

# The Cluster Difference Imaging Photometric Survey (CDIPS). I. Method & TESS Light Curves from XXX Clusters

L. G. BOUMA,<sup>1</sup> W. BHATTI,<sup>1</sup> J. D. HARTMAN,<sup>1</sup> G. Á. BAKOS,<sup>1</sup> AND J. N. WINN<sup>1</sup>

<sup>1</sup> *Department of Astrophysical Sciences, Princeton University, 4 Ivy Lane, Princeton, NJ 08540, USA*

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## ABSTRACT

Lorem ipsum.

**Keywords:** methods: data analysis — techniques: photometric — (Galaxy:) open clusters and associations: general — planets and satellites: detection

## 1. INTRODUCTION

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In what follows, § 2 presents BLAH, and § 4 describes BLAH BLAH. § 5 discusses, and § 6 concludes.

## 2. METHOD: PHOTOMETRY

### 2.1. Overview

We reduced the TESS images to lightcurves by performing a sequence of steps using stand-alone programs. A conceptual overview of our “pipeline” is given in Figure 2. Our overall method is in the spirit of the reduction approaches used by Pál (2009), Soares-Furtado et al. (2017) and Oelkers & Stassun (2018).

We begin with the calibrated full frame images produced by SPOC (§ 2.2). We then perform a collection of preparatory steps, including source extraction of bright stars, astrometry using the resulting positions, and coarse simple aperture photometry (§ 2.3). Using the shape values from the initial astrometry, we select an astrometric reference frame and transform all of the calibrated images to it. We construct a photometric reference by stacking a collection of frames, and then convolve all the transformed frames to the photometric reference, and subtract (§ 2.4). We perform aperture photometry on the subtracted images using positions projected onto the frame from Gaia DR2. We detrend the resulting lightcurves (§ 2.5). We then select stars that we believe are “cluster members”, roughly X% of the overall dataset (§ 3). Focusing on the lightcurves of these stars, their white noise and red noise properties, and point out a few interesting cases of variability (§ 4).

### 2.2. Observations

The TESS spacecraft began science operations on July 25, 2018. To keep its cameras pointed opposite the Sun, the spacecraft advances by  $\approx 28$  degrees in ecliptic longitude every lunar month. Data acquired throughout each “sector” are downlinked at spacecraft perigee through the Deep Space Network. Verbose descriptions of the spacecraft’s design and operations are given by Ricker et al. (2015) and the instrument handbook (Vanderspek et al. 2018).

For us, the main data product of interest is the calibrated full frame image (FFI). Each TESS camera reads out every 2 seconds. To produce a manageable telemetric load, the resulting pixel values are averaged by the onboard computer into 30 minute exposures. An on-board cosmic ray mitigation algorithm is applied (CITE: BERTA-THOMPSON). Once transmitted to the ground, the raw images are calibrated by the Science Processing Operations Center. The calibration process includes an overscan, bias, and dark current correction, and also divides out a flat field. The details are given by Clarke et al. (2017), and the resulting science data products are described by Tenenbaum & Jenkins (2018).

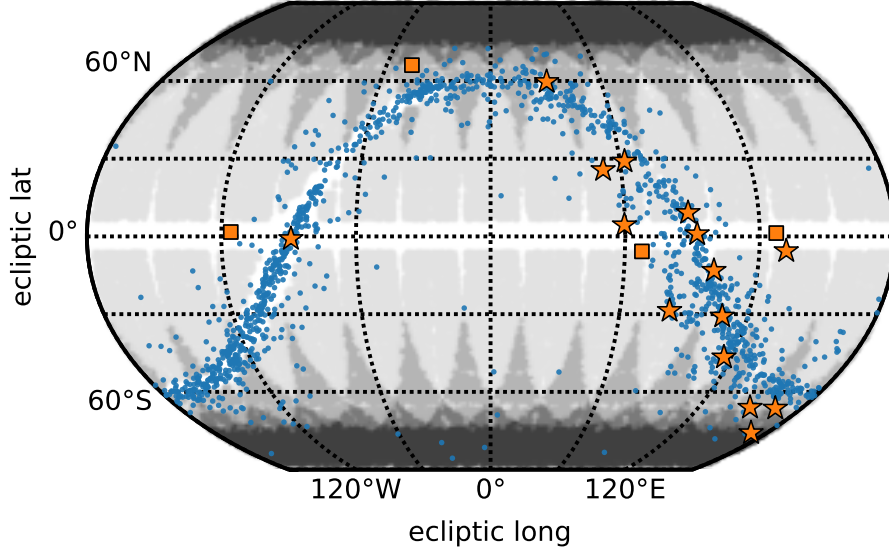
We begin our analysis using the calibrated images, their uncertainty maps, and their associated headers. The spacecraft has four cameras, and each camera has four CCDs. In the following analysis, all image-level operations are thus performed on the images for each CCD, so that at any instant of time there are 16 independent images undergoing analysis.

