

## LGT4HEP Class 2

Q.) How to sample arbitrary distribution?

- \* Input is a sequence of random no.s uniformly distributed b/w 0-1.
- \* Exactly
- \* function of a random variable is also a random variable
- \* we define a probability distribution function PDF for continuous case,

$P_X(x)$  - PDF      in  $x \in [a, b]$

$$P(X \leq x) \equiv F_X(x) = \int_a^x dx P_X(x)$$

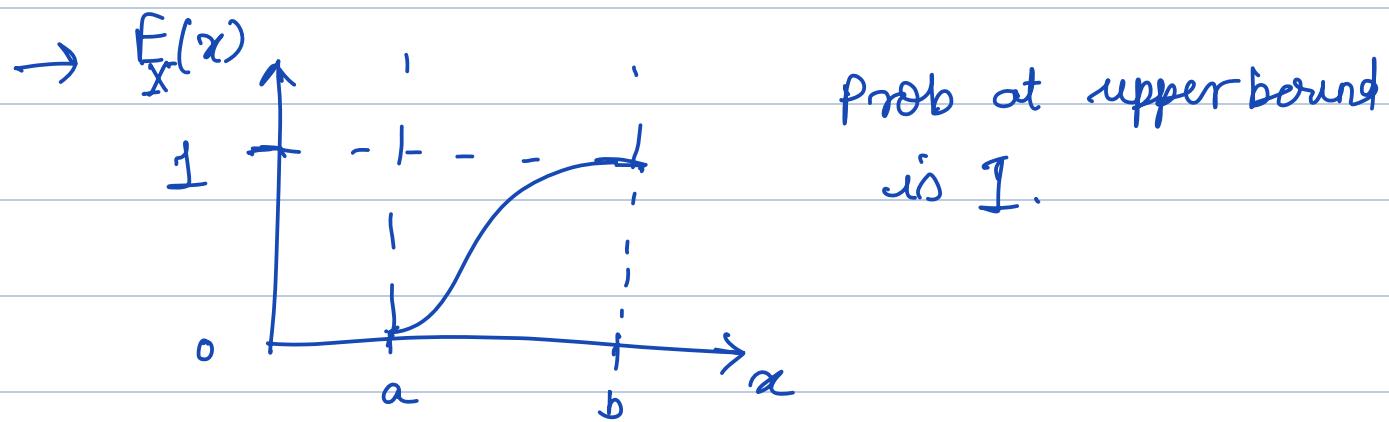
Random Label  
Value                          ↓  
Probability that  $X$  is  
- CDF - lower than a chosen  $x$ .

Q) How can we sample PDF  $P_X(x)$ ?

Q) What is  $F_X(x)$ ?

→ monotonic fn of  $x$

→ PDFs are normalized such that the total area is 1



We call  $Y = F_X(X)$  is a random variable

Q) How is  $Y$  distributed?

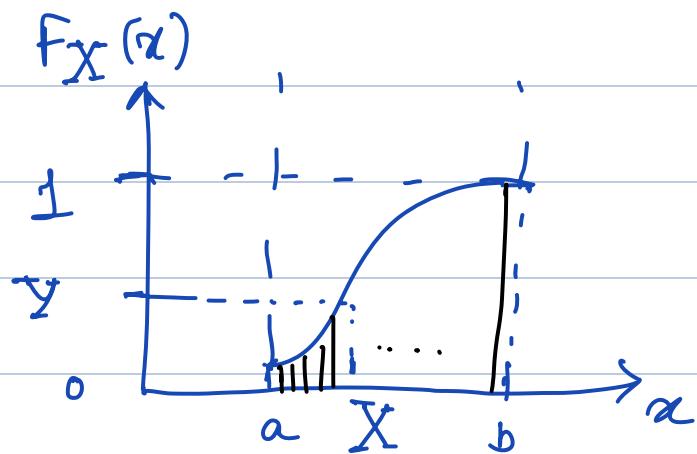
i.e. What is this function  $F_Y(y) = ?$

By definition,  $F_Y(y) = P(Y \leq y)$

$$Y, y \in [0, 1]$$

→ switch to discrete selection of intervals

$$Y = F_{X_i}(x)$$



$$F_Y(y) = P(Y \leq y) = P(X_i \leq x) = F_X(x) = y$$

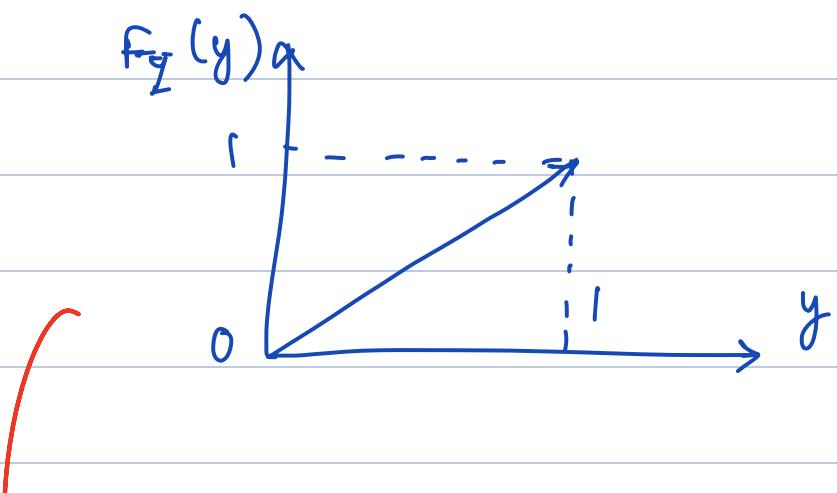
$\hookrightarrow$  Sequence

The CDF for variable  $y$

$$\therefore F_Y(y) = y$$

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∴ we know that:-

$$P_Y(y) = \frac{dF_Y(y)}{dy} = 1$$

→ The random variable  $\bar{Y}$  is uniformly distributed.

→ We now want to map backwards,  
 $\underline{X}$  is what I want to generate :

$$\underline{X} = F_X^{-1}(\bar{Y})$$

→  $\bar{Y}$  is uniform in  $[0, 1]$

$\underline{X}$  is from & distributed as  $P_{\underline{X}}(x)$

→ Some cases,  $F_X(\bar{Y})$  is invertible.

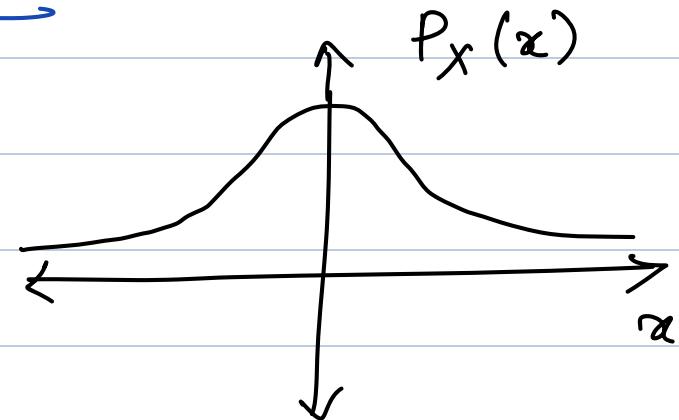
it is easy to turn sequence of uniform random variables in  $0-1$  range into a distributed set of random no.'s.

