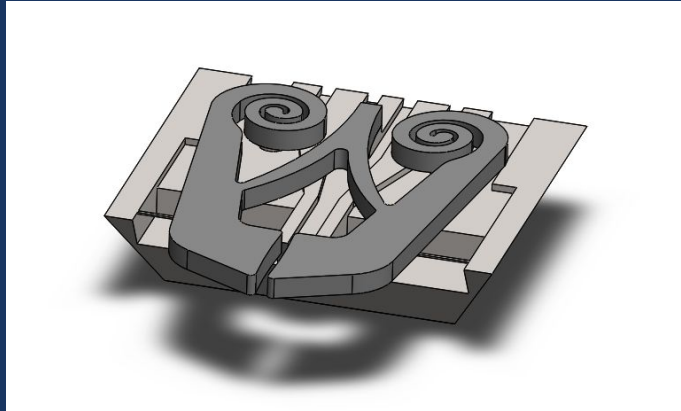


MicroSurgical Suture Device for Targeted Neurovascular Hemostasis with Integrated Hotwire Flow Sensor and Nitinol Actuator

Liam McHugh

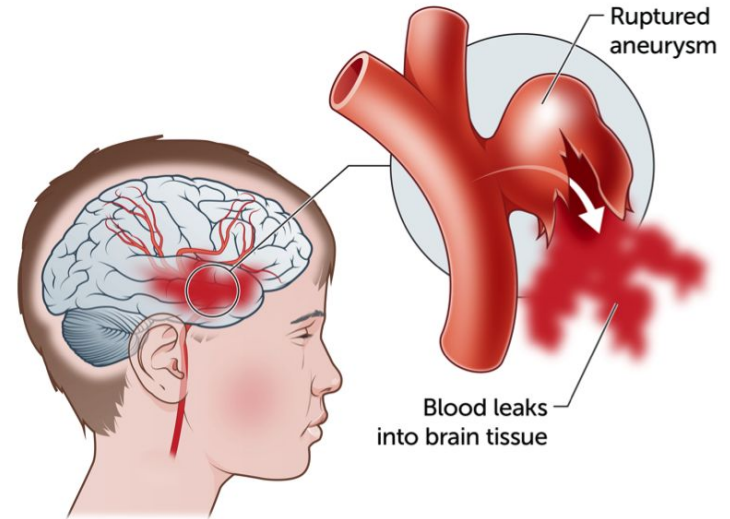
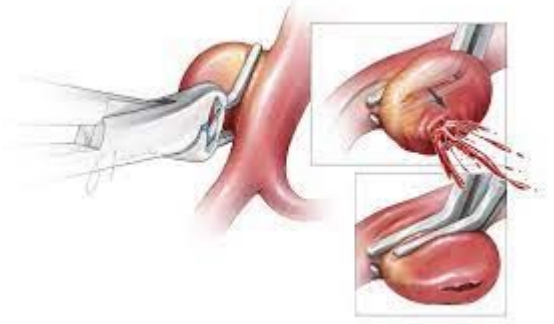
Sukhpal Ghotra

Berkeley
UNIVERSITY OF CALIFORNIA



Problem, System Requirements

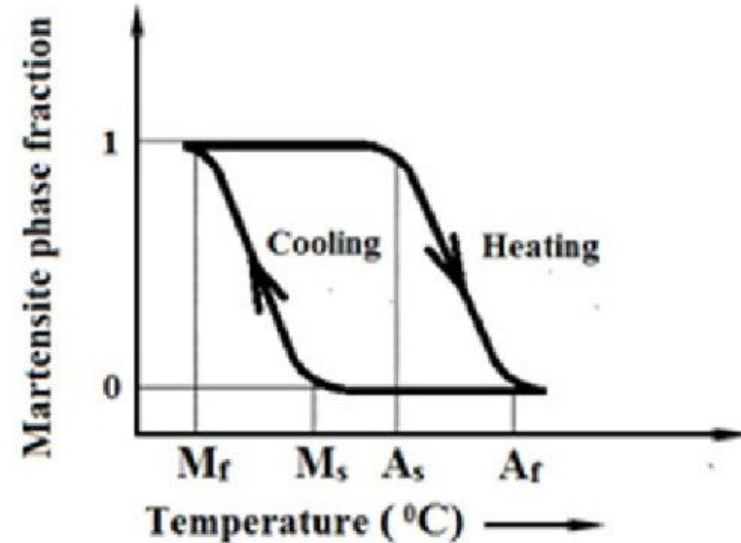
- Prolonged Intracranial Micro-Hemorrhaging causes brain necrosis
- 795,000 strokes per year in US alone
- Minimally Invasive Surgery, Computational Robotics Developing