### 2.3. Image Preparation & Background Removal

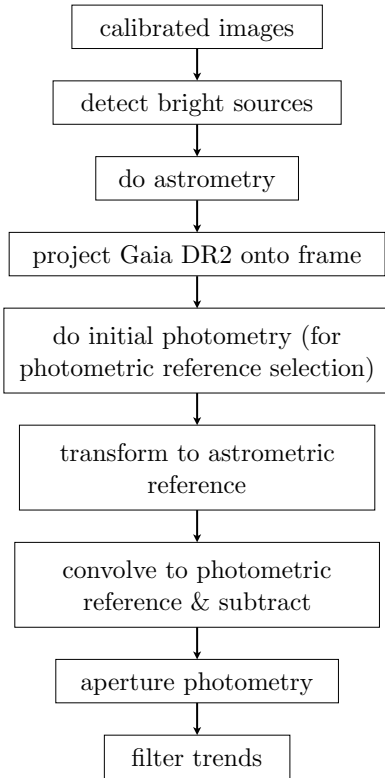
Before we can perform any kind of photometry, a few janitorial tasks are required.

First, we trim the images. We convert the calibrated image from MAST into a single-extension FITS image, trimmed to remove virtual rows and columns using the SCIRROWS, SCIROWE, SCCSA, and SCCED header values.

We then estimate the background of each frame. We do this by temporarily masking out pixels more than  $2\sigma$  from the median, and then passing a  $48 \times 48$  median box filter over



**Figure 1.** There are many clusters; TESS looks at them. Placeholder sky map.



**Figure 2. Pipeline.** This is what we do.

each pixel in the image, using reflective boundary conditions. We subtract out this smooth background estimate from each image. This step helps mitigate two unwanted image artifacts. First, it removes a low-level glow present in the corners of many images, which remains even after flat-fielding (see Vanderspek et al. 2018, §7.3.5). Second, background

subtraction removes scattered light patches from the Earth and Moon, which vary in positions around the camera bore-sight over each spacecraft orbit (see Vanderspek et al. 2018, §7.3.1–7.3.4). The typical size of scattered light patches is greater than 48 pixels, and their typical amplitude is  $\sim 10\times$  the sky background level.

After subtracting the background, we mask out saturated stars using a fixed saturation level of  $8 \times 10^4$  ADU. This value was chosen based on the onset of visible trails of bleeding charge, and is slightly greater than the expected saturation level quoted by Vanderspek et al. (2018). As described by Pál (2009), our masks are metadata to the image, and are only applied to the pixel values during the specific image processing steps (e.g., convolution) in which they are necessary. We also extend the masks beyond purely saturated pixels to “bloomed” pixels horizontally and vertically adjacent to the saturated pixels using the algorithm described by Pál (2009).

Finally, for frames with the DQUALITY bit-flag corresponding to the “momentum dumps” and “coarse pointing modes” described by Vanderspek et al. (2018), we mask out the entire frame. This removes on average a few frames per sector. Through visual inspection, we see that the stars on these frames are extremely smeared, and are unlikely to produce useful science data. In addition, we use the sector-specific data release notes<sup>1</sup> to identify further times with anomalously poor spacecraft performance, which we omit from consideration. For Sectors 1 through 5, these include coarse pointing windows from orbits 10, 13, 14, and an instrumental anomaly window in orbit 15.

Next, we perform some initial analysis steps to produce metadata needed during image subtraction. To obtain an astrometric solution (independent from the WCS data packaged

<sup>1</sup> [archive.stsci.edu/tess/tess\\_drn.html](https://archive.stsci.edu/tess/tess_drn.html)

with the frames), we use `fistar` to perform source extraction on bright stars in each image. We pass the resulting source lists through `astrometry.net` (Lang et al. 2010), which returns an astrometric solution for each frame packaged in the WCS format (Pence et al. 2010, Sec. 8). During the initial source extraction, we also fit elongated gaussians to the bright stars, yielding the shape parameters  $(s, d, k)$ , where the flux as a function of position is assumed to take the form

$$f_{\text{elong}}(\vec{x}) = B + A \exp\{-0.5 \times (s(\Delta x^2 + \Delta y^2) + d(\Delta x^2 - \Delta y^2) + k(2\Delta x \Delta y))\}, \quad (1)$$

for  $\Delta x = x - x_0$ , and  $\Delta y = y - y_0$ . For a nearly circular shape profile, the sharpness  $s$  is related to the FWHM as  $\text{FWHM} \approx 2.35\sqrt{s}$  (e.g., Pál 2009). These shape parameters are later used when selecting an astrometric reference (§ 2.4). We note that the fast focal ratio of the TESS cameras introduces significant comatic aberrations to the images: stars closer to the center of the field are more round, while stars towards the edges are more triangular.

With the resulting WCS information, we then project a source catalog from Gaia-DR2 onto the frame, down to a pre-selected magnitude cutoff (Gaia Collaboration et al. 2018b). We use these expected positions to center the apertures in our photometry, rather than attempting to detect the positions. Such “forced-aperture photometry” is preferable to performing source extraction because of the large TESS pixels, and the accurate Gaia positions. The Gaia-DR2 epoch is J2015.5, so even the fastest-moving stars with proper motions of  $\sim 1 \text{ arcsecond yr}^{-1}$  are still well within one pixel of their predicted positions in the TESS images. The projection and catalog-indexing is performed using `gaia2read`<sup>2</sup> (Kim 2018).

