MRI Notes

Momentum Equation: Nonlinear Terms

Verbatim from Jeff Oishi's MRI paper:

$$\frac{D\boldsymbol{u'}}{Dt} + f\hat{\boldsymbol{z}} \times \boldsymbol{u'} + Su'_x\hat{\boldsymbol{y}} + \boldsymbol{\nabla}p' + \nu\boldsymbol{\nabla} \times \boldsymbol{\omega'} = B_0\partial_z\boldsymbol{b'}$$

where f is the corriolis parameter, S is the background shearing rate, and $B_0\hat{z}$ is a uniform background magnetic field. This equation is linearized wrt perturbations. Accordingly, the material derivative goes like

$$\frac{D}{Dt} \equiv \partial_t + \boldsymbol{u} \cdot \boldsymbol{\nabla}$$
$$= \partial_t + Sx \partial_y$$

due to the background velocity $\overline{\boldsymbol{u}} = Sx\hat{\boldsymbol{y}}$. In the nonlinear case we have

$$= \partial_t + (Sx\hat{\boldsymbol{y}} + \boldsymbol{u'}) \cdot \boldsymbol{\nabla}$$

From inspection and stuff, the irrotational momentum equation goes like

$$\frac{D\boldsymbol{u}}{Dt} + \boldsymbol{\nabla}p + \boldsymbol{\nu} \times \boldsymbol{\omega} = \boldsymbol{b} \cdot \boldsymbol{\nabla}\boldsymbol{b}$$

Next we generalize $\mathbf{u} = \mathbf{u'} + Sx\hat{\mathbf{u}}$ and $\mathbf{b} = \mathbf{b'} + B_0\hat{\mathbf{z}}$, giving

$$\partial_t u' + u' \cdot \nabla u' + Sx \partial_y u' + Su'_x \hat{y} + \nabla p + \nu \nabla \times \omega = B_0 \partial_z b' + b' \cdot \nabla b'$$

where the material derivative $\frac{Du}{Dt}$ consists of the underlined terms. Note this definition differs from that of the associated script

Induction Equation: Nonlinear Terms

The MHD induction equation (as given by Fluid Mechanics of Planets and Stars, 2019) is given by

$$\partial_t \boldsymbol{b} = \underline{\boldsymbol{\nabla} \times (\boldsymbol{u} \times \boldsymbol{b})} + \eta \nabla^2 \boldsymbol{b}.$$

We expand the underlined term using the following identity

$$\mathbf{\nabla} \times (\mathbf{u} \times \mathbf{b}) = \mathbf{u} \mathbf{\nabla} \cdot \mathbf{b} - \mathbf{b} \mathbf{\nabla} \cdot \mathbf{u} + \mathbf{b} \cdot \mathbf{\nabla} \mathbf{u} - \mathbf{u} \cdot \mathbf{\nabla} \mathbf{b}$$

where the first two terms on the RHS vanish due to incompressibility and the abscence of magnetic monopoles. Therefore

$$\partial_t \boldsymbol{b} + \boldsymbol{u} \cdot \nabla \boldsymbol{b} = \boldsymbol{b} \cdot \nabla \boldsymbol{u} + \eta \nabla^2 \boldsymbol{b}.$$

Substituting the decompositions for \boldsymbol{u} and \boldsymbol{b} as above yields

$$\partial_t (B_0 \hat{\boldsymbol{z}} + \boldsymbol{b'}) + (Sx\hat{\boldsymbol{y}} + \boldsymbol{u'}) \cdot \nabla (B_0 \hat{\boldsymbol{z}} + \boldsymbol{b'}) = (B_0 \hat{\boldsymbol{z}} + \boldsymbol{b'}) \cdot \nabla (Sx\hat{\boldsymbol{y}} + \boldsymbol{u'}) + \eta \nabla^2 (B_0 \hat{\boldsymbol{z}} + \boldsymbol{b'})$$
$$\partial_t \boldsymbol{b'} + (Sx\hat{\boldsymbol{y}} + \boldsymbol{u'}) \cdot \nabla \boldsymbol{b'} = (B_0 \hat{\boldsymbol{z}} + \boldsymbol{b'}) \cdot \nabla (Sx\hat{\boldsymbol{y}} + \boldsymbol{u'}) + \eta \nabla^2 \boldsymbol{b'}$$