These are prerequisites to more complicated distributions.

This is called CDF Inversion method.

e.g. Cauchy Distribution:

$$P_{\bar{X}}(x) = \frac{1}{\pi} \cdot \frac{1}{1+x^2}$$



$$x \in (-\infty, \infty)$$

$$\Rightarrow Y = F_{\bar{X}}(x) = \int_{-\infty}^x dx' \frac{1}{\pi} \cdot \frac{1}{1+x'^2}$$

$$= \left. \frac{1}{\pi} \arctan(x') \right|_{-\infty}^{x'}$$

$$= \frac{1}{\pi} \arctan(x) + \frac{1}{2}$$

$$\Rightarrow \bar{X} = \tan \left( \pi Y - \frac{\pi}{2} \right), \quad Y \in [0, 1]$$

=====

Q) How to sample more complex Distributions?

$$\tilde{P}(x) \sim (1-x^2)^{3/2}, \quad x \in [-1, 1]$$

→ integrable but not trivial.

$$\int_{-1}^x \tilde{P}(z) dz = \frac{1}{8} \left[ x (5 - 2x^2) \sqrt{1-x^2} \right.$$

$$+ 3 \arcsin(x) + \left. \frac{3\pi}{2} \right] \quad \text{usually worse than this}$$

↪ Normalized distribution

$$P(x)$$

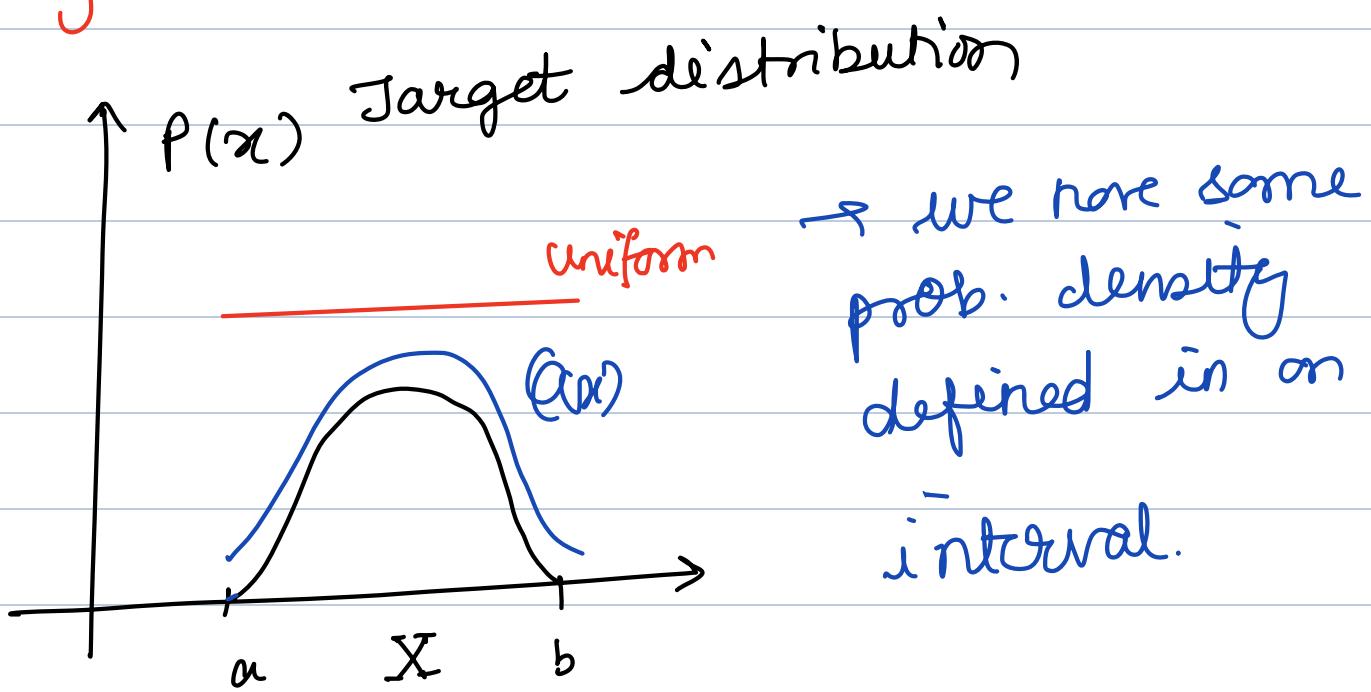
$$= \frac{8}{3\pi} (1-x^2)^{3/2}$$

→ It is not so easy to invert this CDFs can be done but will have to solve the N.L. eq every time we produce a variable.

→ Practical way around is to create a table around it, but impractical

→ Some other way?

Rejection method. : Heat Bath



- Generate a random variable distributed in this way.
- $P(x) = \text{Target Dist.}$
- Try to find an auxiliary / proposal distribution.  $\varrho(x)$   
 (which can be differently normalized.)
- We need a proposal distribution such that CDF can be inverted.

The algorithm :-

- ① Draw  $X$  from  $\varrho(x)$
- ② Draw a uniform  $r \in [0, 1]$  (random number)
- ③ If  $r \leq P(x)/\varrho(x)$ , take  $X$ , otherwise repeat from step ①.

→ Loop breaks only when we generated a new value.

→ We want to check the following probability for a continuous distributions:

