

271B - Homework 1

Problem 1. The standard Ornstein-Uhlenbeck process X_t is a Gaussian process with mean zero and auto-covariance $C(t, s) = \mathbb{E}[X_t X_s] = \exp(-|t - s|)/2$. Let N_t be the standard Poisson process and define the process $Y_t = \zeta(-1)^{N_t}$, where ζ is a random variable independent of the Poisson process that takes values ± 1 with probability $1/2$.

Show that X_t and $Z_t = Y_{t/2}/\sqrt{2}$ are both stationary in the strong sense and have the same covariance. Does Y_t satisfy the Kolmogorov continuity condition? Are these processes stochastically continuous?

Solution. First we'll show that X_t is stationary. Let $\tau \in \mathbb{R}$. Since X_t is Gaussian with mean zero for all t , so is $X_{t+\tau}$. For any s and t we also have that

$$\mathbb{E}[X_{s+\tau} X_{t+\tau}] = \frac{1}{2} e^{-|(s+\tau)-(t+\tau)|} = \frac{1}{2} e^{-|s-t|} = \mathbb{E}[X_s X_t].$$

Since a Gaussian process is determined by its mean and covariance, we have that X_t and $X_{t+\tau}$ are equal in distribution, so the process is stationary.

Now for Z_t . We claim that Z_t has the Markov property, i.e. for any $t_1 < t_2 < \dots < t_n$ and $\alpha_i = \pm 1/\sqrt{2}$

$$\begin{aligned} \mathbb{P}[Z_{t_1} = \alpha_1, Z_{t_2} = \alpha_2, \dots, Z_{t_n} = \alpha_n] \\ = \mathbb{P}[Z_{t_1} = \alpha_1] \mathbb{P}[Z_{t_2} = \alpha_2 \mid Z_{t_1} = \alpha_1] \cdots \mathbb{P}[Z_{t_n} = \alpha_n \mid Z_{t_{n-1}} = \alpha_{n-1}] \end{aligned} \quad (1)$$

Informally, the value of Z_{t_j} given $Z_{t_1}, \dots, Z_{t_{j-1}}$ depends only on the number of sign flips of Z over the interval $(t_{j-1}, t_j]$. This only depends on the parity of $N_{t_j} - N_{t_{j-1}}$. Let's look at the terms on the right-hand side of (1).

$$\begin{aligned} \mathbb{P}[Z_{t_j} = \alpha_j \mid Z_{t_{j-1}} = \alpha_{j-1}] &= \begin{cases} \mathbb{P}[N_{t_j - t_{j-1}} \text{ is even}], & \text{if } \alpha_j = \alpha_{j-1} \\ \mathbb{P}[N_{t_j - t_{j-1}} \text{ is odd}], & \text{if } \alpha_j = -\alpha_{j-1} \end{cases} \\ &= \mathbb{P}[Z_{t_j + m} = \alpha_j \mid Z_{t_{j-1} + m} = \alpha_{j-1}] \end{aligned} \quad (2)$$

The last equality follows from the stationarity of Poisson increments. Equations (1) and (2) imply that Z is indeed stationary.

Let's compute the covariance of Z_t . Since ζ is independent of N_t we have

$$\mathbb{E}[Z_t] = \frac{1}{\sqrt{2}} \mathbb{E}[\zeta] \cdot \mathbb{E}[Y_{t/2}] = 0.$$

Consequently, for any s and t , the covariance is given by

$$\begin{aligned}\mathbb{E}[Z_s Z_t] &= \mathbb{E}[Z_0 Z_{|t-s|}] = \frac{1}{2} \mathbb{E}[\zeta^2] \mathbb{E}[(-1)^{N_{|t-s|/2}}] = \frac{1}{2} (\mathbb{P}[N_{|t-s|/2} \text{ is even}] - \mathbb{P}[N_{|t-s|/2} \text{ is odd}]) \\ &= \frac{1}{2} (2\mathbb{P}[N_{|t-s|/2} \text{ is even}] - 1). \quad (3)\end{aligned}$$

As for that probability, we have

$$\mathbb{P}[N_{|t-s|/2} \text{ is even}] = \sum_{n=0}^{\infty} \mathbb{P}[N_{|t-s|/2} = 2n] = \sum_{n=0}^{\infty} \frac{(|t-s|/2)^{2n} e^{-|t-s|/2}}{(2n)!} = e^{-|t-s|/2} \cosh(|t-s|/2).$$

Substituting this expression into (3) gives

$$\mathbb{E}[Z_s Z_t] = \frac{1}{2} e^{-|t-s|/2} = \mathbb{E}[X_s X_t],$$

as desired.

