# Alexandros Filotheou

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I have 7+ years of hands-on experience in robotics which includes SLAM, Localisation, Autonomous Navigation, Control, Computer Vision, and general integration, problem-solving, and troubleshooting. These I have acquired in real conditions with real robots as well as in simulation, working for research projects funded by the European Commission and the Greek State, or through volunteering. I am proficient in ROS and ROS 2, in versioning through git, virtualisation via Docker, and also in MAT-LAB/Octave, all the while under Linux. My primary coding language is C++ and my secondary Python.

# Work Experience

Sep 2023 – present	Robotics Engineer
	Center for Research and Technology Hellas (CERTH), Thessaloniki, Greece
Sep $2018 - \text{Mar } 2023 \ [4.5Y]$	Robotics and Control Engineer ECE Department, Aristotle University of Thessaloniki, Greece
Sep 2016 – Nov 2016 [3 mo]	<b>Teaching Assistant</b> · DD2380 Artificial Intelligence KTH Royal Institute of Technology, Stockholm, Sweden

## Voluntary Experience

Oct 2013 – Jul 2014 [10 mo] Computer Vision Engineer, PANDORA Robotics Team ECE Department, Aristotle University of Thessaloniki, Greece

## Education

Sep 2018 – Jun 2023 Sep 2005 – Jul 2013	
Sep $2015 - Jun\ 2017$	Master of Science · Systems, Control, and Robotics School of Electrical Engineering and Computer Science KTH Royal Institute of Technology, Stockholm, Sweden

## Skills

Languages C/C++, Python, shell, MATLAB/Octave {Meta-}Operating Systems Linux, ROS 2, ROS
Tools git, Docker, Eigen, Behavior Trees, Gazebo, CI/CD, Qt / Tkinter, OpenCV, IATEX

Control Techniques MPC, PID, LQR

#### Languages

English Fluent — IELTS Score 8.5 (Greek Native)

#### References

Dr. Antonis Dimitriou · Coordinator of the projects for which I worked during my A.U.Th. years (+30) 697 88 96 350 | antodimi@auth.gr

For a complete list of references, whether they be supervisors or coworkers, visit

https://github.com/li9i/cv/tree/master/references