

Synchronization: Basics

Introduction to Computer Systems
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Instructors:

Class 1: Chen Xiangqun, Liu Xianhua

Class 2: Guan Xuetao

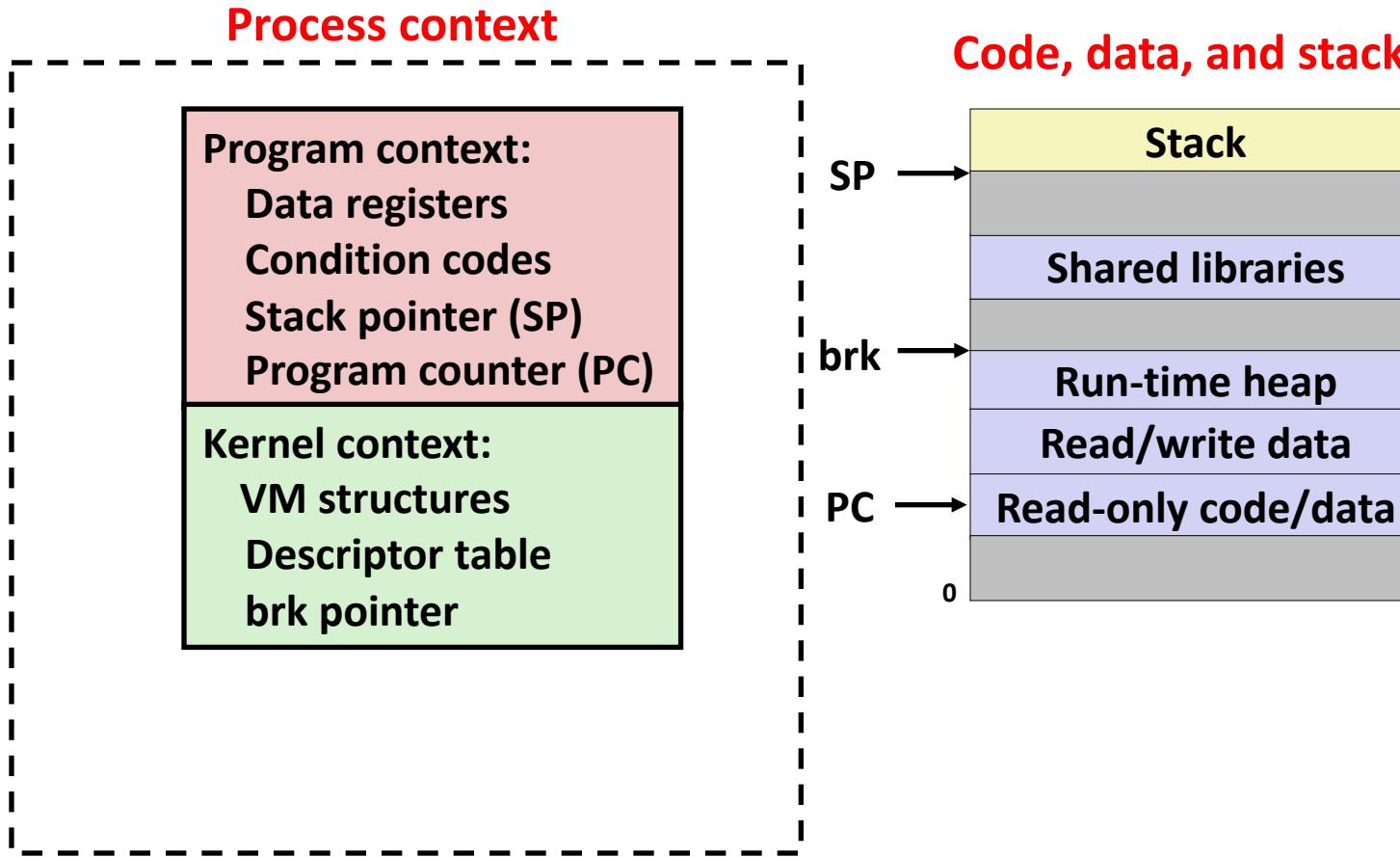
Class 3: Lu Junlin

Today

- Threads review
- Sharing
- Mutual exclusion
- Semaphores

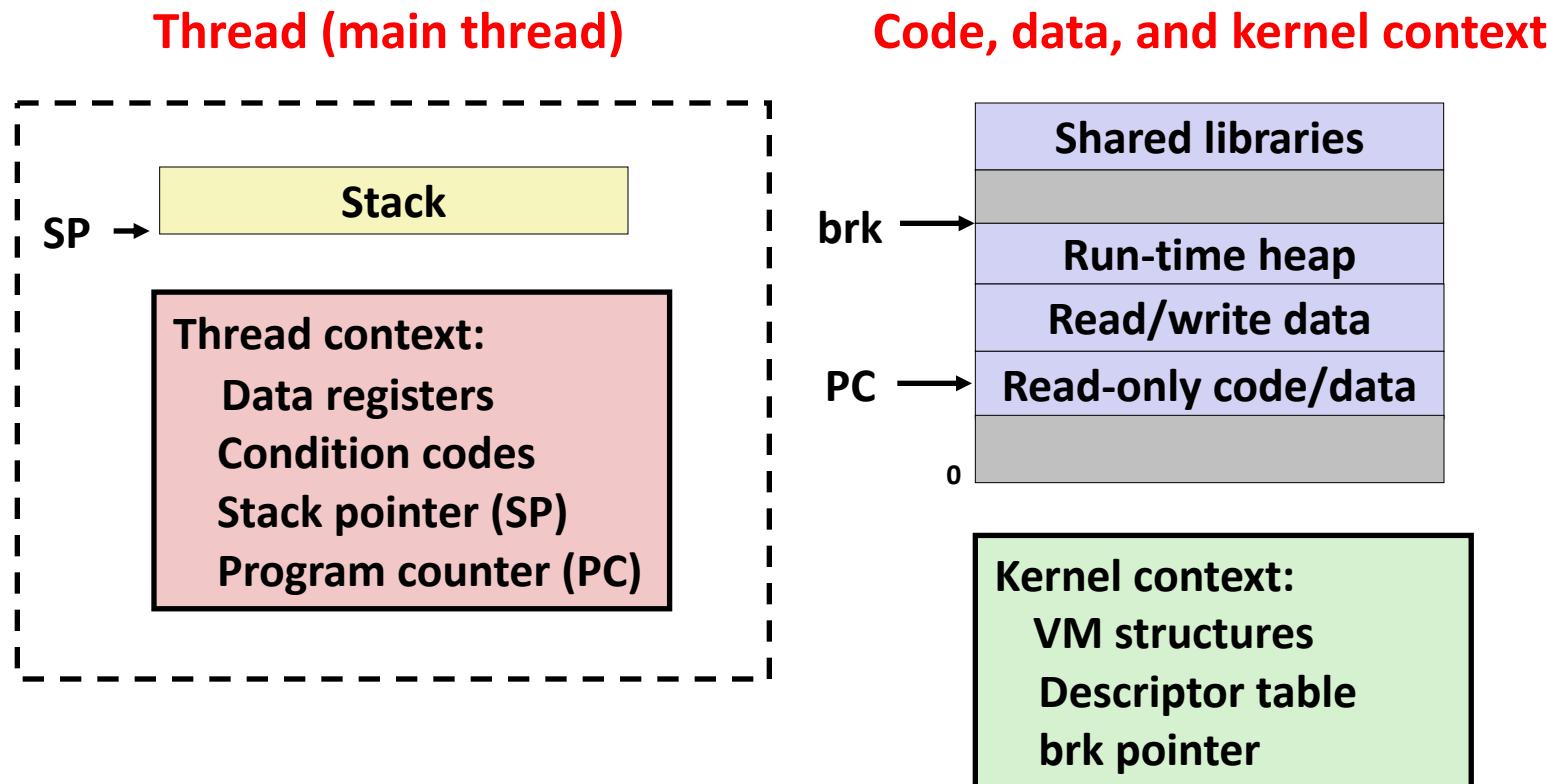
Traditional View of a Process

- Process = process context + code, data, and stack



Alternate View of a Process

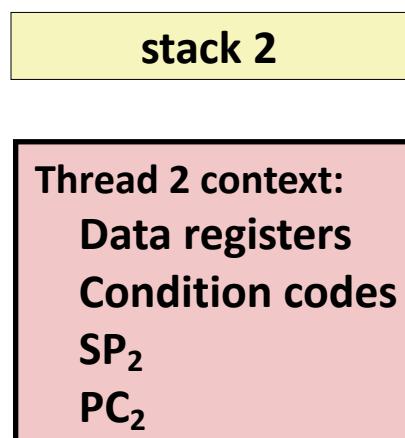
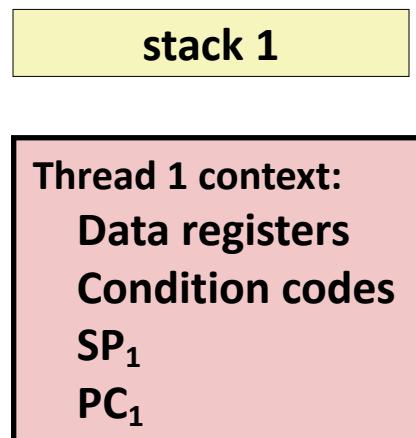
- Process = thread + code, data, and kernel context



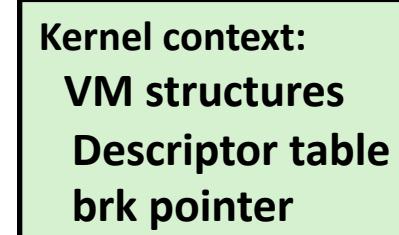
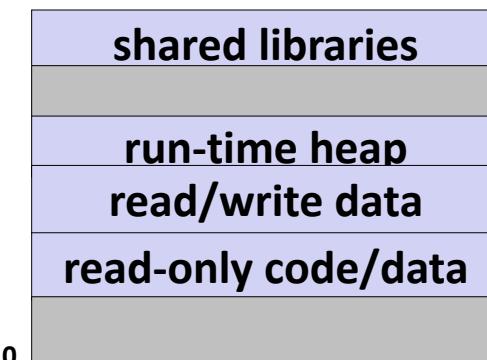
A Process With Multiple Threads

- **Multiple threads can be associated with a process**
 - Each thread has its own logical control flow
 - Each thread shares the same code, data, and kernel context
 - Each thread has its own stack for local variables
 - but not protected from other threads
 - Each thread has its own thread id (TID)

Thread 1 (main thread) Thread 2 (peer thread)



Shared code and data



Don't let picture confuse you!