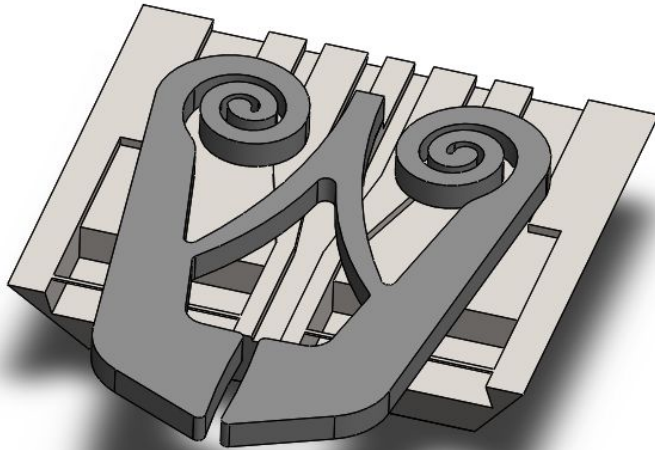
Solution Analysis

Operating Process:

- Fluid sensor detects precise geometry of blood hemorrhage
- Surgical Harness carries information to Processor, Triggers electrical power to Gripper
- Current flows through actuators > resistive heating > Crystallographic Phase Transition
- Gripper Closes to stitch up the end of the vessel
- Device snaps off at base to disconnect harness/surgical wire



Design & Fabrication



Flow Sensor & Nitinol Microgripper

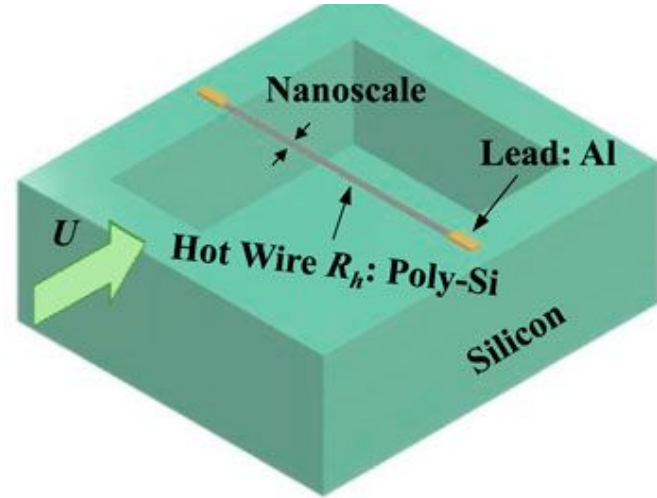
Fabrication Process: CMOS-MEMS

CMOS-MEMS:

