

DESCRIPTION

The MP6515 is an H-bridge motor driver. It can operate from a supply voltage of up to 35V and can deliver motor current up to 2.8A. The MP6515 is typically used to drive a DC brush motor.

An internal current sensing circuit provides an output whose voltage is proportional to the load current. In addition, cycle-by-cycle current regulation / limiting is provided. These features do not require the use of a low-ohm shunt resistor.

Internal safety features include over-current protection, input over-voltage protection, under-voltage lockout (UVLO), and thermal shutdown.

The MP6515 is available in 16-pin 5.0mm×6.4mm TSSOP-EP and 3mmx4mm QFN package with exposed thermal pad.

FEATURES

- Wide 5.4V to 35V Input Voltage Range
- 2.8A Peak Output Current
- Internal Full H-Bridge Driver
- Cycle-by-cycle Current Regulation / Limit
- Low On Resistance (HS:200mΩ;LS:200mΩ)
- Simple, Versatile Logic Interfaces
- 3.3V and 5V Compatible Logic Supply
- Over-Current Protection
- Over-Voltage Protection
- Thermal Shutdown
- Under-Voltage Lockout
- Fault Indication Output
- Thermally Enhanced Surface-Mount Package

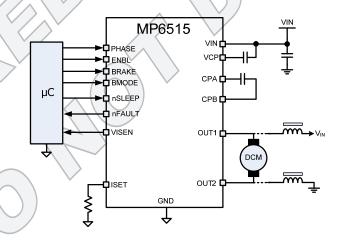
APPLICATIONS

- Solenoid Drivers
- DC Brush Motor Drive

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TYPICAL APPLICATION





ORDERING INFORMATION

Part Number*	Top Marking	
MP6515GF*	TSSOP-16 EP (5.0mm × 6.4mm)	See Below
MP6515GL**	QFN-20 (3mm x 4mm)	See Below

^{*} For Tape & Reel, add suffix -Z (e.g. MP6515GF-Z)

TOP MARKING (TSSOP-16EP)

M<u>PSYYWW</u> MP6515 LLLLLL

MPS: MPS prefix: YY: year code; WW: week code: MP6515: part number; LLLLLL: lot number;

TOP MARKING (QFN-20)

MPYW

6515

LLL

MP: MPS prefix: Y: year code; W: week code:

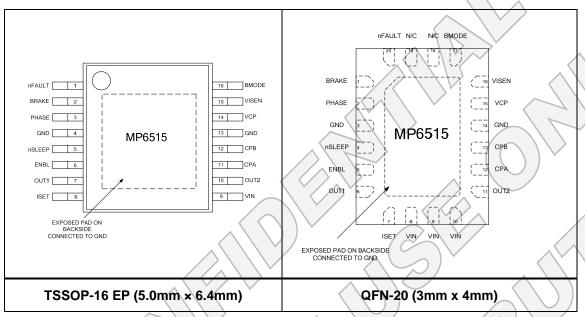
6515: first four digits of the part number;

LLL: lot number,

^{**} For Tape & Reel, add suffix –Z (e.g. MP6515GL–Z)



PACKAGE REFERENCE



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ABSOL	LITE	$NA \times V$	1841 184	D V 4	FINIC	(1)
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Supply Voltage V _{IN} 0.3	√ to 40V
OUTx Voltage V _{OUT1/2} 0.7\	√ to 40V
VCP, CPBV _{IN} to \	/ _{IN} +6.5V/
ESD Rating (HBD)	2kV
ISET0.3V	to 4.5V
All Other Pins to GND0.3V	to 6.5V
Continuous Power Dissipation ($T_A = +25$	°C) (2)
TSSOP-16 EP	2.77W
QFN-20 (3mm x4mm)	.2.60W
Storage Temperature55°C to	+150°C
Junction Temperature,	.+150°C
Lead Temperature (Solder)	.+260°C

Thermal Resistance (5) θ _{JA}	θ_{JC}
TSSOP-16 EP45	10 °C/W
QFN-20 (3mm x4mm) 48	10 °C/W

Notes:

