Compiler Optimizations using Deep Reinforcement Learning

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Abstract

Treating compiler optimizations as a contextual-bandit problem will allow a deep reinforcement model to successfully map features to compiler flags, surpassing human-level ability with a *tabula rasa* approach.

1 Introduction

When compiling high-level code for release, most developers want the fastest runtime, most power efficient operation, and/or smallest memory footprint; yet, few actually know how to get this top-level performance out of modern compilers. In fact, most compilers support hundreds of possible optimization flags that can be rearranged, repeated, left out completely, or any combination of the former. It is because of this extreme complexity that no perfect compiler exists. Current solutions to this problem use various statistical and machine-learning-based methods to try and derive the best possible options, yet fall short of truly optimal performance, or lack the ability to generalize across multiple architectures and benchmarks.

Trying to eke out performance gains for production releases may seem trivial to some, however, when one considers the impact this may have on embedded devices, it is impossible to consider the impact as anything less than massive. Source code for embedded devices, such as cars, power tools, digital watches, pace makers, etc., is normally compiled a single time, before being deployed to millions of devices. Even with conservative estimates of 40 embedded devices per household, better preforming compilers would result in billions of devices performing faster, saving energy, and requiring less memory.

To truly master the compiler optimization space, one needs to consider learning tabula rasa, since no ground truth actually exists about the search space. At it's heart, this problem is comparable to the work Deep Mind has done with the game of Go, which similarly exhibits a cost-prohibitively-large search-space. Unlike Go, compiler optimization emits no change in state, and must therefore be treated as an extremely large contextual-bandit problem, where the programs

are the bandits, and the arms represent potential optimization sequences. The agent then interacts with these bandits in order to learn the relations between program features and compiler optimizations, using deep learning and hind-sight experience replay to build underlying relations directly from the full feature set.

This paper explores how deep reinforcement learning copes with such a large search-space in a contextual-bandit problem by first implementing it on a smaller scale. Starting with just seven possible flags, arranged in sub-sets of various lengths, without allowing reordering or repetition. The goal of this work is to produce a model capable of examining the context of a program, and producing the optimal flags out of the provided search-space. For this work, the only metric being optimized is the runtime of a given program, in future works both larger search-spaces, and multi-goal approaches should be explored.

2 Training and Testing

In order to thoroughly evaluate the proposed model, this work employed leave-one-out testing against each program, for each feature set present in the data. The script begins by first loading all cBench programs, along with their static and dynamic features ¹. Once these features are loaded, the script then computes all 128 runtimes for each individual application, although this approach will not be feasible when the search space is expanded, it allowed direct comparisons between agents selections and each programs true optimal. After runtimes are computed, the actual testing/training loop.

The outer loop of the script cycles through each feature set: static, dynamic, and hybrid; while the inner loop cycles through each individual application. Due to the nature of leave-one-out testing, within the inner loop, a unique agent is created as a combination of the program to test against, and the feature set in use. Once this agent is instantiated, it is given 100 episodes to explore the relation between program features, compiler flags, and runtimes. During each episode a program is selected at random from the training set, the selected features are then exposed to the agent as "context", which the agent then uses to predict one, or more, "actions" it thinks will minimize the runtime. These actions, correspond to a distinct subset of compiler flags; these flags are then evaluated by the program, producing a runtime that is saved into the agents memory, along with the context and action selected. Every 20th episode, the agent batch-trains against a random sample of events saved into its memory.

Testing the model is done in a very similar matter to training, with the exception that the agent does not save any data about the testing program, and that multiple actions are actually used, to compute five-shot testing metrics. Once an agent has completed it's 100 episodes of training, the epsilon (chance of doing something random) is dropped to 0, and the agent is exposed to the appropriate context of the testing program. Five actions are returned and evaluated. The resulting runtimes, along with a baseline of no flags, are used to compute important metrics, such as single-shot speedup, five-shot speedup, and

 $^{^{1}}$ Courtesy of the work done for COREL

optimal speedup. These metrics are then used as the basis for the rest of this work.

3 Results

Initial results are extremely positive, with five-shot testing finding nearly optimal results after only 100 episodes, nearly across the board. There were two programs in the entirety of the first pass that performed sub-baseline in the one-shot test.

4 Conclusions

References

 $[Ashouri] \ \ COBAYN: \ Compiler \ autotuning \ with \ BAYsian \ Network$