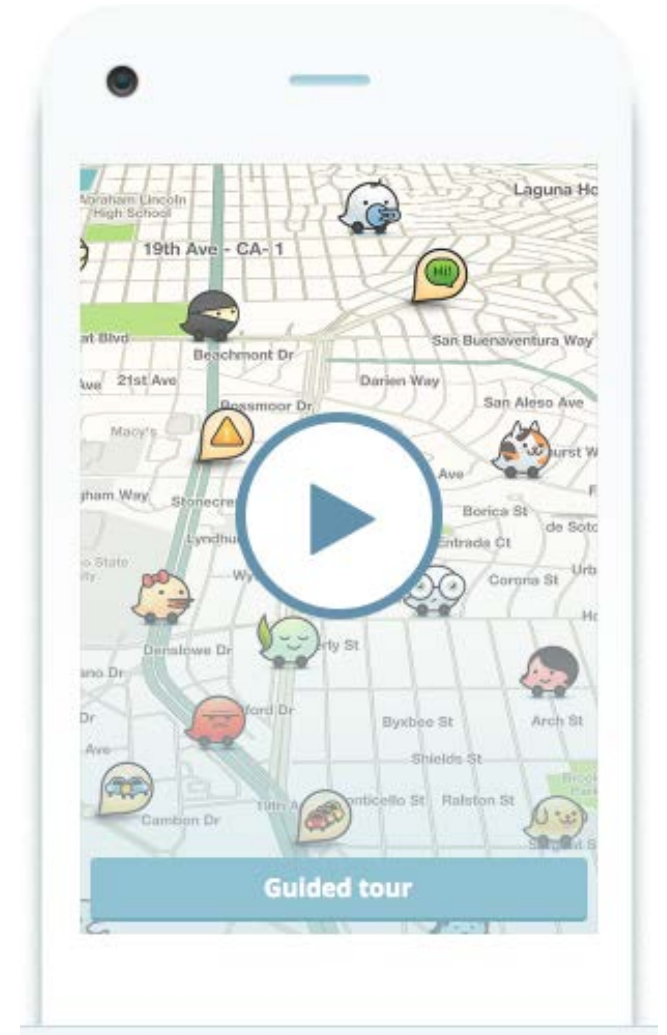


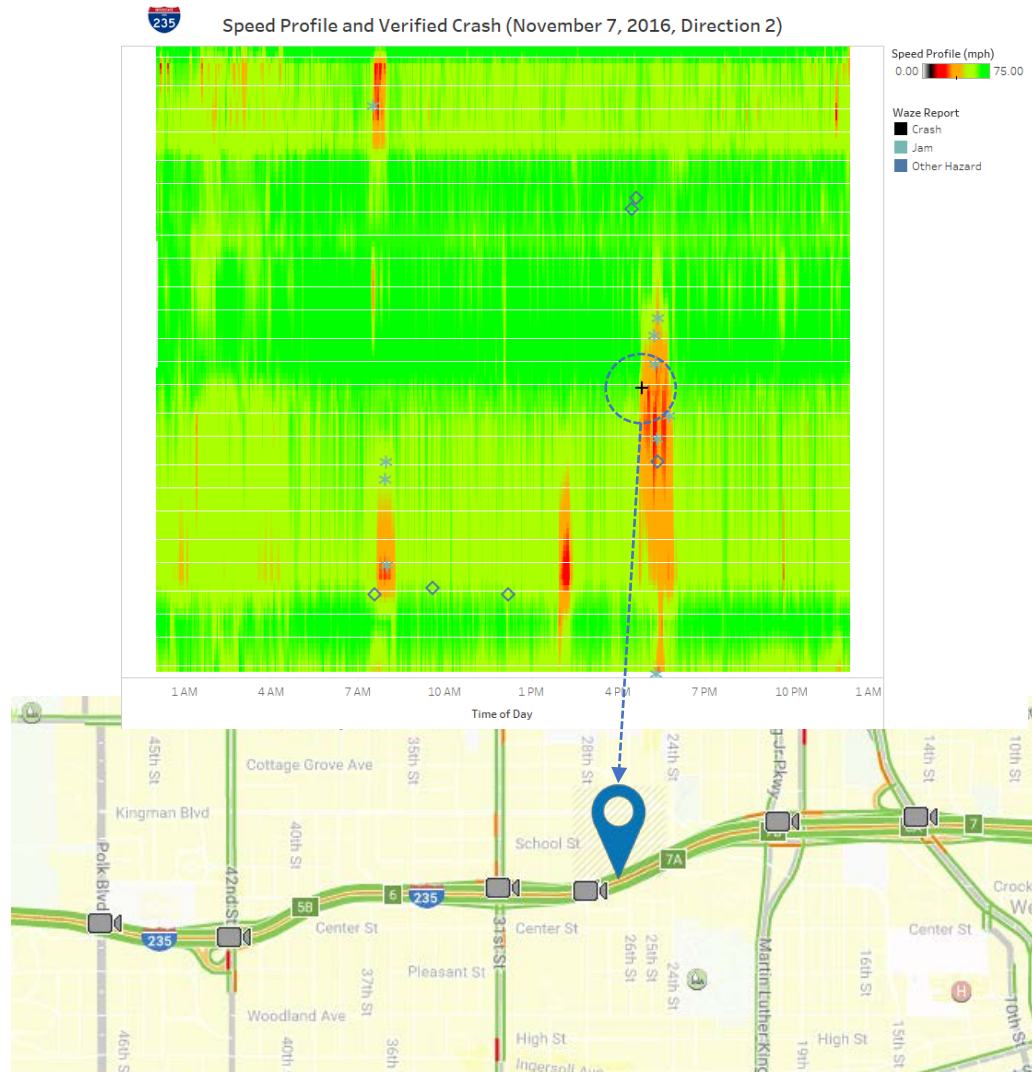
Crash Identification using Waze Report

Problem Description – Waze

- Waze is a mobile application for user to report traffic issues
- Three types to report:
 - Accident
 - Jam
 - Hazard
- Google bought Waze in 2013
- Iowa DOT is using Waze for crash identification



Problem Description – Waze



East I-235 @ Keo Way (DMTV09) 11/07/2016 17:01:01



East I-235 @ Polk Blvd (DMTV14) 11/07/2016 17:01:01



Problem Description - Summary

- Crash or not is what DOT cares about
- It is necessary and beneficial to score Waze reports in terms of crash likelihood (100,000 /year state-wide)
- Waze score their reports based on user credit level
- **We score Waze reports based real traffic and weather condition: $P(\text{Crash} \mid \text{traffic, weather})$**

Case Study

 **Location:** Interstate 235 in Des Moines, both directions

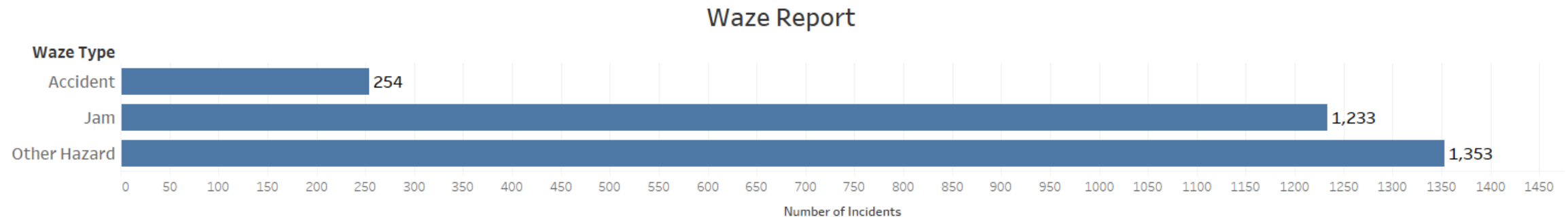
 **Time Period:** Sep. 2016 - Dec.2016

 **Data Sources:**

- Waze reports
- Wavetronix - traffic
- RWIS - weather
- TMC crash reports

Data Description – Waze

- 2,840 – Total
- 254 – Accident
- 1,233 – Jam
- 1,353 – Hazard



Data Description – Wavetronix

- Radar sensors collect traffic data including:
vehicle speed (mi/h);
volume (veh/h);
sensor occupancy (%).
- 15 sensors on EB /14 sensors on WB.
- Data resolution: every 20 seconds.



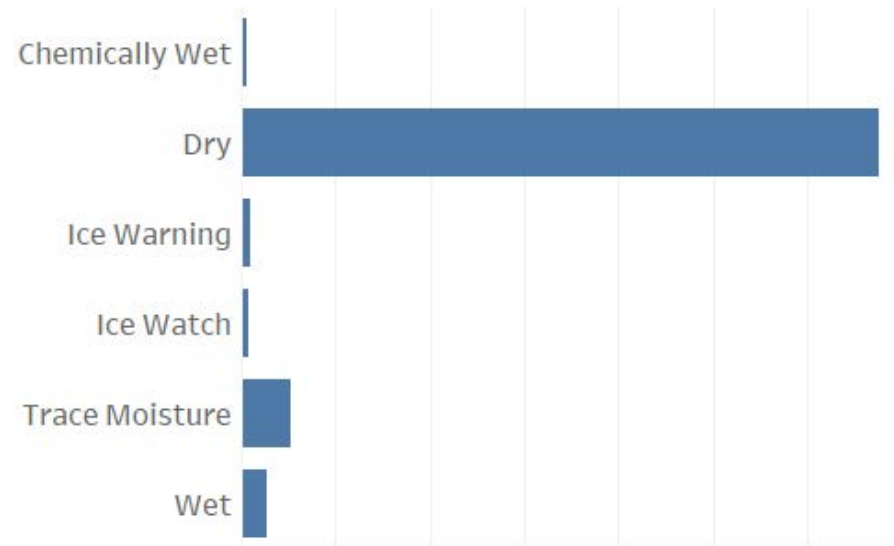
Wavetronix Sensor



Sensor Locations

Data Description – RWIS

- Road Weather Information System (RWIS)
 - Temperatures
 - Pavement conditions
- Pavement Conditions:



