

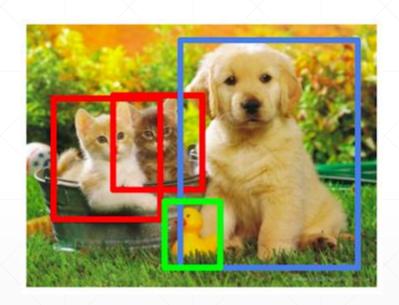
目标检测

主讲: 龙良曲

Computer Vision



Classification



Object Detection

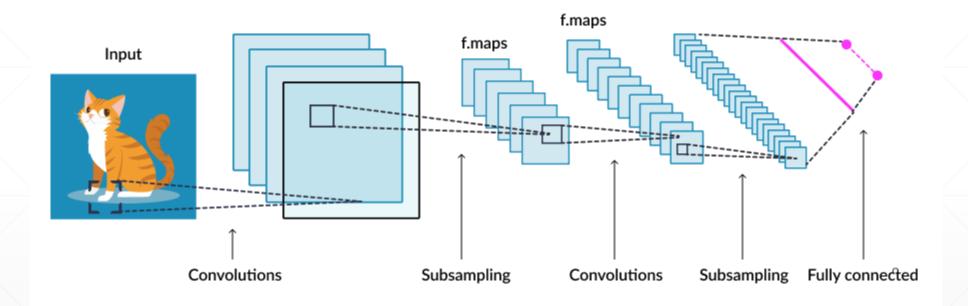


Semantic Segmentation

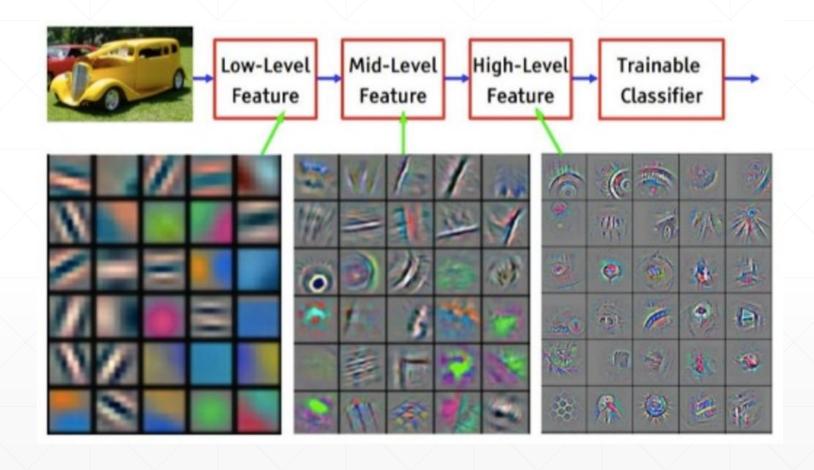
Enjoy!



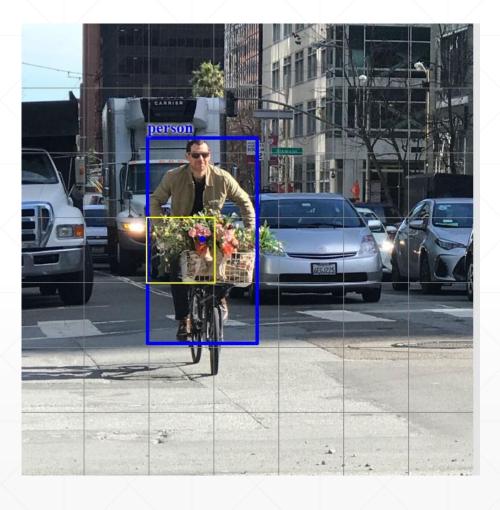
Review: Classification

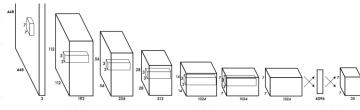


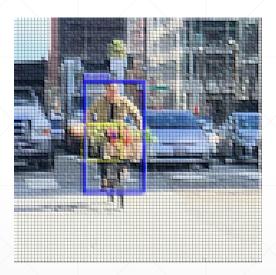
CNN keep spatial info



Confidence 1 or 0?