- 1) Exceeding these ratings may damage the device.
- 2) The maximum allowable power dissipation is a function of the maximum junction temperature T_J (MAX), the junction-to-ambient thermal resistance θ_{JA}, and the ambient temperature T_A. The maximum allowable continuous power dissipation at any ambient temperature is calculated by P_D (MAX) = (T_J (MAX)-T_A)/θ_{JA}. Exceeding the maximum allowable power dissipation will cause excessive die temperature, and the regulator will go into thermal shutdown. Internal thermal shutdown circuitry protects the device from permanent damage.
- The device is not guaranteed to function outside of its operating conditions.
- Continuous current depends on PCB layout and ambient temperature.
- 5) Measured on JESD51-7, 4-layer PCB



ELECTRICAL CHARACTERISTICS

 $V_{IN}=24V$, $T_A=+25$ °C, unless otherwise noted.

Parameter	Symbol	Condition	Min	Тур	Max	Units
Power Supply					>	
Input Supply Voltage	V_{IN}		5.4	24	35	V
	I _Q	V _{IN} =24V; nSLEEP=1		1.5	2	mA
Quiescent Current		no load current		/ 1.0		
	SLEEP	V _{IN} =24V; nSLEEP=0			1	μA
Charge Pump Frequency	f _{CP}			680		kHz
Internal MOSFETs		V 04V 1			(
	R _{HS}	V _{IN} =24V, I _{OUT} =1A, T _J =25°C		0.25	0.3	Ω
Output On Resistance	' HS	T _J =25°C V _{IN} =24V, I _{OUT} =1A, T _J =85°C		0.3	•	Ω
Output Off Resistance	В	V _{IN} =24V, I _{OUT} =1A, T ₁ =25°C		0.25	0.3	Ω
	R _{LS}	V _{IN} =24V, I _{OUT} =1A, T ₁ =85°C		0.3		Ω
Body Diode Forward Voltage	VE	I _{OUT} =1.5A	//		1.1	V
Control Logic						
Input Logic 'Low' Threshold	VIL				0.8	V
Input Logic 'High' Threshold	ViH		2			V
Logic Input Current	$I_{IN(H)}$	V _{IH} =5V	-20	24	20	μΑ
	I _{IN(L)}	V _{IL} =0.8V	-20		20	μA
Internal Pull Down Resistance	R _{PD}			515		kΩ
nFault Output (Open-Drain Ou	,				0.5	.,
Output Low Voltage	V _{OL}	I ₀ =5mA			0.5	V
Output High Leakage Current	J _{ОН}	V ₀ =3.3V			1	μΑ
Protection Circuits	(V)			5	F 2	1/
UVLO Rising Threshold UVLO Hysteresis	V _{IN RISE}			310	5.3	V mV
	V _{HYS}		36	38	40	V
Input OVP Threshold	ΔV_{OVP}		36		40	-
Input OVP Hysteresis	7	Sinking	3.2	2000	5	mV A
Over-Current Trip Level	I _{OCP1}	Sourcing	3.2	4	5	A
Over-Current Deglitch Time ⁽⁶⁾	t _{OCPD}	333.3119	0.2	1	<u> </u>	μs
Over-Current Retry Time	t _{OCP}			0.9		ms
Thermal Shutdown	T_{TSD}	\cup		165		°C
Thermal Shutdown Hysteresis	ΔT_{TSD}			15		°C
	100			-	<u> </u>	



