§1.4 克莱姆法则

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$$\begin{cases} a_{11}x_1 + a_{12}x_2 = b_1 \\ a_{21}x_2 + a_{22}y_2 = b_2 \end{cases}$$



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的解是

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注

•
$$D = \begin{vmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{vmatrix}$$
 称为系数行列式

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• D_i : 将 D 的第 i 列换成常数项 $\begin{pmatrix} b_1 \\ b_2 \end{pmatrix}$



三元线性方程组
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$$x_{3} = \frac{A_{11} + A_{12} + A_{13} + A$$



对n元线性 $\begin{cases} a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n = b_1 \\ a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n = b_2 \\ \vdots \\ a_{n1}x_1 + a_{n2}x_2 + \cdots + a_{nn}x_n = b_n \end{cases}$

$$D = \begin{vmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{vmatrix}$$

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$$\begin{vmatrix} a_{11} & \cdots & a_{1j-1} & a_{1,j} & a_{1j+1} & \cdots & a_{1n} \\ a_{21} & \cdots & a_{2j-1} & a_{2,j} & a_{2j+1} & \cdots & a_{2n} \\ \vdots & & \vdots & & \vdots & & \vdots \\ a_{n1} & \cdots & a_{nj-1} & a_{n,j} & a_{nj+1} & \cdots & a_{nn} \end{vmatrix}$$

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定理(克莱姆法则) 线性方程组

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当系数行列式 $D \neq 0$ 时,方程具有唯一解:



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注 两个前提: (1) 未知元个数 = 方程个数; (2) 系数行列式 $D \neq 0$



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注 两个前提: (1) 未知元个数 = 方程个数; (2) 系数行列式 $D \neq 0$

(3) 若 D=0,则方程有无穷多解或无解(以后详说)





$$\bullet \begin{cases} x+y=1 \\ x+y=0 \end{cases}, D=\begin{vmatrix} 1 & 1 \\ 1 & 1 \end{vmatrix}=0$$



•
$$\begin{cases} x+y=1 \\ x+y=1 \end{cases}, D = \begin{vmatrix} 1 & 1 \\ 1 & 1 \end{vmatrix} = 0, 实质上只有一条方程 x+y=1,$$
 显然有无穷多解。

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•
$$\begin{cases} x+y=1\\ x+y=0 \end{cases}$$
 , $D=\begin{vmatrix} 1 & 1\\ 1 & 1 \end{vmatrix}=0$, 方程组包含矛盾方程,显然无解。



例 解线性方程组

$$\begin{cases} 2x_1 + x_2 - x_3 = 1\\ 3x_1 - x_2 - x_3 = -2\\ -x_1 + 2x_2 + x_3 = 6 \end{cases}$$

练习 解线性方程组

$$\begin{cases} x_1 + x_2 = 90 \\ x_2 + x_3 = 86 \\ x_1 + x_3 = 80 \end{cases}$$

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提示
$$D = -5$$
, $D_1 = -5$, $D_2 = -10$, $D_3 = -15$

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$$D = -5$$
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$$\begin{cases} x_1 + x_2 = 90 \\ x_2 + x_3 = 86 \\ x_1 + x_3 = 80 \end{cases}$$

提示 D = 2, $D_1 = 84$, $D_2 = 96$, $D_3 = 76$



齐次线性方程组

定理 齐次线性方程组

$$\begin{cases} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = 0 \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = 0 \\ \vdots \\ a_{n1}x_1 + a_{n2}x_2 + \dots + a_{nn}x_n = 0 \end{cases}$$

当系数行列式 $D \neq 0$ 时,仅有零解($x_1 = x_2 = \cdots = x_n = 0$)

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 当系数行列式 $D \neq 0$ 时,仅有零解($x_1 = x_2 = \cdots = x_n = 0$)证明 $x_1 = x_2 = \cdots = x_n = 0$ 显然是方程组的解