$$P(X \leq x) = \sum_{x' \leq x} Q_X(x') \cdot \Delta x$$

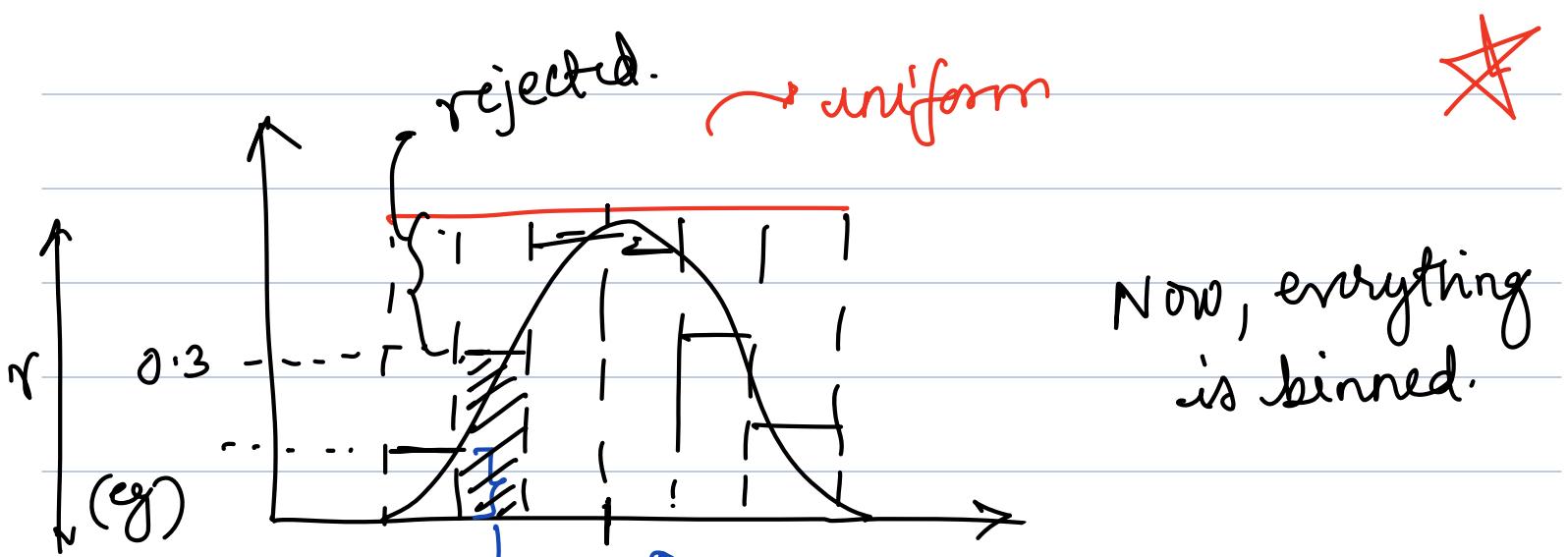
“or”      P-Density      width “and”       $\frac{P(x')}{Q(x')}$

Probability of  $X$  to be in some bin around point  $x'$ .      Probability that the no. is generated & accepted.

$x'$  → running label

$a$  → label

This will generate random numbers from  $Q$ .



Now, everything is binned.



measuring the height at this point

→ Randomly deciding whether to take this number or not, but it is a probability

$$\frac{P(x)}{g(x)} = 0.3, \text{ then only } 30\% \text{ cases will be accepted.}$$

Accept everything  $\rightarrow$  Uniform distribution

Probability that condition ③ is satisfied is this ratio:  $P(x')/g(x')$

→ We need to hit every bin to the left of ' $x'$ , by generating variable from repeat until

$\varphi(x)$ , and accepted  
"and"

$$p(x')/\varphi(x') \xrightarrow{\Delta x \rightarrow 0} \int_a^x \varphi(x') dx$$

↑  
Target prob.  
density.

→ Algorithm indeed samples the target distribution  $P(x)$ .

→ Efficiency of the method is the area under the distribution

Ask

closer are  $\varphi$  to  $P$ , more efficient the method.

$$\text{efficiency : } \frac{\int \varphi(x) dx}{\int P(x) dx}$$

① ② ③

we have to repeat until  
the condition is satisfied.

→ This method would not scale up  
to a multidimensional distribution

→ Integration  $\rightarrow$  Inversion (analytically)  
Ridiculous for 10 dim.

→ But, Separable high dimensional distribution  
can be used.

→ For fermions, we need more  
sophisticated algorithms. This is  
still very powerful.

METROPOLIS

ALGORITHM:

- generic feature
- very imp. idea.

→ used as a sol<sup>n</sup> to obtain the transition Matrix T.  
Similar to rejection method.

① choose trial  $\tilde{x}^1$  (being at  $x$ )

from PDF called  $Q(x')$  or

generically  $Q(x', x)$ .

e.g. spin configuration where only  
1 change is seen,  $x'$  is changed,

but  $Q$  will realistically also have  
some dependence on the surrounding.

If  $Q(x', x)$  has no ' $x$ ' dependence, it  
produces independent  $x'$  (best case  
scenario)

So,  $Q$  has two arguments, the  
trial state and the previous state.

So, we have a trial configuration.

Then,

Accept  $x'$  ( $x' = \tilde{x}$ ) with

(2) probability :-

$$TA(\tilde{x}', x) = \min \left\{ 1, \frac{P(\tilde{x}')}{Q(\tilde{x}', x)} \right\}$$

Defining feature of the Metropolis

Alg. is that the acceptance prob.  
is a fn. of what we had before  
and what we are proposing.

$TA(\tilde{x}, x)$  should satisfy the

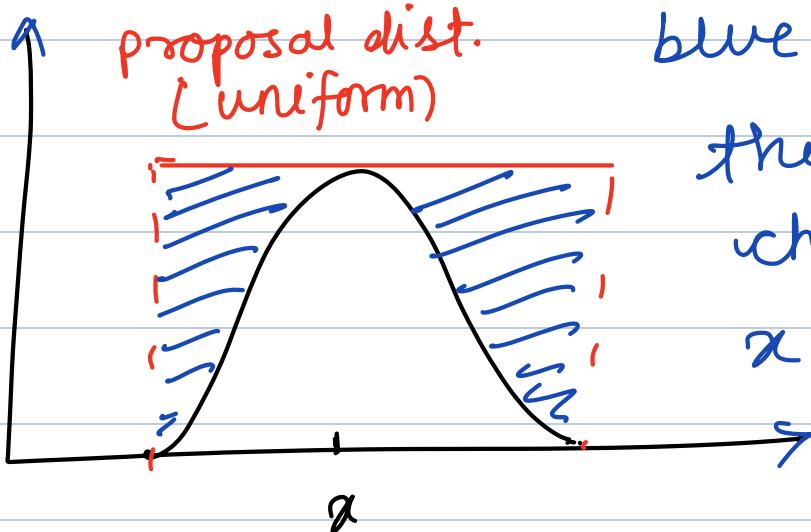
Detailed Balance equation.

(3) If rejected, take  $x' = x$ .  
Record the state we were in  
again as a new state.

If we think abt Rejection method

first :

→ carrying out the

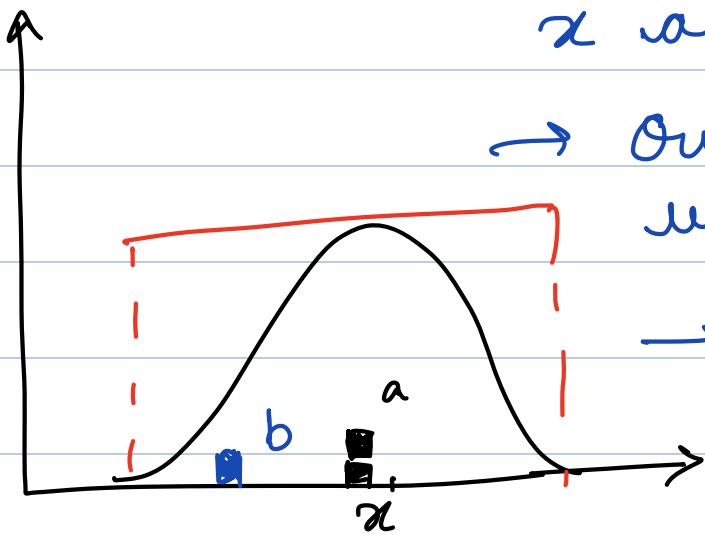


blue part, so  
there is a higher  
chance to be near  
 $x$  than the edges

Now, Metropolis is doing this in an  
entirely different way.

