

Data Analysis with Mixed-Integer Optimisation for Scheduling Royal Mail Deliveries

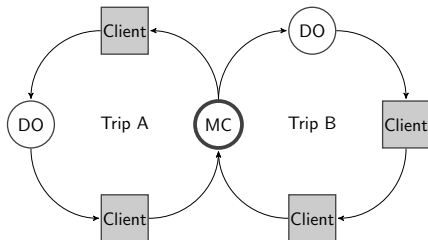
MENG INDIVIDUAL PROJECT

Athanasios Liaskas

Problem Description

Context of the Problem

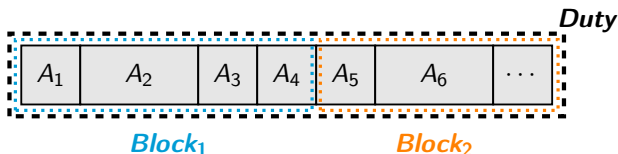
- Each MC is responsible for a broad geographic region.
- Trips are performed by each MC's fleet of HGV vehicles.



Atomic Block Definition

A **single round-trip** that commences at the Exeter MC, and after stopping at various external locations concludes again at the MC.

Breakdown of an Atomic Block



Structure of a driver's Duty: *Activities* (A_i), inside *Atomic Blocks* which themselves create a *Duty*.

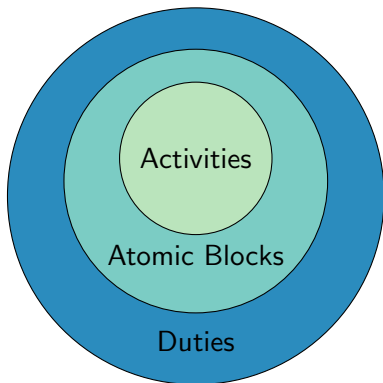
What is an Activity?

Types of *Activities* featured in the dataset

The set of activities signifying the *task by task* actions performed by drivers, as observed in the data exploration.

Activity	Description
Start/End	The <i>beginning</i> , and <i>end</i> of a duty.
Travel	A <i>travel leg</i> between locations.
Load/Unload	<i>Loading</i> and <i>offloading</i> of mail units.
Meal Relief	A <i>meal-allowance</i> break.
Distribution/Processing	Non-essential administrative tasks.
Park Vehicle	<i>Parking</i> of HGV at end of duty.
Check	Scheduled <i>servicing</i> of HGV.
Clean	Scheduled <i>cleaning</i> of HGV.

High-level Overview



The *duty* assigned to each driver is a collection of *blocks*, which themselves contain *activities*.

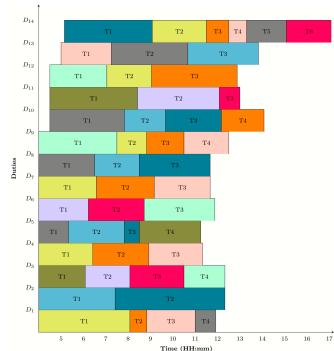
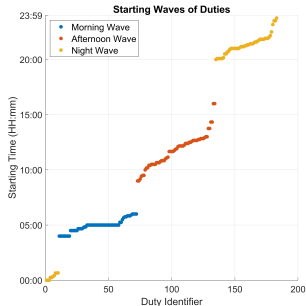
Building Blocks

- Activity: Intervals of jobs performed inside an Atomic Block.
- Atomic Block: A round-trip starting and concluding at the MC.
- Duty: The total time that a driver works for, in a day.

Royal Mail Historical Schedules

What is a Schedule?

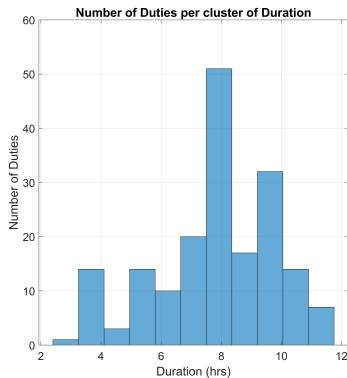
The set of all the **duties** assigned to each HGV driver for a day of the week.



Evaluation of Historical Schedules

Motivation for Sensitivity Analysis

- How good are the historical schedules, and can they be improved?
- Our goal is to propose schedules with favourable characteristics.