dropping the 's and taking the x, y, and z components of the above yields

$$\partial_t b_x + Sx \partial_y b_x + \boldsymbol{u} \cdot \boldsymbol{\nabla} b_x = B_0 \partial_z u_x + \boldsymbol{b} \cdot \boldsymbol{\nabla} u_x + \eta \nabla^2 b_x$$

$$\partial_t b_y + Sx \partial_y b_y + \boldsymbol{u} \cdot \boldsymbol{\nabla} b_y = B_0 \partial_z u_y + \boldsymbol{b} \cdot \boldsymbol{\nabla} u_y + Sb_x + \eta \nabla^2 b_y$$

$$\partial_t b_z + Sx \partial_y b_z + \boldsymbol{u} \cdot \boldsymbol{\nabla} b_z = B_0 \partial_z u_z + \boldsymbol{b} \cdot \boldsymbol{\nabla} u_z + \eta \nabla^2 b_z$$

Note that the nonlinear operator on the LHS is identical for each scalar equation. Accordingly, we redefine D_t to be this operator, i.e.

$$D_t A \equiv \partial_t A + Sx \partial_u A + \boldsymbol{u} \cdot \boldsymbol{\nabla} A$$

NOTE: the material derivative substitution implemented in Dedalus excludes the nonlinear term.

We continue by taking ∂_z of the b_y equation

$$\partial_z D_t b_y = \partial_z \Big[\partial_t b_y + Sx \partial_y b_y + \boldsymbol{u} \cdot \boldsymbol{\nabla} b_y \Big] = \partial_z B_0 \partial_z u_y + \partial_z [\boldsymbol{b} \cdot \boldsymbol{\nabla} u_y] + S \partial_z b_x + \eta \nabla^2 \partial_z b_y$$
$$D_t \partial_z b_y + \partial_z \boldsymbol{u} \cdot \boldsymbol{\nabla} b_y = B_0 \partial_z^2 u_y + \partial_z \boldsymbol{b} \cdot \boldsymbol{\nabla} u_y + \boldsymbol{b} \cdot \boldsymbol{\nabla} \partial_z u_y + S \partial_z b_x + \eta \nabla^2 \partial_z b_y$$

and the ∂_y of the b_z equation

$$\partial_y D_t b_z = \partial_y \Big[\partial_t b_z + Sx \partial_y b_z + \boldsymbol{u} \cdot \boldsymbol{\nabla} b_z \Big] = B_0 \partial_z \partial_y u_z + \partial_y [\boldsymbol{b} \cdot \boldsymbol{\nabla} u_z] + \eta \nabla^2 \partial_y b_z$$
$$D_t \partial_y b_z + \partial_y \boldsymbol{u} \cdot \boldsymbol{\nabla} b_z = B_0 \partial_z \partial_y u_z + \partial_y \boldsymbol{b} \cdot \boldsymbol{\nabla} u_z + \boldsymbol{b} \cdot \boldsymbol{\nabla} \partial_y u_z + \eta \nabla^2 \partial_y b_z$$

Recall that the current density is given by

Therefore

$$D_t j_x + \partial_y \boldsymbol{u} \cdot \boldsymbol{\nabla} b_z - \partial_z \boldsymbol{u} \cdot \boldsymbol{\nabla} b_y = B_0 \partial_z \omega_x + \boldsymbol{b} \cdot \boldsymbol{\nabla} \omega_x - S \partial_z b_x + \eta \nabla^2 j_x + \partial_y \boldsymbol{b} \cdot \boldsymbol{\nabla} u_z - \partial_z \boldsymbol{b} \cdot \boldsymbol{\nabla} u_y$$