→ Let's say I ended up near  
 $x$  and put a brick (a)

→ Our proposal dist. is  
uniform again



→ choose some 'different'  
trial configuration (b)  
but the probability

to be in the old coefficient (a) is much  
higher than to move some where else so put  
2 bricks on (a).

- Histogram will be populated / built more where the probability is higher.
- and after multiple iteratns, we get the full distribution of histogram.

## Total transition Probability

= (Prob to generate  $\tilde{x}'$ )  $\times$  (Prob. to make  $T_A(\tilde{x}', x)$  accept)  
 "and"

$$T(x \rightarrow x') = Q(x', x) T_A(x', x)$$

We want to check that:

$$T(x \rightarrow x') P(x) = P(x) Q(x', x) \cdot$$

$\underbrace{\quad}_{\text{From of}} \quad \downarrow \quad \begin{matrix} \text{prob. of} \\ \text{transitioning} \\ \text{to } x' \end{matrix}$

$$\min \left\{ 1, \frac{P(x')}{Q(x', x)} \middle| \frac{P(x)}{Q(x, x')} \right\}$$

$$\Rightarrow \min \left\{ P(x) Q(x', x), P(x') Q(x, x') \right\}$$

$$= \min \left\{ \frac{P(x)Q(x', x)}{P(x')Q(x, x')}, 1 \right\} \cdot P(x')Q(x, x')$$

$$= T(x' \rightarrow x) \cdot P(x')$$

} RHS of detailed balance eqn.

At this early we assume that  $Q$  is symm.

If  $Q$  is symmetric,

$$Q(x, x') = Q(x', x), \text{ but, in general,}$$

$$Q(x, x') = Q(x', x) \sim 1$$

$$\Rightarrow T_A = \min \left\{ 1, \frac{P(x')}{P(x)} \right\}$$

$$P(x) \sim \exp \left\{ -\beta E(\sigma) \right\}$$

spin configuration ↑

$$\Rightarrow T_A = \min \left\{ 1, \exp \left\{ -\beta (E(\sigma') - E(\sigma)) \right\} \right\}$$

If  $E[\sigma'] < E(\sigma)$ , of the new conf.  
 ends up decreasing energy, it's always accepted.  
 $\Rightarrow$  always Accepted

But,  $E[\sigma'] > E(\sigma)$ ,

$\Rightarrow$  Conditionally accepted.

A real distinctive feature of the Metropolis algorithm different from ODF inversion / Rejection method is that we have to know some normalization for the later 2.

$$P(x) = \frac{1}{Z} \cdot e^{-\beta E[\sigma]} , Z = \sum_{\{\sigma\}} e^{-\beta E[\sigma]} \quad \text{partition fn.}$$

$\rightarrow$  Because of the way transition prob. is defined, overall normalization cancels out, so it's enough to have the relative weights and the term.

$\rightarrow$  It is guaranteed to equilibrate to the stationary distribution.

- This is a powerful feature as I don't need to know the overall normalization to be able to sample that distribution.
- For any realistic system, the overall normalization is a non-trivially hard to get, it's the partition fn. calculated.
- For a decent acceptance rate, one would need some proposal distribution which is either with the CDF inversion method / some other method where we can control and produce things quickly.

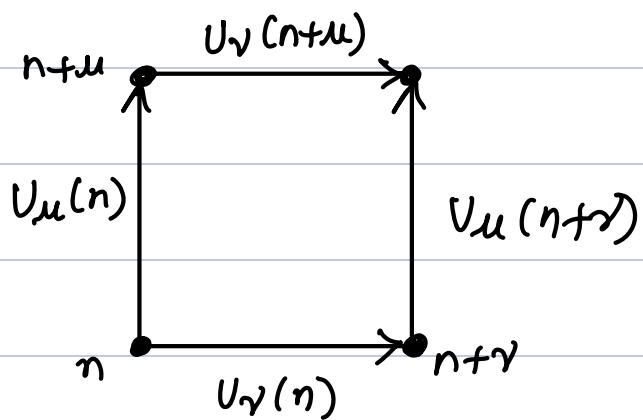
# $SU(N_c)$ Pure gauge Theory

→ The Path Integral on the lattice

$$Z = \int \mathcal{D}[U] e^{-S_G[U]},$$

$$S_G[U] = \frac{\beta}{N_c} \sum_{n \in \Lambda} \sum_{\mu < \nu} \text{Re} \Im \{ \text{Tr} \{ U - U_{\mu\nu}(n) \} \}$$

→ Plaquette:  $U_{\mu\nu}(n) = U_\mu(n) U_\nu(n + \hat{\mu}) U_\mu^+(n + \nu) U_\nu^+(n)$



Staples:

→ Consider a link  $U_\mu(n)$  and what plaquettes it contributes to :-

$U_{\mu\nu}(n), U_{\mu\nu}(n-\nu)$  for any  $\nu \neq \mu$

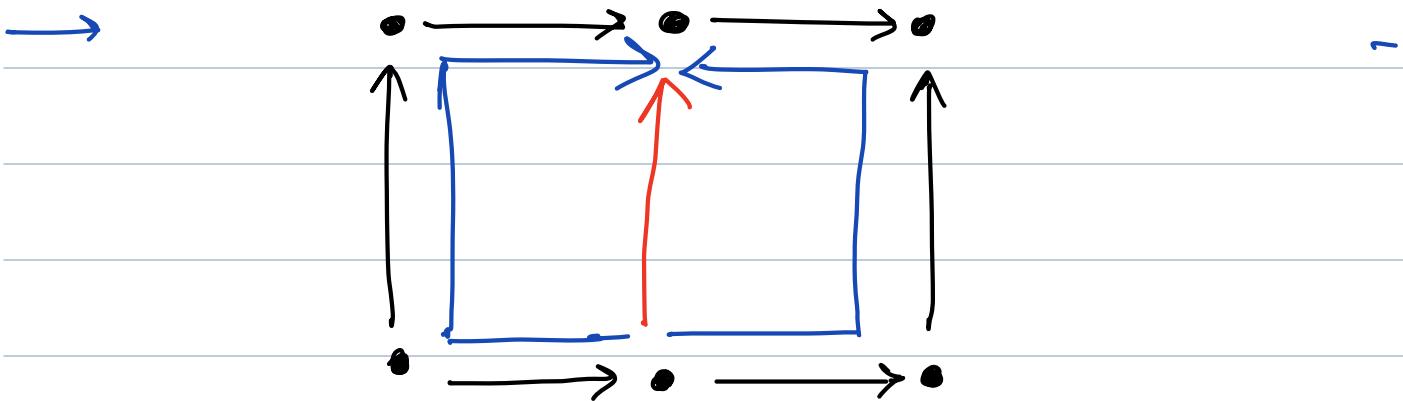
→ Rewriting contribution to the action differently:

$$\text{ReTr} \{ U_{\mu\nu}(n) \} = \text{ReTr} \{ S_{\mu,+\nu}^+(n) U_\mu(n) \}$$

$$\text{ReTr} \{ U_{\mu\nu}(n-\nu) \} = \text{ReTr} \{ S_{\mu,-\nu}^+(n) U_\mu(n) \}$$

$$S_{\mu,+\nu}(n) = U_\nu(n) U_\mu(n+\nu) U_\nu^+(n+\mu)$$

$$S_{\mu,-\nu}(n) = U_\nu^+(n-\nu) U_\mu(n-\nu) U_\nu(n-\nu+\mu)$$



→  $SU(2)$  gauge theory.