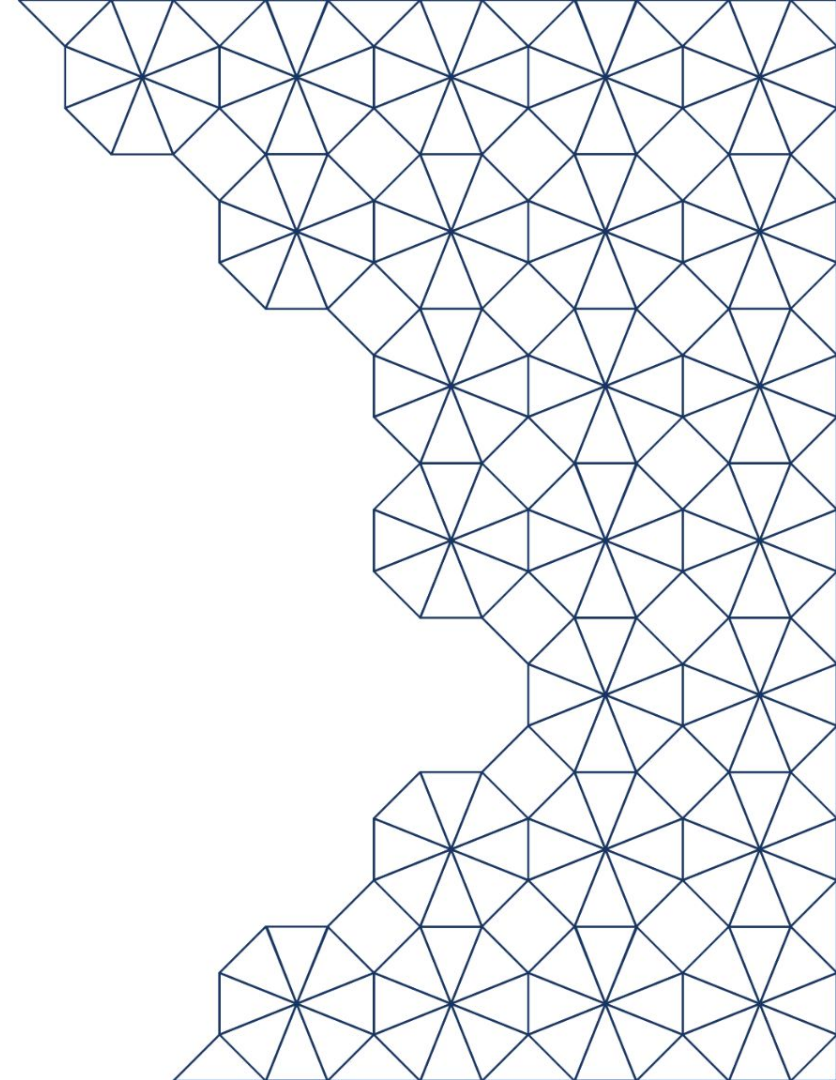
- 3 Process - Pre, Intra, Post-CMOS
- Miniaturization and Performance Improvement of structures
- Cost-Effective
 - Sensor and Circuit at same time
- Multiple steps for polysilicon and metal deposition

Post CMOS:

- Nitinol Sputter Deposition
 - Creates the Microgripper
 - Connects it to the surgical harness



Fluid Sensor: Hot Wire Anemometer



Hot-Wire Flow Sensor Functionality

How Does the Hot-Wire Sensor Work?

The cooling effect generated by forced convection are used to detect fluid flow

Polysilicon Wire:

- Thermal Coefficient of resistance is high = higher sensitivity
- Higher melting point >800 C
 - Useful when working with deposition of metals with higher melting points

Surgical Harness:

- Connects wheatstone bridge circuit to the nitinol gripper
- Current sent back will trigger current to be sent to the Nitinol gripper

Flow passes over the polysilicon wire



Speed of the flow the wire's temperature changes



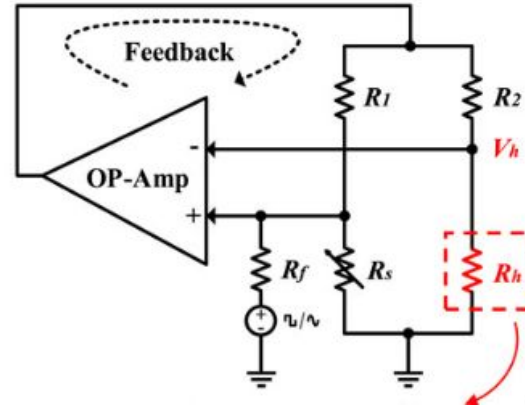
Resistivity of the wire changes



Signal sent back to the surgical harness

CT Wheatstone Bridge Circuit

- Fluid flow rate increases over the microheater, the resistance of the hot wire (R_h) decreases due to the cooling effect.
- Changes the voltage difference on input/output ends
- More voltage needs to be fed into the wheatstone bridge, increasing the heating power of the resistor and rebalancing it
- We monitor the power consumption needed to maintain a constant temperature on the hotwire
- Control Temperature (CT):
 - significantly reduce the response time of the flow sensor