Let's check to see if Y_t satisfies the Kolmogorov continuity condition. For any s and t , the quantity $|(-1)^{N_t} - (-1)^{N_s}|$ will be zero if N_t and N_s have the same parity and 2 if they have opposite parity. By the stationarity of Poisson increments, we have that

$$|(-1)^{N_t} - (-1)^{N_s}| = \begin{cases} 0, & N_{|t-s|} \text{ is even} \\ 2, & N_{|t-s|} \text{ is odd} \end{cases}.$$

Let $\alpha > 0$. By the above reasoning, we have that

$$\mathbb{E}[|Y_t - Y_s|^\alpha] = 2^\alpha \mathbb{P}[N_{|t-s|} \text{ is odd}] = 2^\alpha e^{-|t-s|} \sinh |t-s| = 2^{\alpha-1} (1 - e^{-2|t-s|}). \quad (4)$$

We claim that there are no positive K or β such that

$$\mathbb{E}[|Y_t - Y_s|^\alpha] \leq K |t-s|^{1+\beta}$$

for all s, t . The right-hand side of (4) is $\Theta(|t-s|)$ as $|t-s| \rightarrow 0$, while $K |t-s|^{1+\beta}$ is $o(|t-s|)$ as $|t-s| \rightarrow 0$. We conclude that Y_t does *not* satisfy the Kolmogorov continuity condition.

Let's check for stochastic continuity. By Markov we have

$$\begin{aligned}\mathbb{P}[|X_{t+h} - X_t| > \delta] &\leq \frac{1}{\delta^2} \mathbb{E}[(X_{t+h} - X_t)^2] \\ &= \frac{1}{\delta^2} (1 - e^{-|h|}),\end{aligned}$$

which goes to zero as $h \rightarrow 0$ for any $\delta > 0$, so X is stochastically continuous. Now for Y . The quantity $|Y_{t+h} - Y_t|$ is zero when N_{t+h} and N_t have the same parity and is 2 when they have opposite parity. For $\delta < 2$ we have

$$\begin{aligned}\mathbb{P}[|Y_{t+h} - Y_t| > \delta] &= \mathbb{P}[N_{|h|} \text{ is odd}] \\ &= e^{-|h|} \sinh |h|,\end{aligned}$$

which goes to zero as $h \rightarrow 0$, so Y is stochastically continuous. The same argument shows that Z is stochastically continuous as well. \square

Problem 2. Let X_n be defined by the stochastic recursion

$$X_{n+1} = X_n - \Delta t X_n + (B_{(n+1)\Delta t} - B_{n\Delta t}), \quad X_0 = \zeta, \quad (5)$$

for B_t standard Brownian motion. Find ζ so that X_n is stationary in the strong sense and give the associated auto-covariance function. What is the continuum limit of this process as $n \rightarrow \infty$, $\Delta t \rightarrow 0$ so that $n\Delta t = t$.

Solution. By induction we have that

$$X_{n+1} = (1 - \Delta t)^{n+1} \zeta + \sum_{k=0}^n (1 - \Delta t)^{n-k} (B_{(k+1)\Delta t} - B_{k\Delta t}). \quad (6)$$

By the above expansion, we can see that for $0 < \Delta t < 1$, ζ contributes less to X_{n+1} . The sum term is a sum of independent Gaussians, and hence Gaussian. We conclude that for n large, X_n approaches a Gaussian. In order for the process to be stationary, ζ must also be Gaussian.

Since ζ is Gaussian, it is determined by its mean and variance. Taking the expectation on both sides of the recursive formula (5) gives

$$\mathbb{E}[X_{n+1}] = (1 - \Delta t) \mathbb{E}[X_n].$$

By stationarity, $\mathbb{E}[X_{n+1}] = \mathbb{E}[X_n]$. The above equation then forces $\mathbb{E}[X_n] = 0$ for all n , so $\mathbb{E}[\zeta] = 0$ as well. Taking the variance of both sides of the inductive formula (6) and using stationarity gives

$$\begin{aligned} \text{Var}[\zeta] = \text{Var}[X_{n+1}] &= (1 - \Delta t)^{2(n+1)} \text{Var}[\zeta] + \Delta t \sum_{k=0}^n (1 - \Delta t)^{2(n-k)} \\ &= (1 - \Delta t)^{2(n+1)} \text{Var}[\zeta] + \Delta t (1 - \Delta t)^{2n} \cdot \frac{1 - (1 - \Delta t)^{-2(n+1)}}{1 - (1 - \Delta t)^{-2}}. \end{aligned}$$

Solving for $\text{Var}[\zeta]$ gives $\text{Var}[\zeta] = \frac{1}{2 - \Delta t}$.

