
The background of the slide is a dark blue, abstract image. It features a perspective view of a tunnel or a path that recedes into the distance. The walls of the tunnel are composed of glowing binary code (0s and 1s) in various shades of blue and green. Light streaks and lens flare effects are visible, creating a sense of motion and depth. The overall aesthetic is futuristic and technological.

CWE Challenge - Interpreter

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Introduction

This challenge consists of implementing a header file provided to accurately interpret the binary file. To do this, I created two functions from the “interpreter.h” file, `sizeofInstruction()` and `interpretByteArray()`. This writeup will showcase how I used these two functions to interpret the binary file.

Interpreter Program

Function Declarations

At the start of the program, I make sure to include the “interpreter.h” file as well as “stdint.h”. There are three functions total that I use in this program: `sizeofInstruction()`, `interpretByteArray()`, and `reverse()`.

```
1 #include "interpreter.h"
2 #include <stdint.h>
3
4 //function declarations
5 int sizeofInstruction(uint8_t opcode);
6 unsigned char reverse(uint8_t b);
7 void interpretByteArray(uint8_t *byteArray);
```

The code for these functions are written after the main function.

Initialization

At the start of `main()`, a FILE pointer is created to read in bytes from the binary file.

```
1 int main()
2 {
3     FILE *fp = fopen(FILE_NAME, "rb");
4     if (fp == NULL)
5     {
6         exit(1);
7     }
8
9     /*
10      * read in the number of bytes and store them into a byte array
11      */
12     fseek(fp, 0, SEEK_END); //move the file pointer to the end of the
        file
13     long numberOfBytes = ftell(fp); //save the number of bytes
14     fseek(fp, 0, SEEK_SET); //move the file pointer back to the
        beginning of the file
```

The `fseek()` is used to traverse to the end of the file and `ftell()` will be used to save the byte count that the file pointer is pointing to. Then, `fseek()` is used again to set the file pointer back to the beginning of the file. Now, we can create the byte array that will save all the data from the binary.

```
1  uint8_t *byteArray = malloc(numberOfBytes * sizeof(uint8_t)); //create
    the byte array
2      if (byteArray == NULL)
3      {
4          exit(1);
5      }
6
7      //read in the bytes and place them in the byte array
8      int i = 0;
9      while (!feof(fp))
10     {
11         fread(&byteArray[i], sizeof(uint8_t), 1, fp);
12         i++;
13     }
14     fclose(fp);
15     fp = NULL;
```

Memory is allocated to `byteArray` equal to the number of bytes in the file. After reading in the bytes, `fclose()` is used to close the file and the file pointer is set to `NULL`.

Function Calls

At the end of `main()`, I run the following functions to interpret and print the flag as well as freeing the byte array.

```
1  //function calls
2      interpretByteArray(byteArray);
3      free(byteArray);
4      return 0;
5  }
```

The above code is the end of `main`, which means `interpretByteArray()` was really the only function I used in `main()`. However, the following functions were also used in this program.

sizeofInstruction()

This function will take a byte and return the size of the instruction that the byte represents.

```
1  //used a function to receive the correct instruction length
2  int sizeofInstruction(uint8_t opcode)
3  {
```

```
4     switch(opcode)
5     {
6         case END:
7         {
8             return END_SIZE;
9         }
10        case JMP:
11        {
12            return JMP_SIZE;
13        }
14        case SWP:
15        {
16            return SWP_SIZE;
17        }
18        case ADD:
19        {
20            return ADD_SIZE;
21        }
22        case XOR:
23        {
24            return XOR_SIZE;
25        }
26        case INVERT:
27        {
28            return INVERT_SIZE;
29        }
30        case PRINT:
31        {
32            return PRINT_SIZE;
33        }
34        default:
35        {
36            printf("%s", "unknown opcode");
37            break;
38        }
39    }
40    return 0;
41 }
```

A switch statement is used to avoid going through nested if statements.

reverse()

This function will take a byte and return the bytes in reverse order.

```
1  /*
2   * function to reverse the bits of a byte.
3   * First the left four bits are swapped with the right four bits.
```

```

4  * Then all adjacent pairs are swapped and then all adjacent single
    bits.
5  * This results in a reversed order.
6  */
7  uint8_t reverse(uint8_t b) {
8      b = (b & 0xF0) >> 4 | (b & 0x0F) << 4;
9      b = (b & 0xCC) >> 2 | (b & 0x33) << 2;
10     b = (b & 0xAA) >> 1 | (b & 0x55) << 1;
11     return b;
12 }