ELECTRICAL CHARACTERISTICS

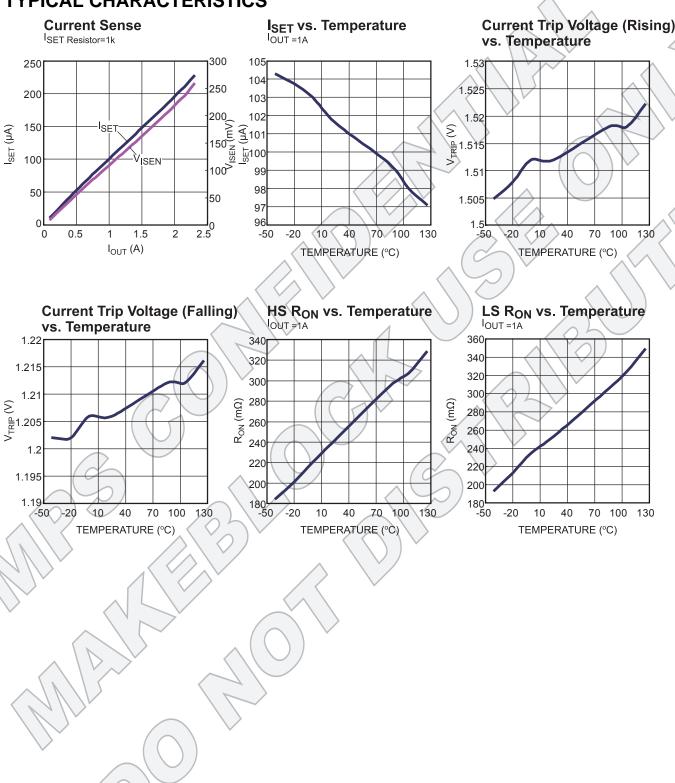
 $V_{IN}=24V$, $T_A=+25$ °C, unless otherwise noted.

Current Control						
Off Time	t _{ITRIP}	After ITRIP		16	>	μs
ISET current	I _{ISET}		90	100	110	μA/A
Current Trip Voltage(Rising)	V _{ITRIP-R}	At VISEN pin	1.44	1.5	1.56	(V)
Current Trip Voltage(Falling)	$V_{ITRIP-F}$	At VISEN pin	1.15	1.2	1.25/	V
VISEN output						
Output Voltage Accuracy	ΔV_{VISEN}	V _{ISET} >0.5V	-5		5	%