齐次线性方程组

定理 齐次线性方程组

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$$\vdots$$

$$a_{n1}x_1 + a_{n2}x_2 + \cdots + a_{nn}x_n = 0$$
当系数行列式 $D \neq 0$ 时,仅有零解($x_1 = x_2 = \cdots = x_n = 0$)
证明 $x_1 = x_2 = \cdots = x_n = 0$ 显然是方程组的解

另一方面,因为
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,所以方程组有唯一解(克莱姆法则)



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另一方面,因为 $D \neq 0$,所以方程组有唯一解(克莱姆法则)

所以方程组除 $x_1 = x_2 = \cdots = x_n = 0$ 外,没有其他解



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 时,仅有零解($x_1 = x_2 = \cdots = x_n = 0$)

证明
$$x_1 = x_2 = \cdots = x_n = 0$$
 显然是方程组的解

另一方面,因为 $D \neq 0$,所以方程组有唯一解(克莱姆法则)

所以方程组除 $x_1 = x_2 = \cdots = x_n = 0$ 外,没有其他解

注

其实是充分必要条件:仅有零解的充分必要条件是 D ≠ 0

齐次线性方程组

定理 齐次线性方程组

$$\begin{cases} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = 0 \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = 0 \\ \vdots \\ a_{n1}x_1 + a_{n2}x_2 + \dots + a_{nn}x_n = 0 \end{cases}$$

当系数行列式
$$D \neq 0$$
 时,仅有零解($x_1 = x_2 = \cdots = x_n = 0$)

证明
$$X_1 = X_2 = \cdots = X_n = 0$$
 显然是方程组的解

另一方面,因为 $D \neq 0$,所以方程组有唯一解(克莱姆法则)

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其实是充分必要条件: 仅有零解的充分必要条件是 D ≠ 0





例 齐次方程组
$$\begin{cases} x_1 - 2x_2 = 0 \\ 2x_1 - 4x_2 = 0 \end{cases}$$
 的系数矩阵 $D = \begin{vmatrix} 1 & -2 \\ 2 & -4 \end{vmatrix}$



例 齐次方程组
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例 判断线性方程组
$$\begin{cases} 2x_1 + 3x_2 + 4x_3 + 5x_4 = 0 \\ 3x_1 + 4x_2 + 5x_3 + 5x_4 = 0 \\ 4x_1 + 5x_2 + 6x_3 + 6x_4 = 0 \\ 5x_1 + 6x_2 + 8x_3 + 9x_4 = 0 \end{cases}$$

是否只有零解



§1.4 克莱姆法则

2 3 4 5 3 4 5 5 4 5 6 6 5 6 8 9

 $\begin{vmatrix} 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 5 \\ 4 & 5 & 6 & 6 \\ 5 & 6 & 8 & 9 \end{vmatrix} \xrightarrow{r_4 - r_3}$

2	3	4	5					
3	4	5	5	r_4-r_3	İ			
4	5	6	6					
5	6	8	9	r_4-r_3	1	1	2	3

2	3	4	5		2	3	4	5
3	4	5	5	r_4-r_3	3	4	5	5
4	5	6	6		4	5	6	6
5	6	8	9	<u>r₄-r₃</u>	1	1	2	3

2	3	4	5		2	3	4	5	
3	4	5	5	r_4-r_3	3	4	5	5	r_3-r_2
4	5	6	6		4	5	6	6	
5	6	8	9		1	1	2	3	<u>r₃-r₂</u>

$\begin{vmatrix} 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 5 \\ 4 & 5 & 6 & 6 \\ 5 & 6 & 8 & 9 \end{vmatrix} \xrightarrow{\underline{r_4 - r_3}} \begin{vmatrix} 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 5 \\ 4 & 5 & 6 & 6 \\ 1 & 1 & 2 & 3 \end{vmatrix} \xrightarrow{\underline{r_3 - r_2}} \begin{vmatrix} 1 & 1 & 1 & 1 \end{vmatrix}$	2	3 4	4 5	5	<u>r_4-r_3</u>	2	3 4	4 5	5	<u>r_3-r_2</u>	1	1	1	1	
	5	6	8	9		1	1	2	3		1	1	1	1	