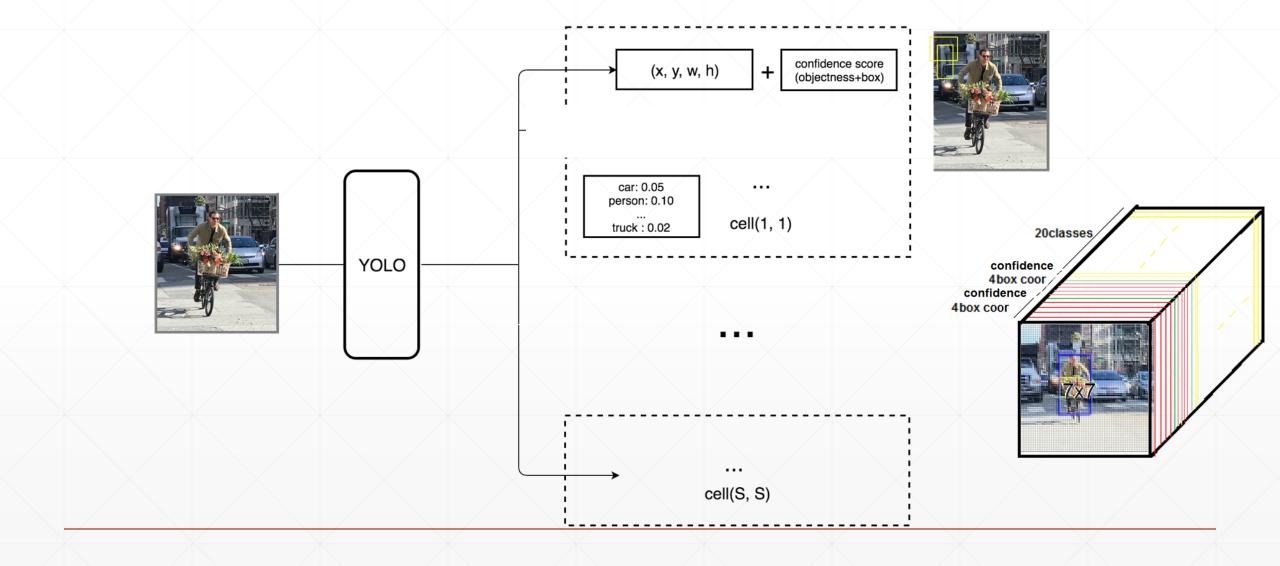


Problems

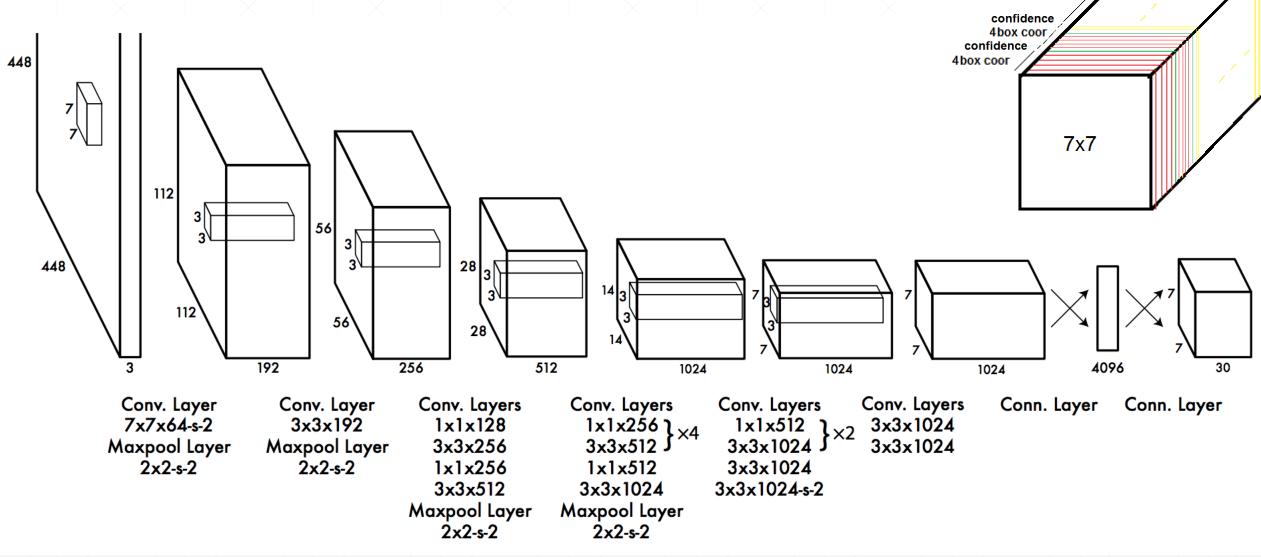
(x,y,w,h) prediction

Class information

YOLO: You only look once



YOLO model



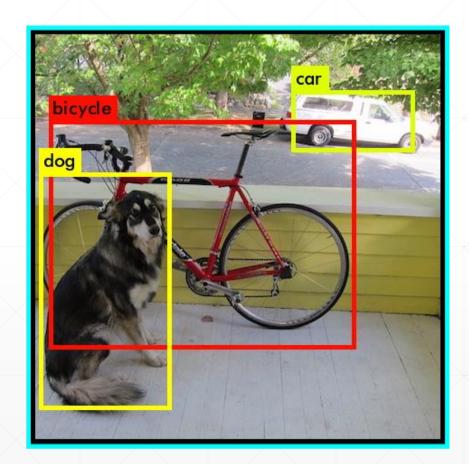
20classes

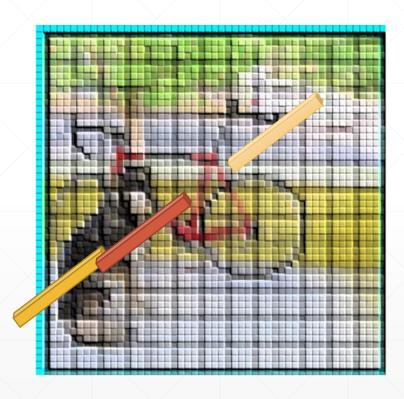
Train YOLO

Compose GT boxes

Forward

Loss

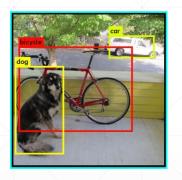


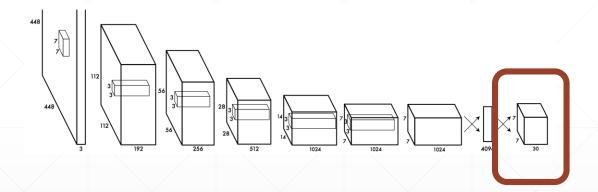


Train YOLO

Compose GT boxes

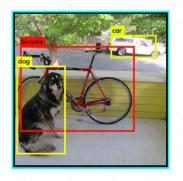
Forward

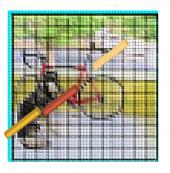


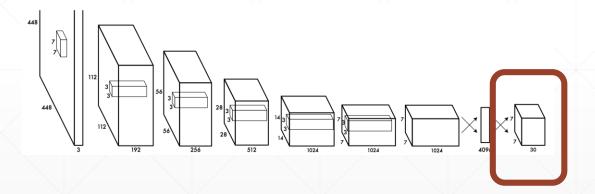


Loss

YOLO loss







Benchmark

| Model | Train | Test | mAP | FLOPS | FPS | Cfg | Weights |
|----------------|---------------|----------|------|----------|-----|-----|---------|
| Old YOLO | VOC 2007+2012 | 2007 | 63.4 | 40.19 Bn | 45 | | link |
| SSD300 | VOC 2007+2012 | 2007 | 74.3 | | 46 | | link |
| SSD500 | VOC 2007+2012 | 2007 | 76.8 | | 19 | | link |
| YOLOv2 | VOC 2007+2012 | 2007 | 76.8 | 34.90 Bn | 67 | cfg | weights |
| YOLOv2 544x544 | VOC 2007+2012 | 2007 | 78.6 | 59.68 Bn | 40 | cfg | weights |
| Tiny YOLO | VOC 2007+2012 | 2007 | 57.1 | 6.97 Bn | 207 | cfg | weights |
| SSD300 | COCO trainval | test-dev | 41.2 | - | 46 | | link |
| SSD500 | COCO trainval | test-dev | 46.5 | | 19 | | link |
| YOLOv2 608x608 | COCO trainval | test-dev | 48.1 | 62.94 Bn | 40 | cfg | weights |
| Tiny YOLO | COCO trainval | | | 7.07 Bn | 200 | cfg | weights |

