

FILOTHEOU, Alexandros

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github.com/li9i · Portfolio · References

Robotics Software Engineer specialising in the full product lifecycle: from conception, design, coding, and simulation to continuous system integration, field testing, troubleshooting on real hardware, documentation, and delivery. Proven ability to work independently and materialise research into real-world results, bridging the two worlds to deliver cutting-edge systems with repeatable behaviours.

integration ROS 2 state estimation localisation autonomous navigation (1) (2) control computer vision

Skills

English Languages	Native / Fluent (IELTS 8.5 - C2 Proficiency) C/C++, Python, shell, MATLAB/Octave
Robotics/OS	Linux, ROS/ROS 2
Tools/Frameworks	git, Docker, Eigen, Behavior Trees, Gazebo, CI/CD, Qt/Tkinter, OpenCV
Control Techniques	MPC, PID, LQR

Achievements so far

- Engaging 2,000+ visitors annually since 2023 at the [AMTh](#) museum by deploying [human-robot applications](#)
- Engineered 50% boost in localisation accuracy for fleet of RFID-inventorying robots, achieving cm accuracy
- Identified bottlenecks and reduced deployment time >10x across fleet of additive manufacturing robots
- Reliable and robust ROS-ROS 2 interoperability and communication across multiple machines using [Zenoh](#)
- One of only eighteen authors of single-authored papers presented at IEEE IROS 2024 (1,587 total)

Experience

Robotics Software Engineer · ITI-CERTH, Thessaloniki GR	Sep 2023 – Present
• Owner of software integration, DevOps, and git repository maintainer of R&D project RoBétArmé	
• Engineered development and deployment principles for ≈10 S/W teams and >50 Dockerised ROS packages	
• Orchestrated fleet of concrete- and metal-additive manufacturing robots with Behaviour Trees	
• Ensured code quality via googletest and cpplint, continuous integration/deployment via CI/CD pipelines	
Robotics & Control Engineer · ECE Dept., Aristotle University of Thessaloniki GR	Sep 2018 – Mar 2023
• Owner of everything robotics in large-scale R&D projects RELIEF and CultureId	
• Developed and deployed autonomous ground and aerial platforms in libraries , museums , and outdoors	
• Delivered 2D/3D SLAM and collision-avoiding navigation pipelines with intuitive user GUIs using Qt, teb planner, rtabmap, and karto	
• Developed and integrated modular codebases for 18+ publications in top-tier IEEE journals/conferences, enabling multi-team experiments, translating novel robotics and RFID research to real-world opportunities	
Teaching Assistant · KTH Royal Institute of Technology, Stockholm SE	Sep 2016 – Nov 2016
• <i>DD2380 - Artificial Intelligence</i> under Prof. Patric Jensfelt	

Volunteering

Computer Vision Engineer · PANDORA Robotics , Thessaloniki GR	Oct 2013 – Jul 2014
• Increased survivor rescue probability and gained 2 nd place in the 2015 International RoboCup Rescue competition by developing a C++ wall-hole detection system using a Microsoft Kinect RGB-D camera	

Links

Software packages	Global Localisation · LiDAR Odometry · ros2-utils · lama-odom
Demos/Videos	Global Localisation · LiDAR Odometry · Robust Path-tracking · RELIEF · CultureId
Publications	[Global Localisation] · [LiDAR Odometry] · [Multi-agent navigation] · [Navigation survey]

Education

Doctorate · Electrical & Computer Engineering · Aristotle University of Thessaloniki	Sep 2018 – Jun 2023
Master of Science · Systems, Control, and Robotics · KTH Royal Inst. of Technology	Sep 2015 – Jun 2017
Diploma · Electrical & Computer Engineering · Aristotle University of Thessaloniki	Sep 2005 – Jul 2013