Finally, we perform aperture photometry on the bright stars from the source list, by summing the counts inside appropriately-weighted circular apertures centered on the projected positions from Gaia DR2. The pixel weights  $w_{x,y}$  are equal to the fraction of the pixel that falls within the aperture. They are thus unity for pixels entirely within the aperture, and fractional along the aperture boundary (e.g., Pál 2009 Fig 17). The background levels are measured in annuli around each aperture center. The raw flux of the object after background removal is then (Pál 2009 Eq 65)

$$f = \sum_{x,y} w_{x,y} (I_{x,y} - B) = f_{\text{total}} - B r_0^2. \quad (2)$$

The resulting measurements, for instance of the background level of each aperture, and the number of “good” objects that are detected, are later used as input for selecting photometric reference frames.

#### 2.4. Image Subtraction

The core operation of “classical” image subtraction attempts to match a photometric reference  $R$  and a target image

$I$  by computing a convolution kernel. The kernel, once applied to the high signal-to noise reference, produces a model image,  $M_{xy}$ ,

$$M_{xy} = (R \otimes K)_{xy} + B_{xy}, \quad (3)$$

where  $B_{xy}$  is a component of the model image that allows for background variations. The convolution kernel  $K$  is typically decomposed onto a basis,  $K = \sum_i c_i K_i$ , and the coefficients are found by minimizing

$$\chi^2 = \sum_{xy} \left( \frac{I_{xy} - M_{xy}}{\sigma_{xy}} \right)^2, \quad (4)$$

where  $\sigma_{xy}$  is the uncertainty in the target image pixel values. Photometry is then performed on the difference image  $D_{xy}$ , where  $D_{xy} = I_{xy} - M_{xy}$ .

The choice of kernel ...

We then select two “reference frames” for image subtraction. The first is the astrometric reference; the second is the photometric reference. To choose the astrometric reference, we use the following heuristics:

1. The frame must have large and round stars (largest “S”, smallest “D” and “K” values).
2. The frame must minimal background noise, as measured in annuli around the bright stars selected in § 2.3.
3. The frame must have, relative to the other frames being considered, a large number of detected sources.

We sort the frames using the above metrics, and then select the astrometric reference from successive intersections of each sorted list. Using the algorithm presented by Pál & Bakos (2006), we then calculate a spatial transformation that maps the X and Y coordinates from each calibrated frame onto the the astrometric reference.

“Registering” the images onto a common astrometric reference frame requires some care. In particular, the transformation must preserve the fluxes of the sources. Since the transformation is affine (a combination of e.g., translation, rotation, dilation, and shear) standard bilinear or bicubic interpolation would not achieve flux conservations. We therefore use the flux-conserving interpolation scheme described by Pál (2009) which is based on analytic integration of the surfaces determined by the pixel values. The largest component of the transformation is a translation, of order 2 arcseconds, or about 0.1 TESS pixels.

The second reference frame needed for image subtraction is the photometric reference. Generically, if one were to simply subtract two arbitrary frames, the noise level in the resulting difference image would be  $\sqrt{2}$  times greater than that in the original target frame. To minimize this effect, we create a high-SNR median average of  $N$  selected frames, so that the noise level in the resulting subtracted images goes as  $\sqrt{1 + 1/N}$ . This “photometric reference” is used both to calculate the convolution kernel during image subtraction, and to measure the reference flux of each star. To select viable frames for inclusion in the photometric reference, we use the

<sup>2</sup> [github.com/samuelyeewl/gaia2read](https://github.com/samuelyeewl/gaia2read)

results of our initial photometry step (§ 2.3), and sort frames for each sector by:

1. Lowest median scatter in photometry
2. Lowest median error in photometry
3. Lowest median background measurement
4. Lowest median absolute deviation in background measurements
5. Largest number of stars detected by `fiphot` with good flags.

We convolve the 50 best candidate photometric references to the best photometric reference, and then perform a median combination of the frames to make the photometric reference.

Some details of, and motivation for, the convolution process are warranted. The general idea of the image subtraction problem is to...

This has some benefits for crowded regions. Most notably, it enables a measurement of the background flux level.

Our approach follows from the algorithm presented by Alard & Lupton (1998), and explained in detail by Miller et al. (2008). The process is:

1. Select a set of isolated stars (“stamps”).
2. Choose basis vectors  $K_n$  for the kernel,  $K = \sum_{n=1}^N a_n K_n$ . Our goal is to determine the best-fitting coefficients  $a_n$ .
3. Using these stamps and the least-squares method, ...

