

Comp6211e: Optimization for Machine Learning

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Lecture 18: Randomized Coordinate Descent and Acceleration

Regularized Loss Minimization

Last lecture, we consider the composite optimization problem, but with an added finite sum structure as follows,

$$\phi(\mathbf{w}) = \frac{1}{n} \sum_{i=1}^n f_i(\mathbf{X}_i^\top \mathbf{w}) + \lambda g(\mathbf{w}), \quad (1)$$

where $\mathbf{w} \in \mathbb{R}^d$ is the model parameter:

We assume that $g(\mathbf{w})$ is strongly convex.

Decomposable Linear Model

In this lecture, we consider optimization problem with the model parameter $w \in \mathbb{R}^d$. Here w can be decomposed into p components $w = [w_1, \dots, w_p]$, where each w_j is a d_j dimensional vector, with $\sum_{j=1}^p d_j = d$.

We consider the following form of optimization problem:

$$\phi(w) = f(w) + g(w), \quad (2)$$

where

$$f(w) = \psi \left(\sum_{j=1}^p A_j w_j \right), \quad g(w) = \sum_{j=1}^p g(w_j).$$

We assume that $f(\cdot)$ is L_i -smooth with respect to w_j , and $g(\cdot)$ is convex but may not be smooth.

Example

Consider the dual formulation of the regularized loss minimization problem:

$$\phi_D(\alpha) = \frac{1}{n} \sum_{i=1}^n -f_i^*(-\alpha_i) - \lambda g^* \left(\frac{1}{\lambda n} \sum_{i=1}^n X_i \alpha_i \right),$$

where each $\alpha_i \in \mathbb{R}^k$. Here $-\phi_D(\alpha)$ can be written as

$$\tilde{\psi} \left(\sum_{j=1}^p A_j \tilde{w}_j \right) + \sum_{j=1}^p \tilde{g}_j(\tilde{w}_j).$$

Here $\tilde{w}_j = \alpha_j$, $p = n$, $d = nk$, $\tilde{\psi}(u) = \lambda g^*(u)$, $A_j = (\lambda n)^{-1} X_j$, $\tilde{g}_j(\tilde{w}_j) = n^{-1} f_j^*(-\alpha_j)$ for $j = 1, \dots, p$.

Randomized Coordinate Descent

In randomized coordinate descent algorithm for solving (2), we randomly select a variable i from 1 to p , and minimize the objective with respect to w_i using proximal gradient.

That is, we select i , and optimize with respect $w_i + \Delta w_i$:

$$f \left(\sum_{j=1}^p A_j w_j + A_i \Delta w_i \right) + \sum_{j=1}^p g_j \left(w_j + \Delta w_i \delta_i^j \right).$$

Proximal Coordinate Optimization

Given $\eta_i \leq 1/L_i$, we use an upper bound of $f(\cdot)$ as follows:

$$\psi \left(\sum_{j=1}^p A_j w_j \right) + \nabla \psi \left(\sum_{j=1}^p A_j w_j \right)^\top (A_i \Delta w_i) + \frac{1}{2\eta_i} \|\Delta w_i\|_2^2 + g_i(w_i + \Delta w_i).$$

Let

$$u = \sum_{j=1}^p A_j w_j,$$

Derivation of Primal CD Method

We can optimize

$$\begin{aligned}\Delta w_i &= \arg \min_{\Delta w} \left[(A_i^\top \nabla f(u))^\top \Delta w + \frac{1}{2\eta} \|A_i\|_2^2 \|\Delta w\|_2^2 + g_i(w_i + \Delta w) \right] \\ &= \arg \min_{\Delta w} \left[\frac{1}{2\eta_i} \|\Delta w + \eta_i A_i^\top \nabla f(u)\|_2^2 + g_i(w_i + \Delta w) \right] \\ &= \text{prox}_{\eta_i g_i}(w_i - \eta_i A_i^\top \nabla f(u)) - w_i,\end{aligned}$$

and

$$\text{prox}_{\eta_i g_i}(w) = \arg \min_{z \in \mathbb{R}^{d_i}} \left[\frac{1}{2} \|z - w\|_2^2 + \eta_i g_i(z) \right].$$