Expanding the material derivative and grouping linear terms on the LHS gives

$$\partial_t j_x + Sx \partial_y j_x - B_0 \partial_z \omega_x + S \partial_z b_x - \eta \nabla^2 j_x = \boldsymbol{b} \cdot \boldsymbol{\nabla} \omega_x - \boldsymbol{u} \cdot \boldsymbol{\nabla} j_x$$

$$+ \partial_y \boldsymbol{b} \cdot \boldsymbol{\nabla} u_z - \partial_z \boldsymbol{b} \cdot \boldsymbol{\nabla} u_y$$

$$- \partial_y \boldsymbol{u} \cdot \boldsymbol{\nabla} b_z + \partial_z \boldsymbol{u} \cdot \boldsymbol{\nabla} b_y$$

Let's check that. Using the following identity

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Taking the x-component gives

$$\begin{split} \hat{\boldsymbol{x}} \cdot \boldsymbol{\nabla} \times \boldsymbol{\nabla} \times (\boldsymbol{u} \times \boldsymbol{b}) &= \partial_y (\boldsymbol{b} \cdot \boldsymbol{\nabla} u_z - \boldsymbol{u} \cdot \boldsymbol{\nabla} b_z) - \partial_z (\boldsymbol{b} \cdot \boldsymbol{\nabla} u_y - \boldsymbol{u} \cdot \boldsymbol{\nabla} b_y) \\ &= \partial_y \boldsymbol{b} \cdot \boldsymbol{\nabla} u_z + \boldsymbol{b} \cdot \boldsymbol{\nabla} \partial_y u_z - \partial_y \boldsymbol{u} \cdot \boldsymbol{\nabla} b_z - \boldsymbol{u} \cdot \boldsymbol{\nabla} \partial_y b_z \\ &- \partial_z \boldsymbol{b} \cdot \boldsymbol{\nabla} u_y - \boldsymbol{b} \cdot \boldsymbol{\nabla} \partial_z u_y + \partial_z \boldsymbol{u} \cdot \boldsymbol{\nabla} b_y + \boldsymbol{u} \cdot \boldsymbol{\nabla} \partial_z b_y \\ &= \boldsymbol{b} \cdot \boldsymbol{\nabla} \omega_x - \boldsymbol{u} \cdot \boldsymbol{\nabla} j_x \\ &+ \partial_y \boldsymbol{b} \cdot \boldsymbol{\nabla} u_z - \partial_z \boldsymbol{b} \cdot \boldsymbol{\nabla} u_y + \partial_z \boldsymbol{u} \cdot \boldsymbol{\nabla} b_y - \partial_y \boldsymbol{u} \cdot \boldsymbol{\nabla} b_z \end{split}$$

Letting $B_0 = S = 0$, the expanded current-density equation is given by

$$\begin{aligned} \partial_t j_x &= \eta \nabla^2 j_x \\ &+ \boldsymbol{b} \cdot \boldsymbol{\nabla} \omega_x - \boldsymbol{u} \cdot \boldsymbol{\nabla} j_x \\ &+ \partial_y \boldsymbol{b} \cdot \boldsymbol{\nabla} u_z - \partial_z \boldsymbol{b} \cdot \boldsymbol{\nabla} u_y + \partial_z \boldsymbol{u} \cdot \boldsymbol{\nabla} b_y - \partial_y \boldsymbol{u} \cdot \boldsymbol{\nabla} b_z \\ &= \eta \nabla^2 j_x + \hat{\boldsymbol{x}} \cdot \boldsymbol{\nabla} \times \boldsymbol{\nabla} \times (\boldsymbol{u} \times \boldsymbol{b}). \end{aligned}$$

by symmetry we have

$$\partial_t \mathbf{j} = \eta \nabla^2 \mathbf{j} + \nabla \times \nabla \times (\mathbf{u} \times \mathbf{b})$$

We can "uncurl" this equation, and if we assume the unknown scalar potential-gradient term $\nabla \phi = \mathbf{0}$, we have

$$\partial_t \boldsymbol{b} = \boldsymbol{\nabla} \times (\boldsymbol{u} \times \boldsymbol{b}) + \eta \boldsymbol{\nabla}^2 \boldsymbol{b}$$

which is the usual form of the induction equation