```

I was thankfully able to obtain this code from stack overflow. The alternative to this function is to use a lookup table; using a lookup table would have technically been more efficient, but for this program, efficiency is not as necessary. If needed, the following is the lookup table I would have used from the same source.

```

1  unsigned char reverse(unsigned char x)
2  {
3      static const unsigned char table[] = {
4          0x00, 0x80, 0x40, 0xc0, 0x20, 0xa0, 0x60, 0xe0,
5          0x10, 0x90, 0x50, 0xd0, 0x30, 0xb0, 0x70, 0xf0,
6          0x08, 0x88, 0x48, 0xc8, 0x28, 0xa8, 0x68, 0xe8,
7          0x18, 0x98, 0x58, 0xd8, 0x38, 0xb8, 0x78, 0xf8,
8          0x04, 0x84, 0x44, 0xc4, 0x24, 0xa4, 0x64, 0xe4,
9          0x14, 0x94, 0x54, 0xd4, 0x34, 0xb4, 0x74, 0xf4,
10         0x0c, 0x8c, 0x4c, 0xcc, 0x2c, 0xac, 0x6c, 0xec,
11         0x1c, 0x9c, 0x5c, 0xdc, 0x3c, 0xbc, 0x7c, 0xfc,
12         0x02, 0x82, 0x42, 0xc2, 0x22, 0xa2, 0x62, 0xe2,
13         0x12, 0x92, 0x52, 0xd2, 0x32, 0xb2, 0x72, 0xf2,
14         0x0a, 0x8a, 0x4a, 0xca, 0x2a, 0xaa, 0x6a, 0xea,
15         0x1a, 0x9a, 0x5a, 0xda, 0x3a, 0xba, 0x7a, 0xfa,
16         0x06, 0x86, 0x46, 0xc6, 0x26, 0xa6, 0x66, 0xe6,
17         0x16, 0x96, 0x56, 0xd6, 0x36, 0xb6, 0x76, 0xf6,
18         0x0e, 0x8e, 0x4e, 0xce, 0x2e, 0xae, 0x6e, 0xee,
19         0x1e, 0x9e, 0x5e, 0xde, 0x3e, 0xbe, 0x7e, 0xfe,
20         0x01, 0x81, 0x41, 0xc1, 0x21, 0xa1, 0x61, 0xe1,
21         0x11, 0x91, 0x51, 0xd1, 0x31, 0xb1, 0x71, 0xf1,
22         0x09, 0x89, 0x49, 0xc9, 0x29, 0xa9, 0x69, 0xe9,
23         0x19, 0x99, 0x59, 0xd9, 0x39, 0xb9, 0x79, 0xf9,
24         0x05, 0x85, 0x45, 0xc5, 0x25, 0xa5, 0x65, 0xe5,
25         0x15, 0x95, 0x55, 0xd5, 0x35, 0xb5, 0x75, 0xf5,
26         0x0d, 0x8d, 0x4d, 0xcd, 0x2d, 0xad, 0x6d, 0xed,
27         0x1d, 0x9d, 0x5d, 0xdd, 0x3d, 0xbd, 0x7d, 0xfd,
28         0x03, 0x83, 0x43, 0xc3, 0x23, 0xa3, 0x63, 0xe3,
29         0x13, 0x93, 0x53, 0xd3, 0x33, 0xb3, 0x73, 0xf3,
30         0x0b, 0x8b, 0x4b, 0xcb, 0x2b, 0xab, 0x6b, 0xeb,
31         0x1b, 0x9b, 0x5b, 0xdb, 0x3b, 0xbb, 0x7b, 0xfb,
32         0x07, 0x87, 0x47, 0xc7, 0x27, 0xa7, 0x67, 0xe7,
33         0x17, 0x97, 0x57, 0xd7, 0x37, 0xb7, 0x77, 0xf7,
34         0x0f, 0x8f, 0x4f, 0xcf, 0x2f, 0xaf, 0x6f, 0xef,

```

```
35     0x1f, 0x9f, 0x5f, 0xdf, 0x3f, 0xbf, 0x7f, 0xff,  
36 };  
37     return table[x];  
38 }
```

interpretByteArray()

This function takes in a byte array and prints the flag

```
1 void interpretByteArray(uint8_t *byteArray)  
2 {  
3     int currentInstruction = 0;    //initialize current instruction  
4  
5     while (1)  
6     {  
7         uint8_t opcode = byteArray[currentInstruction]; //initialize  
            opcode  
8         int instructionLength = sizeofInstruction(opcode); //retrieve  
            the size of the instruction  
9  
10        switch (opcode)
```

The beginning of this function will initialize the index of the current instruction. For example, the first instruction will be “byteArray[currentInstruction]”. The while loop will take the current instruction and save it as a byte called opcode. This opcode will be passed to the sizeofInstruction() to save the size of the current instruction to “instructionLength”. Now, at the end of every case, the current instruction index can be updated by adding the “instructionLength” variable.

