-09
; Author:
; Loic GALLAND
; Leonardo PEDRO
; Lab number: 1
; Title: How to use the PORTs. Digital input/output. Subroutine call.
 Hardware: STK600, CPU ATmega2560
; Function: Program to light up the LED number 2
 Input ports: NO inputs ports in this Task
 Output ports: The portB is used as an output port
 Subroutines: If applicable.
; Included files: m2560def.inc
; Other information:
; Changes in program: (Description and date)
.includes "m2560def.inc"
ldi r16, 0xFF
out DDRB, r16
ldi r16 , 0b11111011
out portB, r16
```

To be able to light up the LEDs we need 4 lines of code. The first line is to store into the register r16 the value 0xFF. In the second line the register r16 is loaded to DDRB (Data Direction Register of port B). In the third line the desired binary code is stored into register r16. The binary number will determine which LED will light up. In the last line the register r16 is loaded into the PortB (Data Register of Port B).

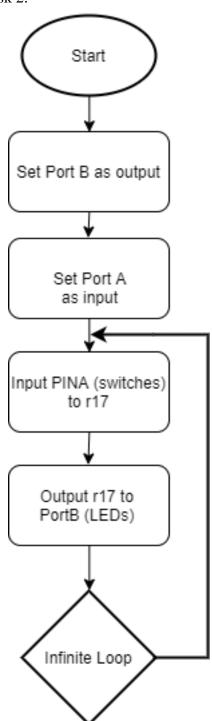
This is the flowchart of the task 1:



Write a program in Assembly language to read the switches and light the corresponding LED. Example: When you press SW5, LED5 so should light. Make an initialization part of the program and after that an infinite loop.

```
;>>>>>>>>>>>>>>>>>>>>>>>>>>>>>>
; 1DT301, Computer Technology I
; Date: 2019-09-09
; Author:
; Loic GALLAND
; Leonardo PEDRO
; Lab number: 1
; Title: How to use the PORTs. Digital input/output. Subroutine call.
; Hardware: STK600, CPU ATmega2560
; Function: Program to light up the LED correponding to the switch. EX:
    (Switch number 1 will light up LED number 1)
; Input ports: PortA is used as input to get the information from the
   switches
; Output ports: The portB is used as an output ports to control the
; Subroutines: If applicable.
; Included files: m2560def.inc
; Other information:
;
; Changes in program: (Description and date)
;<<<<<<<<<<<<<<<<<<<<<<
.include "m2560def.inc"
ldi r16, 0xFF
                      ;Setting up the data direction for Port B
                   ;Set port B as output
out DDRB, r16
ldi r16, 0x00
                     ;Setting up the data direction for Port A
out DDRA, r16
                      ; Set Port A as output
my_loop:
                      ;Loop to always check which switch is pressed
       in r17,PINA ; Getting the information of which switch is pressed
       out portB, R17 ; Lighting up the corresponding LED
rjmp my_loop
```

This is the flowchart for Task 2:



This is the code for the third task:

```
; 1DT301, Computer Technology I
; Date: 2019-09-09
; Author:
; Loic GALLAND
; Leonardo PEDRO
; Lab number: 1
; Title: How to use the PORTs. Digital input/output. Subroutine call.
; Hardware: STK600, CPU ATmega2560
; Function: Program to only light up LED number 0 if the switch number
   5 is pressed. If any other switch is pressed, nothing will happen
; Input ports: The Port A will be used as an input port in this Task
; Output ports: The portB is used as an output port
; Subroutines: If applicable.
; Included files: m2560def.inc
; Other information:
; Changes in program: (Description and date)
                      ;Setting up the data direction for Port B
ldi r16, 0xFF
out DDRB, r16
                      ;Set port B as output
ldi r16, 0x00
                       ; Setting up the data direction for Port A
out DDRA, r16
                       ;Set Port A as output
ldi r16, 0xFF
                      ;Turn off all the LEDs
out portB, r16
ldi r18, 0b11011111
ldi r19, 0b11111110
my_loop:
        in r17, PINA
                      ; get the info from the switch
       cp r17, r18
                      ; compare switch info with desired one
       breq light
                      ; condition if r17=r18 go to the "light"
rjmp my_loop
light: out portB, r19 ; turns on the LED0
```

This is the code for the fifth task:

```
; 1DT301, Computer Technology I
; Date: 2019-09-09
; Author:
; Loic GALLAND
; Leonardo PEDRO
; Lab number: 1
; Title: How to use the PORTs. Digital input/output. Subroutine call.
; Hardware: STK600, CPU ATmega2560
; Function: Create a program that creates a Ring Counter with a delay
   of approximately 0.5 seconds between each step.
; Input ports: NO inputs ports in this Task
; Output ports: The portB is used as an output port
; Subroutines: A subroutine will be used when creating the 0.5 second
  delay.
; Included files: m2560def.inc
.includes "m2560def.inc"
; Initialize SP, Stack Pointer
ldi r20, HIGH(RAMEND) ; R20 = high part of RAMEND address
                     ; SPH = high part of RAMEND address
out SPH, R20
ldi R20, low(RAMEND) ; R20 = low part of RAMEND address
                     ; SPL = low part of RAMEND address
out SPL, R20
                     ;Setting up the data direction for Port B
ldi r16, 0xFF
out DDRB, r16
                     ;Set port B as output
ldi r17, Ob111111110 ;Initial LED state
out PortB, r17
my_loop:
       out portB, r17
       CALL Delay
       com r17
       LSL r17
       com r17
rjmp my_loop
Delay:
; Generated by delay loop calculator
:at http://www.bretmulvey.com/avrdelay.html
; Delay 4 050 000 cycles
;500ms at 8.1 MHz
       ldi r18, 21
       ldi r19, 140
```

```
ldi 20, 174

L1: dec r20
brne L1
dec r19
brne L1
dec r18
brne L1
rjmp PC+1

RET
```

This is the code for the sixth task:

```
; 1DT301, Computer Technology I
; Date: 2019-09-09
; Author:
; Loic GALLAND
; Leonardo PEDRO
; Lab number: 1
; Title: How to use the PORTs. Digital input/output. Subroutine call.
; Hardware: STK600, CPU ATmega2560
; Function: Creates a program that creates a Johnson Counter in an
  infinite loop
; Input ports: NO inputs ports in this Task
; Output ports: The portB is used as an output port
; Subroutines: To be able to use the delay
; Included files: m2560def.inc
.includes "m2560def.inc"
; Initialize SP, Stack Pointer
ldi r20, HIGH(RAMEND) ; R20 = high part of RAMEND address
out SPH, R20
                     ; SPH = high part of RAMEND address
ldi R20, low(RAMEND)
                     ; R20 = low part of RAMEND address
out SPL, R20
                      ; SPL = low part of RAMEND address
ldi r16, 0xFF ;Setting up the date direction register for Port B
out DDRB, r16
              ;Set port B as output
ldi r16, 0xFF
out portB, r16
ldi r21, 0b111111110
                  ;Initial LED state
ldi r22, 0xFF ;When all the LEDs are turned off
ldi r23, 0x00 ; When all the LEDs are turned on
my_loop:
       out portB, r21
       LSL r21
       CALL Delay
       ; Compare the current status of the LEDs to check if they are
          all turned on.
       cp r21, r23
       breq light
rjmp my_loop
light:
       out portB, r23
       CALL Delay
       ldi r21, 0b10000000
       out portB, r21
```

```
Second_loop:
               out portB, r21
               ASR r21
               CALL Delay
                cp r21, r22
                                ;Compare the current status to
                  know if it needs to start going the other way
               breq my_loop
        rjmp Second_loop
Delay:
; Generated by delay loop calculator
:at http://www.bretmulvey.com/avrdelay.html
;Delay 4 050 000 cycles
;500ms at 8.1 MHz
        ldi r18, 21
        ldi r19, 140
        ldi 20, 174
L1:
        dec r20
        brne L1
        dec r19
        brne L1
        dec r18
        brne L1
        rjmp PC+1
RET
```