Primal Coordinate Descent

Algorithm 1: Randomized Proximal Coordinate Descent

Input: $\phi(\cdot)$, $\eta_i \leq 1/L_i (i = 1, \dots, p)$, $w^{(0)}$

Output: $w^{(T)}$

- 1 Let $u^{(0)} = \sum_{j=1}^p A_j w_j^{(0)}$
- 2 **for** $t = 1, 2, \dots, T$ **do**
- 3 Randomly pick $i \sim [1, \dots, p]$
- 4 Let $w_i^{(t)} = \text{prox}_{\eta_i g_i}(w_i^{(t)} - \eta_i A_i^\top \nabla f(u^{(t-1)}))$
- 5 Let $w_j^{(t)} = w_j^{(t-1)}$ for $j \neq i$
- 6 Let $u^{(t)} = u^{(t-1)} + A_i(w_i^{(t)} - w_i^{(t-1)})$

Return: $w^{(T)}$

Theorem

In Algorithm 1, assume that $\eta \leq 1/L$, then $\forall w = [w_1, \dots, w_p] \in \mathbb{R}^d$:

$$\begin{aligned} & \frac{p-1}{T} \mathbf{E} \phi(w^{(T)}) + \frac{1}{T} \sum_{t=1}^T \mathbf{E} \phi(w^{(t)}) \\ & \leq \frac{p-1}{T} \phi(w^{(0)}) + \phi(w) + \frac{1}{T} \sum_{i=1}^p \frac{1}{2\eta_i} \|w_i^{(0)} - w_i\|_2^2. \end{aligned}$$

Proof

Let $\sum_j A_j w_j^{(t)} = \sum_j A_j w_j^{(t-1)} + A_i(w_i^{(t)} - w_i^{(t-1)})$. We have for all $w \in \mathbb{R}^d$:

$$\begin{aligned}\phi(w^{(t)}) &= \left[\psi \left(u^{(t-1)} + A_i(w_i^{(t)} - w_i^{(t-1)}) \right) + g(w^{(t)}) \right] \\ &\leq \psi \left(u^{(t-1)} \right) + \left(A_i^\top \nabla \psi \left(u^{(t-1)} \right) \right)^\top (w_i^{(t)} - w_i^{(t-1)}) \\ &\quad + \frac{1}{2\eta_i} \|w_i^{(t)} - w_i^{(t-1)}\|_2^2 + g(w^{(t)}) \\ &\leq \psi \left(u^{(t-1)} \right) + \left(A_i^\top \nabla \psi \left(u^{(t-1)} \right) \right)^\top (w_i - w_i^{(t-1)}) \\ &\quad + \frac{1}{2\eta_i} \|w_i - w_i^{(t-1)}\|_2^2 + g(w_i) \\ &\quad + \sum_{j \neq i} g(w_j^{(t-1)}) - \frac{1}{2\eta_i} \|w_i - w_i^{(t)}\|_2^2.\end{aligned}\tag{3}$$

