# SLDM Homework 3

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- Solution proposals are individual.
- Each solution must be reproducible by your peer. Code should be added to the appendix.
- The solution to each subproblem yield 0 to 2 points. Students are expected to attempt each problem.

## 1

We observe i.i.d. data  $\mathbf{z}^n$  for the number of earthquakes each year. We consider a Poisson model class

$$p_{\theta}(z) = \text{Poisson}(z; \theta)$$
  $\theta > 0$ 

and want to validate a learned model.

a) Generate training data  $\mathbf{z}^n$  from

$$p(z) = Poisson(z; 40)$$

Then use the model  $p_{\theta}(z)$  to generate K synthetic datasets  $\widetilde{\mathbf{z}}_{(1)}^{n}, \dots, \widetilde{\mathbf{z}}_{(K)}^{n}$  to numerically evaluate the probability

$$P(\theta) = \mathbb{P}_{\theta} \left( T_{\theta}(\widetilde{\mathbf{z}}^{n}) \le T_{\theta}(\mathbf{z}^{n}) \right)$$

$$\simeq \frac{1}{K} \sum_{k=1}^{K} 1 \left\{ T_{\theta}(\widetilde{\mathbf{z}}_{(k)}^{n}) \le T_{\theta}(\mathbf{z}^{n}) \right\}$$
(1)

Report  $\alpha_{\theta}$  for parameters  $\theta = 30$  and 40, respectively. Consider n = 5, 50 and 500, respectively, and use a large K.

- b) Use ERM  $\widehat{\theta}_n$  on training data  $\mathbf{z}^n$  and report  $\alpha_{\theta}$  for  $\theta = \widehat{\theta}_n$  (n = 5, 50 and 500, respectively).
- c) Repeat b) for but now consider data

$$p(z) = \text{NegBinomial}(z; r, p)$$
  $r \in \mathbb{N}, p = \frac{40}{r + 40}$ 

Consider two cases: r = 10 and  $r = 10^4$ .

2

Consider the ship localization problem from HW2 using timing data and the Gaussian data model  $\,$ 

$$p_{\theta}(\mathbf{z}) = \prod_{m=1}^{M} \mathcal{N}(z_m; 2c^{-1} || \mathbf{s} - \mathbf{a}_m ||, v) \qquad \boldsymbol{\theta} = \begin{bmatrix} \mathbf{s} \\ v \end{bmatrix}$$

where  $c = 3 \times 10^8$  and M = 3.

Generate  $\mathbf{z}^n$  i.i.d. samples from the following distributions and report  $\alpha_{\theta}$  for  $\theta = \widehat{\boldsymbol{\theta}}_n$  for n = 10, 100 and 1000.

a) Gaussian data:

$$p(\mathbf{z}) = \prod_{m=1}^{M} \mathcal{N}(z_m; \mu_m, (10^{-7})^2)$$

b) Exponential data:

$$p(\mathbf{z}) = \prod_{m=1}^{M} \operatorname{Exp}(z_m; \mu_m)$$

where  $\mu_m = 2c^{-1} || [200 \ 200]^{\top} - \mathbf{a}_m ||$ 

3

We'll continue the localization task from HW2 but consider the small sample case, writing the Gaussian data model as

$$p_{\theta}(\mathbf{z}) = \mathcal{N}\left(\mathbf{z}; 2c^{-1} \underbrace{\begin{bmatrix} \|\mathbf{s} - \mathbf{a}_1\| \\ \|\mathbf{s} - \mathbf{a}_2\| \\ \|\mathbf{s} - \mathbf{a}_3\| \end{bmatrix}}_{u(\mathbf{s})}, v\mathbf{I}_3\right) \quad \boldsymbol{\theta} = \begin{bmatrix} \mathbf{s} \\ v \end{bmatrix}$$

Where we consider a learning parameter based on the maximum posterior belief (aka. MAP):

$$\widehat{\boldsymbol{\theta}}_n = \operatorname*{arg\,max}_{\boldsymbol{\theta}} b(\boldsymbol{\theta}|\mathbf{z}^n)$$

using a prior belief distribution for the parameters:

$$b(\boldsymbol{\theta}) = \mathcal{N}(\mathbf{s}; \mathbf{s}_0, v_0 \mathbf{I})$$

so that we consider uniform beliefs for the noise variance v > 0.

a) Use the results from the lecture slides to show that we obtain a regularized learning method:

$$\widehat{\boldsymbol{\theta}}_n \equiv \operatorname*{arg\,min}_{\boldsymbol{\theta} \in \Theta} L(\boldsymbol{\theta}, p_n) + \frac{1}{2v_0 n} \|\mathbf{s} - \mathbf{s}_0\|^2$$

and note happens when  $v_0 \to \infty$  and what this means in the prior belief distribution. Also note that for any fixed n, the variance parameter  $v_0$  can be chosen to offset any amount of data.