Finally, we convolve and subtract all the frames that have been translated from the photometric reference (`grcombine`). We use the same kernel formalism as described by Soares-Furtado et al. (2017). To compute the convolution kernel, we minimize the difference between each image and the photometric reference (or something like this), using the Alard & Lupton 1998 method (CITE, also CITE Miller’s reference). The software implementation is that by Pál (2009), in the `ficonv` program. The implemented math is as follows.

$$XXX = XXX. \quad (5)$$

We explored a variety of kernel options, including X, Y, and Z. We wound up including an “identity” term (MEANING?), a “background term” (MEANING?) and a delta function term (MEANING? Give math for all of these). There are also spatially-varying terms of order XX. (MEANING?)

We perform forced-aperture photometry on the subtracted frames, using the locations from the Gaia projection, to measure the resulting difference fluxes. We use circular apertures, with the appropriate weights along the boundaries (`fiphot`; Pál (2009) Section FIXME).

Note that to measure the fluxes on the differenced images, a slightly different procedure from Eq. 2 is relevant. (Pal 2009 Section 2.9). Specifically, the subtracted image  $S$  is

given by  $I - B - R * K$ , for  $I$  the original image,  $B$  the background,  $R$  the reference image, and  $K$  the convolution kernel. The flux in the original image is given by

$$f = \sum_{x,y} w_{x,y} I_{x,y} \quad (6)$$

$$= \frac{1}{\|K\|_1^2} \sum_{x,y} S_{x,y} (w * K)_{x,y} + \sum_{x,y} R_{x,y} w_{x,y}, \quad (7)$$

Finally, to convert from a list of sources on each frame to a list of flux values at any given time, we use the `grcollect` transposition tool.

## 2.5. Lightcurve Detrending

The preceding steps produce lightcurves that include both instrumental systematics as well as astrophysical variability. The detrending philosophy adopted by the HAT group typically proceeds in two sequential stages (see discussions from e.g. Bakos et al. 2010; Huang et al. 2015; Zhang et al. 2016). The first stage is to decorrelate against external parameters that are known to affect the stellar flux measurements (EPD, Bakos et al. 2010). The second stage is to filter remaining systematic trends caused by unknown parameters by decorrelating the measured brightnesses of stars against each other (TFA, Kovács et al. 2005).

In general though, one must adapt detrending procedures to the data at hand. In § 2.5.1, we show that the “external parameter” dependence visible in the TESS data is rather complex: ordinary linear model-fitting, as well as an initial attempts at non-linear model fitting, are poor descriptions of the data. We go on to show (§ 2.5.2) that a plausible detrending approach for the purpose of transit discovery is to simply decorrelate against other nearby stars with standard TFA.

### 2.5.1. Flux versus external parameters

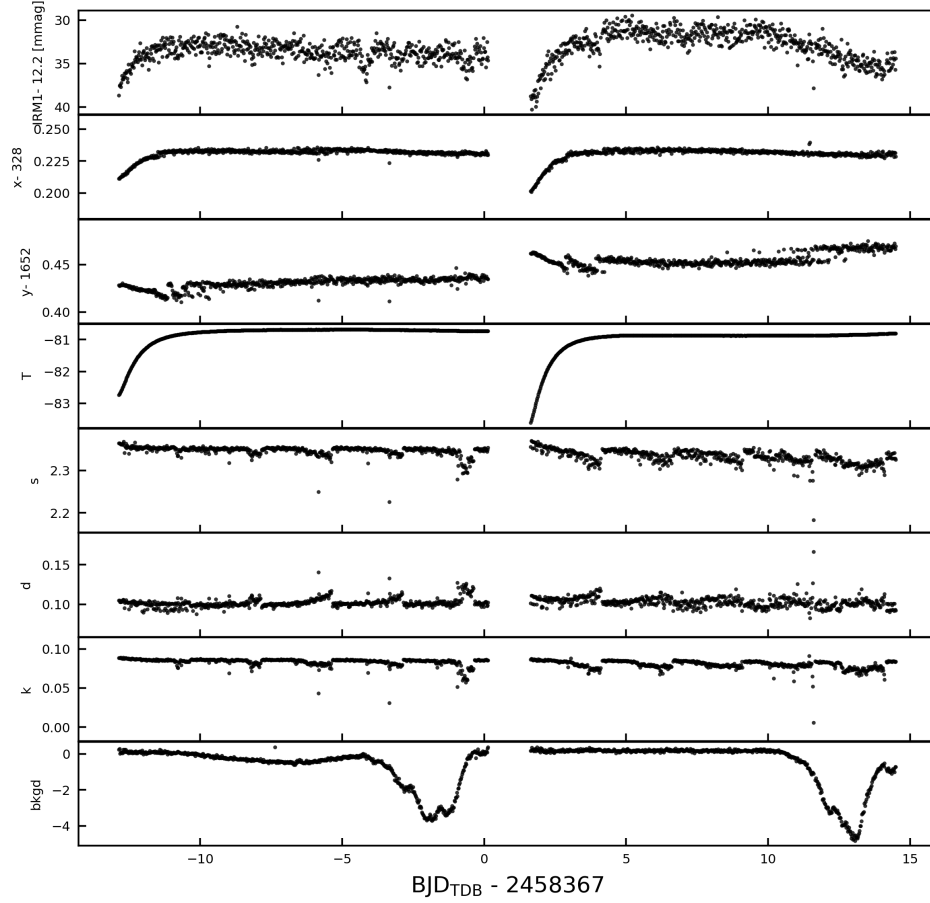
The traditional approach to EPD (Pál 2009; Bakos et al. 2010; Zhang et al. 2016) is to fit and subtract a model for the magnitudes  $m$  of the form