Improvements-1

Model updated: Dartnet-19

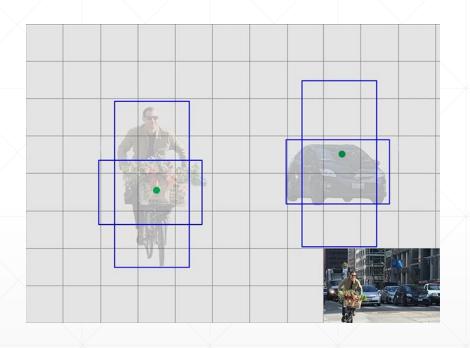
BN

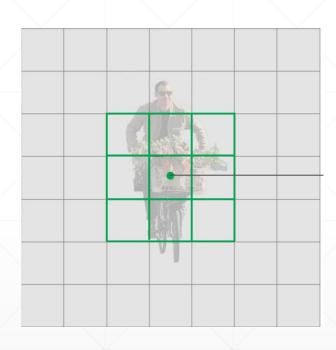
• FC

| | Тор 1 | Тор 5 | FLOPs | GPU Speed |
|---------------------|-------|-------|----------|-----------|
| VGG-16 | 70.5 | 90.0 | 30.95 Bn | 100 FPS |
| Extraction (YOLOv1) | 72.5 | 90.8 | 8.52 Bn | 180 FPS |
| Resnet50 | 75.3 | 92.2 | 7.66 Bn | 90 FPS |
| Darknet19 | 74.0 | 91.8 | 5.58 Bn | 200 FPS |