- Electrical Configuration:
 - Negative feedback circuit comprising a Wheatstone bridge and an operational amplifier.
- Components in the CT Mode Configuration:
 - The hot wire (R_h), serves as a heater and a sensor, is placed in a quarter bridge. Off-MEMS resistors (R_1 , R_2 , and R_s)

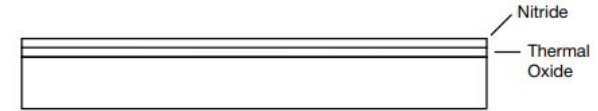
Hot-Wire Flow Sensor Fabrication

Pre-CMOS:

Assumption: Rest of Hot-Wire circuit on surgical harness or created separately in the CMOS process. Focusing only on the creation of the MEMS structure using inspiration from CMOS process by GlobalFoundries and MUMPS design specifications

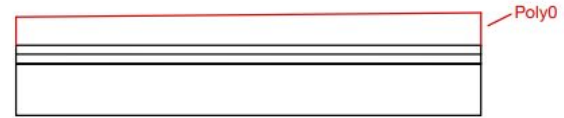
Step 1: .25 um deposition of thermal Oxide on top of Si

- a. Etch stop for DRIE release etch later, prevent undercutting



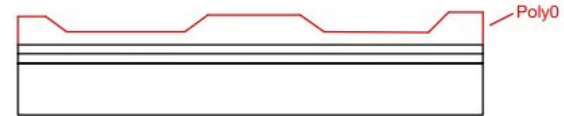
Step 2: .25 um Deposit low stress LPCVD nitride on top of the Oxide

- b. Excellent for the high temp electrical passivation and liquid applications



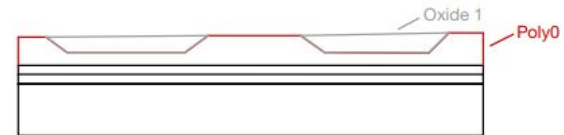
Step 3: 2 um PolySilicon deposition

- c. **Anisotropic** Etching of Poly to get trapezoidal shape
- d. Dry etching is fine no need for poly - make it square



Step 4: .75 um Oxide deposition

- e. Sacrificial layer removed later in HF solution



Hot-Wire Flow Sensor Fabrication

Step 5: .76 um Thin film polysilicon deposition using LPCVD

e. Used as the wire

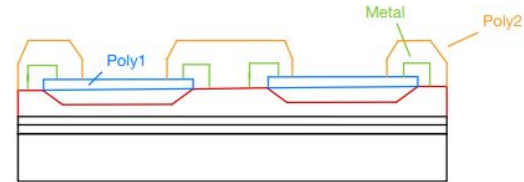
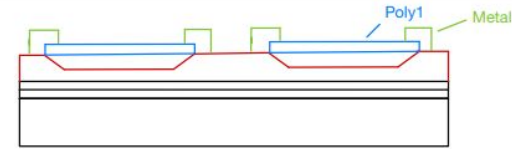
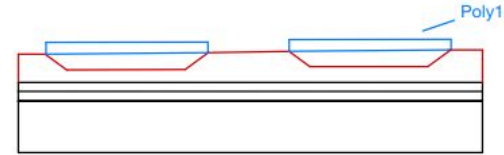
Step 6 : .5 um Metal Layer deposited (Aluminum)

f. Tab the wire, connect it to the rest of circuit

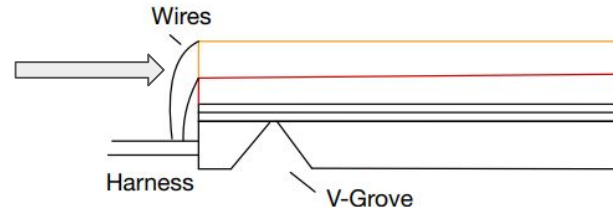
Step 7: 1.5 um Polysilicon Deposition

g. Supports for Nitinol Microgripper

Step 8: Deep Reactive Ion Etching (DRIE) from bottom creating V-Groove up to thermal oxide boundary layer