$$m = \text{const.} + \sum_i c_i \theta_i, \quad (8)$$

where  $\vec{\theta}$  is a vector of parameters such as the shape parameters ( $s, d, k$ ), their products ( $s^2, s \cdot d, d^2, \dots$ ), the temperature  $T$  of the instrument or environment<sup>3</sup>, the centroid positions  $(x, y)$ , the fractional part of the centroid positions ( $\{x\}, \{y\}$ ), and any other parameters that are expected<sup>5</sup> to correlate strongly with the observed flux. The coefficients  $c_i$  are calculated through linear least-squares, and subtracted to produce “EPD” lightcurves.

<sup>3</sup> We used the temperature from the on-chip aluminum-copper sensor measurements included in the engineering data<sup>4</sup>.

<sup>5</sup> The fractional centroid positions might matter because intra-pixel quantum efficiency variations could affect the measured stellar brightness. The varying temperature  $T$  of the CCD electronics might matter.



**Figure 3. Timeseries of “external parameters” for a representative star.** *Top:* Instrumental raw magnitude (with a particular aperture size), as a function of time. *Second and third from top:*  $x$  and  $y$  centroid positions as a function of time. Continuing in order are the CCD temperature, the  $(s, d, k)$  shape parameters, and the measured background value. Most of the apparent variability is instrumental: see § 2.5.1.

The premise of this model is that the correlations between the magnitudes and the external parameters are linear. For ground-based CCD data (e.g., HATNet, HATS, and Nikon DSLRs), Bakos et al. (2010) and Zhang et al. (2016) have verified that this model is a reasonable description to the data.

To discern whether such a model extends to the TESS data, we examined scatter plots of each parameter, as a function of all the other parameters. We also examined plots of each parameter as a function of time. A few prominent trends were present.

1. *Flux vs. time.* Most of the lightcurves we examined showed a secular drift with amplitude 0.01 mag over the timescale of each orbit. Sharper trends (“hooks”) at the beginning of each orbit seemed to be less prominent for stars at the corners of the fields than stars at the center. The periodicity incurred by the 2.5 day momentum dumps was also noticeable in more of the lightcurves at the center of the field than at the corners.
2. *Flux vs. centroid positions.* The flux as a function of centroid position often showed non-linear “hooks” (see Figure 4). Most of the data points from a given orbit

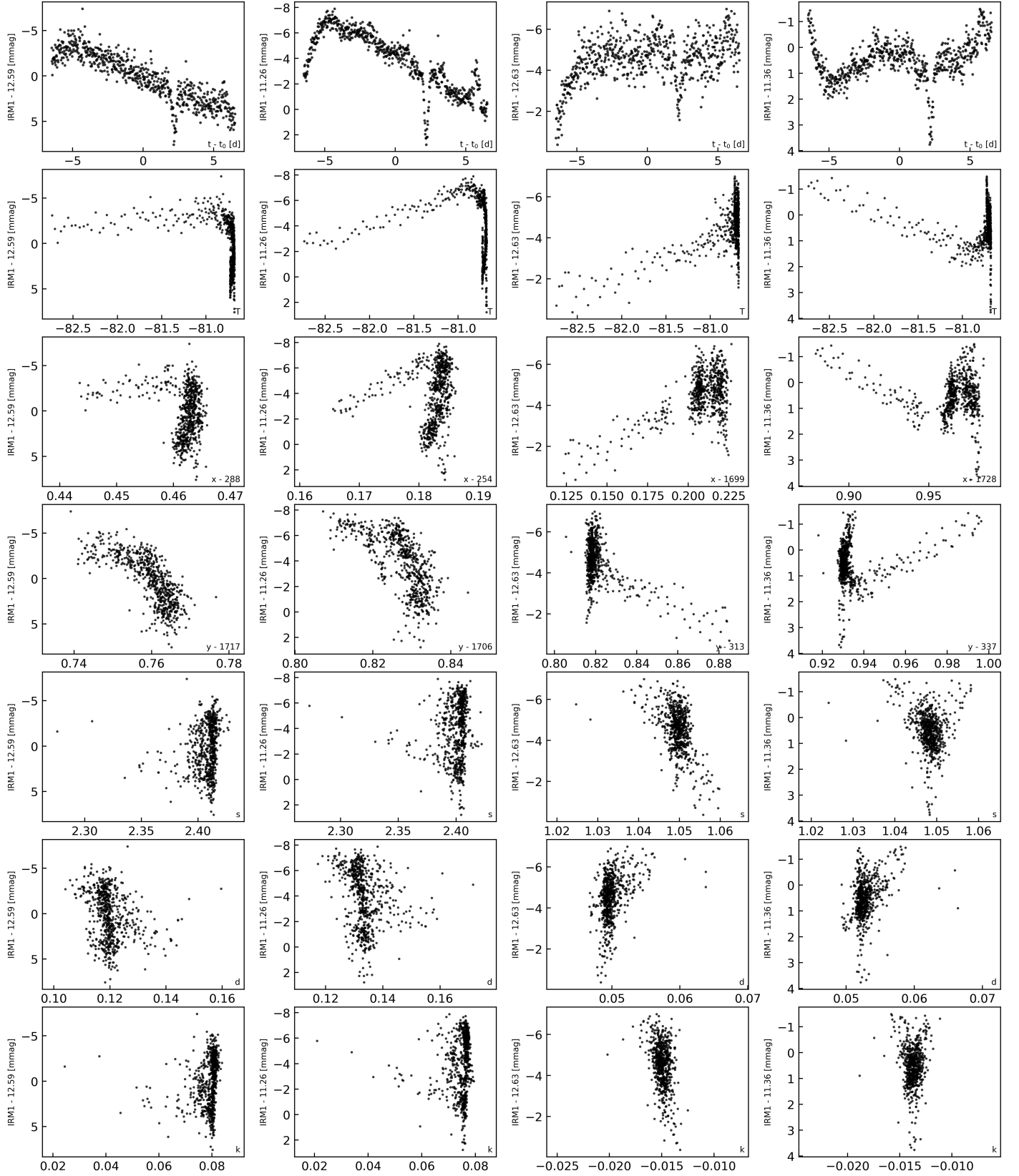
reside at a given level, but about 10% are in a tail. This was seen in lightcurves all across the TESS field of view.