Thread 1 (main thread) Thread 2 (peer thread)

stack 1

stack 2

Thread 1 context:
Data registers
Condition codes
 SP_1
 PC_1

Thread 2 context:
Data registers
Condition codes
 SP_2
 PC_2

Memory is shared between all threads

Shared code and data

shared libraries

run-time heap

read/write data

read-only code/data

0

Kernel context:
VM structures
Descriptor table
brk pointer

Threads vs. Processes

■ Threads and processes: similarities

- Each has its own logical control flow
- Each can run concurrently with others
- Each is scheduled and context switched by the kernel

■ Threads and processes: differences

- Threads share code and data, processes (typically) do not
- Threads are less expensive than processes
 - Process control (creating and reaping) is more expensive than thread control
 - Context switches for processes more expensive than for threads

Pros and Cons of Thread-Based Designs

- **+ Easy to share data structures between threads**
 - e.g., logging information, file cache
- **+ Threads are more efficient than processes**
- **– Unintentional sharing can introduce subtle and hard-to-reproduce errors!**

Today

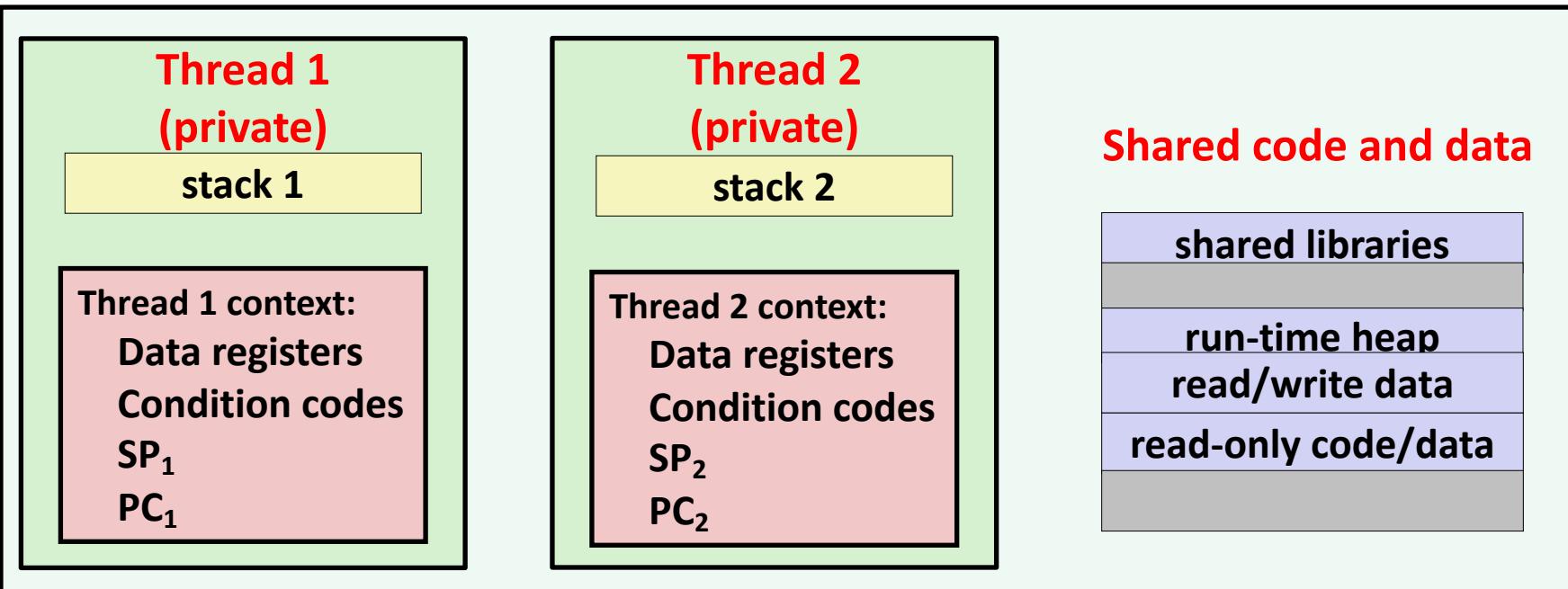
- Threads review
- Sharing
- Mutual exclusion
- Semaphores
- Producer-Consumer Synchronization

Shared Variables in Threaded C Programs

- **Question: Which variables in a threaded C program are shared?**
 - The answer is not as simple as “*global variables are shared*” and “*stack variables are private*”
- **Def:** A variable **x** is *shared* if and only if multiple threads reference some instance of **x**.
- **Requires answers to the following questions:**
 - What is the memory model for threads?
 - How are instances of variables mapped to memory?
 - How many threads might reference each of these instances?

Threads Memory Model: Conceptual

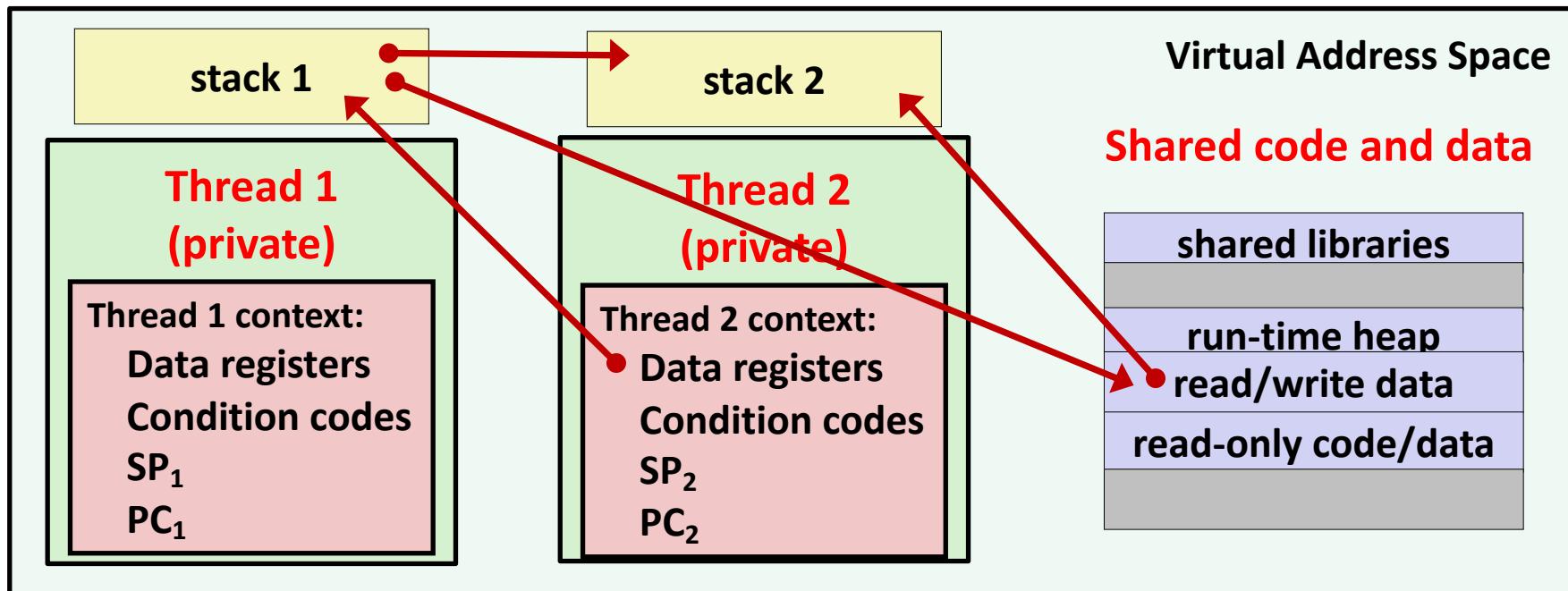
- Multiple threads run within the context of a single process
- Each thread has its own separate thread context
 - Thread ID, stack, stack pointer, PC, condition codes, and GP registers
- All threads share the remaining process context
 - Code, data, heap, and shared library segments of the process virtual address space
 - Open files and installed handlers



Threads Memory Model: Actual

■ Separation of data is not strictly enforced:

- Register values are truly separate and protected, but...
- Any thread can read and write the stack of any other thread



*The mismatch between the conceptual and operation model
is a source of confusion and errors*

Passing an argument to a thread - Pedantic

```

int hist[N] = {0};

int main(int argc, char *argv[]) {
    long i;
    pthread_t tids[N];

    for (i = 0; i < N; i++) {
        long* p = Malloc(sizeof(long));
        *p = i;
        Pthread_create(&tids[i],
                      NULL,
                      thread,
                      (void *)p);
    }
    for (i = 0; i < N; i++)
        Pthread_join(tids[i], NULL);
    check();
}

```

```

void *thread(void *vargp)
{
    hist[*((long *)vargp)] += 1;
    Free(vargp);
    return NULL;
}

```

```

void check(void) {
    for (int i=0; i<N; i++) {
        if (hist[i] != 1) {
            printf("Failed at %d\n", i);
            exit(-1);
        }
    }
    printf("OK\n");
}

```

Passing an argument to a thread - Pedantic

```

int hist[N] = {0};

int main(int argc, char *argv[]) {
    long i;
    pthread_t tids[N];

    for (i = 0; i < N; i++) {
        long* p = Malloc(sizeof(long));
        *p = i;
        Pthread_create(&tids[i],
                      NULL,
                      thread,
                      (void *)p);
    }
    for (i = 0; i < N; i++)
        Pthread_join(tids[i], NULL);
    check();
}

```

```

void *thread(void *vargp)
{
    hist[*((long *)vargp)] += 1;
    Free(vargp);
    return NULL;
}

```

- Use malloc to create a per thread heap allocated place in memory for the argument
- Remember to free in thread!
- Producer-consumer pattern

Passing an argument to a thread – Also OK!

```
int hist[N] = {0};

int main(int argc, char *argv[])
{
    long i;
    pthread_t tids[N];

    for (i = 0; i < N; i++)
        Pthread_create(&tids[i],
                       NULL,
                       thread,
                       (void *)i);
    for (i = 0; i < N; i++)
        Pthread_join(tids[i], NULL);
    check();
}
```

```
void *thread(void *vargp)
{
    hist[(long)vargp] += 1;
    return NULL;
}
```

- Ok to Use cast since $\text{sizeof}(\text{long}) \leq \text{sizeof}(\text{void}^*)$
- Cast does NOT change bits

Passing an argument to a thread – **WRONG!**

```
int hist[N] = {0};

int main(int argc, char *argv[])
{
    long i;
    pthread_t tids[N];

    for (i = 0; i < N; i++)
        Pthread_create(&tids[i],
                       NULL,
                       thread,
                       (void *) &i);
    for (i = 0; i < N; i++)
        Pthread_join(tids[i], NULL);
    check();
}
```

```
void *thread(void *vargp)
{
    hist[*((long *)vargp)] += 1;
    return NULL;
}
```

- **&i points to same location for all threads!**
- **Creates a data race!**

Three Ways to Pass Thread Arg

■ **Malloc/free**

- Producer malloc's space, passes pointer to pthread_create
- Consumer dereferences pointer

■ **Ptr to stack slot**

- Producer passes address to producer's stack in pthread_create
- Consumer dereferences pointer

■ **Cast of int**

- Producer casts an int/long to address in pthread_create
- Consumer casts void* argument back to int/long

Example Program to Illustrate Sharing

```

char **ptr; /* global var */

int main(int argc, char *argv[])
{
    long i;
    pthread_t tid;
    char *msgs[2] = {
        "Hello from foo",
        "Hello from bar"
    };

    ptr = msgs;
    for (i = 0; i < 2; i++)
        Pthread_create(&tid,
                      NULL,
                      thread,
                      (void *)i);
    Pthread_exit(NULL);
}

```

sharing.c

```

void *thread(void *vargp)
{
    long myid = (long)vargp;
    static int cnt = 0;

    printf("[%ld]: %s (cnt=%d)\n",
           myid, ptr[myid], ++cnt);
    return NULL;
}

```

*Peer threads reference main thread's stack
indirectly through global ptr variable*

*A common, but inelegant way to
pass a single argument to a
thread routine*

Mapping Variable Instances to Memory

■ Global variables

- *Def:* Variable declared outside of a function
- **Virtual memory contains exactly one instance of any global variable**

■ Local variables

- *Def:* Variable declared inside function without `static` attribute
- **Each thread stack contains one instance of each local variable**

■ Local static variables

- *Def:* Variable declared inside function with the `static` attribute
- **Virtual memory contains exactly one instance of any local static variable.**

Mapping Variable Instances to Memory

Global var: 1 instance (ptr [data])

```
char **ptr; /* global var */

int main(int main, char *argv[])
{
    long i;
    pthread_t tid;
    char *msgs[2] = {
        "Hello from foo",
        "Hello from bar"
    };

    ptr = msgs;
    for (i = 0; i < 2; i++)
        Pthread_create(&tid,
                      NULL,
                      thread,
                      (void *)i);
    Pthread_exit(NULL);
}
```

sharing.c

Local vars: 1 instance (i.m, msgs.m)

Local var: 2 instances (

myid.p0 [peer thread 0's stack],
myid.p1 [peer thread 1's stack]

)

```
void *thread(void *vargp)
{
    long myid = (long)vargp;
    static int cnt = 0;

    printf("[%ld]: %s (cnt=%d)\n",
           myid, ptr[myid], ++cnt);
    return NULL;
}
```

Local static var: 1 instance (cnt [data])

Shared Variable Analysis

■ Which variables are shared?