Simplifying Assumptions

Key Simplifications

- (1) We consider a **duty** as a *machine* and a **block** as a *job*, freely assigning blocks to duties.
 - (2) The **duration** of a **block** stays **constant**, irrespective of the timing of its occurrence.
 - (3) The **routes** are **fixed**, and we **maintain** the **order** with which we visit external locations.
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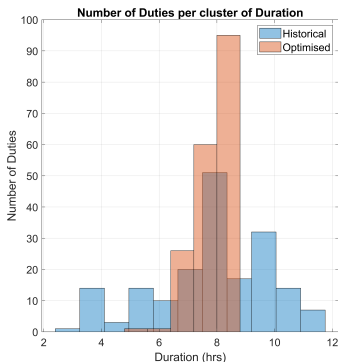
Load Balancing

Model Description

- Objective: find a more **balanced schedule** in terms of **duty length**.
- We minimise the **maximum length of a duty**.
- We execute all blocks featured in the historical schedule.
- Each driver executes at most one block per unit of time.

$$\begin{aligned} & \text{minimize} && y \\ & \text{subject to} && y \geq \sum_{j=1}^n x_{i,j} p_j && \forall i \in D \\ & && \sum_{i=1}^m x_{i,j} = 1 && \forall j \in B \\ & && y \geq 0 \\ & && x_{i,j} \in \{0, 1\} && \forall j \in B, i \in D \end{aligned}$$

Numerical Results



(%) Reduction	
Makespan	Maximum Difference
28%	72%

Results Interpretation

A more **balanced** schedule. We redistributed the workload to reduce the amount of overtime that drivers need to perform.

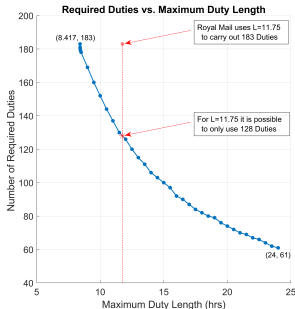
Number of Duties vs Maximum Duty Length

Model Description

- We fix an upper threshold of duty length L and execute all blocks while **minimising the amount of duties**.
- We vary L and conduct a Sensitivity Analysis to determine the minimum number of duties that give us a feasible schedule.

$$\begin{aligned} & \text{minimize} && \sum_{i=1}^m y_i \\ & \text{subject to} && y_i \geq x_{i,j} && \forall i \in D, j \in B \\ & && \sum_{i=1}^m x_{i,j} = 1 && \forall j \in B \\ & && \sum_{j=1}^n x_{i,j} p_j \leq L && \forall i \in D \\ & && y \geq 0 \\ & && x_{i,j} \in \{0, 1\} && \forall j \in B, i \in D \end{aligned}$$

Numerical Results



Results Interpretation

There is a trade-off between the maximum duty length and the number of duties. It is possible to schedule **all blocks** with around **30% fewer duties**.

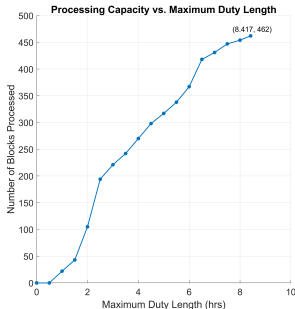
Number of Blocks with Limited Driver Time

Model Description

- Minimise the maximum duty L and determine the **maximum number of blocks** that can **still be completed**.
- We preserve the duties at the historical level of 183 duties.
- We conduct a Sensitivity Analysis by varying L to determine the maximum number of blocks that can be processed for each L .

$$\begin{aligned} & \text{maximize} && \sum_{i=1}^m x_{i,j} \\ & \text{subject to} && \sum_{i=1}^m x_{i,j} \leq 1 && \forall j \in B \\ & && \sum_{j=1}^n x_{i,j} p_j \leq L && \forall i \in D \\ & && y \geq 0 \\ & && x_{i,j} \in \{0, 1\} && \forall j \in B, i \in D \end{aligned}$$

Numerical Results



Results Interpretation

Reducing the maximum time a driver works for by **25%** only reduces the number of blocks that can be processed by **10%**.

Eliminating Redundant Activities

What is **useful** time?