FIX - Showcase the poly not going over wire

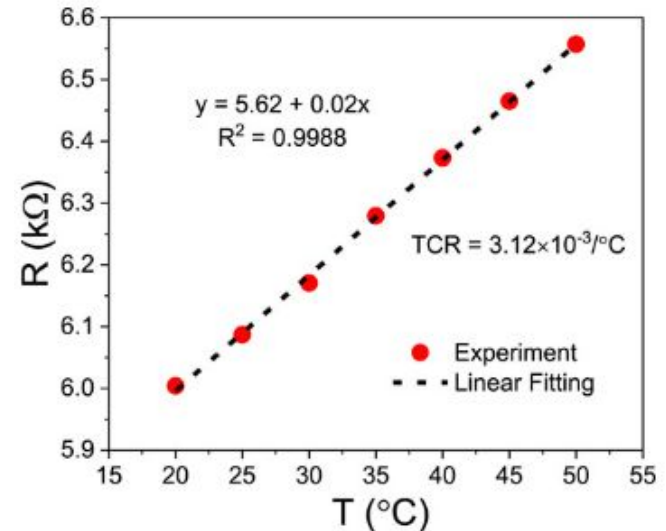
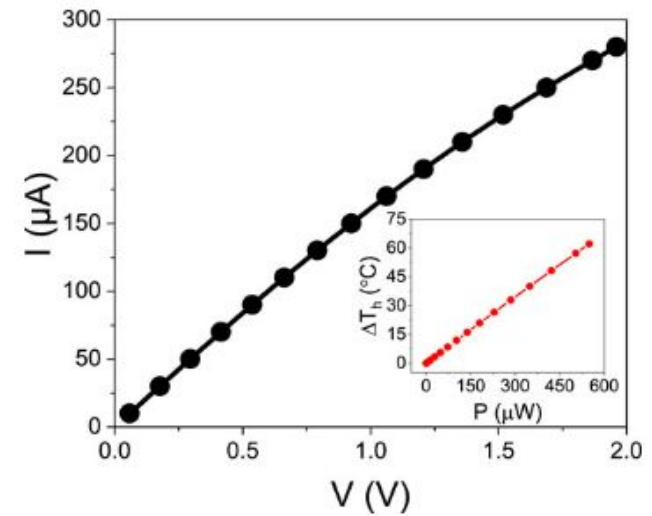


