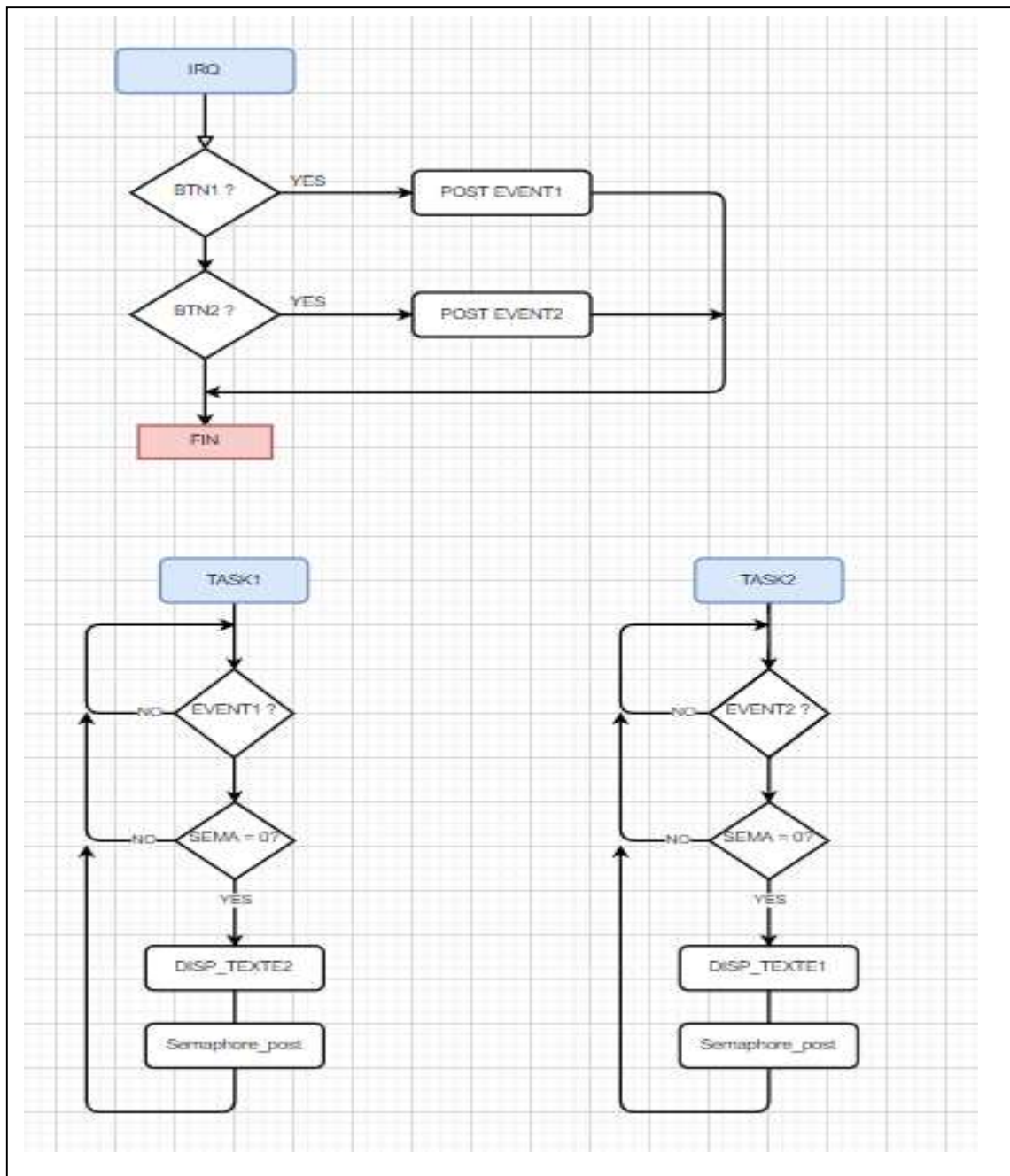


Exemples Semaphore



```

/*****
 * main.h
 *
 * Created on: 18 oct. 2022
 * Author:
 *****/

#ifndef MAIN_H_
#define MAIN_H_

//PORT1
#define LED_ROUGE    GPIO_PIN0
#define BOUTON1      GPIO_PIN1
#define BOUTON2      GPIO_PIN2
//PORT9
#define LED_VERTE    GPIO_PIN7

//EVENT CONSTANT
#define EVENT_TIMEOUT    12
#define BTN1_EVENT       Event_Id_01
#define BTN2_EVENT       Event_Id_02

#endif /* MAIN_H_ */

```

```

/*****
 * Copyright (c) 2015, Texas Instruments Incorporated
 * All rights reserved.
 *
 * ===== IRQ Example =====
 *
 *****/
#include <stdint.h>
#include <stdbool.h>
#include <string.h>
/* XDCtools Header files */
#include <xdc/std.h>
#include <xdc/runtime/System.h>
#include <xdc/cfg/global.h>
/* BIOS Header files */
#include <ti/sysbios/BIOS.h>
#include <ti/sysbios/knl/Task.h>
#include <ti/sysbios/knl/Event.h>
#include <ti/sysbios/knl/Semaphore.h>
/* TI-RTOS Header files */
#include <driverlib.h>
/* Board Header file */
#include "main.h"
#include "hal_LCD.h"

/*****
 * Prototype de fonction
 *****/
void Init_GPIO(void);
void Blink_RED(UArg arg0, UArg arg1);
void Task_Event_BTN1(UArg arg0, UArg arg1);
void Task_Event_BTN2(UArg arg0, UArg arg1);
void IRQ_Port1(unsigned index);
void ScrollText(char *msg);

/*****
 *****/
 * ===== main =====

 *****/
*****/
int main(void)
{
    WDT_A_hold(WDT_A_BASE); //Stop WDT
    PM5CTL0 &= ~LOCKLPM5;

    Init_GPIO();
    Init_LCD();