Now let's show that the choice $\zeta \sim \mathcal{N}(0, \frac{1}{2 - \Delta t})$ makes X_n stationary. It's clear that this choice of ζ makes X_n a Gaussian process with zero mean for all n , so to check stationarity, it suffices to show that $\text{Cov}(X_n, X_{n+1})$ is independent of n . The same calculation that we used to find $\text{Var}[\zeta]$ shows that $\text{Var}[X_n] = \frac{1}{2 - \Delta t}$. Now we compute the covariance.

$$\text{Cov}(X_n, X_{n+1}) = (1 - \Delta t) \text{Var}[X_n] + \text{Cov}(X_n, B_{(n+1)\Delta t} - B_{n\Delta t}) = \frac{1 - \Delta t}{2 - \Delta t}.$$

Here we've used the fact that disjoint increments of Brownian motion are independent. Since the covariance is independent of n , we conclude that this choice of ζ does indeed make the process stationary. By induction, the auto-covariance is given by

$$\text{Cov}(X_n, X_{n+m}) = \frac{(1 - \Delta t)^m}{2 - \Delta t}.$$

□

Problem 3. Consider

$$X_t = \int_0^t (t-s)^{H-1/2} dB_s,$$

for B_t standard Brownian motion. For which values of H is X_t well defined? Find the distribution of X_t . Compare with the distribution of fractional Brownian motion B_t^H .

Solution. The family $(t-s)^{H-1/2}$ is continuous and adapted, and hence progressively measurable. We also have

$$\mathbb{E} \left[\int_0^t (t-s)^{2H-1} ds \right] = \int_0^t (t-s)^{2H-1} ds < \infty \iff H > 0.$$

Consequently, X_t is well defined for $H > 0$. The family $f_s^{(t)} = (t-s)^{H-1/2}$ is uniformly \mathbb{P} -integrable, so we have

$$X_t = \int_0^t (t-s)^{H-1/2} dB_s = \lim_{\Delta t \rightarrow 0} \sum_{k=1}^{t/\Delta t} f_{t_i}^{(t)} \Delta B_{t_{i+1}},$$

where $t_i = i\Delta t$, and $\Delta B_{t_{i+1}} = B_{t_{i+1}} - B_{t_i}$. Now for any fixed t , the values $f_{t_i}^{(t)}$ are deterministic constants. The increments $\Delta B_{t_{i+1}}$ are independent Gaussians, so the above sum is a limit (in some sense) of Gaussians. We'll show that the above sum weakly converges to a Gaussian by showing that its mean and variance converge.

The increment $\Delta B_{t_{i+1}}$ has mean zero, so for any $\Delta t > 0$, the above sum has mean zero. As the increments are independent and have variance Δt , the variance of the sum is given by

$$\sigma_{\Delta t}^2 = \sum_{k=1}^{t/\Delta t} \left(f_{t_i}^{(t)} \right)^2 \Delta t,$$

which we recognize as a Riemann sum that converges to $\int_0^t (f^{(t)})^2 ds$. We conclude that

$$X_t \sim \mathcal{N} \left(0, \int_0^t (t-s)^{2H-1} ds \right) = \mathcal{N} \left(0, \frac{t^{2H}}{2H} \right).$$

This almost has the same distribution as fractional Brownian motion, which satisfies

$$B_t^H \sim \mathcal{N}(0, t^{2H}).$$

□

Problem 4. Prove directly from the definition of Itô integrals the integration by parts relation:

$$\int_0^t s dB_s = tB_t - \int_0^t B_s ds.$$

Proof. Since the function $(s, \omega) \mapsto s$ is deterministic, it is adapted and uniformly integrable, so we have by summation by parts

$$\begin{aligned}
\int_0^t s \, dB_s &= \lim_{\Delta t \rightarrow 0} \sum_{k=1}^{t/\Delta t} t_i (B_{t_{i+1}} - B_{t_i}) \\
&= \lim_{\Delta t \rightarrow 0} \left[t_{t/\Delta t} (B_{t_{t/\Delta t}} - B_0) - \sum_{k=1}^{t/\Delta t} B_{t_i} (t_{i+1} - t_i) \right] \\
&= \lim_{\Delta t \rightarrow 0} \left[t B_t - \sum_{k=1}^{t/\Delta t} B_{t_i} \Delta t \right] \\
&= t B_t - \int_0^t B_s \, ds.
\end{aligned}$$

□

Problem 5. Prove directly from the definition of the Itô integral that

$$\int_0^t B_s^2 \, dB_s = \frac{1}{3} B_t^3 - \int_0^t B_s \, ds.$$

Proof. The family of functions $\{B_s^2\}_{s \leq t}$ is uniformly \mathbb{P} -integrable since $\mathbb{E}[B_s^2] = s$.

□