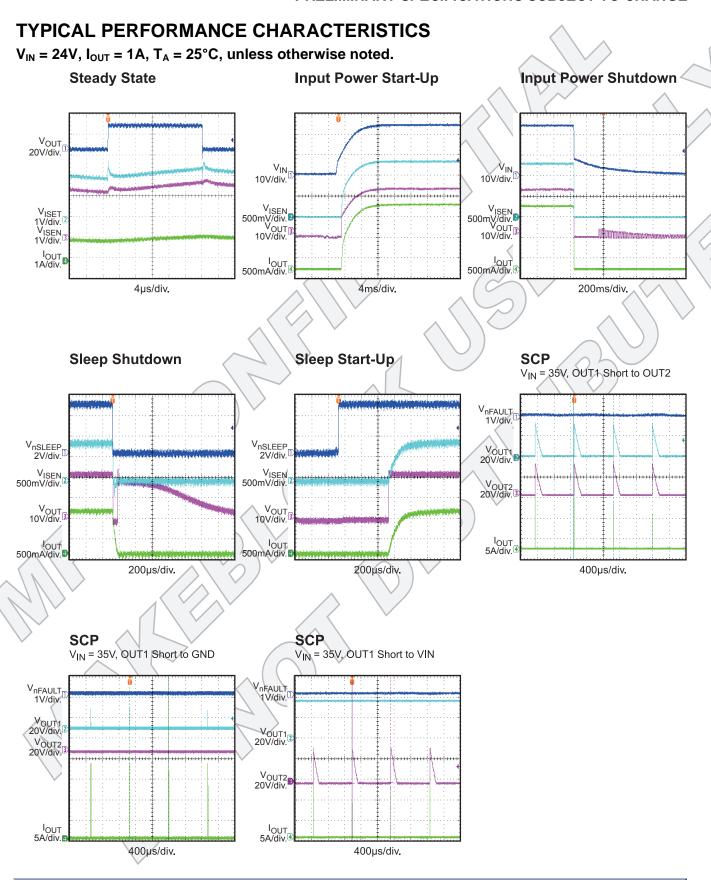
6) Guarantee by design



TYPICAL CHARACTERISTICS





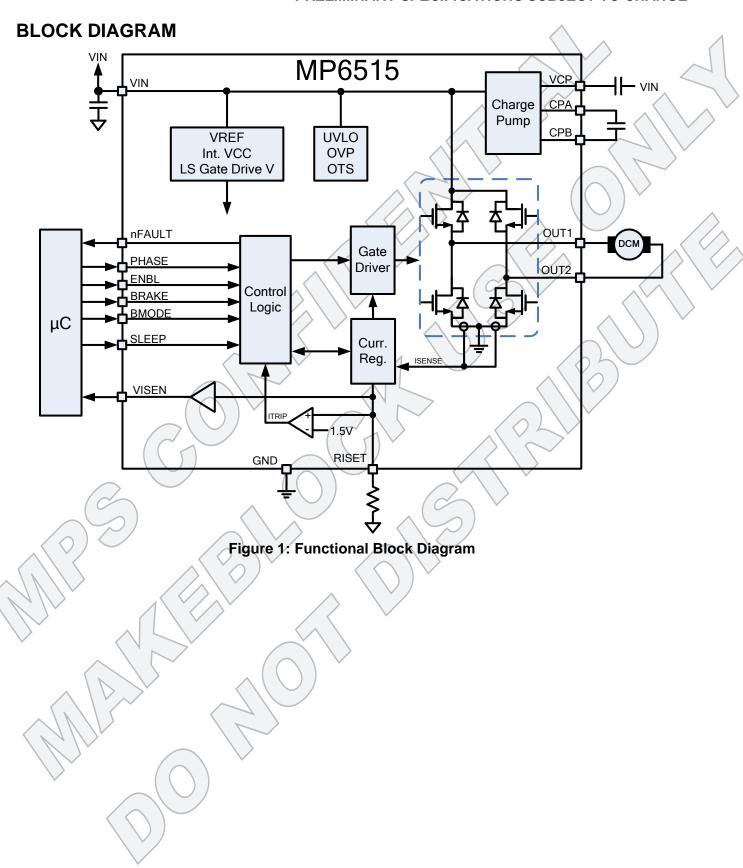




PIN FUNCTIONS

TSSOP16 Pin #	QFN20 Pin #	Name	Description
1	20	nFAULT	Fault indication. Open-drain output type, logic low when in fault condition (OCP, OTP, OVP).
2	1	BRAKE	Brake input. Internal pull down.
3	2	PHASE	H-bridge phase input (motor direction). Internal pulldown.
4, 13	3, 14	GND	System ground connection.
5	4	nSLEEP	Sleep mode input. Logic low to enter low-power sleep mode. Internal pull down.
6	5	ENBL	H-bridge enable input. High to enable H-bridge. Internal pull down.
7	6	OUT1	Output terminal 1.
8	7	ISET	Current programming resistor. Connect a resistor to ground to set current limit and VISEN output voltage.
9	8, 9, 10	VIN	Input supply voltage. Decouple to GND with minimum 100nF ceramic capacitor to GND.
10	11	OUT2	Output terminal 2.
11	12	CPA	Charge pump flying capacitor. Connect a 100nF ceramic capacitor
12	13	CPB	between these pins.
14	15	VCP	Charge pump output. Connect a 100nF capacitor to VIN.
15	16	VISEN	Current sense output voltage.
16	17	BMODE	Brake mode. Internal pulldown.
-	18, 19	NC \	No connection.
EP	EP	GND	The exposed pad MUST be connected to ground.







OPERATION

The MP6515 is an H-bridge motor driver which integrates four N-Channel power MOSFETs with 2.8A peak current capability. It operates over a wide input voltage range of 5.4V to 35V. It is designed to drive bipolar stepper motors, DC brush motors, solenoids, or other loads.

Current Sensing

The current flowing in the two low-side MOSFETs is sensed with an internal current sensing circuit. A voltage that is proportional to the output current is sourced on the VISEN pin.

The VISEN output voltage scaling is set by a resistor connected between the ISET pin and ground. For 1A of output current, $100\mu\text{A}$ of current is sourced into the resistor connected to VISEN. For example, if a $10k\Omega$ resistor is connected between ISET and ground, the output voltage on the VISEN pin will be 1V/A of output current.

Current is sensed any time one of the low-side MOSFETs are turned on, including during slow decay (brake) mode.

The load current applied to the VISEN pin should be kept below 2mA, with no more than 500pF of capacitance.