2	3	4	5		2	3	4	5	ļ	2	3	4	5
3	4	5	5	r_4-r_3	3	4	5	5	r_3-r_2	3	4	5	5
4	5	6	6		4	5	6	6		1	1	1	1
5	6	8	9		1	1	2	3	<u>r₃-r₂</u>	1	1	2	3



2	3	4	5		2	3	4	5		2	3	4	5
3	4	5	5	<u>r₄-r₃</u>	3	4	5	5	r_3-r_2	3	4	5	5
4	5	6	6		4	5	6	6		1	1	1	1
5	6	8	9		1	1	2	3		1	1	2	3

 r_2-r_1



$$\begin{vmatrix} 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 5 \\ 4 & 5 & 6 & 6 \\ 5 & 6 & 8 & 9 \end{vmatrix} \xrightarrow{\underline{r_4 - r_3}} \begin{vmatrix} 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 5 \\ 4 & 5 & 6 & 6 \\ 1 & 1 & 2 & 3 \end{vmatrix} \xrightarrow{\underline{r_3 - r_2}} \begin{vmatrix} 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 5 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 2 & 3 \end{vmatrix}$$

$$\frac{r_2-r_1}{} \begin{vmatrix} 1 & 1 & 1 & 0 \end{vmatrix}$$

$$\begin{vmatrix} 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 5 \\ 4 & 5 & 6 & 6 \\ 5 & 6 & 8 & 9 \end{vmatrix} \xrightarrow{\underline{r_4 - r_3}} \begin{vmatrix} 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 5 \\ 4 & 5 & 6 & 6 \\ 1 & 1 & 2 & 3 \end{vmatrix} \xrightarrow{\underline{r_3 - r_2}} \begin{vmatrix} 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 5 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 2 & 3 \end{vmatrix}$$

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$$\begin{vmatrix} 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 5 \\ 4 & 5 & 6 & 6 \\ 5 & 6 & 8 & 9 \end{vmatrix} \xrightarrow{\underline{r_4 - r_3}} \begin{vmatrix} 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 5 \\ 4 & 5 & 6 & 6 \\ 1 & 1 & 2 & 3 \end{vmatrix} \xrightarrow{\underline{r_3 - r_2}} \begin{vmatrix} 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 5 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 2 & 3 \end{vmatrix}$$



$$\begin{vmatrix} 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 5 \\ 4 & 5 & 6 & 6 \\ 5 & 6 & 8 & 9 \end{vmatrix} \xrightarrow{\underline{r_4 - r_3}} \begin{vmatrix} 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 5 \\ 4 & 5 & 6 & 6 \\ 1 & 1 & 2 & 3 \end{vmatrix} \xrightarrow{\underline{r_3 - r_2}} \begin{vmatrix} 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 5 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 2 & 3 \end{vmatrix}$$



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$$r_4 - 2r_2$$



§1.4 克莱姆法则

$$\begin{vmatrix} 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 5 \\ 4 & 5 & 6 & 6 \\ 5 & 6 & 8 & 9 \end{vmatrix} \xrightarrow{\underline{r_4 - r_3}} \begin{vmatrix} 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 5 \\ 4 & 5 & 6 & 6 \\ 1 & 1 & 2 & 3 \end{vmatrix} \xrightarrow{\underline{r_3 - r_2}} \begin{vmatrix} 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 5 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 2 & 3 \end{vmatrix}$$

$$\frac{\underline{r_2 - r_1}}{2} \begin{vmatrix} 2 & 3 & 4 & 5 \\ 1 & 1 & 1 & 0 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 2 & 3 \end{vmatrix} = \frac{\underline{r_1 - 2r_2}}{2} \begin{vmatrix} 0 & 1 & 2 & 5 \\ 1 & 1 & 1 & 0 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 2 & 3 \end{vmatrix} = \frac{\underline{r_3 - r_2}}{2} \begin{vmatrix} 0 & 1 & 2 & 5 \\ 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 1 & 2 & 3 \end{vmatrix}$$