Dry = 0

Not Dry = 1



Weather Sensor RWIS Used

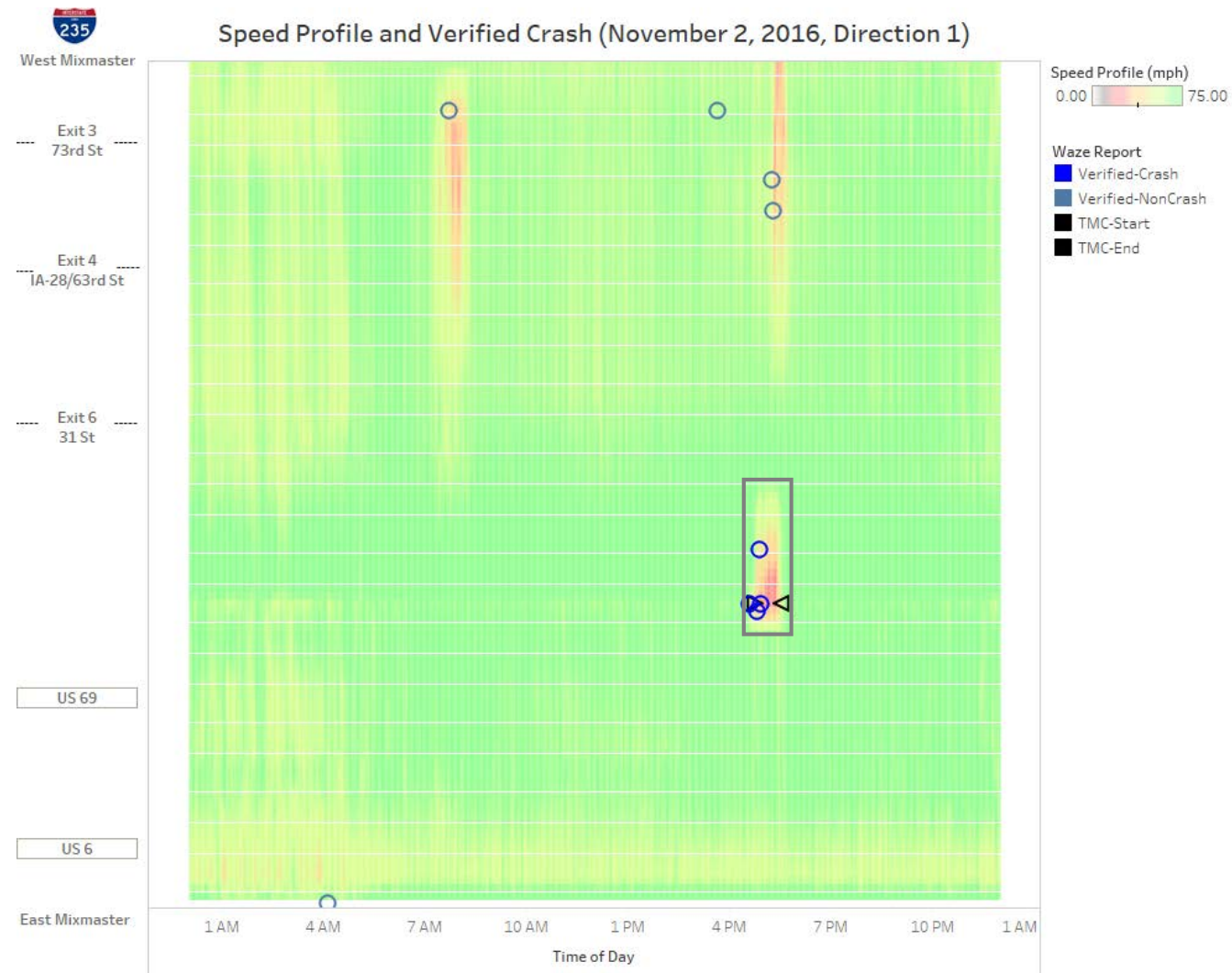


Sensor Location in Our Study Area

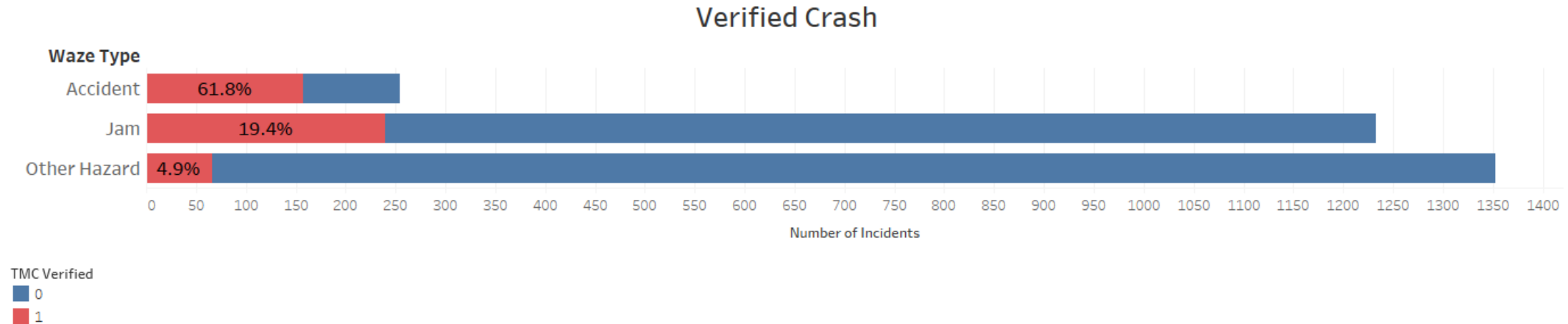
Data Description – TMC crash reports

- TMC = Traffic Management Center of Iowa DOT
- 239 verified crash reports

Data Preparation – Labels



Data Preparation – Label



	ACCIDENT	JAM	HAZARD	Total
Label 1	157	239	66	462
Label 0	97	994	1287	2378
Total	254	1233	1353	2840

Data Preparation – Features

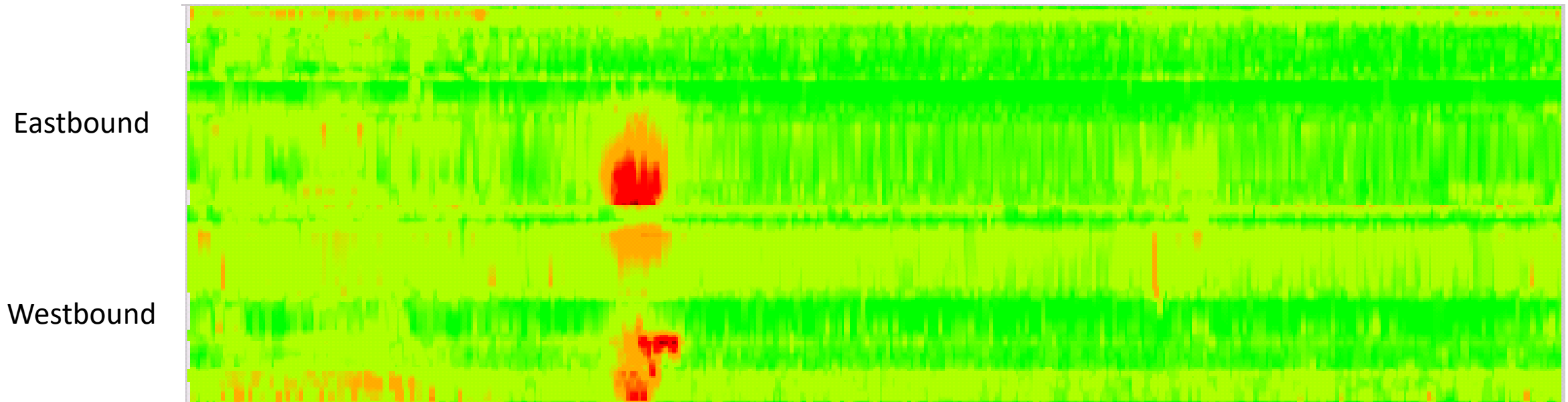
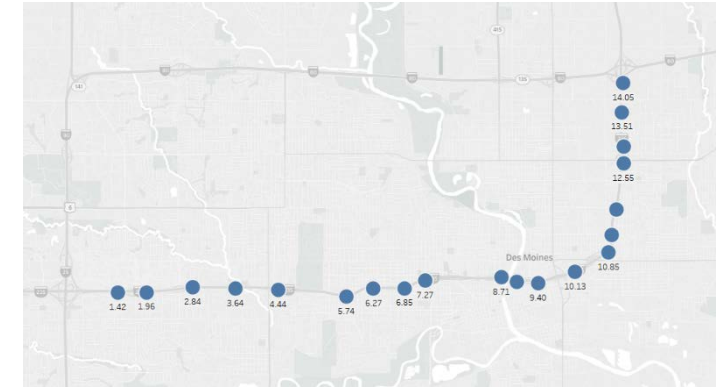
Raw Data → Full Mesh-grid

- Vertical axis

Discrete Sensor Mile Marker → Every 0.1 miles

- Horizontal axis

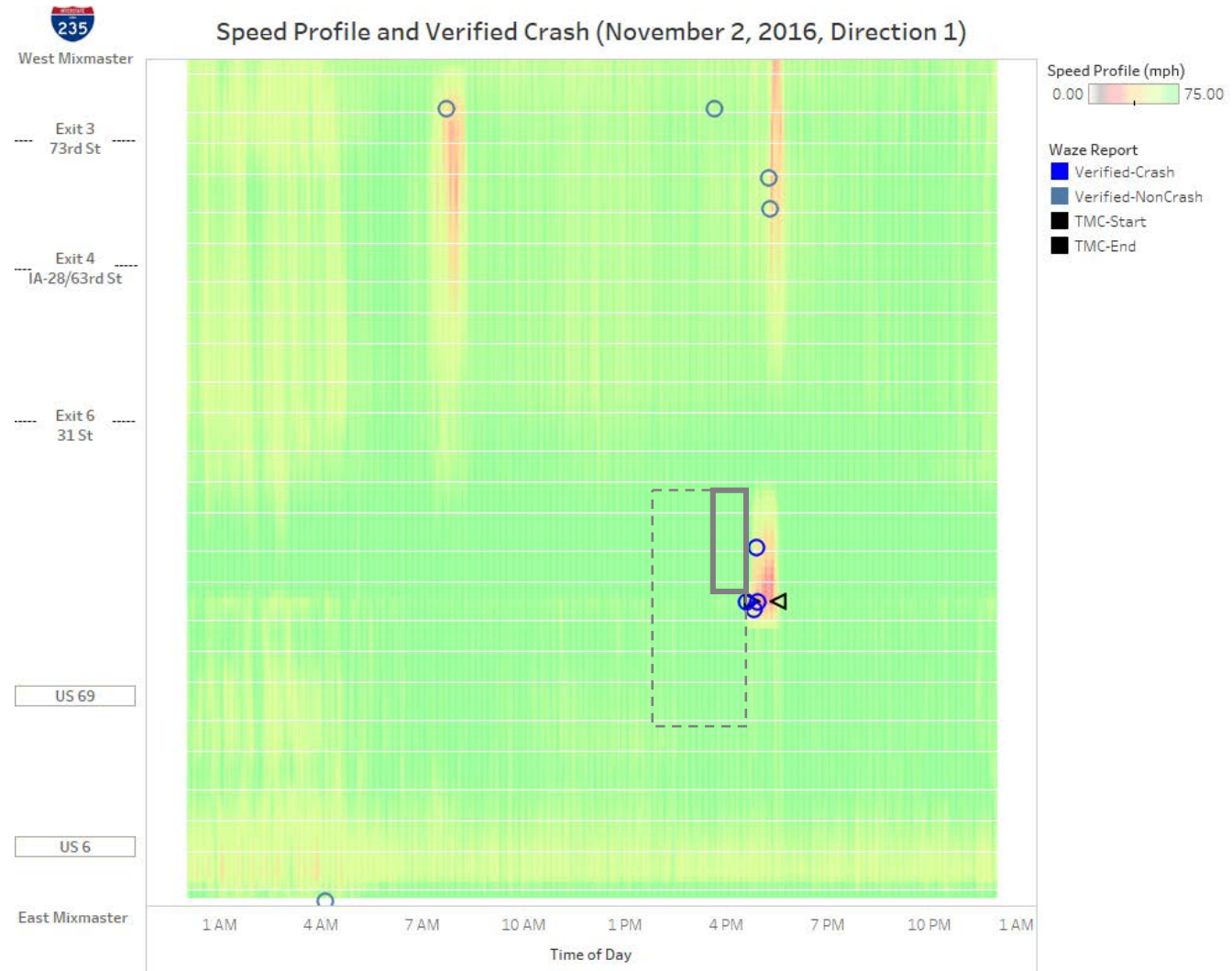
1 Minute with Null Values → Every 1 minute



