# EE-559 - Deep learning

# 10.4. Model persistence and checkpoints

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It also allows to implement **checkpoints** which keep track of the state during training and allow to either restart after an expected interruption, or modulate meta-parameters manually.

The underlying operation is **serialization**, that is the transcription of an arbitrary object into a sequence of bytes saved on disk.

The main PyTorch methods for serializing are torch.save(obj, filename) and torch.load(filename).

```
>>> x = 34
>>> torch.save(x, 'x.pth')
>>> y = torch.load('x.pth')
>>> y
34
```

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# One can save directly a full model like this, including arbitrary fields

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# Additionally

- Tensors are saved with their locations (CPU, or GPU), and will be loaded in the same configuration,
- in your Modules, buffers have to be identified with register\_buffer,
- · loaded models are in train mode by default,
- optimizers have a state too (momentum, Adam).

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A checkpoint is a persistent object that keeps the global state of the training: model and optimizer. In the following example (1) we load it when we start if it exists, and (2) we save it at every epoch.

```
nb_{epochs_finished} = 0
model = Net()
optimizer = torch.optim.SGD(model.parameters(), lr = lr)
checkpoint_name = 'checkpoint.pth'
try:
    checkpoint = torch.load(checkpoint_name)
    nb_epochs_finished = checkpoint['nb_epochs_finished']
    model.load state dict(checkpoint['model state'])
    optimizer.load_state_dict(checkpoint['optimizer_state'])
    print('Checkpoint loaded with %d epochs finished.' % nb epochs finished)
except FileNotFoundError:
    print('Starting from scratch.')
except:
    print('Error when loading the checkpoint.')
    exit(1)
```

```
for k in range(nb_epochs_finished, nb_epochs):
    acc loss = 0
    for input, target in zip(train_input.split(batch_size),
                             train_target.split(batch_size)):
        output = model(input)
        loss = criterion(output, target)
        acc loss += loss.item()
        optimizer.zero_grad()
        loss.backward()
        optimizer.step()
    print(k, acc_loss)
    checkpoint = {
        'nb epochs finished': k + 1.
        'model_state': model.state_dict(),
        'optimizer_state': optimizer.state_dict()
    torch.save(checkpoint, checkpoint_name)
```

## If we killall python during training

fleuret@elk:/tmp/ ./tinywithcheckpoint.py Starting from scratch. 0 161.2404215920251

1 35.50377965264488 2 24.43254833246465

3 18.57419647696952

4 14.582882737944601

Killed

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```
fleuret@elk:/tmp/ ./tinywithcheckpoint.py
Starting from scratch.
0 161.2404215920251
1 35.50377965264488
2 24.43254833246465
3 18.57419647696952
4 14.582882737944601
```

#### and re-start

```
fleuret@elk:/tmp/ ./tinywithcheckpoint.py
Checkpoint loaded with 5 epochs finished.
5 11.396404800716482
6 8.944935847055604
7 7.116929043420896
8 5.463898817846712
9 4.41012461569494
test_error 1.01% (101/10000)
```



Since a model is saved with information about the CPU/GPUs where each Storage is located there may be issues if the model is loaded on a different hardware configuration.

## For instance, if we save a model located on a GPU:

```
>>> x = torch.nn.Linear(10, 4)
>>> x.to('cuda')
Linear(in_features=10, out_features=4, bias=True)
>>> torch.save(x, 'x.pth')
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## And load it on a machine without GPU:

>>> x = torch.load('x.pth')

```
Traceback (most recent call last):
/.../
RuntimeError: cuda runtime error (35): CUDA driver version is insufficient for
CUDA runtime version at torch/csrc/cuda/Module.cpp:51
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This can be fixed by specifying at load time how to relocate storages:

```
>>> x = torch.load('x.pth', map_location = lambda storage, loc: storage)
```