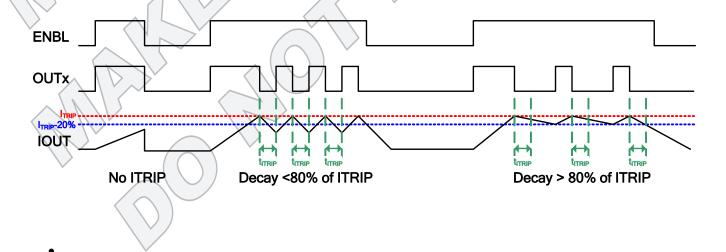
Current Limit / Regulation

The current in the outputs is limited using constant off-time PWM (pulse width modulation) control circuitry. This operates as described below:

- Initially, a diagonal pair of MOSFETs turns on and drives current through the load.
- The current increases in the load, which is sensed by the internal current sense circuit.
- If the load current reaches the current trip threshold, the H-bridge switches to slow decay mode, with the two low-side MOSFETs turned on.
- After a fixed off-time (t_{ITRIP}), if the load current has fallen at least 20% below the current limit threshold, the FETs are re-enabled and the cycle repeats.
- If the current is still higher than this level, the off time is extended until the current falls to 20% below the current limit threshold.

The current limit threshold is reached when the VISEN pin reaches 1.5V. As an example, with a $10k\Omega$ resistor from ISET to ground, the VISEN voltage is 1V/A of output current. So, when the current reaches 1.5A, the VISET pin voltage reaches 1.5V, and a current trip occurs.

During current regulation, the nFAULT pin is not activated.





Blanking Time

There is often a current spike during the turn-on, due to the body diode's reverse-recovery current or the shunt capacitance of the load. This current spike requires filtering to prevent it from erroneously shutting down the high-side MOSFET. An internal fixed blanking time t_{OCPD} blanks the output of the current sense comparator when the outputs are switched. This blanking time also sets the minimum on time for high-side MOSFET.

Input Logic

For the MP6515, control of the outputs is accomplished through the PHASE, ENBL, BRAKE, and BMODE pins as shown in the table below:

ENBL	PHASE	BRAKE	BMODE	OUT1	OUT2	Function
1	0	X	Χ	L	Н	Reverse
1	1	Х	Х	Н	L	Forward
0	Х	1	0	L	-	Brake (low)
0	Х	1	1	Н	\H ,	Brake (high)
0	0	0	Х	H*	7.	Sync fast decay
0	1	0	Х	/L*_	H*/	Sync fast decay

^{*} As the current through the H-bridge approaches zero, the outputs are tri-stated

nSLEEP Operation

Driving nSLEEP low will put the device into a low power sleep state. In this state, all internal circuits including the gate drive charge pump are disabled, and the H-bridge outputs are turned off. All inputs are ignored when nSLEEP is active low. When waking up from sleep mode, some time (approximately 1ms) needs to pass before the outputs will operate.

Fault

MP6515 provides an nFAULT pin which is driven active low if any of the protection circuits are activated. These fault conditions include over-current, over-temperature, and over-voltage. nFAULT is not driven low when a current limit trip occurs. nFAULT is an opendrain output and requires an external pull-up resistor. When the fault condition is removed, the nFAULT pin is pulled inactive high by the pull-up resistor.

Over-Current Protection

The over-current protection circuit limits the current through each FET by reducing the gate drive to the FET. If the FET remains in the current limit condition for longer than the overcurrent deglitch time, all MOSFETs in the Hbridge will be disabled and the nFAULT pin will be driven low. The driver will remain disabled for t_{OCP}, at which point it will automatically be reenabled. Over-Current conditions are sensed on both high and low side devices; i.e., a short to ground, supply, or across the motor winding will all result in an over-current shutdown. Note that over-current protection does not use the current sense circuitry used for PWM current control, and is independent of the ISET resistor value.

Over-Voltage Protection

If the input voltage applied to the VIN pin is higher than the OVP threshold, the H-bridge output will be disabled and the nFAULT pin will be driven low. This protection is released when VIN drops to a safe level.