We classify the activities as **useful** or **not** to signify which activities must be maintained when minimising *non-useful* time.

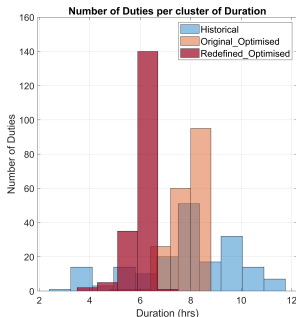
Activity	Useful Time
Start/End	✓
Travel	✓
Load/Unload	✓
Meal Relief	✓
Distribution/Processing	✗
Park Vehicle	✗
Check	✗
Clean	✗

Table 1: List of *useful* or *not* activities.

Redefining the Problem

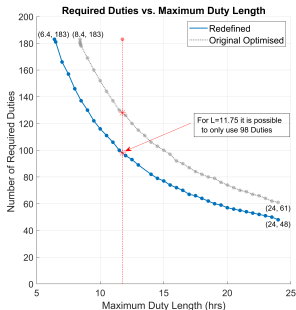
Actions Taken

Artificially created more space for optimisation in the data by deleting activities that we classified as **non-useful working time**.

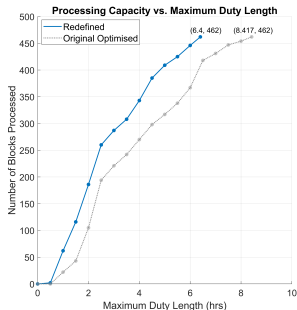


(%) Reduction		
Schedule	Makespan	Maximum Difference
Historical	28%	72%
Redefined	36%	78%

Redefined Sensitivity Analysis



(a) Number of duties required as a function of the Maximum Duty Length (in 30min intervals), up to 24 hours per duty.

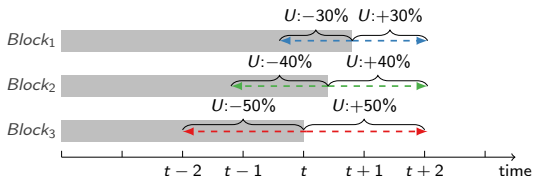


(b) Number of blocks processed as a function of the Maximum Duty Length (in 30min intervals), up to the historical average duty length.

Dealing with Uncertainty

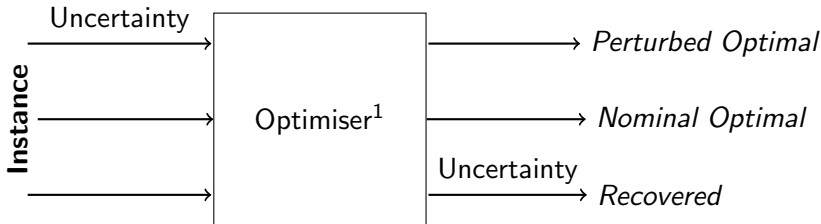
Motivation for Uncertainty Study

- Initial study to determine the schedules' level of **robustness**.
- Robustness is evaluated by measuring **deadline deviations** and **delays to makespan**.
- Our goal is to determine which methodology provides the most robust schedule.



We simulate uncertainty by applying *box uncertainty sets* of different magnitudes on the blocks of an instance.

Incorporating Uncertainty into Schedules



¹Applies Makespan Scheduling Formulation from slide 9

Numerical Results

Schedule		Optimised	Recovered	Makespan	Overrun Duties
Undisturbed					
Nominal		✓		08:25	0
Disturbed					
Instance					
$U: \pm 30\%$	reduced	✓		10:00	71
			✗	10:46	44
	augmented	✓		10:12	73
			✗	10:46	60
$U: \pm 40\%$	reduced	✓		10:44	79
			✗	11:29	66
	augmented	✓		11:26	89
			✗	11:41	68
$U: \pm 50\%$	reduced	✓		10:44	68
			✗	12:15	58
	augmented	✓		10:52	82
			✗	12:19	79

Results Interpretation

The **perturbed optimal** schedule has an improved makespan compared to the **recovered** schedule. However, it has substantially more delayed duties.

