

# Elizabeth H. Childs

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## Education

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### Stanford University

*PhD in Mechanical Engineering*

Knight Hennessy Scholar (Three Year Leadership Fellowship)

Impact Labs PhD Fellowship (Fellowship for solutions-oriented research)

*MA in Education*

*Stanford, CA*

*Expected May 2027*

*Expected May 2026*

### University of Maryland, College Park

*B.S. Mechanical Engineering*

Banneker Key Scholar (Full Scholarship)

*College Park, MD*

*Aug 2016 – Dec 2020*

## Human-Computer Interaction / Extended Reality Experience

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### Stanford University

*Interaction and Design Lab & CHARM Lab*

Advisor: Prof. James Landay, Prof. Allison Okamura

Augmented Reality for Democratizing Education

*Stanford, CA*

*June 2021 – Present*

### Dolby Laboratories

*Researcher, Advanced Technology Group*

Investigated immersive technology for learning

*Sunnyvale, CA*

*May 2024 – Aug 2024*

### Lam Research Corporation

*Mechanical Engineer, Global Products Engineering*

Designed HoloLens applications for visualizing industrial robots

Created UX applications to visualize and diagnose robot errors

*Fremont, CA*

*May 2021 – Aug 2021*

### University of Maryland, College Park

*Geometric Algorithms for Modeling, Motion, and Animation*

*Laboratory*

Advisor: Prof. Dinesh Manocha

Telepresence in Virtual Reality

*College Park, MD*

*Aug 2020 – Aug 2021*

## Publications

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### Conference Publications

1. E. Childs, J. E. A. Okamura, J. Landay, “[Centering Teachers’ Voices Design Guidelines for High School Laboratory Technologies](#),” (submitted).
2. E. Childs, K. Her, A. Okamura, J. Landay, “[Effects of Augmented Reality Enhancements on Students’ Scientific Reasoning in an Introductory Physics Laboratory](#),” (in preparation).
3. A. Cheng, J. Ritchie, N. Agrawal, E. Childs, C. DeVaux, Y. Jee, T. Leon, B. Maples, A. Cuadra, J. Landay, “Designing Immersive, Narrative-Based Interfaces to Guide Outdoor Learning,” *Human-Computer Interaction Conference (ACM CHI)*, 2023.
4. U. Bhattacharya, E. Childs, D. Manocha et al., “Speech2AffectiveGestures: Synthesizing Co-Speech Gestures with Generative Adversarial Affective Expression Learning,” *ACM International Conference on Multimedia (ACMMM)*, 2021.

## Journal Publications

1. E. Childs,\* F. Mohammad,\* L. Stevens\*, D. Manocha et al., “An Overview of Enhancing Distance Learning Through Augmented and Virtual Reality Technologies,” *IEEE Transactions on Visualization and Computer Graphics*, 2024. (\*Equal contribution; listed alphabetically.)
2. E.H. Childs, A.V. Latchman, R.D. Sochol et al., “Additive Assembly for PolyJet-Based Multi-Material 3D Printed Microfluidics,” *Journal of Microelectromechanical Systems*, 2020.

## Presentations / Panels

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<b>Human-Computer Interaction Conference (ACM CHI)</b> <i>Hosted workshop on Purposeful XR: Affordances, Challenges, and Speculations for an Ethical Future</i>	<i>Yokohama, Japan</i>  <i>April 2025</i>
<b>Augmented World Expo</b> <i>Panelist, The Educational Rift in Spatial Reasoning</i>	<i>Long Beach, CA</i> <i>June 2024</i>
<b>Stanford XR Conference</b> <i>Panel Moderator, XR in Education</i> <i>Demonstration, Mobile AR Learning</i>	<i>Stanford, CA</i> <i>May 2023</i> <i>May 2022</i>

## Robotics / Mechanical Engineering Experience

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<b>University of Maryland, College Park</b> <i>Bioinspired Advanced Manufacturing (BAM) Laboratory</i> <u>Advisor</u> : Prof. Ryan D. Sochol PolyJet 3D Printing for Microfluidic Applications	<i>College Park, MD</i> <i>Sept 2018 – July 2020</i>
<b>Robotics Realization Lab</b> <u>Advisor</u> : Prof. Sarah Bergbreiter Soft Robotics to Model the Human Hand	<i>Jan 2017 – May 2018</i>
<b>Bioinspired Robotics</b> Designed robot inspired by somersaulting Moroccan Spider	<i>Feb 2019 – May 2019</i>
<b>Institute of Technology of Cambodia</b> <i>International Research Experience for Students, Cambodia</i> <b>Sponsor</b> : National Science Foundation <u>Advisor</u> : Prof. Garrett Clayton Modular Robotics for Explosive Ordnance Disposal in Cambodia	<i>Phnom Penh, Cambodia</i> <i>June 2019 – Aug 2019</i>
<b>Oregon State University, Corvallis</b> <i>Dynamic Robotics Laboratory</i> <b>Sponsor</b> : National Science Foundation <u>Advisor</u> : Prof. Jonathan Hurst Impact Absorption in Dynamic Walking Robots	<i>Corvallis, OR</i> <i>June 2018 – Aug 2018</i>
<b>Key Technologies, Inc</b> <i>Mechanical Engineer, Medical Technology Engineering Consulting</i> Designed, manufactured, and tested for consumer products and medical devices	<i>Baltimore, MD</i> <i>Sept 2019 – Dec 2019</i>

## Technical Skills

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SolidWorks | Arduino | C++ | C# | Maya | Microsoft Office | Unity | D3 | FDM 3D Printing | PDMS (Silicone) Molding | CNC Machining