The opcode is passed to a switch statement to execute the correct code based on the instruction given.

```
1 switch (opcode)  
2 {  
3     case END:  
4     {  
5         return;  
6     }  
7     case JMP:  
8     {  
9         //save the offset as a signed int and move the current  
            instruction  
10        int16_t offset = *(int16_t *) (byteArray + currentInstruction +  
            1); //cast the value as a signed integer  
11        currentInstruction += offset;  
12        break;  
13    }
```

Going down the same line as the header file, I started with the case “END” which will just return from the function call back to main(). The “JMP” case saves the offset and jumps to the byte from the current index to the index of the added offset in the byte array.

```
1 case SWP:
2     {
3         //swap the values at both indexes given
4         uint8_t index1 = byteArray[currentInstruction+1]; //save the
            value of index1
5         uint8_t index2 = byteArray[currentInstruction+2]; //save the
            value of index2
6         uint8_t tmp = byteArray[index1]; //save the value of byte array
            at index1 to a tmp variable
7         byteArray[index1] = byteArray[index2]; //set the value at index
            1 equal to the value at index2
8         byteArray[index2] = tmp; //set the value at index2 equal to the
            original value at index1
9         currentInstruction += instructionLength;
10        break;
11    }
```

The “SWP” case save to indexes and then creates a temporary index which is equal to the first index. Saving the value to a temporary index allows the first index to be set to be equal to the second index. After this is done, the second index can be set to the temporary index which holds the original first index. Now they are swapped!

```
1 case ADD:
2     {
3         //Add a constant unsigned int to the 4 bytes at the given byte
            index.
4         uint8_t index = byteArray[currentInstruction+1];
5         uint32_t adding = *(uint32_t *) (byteArray+currentInstruction+2)
            ; //cast the value to an unsigned integer
6         *(uint32_t *) (byteArray + index) += adding; //add the value at
            the index indicated
7         currentInstruction += instructionLength;
8         break;
9     }
```

This instruction simply adds the value given to the value at the given index, ensuring that the casting is done right ensures things are accurately interpreted. This is important for all the instructions.

```
1 case XOR:
2     {
3         //Xor a constant long long to the 8 bytes at the given byte
            index.
4         uint8_t index = byteArray[currentInstruction + 1];
5         uint64_t xoring = *((uint64_t *) (byteArray + currentInstruction
            + 2)); //cast the value to a long long integer
```



```
6      *((uint64_t *) (byteArray + index)) ^= xoring; //xor the value
      to the 8 bytes at the given byte index
7      currentInstruction += instructionLength;
8      break;
9  }
```

This instruction xor's the byte given to the one at the given index of the byte array. These instructions seem simple, but the casting is not done correctly, then the interpretation will be off.

```
1  case INVERT:
2      {
3          //reverse the order of the bits at the given index
4          uint8_t index = byteArray[currentInstruction+1]; //
5          byteArray[index] = reverse(byteArray[index]); //reverse the
          bits of the byte
6          currentInstruction += instructionLength;
7          break;
8      }
```

This instruction was easier to do because there is a function used to invert or reverse the bits in the byte at the given index.

```
1  case PRINT:
2      {
3          //print the character given
4          uint8_t asciiChar = byteArray[currentInstruction+1];
5          printf("%c", asciiChar);
6          currentInstruction += instructionLength;
7          break;
8      }
9  default:
10     {
11         fprintf(stderr, "\nError: Invalid opcode %02x at instruction %d
            \n", opcode, currentInstruction);
12         return;
13     }
```

The PRINT instruction prints the byte simply enough. Since this is the end of the switch statement, I made sure to add a default case that will help me debug the program when an opcode was read in wrong. This happened mostly because I was flipping the bits in INVERT rather than reversing the bits. I would caution to read the instructions carefully.

Compiling the Program

After compiling the program and making sure it works we get our flag!

```
lilbits@ubuntu:~/Documents/Challenges/Programming/Interpreter$ ./interpreter
flag{1nt3rpr3t_m3}lilbits@ubuntu:~/Documents/Challenges/Programming/Interpreter$
```

Figure 1: Flag

Memory Leakage

To check and see if I freed the memory correctly I used a tool called valgrind.

```
flag{1nt3rpr3t_m3}==66099==
==66099== HEAP SUMMARY:
==66099==    in use at exit: 0 bytes in 0 blocks
==66099==   total heap usage: 4 allocs, 4 frees, 5,848 bytes allocated
==66099==
==66099== All heap blocks were freed -- no leaks are possible
```

Figure 2: Valgrind

Here we can see in the “Heap Summary” that all memory was freed and there are no memory leaks!

Conclusion

This challenge was interesting to do because I knew I would have to use a custom header file. Creating all the instructions for each opcode helped me understand how to cast variables and save the data accurately from the byte array.

References

1. <https://www.geeksforgeeks.org/write-header-file-c/>
2. <https://www.techiedelight.com/find-size-of-file-c/>
3. https://www.tutorialspoint.com/c_standard_library/c_function_fseek.htm
4. <https://stackoverflow.com/questions/2602823/in-c-c-whats-the-simplest-way-to-reverse-the-order-of-bits-in-a-byte>