$$\underline{\underline{r_4 - 2r_2}}$$

$$\begin{vmatrix} 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 5 \\ 4 & 5 & 6 & 6 \\ 5 & 6 & 8 & 9 \end{vmatrix} \xrightarrow{\underline{r_4 - r_3}} \begin{vmatrix} 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 5 \\ 4 & 5 & 6 & 6 \\ 1 & 1 & 2 & 3 \end{vmatrix} \xrightarrow{\underline{r_3 - r_2}} \begin{vmatrix} 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 5 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 2 & 3 \end{vmatrix}$$

$$\frac{r_2 - r_1}{ } \begin{vmatrix} 2 & 3 & 4 & 5 \\ 1 & 1 & 1 & 0 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 2 & 3 \end{vmatrix}
\frac{r_1 - 2r_2}{ } \begin{vmatrix} 0 & 1 & 2 & 5 \\ 1 & 1 & 1 & 0 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 2 & 3 \end{vmatrix}
\frac{r_3 - r_2}{ } \begin{vmatrix} 0 & 1 & 2 & 5 \\ 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 1 & 2 & 3 \end{vmatrix}
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§1.4 克莱姆法则

$$\begin{vmatrix} 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 5 \\ 4 & 5 & 6 & 6 \\ 5 & 6 & 8 & 9 \end{vmatrix} \xrightarrow{\underline{r_4 - r_3}} \begin{vmatrix} 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 5 \\ 4 & 5 & 6 & 6 \\ 1 & 1 & 2 & 3 \end{vmatrix} \xrightarrow{\underline{r_3 - r_2}} \begin{vmatrix} 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 5 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 2 & 3 \end{vmatrix}$$

$$\frac{r_2 - r_1}{\begin{vmatrix} 1 & 1 & 1 & 0 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 2 & 3 \end{vmatrix}} = \frac{r_1 - 2r_2}{\begin{vmatrix} 1 & 1 & 1 & 0 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 2 & 3 \end{vmatrix}} = \frac{r_3 - r_2}{\begin{vmatrix} 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 1 & 2 & 3 \end{vmatrix}} = \frac{r_3 - r_2}{\begin{vmatrix} 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 1 & 2 & 3 \end{vmatrix}}$$

$$\frac{r_4 - 2r_2}{\begin{array}{c|cccc} \hline \\ 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 3 \\ \end{array}} = - \begin{vmatrix} 0 & 1 & 2 \\ 1 & 1 & 1 \\ 0 & 0 & 1 \end{vmatrix}$$



$$\begin{vmatrix} 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 5 \\ 4 & 5 & 6 & 6 \\ 5 & 6 & 8 & 9 \end{vmatrix} \xrightarrow{\underline{r_4 - r_3}} \begin{vmatrix} 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 5 \\ 4 & 5 & 6 & 6 \\ 1 & 1 & 2 & 3 \end{vmatrix} \xrightarrow{\underline{r_3 - r_2}} \begin{vmatrix} 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 5 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 2 & 3 \end{vmatrix}$$

$$\frac{r_2 - r_1}{2} \begin{vmatrix} 2 & 3 & 4 & 5 \\ 1 & 1 & 1 & 0 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 2 & 3 \end{vmatrix} = \frac{r_1 - 2r_2}{2} \begin{vmatrix} 0 & 1 & 2 & 5 \\ 1 & 1 & 1 & 0 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 2 & 3 \end{vmatrix} = \begin{vmatrix} 0 & 1 & 2 & 5 \\ 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 1 & 2 & 3 \end{vmatrix}$$

$$\frac{r_4 - 2r_2}{\begin{vmatrix}
0 & 1 & 2 & 5 \\
1 & 1 & 1 & 0 \\
0 & 0 & 0 & 1 \\
0 & 0 & 1 & 3
\end{vmatrix} = - \begin{vmatrix}
0 & 1 & 2 \\
1 & 1 & 1 \\
0 & 0 & 1
\end{vmatrix} = - \begin{vmatrix}
0 & 1 \\
1 & 1
\end{vmatrix}$$