Data Preparation – Features

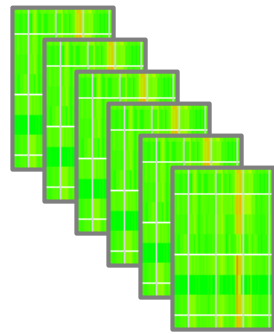
1 mile
 (10 pixels)

 5 minutes
 (5 pixels)

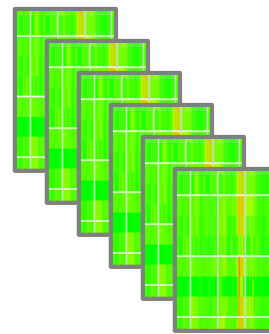


Data Preparation – Summary

- 462 out of 2,840 Waze Reports are labeled as Crash
- 73,014 samples Generated
- 9 Features Included
- Balanced Sample: 7,920 Crashes vs. 7,920 Non-Crashes
- 70% train 30% validation



(7920, 10, 5, 9)

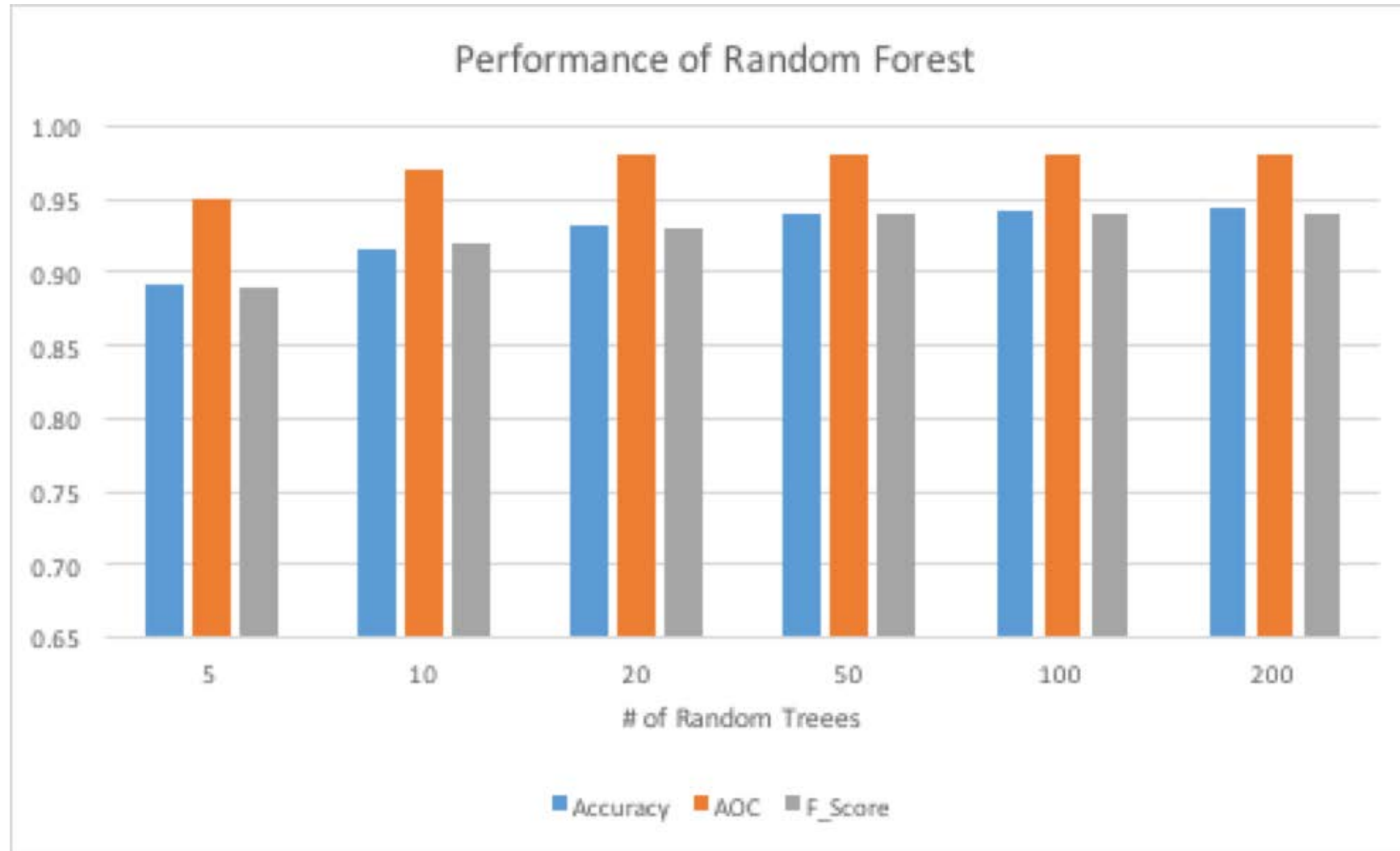


(7920, 10, 5, 9)