<i>Variable instance</i>	<i>Referenced by main thread?</i>	<i>Referenced by peer thread 0?</i>	<i>Referenced by peer thread 1?</i>
ptr	yes	yes	yes
cnt	no	yes	yes
i.m	yes	no	no
msgs.m	yes	yes	yes
myid.p0	no	yes	no
myid.p1	no	no	yes

```
char **ptr; /* global var */
int main(int argc, char *argv[])
{
    long i; pthread_t tid;
    char *msgs[2] = {"Hello from foo",
                     "Hello from bar" };
    ptr = msgs;
    for (i = 0; i < 2; i++)
        Pthread_create(&tid,
                      NULL, thread, (void *)i);
    Pthread_exit(NULL); }
```

```
void *thread(void *vargp)
{
    long myid = (long)vargp;
    static int cnt = 0;

    printf("[%ld]: %s (cnt=%d)\n",
           myid, ptr[myid], ++cnt);
    return NULL;
}
```

Shared Variable Analysis

■ Which variables are shared?

<i>Variable instance</i>	<i>Referenced by main thread?</i>	<i>Referenced by peer thread 0?</i>	<i>Referenced by peer thread 1?</i>
ptr	yes	yes	yes
cnt	no	yes	yes
i.m	yes	no	no
msgs.m	yes	yes	yes
myid.p0	no	yes	no
myid.p1	no	no	yes

■ Answer: A variable **x** is shared iff multiple threads reference at least one instance of **x**. Thus:

- ptr, cnt, and msgs are shared
- i and myid are **not** shared

Today

- Threads review
- Sharing
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- Semaphores
- Producer-Consumer Synchronization

Synchronizing Threads

- Shared variables are handy...
- ...but introduce the possibility of nasty *synchronization* errors.

badcnt.c: Improper Synchronization

```

/* Global shared variable */
volatile long cnt = 0; /* Counter */

int main(int argc, char **argv)
{
    long niters;
    pthread_t tid1, tid2;

    niters = atoi(argv[1]);
    Pthread_create(&tid1, NULL,
                   thread, &niters);
    Pthread_create(&tid2, NULL,
                   thread, &niters);
    Pthread_join(tid1, NULL);
    Pthread_join(tid2, NULL);

    /* Check result */
    if (cnt != (2 * niters))
        printf("BOOM! cnt=%ld\n", cnt);
    else
        printf("OK cnt=%ld\n", cnt);
    exit(0);
}

```

badcnt.c

```

/* Thread routine */
void *thread(void *vargp)
{
    long i, niters =
        *((long *)vargp);

    for (i = 0; i < niters; i++)
        cnt++;

    return NULL;
}

```

```

linux> ./badcnt 10000
OK cnt=20000
linux> ./badcnt 10000
BOOM! cnt=13051
linux>

```

cnt should equal 20,000.

What went wrong?

Assembly Code for Counter Loop

C code for counter loop in thread i

```
for (i = 0; i < niters; i++)
    cnt++;
```

Asm code for thread i

```
movq (%rdi), %rcx
testq %rcx, %rcx
jle .L2
movl $0, %eax

.L3:
    movq cnt(%rip), %rdx
    addq $1, %rdx
    movq %rdx, cnt(%rip)
    addq $1, %rax
    cmpq %rcx, %rax
    jne .L3

.L2:
```

The assembly code is annotated with curly braces on the right side:

- A brace above the first four instructions (movq, testq, jle, movl) is labeled H_i : Head.
- A brace spanning the section from movq to cmpq is labeled L_i : Load cnt, U_i : Update cnt, and S_i : Store cnt.
- A brace below the cmpq and jne instructions is labeled T_i : Tail.

Concurrent Execution

- **Key idea:** In general, any sequentially consistent interleaving is possible, but some give an unexpected result!
 - I_i denotes that thread i executes instruction I
 - $\%rdx_i$ is the content of $\%rdx$ in thread i 's context

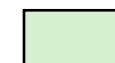
i (thread)	$instr_i$	$\%rdx_1$	$\%rdx_2$	cnt
1	H_1	-	-	0
1	L_1	0	-	0
1	U_1	1	-	0
1	S_1	1	-	1
2	H_2	-	-	1
2	L_2	-	1	1
2	U_2	-	2	1
2	S_2	-	2	2
2	T_2	-	2	2
1	T_1	1	-	2

OK

Concurrent Execution

- **Key idea:** In general, any sequentially consistent interleaving is possible, but some give an unexpected result!
 - I_i denotes that thread i executes instruction I
 - $\%rdx_i$ is the content of $\%rdx$ in thread i 's context

i (thread)	$instr_i$	$\%rdx_1$	$\%rdx_2$	cnt
1	H_1	-	-	0
1	L_1	0	-	0
1	U_1	1	-	0
1	S_1	1	-	1
2	H_2	-	-	1
2	L_2	-	1	1
2	U_2	-	2	1
2	S_2	-	2	2
2	T_2	-	2	2
1	T_1	1	-	2

 Thread 1
 critical section

OK

Concurrent Execution (cont)

- Incorrect ordering: two threads increment the counter, but the result is 1 instead of 2

i (thread)	instr _i	%rdx ₁	%rdx ₂	cnt
1	H ₁	-	-	0
1	L ₁	0	-	0
1	U ₁	1	-	0
2	H ₂	-	-	0
2	L ₂	-	0	0
1	S ₁	1	-	1
1	T ₁	1	-	1
2	U ₂	-	1	1
2	S ₂	-	1	1
2	T ₂	-	1	1

Oops!

Concurrent Execution (cont)

- How about this ordering?

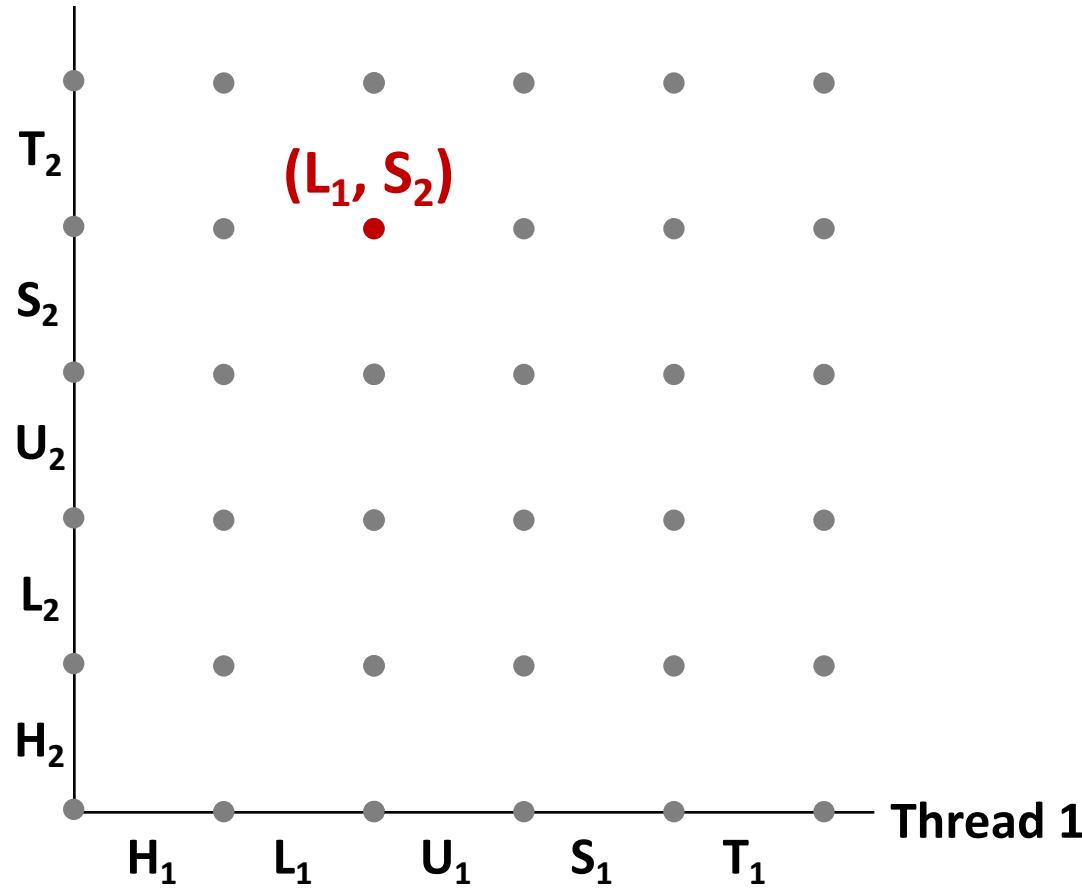
i (thread)	$instr_i$	$\%rdx_1$	$\%rdx_2$	cnt
1	H_1			0
1	L_1	0		
2	H_2			
2	L_2		0	
2	U_2		1	
2	S_2		1	1
1	U_1	1		
1	S_1	1		1
1	T_1			1
2	T_2			1

Oops!

- We can analyze the behavior using a *progress graph*

Progress Graphs

Thread 2



A *progress graph* depicts the discrete *execution state space* of concurrent threads.