Hint: use the logarithm of  $b(\boldsymbol{\theta}|\mathbf{z}^n)$ .

b) Generate synthetic training data from  $p(\mathbf{z})$  in HW2. We specify the prior belief  $b(\boldsymbol{\theta})$  by

$$\mathbf{s}_0 = \begin{bmatrix} 50\\50 \end{bmatrix} \qquad v_0 = 10^2$$

Implement the regularized learning method  $\widehat{\boldsymbol{\theta}}_n$  above using either grid search or gradient-based search and plot results along with ship location learn using ERM (HW2) when  $n=1,\,10$  and 100. Comment on pros and cons using the regularized method.

#### 4

We are now interested in a rather extreme case of n=1, where we observe blood pressure readings from d patients:

$$\mathbf{z} = [z_1, z_2, \dots, z_d]^{\top}$$

drawn from  $p(\mathbf{z})$ . We are interested in reporting a point estimate of the blood pressure for each patient  $k = 1, \ldots, d$ , but we only obtain a single reading from each patient, so that n = 1.

The sensor errors are specified to be  $\pm 20$  [mmHg] (95%).

a) First we consider a data model

$$p_{\theta}(\mathbf{z}) = \prod_{k=1}^{d} \mathcal{N}(z_k; \theta_k, \sigma^2) \qquad \boldsymbol{\theta} = \begin{bmatrix} \theta_1 \\ \vdots \\ \theta_d \end{bmatrix},$$

where  $\sigma = (20/2) = 10$  according to the sensor error specification.

Using the surprisal loss, show that the target parameter is

$$oldsymbol{ heta}_{\circ} = \mathbb{E}[\mathbf{z}]$$

so that each patient blood pressure target is

$$\tau(\boldsymbol{\theta}_{\circ}) = \mathbf{e}_{k}^{\top} \boldsymbol{\theta}_{\circ} \qquad k = 1, \dots, d$$

and conclude that

$$\tau(\widehat{\boldsymbol{\theta}}_n) = z_k \qquad k = 1, \dots, d$$

when using ERM.

b) Next, consider a much simpler model

$$p_{\theta}(\mathbf{z}) = \mathcal{N}(\mathbf{z}; \mu \mathbf{1}, (v + \sigma^2) \mathbf{I}), \quad \boldsymbol{\theta} = \begin{bmatrix} \mu \\ v \end{bmatrix}$$

which models the variability of blood pressures across patients by an unknown variance v.

Show that ERM with surprisal loss is

$$\widehat{\boldsymbol{\theta}} = \begin{bmatrix} \widehat{\mu} \\ \widehat{v} \end{bmatrix}$$

is given by

$$\widehat{\boldsymbol{\mu}} = \frac{1}{d} \mathbf{1}^{\top} \mathbf{z} \qquad \widehat{\boldsymbol{v}} = \max \left( 0, \frac{1}{d} \| \mathbf{z} - \widehat{\boldsymbol{\mu}} \mathbf{1} \|^2 - \sigma^2 \right)$$

c) Consider now a random target parameter

$$\tau(z_k; \boldsymbol{\theta}_\circ) = \frac{v_\circ}{v_\circ + \sigma^2} z_k + \frac{\sigma^2}{v_\circ + \sigma^2} \mu_\circ \qquad k = 1, \dots, d$$

Comment on what this means when the sensor errors  $\sigma \to 0$  and  $\sigma \to \infty$ , respectively. How does this differ from the fixed targets  $\tau(\boldsymbol{\theta}_{\circ})$  considered above?

d) Generate training data **z** from d = 100 patients

$$p(\mathbf{z}) = \prod_{k=1}^{d} \mathcal{N}(z_k; \mu_k, \sigma^2) \quad \mu_k \sim \mathcal{U}[100, 170] \quad \sigma^2 = 100$$

Plot two different estimates,  $\tau(\widehat{\boldsymbol{\theta}}_n)$  and  $\tau(z_k; \widehat{\boldsymbol{\theta}}_n)$ , respectively, versus  $\mu_k$  for all  $k=1,\ldots,d$ . Comment on your results.