Hot-Wire Joule Heating - Resistivity Feedback Analysis

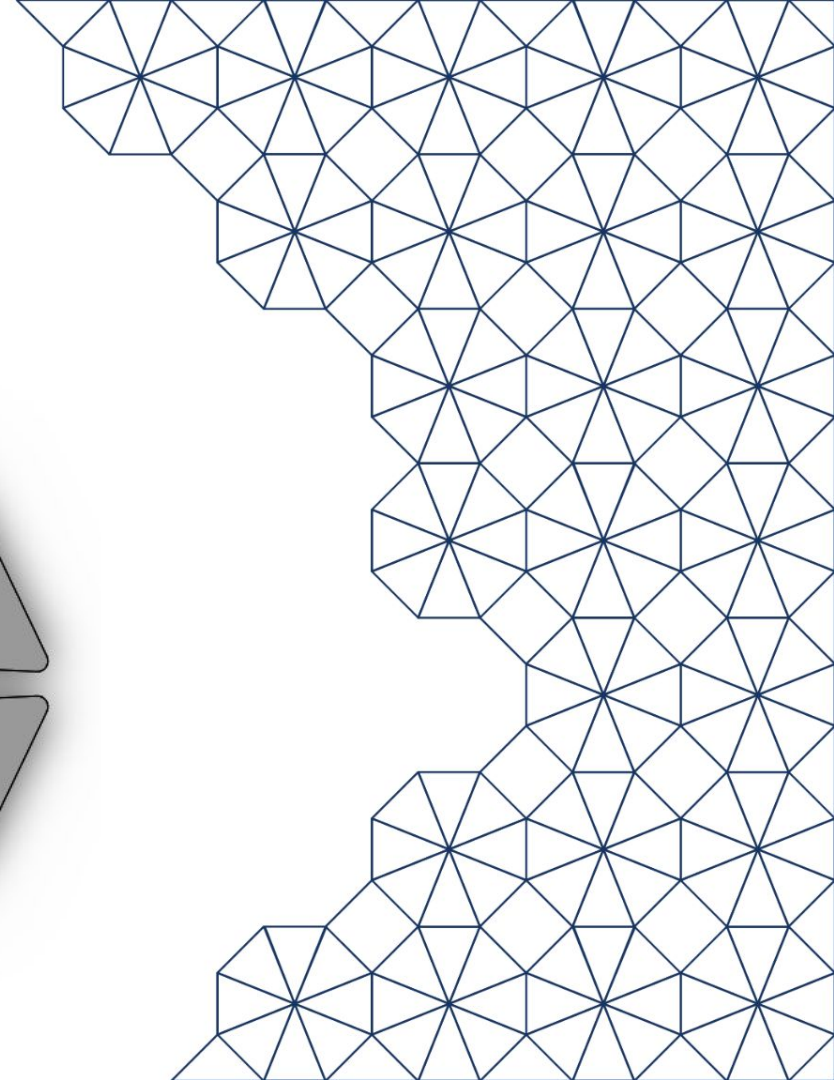
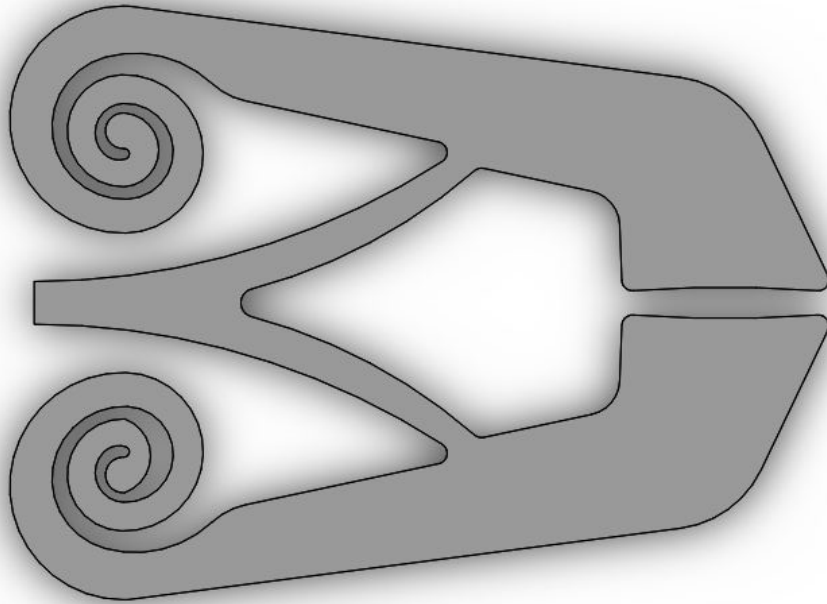
- Power Exchange between Joule Heating and Wire in Crossflow
- Model: Stable Finite Difference Analysis - @0.8V, 0.75m/s ~85C

$$\overline{\text{Nu}}_D = 0.3 + \frac{0.62 \text{Re}_D^{1/2} \text{Pr}^{1/3}}{[1 + (0.4/\text{Pr})^{2/3}]^{1/4}} \left[1 + \left(\frac{\text{Re}_D}{282,000} \right)^{5/8} \right]^{4/5}$$

Lienhard (2020)