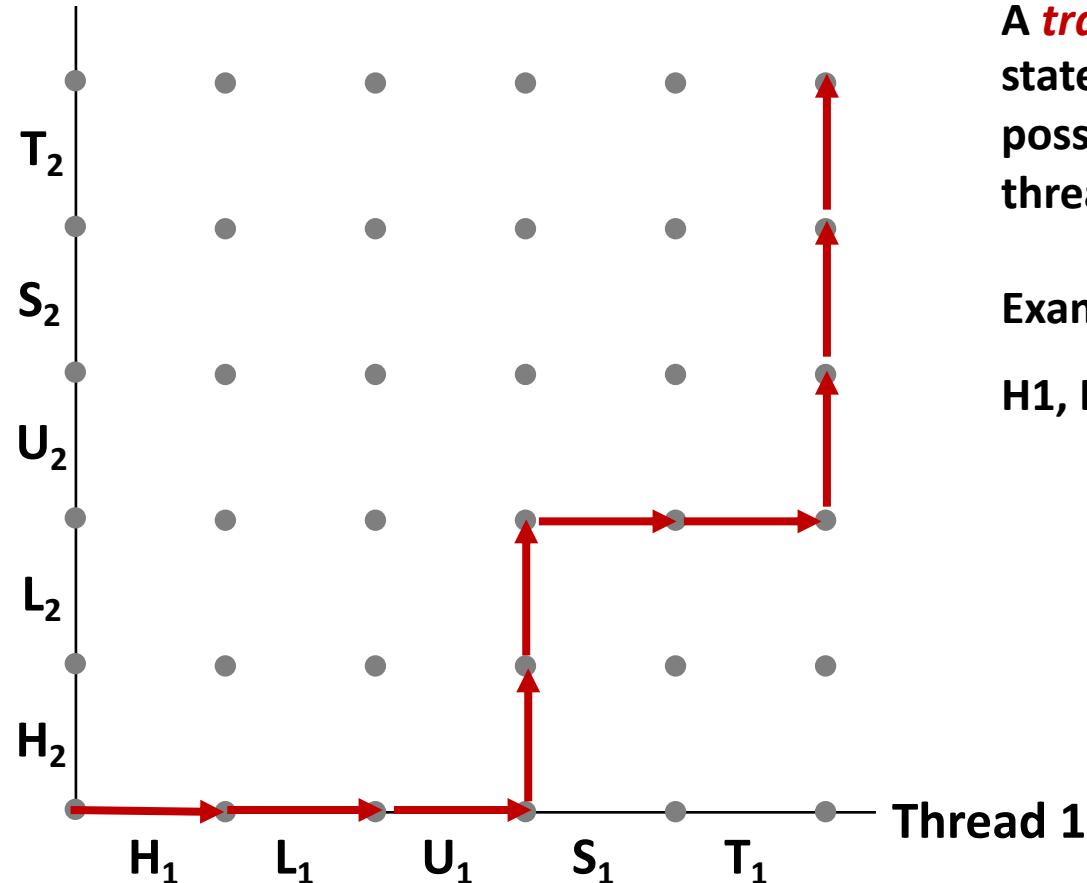
Each axis corresponds to the sequential order of instructions in a thread.

Each point corresponds to a possible *execution state* $(\text{Inst}_1, \text{Inst}_2)$.

E.g., (L_1, S_2) denotes state where thread 1 has completed L_1 and thread 2 has completed S_2 .

Trajectories in Progress Graphs

Thread 2



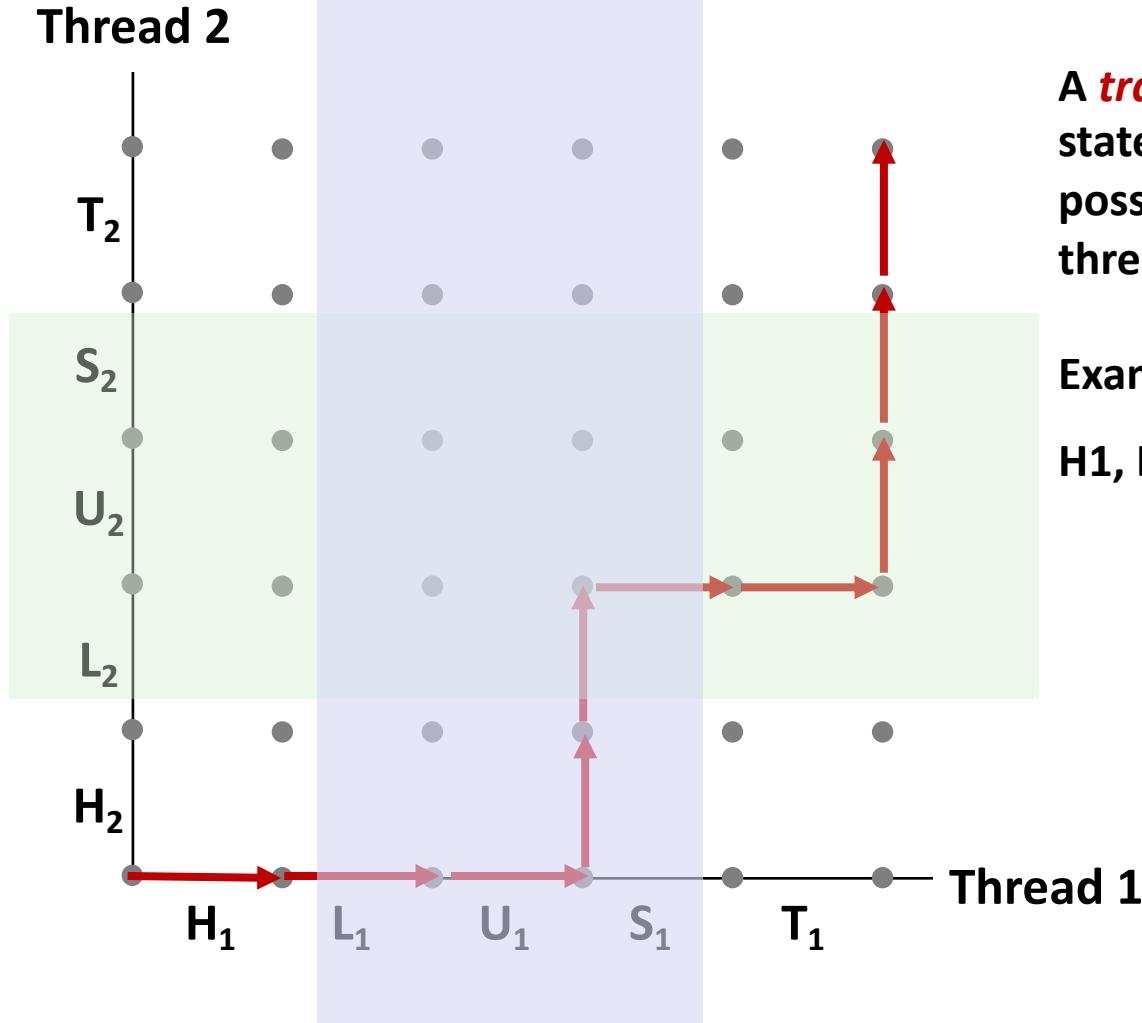
A **trajectory** is a sequence of legal state transitions that describes one possible concurrent execution of the threads.

Example:

$H_1, L_1, U_1, H_2, L_2, S_1, T_1, U_2, S_2, T_2$

Trajectories in Progress Graphs

Thread 2

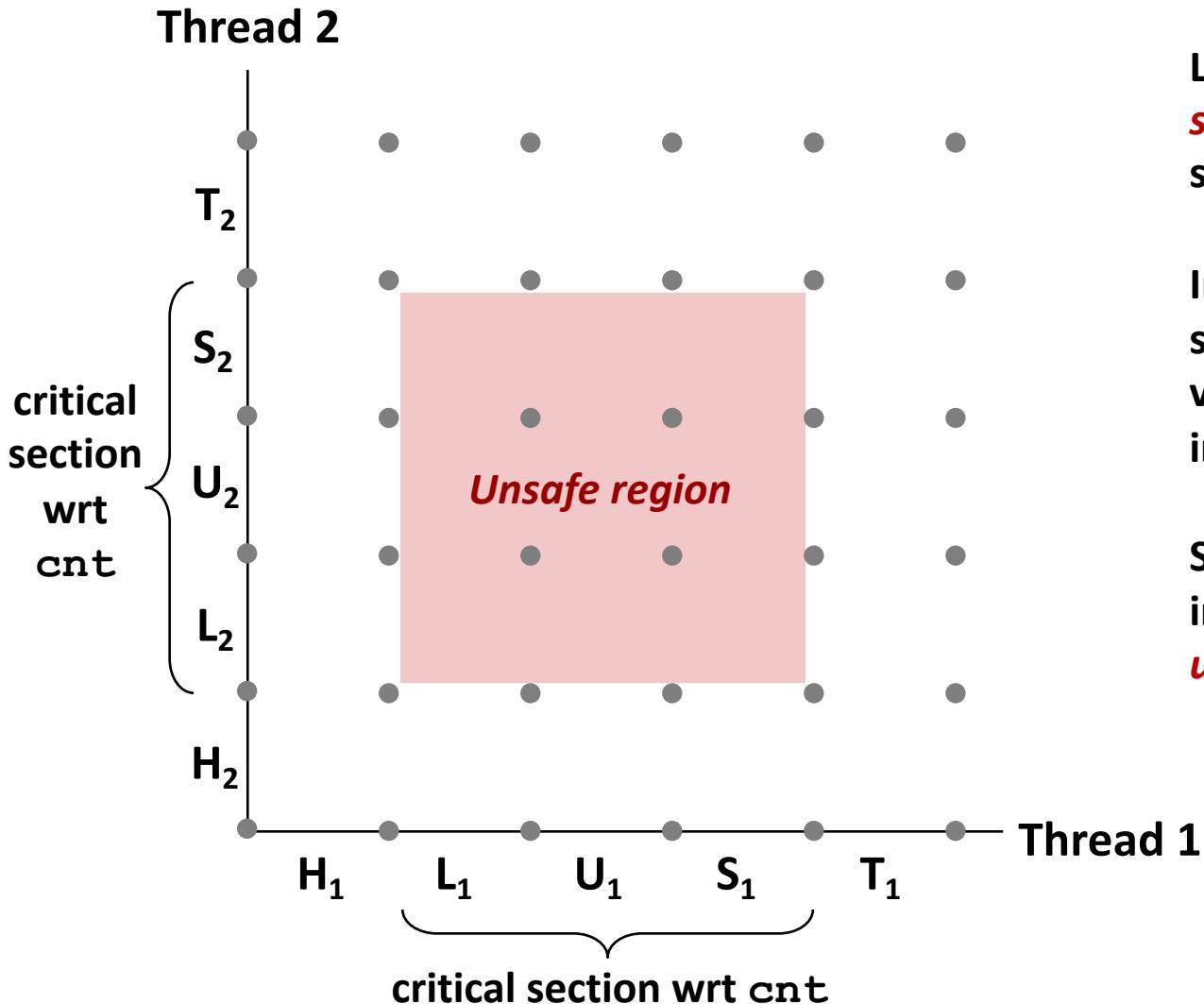


A **trajectory** is a sequence of legal state transitions that describes one possible concurrent execution of the threads.

