

Lab 2: Interprocess Communications with Pipes and Java Threads

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1 Introduction and Objectives

The objective of this lab is to explore interprocess communication (IPC) using UNIX/Linux pipes and to learn about Java threads and thread pools. The specific goals include:

- Understanding IPC mechanisms through the use of pipes in a C program.
- Gaining experience with process management in a Linux environment.
- Learning how to implement and manage threads in Java.
- Comparing the performance of individual threads versus a thread pool.

2 Methodology

The lab was conducted in a Linux virtual machine environment. The following steps were taken to achieve the objectives:

1. **Modify C Program:** Enhanced the `mon.c` program to create `mon2.c` for monitoring processes using pipes.
2. **Compilation:** Compiled the modified `mon2.c` program using `gcc`.
3. **Execution:** Ran the `mon2` program with the `calcloop` argument and observed the filtered output.

4. **Signal Handling:** Experimented with sending `SIGSTOP` and `SIGCONT` signals to the `calclloop` process.
5. **Java Setup:** Compiled the provided Java files for generating the Mandelbrot set.
6. **Execution of Mandelbrot:** Executed the `MandelBrot` application with various parameters.
7. **Thread Implementation:** Modified the Java code to use threads for rendering the Mandelbrot set.
8. **Thread Pool Implementation:** Further modified the code to utilize a thread pool with `Executors`.

3 Presentation and Analysis of Results

3.1 C Program Execution

The execution of the `mon2` program yielded filtered output for the `calclloop` process (Fig. 3). The following changes were made to the original `mon.c`:

1. Creation of `kill_process` function to gracefully terminate a process given a `pid` (line 9).
2. Creation of pipe `fd` for communication between `procmon` and `filter` (line 29).
3. Fork a new process to run `filter` (line 71).
4. Pipe standard output of `procmon` through `fd` (line 61) to standard input of `filter` (line 79) using `dup2()`.

```
#include <stdio.h>
#include <stdlib.h>
#include <sys/types.h>
#include <sys/wait.h>
#include <signal.h>
#include <unistd.h>
#include <string.h>

void kill_process(pid_t pid) {
    if (kill(pid, SIGTERM) == -1) {
```



```

// Fork new process for procmon
procmon_pid = fork();
if(procmon_pid < 0) {
    fprintf(stderr, "Fork failed");
    kill_process(pid);
    return 1;
} else if (procmon_pid == 0) {
    close(fd[0]); // Close read end of pipe
    dup2(fd[1], STDOUT_FILENO); // Redirect output
    of process to write end of pipe
    close(fd[1]); // Close write end of pipe

    // Execute procmon with pid_str as arg
    execl("./procmon", "procmon", pid_str, (char
        *)NULL);
    perror("execl for procmon failed\n");
    exit(EXIT_FAILURE);
}

// Fork new process for filter
filter_pid = fork();
if (filter_pid < 0) {
    fprintf(stderr, "Fork failed\n");
    kill_process(pid);
    kill_process(procmon_pid);
    return 1;
} else if (filter_pid == 0) {
    close(fd[1]); // Close write end of pipe
    dup2(fd[0], STDIN_FILENO); // Redirect read end
    of pipe to process input
    close(fd[0]); // Close read end of pipe

    // Execute filter
    execl("./filter", "filter", (char *)NULL);
    perror("execl for filter failed\n");
    exit(EXIT_FAILURE);
}

// Close both ends of pipe
close(fd[1]);
close(fd[0]);

sleep(20);

```

```
        kill_process(pid);
        sleep(2);
        kill_process(procmon_pid);
        kill_process(filter_pid);
        waitpid(pid, NULL, 0);
        waitpid(procmon_pid, NULL, 0);
        waitpid(filter_pid, NULL, 0);
    }

    return 0;
}
```

3.2 Signal Handling

We successfully sent signals to the `calcloop` process, observing the effects on its output. Screenshots of the commands and their effects are shown in Figure 4.

3.3 Java Threads Implementation

The modified Java code effectively utilized threads for rendering the Mandelbrot set. The updated display is shown in Figure 4.

3.4 Thread Pool Implementation

The implementation of a thread pool improved performance by managing thread resources more efficiently. The impact can be seen in Figure 5.

4 Discussion and Conclusion

This lab provided valuable insights into interprocess communication and threading in Java. Key learnings include:

- The effectiveness of using pipes for IPC in C programs.
- The importance of process management and signal handling in a Linux environment.
- Practical experience in Java threading and the advantages of using thread pools for resource management.

Challenges Encountered

We expected that sending the SIGCONT signal would resume the process, but looking at the output of mon2 in test.log, it seems that it never continued.

Screenshots and Evidence

```
liam@liam-server:~$ tar -xvf lab2.tar
lab2/
lab2/calclloop
lab2/code/
lab2/code/calclloop.c
lab2/code/cplloop.c
lab2/code/filter.c
lab2/code/mon2.c
lab2/code/procmon.c
lab2/cplloop
lab2/filter
lab2/procmon
```

Figure 1: Extraction of lab2.tar.

```
liam@liam-server:~/lab2$ gcc -o mon2 ./mon2.c
./mon2.c: In function 'main':
./mon2.c:51:29: warning: 'sprintf' may write a terminating nul past the end of the destination [-Wformat-overflow=]
   51 |     sprintf(pid_str, "%d", pid);
      |                               ^
./mon2.c:51:9: note: 'sprintf' output between 2 and 11 bytes into a destination of size 10
   51 |     sprintf(pid_str, "%d", pid);
      |     ^~~~~~
liam@liam-server:~/lab2$
```

Figure 2: Compilation of mon2.c.

```
liam@liam-server:~/lab2$ ./mon2 calclloop

Monitoring /proc/56614/stat:
Time      State      SysTm  UstTm
0         Sleeping(memory)  0      0
2         Running      0      0
3         Sleeping(memory)  0      74
6         Running      0      168
7         Sleeping(memory)  0      148
10        Running      0      268
11        Sleeping(memory)  0      224
14        Running      0      380
15        Sleeping(memory)  0      301
20        Zombie       0      373
liam@liam-server:~/lab2$
```

Figure 3: Execution of mon2.

```
liam@liam-server:~/lab2$ ./mon2 calclloop > test.log &
[1] 56676
liam@liam-server:~/lab2$ ps
  PID TTY          TIME CMD
 56563 pts/1    00:00:00 bash
 56676 pts/1    00:00:00 mon2
 56677 pts/1    00:00:00 calclloop
 56678 pts/1    00:00:00 ps
liam@liam-server:~/lab2$ kill -s SIGSTOP 56677
liam@liam-server:~/lab2$ kill -s SIGCONT 56677
liam@liam-server:~/lab2$
[1]+  Done                  ./mon2 calclloop > test.log
liam@liam-server:~/lab2$ cat test.log

      Monitoring /proc/56677/stat:
Time      State          SysTm   UsrTm
0         Sleeping(memory) 0         0
2         Running              0         0
3         Sleeping(memory) 0        72
6         Running              0       100
7         Sleeping(memory) 0       142
10        Traced/Stopped    0       142
liam@liam-server:~/lab2$
```

Figure 4: Sending signals to calclloop.

Figure 5: Compilation of Java files for Mandelbrot.

Figure 6: Execution of MandelBrot with parameters.