3. *Flux vs. temperature* exhibited similar hooks, with most of the flux values residing at a particular level, and perhaps 10% following a non-linear path (often resembling the Nike “swoosh”) away from the bulk of points.
4. *Flux vs. shape parameters.* For lightcurves in the corner of the field of view, similar hooks are present in flux vs.  $(s, d, k)$ , though the hooks are less sharp. In the center of the field of view, gaussian ellipses are a better description of the flux vs. the shape parameters.

Considering the timeseries of parameters other than flux (Figure 3):

1. *Centroid positions vs. time.* The main variability in the centroid positions as a function of time is a secular drift, that is reset every orbit. The 2.5 day momentum wheel dump is superimposed on this secular drift, and has smaller amplitude than the drift.





**Figure 4.** Flux as a function of “external parameters” for four representative stars. The left two columns are stars at the corner of a camera’s field; the right two columns are from the centers. Each row shows a different parameter along the x-axis, given in text at the bottom right of each subplot. “Hooks” are common features in flux as a function of temperature and centroid position. § 2.5.1 gives a verbose description.

2. *Temperature vs. time.* The main variability in temperature vs. time is a secular drift of the same timescale as that for the centroid positions timeseries.
3. *Shape parameters vs. time.* The main variability in the shape parameters as a function of time is the 2.5 day momentum wheel dump periodicity, with hooks before each momentum dump.
4. *Background value vs. time.* The background is typically stable, except when scattered light from the Earth or Moon enters the frame (visible towards the end of each orbit in Figure 3).

Given the characteristics of the variability, a linear model of the form given in Equation 8 is not applicable. To fit out the correlations between flux and parameters which most commonly exhibited “hooks”, we explored fitting a parametric open curve (an  $N$ -dimensional B-spline, Dierckx 1996) to the flux, centroid positions, and temperatures simultaneously. We selected the number of knots through brute-force, by calculating  $\chi^2$  for the model fit over a grid of possible knots, and minimizing the Bayesian Information Criterion. Though this approach showed some initial promise, even with “optimal” knot-selection (in the BIC sense) it introduced undesirable residuals in the lightcurves, and also distorted transits.

Given these complications, for the time being we omit the step of “detrending” as a function of external parameters. To enable further exploration of the issue, we include all the necessary vectors of *e.g.*, centroid positions, temperatures, and shape parameters in our reported lightcurves.

### 2.5.2. Trend filtering algorithm

Since most of the external parameter dependence is shared between stars, we opt to decorrelate the flux timeseries of each star against other stars in the frame (TFA, Kovács et al. 2005).

This requires selecting “template stars”, which are a subsample of star that are supposed to represent all the types of systematics across the dataset. We select 500 template stars randomly from the stars on-chip with  $G_{\text{R}_p}$  magnitudes between 8.5 and 13 (TODO: rather bright?). We additionally require these stars to not have excessive variability, by fitting a parabola in the RMS-magnitude plane, and discarding stars more than  $4\sigma$  away from the prediction of this fit.

Once the template stars are selected, we use the secret TFA implementation from the HATpipe source code, that you and nobody else is allowed to see.

To select template stars, we impose a

The details of this selection procedure are

## 3. METHOD: STAR SELECTION

A major motivator for the CDIPS project is to increase the number of cluster stars for which continuous photometric timeseries are available, and thus facilitate studies of exoplanetary and stellar processes across different times and stellar environments.