→ The contribution to the action for  $U_\mu(n)$ :

$$S_g [U_\mu(n)] \sim -\frac{\beta}{N_c} \text{Re} \text{Tr} \{ \tilde{S}_\mu^+(n) U_\mu(n) \}$$

$$\tilde{S}_\mu(n) = \sum_{\nu \neq \mu} (S_{\mu+\nu}(n) + S_{\mu-\nu}(n))$$

→  $\tilde{S}_\mu(n)$  is no longer a color group element (!), it involves addition of products

→ Consider  $N_c = 2$  and drop  $\mu$  and  $n$  in the notation.

→ We need to sample an  $SU(2)$ -matrix  $U$  from the distribution.

$$dP(U) \sim dU \exp \left\{ \frac{\beta}{2} \text{Re} \text{Tr} \{ \tilde{S}^+ U \} \right\}$$

where  $dU$  is the Haar measure and  $\tilde{S}$  is a sum of  $SU(2)$  matrices.

→ The crucial property of  $SU(2)$  is

that sum of  $SU(2)$  matrices is proportional to an  $SU(2)$  matrix.  
We can normalize:

$$S = \frac{1}{\omega} \tilde{S}, \quad S \in SU(2)$$

$$\omega^2 = \det \| \tilde{S} \|$$

$$dP(U) \sim dU \exp \left\{ \frac{\beta w}{2} \operatorname{Re} \operatorname{Tr} \{ S^+ U \} \right\}$$

→ Change of variables and invariance  
of the Haar measure:

$$V \equiv S^+ U$$

$$dP(V) \sim dV \exp \left\{ \frac{\beta w}{2} \operatorname{Re} \operatorname{Tr} \{ V \} \right\}$$

- Properties of  $SU(2)$  Matrix

$$V \equiv a_0 \mathbb{I} + i \vec{a} \cdot \vec{\sigma} = \begin{pmatrix} a_0 + ia_3 & a_2 + ia_1 \\ -a_2 + ia_1 & a_0 - ia_3 \end{pmatrix}$$

$$1 = a_0^2 + |\vec{a}|^2, \quad a_n \in [-1, 1]$$

$$\operatorname{Re} \operatorname{Tr}\{V\} = 2a_0$$

→ Properties of the Measure:

$$\begin{aligned} dV &\sim da_0 da_1 da_2 da_3 \delta(a_0^2 + |\vec{a}|^2 - 1) \\ &\sim da_0 |\vec{a}|^2 d|\vec{a}| d(\cos(\theta)) d\phi \delta(|\vec{a}|^2 (1 - a_0^2)) \\ &\sim da_0 \sqrt{1 - a_0^2} d(\cos \theta) d\phi \end{aligned}$$

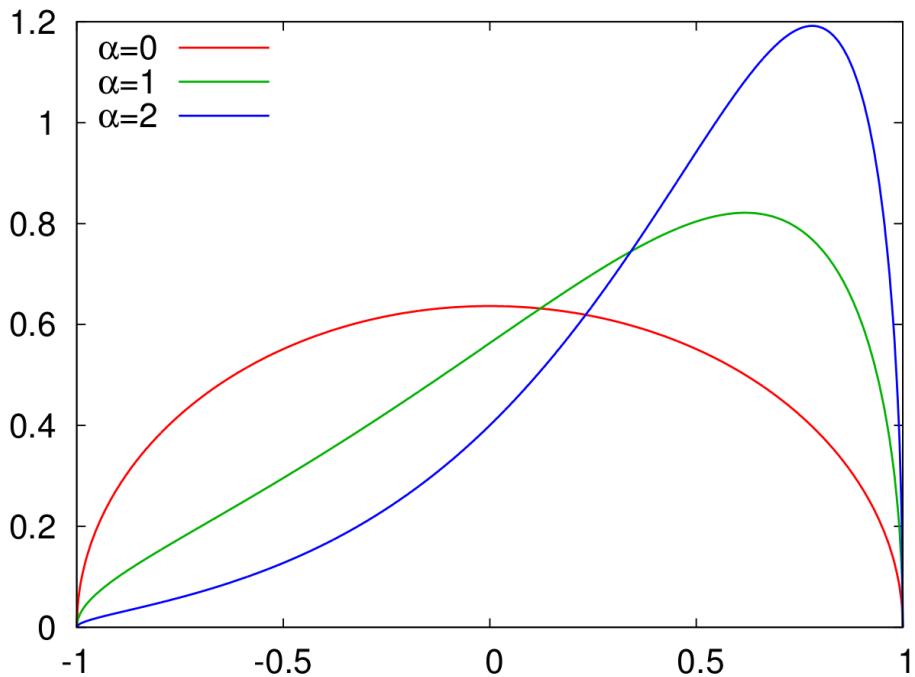
→ The angular part trivially separates:

$$d(\cos \theta) d\phi$$

→ We need to sample the following distribution:

$$dP(a_0) \sim da_0 \sqrt{1 - a_0^2} e^{da_0}$$

where  $\alpha \equiv \beta \omega$  is a parameter.



\* Fig 1: Distributions for  $\alpha = 0, 1, 2$

- PDF & CDF

→ Probability Density Function (PDF)