Example:

$H_1, L_1, U_1, H_2, L_2, S_1, T_1, U_2, S_2, T_2$

Critical Sections and Unsafe Regions

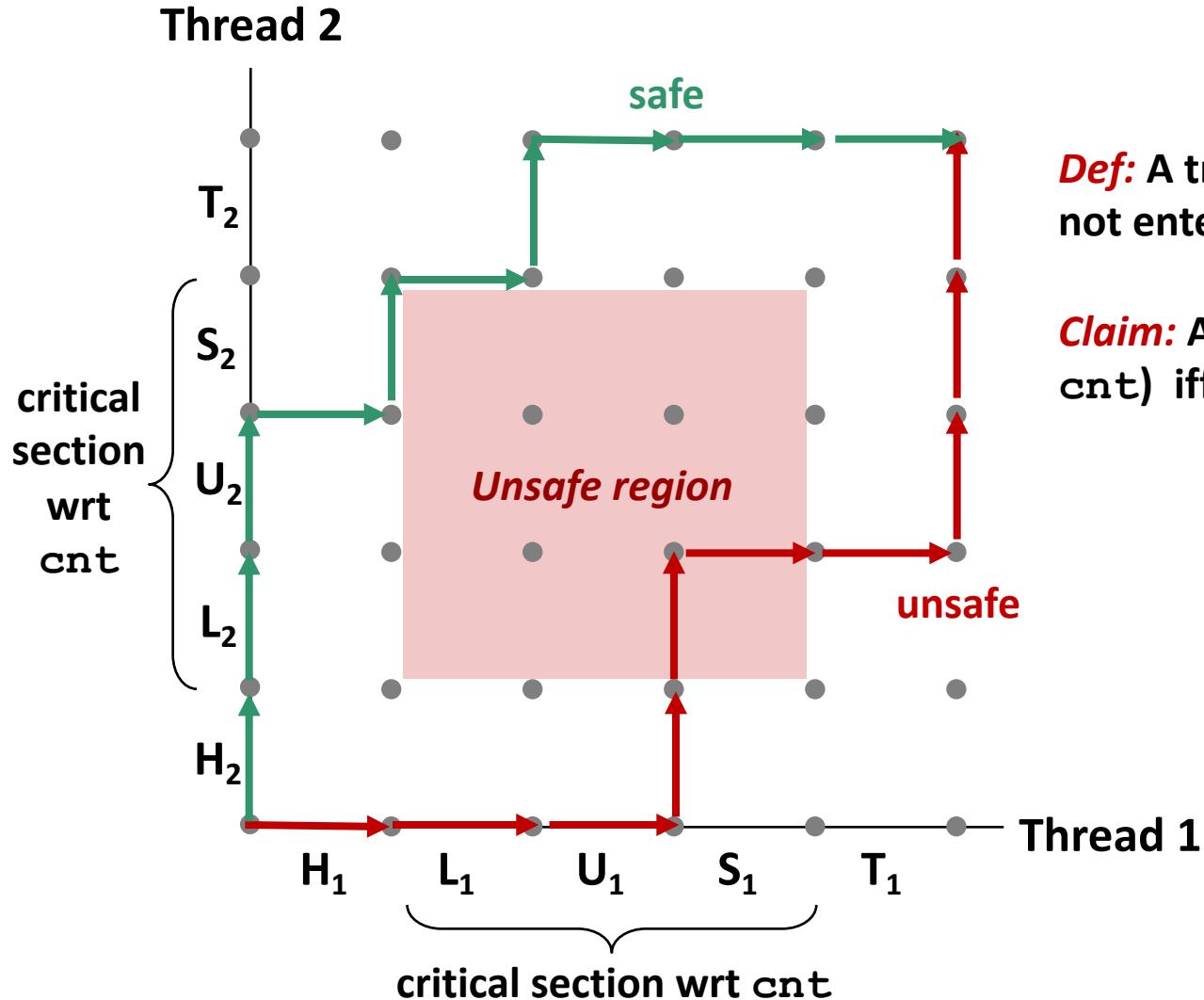


L, U, and S form a ***critical section*** with respect to the shared variable cnt

Instructions in critical sections (wrt some shared variable) should not be interleaved

Sets of states where such interleaving occurs form *unsafe regions*

Critical Sections and Unsafe Regions



Def: A trajectory is **safe** iff it does not enter any unsafe region

Claim: A trajectory is **correct (wrt cnt)** iff it is safe

badcnt.c: Improper Synchronization

```

/* Global shared variable */
volatile long cnt = 0; /* Counter */

int main(int argc, char **argv)
{
    long niters;
    pthread_t tid1, tid2;

    niters = atoi(argv[1]);
    Pthread_create(&tid1, NULL,
                   thread, &niters);
    Pthread_create(&tid2, NULL,
                   thread, &niters);
    Pthread_join(tid1, NULL);
    Pthread_join(tid2, NULL);

    /* Check result */
    if (cnt != (2 * niters))
        printf("BOOM! cnt=%ld\n", cnt);
    else
        printf("OK cnt=%ld\n", cnt);
    exit(0);
}

```

badcnt.c

```

/* Thread routine */
void *thread(void *vargp)
{
    long i, niters =
        *((long *)vargp);

    for (i = 0; i < niters; i++)
        cnt++;

    return NULL;
}

```

Variable	main	thread1	thread2
cnt	yes*	yes	yes
niters.m	yes	no	no
tid1.m	yes	no	no
i.1	no	yes	no
i.2	no	no	yes
niters.1	no	yes	no
niters.2	no	no	yes

Enforcing Mutual Exclusion

- **Question:** How can we guarantee a safe trajectory?
- **Answer:** We must *synchronize* the execution of the threads so that they can never have an unsafe trajectory.
 - i.e., need to guarantee *mutually exclusive access* for each critical section.
- **Classic solution:**
 - Semaphores (Edsger Dijkstra)

Today

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- Sharing
- Mutual exclusion
- Semaphores
- Producer-Consumer Synchronization

Semaphores

- **Semaphore:** non-negative global integer synchronization variable. Manipulated by P and V operations.
- $P(s)$
 - If s is nonzero, then decrement s by 1 and return immediately.
 - Test and decrement operations occur atomically (indivisibly)
 - If s is zero, then suspend thread until s becomes nonzero and the thread is restarted by a V operation.
 - After restarting, the P operation decrements s and returns control to the caller.
- $V(s)$:
 - Increment s by 1.
 - Increment operation occurs atomically
 - If there are any threads blocked in a P operation waiting for s to become non-zero, then restart exactly one of those threads, which then completes its P operation by decrementing s .
- **Semaphore invariant: $(s \geq 0)$**

Semaphores

- **Semaphore:** non-negative global integer synchronization variable
- Manipulated by **P** and **V** operations:
 - $P(s)$: [**while** ($s == 0$) **wait()** ; $s--$;]
 - Dutch for “Proberen” (test)
 - $V(s)$: [$s++$;]
 - Dutch for “Verhogen” (increment)
- OS kernel guarantees that operations between brackets [] are executed indivisibly
 - Only one P or V operation at a time can modify s .
 - When **while** loop in P terminates, only that P can decrement s
- **Semaphore invariant:** $(s \geq 0)$

C Semaphore Operations

Pthreads functions:

```
#include <semaphore.h>

int sem_init(sem_t *s, 0, unsigned int val); /* s = val */
int sem_wait(sem_t *s); /* P(s) */
int sem_post(sem_t *s); /* V(s) */
```

CS:APP wrapper functions:

```
#include "csapp.h"

void P(sem_t *s); /* Wrapper function for sem_wait */
void V(sem_t *s); /* Wrapper function for sem_post */
```

badcnt.c: Improper Synchronization

```

/* Global shared variable */
volatile long cnt = 0; /* Counter */

int main(int argc, char **argv)
{
    long niters;
    pthread_t tid1, tid2;

    niters = atoi(argv[1]);
    Pthread_create(&tid1, NULL,
                   thread, &niters);
    Pthread_create(&tid2, NULL,
                   thread, &niters);
    Pthread_join(tid1, NULL);
    Pthread_join(tid2, NULL);

    /* Check result */
    if (cnt != (2 * niters))
        printf("BOOM! cnt=%ld\n", cnt);
    else
        printf("OK cnt=%ld\n", cnt);
    exit(0);
}

```

badcnt.c

```

/* Thread routine */
void *thread(void *vargp)
{
    long i, niters =
        *((long *)vargp);

    for (i = 0; i < niters; i++)
        cnt++;

    return NULL;
}

```

How can we fix this using semaphores?

Using Semaphores for Mutual Exclusion

■ Basic idea:

- Associate a unique semaphore *mutex*, initially 1, with each shared variable (or related set of shared variables).
- Surround corresponding critical sections with $P(\text{mutex})$ and $V(\text{mutex})$ operations.

■ Terminology:

- *Binary semaphore*: semaphore whose value is always 0 or 1
- *Mutex*: binary semaphore used for mutual exclusion
 - P operation: “*locking*” the mutex
 - V operation: “*unlocking*” or “*releasing*” the mutex
 - “*Holding*” a mutex: locked and not yet unlocked.
- *Counting semaphore*: used as a counter for set of available resources.

goodcnt.c: Proper Synchronization

- Define and initialize a mutex for the shared variable cnt:

```

volatile long cnt = 0; /* Counter */
sem_t mutex;           /* Semaphore that protects cnt */

sem_init(&mutex, 0, 1); /* mutex = 1 */

```

- Surround critical section with *P* and *V*:

```

for (i = 0; i < niters; i++) {
    P(&mutex);
    cnt++;
    V(&mutex);
}

```

goodcnt.c

```

linux> ./goodcnt 10000
OK cnt=20000
linux> ./goodcnt 10000
OK cnt=20000
linux>

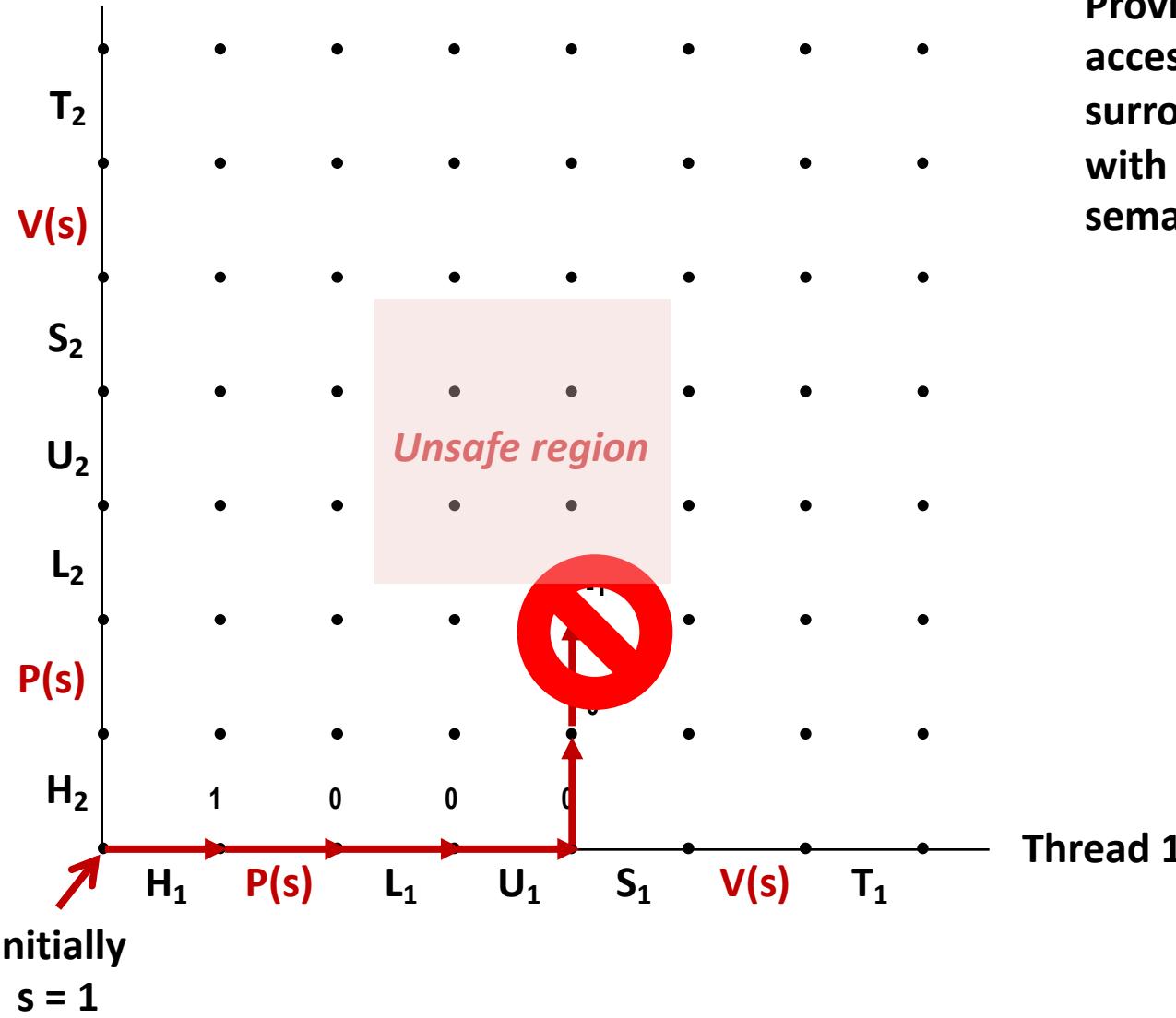
```