Model Results – Shallow Model

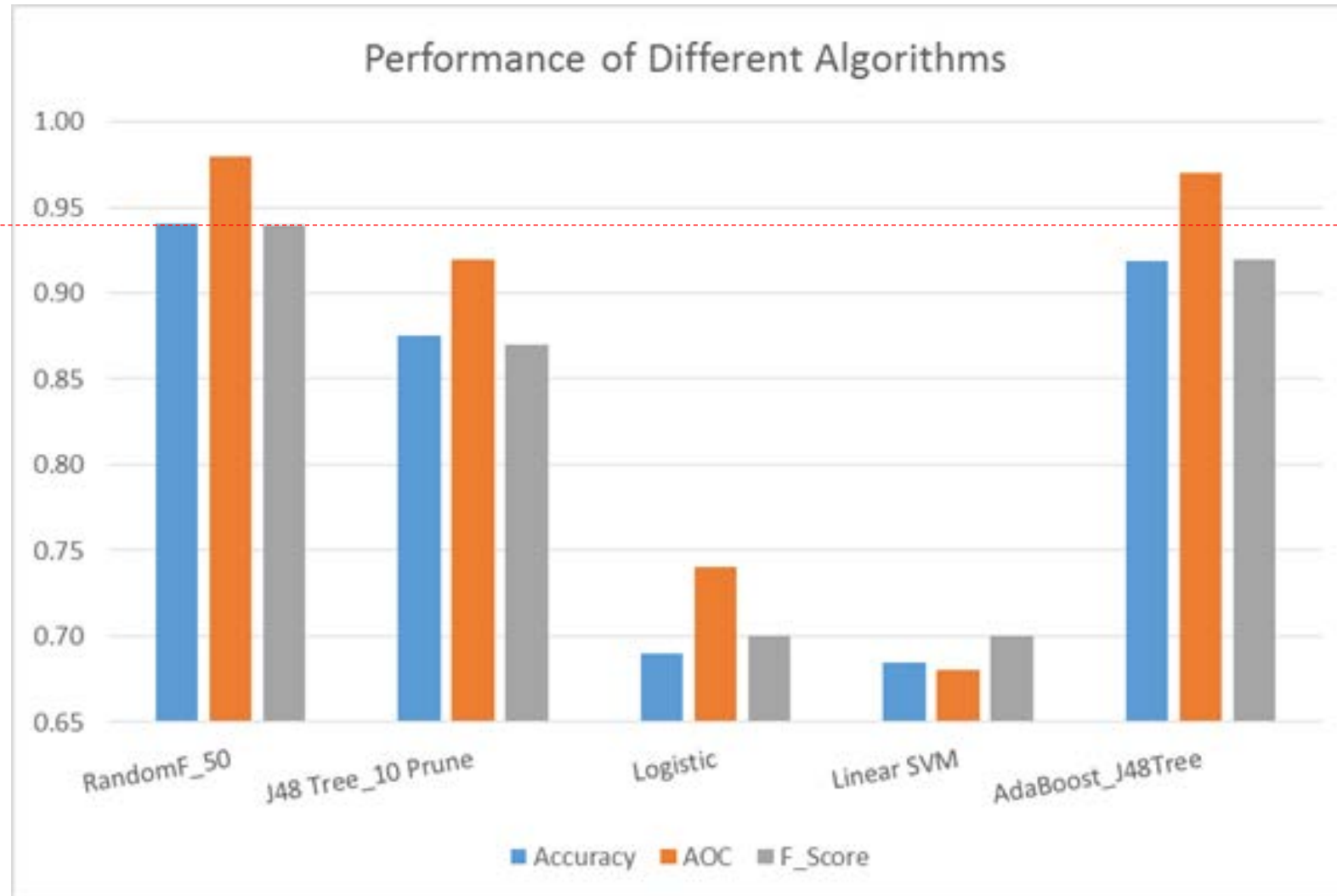


Model Results – Shallow Model

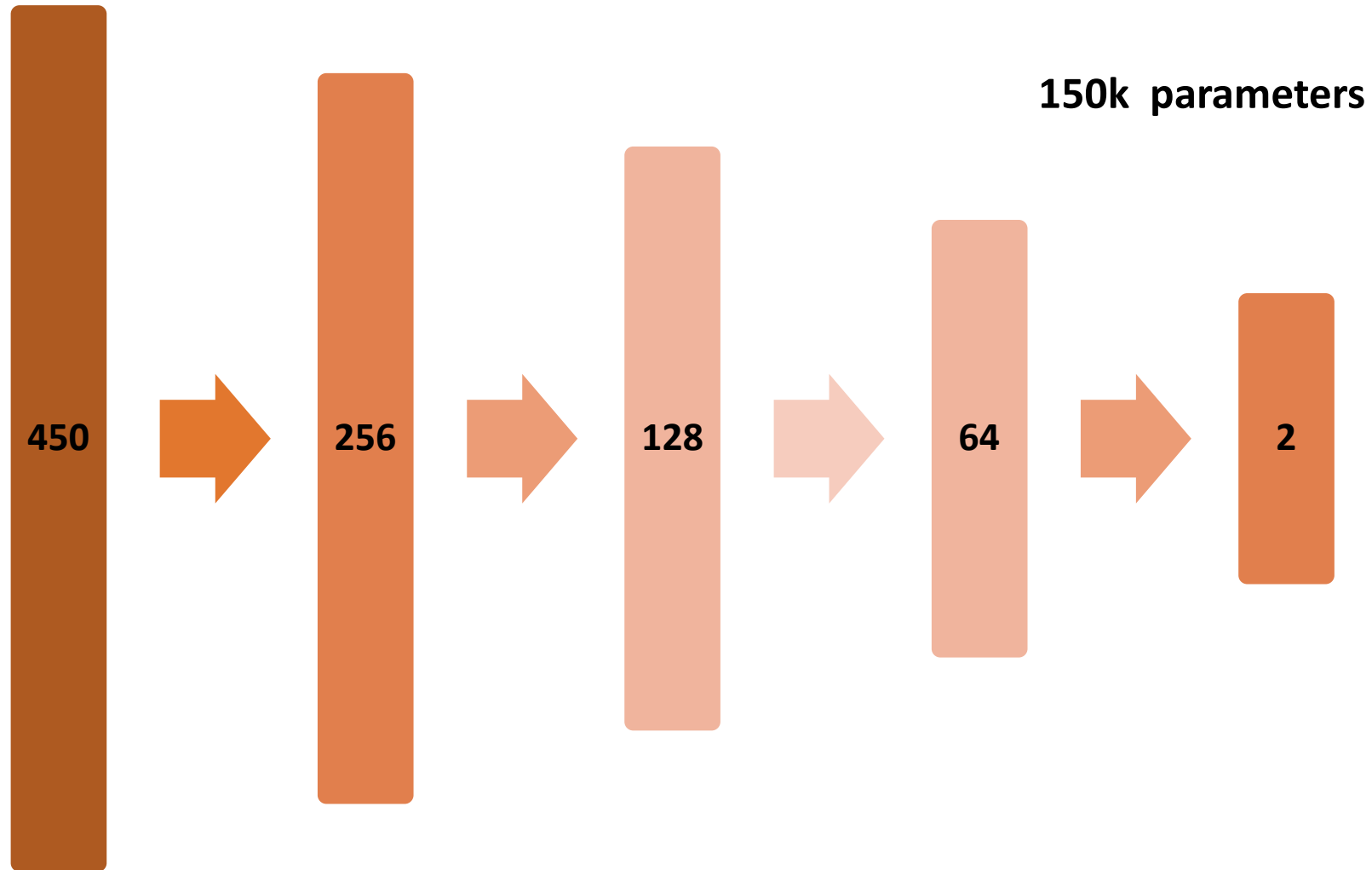


Model Results – Shallow Model

94%

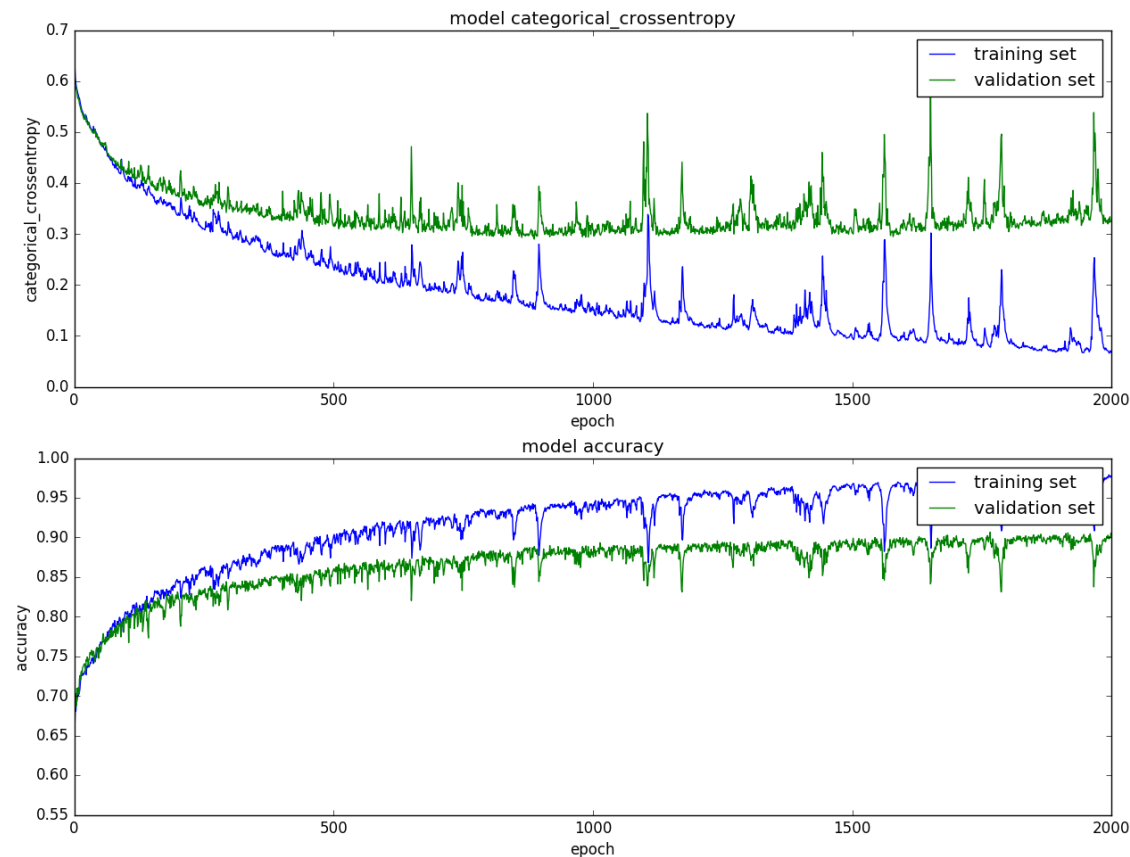


Model Results – Deep Model (FC)



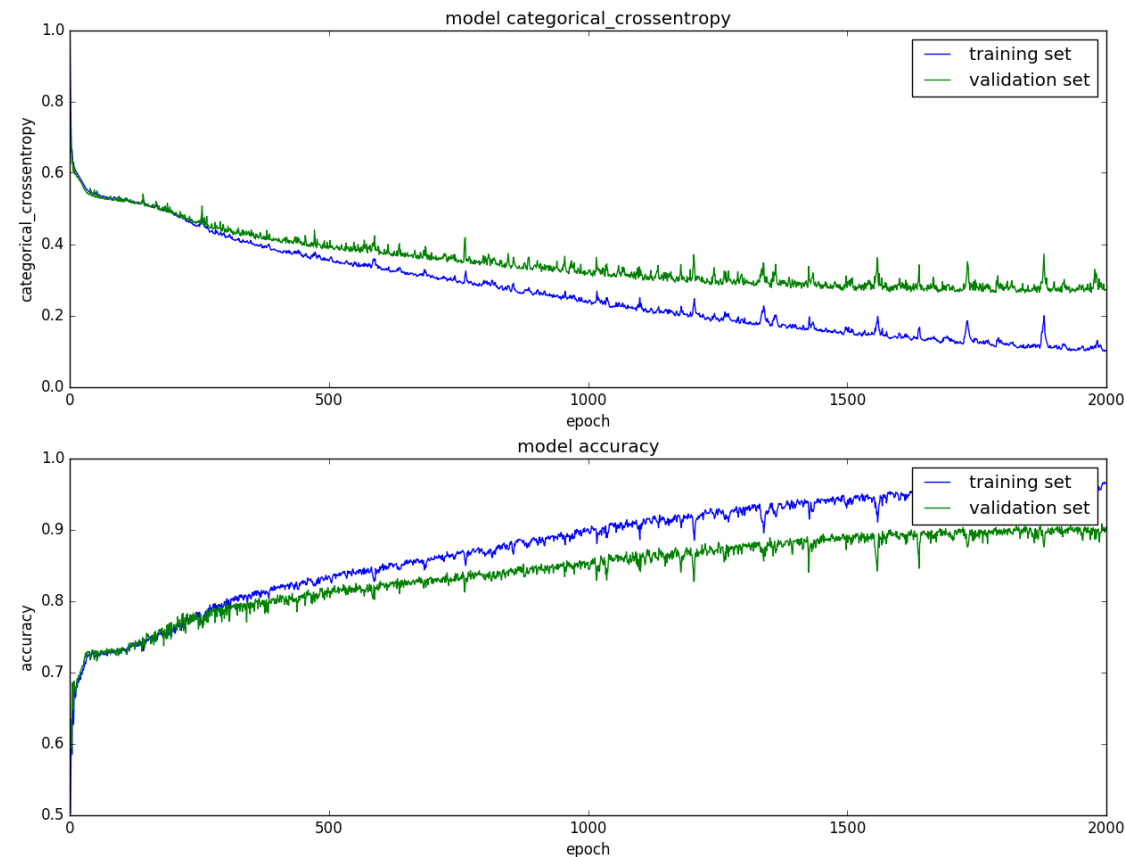
Model Results – Deep Model (FC)

Activation	Epoch	Batch Normalization	Drop Out
ELU	2K	Yes	ALL, 0.25
RELU		No	No



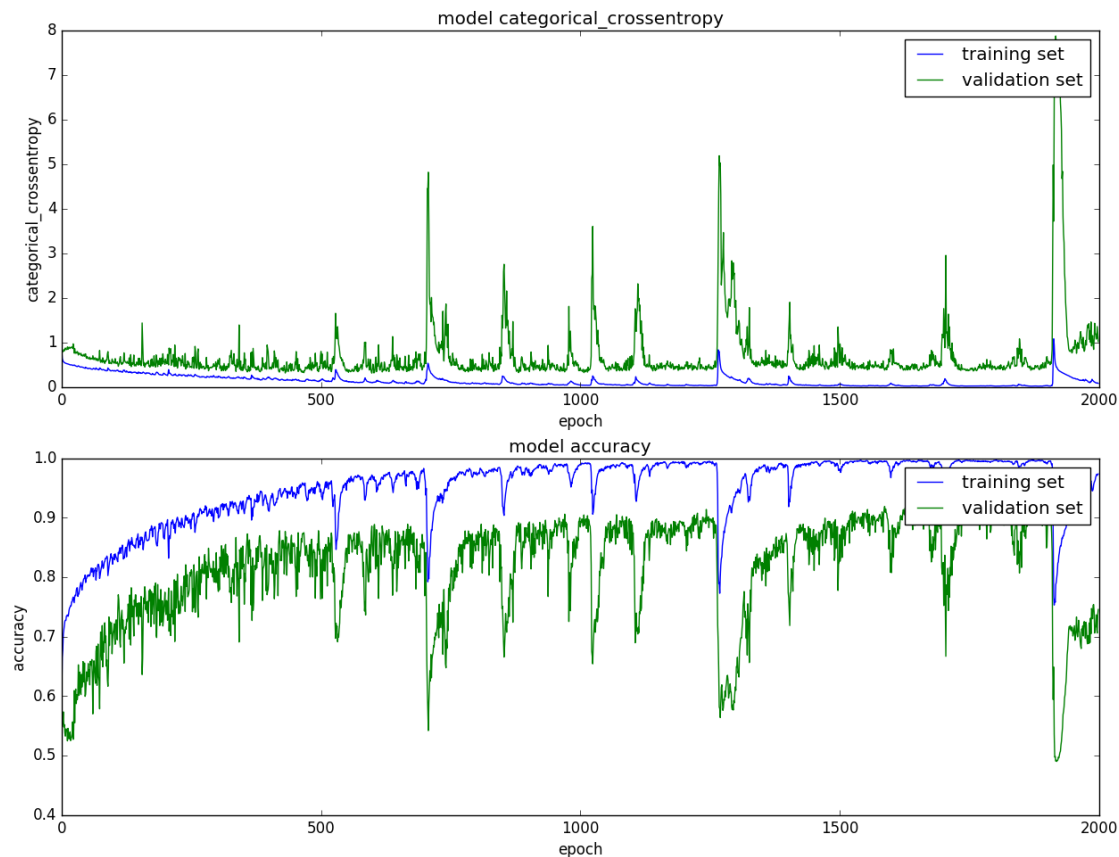
Model Results – Deep Model (FC)