$$\begin{vmatrix} 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 5 \\ 4 & 5 & 6 & 6 \\ 5 & 6 & 8 & 9 \end{vmatrix} \xrightarrow{\underline{r_4 - r_3}} \begin{vmatrix} 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 5 \\ 4 & 5 & 6 & 6 \\ 1 & 1 & 2 & 3 \end{vmatrix} \xrightarrow{\underline{r_3 - r_2}} \begin{vmatrix} 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 5 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 2 & 3 \end{vmatrix}$$

$$\frac{r_2 - r_1}{2} \begin{vmatrix} 2 & 3 & 4 & 5 \\ 1 & 1 & 1 & 0 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 2 & 3 \end{vmatrix} \xrightarrow{r_1 - 2r_2} \begin{vmatrix} 0 & 1 & 2 & 5 \\ 1 & 1 & 1 & 0 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 2 & 3 \end{vmatrix} \xrightarrow{r_3 - r_2} \begin{vmatrix} 0 & 1 & 2 & 5 \\ 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 1 & 2 & 3 \end{vmatrix}$$

$$\frac{r_4 - 2r_2}{\begin{vmatrix} 0 & 1 & 2 & 5 \\ 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 3 \end{vmatrix}} = - \begin{vmatrix} 0 & 1 & 2 \\ 1 & 1 & 1 \\ 0 & 0 & 1 \end{vmatrix} = - \begin{vmatrix} 0 & 1 \\ 1 & 1 \end{vmatrix} = 1 \neq 0$$



§1.4 克莱姆法则

$$\begin{vmatrix} 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 5 \\ 4 & 5 & 6 & 6 \\ 5 & 6 & 8 & 9 \end{vmatrix} \xrightarrow{\underline{r_4 - r_3}} \begin{vmatrix} 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 5 \\ 4 & 5 & 6 & 6 \\ 1 & 1 & 2 & 3 \end{vmatrix} \xrightarrow{\underline{r_3 - r_2}} \begin{vmatrix} 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 5 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 2 & 3 \end{vmatrix}$$

$$\xrightarrow{\underline{r_2 - r_1}} \begin{vmatrix} 2 & 3 & 4 & 5 \\ 1 & 1 & 1 & 0 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 2 & 3 \end{vmatrix} \xrightarrow{\underline{r_1 - 2r_2}} \begin{vmatrix} 0 & 1 & 2 & 5 \\ 1 & 1 & 1 & 0 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 2 & 3 \end{vmatrix} \xrightarrow{\underline{r_3 - r_2}} \begin{vmatrix} 0 & 1 & 2 & 5 \\ 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 1 & 2 & 3 \end{vmatrix}$$

$$\frac{r_4 - 2r_2}{=} \begin{vmatrix} 0 & 1 & 2 & 5 \\ 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 3 \end{vmatrix} = - \begin{vmatrix} 0 & 1 & 2 \\ 1 & 1 & 1 \\ 0 & 0 & 1 \end{vmatrix} = - \begin{vmatrix} 0 & 1 \\ 1 & 1 \end{vmatrix} = 1 \neq 0$$

所以齐次线性方程组有唯一解



练习 齐次线性方程组 $\begin{cases} kx_1 & + x_4 = 0 \\ x_1 + 2x_2 & - x_4 = 0 \\ (k+2)x_1 - x_2 & + 4x_4 = 0 \\ 2x_1 + x_2 + 3x_3 + kx_4 = 0 \end{cases}$ 有非零解

的充分必要条件是 k 满足 $_{___}$



练习 齐次线性方程组
$$\begin{cases} kx_1 + x_4 = 0 \\ x_1 + 2x_2 - x_4 = 0 \\ (k+2)x_1 - x_2 + 4x_4 = 0 \\ 2x_1 + x_2 + 3x_3 + kx_4 = 0 \end{cases}$$