Warning: It's orders of magnitude slower than badcnt.c.

Function	badcnt	goodcnt
Time (ms) niters = 10^6	12	450
Slowdown	1.0	37.5

Why Mutexes Work

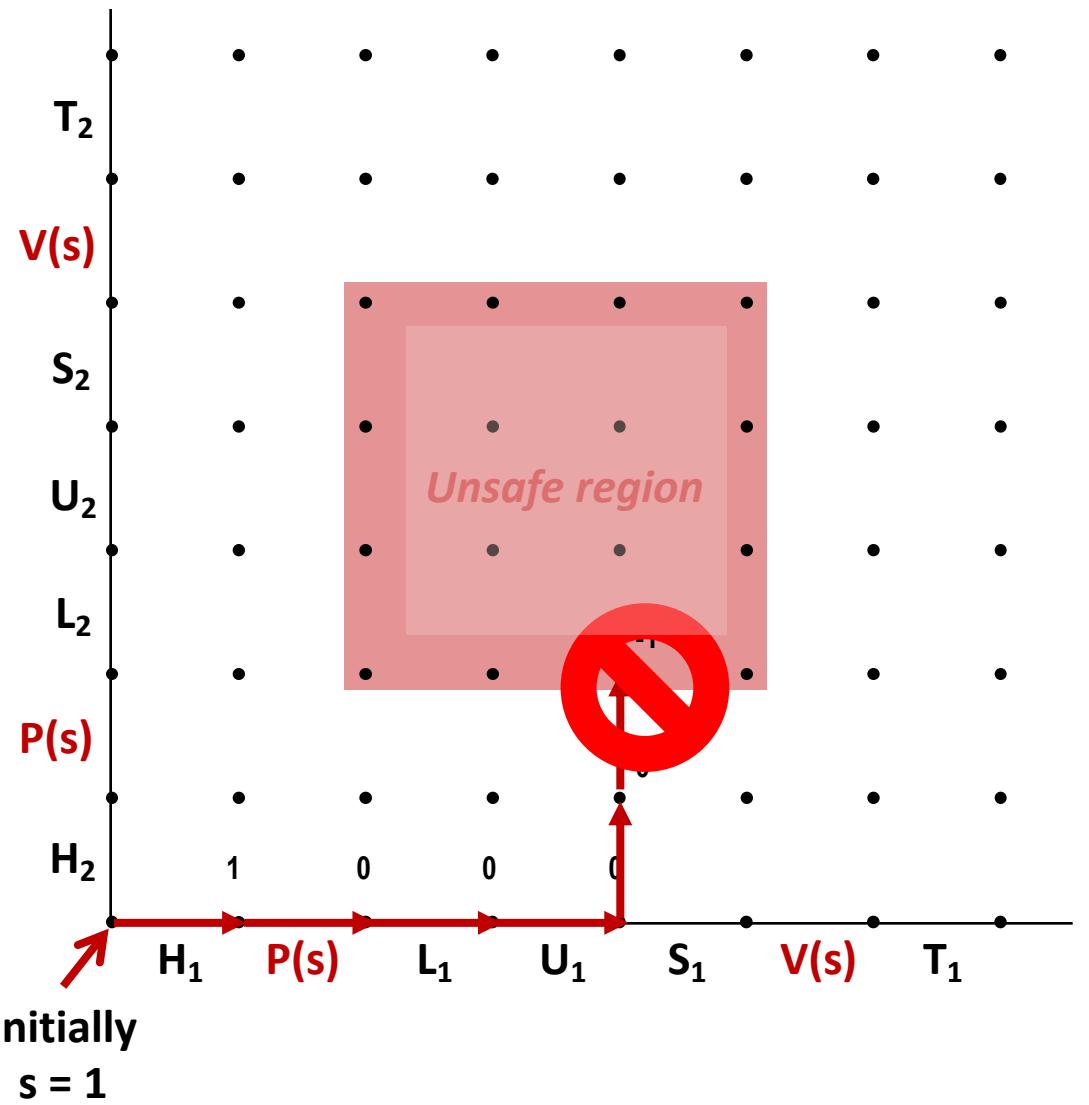
Thread 2



Provide mutually exclusive access to shared variable by surrounding critical section with P and V operations on semaphore s (initially set to 1)

Why Mutexes Work

Thread 2

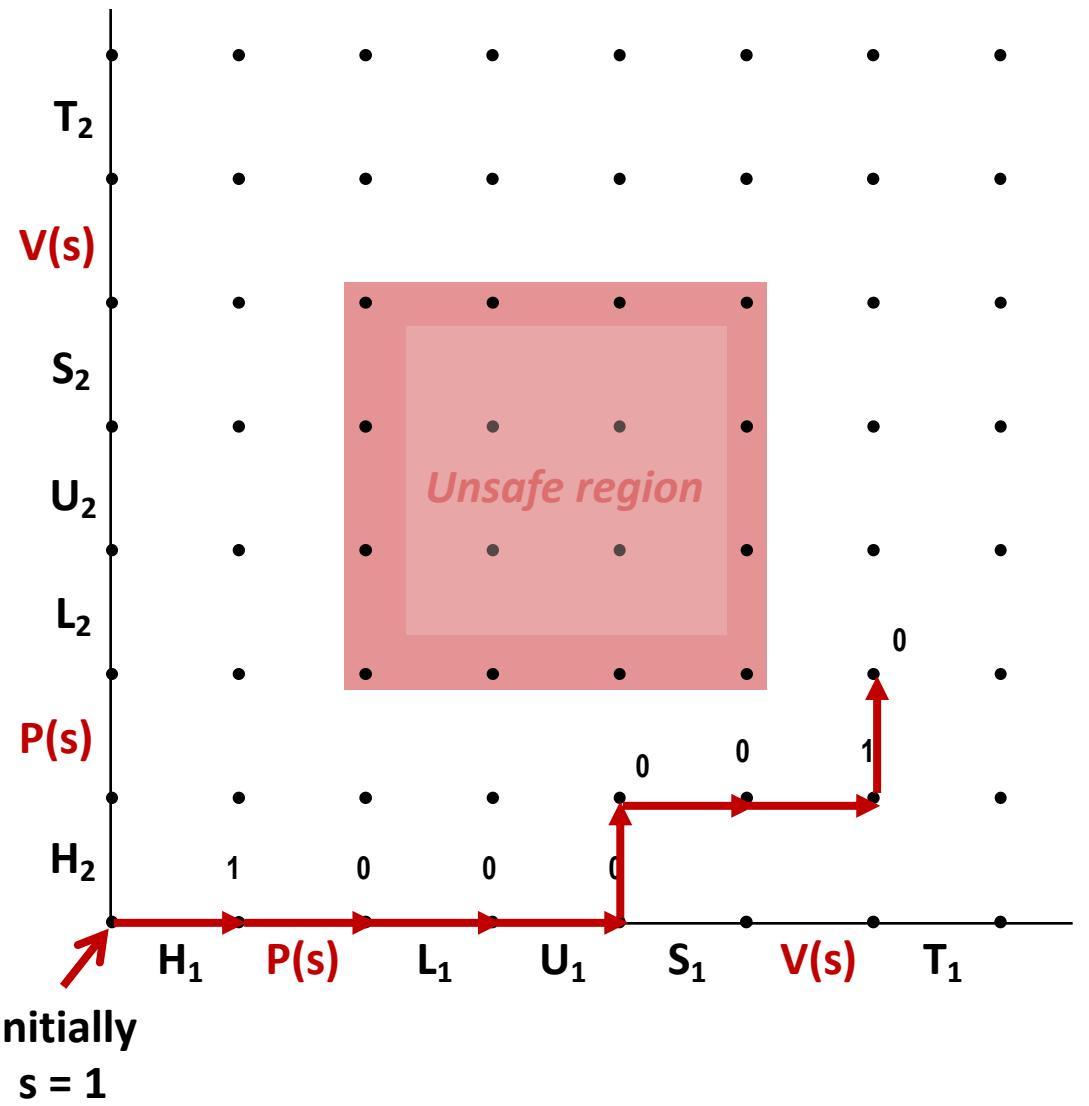


Provide mutually exclusive access to shared variable by surrounding critical section with *P* and *V* operations on semaphore *s* (initially set to 1)

Semaphore invariant creates a *forbidden region* that encloses unsafe region and that cannot be entered by any trajectory.