Activation	Epoch	Batch Normalization	Drop Out
ELU	2K	Yes	ALL, 0.25
RELU		No	No



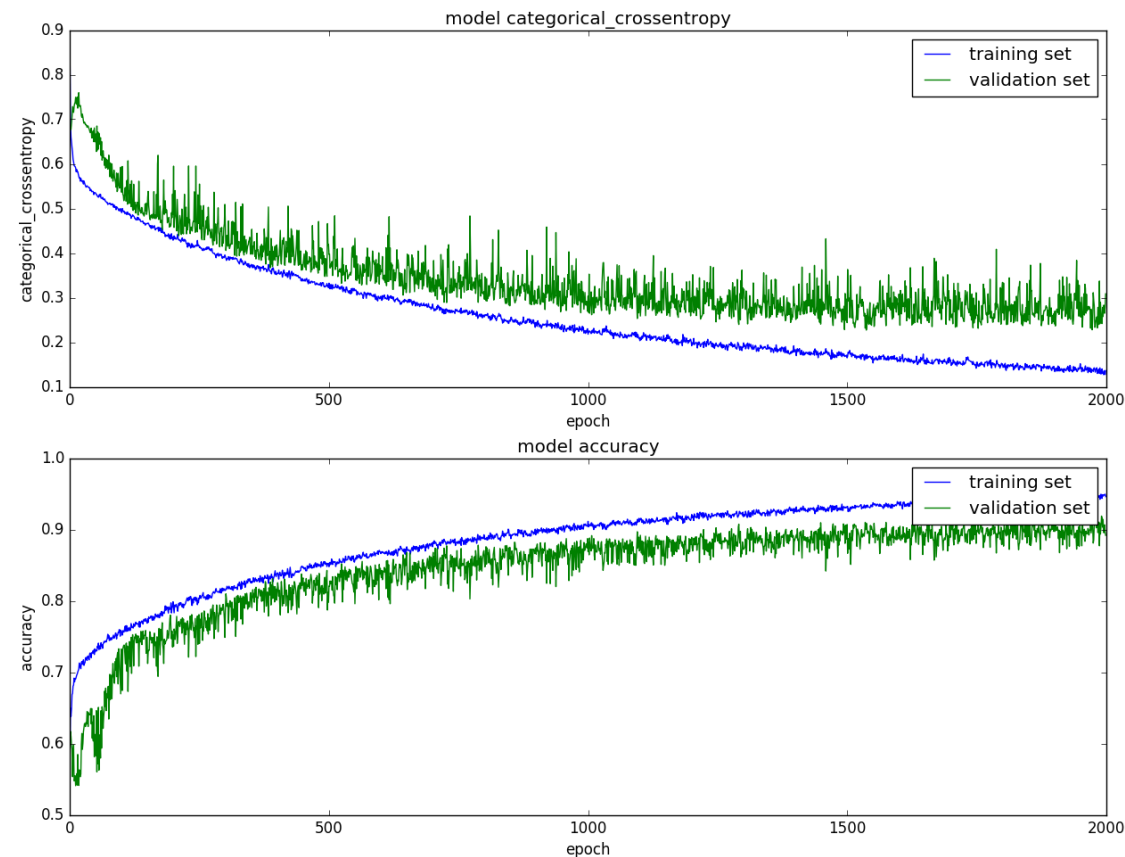
Model Results – Deep Model (FC)

Activation	Epoch	Batch Normalization	Drop Out
ELU	2K	Yes	ALL, 0.25
RELU		No	No



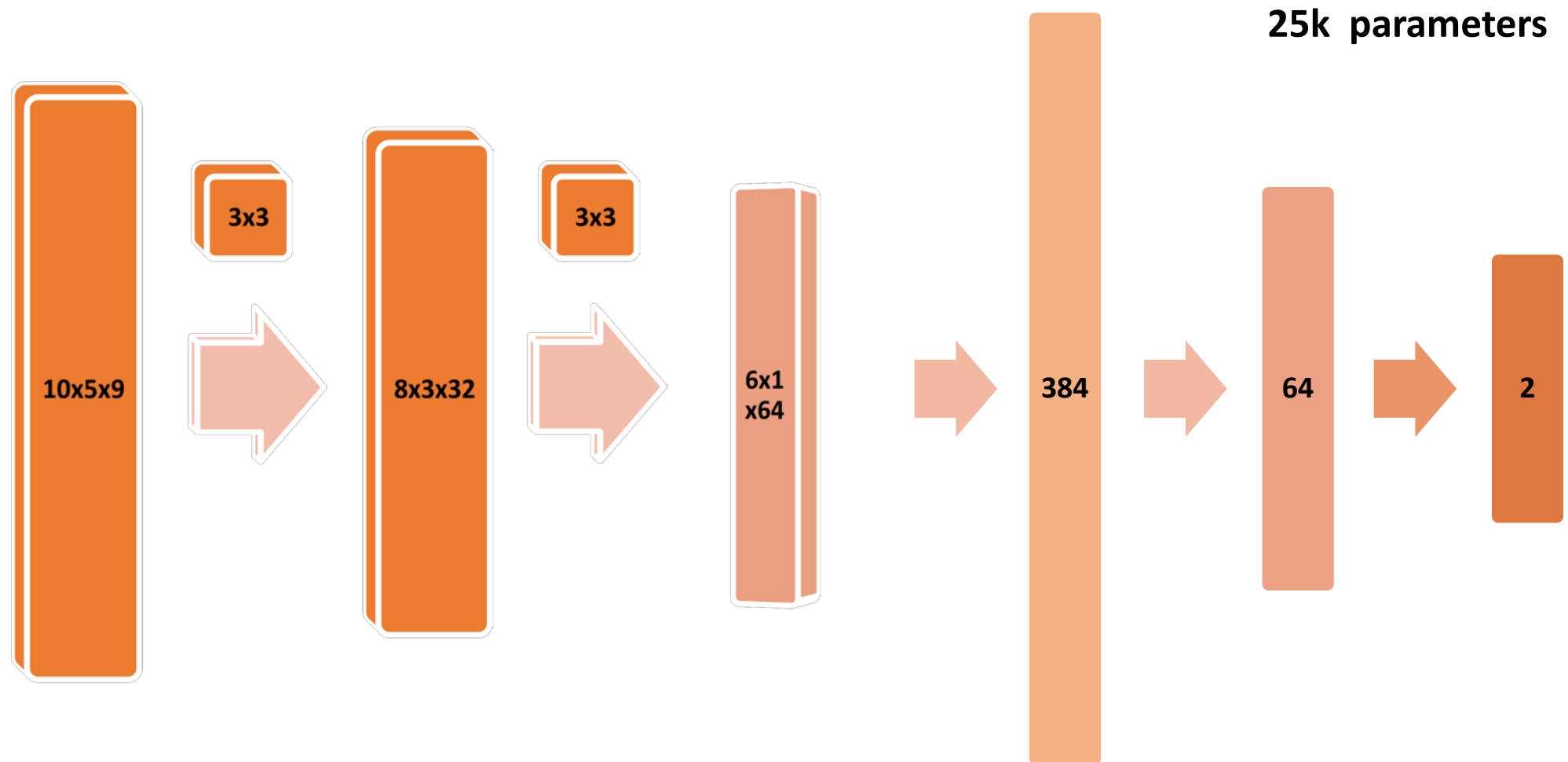
Model Results – Deep Model (FC)

Activation	Epoch	Batch Normalization	Drop Out
ELU	2K	Yes	ALL, 0.25
RELU		No	No



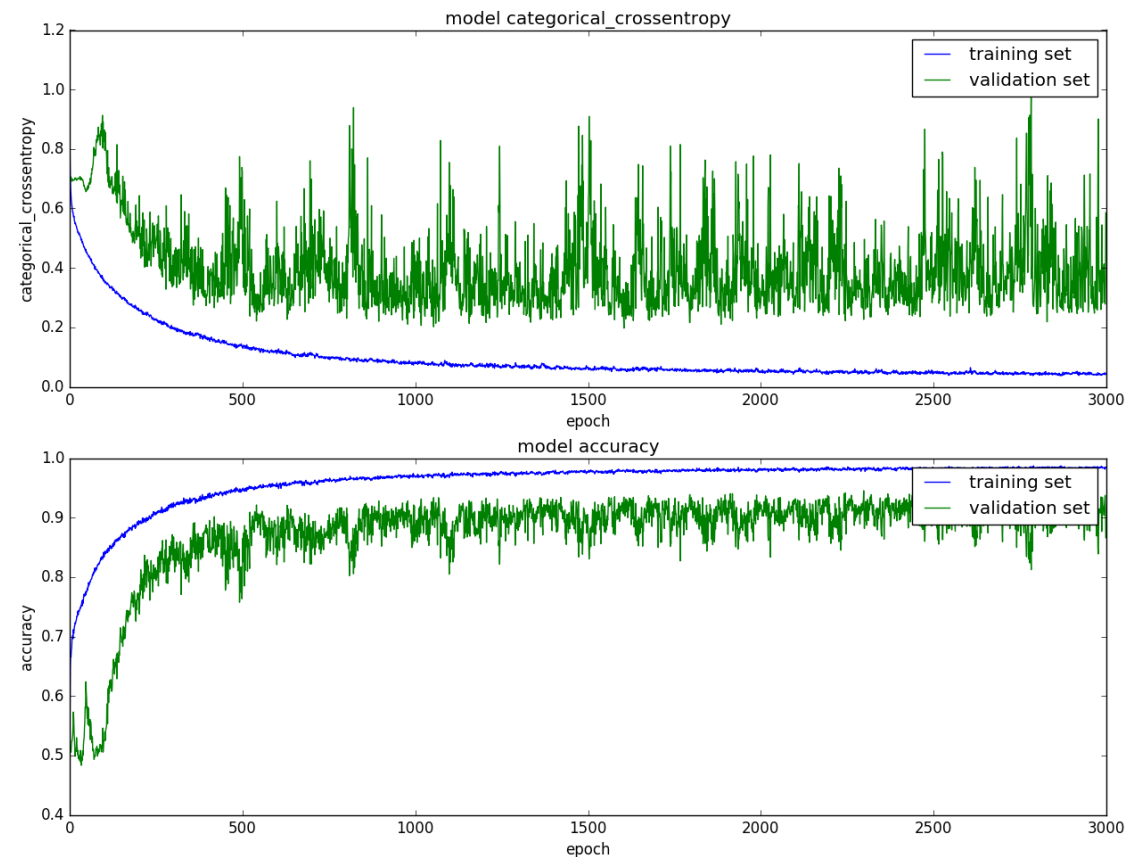
90%

Model Results – Deep Model (CNN)