的充分必要条件是 k 满足

$$D = \begin{vmatrix} k & 0 & 0 & 1 \\ 1 & 2 & 0 & -1 \\ k+2 & -1 & 0 & 4 \\ 2 & 1 & 3 & k \end{vmatrix}$$



有非零解

练习 齐次线性方程组
$$\begin{cases} kx_1 & + x_4 = 0 \\ x_1 + 2x_2 & - x_4 = 0 \\ (k+2)x_1 - x_2 & + 4x_4 = 0 \\ 2x_1 + x_2 + 3x_3 + kx_4 = 0 \end{cases}$$

有非零解

的充分必要条件是 k 满足 ____

$$D = \begin{vmatrix} k & 0 & 0 & 1 \\ 1 & 2 & 0 & -1 \\ k+2 & -1 & 0 & 4 \\ 2 & 1 & 3 & k \end{vmatrix} = 3.$$



练习 齐次线性方程组
$$\begin{cases} kx_1 + x_4 = 0 \\ x_1 + 2x_2 - x_4 = 0 \\ (k+2)x_1 - x_2 + 4x_4 = 0 \\ 2x_1 + x_2 + 3x_3 + kx_4 = 0 \end{cases}$$
 有非零解

的充分必要条件是 k 满足 ____

$$D = \begin{vmatrix} k & 0 & 0 & 1 \\ 1 & 2 & 0 & -1 \\ k+2 & -1 & 0 & 4 \\ 2 & 1 & 3 & k \end{vmatrix} = 3 \cdot (-1)^{3+4} \begin{vmatrix} k & 0 & 1 \\ 1 & 2 & -1 \\ k+2 & -1 & 4 \end{vmatrix}$$



练习 齐次线性方程组
$$\begin{cases} kx_1 & + x_4 = 0 \\ x_1 + 2x_2 & - x_4 = 0 \\ (k+2)x_1 - x_2 & + 4x_4 = 0 \\ 2x_1 + x_2 + 3x_3 + kx_4 = 0 \end{cases}$$
 有非零解

的充分必要条件是 k 满足 $_{__}$

$$D = \begin{vmatrix} k & 0 & 0 & 1 \\ 1 & 2 & 0 & -1 \\ k+2 & -1 & 0 & 4 \\ 2 & 1 & 3 & k \end{vmatrix} = 3 \cdot (-1)^{3+4} \begin{vmatrix} k & 0 & 1 \\ 1 & 2 & -1 \\ k+2 & -1 & 4 \end{vmatrix}$$

$$r_2 + r_1$$



练习 齐次线性方程组 $\begin{cases} kx_1 + x_4 = 0 \\ x_1 + 2x_2 - x_4 = 0 \\ (k+2)x_1 - x_2 + 4x_4 = 0 \\ 2x_1 + x_2 + 3x_3 + kx_4 = 0 \end{cases}$ 有非零解

的充分必要条件是 k 满足 ____

$$D = \begin{vmatrix} k & 0 & 0 & 1 \\ 1 & 2 & 0 & -1 \\ k+2 & -1 & 0 & 4 \\ 2 & 1 & 3 & k \end{vmatrix} = 3 \cdot (-1)^{3+4} \begin{vmatrix} k & 0 & 1 \\ 1 & 2 & -1 \\ k+2 & -1 & 4 \end{vmatrix}$$

$$\frac{r_2 + r_1}{k} (-3) \cdot \begin{vmatrix} k & 0 & 1 \\ k & 0 & 1 \end{vmatrix}$$



练习 齐次线性方程组
$$\begin{cases} kx_1 + x_4 = 0 \\ x_1 + 2x_2 - x_4 = 0 \\ (k+2)x_1 - x_2 + 4x_4 = 0 \\ 2x_1 + x_2 + 3x_3 + kx_4 = 0 \end{cases}$$
 有非零解