```

```

    DisplayText("LCD ON");

    /* Start BIOS */
    BIOS_start();

    return (0);
}

/*****
 * ===== Init_GPIO =====
 *****/
void Init_GPIO(void)
{
    //PORT1
    GPIO_setAsOutputPin(GPIO_PORT_P1, LED_ROUGE);
    GPIO_setOutputLowOnPin(GPIO_PORT_P1, LED_ROUGE);
    GPIO_setAsInputPin(GPIO_PORT_P1, BOUTON1 + BOUTON2);
    GPIO_setAsInputPinWithPullUpResistor(GPIO_PORT_P1, BOUTON1 +
BOUTON2);
    GPIO_selectInterruptEdge(GPIO_PORT_P1, BOUTON1 + BOUTON2,
GPIO_HIGH_TO_LOW_TRANSITION);
    //PORT9
    GPIO_setAsOutputPin(GPIO_PORT_P9, LED_VERTE);
    GPIO_setOutputLowOnPin(GPIO_PORT_P9, LED_VERTE);
    //IRQ
    GPIO_enableInterrupt(GPIO_PORT_P1, BOUTON1 + BOUTON2);
    GPIO_clearInterrupt(GPIO_PORT_P1, BOUTON1 + BOUTON2);
}

/*****
 * ===== Blink_RED =====
 *****/
void Blink_RED(UArg arg0, UArg arg1)
{
    while (1)
    {
        Task_sleep(1000);
        GPIO_toggleOutputOnPin(GPIO_PORT_P1, LED_ROUGE);
    }
}

```

```

/*****
 * ===== Task_Event_BTN1 =====
 *****/
void Task_Event_BTN1(UArg arg0, UArg arg1)
{
    uint16_t Posted;

    while (1)
    {
        Posted = Event_pend(h_event0,                // handle du
registre event
                                Event_Id_NONE,        // andMask
                                BTN1_EVENT,           // orMask
                                EVENT_TIMEOUT);

        switch(Posted)
        {
            case BTN1_EVENT:
                Semaphore_pend(h_semaphore0, BIOS_WAIT_FOREVER);
                ClearLCD();
                DisplayScrollText(LCDstrupr("not remade because of
errors"));
                GPIO_setOutputHighOnPin(GPIO_PORT_P9, LED_VERTE);
                Semaphore_post(h_semaphore0);
                break;
        }

        Task_sleep(10);
    }
}

```

```

/*****
 * ===== Task_Event_BTN2 =====
 *****/
void Task_Event_BTN2(UArg arg0, UArg arg1)
{
    uint16_t Posted;

    while (1)
    {
        Posted = Event_pend(h_event0,          // handle du registre
event                                     Event_Id_NONE, // andMask
                                     BTN2_EVENT,    // orMask
                                     EVENT_TIMEOUT);

        switch(Posted)
        {
            case BTN2_EVENT:
                Semaphore_pend(h_semaphore0, BIOS_WAIT_FOREVER);
                DisplayScrollText(LCDstrupr("too few arguments in
function call"));
                GPIO_setOutputLowOnPin(GPIO_PORT_P9, LED_VERTE);
                Semaphore_post(h_semaphore0);
                break;
        }

        Task_sleep(10);
    }
}

```

```

/*****
 * ===== Irq_Port1 =====
 *
 * Vector: ( .int37 )
 *****/
void IRQ_Port1(unsigned index)
{
    uint16_t Status = GPIO_getInterruptStatus(GPIO_PORT_P1,
BOUTON1+BOUTON2);

    switch(Status)
    {
        case BOUTON1:
            Event_post(h_event0, BTN1_EVENT);
            GPIO_clearInterrupt(GPIO_PORT_P1,BOUTON1);
            break;

        case BOUTON2:
            Event_post(h_event0, BTN2_EVENT);
            GPIO_clearInterrupt(GPIO_PORT_P1,BOUTON2);
            break;
    }
}

/*****

```

TI-RTOS > Products > SYSBIOS > Synchronization > Semaphore - I

[Module](#) [Instance](#) [Advanced](#)

Semaphores

h_semaphore0
 Add ...
 Remove

Required Settings

Handle: h_semaphore0
 Initial count: 1
 Semaphore type:

☐ Counting (FIFO)
 ☒ Binary (FIFO)
 ☐ Counting (priority-based)
 ☐ Binary (priority-based)

Event Support

These options are only available when [Event](#) support is enabled
 Event instance: null
 Event Id: Event_Id_00

type filter text

- BIOS
- Boot
- Clock
- Config (ti.drivers)
- Config (ti.mw)
- Defaults
- Error
- Event
 - h_event0
- Hwi (ti.sysbios.hal)
- Hwi (ti.sysbios.family.msp430)
 - Hwi_IRQ_Port1
- Idle
- Memory
- Power
- Program
- Semaphore
 - h_semaphore0
- Swi
- SysCallback
- System
- Task
 - h_Blink_RED
 - h_Task_Event_BTN1
 - h_Task_Event_BTN2
- Text