Alexandros Filotheou

I have 7+ years of hands-on experience that includes SLAM, localisation, autonomous navigation, control, Computer Vision, and general integration and problem-solving. These I have acquired in real conditions with real robots as well as in simulation, working for research projects funded by the European Commission and the Greek State. I have mainly used ROS and ROS 2, but also MATLAB/Octave, all the while under Linux. My primary coding language is C++ and my secondary Python. I hold a diploma and a PhD in Electrical and Computer Engineering and I am qualified with a Master's degree in Control and Robotics. I have deliberately chosen the academic + software engineering path because I wanted to reconcile the two dominant types of engineers: the academic type whose coding boundary is MATLAB, and the software engineering type whose boundary is code. It is my pleasure to document my motivation and contributions in a clear and concise manner that acknowledges my audience's existing knowledge with regard to code, presentations, technical papers, or tutorials. Most of all I enjoy being a member of a team and solving problems.

```
Portfolio
    Indicative software packages
                                cbgl · fsm-lo · PANDORA Hole Detection
                                                                                    — github
         Indicative publications
                                [cbgl] · [fsm] · [multi-mpc]
                                                                                google scholar
                Demos / videos
                                cbgl · fsm · cultureid · relief · multi-mpc
Work Experience
    2023.09 - present
                             Robotics Engineer
                             Center for Research and Technology Hellas (CERTH), Thessaloniki, Greece
    2018.09 - 2023.03 [4.5Y]
                             Robotics and Control Engineer
                             ECE Department, Aristotle University of Thessaloniki, Greece
    2016.09 - 2016.11 [3 mo]
                             Teaching Assistant · DD2380 Artificial Intelligence
                             KTH Royal Institute of Technology, Stockholm, Sweden
    2011.10 - 2012.03 [6 mo]
                             Database Designer · Egnatia Motorway S.A., Thessaloniki, Greece
    2011.03 - 2011.05 [3 mo]
                             Application Developer (Int) · Egnatia Motorway S.A., Thessaloniki, Greece
    2008.07 - 2009.06 [1Y]
                             Telecommunications Engineer · OTE Group, Thessaloniki, Greece
Voluntary Experience
    2013.10 - 2014.07 [10 mo]
                               Computer Vision Engineer, PANDORA Robotics Team
```

ECE Department, Aristotle University of Thessaloniki, Greece

Education

2018.09 - 2023.06Doctorate 2005.09 - 2013.07**Diploma** Electrical and Computer Engineering (ECE) Department Aristotle University of Thessaloniki, Greece 2015.09 - 2017.06Master of Science · Systems, Control, and Robotics School of Electrical Engineering and Computer Science KTH Royal Institute of Technology, Stockholm, Sweden

Computer and Other Skills

C/C++, Python, shell, MATLAB/Octave, {PL/}SQL Languages {Meta-}Operating Systems Linux, ROS 2, ROS git, OpenCV, Docker, Qt (cpp) | Tkinter (py), Behavior Trees, LATEX Tools Control Techniques

Languages

English Fluent — IELTS Score 8.5 (Greek Native)

References

Dr. Antonis Dimitriou · Coordinator of the projects for which I worked during my A.U.Th. years (+30) 697 88 96 350 | antodimi@auth.gr

Thessaloniki, Greece. JAN 2025 contact: (+30) 693 87 87 677 | alexandros.filotheou@gmail.com source: https://github.com/li9i/cv