的充分必要条件是 k 满足 ____

$$D = \begin{vmatrix} k & 0 & 0 & 1 \\ 1 & 2 & 0 & -1 \\ k+2 & -1 & 0 & 4 \\ 2 & 1 & 3 & k \end{vmatrix} = 3 \cdot (-1)^{3+4} \begin{vmatrix} k & 0 & 1 \\ 1 & 2 & -1 \\ k+2 & -1 & 4 \end{vmatrix}$$

$$\frac{r_2 + r_1}{k} (-3) \cdot \begin{vmatrix} k & 0 & 1 \\ k+1 & 2 & 0 \end{vmatrix}$$



练习 齐次线性方程组
$$\begin{cases} kx_1 + x_4 = 0 \\ x_1 + 2x_2 - x_4 = 0 \\ (k+2)x_1 - x_2 + 4x_4 = 0 \\ 2x_1 + x_2 + 3x_3 + kx_4 = 0 \end{cases}$$

的充分必要条件是 k 满足

$$D = \begin{vmatrix} k & 0 & 0 & 1 \\ 1 & 2 & 0 & -1 \\ k+2 & -1 & 0 & 4 \\ 2 & 1 & 3 & k \end{vmatrix} = 3 \cdot (-1)^{3+4} \begin{vmatrix} k & 0 & 1 \\ 1 & 2 & -1 \\ k+2 & -1 & 4 \end{vmatrix}$$

$$\frac{r_2 + r_1}{r_3 - 4r_1} (-3) \cdot \begin{vmatrix} k & 0 & 1 \\ k + 1 & 2 & 0 \end{vmatrix}$$

有非零解

练习 齐次线性方程组
$$\begin{cases} kx_1 & + x_4 = 0 \\ x_1 + 2x_2 & - x_4 = 0 \\ (k+2)x_1 - x_2 & + 4x_4 = 0 \\ 2x_1 + x_2 + 3x_3 + kx_4 = 0 \end{cases}$$
的充分必要条件是 k 满足

可光力必安东什定人体

$$D = \begin{vmatrix} k & 0 & 0 & 1 \\ 1 & 2 & 0 & -1 \\ k+2 & -1 & 0 & 4 \\ 2 & 1 & 3 & k \end{vmatrix} = 3 \cdot (-1)^{3+4} \begin{vmatrix} k & 0 & 1 \\ 1 & 2 & -1 \\ k+2 & -1 & 4 \end{vmatrix}$$
$$\frac{r_2 + r_1}{r_3 - 4r_1} (-3) \cdot \begin{vmatrix} k & 0 & 1 \\ k+1 & 2 & 0 \\ -3k+2 & -1 & 0 \end{vmatrix}$$



练习 齐次线性方程组 $\begin{cases} kx_1 & + x_4 = 0 \\ x_1 + 2x_2 & - x_4 = 0 \\ (k+2)x_1 - x_2 & + 4x_4 = 0 \\ 2x_1 + x_2 + 3x_3 + kx_4 = 0 \end{cases}$ 有非零解

的充分必要条件是 k 满足 ____

$$D = \begin{vmatrix} k & 0 & 0 & 1 \\ 1 & 2 & 0 & -1 \\ k+2 & -1 & 0 & 4 \\ 2 & 1 & 3 & k \end{vmatrix} = 3 \cdot (-1)^{3+4} \begin{vmatrix} k & 0 & 1 \\ 1 & 2 & -1 \\ k+2 & -1 & 4 \end{vmatrix}$$

$$\frac{r_2 + r_1}{r_3 - 4r_1} (-3) \cdot \begin{vmatrix} k & 0 & 1 \\ k + 1 & 2 & 0 \\ -3k + 2 & -1 & 0 \end{vmatrix} = (-3) \cdot (-1)^{1+3} \cdot \begin{vmatrix} k + 1 & 2 \\ -3k + 2 & -1 \end{vmatrix}$$



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$$= -3(5k-5)$$



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有非零解当且仅当 D=0.

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有非零解当且仅当 D=0,当且仅当 k=1



=-3(5k-5)