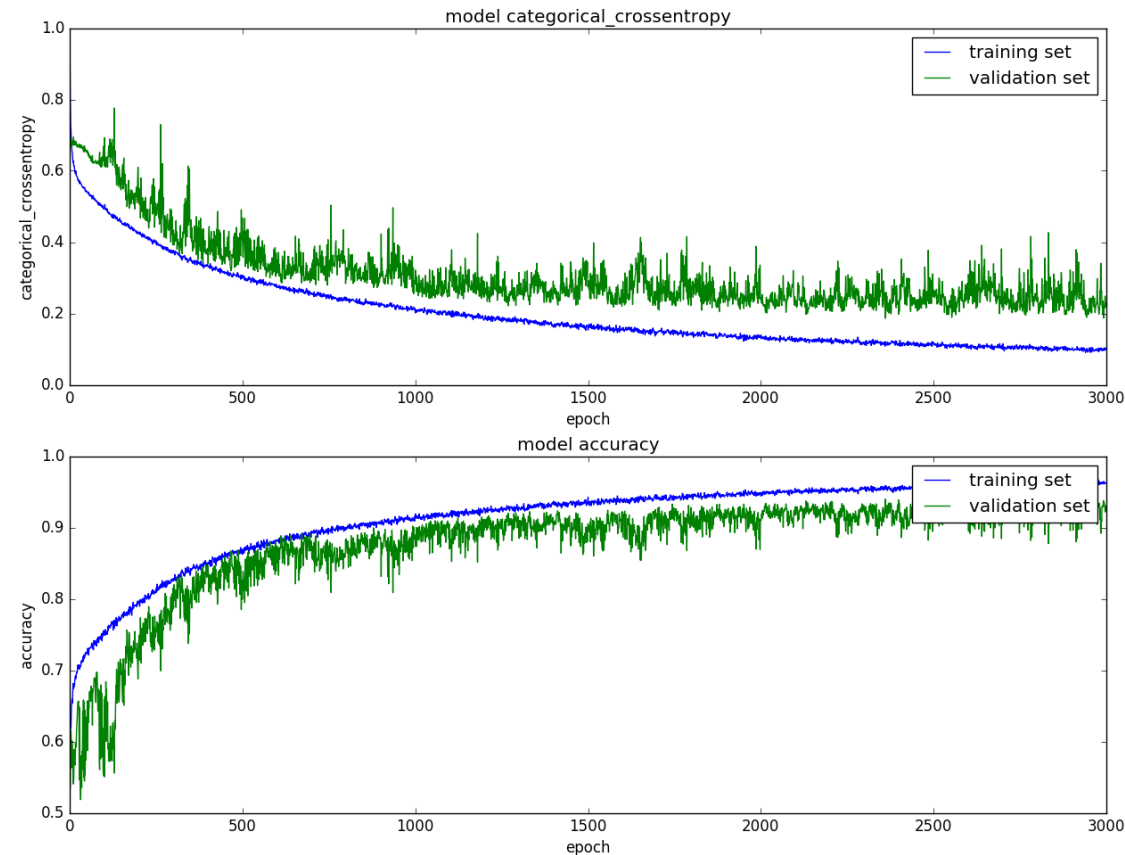
Model Results – Deep Model (CNN)

Activation	Epoch	Batch Normalization	Drop Out	Drop Out Position	Drop Out Rate
ELU	3K	Yes	Yes	ALL	0.25
RELU	10K	No	No	LAST	0.5



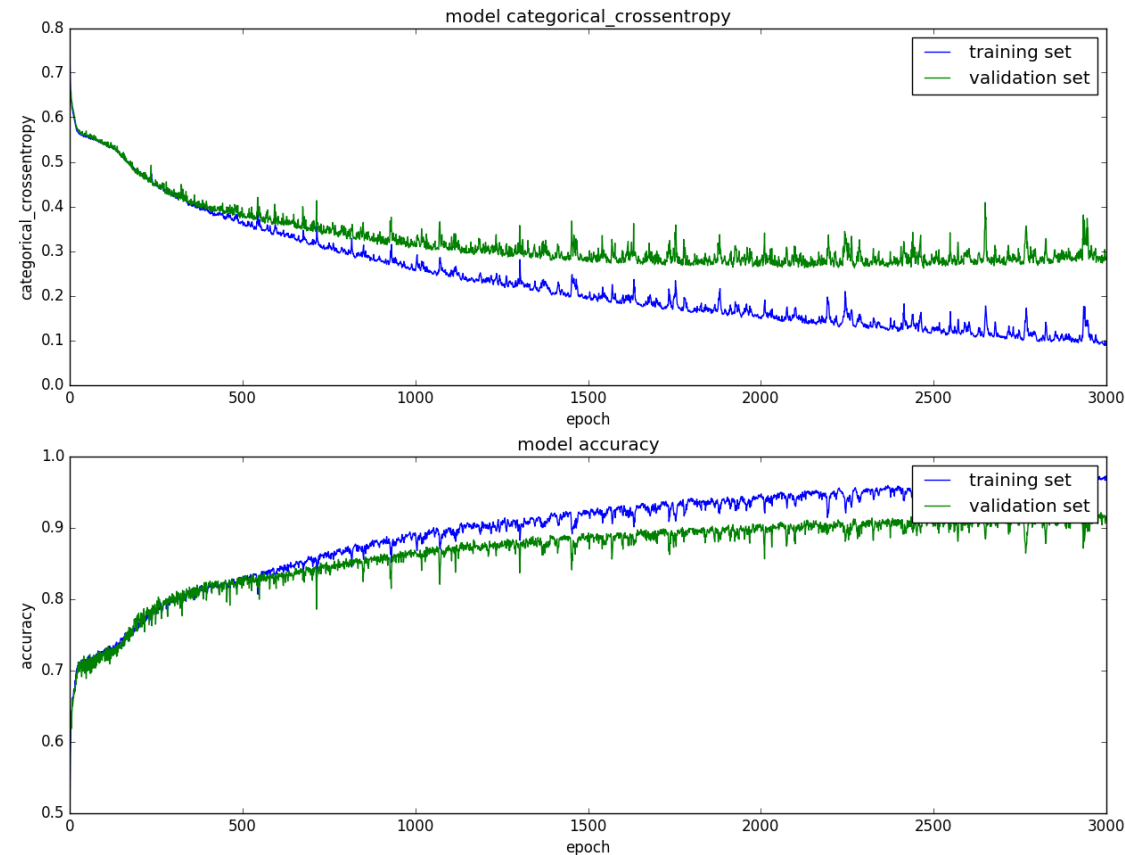
Model Results – Deep Model (CNN)

Activation	Epoch	Batch Normalization	Drop Out	Drop Out Position	Drop Out Rate
ELU	3K	Yes	Yes	ALL	0.25
RELU	10K	No	No	LAST	0.5



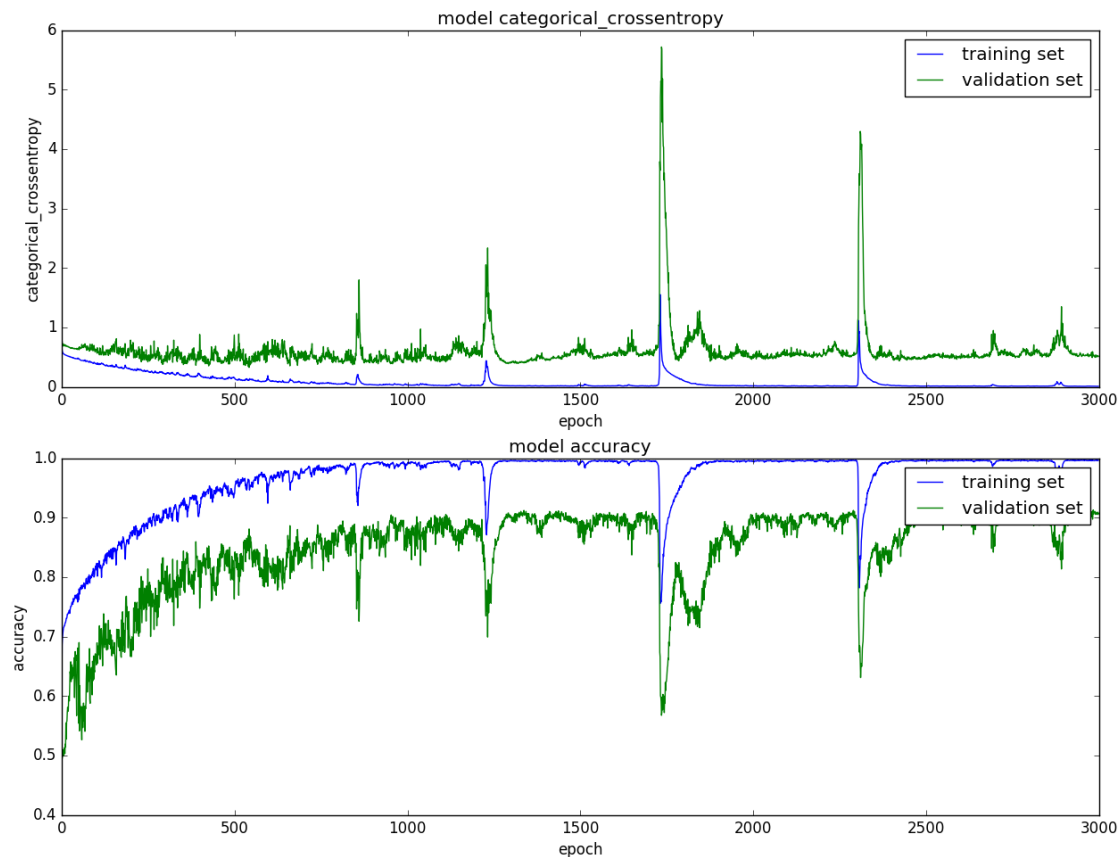
Model Results – Deep Model (CNN)