Take expectation with respect to i , we obtain

$$\begin{aligned}
 \mathbf{E}_i \phi(\mathbf{w}^{(t)}) &\leq \psi\left(\mathbf{u}^{(t-1)}\right) + \frac{1}{p} \nabla \psi\left(\mathbf{u}^{(t-1)}\right)^{\top} \left(\sum_{i=1}^p A_i \mathbf{w}_i - \mathbf{u}^{(t-1)} \right) \\
 &\quad + \frac{1}{p} g(\mathbf{w}) + \frac{p-1}{p} g(\mathbf{w}^{(t-1)}) \\
 &\quad + \frac{1}{p} \sum_{i=1}^p \frac{1}{2\eta_i} \|\mathbf{w}_i - \mathbf{w}_i^{(t-1)}\|_2^2 - \frac{1}{p} \sum_{i=1}^p \frac{1}{2\eta_i} \|\mathbf{w}_i - \mathbf{w}_i^{(t)}\|_2^2 \\
 &\leq \frac{p-1}{p} \phi(\mathbf{w}^{(t-1)}) + \frac{1}{p} \phi(\mathbf{w}) + \frac{1}{p} \sum_{i=1}^p \frac{1}{2\eta_i} \|\mathbf{w}_i - \mathbf{w}_i^{(t-1)}\|_2^2 \\
 &\quad - \frac{1}{p} \sum_{i=1}^p \frac{1}{2\eta_i} \|\mathbf{w}_i - \mathbf{w}_i^{(t)}\|_2^2.
 \end{aligned}$$

It is possible to derive accelerated coordinate descent methods.

We present an accelerated method for SDCA in Algorithm 2, which applies to the dual formulation for regularized loss minimization problem:

$$\frac{1}{n} \sum_{i=1}^n -f^*(-\alpha_i) - g^* \left(\frac{1}{n} \sum_{i=1}^n X_i \alpha_i \right)$$

strongly convex problems.

Algorithm 2: Stochastic Primal-Dual Coordinate Method (SPDC)

Input: $\phi(\cdot)$, L , λ , $\alpha^{(0)}$, and R such that $\|X_i\|_2 \leq R$

Output: $\alpha^{(T)}$, $w^{(T)}$

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1 Let  $\tau = 1/(2R\sqrt{n\lambda L})$ 
2 Let  $\sigma = \sqrt{n\lambda L}/(2R)$ 
3 Let  $\theta = 1 - 1/(n + R\sqrt{nL/\lambda})$ 
4 Let  $u^{(0)} = n^{-1} \sum_{i=1}^n X_i \alpha_i$ 
5 Let  $w^{(0)} = \nabla g^*(u^{(0)})$ 
6 let  $\bar{w}^{(0)} = w^{(0)}$ 
7 for  $t = 1, 2, \dots, T$  do
8   Randomly pick  $i$ 
9   Let  $\Delta\alpha_i \in \arg \max_{\Delta\alpha_i} \left[ -f_i^*(-(\alpha_i^{(t-1)} + \Delta\alpha_i)) - \bar{w}^{(t-1)\top} X_i \Delta\alpha_i - \frac{1}{2\sigma} \|\Delta\alpha_i\|_2^2 \right]$ 
10  Let  $\alpha_i^{(t)} = \alpha_i^{(t-1)} + \Delta\alpha_i$  and  $\alpha_j^{(t)} = \alpha_j^{(t-1)}$  when  $j \neq i$ 
11  Let  $w^{(t)} = \text{prox}_{\tau g}(w^{(t-1)} + \tau(u^{(t-1)} + X_i \Delta\alpha_i))$ 
12  Let  $u^{(t)} = u^{(t-1)} + n^{-1} X_i \Delta\alpha_i$ 
13  Let  $\bar{w}^{(t)} = w^{(t)} + \theta(w^{(t)} - w^{(t-1)})$ 
  
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Return: $\alpha^{(T)}$, $w^{(T)}$

Theorem (Convergence of SPDC)

Assume that $f_i^*(\cdot)$ is $1/L$ -strongly convex, and $g(\cdot)$ is λ -strongly convex. Let $R = \max_i \|X_i\|_2$. We have

$$\begin{aligned} & \left(\frac{1}{2\tau} + \lambda \right) \mathbf{E} \| \mathbf{w}^{(t)} - \mathbf{w}_* \|_2^2 + \left(\frac{1}{4\sigma} + \frac{1}{L} \right) \mathbf{E} \| \alpha^{(t)} - \alpha_* \|_2^2 \\ & \leq \theta^t \left(\left(\frac{1}{2\tau} + \lambda \right) \mathbf{E} \| \mathbf{w}^{(0)} - \mathbf{w}_* \|_2^2 + \left(\frac{1}{4\sigma} + \frac{1}{L} \right) \mathbf{E} \| \alpha^{(0)} - \alpha_* \|_2^2 \right). \end{aligned}$$