An essential aspect of the project is therefore to define a *cluster star sample*, consisting of stars that are thought to be members of clusters.

Performing a homogeneous membership determination for every known cluster is beyond the scope of this work. Instead, we collect various cluster membership catalogs from the literature. We then use them to identify cluster members for which we have already made lightcurves from the TESS images. Our goal in selecting stars is completeness, rather than precision. If there has been a claim in the literature that a star should be considered as a cluster member, we aim to provide a lightcurve for that star.

Table N describes the cluster membership catalogs we have used to identify candidate cluster members. Since our photometric reduction is based on positions reported in *Gaia* DR2, each of our lightcurve sources by default is associated with a *Gaia* identifier. Correspondingly, the cluster membership determinations performed by Cantat-Gaudin et al. (2018) and *Gaia* Collaboration et al. (2018a) are the easiest case for us to merge against our lightcurve database. For the TESS Sectors 1–5 lightcurves produced in this study, this yielded X and Y lightcurves respectively.

### 3.1. Open clusters (OCs)

*Gaia*-derived OC memberships—At the time of writing, two relatively large, homogeneous cluster memberships studies had been performed using *Gaia*-DR2: those by Cantat-Gaudin et al. (2018) and *Gaia* Collaboration et al. (2018a).

Cantat-Gaudin et al. (2018) used an unsupervised membership assignment algorithm to identify clusters in the three-dimensional astrometric space of proper motion and parallax. They used *Gaia* photometry and radial velocities to then verify the claimed membership properties. From their Table 2, we collect 401,448 cluster members, in 1229 clusters, down to a limiting magnitude of  $G = 18$ .

*Gaia* Collaboration et al. (2018a) reported memberships for stars in a smaller, more select group of well-studied open clusters. From their Table A1, we collect 40,903 cluster members, in 41 open clusters, mostly within 500 pc. While this work also included memberships for globular clusters, we omitted these from consideration.

*Pre-Gaia* OC memberships—Kharchenko et al. (2013) used proper motions measured by PPMXL (CITE Roser 2010) and near-infrared photometry from 2MASS (CITE) and reported the existence of 2859 open clusters and stellar associations. We selected their “ $1\sigma$ ” members according to the combined photometric, kinematic, and spatial criteria described by Kharchenko et al. (2012). Then, to obtain *Gaia*-DR2 source identifiers for the members, we performed a cross-match for *Gaia*-DR2 sources within 5 arcseconds of the listed positions. As an additional constraint, we used the 2MASS photometry to predict the  $G$ -band magnitudes<sup>6</sup>, and required

<sup>6</sup> See [https://gea.esac.esa.int/archive/documentation/GDR2/Data\\_processing/chap\\_cu5pho/sec\\_cu5pho\\_calibr/ssec\\_cu5pho\\_PhotTransf.html](https://gea.esac.esa.int/archive/documentation/GDR2/Data_processing/chap_cu5pho/sec_cu5pho_calibr/ssec_cu5pho_PhotTransf.html), online, 2019-03-29, or Carrasco et al. (2016)

that the measured  $G$ -magnitude fall within 2 magnitudes of the predicted  $G$ -magnitude. If multiple neighbors matched the position and magnitude constraints, we took the nearest spatial neighbor as the match. From 373,226 stars, this yielded a unique best neighbor for 352,332 stars (94.4% of the sample), and a choice between two neighbors for 17,774 stars.

The second (non-*Gaia* derived) open cluster membership catalog we used was the Dias et al. (2014) catalog, which was based on UCAC4 proper motions. From their 1805 reported open clusters, we selected sources with quoted membership probability above 50%. To obtain *Gaia*-DR2 source identifiers for the members, we performed a similar crossmatch as before, looking for sources within 5 arcseconds of the listed positions, and within  $\pm 2$   $G$ -band magnitudes of the prediction. From 2,034,269 stars, this yielded a unique best neighbor for 1,828,630 stars (89.9% of the sample), and a choice between two neighbors for 8.7% of the remaining sample.

The distributions of the cross-matching statistics are shown in Figure

### 3.2. Moving groups and stellar associations

Gagn   et al. (2018b) Gagn   et al. (2018a) Gagn   & Faherty (2018)

Oh et al. (2017)

Kraus et al. (2014) Bell et al. (2017) Rizzuto et al. (2011) R  user et al. (2011)

## 4. RESULTS

RMS vs mag plots.

SNR of retrieved HJs.

Some stellar variability plots (perhaps of known stellar variables).

Some focus on actual cluster fields.

## 5. DISCUSSION

Lorem ipsum.