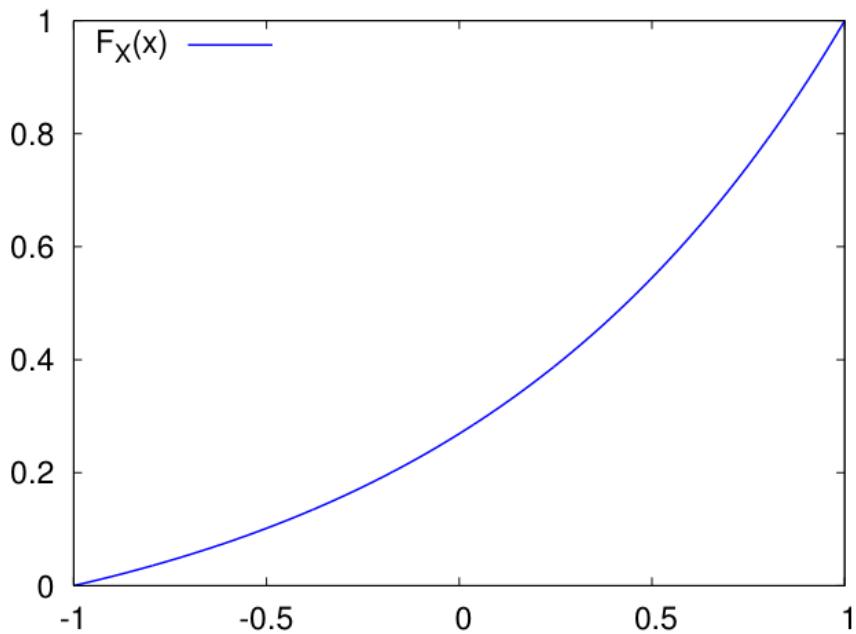
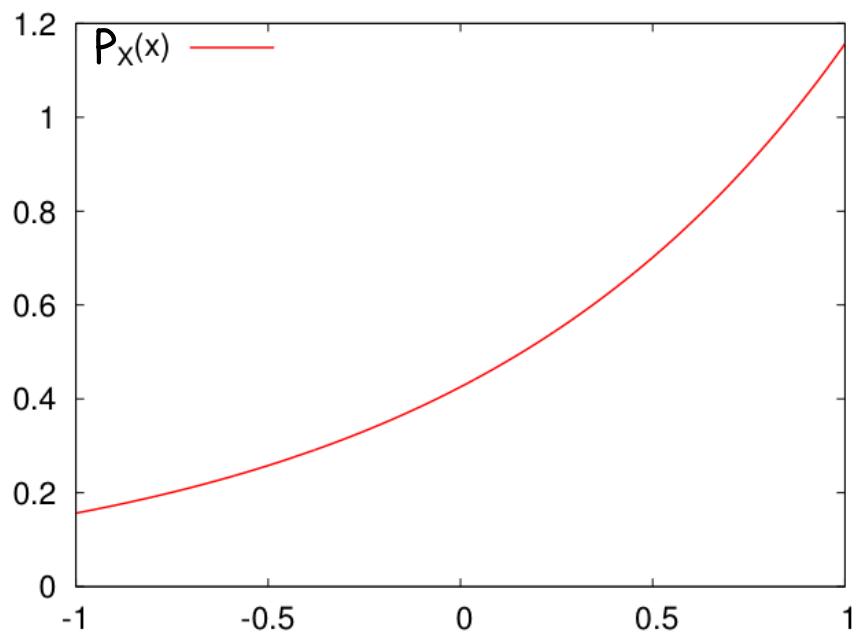
$$p_X(x) = \frac{2x}{\sinh \alpha} e^{\alpha x} \quad x \in [-1, 1]$$

→ cumulative Distribution Function (CDF)

$$F_X(x) \equiv P(X \leq x)$$

$$= \frac{2\alpha}{\sinh \alpha} \int_{-1}^{\chi} dx' e^{\alpha x'}$$

$$= \frac{2}{\sinh \alpha} (e^{\alpha x} - e^{-\alpha})$$



★ Plots of PDF and CDF

## Inverse CDF Filter

- Let  $X$  be a random variable distributed according to  $P_X(x)$ .
- Then  $Y \equiv F_X(X)$  is also a random variable.  
How is  $Y$  distributed?  
→ As seen in last class,  $Y$  is uniformly distributed in  $[0,1]$
- Then,  $X = F_X^{-1}(Y)$  i.e.

The inverse of the CDF acts as a filter that converts a uniform distributed random number into a random variable from the desired distribution  $F_X(x)$  e.g.

$$X = \frac{1}{\alpha} \ln \left( e^{-\alpha} + \frac{1}{2} \sinh(\alpha Y) \right)$$

→ This can be achieved for a limited no. of P.D.F.s.

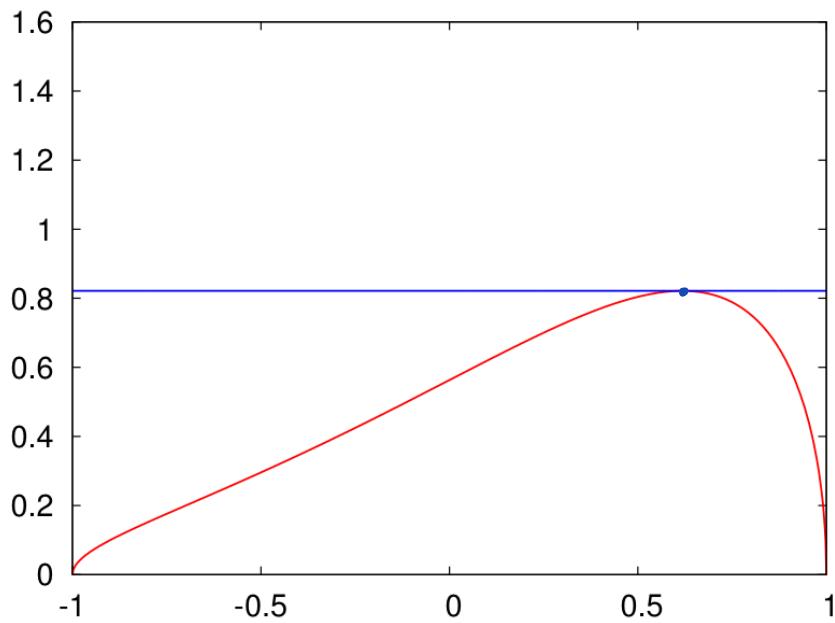
→ In realistic cases, one needs to draw  $X$  from a "wrong" distribution  $\varphi_X(x)$  and then correct by accepting the value with probability:

$$\sim \frac{P_X(x)}{\varphi_X(x)} \quad (\text{The Rejection / Flatbath method})$$

## \* Plot of the $P(a_0)$ Distribution !

→ Consider  $dP(a_0) \sim da_0 \sqrt{1-a_0^2} e^{da_0}$ ,  $\alpha=1$

→ Simplest way: - Draw  $a_0$  from  $\varphi(a_0) \sim 1$ , correct with  $\sqrt{1-a_0^2} e^{da_0}$  (61% Efficiency)



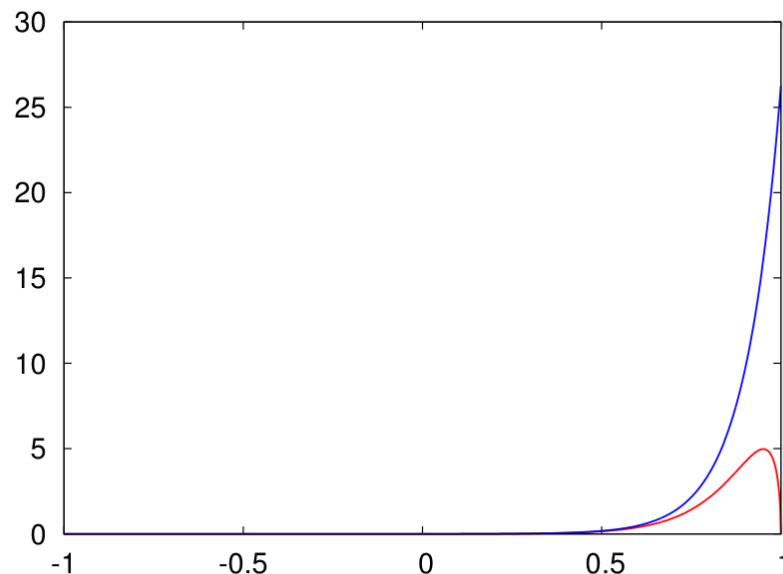
Intersects  
at one  
point.  
(tangential)

