Alexandros FILOTHEOU

Thessaloniki GR · alexandros.filotheou@gmail.com · (+30) 693 8787 677 · linkedin.com/in/alexandros-filotheou
github.com/li9i · Portfolio

Senior Robotics Engineer specialising in the full product lifecycle, from concept and simulation to continuous system integration and field deployment. With 9+ years of experience in integration, state estimation, sensor fusion, SLAM, localisation, autonomous navigation, control, perception, computer vision, and hardware. Delivered a 50% boost in localisation accuracy for a fleet of RFID-based inventory robots, achieving centimeter precision. Proven ability to materialise research into real-world development and deployment, bridging the two worlds to deliver cutting-edge systems with repeatable behaviours.

Skills

English	Native / Fluent (IELTS 8.5 - C2 Proficiency)
Languages	`C/C++`, `Python`, `shell`, `MATLAB/Octave`
Robotics/OS	`Linux`, `ROS/ROS 2`
Tools/Frameworks	`git`, `Docker`, Eigen, Behavior Trees, Gazebo, `CI/CD`, `Qt/Tkinter`, `OpenCV`
Control Techniques	MPC, PID, LQR

Experience

Robotics Software Engineer · ITI-CERTH, Thessaloniki GR — Sep 2023 – Present

- Owner of software integration and git repository maintainer in EU-funded R&D project RoBétArmé
- Determined development and deployment principles for 9 partners and >50 Dockerised ROS packages
- Orchestrated fleet of concrete- and metal-additive manufacturing robots with Behaviour Trees
- Identified bottlenecks and reduced deployment time >10x across fleet by utilising tmux features
- Ensured code quality via googletest and cpplint, continuous integration/deployment via CI/CD pipelines
- Achieved robust ROS-ROS 2 interoperability and communication across multiple machines using Zenoh

Robotics & Control Engineer · ECE dept., Aristotle University of Thessaloniki GR — Sep 2018 – Mar 2023

- Technical Leader of robotics division in large-scale R&D projects RELIEF and CultureId
- Developed and deployed autonomous ground and aerial platforms in libraries, museums, and outdoors
- Boosted RFID-tag localisation accuracy by >3x by robustifying LiDAR-based filtering via Fourier analysis
- Deployed human-robot applications engaging $2,000+$ visitors annually since 2023 at the AMTh museum
- Delivered production-grade 2D/3D SLAM and collision-avoiding navigation pipelines with intuitive user GUIs using Qt, teb planner, rtabmap, and karto
- Developed and integrated codebases for 18+ publications in top-tier IEEE journals/conferences, enabling multi-team experiments, translating novel robotics and RFID research to real-world solutions

Teaching Assistant · KTH Royal Institute of Technology, Stockholm SE — Sep 2016 – Nov 2016

- *DD2380 - Artificial Intelligence* under Prof. Patric Jensfelt

Volunteering

Computer Vision Engineer · PANDORA Robotics, Thessaloniki GR — Oct 2013 – Jul 2014

- Increased rescue probabilities by developing a C++ wall-hole detection system using Microsoft Kinect RGB-D in the international RoboCup Rescue competition, gaining 2nd place in 2015

Links

Software packages	`ros2-utils` · `cbgl` · `fsm` · `lama-odom` · `pandora-hole-detection`
Demos/Videos	Global Localisation · LiDAR Odometry · Multi-agent navigation · RELIEF · CultureId
Publications	[Global Localisation] · [LiDAR Odometry] · [Multi-agent navigation]

Education

Doctorate · Electrical & Computer Engineering · Aristotle University of Thessaloniki — Sep 2018 – Jun 2023
Master of Science · Systems, Control, and Robotics · KTH Royal Inst. of Technology — Sep 2015 – Jun 2017
Diploma · Electrical & Computer Engineering · Aristotle University of Thessaloniki — Sep 2005 – Jul 2013

References

- Antonis Dimitriou · Coordinator of R&D projects · (+30) 697 88 96 350 · antodimi@auth.gr
- A complete list of professional references comprising supervisors and colleagues may be found at

github.com/li9i/cv/tree/master/references