## 6. CONCLUSION

L.G.B. gladly acknowledges helpful discussions with ..., and is grateful to the people who have turned TESS from an idea into reality. J.N.W. thanks ... This paper includes data collected by the TESS mission, which are publicly available from the Mikulski Archive for Space Telescopes (MAST). Funding for the TESS mission is provided by NASA's Science Mission directorate. This research has made use of the NASA Exoplanet Archive, which is operated by the California Institute of Technology, under contract with the National Aeronautics and Space Administration under the Exoplanet Exploration Program. This work made use of NASA's Astrophysics Data System Bibliographic Services. This research has made use of the VizieR catalogue access tool, CDS, Strasbourg, France. The original description of the VizieR service was published in A&AS 143, 23. This work has made use of data from the European Space Agency (ESA) mission *Gaia* (<https://www.cosmos.esa.int/gaia>), processed by the *Gaia* Data Processing and Analysis Consortium (DPAC, <https://www.cosmos.esa.int/web/gaia/dpac/consortium>). Funding for the DPAC has been provided by national institutions, in particular the institutions participating in the *Gaia* Multilateral Agreement.

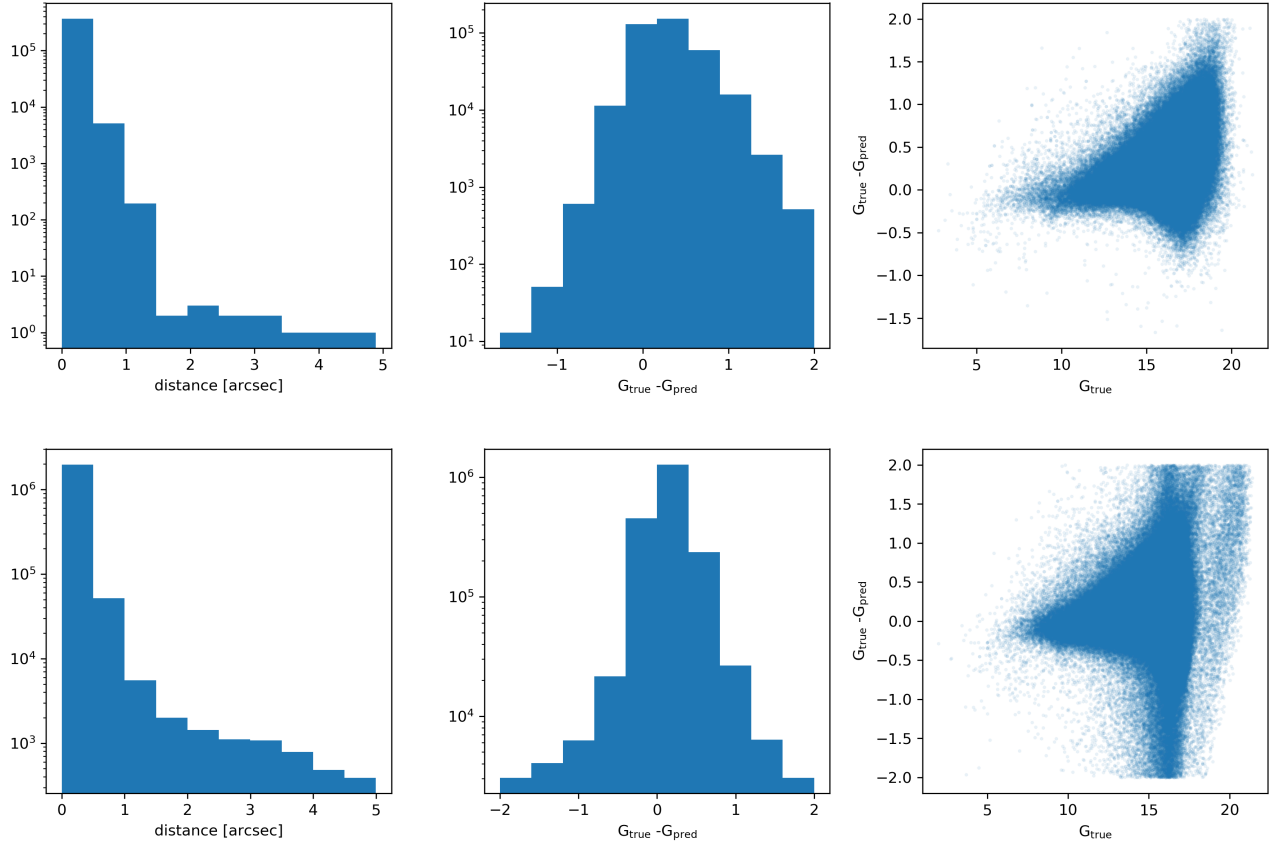
*Facility:* TESS (Ricker et al. 2015), *Gaia* (Gaia Collaboration et al. 2016, 2018b)

*Software:* *astrobase* (Bhatti et al. 2018), *astropy* (Collaboration et al. 2018), *astroquery* (Ginsburg et al. 2018), *BATMAN* (Kreidberg 2015), *corner* (Foreman-Mackey 2016), *emcee* (Foreman-Mackey et al. 2013), *fitsh* (P  l 2012), *IPython* (P  rez & Granger 2007), *matplotlib* (Hunter 2007), *numpy* (Walt et al. 2011), *pandas* (McKinney 2010), *scipy* (Jones et al. 2001).

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**Figure 5.** *Top.* Cross-match statistics from Kharchenko et al. (2013) vs. Gaia-DR2. *Bottom.* Ditto, for Dias et al. (2014) vs. Gaia-DR2.

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