Sci One Physics Final Formula Sheet

Unit 1: Modeling and Measuring Movement

Euler's Forward Method

$x(t+\Delta t) = x_0 + v_0 \Delta t$
$v(t+\Delta t) = v_0 + a_0 \Delta t$

Drag (F_D)

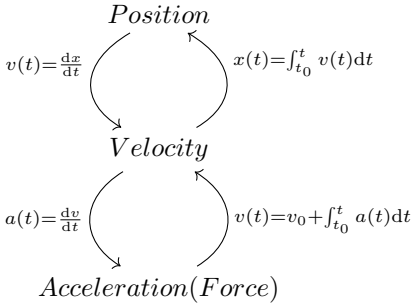
Inertial: $\frac{1}{2} C_D \rho A v^2$ (big and/or fast, $A = \pi a^2$)
Viscous: $-6\pi\eta a v$ (small and/or slow)

Orbits

$r^2 = (x_1 - x_2)^2 + (y_1 - y_2)^2$
$|F| = \frac{G m_1 m_2}{r^2}$
$F_r = -\frac{\mathrm{d}u}{\mathrm{d}r}$, $u(r) = \int \frac{G m_1 m_2}{r^2} = \frac{-G m_1 m_2}{r}$

Unit 2: Dynamics and Conservation Laws

$\vec{F}_{net} = \frac{\mathrm{d}\vec{p}}{\mathrm{d}t}$
$\vec{J} = \int_{t_0}^{t} \vec{F}(t)\,\mathrm{d}t = \vec{F}_{avg}\Delta t$
$F_{spring} = -k\Delta x$, $E_{spring} = \frac{1}{2}kx^2$



Weighted Averages

$\vec{F}_{avg} = \frac{\sum_n F_n(t_n)\delta t}{\Delta t} = \frac{1}{\Delta t}\int F(t)\,\mathrm{d}t$
Above δt is the partial weight, and Δt is the sum of the weights.

Collisions and Orbits

$\vec{F}_{net} = \frac{\mathrm{d}\vec{p}_{sys}}{\mathrm{d}t} = 0 \Longrightarrow \vec{p}(t) = \text{constant}$
$K = \frac{1}{2}mv^2$
$W = F_{\parallel} d$ (this is a "dot product", $A \cdot B = AB\cos\theta$)

Unit 3: Thermodynamics

Quantity	Angular	Linear	Units
Position	θ	x	rad
Speed	ω	v	rad/s
Acceleration	α	a	rad/s^2

Arclength: $S = \theta\vec{r}$
$v_{tangential} = r\vec{\omega}$, $a_{tangential} = r\vec{\alpha}$

Rigid Objects

Conditions: All particles rotate with axis of rotation, and with same $\vec{\omega}$.
$K_{rot} = \sum_n \frac{1}{2} m_n v_n^2 = \frac{1}{2} I\vec{\omega}^2$
$I = \sum_n m_n r_n^2$ for every particle
$I = \square m r^2$ for an object

Unit 4: Rotational Motion

Stuff here!

Unit 5: Special Relativity

Stuff here!