Nitinol-Actuated Clamp



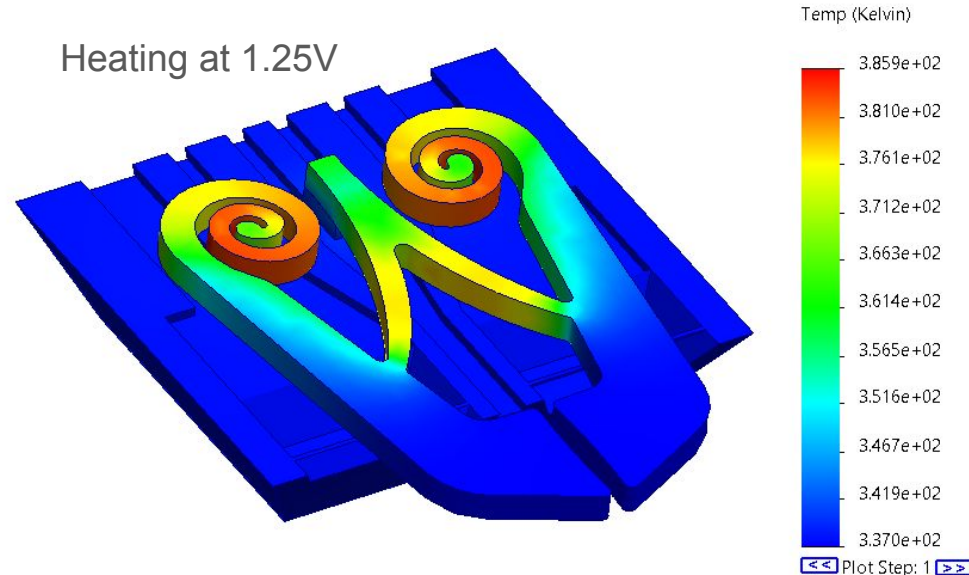
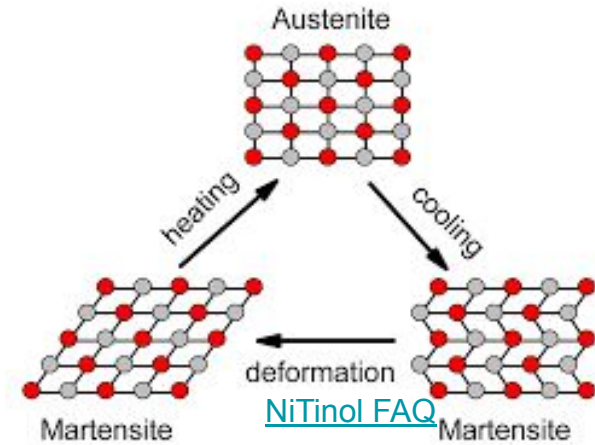
Nitinol Layer Design, Fabrication

Post-CMOS Sputter Deposition (6um) - Alloying control

400C Heat Treatment in Closed Position - Phase Behavior Control

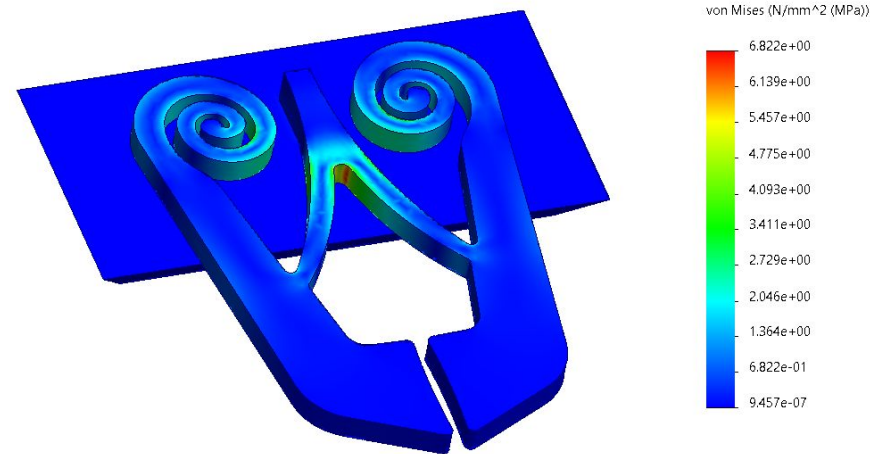
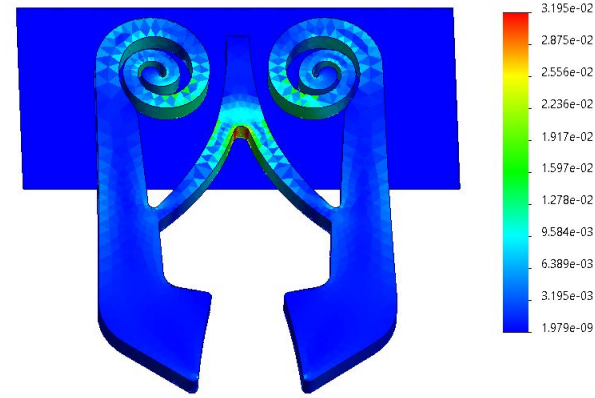
Twinned Martensite Structure on Cooling