We study the smoothed hinge loss function $\phi_\gamma(z)$ with $\gamma = 1$, and solves the following $L_1 - L_2$ regularization problem:

$$\min_w \left[\underbrace{\frac{1}{n} \sum_{i=1}^n \phi_\gamma(w^\top x_i y_i)}_{f(w)} + \underbrace{\frac{\lambda}{2} \|w\|_2^2 + \mu \|w\|_1}_{g(w)} \right].$$

We compare different algorithms

Comparisons

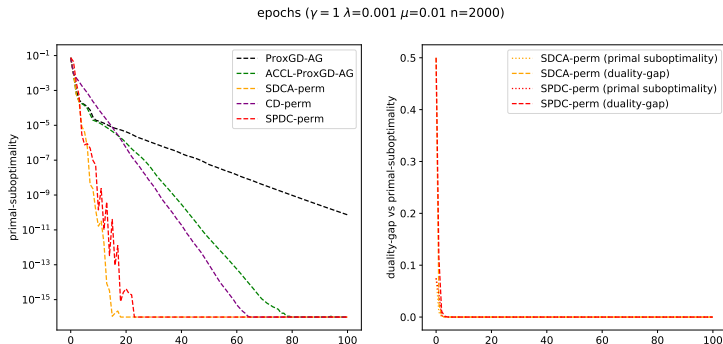


Figure: Comparisons of Proximal Gradient, SDCA and primal CD, SPDC

Comparisons

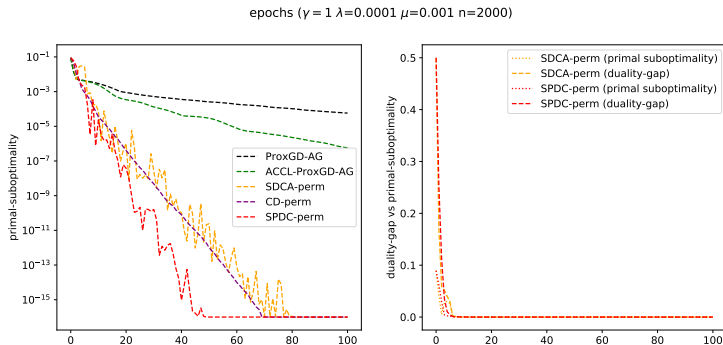
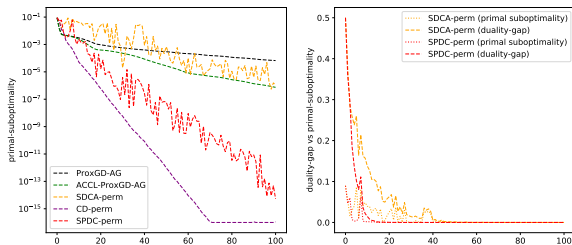


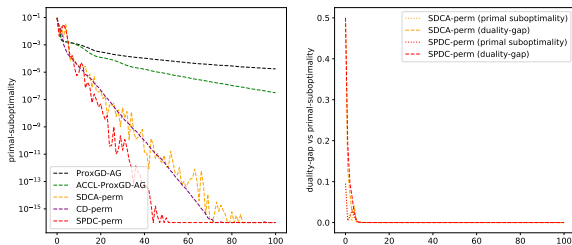
Figure: Comparisons of Proximal Gradient, SDCA and primal CD, SPDC

Comparisons

epochs ($\gamma = 1$ $\lambda = 1e-05$ $\mu = 0.001$ $n = 2000$)



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Summary

Regularized Loss Minimization

- finite sum structure
- decomposable linear model

Primal Coordinate Descent

- primal variables
- insensitive to λ and n

Primal-Dual SPDC

- accelerated dual coordinate
- works better when $\lambda n \ll 1$