Improvement-2

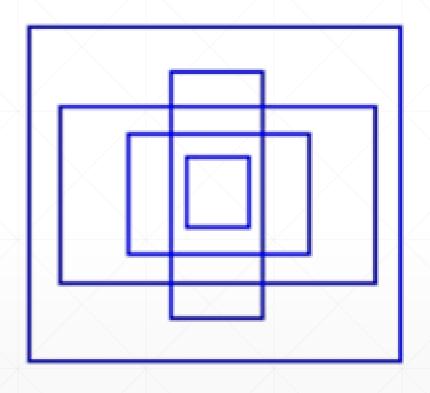
Pre-defined Anchors



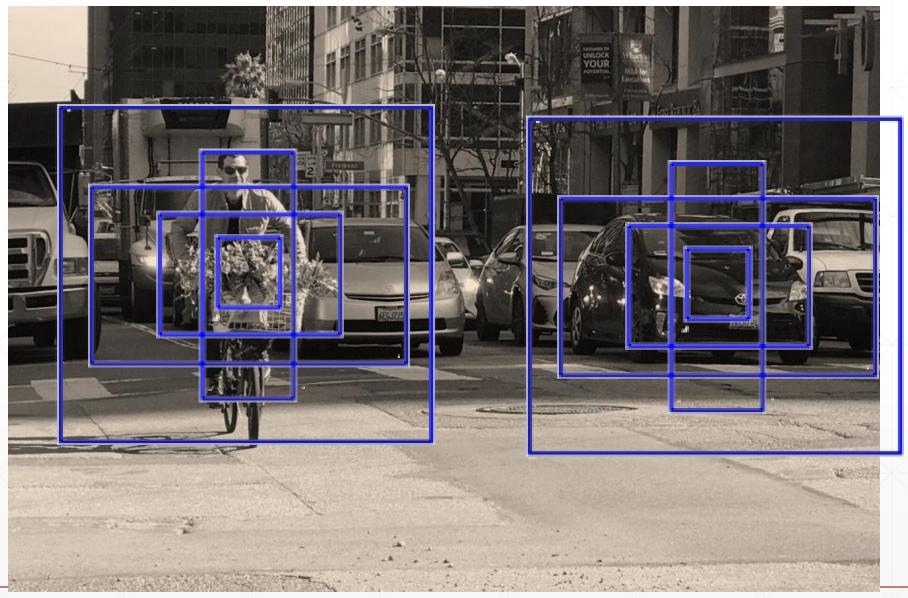


Predefined Anchors

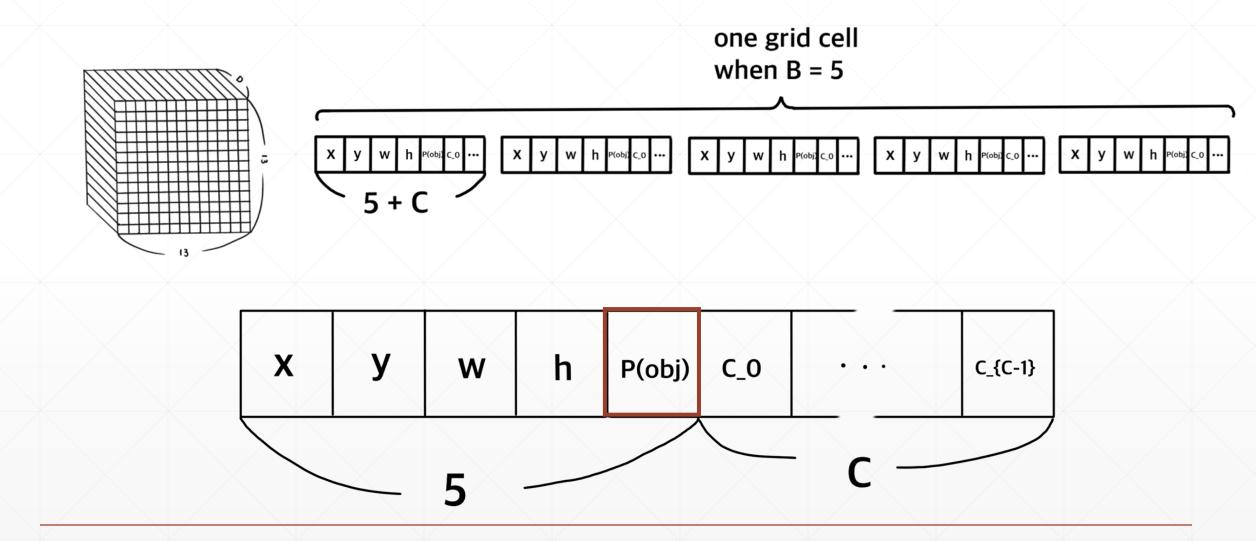
More or less?



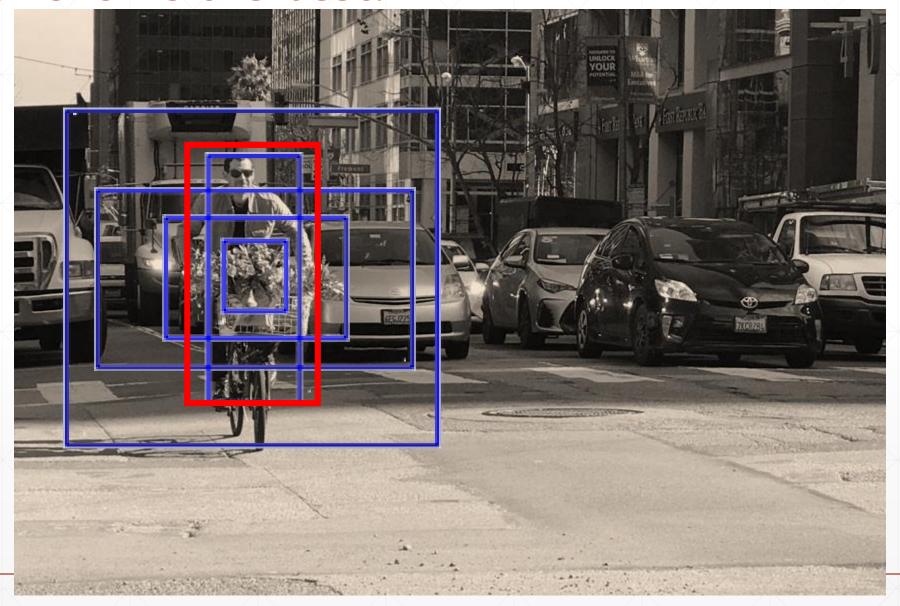
Pre-defined Anchors



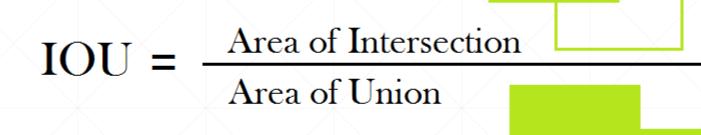
Output Vector

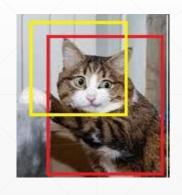


Which anchor is the best?