Activation	Epoch	Batch Normalization	Drop Out	Drop Out Position	Drop Out Rate
ELU	3K	Yes	Yes	ALL	0.25
RELU	10K	No	No	LAST	0.5



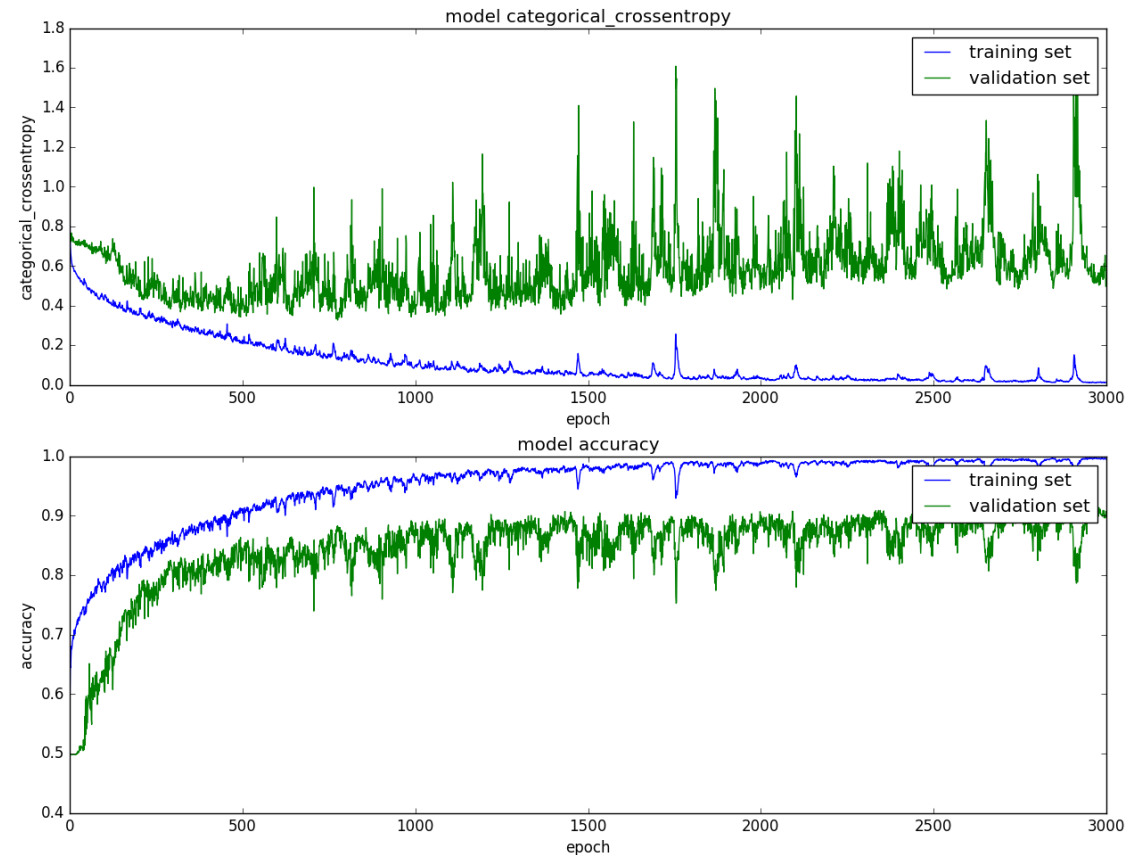
Model Results – Deep Model (CNN)

Activation	Epoch	Batch Normalization	Drop Out	Drop Out Position	Drop Out Rate
ELU	3K	Yes	Yes	ALL	0.25
RELU	10K	No	No	LAST	0.5



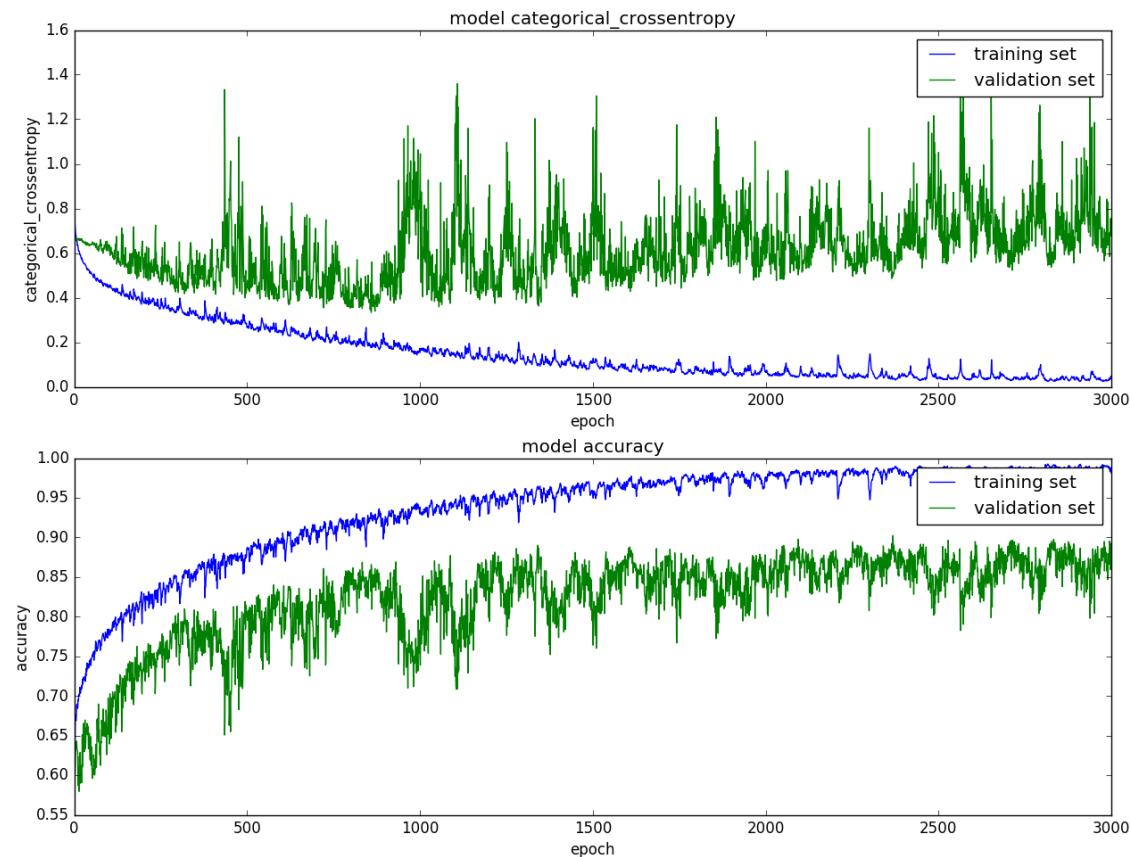
Model Results – Deep Model (CNN)

Activation	Epoch	Batch Normalization	Drop Out	Drop Out Position	Drop Out Rate
ELU	3K	Yes	Yes	ALL	0.25
RELU	10K	No	No	LAST	0.5



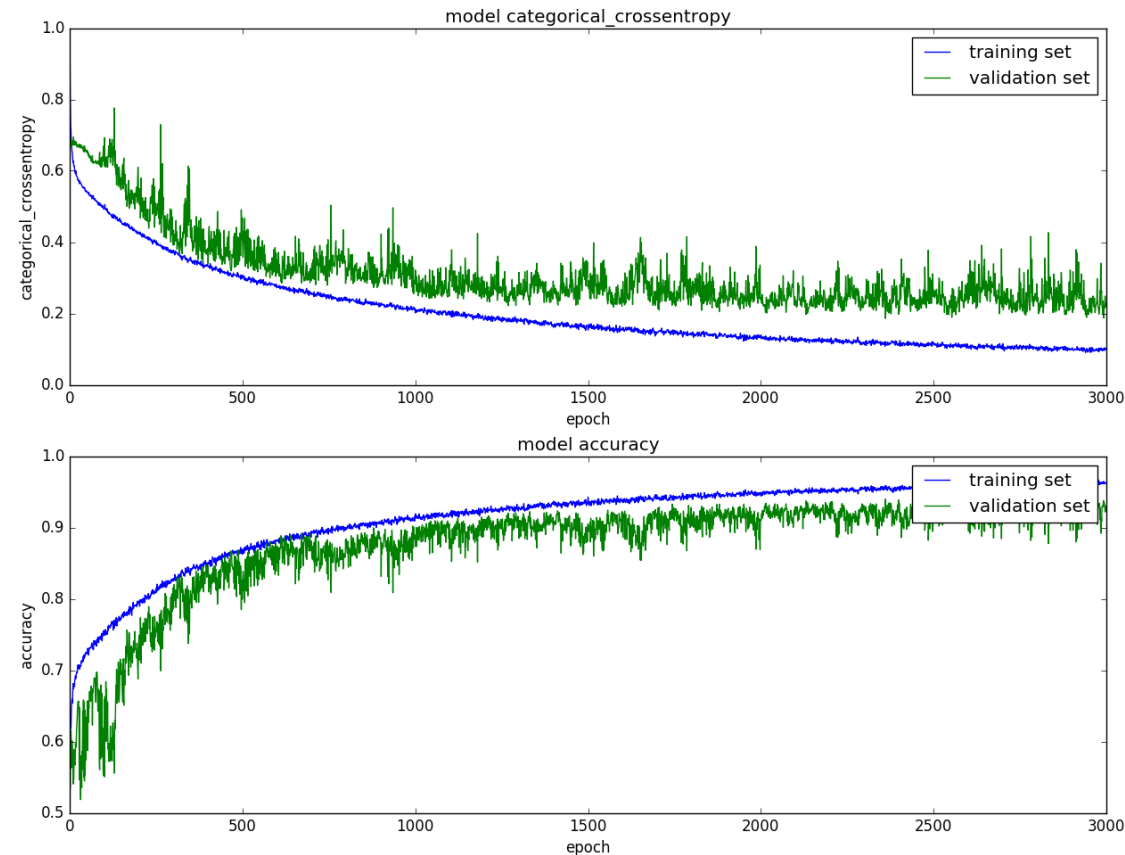
Model Results – Deep Model (CNN)

Activation	Epoch	Batch Normalization	Drop Out	Drop Out Position	Drop Out Rate
ELU	3K	Yes	Yes	ALL	0.25
RELU	10K	No	No	LAST	0.5