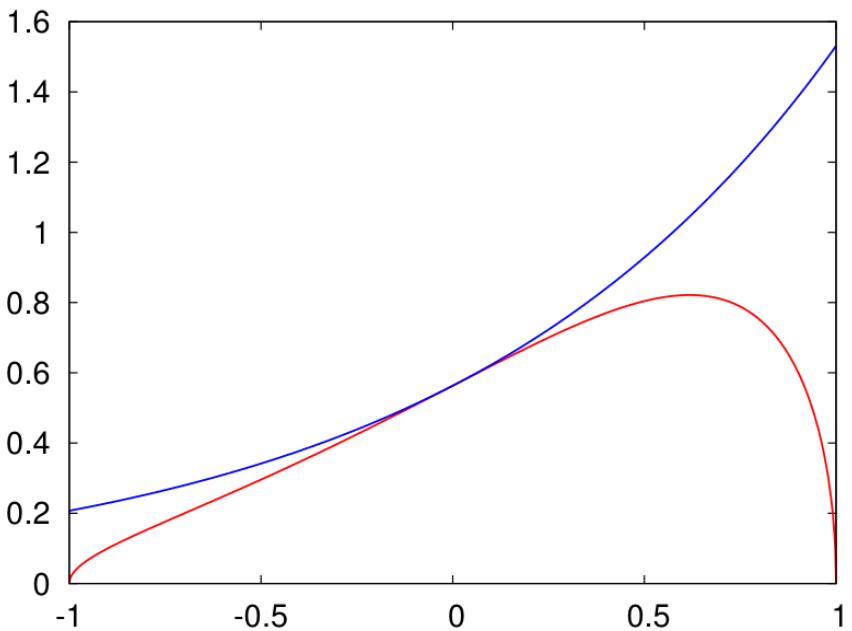
\* Plot of  $P(x), \varphi(x)$  - uniform

Consider  $dP(a_0) \sim da_0 \sqrt{1-a_0^2} e^{da_0}$ ,  $d=1$

→ Now, Creutz (1980) :

Draw  $a_0$  from  $\varphi(a_0) \sim e^{da_0}$ , correct  
with  $\sqrt{1-a_0^2}$  (76% Efficiency)





\* Plot of  $P(\alpha)$ ,  $\varphi(\alpha) - e^{\alpha a_0}$ ,  $\alpha = 10$

→ Consider  $dP(a_0) \sim da_0 \sqrt{1-a_0^2} e^{\alpha a_0}$ ,  $\alpha = 10$

→ Draw  $a_0$  from  $\varphi(a_0) \sim e^{\alpha a_0}$ , correct with  $\sqrt{1-a_0^2}$  (38% efficiency)

→ Other improvements in the  $P(a_0)$  Distribution.

→ Further improvements :

- Fabričius, Haan (1984)
- Kennedy, Pendleton (1985)

→ Change of variables :

$$r = \sqrt{1 - a_0}, \quad r \in [0, \sqrt{2}]$$

$$dP(r) \sim dr \sqrt{1 - \frac{1}{2} r^2 r^2 e^{-\alpha r^2}}$$

$$dQ(r) \sim dr r^2 e^{-\alpha r^2}$$

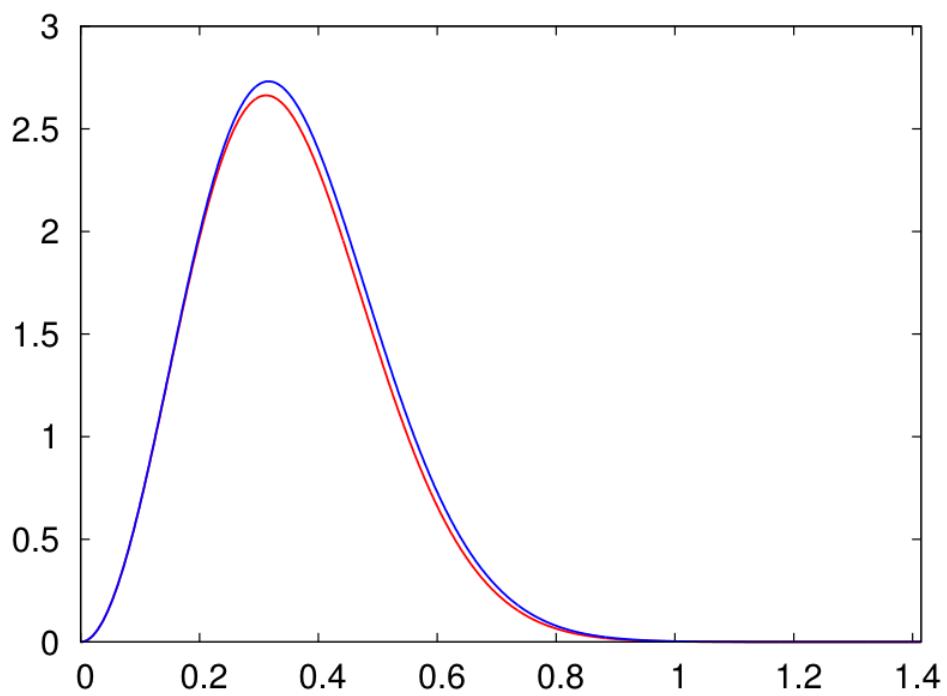
→  $Q(r)$  can be considered as a three-dimensional gaussian distribution with a trivial angular dependence.

\* Plot of  $P(r)$  &  $Q(r)$  (improved)

$$\rightarrow \text{consider } P(r) \sim \sqrt{1 - \frac{1}{2} r^2 r^2 e^{-\alpha r^2}},$$

$$\alpha = 10.$$

→ FHKP : Draw  $r$  from  $Q(r) \sim r^2 e^{-\alpha r^2}$ ,  
correct with  $\sqrt{1 - r^2/2}$   
(96% efficiency)



## \* SU(2) Heatbath Algorithm

① → calculate the sum of the staples  $\tilde{S}$  and project to SU(2)

$$S = \tilde{S} / \sqrt{\det \|\tilde{S}\|}$$

② → change of variables  $V \equiv S^+ U$

③ → sample  $a_0$  from:

$$dP(a_0) \sim da_0 \sqrt{1-a_0^2} e^{\alpha a_0} \text{ (with the Creutz / Improved FHKP Algorithm)}$$

$$\alpha = \beta \sqrt{\det \|\tilde{S}\|}$$

④ → sample  $\theta$  and  $\phi$  on a sphere.

