LIAM BOWERS

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Python

- C/C++
- JavaScript
- Test-driven Development

- Computer Vision
- Sensor Fusion
- Localization
- Tensorflow/Keras

EDUCATION

Georgia Institute of Technology

Aug 2015 - Dec 2018

• Master of Science in Computer Science: Computational Perception & Robotics

Udacity

Feb 2017 - Dec 2017

• Self-Driving Car Engineer Nanodegree

EXPERIENCE

Senior Software Engineer: Lifion by ADP

Mar 2016 - Present

- Delivering the runtime of a metadata-driven platform for application development across web and mobile, using Node.js, React Native, Redux, Jest
- Helping foster a culture of rigorous testing and code review, improving code quality and productivity across the teams to which I contribute

Senior Software Engineer: Insight Catastrophe Group

Feb 2014 - Mar 2016

- Built modular, full-stack applications in Backbone, React, and Node.js to manage the underwriting and servicing of insurance policies and quotes
- Enabled product team to rapidly create their own policy and underwriting products by creating automated build tooling

Web Developer: Artspace Marketplace

Jan 2013 - Feb 2014

- Improved site reliability by implementing graceful degradation strategies for legacy browsers
- Reduced page load time by 80% and improved site performance across the stack by redesigning static asset build and deployment pipeline

Web Developer: SeatGeek

Sep 2010 - Dec 2012

- Streamlined the production and deployment of 100s of seating charts for sports and concerts
- Built interactive seating charts, events calendar, ad platform and more using Symfony on the server and Backbone.js on the client

RECENT PROJECTS

Road Classifier (Semantic Segmentation) - github.com/liamondrop/semantic-segmentation

Dec 2017

• Classifying the road in a series of images with a Fully Convolutional Network

Path Planner - github.com/liamondrop/path-planning

Nov 2017

• Safely navigate a vehicle around a virtual highway filled with traffic

Model Predictive Controller - github.com/liamondrop/model-predictive-control

Sep 2017

• Enables a vehicle to safely follow a pre-determined path at high speed