UCLouvain

Probabilistic mapping of the sub-cellular proteome

Laurent Gatto February 9, 2020

Abstract: In biology, localisation is function - understanding the sub-cellular localisation of proteins is paramount to comprehend the context and full extend of their functions. Shotgun mass spectrometry-based spatial proteomics method are orthogonal to widely used targeted microscopy-based assay. In conjunction with contemporary machine learning, the former enable to build proteome-wide protein localisation maps, informing us on the location of thousands of proteins. When studying these proteome-wide spatial maps, one can learn that while some proteins can be found in a single location within a cell, up to half of the proteins may reside in multiple locations, can dynamically re-localise, or reside within an unknown functional compartment, leading to considerable uncertainty in associating proteins to their sub-cellular location. Recent Bayesian modelling approaches enable us to mine these data, and in particular the dynamic fraction of the spatial proteome, in much greater depth. We are now in a position to (1) probabilistically model protein localisation as well as quantify the uncertainty in the location assignments, and (2) compute a probability for, and quantify uncertainty in, whether a protein is differentially localised upon cellular perturbation. These computational approaches lead to better and more trustworthy biological interpretation of these rich spatial proteomics data.

Acknowledgements

- Mr Oliver Crook
- Dr Lisa Breckels

Spatial proteomics

Data analysis

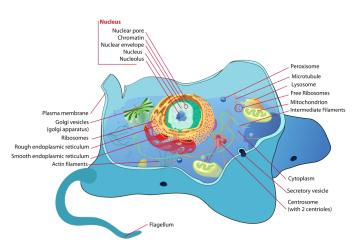
Computational challenges

Novelty detection

Multi-localisation and uncertainly quantification

Spatial dynamics

Cell organisation - localisation is function



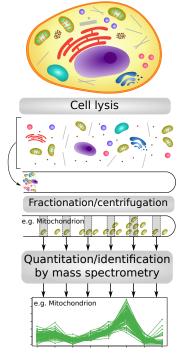
Spatial proteomics is the systematic study of protein localisations.

Localisation – re-localisation – mis-localisation

Image from Wikipedia http://en.wikipedia.org/wiki/Cell_(biology).

Explorative/discovery approaches, steady-state global localisation maps (as opposed to microscopy-based targeted approaches).

Density gradient: PCP (Dunkley et al., 2006), LOPIT (Foster et al., 2006), hyperLOPIT (Christoforou et al., 2016; Mulvey et al., 2017) and Differential centrifugation Itzhak et al. (2016), LOPIT-DC (Geladaki et al., 2018).



Quantitation data

	Fraction ₁	Fraction ₂		$Fraction_L$
x_1	<i>x</i> _{1,1}	<i>X</i> _{1,2}		$x_{1,L}$
x ₂	x _{2,1}	<i>x</i> _{2,2}		$x_{2,L}$
x ₃	<i>x</i> _{3,1}	<i>X</i> 3,2		<i>x</i> _{3,L}
:	:	:	:	:
Χi	<i>x</i> _{i,1}	<i>X</i> _{i,2}		$x_{i,L}$
:	:	:	:	:
ΧN	<i>x</i> _{N,1}	<i>X</i> N,2		XN, L

Quantitation data and organelle markers

	Fraction ₁	Fraction ₂		$Fraction_L$	markers
\mathbf{x}_1	<i>x</i> _{1,1}	X _{1,2}		<i>x</i> _{1,L}	unknown
x ₂	x _{2,1}	<i>X</i> _{2,2}		<i>X</i> _{2,L}	loc ₁
x ₃	<i>x</i> _{3,1}	<i>X</i> _{3,2}		<i>x</i> _{3,L}	unknown
:	•	:	:	:	:
Χi	<i>x</i> _{i,1}	<i>X</i> _{i,2}		$x_{i,L}$	loc _k
:	:	:	Ė	:	:
×Ν	<i>x</i> _{N,1}	<i>x</i> _{N,2}		XN, K	unknown

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Visualisation

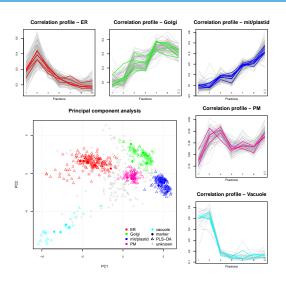


Figure: From Gatto et al. (2010), *Arabidopsis thaliana* data from Dunkley et al. (2006)

Problem statement: classification

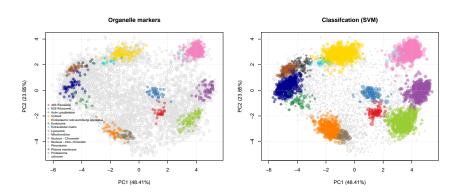


Figure: Support vector machines classifier (after 5% FDR classification cutoff) on the embryonic stem cell data from Christoforou et al. (2016).

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Computational challenges

- Visualisation (cluster, unsupervised learning)
- Classification (supervised learning)
- Novelty detection (semi-supervised learning)
- Data integration (transfer learning)
- Unvertainty quantification
- Multi-localisation
- Spatial dynamics

To uncover and understand biology

Spatial proteomics

Data analysis

Computational challenges

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Novelty detection



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Thank you for your attention

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