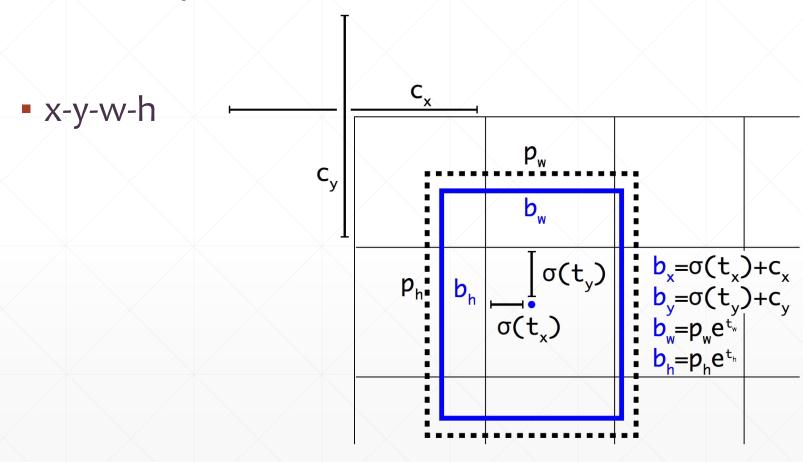






Improvements-3

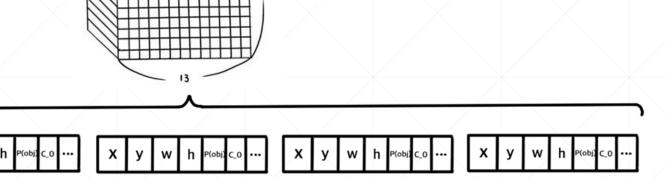
Position prediction-3



YOLOv2

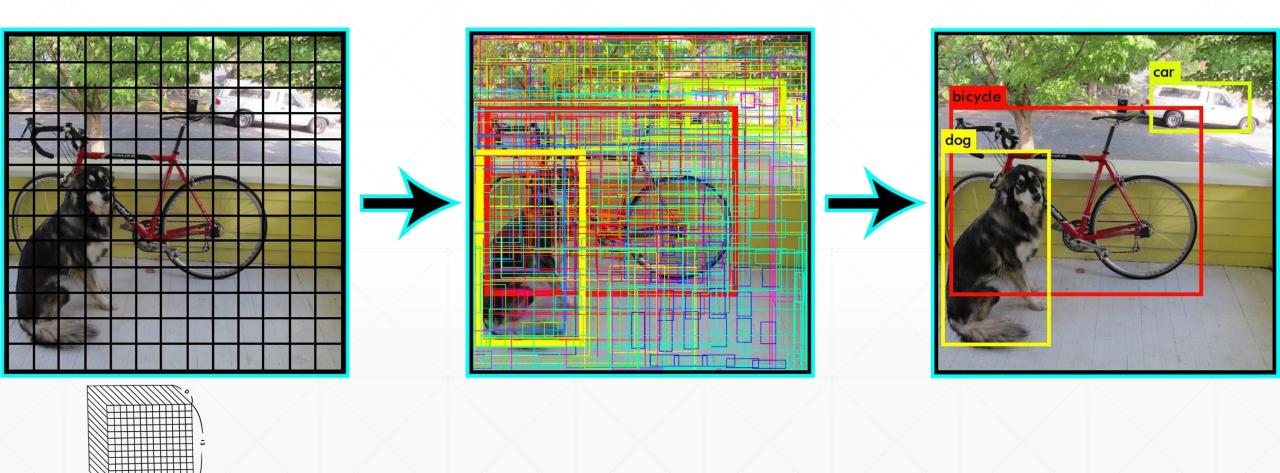
Compose Target

Forward

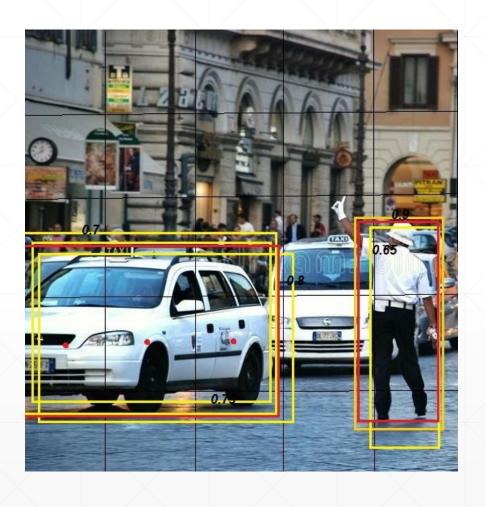


- Loss
 - Coordinate loss: x-y-w-h 4
 - Class loss: 20
 - Confidence loss:1

Inference



Non-Max-Suppresion



高能预警!

- 代码请加QQ群下载: 441082251

- 多动手练习!

Acknowledgement

- https://www.jeremyjordan.me/semantic-segmentation/
- https://divamgupta.com/imagesegmentation/2019/06/06/deep-learning-semanticsegmentation-keras.html
- https://medium.com/@y1017c121y/how-does-yolov2-workdaaaa967c5f7
- https://medium.com/@amrokamal_47691/yolo-yolov2-and-yolov3-all-you-want-to-know-7e3e92dc4899

下一课时

Thank You.