⑤ → construct  $a_1, a_2, \text{ and } a_3$

⑥ →  $U = SV$  is a new value for the

link variable.

## \* $SU(N_c)$ Heatbath Algorithm

Q) How can all this be carried over to arbitrary  $N_c > 2$ ?

→ Updates in  $SU(N_c)$  can be built as a sequence of  $SU(2)$  subgroups updates, Cabibbo, Marinari (1982)

$$U' = A_m A_{m-1} \cdots A_1 U$$

where,

$U$  is the current  $SU(N_c)$  matrix  
and  $A_k$  are  $SU(2)$  matrices (embedded in  $SU(N_c)$ )

→ The staple calculation is carried out in the same way as for the  $SU(2)$  case, then for generating the

$A_K$   $SU(2)$  matrix one needs only the part of the total sample matrix that has the same block structure as  $A_K$ .

→  $SU(N_c)$  overrelaxation algorithm is similarly built by updating  $SU(2)$  subgroups.

→ Multi Hit Metropolis algorithm,  
used for Wilson's Gauge action

Metropolis algorithm w/ single link  
variable  $U_{\mu}(n)$ . This link is shared  
by 6 plaquettes and only these  
6 plaquettes are affected when  
changing  $U_{\mu}(n) \rightarrow U_{\mu}(n)'$ .

## Exercises :-

Given a complex scalar field :

$$\phi(x) = \rho(x) e^{i\theta(x)}$$

in the limit  $\lambda \rightarrow \infty$ , where magnitude is frozen  $\rho(x) = 1$

The degree of freedom is :

$\theta(x) \in [-\pi, \pi]$ . The Action is :-

$$S[\theta] = -2K \sum_z \sum_{\hat{\mu}} \operatorname{Re} \left\{ \exp(-i\theta_z + \hat{\mu}) \exp(i\theta_z) \right\}$$

$$= -2K \sum_z \sum_{\hat{\mu}} \cos(\theta_z - \theta_{z+\hat{\mu}})$$

The Partition function is :-

$$Z = \int_{-\pi}^{\pi} T T d\theta_x e^{-S[\theta]}$$

Goal :- 2D lattice, V = no. of sites.

Build a Markov Chain  
Monte Carlo process the sample  
the field configurations (i.e  $\theta_x$ )  
& calculate the observable :-

$$L_\phi \equiv \frac{1}{2V} \sum_{\langle xy \rangle} \exp(-i\theta_x) \exp(i\theta_y)$$

$$\equiv \frac{1}{V} \sum_z \sum_{\mu} \text{Re} \left\{ \exp(-i\theta_{z+\hat{\mu}}) \exp(i\theta_z) \right\}$$

$$\equiv \frac{1}{V} \sum_z \sum_n \cos(\theta_z - \theta_{z+\hat{n}})$$

## Explaining the setup of the problem :-

Through all the angular,

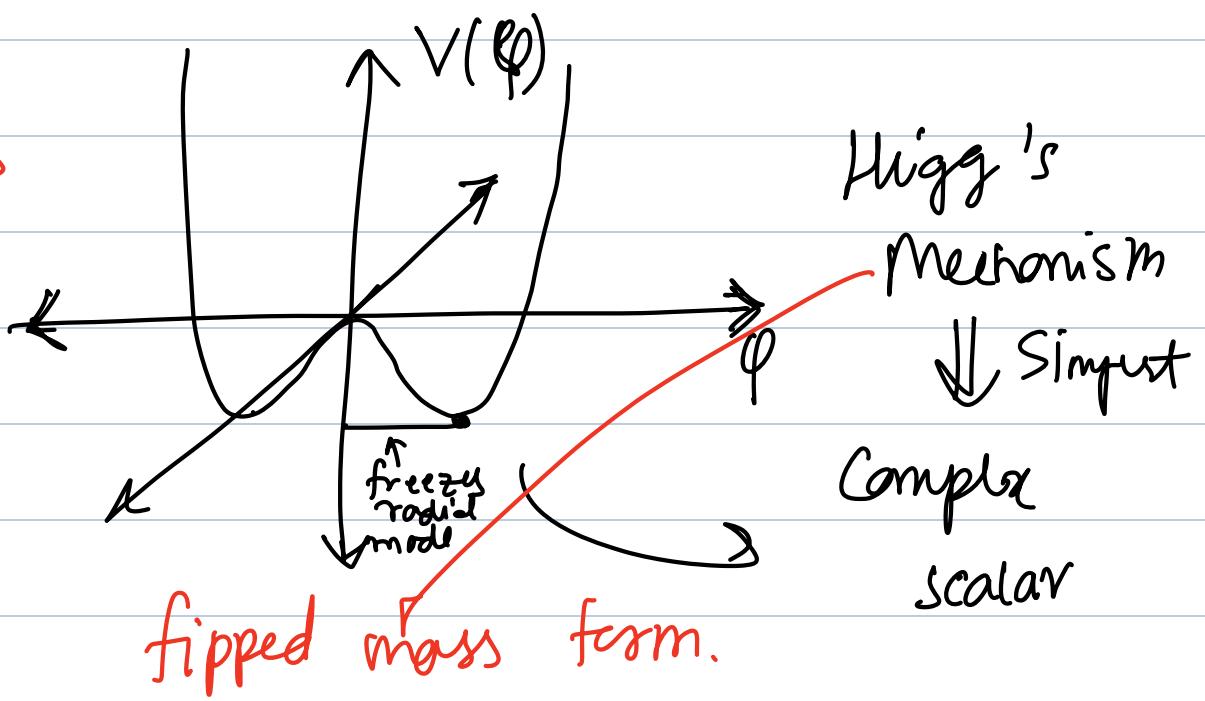
$$\varphi_z = s_z \alpha_z = f_z e^{i\theta_z}$$

↗ Complex no.  
↓ Radial part  
→ Angular Part  
 (Magnitude)

$$|\varphi_z|^2 = s_z^2$$

$$\text{If } \lambda \rightarrow 0 \quad |\varphi_z|^2 = 1 \Rightarrow s_z = 1$$

↓  
 lattice dimensionless coupling



Looking at the action for complex scalar  $\phi^4$  theory:

In limit  $\gamma \rightarrow \infty$ , the interaction term is multiplied by  $\infty$ , so any deviation of the magnitude from 1 has very large penalty in energy.

→ configurations where the magnitude is not one will be highly suppressed, as they won't contribute to the path integral.  
 $\hookrightarrow e^{-S[\phi]}$

→ This is the limit that freezes the radial mode & we are left with the angular part.

$$S[\phi] = -2K \sum_z \sum_{\mu} \cos(\theta_z - \theta_{z+\hat{\mu}})$$

→ we have a degree of freedom per site, which is essentially an angle → (extension of the Ising model)