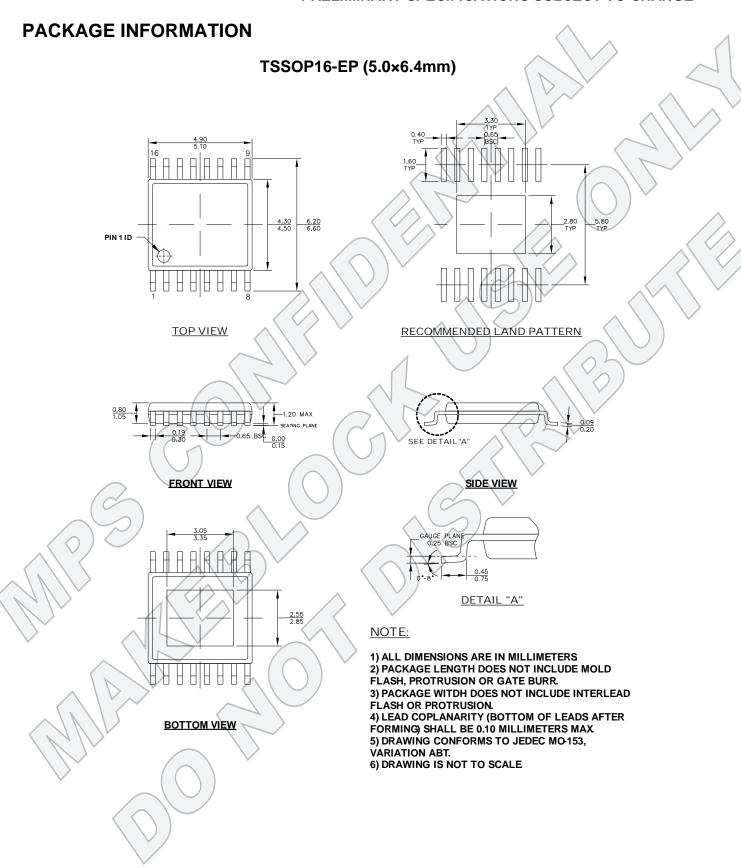
Input UVLO Protection

If at any time the voltage on the VIN pin falls below the under-voltage lockout threshold, all circuitry in the device will be disabled and internal logic will be reset. Operation will resume when VIN rises above the UVLO threshold.

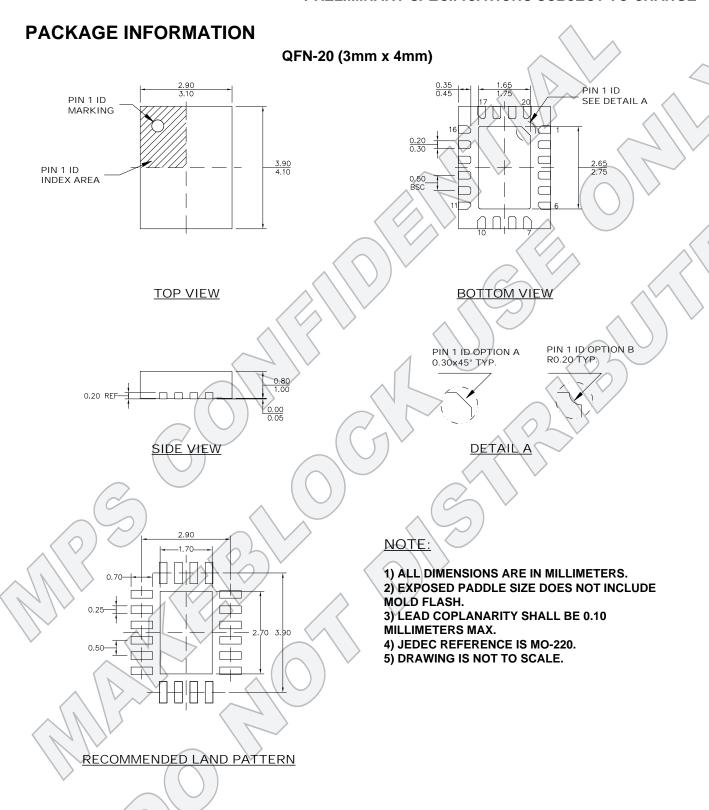
Thermal Shutdown

If the die temperature exceeds safe limits, all MOSFETs in the H-bridge will be disabled and the nFAULT pin will be driven low. Once the die temperature has fallen to a safe level operation will automatically resume.









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