Why Mutexes Work

Thread 2

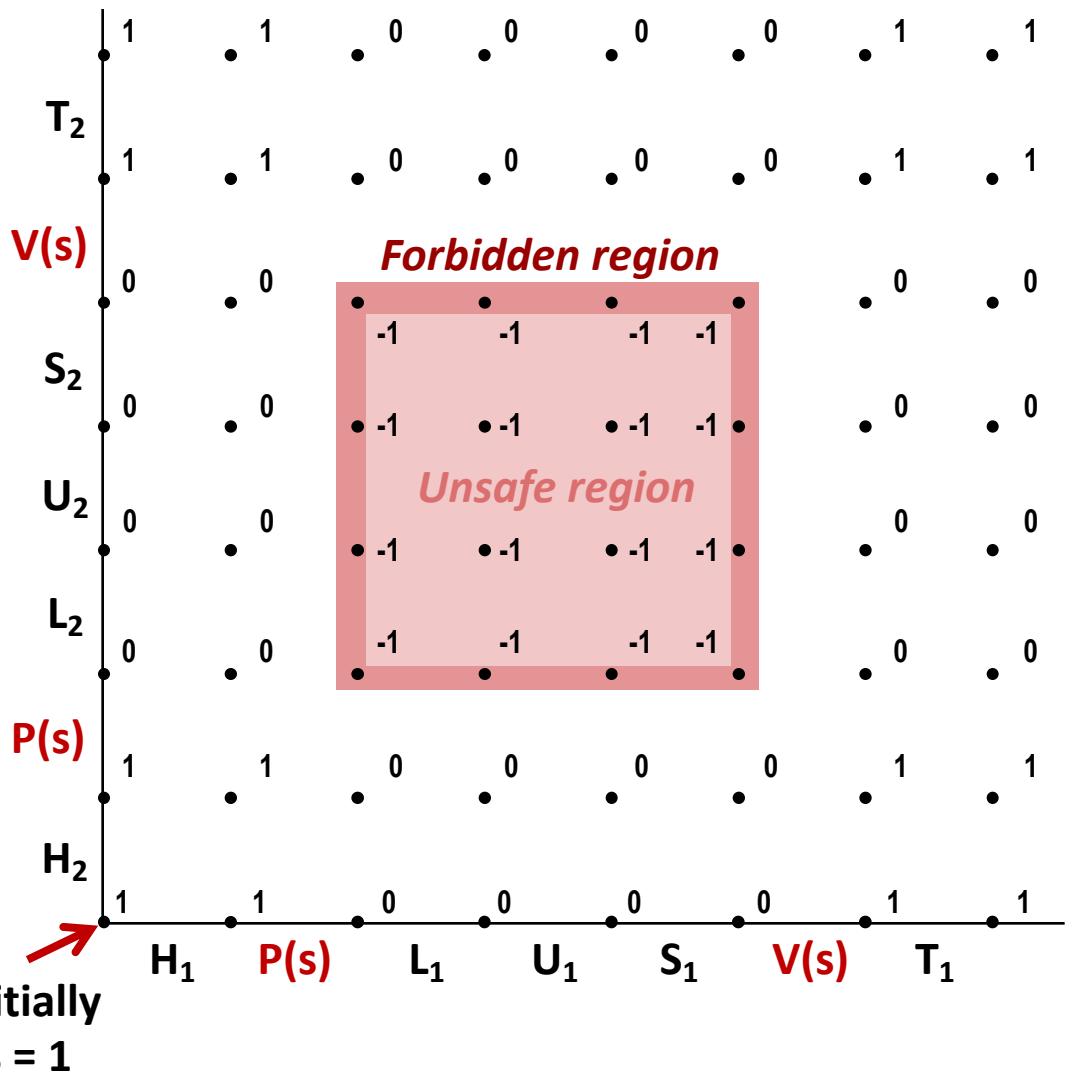


Provide mutually exclusive access to shared variable by surrounding critical section with P and V operations on semaphore s (initially set to 1)

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Why Mutexes Work

Thread 2



Provide mutually exclusive access to shared variable by surrounding critical section with P and V operations on semaphore s (initially set to 1)

Semaphore invariant creates a *forbidden region* that encloses unsafe region and that cannot be entered by any trajectory.

Enforcing Mutual Exclusion

- **Mutex is special case of semaphore**
 - Value either 0 or 1
- **Pthreads provides `pthread_mutex_t`**
 - Operations: lock, unlock
- **Recommended over general semaphores when appropriate**

goodmcnt.c: Mutex Synchronization

- Define and initialize a mutex for the shared variable cnt:

```

volatile long cnt = 0; /* Counter */
pthread_mutex_t mutex;
pthread_mutex_init(&mutex, NULL); // No special attributes

```

- Surround critical section with *lock* and *unlock*:

```

for (i = 0; i < niters; i++) {
    pthread_mutex_lock(&mutex);
    cnt++;
    pthread_mutex_unlock(&mutex);
}

```

goodcnt.c

```

linux> ./goodmcnt 10000
OK cnt=20000
linux> ./goodmcnt 10000
OK cnt=20000
linux>

```

Function	badcnt	goodcnt	goodmcnt
Time (ms) niters = 10^6	12	450	214
Slowdown	1.0	37.5	17.8

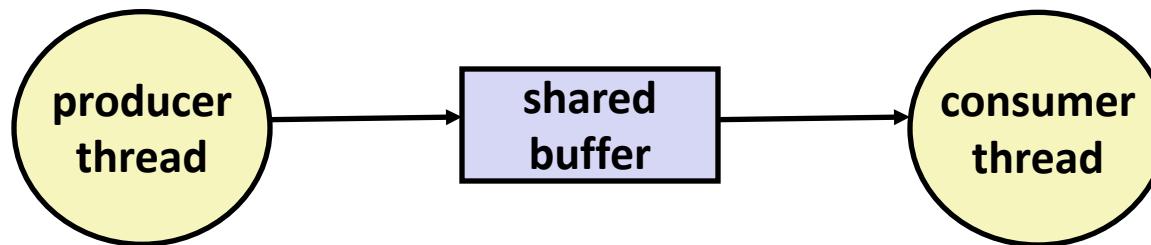
Today

- Threads review
- Sharing
- Mutual exclusion
- Semaphores
- Producer-Consumer Synchronization

Using Semaphores to Coordinate Access to Shared Resources

- **Basic idea: Thread uses a semaphore operation to notify another thread that some condition has become true**
 - Use counting semaphores to keep track of resource state.
 - Use binary semaphores to notify other threads.
- **The Producer-Consumer Problem**
 - Mediating interactions between processes that generate information and that then make use of that information

Producer-Consumer Problem



■ Common synchronization pattern:

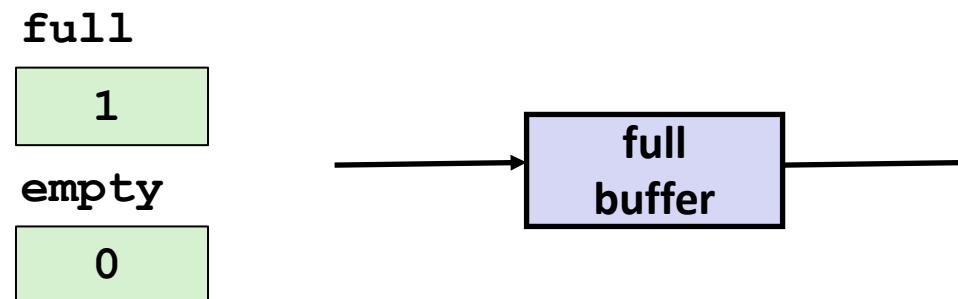
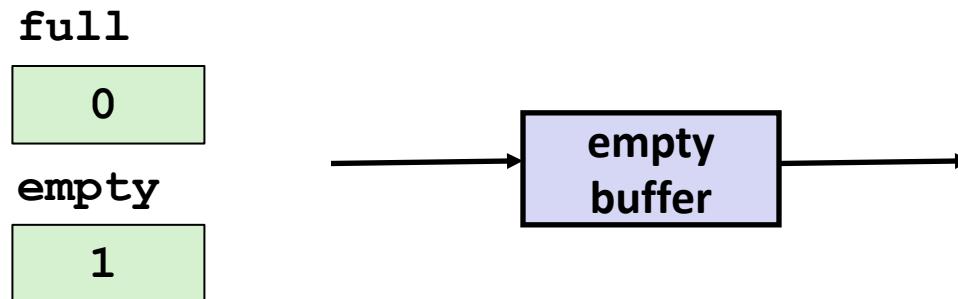
- Producer waits for empty *slot*, inserts item in buffer, and notifies consumer
- Consumer waits for *item*, removes it from buffer, and notifies producer

■ Examples

- Multimedia processing:
 - Producer creates video frames, consumer renders them
- Event-driven graphical user interfaces
 - Producer detects mouse clicks, mouse movements, and keyboard hits and inserts corresponding events in buffer
 - Consumer retrieves events from buffer and paints the display

Producer-Consumer on 1-element Buffer

- Maintain two semaphores: `full` + `empty`



Producer-Consumer on 1-element Buffer

```
#include "csapp.h"

#define NITERS 5

void *producer(void *arg);
void *consumer(void *arg);

struct {
    int buf; /* shared var */
    sem_t full; /* sems */
    sem_t empty;
} shared;
```

```
int main(int argc, char** argv) {
    pthread_t tid_producer;
    pthread_t tid_consumer;

    /* Initialize the semaphores */
    Sem_init(&shared.empty, 0, 1);
    Sem_init(&shared.full, 0, 0);

    /* Create threads and wait */
    Pthread_create(&tid_producer, NULL,
                  producer, NULL);
    Pthread_create(&tid_consumer, NULL,
                  consumer, NULL);

    Pthread_join(tid_producer, NULL);
    Pthread_join(tid_consumer, NULL);

    return 0;
}
```

Producer-Consumer on 1-element Buffer

Initially: empty==1, full==0

Producer Thread

```
void *producer(void *arg) {
    int i, item;

    for (i=0; i<NITERS; i++) {
        /* Produce item */
        item = i;
        printf("produced %d\n",
               item);

        /* Write item to buf */
        P(&shared.empty);
        shared.buf = item;
        V(&shared.full);
    }
    return NULL;
}
```

Consumer Thread

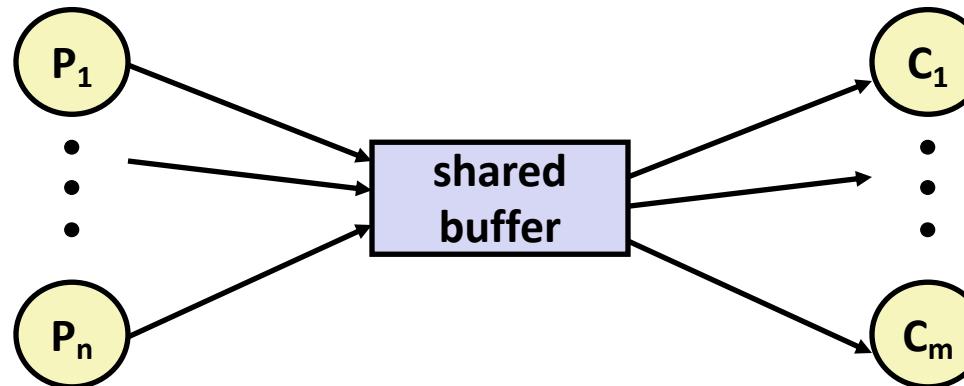
```
void *consumer(void *arg) {
    int i, item;

    for (i=0; i<NITERS; i++) {
        /* Read item from buf */
        P(&shared.full);
        item = shared.buf;
        V(&shared.empty);

        /* Consume item */
        printf("consumed %d\n", item);
    }
    return NULL;
}
```

Why 2 Semaphores for 1-Entry Buffer?