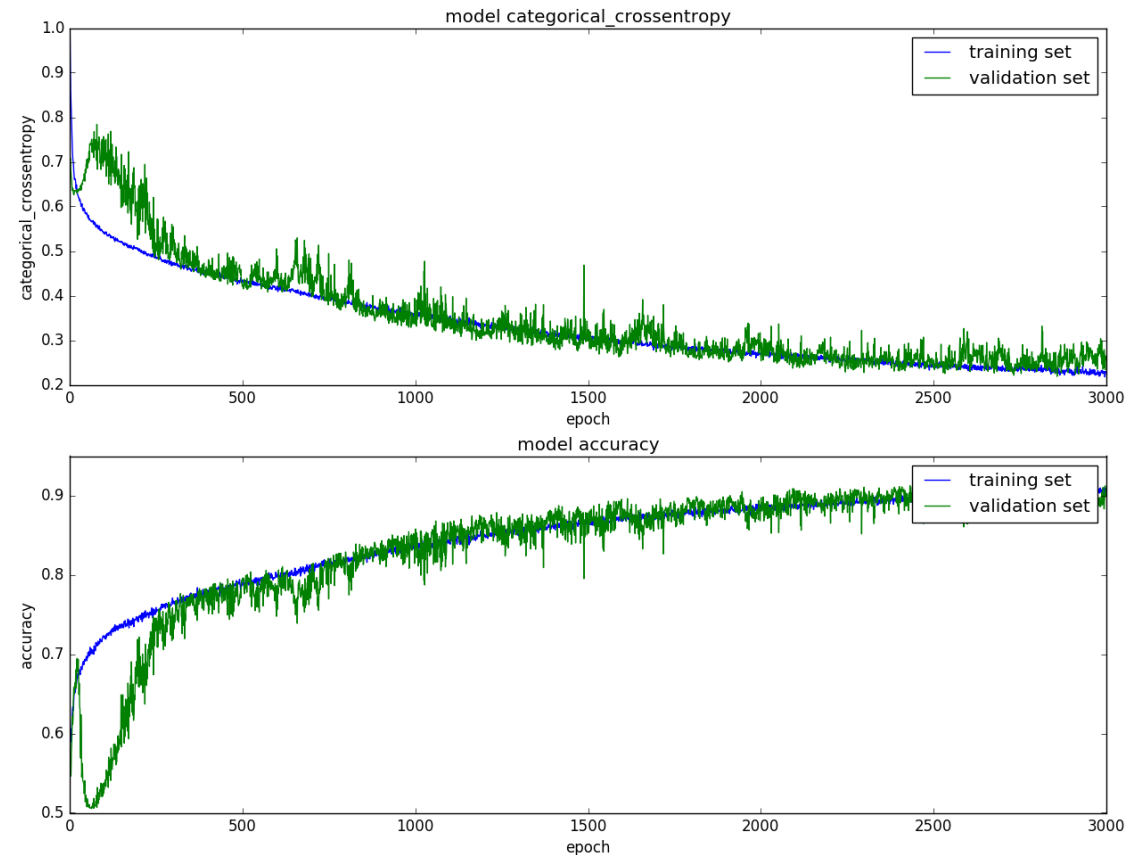
Model Results – Deep Model (CNN)

Activation	Epoch	Batch Normalization	Drop Out	Drop Out Position	Drop Out Rate
ELU	3K	Yes	Yes	ALL	0.25
RELU	10K	No	No	LAST	0.5



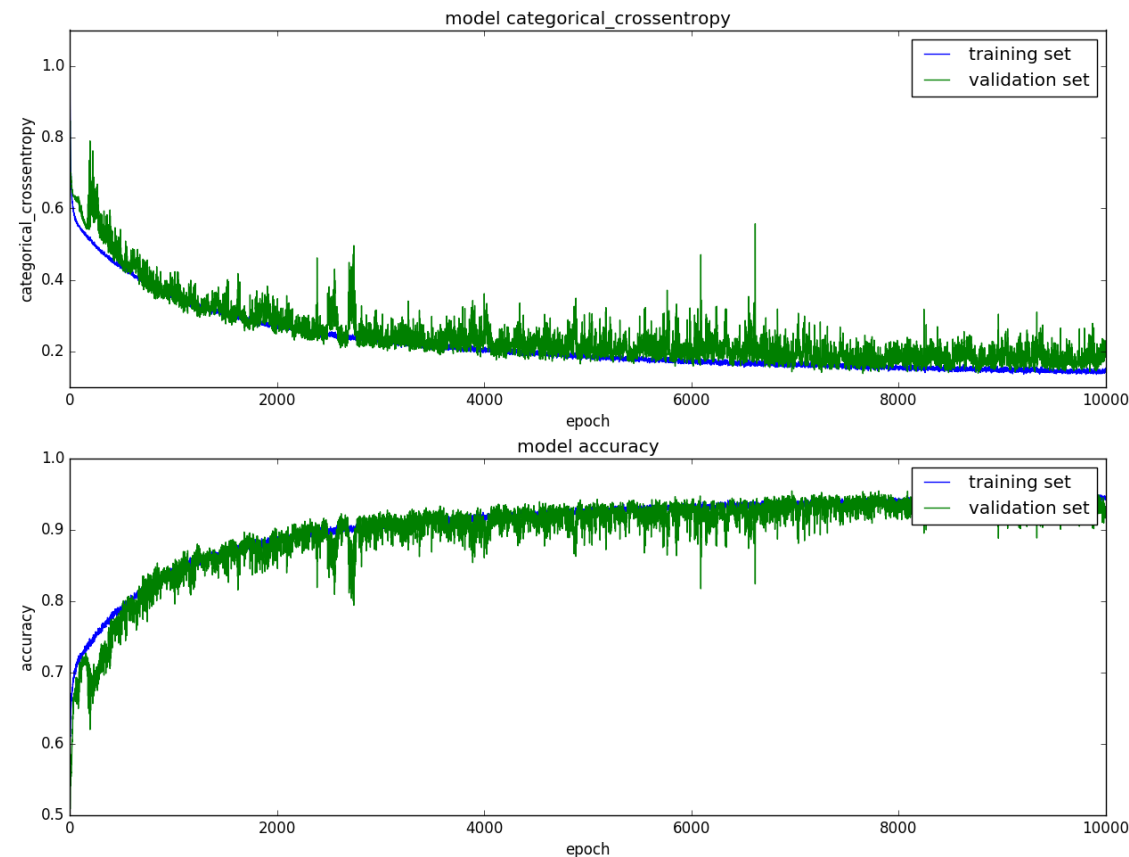
Model Results – Deep Model (CNN)

Activation	Epoch	Batch Normalization	Drop Out	Drop Out Position	Drop Out Rate
ELU	3K	Yes	Yes	ALL	0.25
RELU	10K	No	No	LAST	0.5



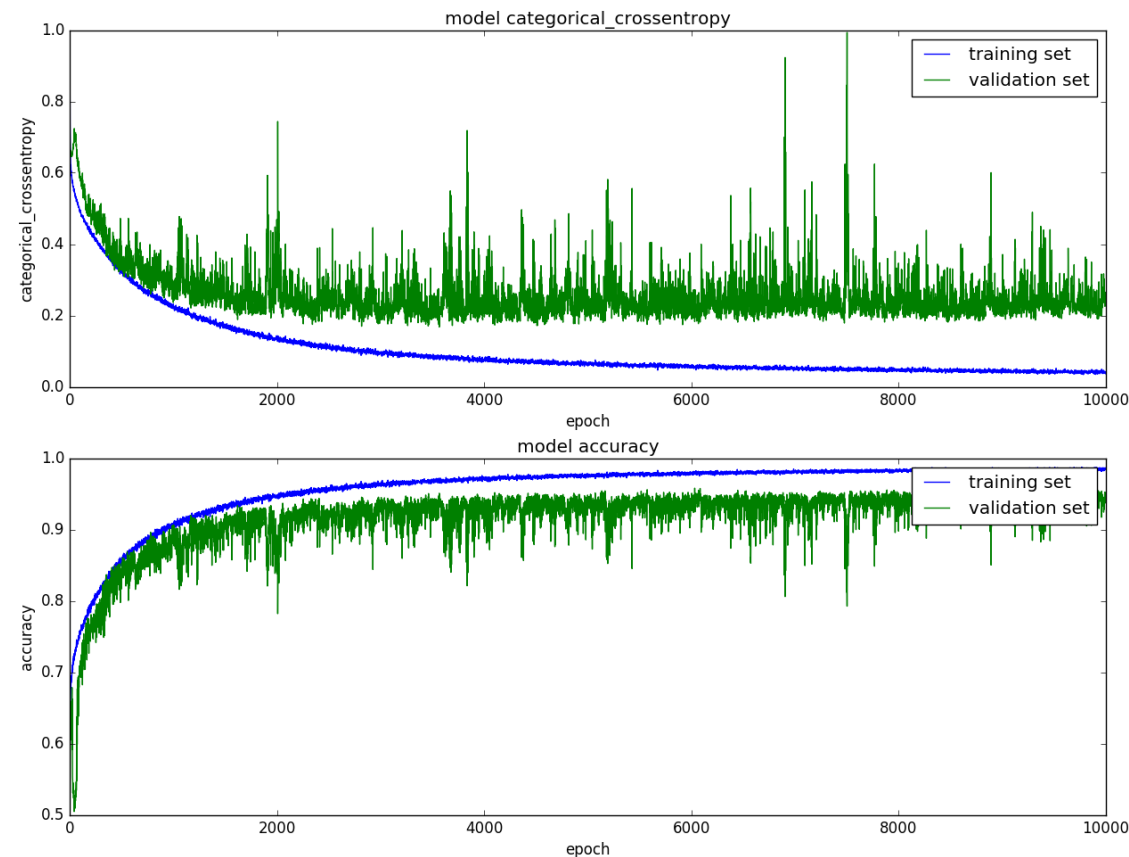
Model Results – Deep Model (CNN)

Activation	Epoch	Batch Normalization	Drop Out	Drop Out Position	Drop Out Rate
ELU	3K	Yes	Yes	ALL	0.25
RELU	10K	No	No	LAST	0.5



Model Results – Deep Model (Best)

Activation	Epoch	Batch Normalization	Drop Out	Drop Out Position	Drop Out Rate
ELU	3K	Yes	Yes	ALL	0.25
RELU	10K	No	No	LAST	0.5

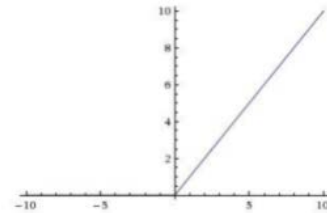
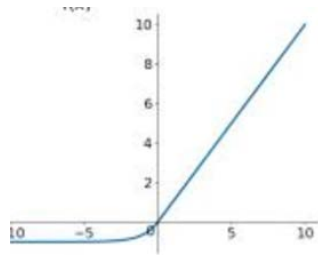


Train: 99.3%

Validation: 95.54%

Discussion

- Random forest can compete with deep models while shallow models can not
- ELU is more stable than ReLU in term of training



- Batch normalization helps training accuracy a lot
- Dropout to all hidden layer can better reduce overfitting
- CNN is better than FC
- Best accuracy: Train 99.3% Validation: 95.54%