Assumption: Flow Sensor signals the harness to send current directly to the Nitinol, resulting in self-heating and closure



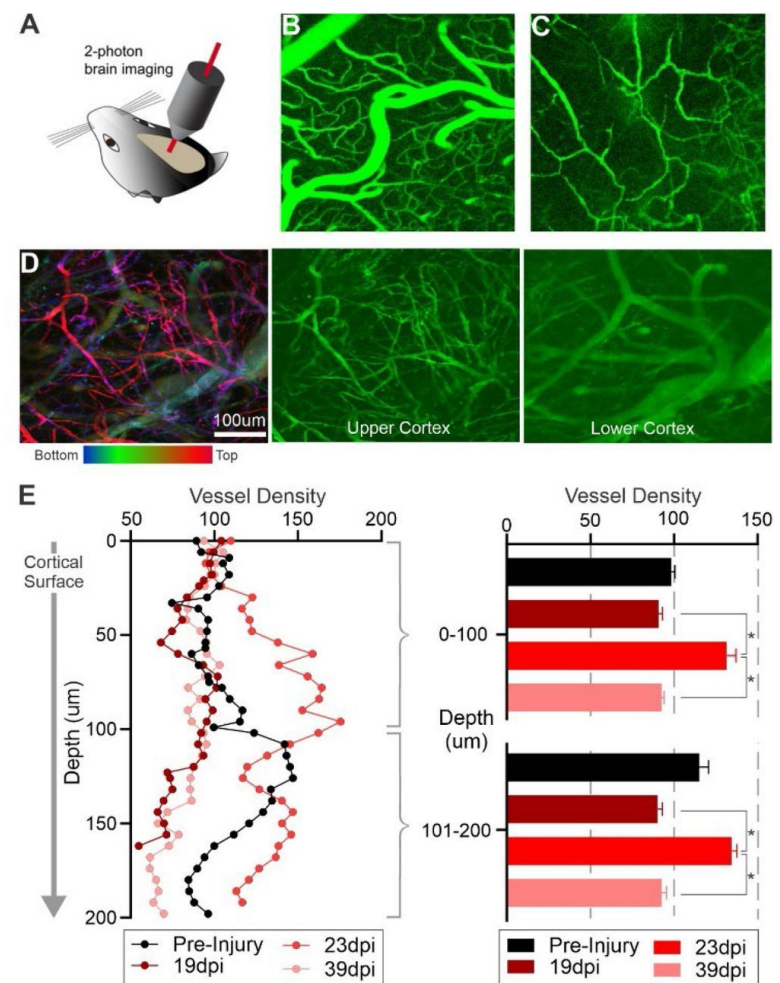
Structural, Operational Analysis

- Martensitic Phase Plastically Deforms below 6% strain
- Easily Withstands Closure Pressures for vessels in the 10-50 μ m range (10-25kPa)



Further Improvements

- Rigorous Vessel / Aneurysm Operational Analysis
- Coupled Joule Heating - Structural Analysis of Microgripper
- Detailed Hotwire FEM for geometric prediction and transient response



Conclusion & Resources

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