- Consider multiple producers & multiple consumers



- Producers will contend with each to get empty
- Consumers will contend with each other to get full

Producers

```
P(&shared.empty);  
shared.buf = item;  
V(&shared.full);
```

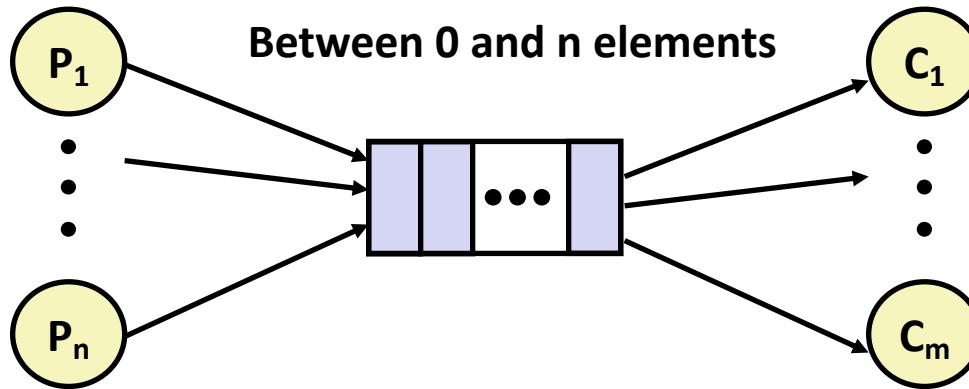
empty

full

Consumers

```
P(&shared.full);  
item = shared.buf;  
V(&shared.empty);
```

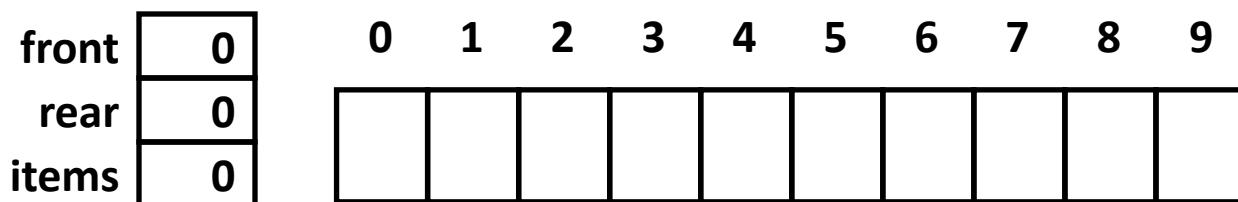
Producer-Consumer on an n -element Buffer



- Implemented using a shared buffer package called `sbuf`.

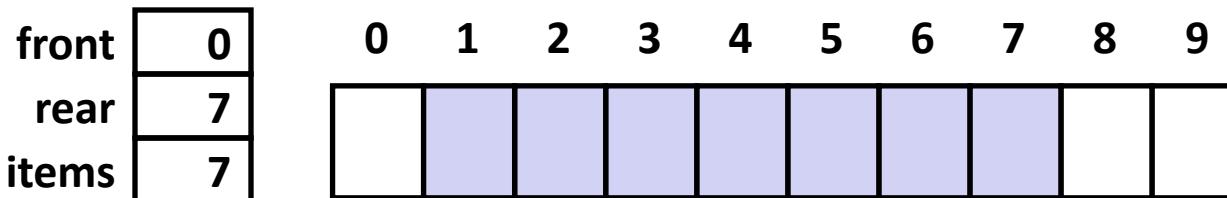
Circular Buffer (n = 10)

- Store elements in array of size n
- items: number of elements in buffer
- Empty buffer:
 - front = rear
- Nonempty buffer
 - rear: index of most recently inserted element
 - front: (index of next element to remove – 1) mod n
- Initially:

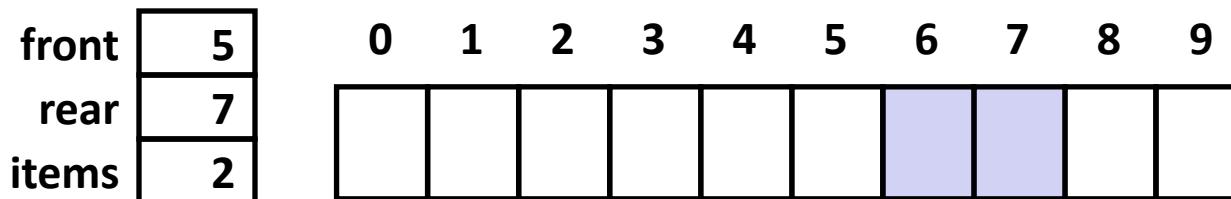


Circular Buffer Operation (n = 10)

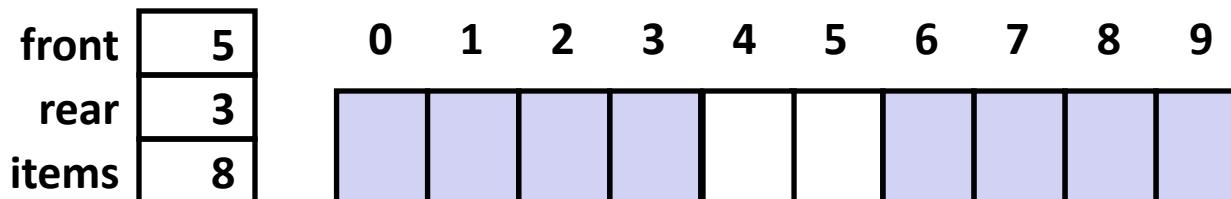
■ Insert 7 elements



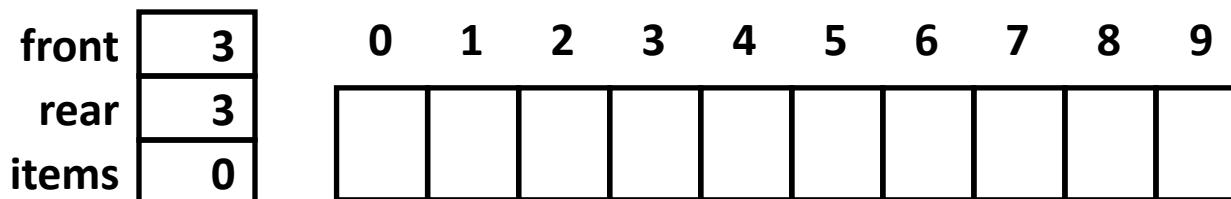
■ Remove 5 elements



■ Insert 6 elements



■ Remove 8 elements



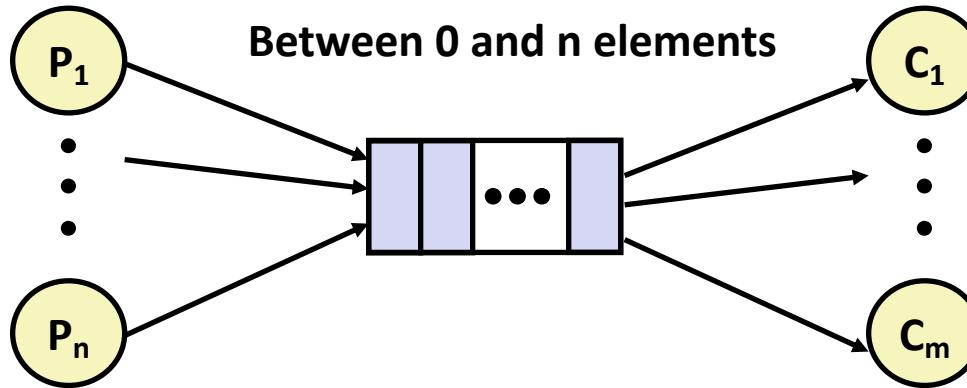
Sequential Circular Buffer Code

```
init(int v)
{
    items = front = rear = 0;
}

insert(int v)
{
    if (items >= n)
        error();
    if (++rear >= n) rear = 0;
    buf[rear] = v;
    items++;
}

int remove()
{
    if (items == 0)
        error();
    if (++front >= n) front = 0;
    int v = buf[front];
    items--;
    return v;
}
```

Producer-Consumer on an n -element Buffer



- **Requires a mutex and two counting semaphores:**

- mutex: enforces mutually exclusive access to the buffer and counters
- slots: counts the available slots in the buffer
- items: counts the available items in the buffer

- **Makes use of general semaphores**

- Will range in value from 0 to n

sbuf Package - Declarations

```
#include "csapp.h"

typedef struct {
    int *buf;          /* Buffer array */ 
    int n;             /* Maximum number of slots */ 
    int front;         /* buf[front+1 (mod n)] is first item */ 
    int rear;          /* buf[rear] is last item */ 
    sem_t mutex;       /* Protects accesses to buf */ 
    sem_t slots;       /* Counts available slots */ 
    sem_t items;       /* Counts available items */ 
} sbuf_t;

void sbuf_init(sbuf_t *sp, int n);
void sbuf_deinit(sbuf_t *sp);
void sbuf_insert(sbuf_t *sp, int item);
int sbuf_remove(sbuf_t *sp);
```

sbuf.h

sbuf Package - Implementation

Initializing and deinitializing a shared buffer:

```
/* Create an empty, bounded, shared FIFO buffer with n slots */
void sbuf_init(sbuf_t *sp, int n)
{
    sp->buf = Calloc(n, sizeof(int));
    sp->n = n;                                /* Buffer holds max of n items */
    sp->front = sp->rear = 0;      /* Empty buffer iff front == rear */
    Sem_init(&sp->mutex, 0, 1); /* Binary semaphore for locking */
    Sem_init(&sp->slots, 0, n); /* Initially, buf has n empty slots */
    Sem_init(&sp->items, 0, 0); /* Initially, buf has zero items */
}

/* Clean up buffer sp */
void sbuf_deinit(sbuf_t *sp)
{
    Free(sp->buf);
}
```

sbuf Package - Implementation

Inserting an item into a shared buffer:

```
/* Insert item onto the rear of shared buffer sp */
void sbuf_insert(sbuf_t *sp, int item)
{
    P(&sp->slots);                      /* Wait for available slot */
    P(&sp->mutex);                      /* Lock the buffer */
    if (++sp->rear >= sp->n)           /* Increment index (mod n) */
        sp->rear = 0;
    sp->buf[sp->rear] = item;           /* Insert the item */
    V(&sp->mutex);                      /* Unlock the buffer */
    V(&sp->items);                      /* Announce available item */
}
```

sbuc.c

sbuf Package - Implementation

Removing an item from a shared buffer:

```
/* Remove and return the first item from buffer sp */
int sbuf_remove(sbuf_t *sp)
{
    int item;
    P(&sp->items);                      /* Wait for available item */
    P(&sp->mutex);                      /* Lock the buffer */
    if (++sp->front >= sp->n)          /* Increment index (mod n) */
        sp->front = 0;
    item = sp->buf[sp->front];          /* Remove the item */
    V(&sp->mutex);                      /* Unlock the buffer */
    V(&sp->slots);                      /* Announce available slot */
    return item;
}
```

sbuf.c

Demonstration

- See program `produce-consume.c` in code directory
- 10-entry shared circular buffer
- 5 producers
 - Agent i generates numbers from $20*i$ to $20*i - 1$.
 - Puts them in buffer
- 5 consumers
 - Each retrieves 20 elements from buffer
- Main program
 - Makes sure each value between 0 and 99 retrieved once

Summary

- Programmers need a clear model of how variables are shared by threads.
- Variables shared by multiple threads must be protected to ensure mutually exclusive access.
- Semaphores are a fundamental mechanism for enforcing mutual exclusion
 - And can also support producer-consumer synchronization