Lexicographic Load Balancing

Model Description

- We minimise the **LexOpt Weighted Sum** to obtain a new schedule. We then compare it to the **recovered** wrt. robustness.

$$\begin{aligned} &\text{minimise} && \sum_{i=1}^m w_i y_i \\ &\text{subject to} && y_i \geq y_{i+1} && \forall i \in D \\ & && y_i \geq \frac{1}{m-i+1} \left(\sum_{j=1}^n p_j - \sum_{q=1}^i y_q \right) && \forall i \in D \\ & && y_i \geq \sum_{j=1}^n p_j * x_{i,j} && \forall i \in D \\ & && \sum_{i=1}^m x_{i,j} = 1 && \forall j \in B \\ & && y_i \geq 0 \\ & && x_{i,j} \in \{0, 1\} && \forall j \in B, i \in D \\ & && \text{where } w_i = 2^{m-i} \end{aligned}$$

Numerical Results

Schedule		Lexicographic	Recovered	Makespan	Overrun Duties
Undisturbed					
Nominal		✓		08:25	0
Disturbed					
Instance					
$U: \pm 30\%$	reduced	✓		10:49	43
			X	10:46	44
	augmented	✓		10:53	58
			X	10:46	60
$U: \pm 40\%$	reduced	✓		12:16	64
			X	11:29	66
	augmented	✓		11:45	68
			X	11:41	68
$U: \pm 50\%$	reduced	✓		12:15	57
			X	12:15	58
	augmented	✓		12:22	79
			X	12:19	79

Results Interpretation

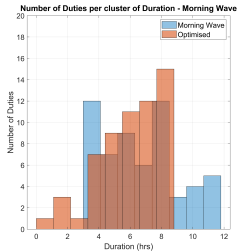
The **LexOpt** generated schedule consistently outperforms or matches the **recovered** wrt. deadline deviations. It is only marginally beaten in terms of makespan delays.

Concluding Remarks

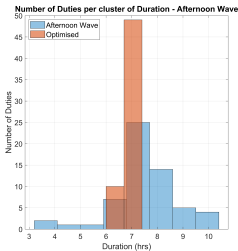
Future Directions

- (1) Schedules that satisfy the **Meal-Relief** constraint enforced by EU regulations.
 - (2) Incorporating Deadline Constraints.
 - (3) Investigating the *VRP* aspect of the problem.
 - (4) Study the effect of Ellipsoidal Uncertainty Sets.
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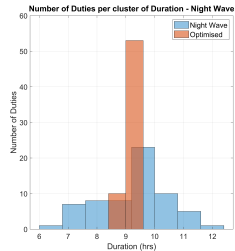
Appendix - Departure Waves Scheduling



(a) Morning



(b) Afternoon



(c) Night

Results Interpretation

Optimising the problem in *wave sub-instances* generates schedules with an **08:25** makespan similar to the results seen in slide 10.

Appendix - Pre-emptive Load Balancing

Model Description

- Objective: find the **theoretical optimal schedule** wrt. **duty length**.
- We minimise the **maximum length of a duty**.
- We execute all blocks featured in the historical schedule.
- Each driver executes at most one activity per unit of time.

$$\begin{aligned} & \text{minimise} && y \\ & \text{subject to} && y \geq \sum_{j=1}^n x_{i,j} && \forall i \in D \\ & && \sum_{i=1}^m x_{i,j} = p_j && \forall j \in B \\ & && y \geq \sum_{i=1}^m x_{i,j} && \forall j \in B \\ & && y, x_{i,j} \geq 0 \end{aligned}$$

Appendix - Numerical Results

Historical	
Makespan	Optimality Gap
08:05	3.1%

Redefined	
Makespan	Optimality Gap
06:32	6.6%

Results Interpretation

We achieve a lower-bound with respect to the maximum duty length observed in the **theoretical optimal schedules**. They are merely theoretical limits that are practically unrealisable.

Appendix - Glossary

These terms are used interchangeably throughout the dissertation, to not tire the reader by using the same term repeatedly.

- Timetable = Schedule = Itinerary
- Duty = Shift
- Break = Meal-Relief
- HGV = Heavy Goods Vehicles = 7.5 tonne lorries
- HGV Driver = Employee
- Model = Formulation
- Maximum Difference² = Measure of the difference in the distribution of load between the heaviest and least loaded duties.

²Stein C. et al. Scheduling When You Do Not Know the Number of Machines.