

①a Let $y_t' = y_t \wedge y_{t-1} = y_t, y_{t-1}$

$$\begin{aligned} \text{Then, } & \Pr(y_t' | y_{t-1}') \\ &= \Pr(y_t' = (a, b) | y_{t-1}' = (c, d)) \\ &= \Pr(y_t = a, y_{t-1} = b | y_{t-1} = c, y_{t-2} = d) \\ &= \begin{cases} 0 & b \neq c \\ P(y_t = a | y_{t-1} = c, y_{t-2} = d) = P(y_t | y_{t-1}, y_{t-2}) & b = c \end{cases} \end{aligned}$$

$$\begin{aligned} & \Pr(x_t | y_t') \\ &= \Pr(x_t = a | y_t' = (b, c)) \\ &= \Pr(x_t = a | y_t = b, y_{t-1} = c) \\ &= \Pr(x_t = a | y_t = b) \quad (x_t \text{ only depends on } y_t) \\ &= \Pr(x_t | y_t) \end{aligned}$$

\Rightarrow We have a HMM parameterized by $\Pr(y_t' | y_{t-1}') + \Pr(x_t | y_t')$.

b Yes, because the reparameterized system has a non-zero parameter only for each non-zero parameter in the initial system.

More Concretely, if there are N distinct output classes,

System	$\Pr(y_t y_{t-1}, y_{t-2}) \Pr(x_t y_t)$	$\Pr(y_t' y_{t-1}') \Pr(x_t y_t')$
Initial State	$N^2 - 1$ $(\Pr(y_0, y_1))$	$N^2 - 1$ $(\Pr(y_1') = \Pr(y_0, y_1))$
Transition	$N^2(N-1)$ $(\Pr(y_t y_{t-1}, y_{t-2}))$	$N^2(N-1)$ $(\text{Only non-zero parameters are } \Pr(y_t y_{t-1}, y_{t-2})).$
Emission	$2N$ $(\Pr(x_t y_t) \leftarrow 2 \text{ Gaussian Parameters})$	$2N$ $(\Pr(x_t y_t') = \Pr(x_t y_t))$

\Rightarrow Both systems have $(N^2 - 1) + N^2(N - 1) + 2N = N^3 + 2N - 1$ parameters.
 \Rightarrow No increase in parameters. Hilary

$$\textcircled{2} \Pr(x_1 \dots x_T) = \sum_{y_1, \dots, y_T} \Pr(x_1 \dots x_T | y_1 \dots y_T) \Pr(y_1 \dots y_T)$$

$$= \sum_{y_1, \dots, y_T} \left[\prod_{i=1}^T \Pr(x_i | y_i) \Pr(y_1) \prod_{i=2}^T \Pr(y_i | y_{i-1}) \right]$$

* For 2 classes C_1, C_2 , and two outputs V_1, V_2
~~# C_1 start~~
~~# C_i~~
~~# (C_i, C_j)~~
~~# (V_i, V_j)~~

$$= \sum_{y_1, \dots, y_T} \left[\frac{(\pi_{C_1})^{\#C_1 \text{ start}} (1 - \pi_{C_1})^{\#C_2 \text{ start}} (\theta_{C_1, C_1})^{\#(C_1, C_1)} (1 - \theta_{C_1, C_1})^{\#(C_2, C_1)}}{(\theta_{C_1, C_2})^{\#(C_1, C_2)} (1 - \theta_{C_1, C_2})^{\#(C_2, C_2)}} \right]$$

$$= \sum_{y_1, \dots, y_T} \left[\prod_{i=1}^T \phi_{x_i | y_i} \prod_{i=2}^T \theta_{y_i | y_{i-1}} \pi_{y_1} \right]$$

$$\Rightarrow \pi^*, \theta^*, \phi^* = \underset{\pi, \theta, \phi}{\operatorname{argmax}} \sum_{y_1, \dots, y_T} \left[\pi_{y_1} \prod_{i=1}^T \phi_{x_i | y_i} \prod_{i=2}^T \theta_{y_i | y_{i-1}} \right]$$

$$= \underset{\pi, \theta, \phi}{\operatorname{argmax}} \sum_{y_1=C_1}^{C_N} \sum_{y_2=C_1}^{C_N} \dots \sum_{y_T=C_1}^{C_N} \left[\pi_{y_1} \prod_{i=1}^T \phi_{x_i | y_i} \prod_{i=2}^T \theta_{y_i | y_{i-1}} \right]$$

↓ If $\{C_1, \dots, C_N\}$ are the classes.