

Homework/Programming 5. (Due Oct. 28)

Math. 609-600

Problem 1. Do Exercise 3 on p.5 of the 639 lecture 7 notes. You will have to use the (positive) square operator defined on p.4-5 of those notes.

The next problem that we consider here comes from a finite element approximation to a one dimensional second order elliptic boundary value problem. The problem that we consider is to approximate the solution $y : [0, 1] \rightarrow \mathbb{R}$. of

$$(1.1) \quad \begin{aligned} -y''(x) &= f(x), \quad x \in (0, 1), \\ y(0) &= y(1) = 0. \end{aligned}$$

The approximation involves a mesh of equally spaced points on $[0, 1]$, namely, $\{x_i := ih\}$, where $h = 1/N$ and $N > 1$ is an integer. We define the finite element approximation space, V_h to be the set of functions on $[0, 1]$ which are continuous and piecewise linear with respect to the above mesh and vanish on the endpoints, i.e., at 0 and 1. This space and the resulting approximation will be discussed in more detail in recitation, in particular:

- (a) The functions in V_h are uniquely determined by their values at the nodes, x_i , $i = 1, 2, \dots, N - 1$.
- (b) There is a natural basis for V_h (called the finite element basis), namely, ξ_i , $i = 1, \dots, N - 1$ where

$$\xi_i(x_j) = \delta_{i,j}$$

with $\delta_{i,j}$ denoting the Kronecker delta function.

- (c) To define the weak formulation of (1.1), we multiply (1.1) by a “test function” ϕ (which vanishes at the endpoints), integrate the product over $[0, 1]$ and integrate by parts. The weak form of (1.1) is then to find $y \in V$ satisfying

$$(1.2) \quad A(y, \phi) = (f, \phi), \quad \text{for all } \phi \in V$$

where

$$A(v, w) := \int_0^1 v'(x)w'(x) dx \quad \text{and} \quad (v, w) := \int_0^1 v(x)w(x) dx.$$

Here V is a space of functions defined on $[0, 1]$ (the precise definition of V is beyond the scope of this class). This is a weak formulation as the functions in V need only have integrable first derivatives while the strong form (1.1) requires the solution $y \in C^2$.

- (d) The Galerkin approximation to y solving (1.2) is the unique function $y_h \in V_h$ satisfying

$$(1.3) \quad A(y_h, \xi_h) = (f, \xi_h), \quad \text{for all } \xi_h \in V_h.$$

- (e) Expanding $y_h = \sum_{i=1}^{N-1} c_i \xi_i$ in the finite element basis we are led to the linear system:

$$(1.4) \quad \tilde{A}c = \tilde{B}F$$

with \tilde{A} and \tilde{B} being tri-diagonal $(N-1) \times (N-1)$ matrices with entries

$$\tilde{A}_{ij} = h^{-1} \begin{cases} 2 & \text{if } i = j, \\ -1 & \text{if } |i - j| = 1, \\ 0 & \text{otherwise,} \end{cases}$$

and

$$\tilde{B}_{ij} = \frac{h}{6} \begin{cases} 4 & \text{if } i = j, \\ 1 & \text{if } |i - j| = 1, \\ 0 & \text{otherwise,} \end{cases}$$

and, finally, $F_j = (f, \xi_j)$, for $j = 1, 2, \dots, N-1$. Both \tilde{A} and \tilde{B} are symmetric and positive definite.

- (f) We rewrite (1.4) as

$$(1.5) \quad \mathcal{A}y := \tilde{B}^{-1}\tilde{A}y = F.$$

Problem 2. (a) Using the fact that both \tilde{A} and \tilde{B} are symmetric and positive definite, show that the matrix \mathcal{A} is self adjoint with respect to the \tilde{B} inner product even in the case of non-uniformly spaced meshes although the entries of \tilde{A} and \tilde{B} are a little more complicated in that case.

- (b) It is known that there are positive constants c_0 and c_1 not depending on h and satisfying

$$(2.1) \quad c_0 \leq \lambda_1 \leq \lambda_{N-1} \leq c_1 h^{-2}$$

with λ_1 and λ_{N-1} denoting the smallest and largest eigenvalue of \mathcal{A} . Let e^j denote the error in the j 'th iterate of Richardson's method with $\tau = 1/\lambda_{N-1}$ and expand

$$e^j = \sum_{i=1}^{N-1} c_{i,j} \phi_i$$

with ϕ_i as in Theorem 2 of 639 lecture 7 (with A and B of that theorem replaced by \mathcal{A} and \tilde{B} , resp.). Show that

$$|c_{i,j}| = |(1 - \lambda_i/\lambda_{N-1})^j c_{i,0}| \leq (1 - 1/K)^j |c_{i,0}|.$$

Here $K := \lambda_{N-1}/\lambda_1$ is the spectral condition number.

- (c) Use linear Maclaren expansion of $\ln(1+x)$ to show the expected number of steps required to reduce the error by ϵ is $j \approx K \ln(\epsilon^{-1})$.
- (d) Now switch to the method with optimal parameter, i.e., $\tau = 2/(\lambda_1 + \lambda_{N-1})$. Show that in this case the expected number of steps required to reduce the error is $j \approx K \ln(\epsilon^{-1})/2$. Hint: Write $\rho(G)$ on p. 7 of the 639 lecture notes 7 in terms of K and, also, use the linear Maclaren approximation to $(1-x)/(1+x)$.

Problem 3. This is a programming problem using the two iteration methods considered in the above problem. In this case, we have

$$\lambda_j = 6h^{-2}(2 - 2\cos(j\pi/N))/(4 + 2\cos(j\pi/N)), \quad \text{for } j = 1, \dots, N-1.$$

For simplicity, we consider iterating for the solution of the somewhat trivial problem

$$(3.1) \quad \mathcal{A}x = 0$$

with initial vector x^0 being the vector in \mathbb{R}^{N-1} with all entries set to 1. The advantages of solving this problem is that the error $e^j = x - x^j = -x^j$ is trivial to compute.

- (a) Run your code with $\tau = 1/\lambda_{N-1}$ and report the number of iterations required to reduce the maximum norm of error to $\epsilon = 10^{-2}$ and $\epsilon = 10^{-4}$ as a function of N over the range 4, 8, ..., 128. Also, for $N > 4$, report the iteration increase factor, i.e., the number of iterations at N divided by the number of iterations at $N/2$ (for the same ϵ). The asymptotic iteration increase factor (as $N \rightarrow \infty$)

should follow (2.1) and is related to the answers of Parts (c) and (d) of the previous problem.

- (b) Switch to the optimal τ and make the runs and report errors analogous to those of Part (a) above.