

Why branch-and-bounds are meta-heuristics

state-of-the-art heuristics from branch-and-bounds

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Context & Methodology

Two ways to solve a problem

- **Exact methods:** MIPs, CP, Branch and Price ...

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- **(Meta-)heuristics:** local-search, genetic algorithms, ant colony ...

Mathematical Programming Solver based on Local Search ([1]):

*“ Tree search approaches like branch-and-bound are in essence **designed to prove optimality** [...] Moreover, tree search has an exponential behavior which makes it **not scalable** faced with real-world combinatorial problems inducing millions of binary decisions. ”*

Conventional wisdom - about Tree Search

Mathematical Programming Solver based on Local Search ([1]):

*“ Tree search approaches like branch-and-bound are in essence **designed to prove optimality** [...] Moreover, tree search has an exponential behavior which makes it **not scalable** faced with real-world combinatorial problems inducing millions of binary decisions. ”*

We believe it is false considering **anytime tree searches**

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Many presented in AI/planning conferences

- Some famous ones: **LDS**, **Beam Search**, **wA*** ...
- Some recent: **Anytime pack search**, **Anytime Focal Search**

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Similar in purpose and definitions to meta-heuristics

Still not used much compared to classical meta-heuristics

why anytime tree searches are not used more?

two hypothesis:

1. They are not efficient?
2. They are underestimated?

We believe the latter is true

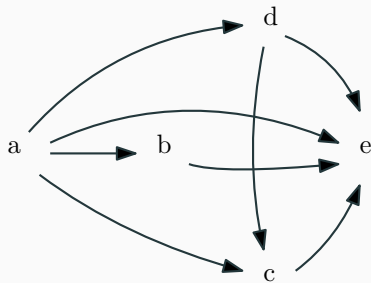
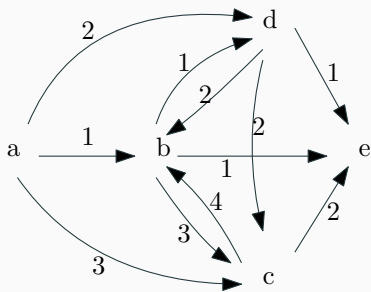
Our experiment

- We consider a well known benchmark (SOP)
- Apply anytime tree searches

Sequential Ordering Problem

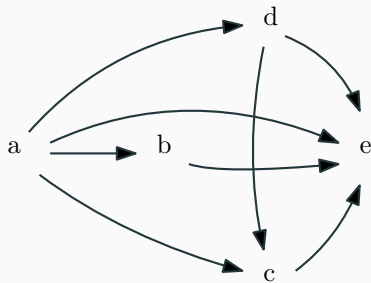
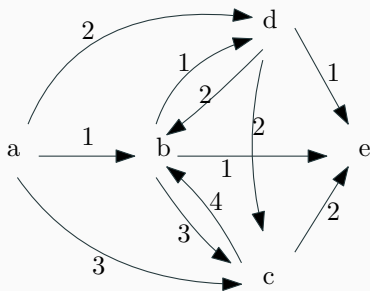
SOP - problem definition

Asymmetric Traveling Salesman Problem with precedence constraints



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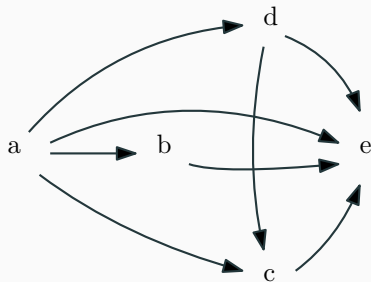
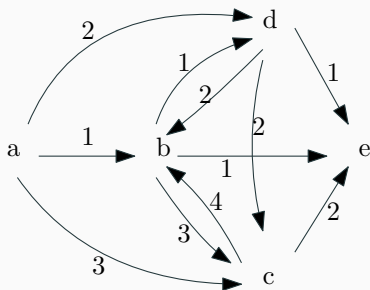
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- a,d,c,b,e is a feasible and costs 9

SOP - problem definition

Asymmetric Traveling Salesman Problem with precedence constraints



- a,d,c,b,e is a feasible and costs 9
- a,b,c,d,e is not feasible

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- Published in 2006
- Standard for meta-heuristics
- “Large” instances (200 to 700 cities)
- Different densities (1, 15, 30, 60) % precedence constraints
- 15% precedence-dense instances remain open (7 instances)

Many methods implemented during the 30 last years to solve SOP

Exact Methods:

- Branch and cuts
- Decision diagrams + CP
- Branch & Bounds with advanced bounds/fathomings

Meta-heuristics:

- Local searches (3-opt)
- Ant Colony Optimization
- Various heuristics (GA, ABC, parallel roll-out, LKH ...)

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Meta-heuristics:

- Local searches (3-opt)
- Ant Colony Optimization
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- Exact methods tend to build stronger bounds
- Meta-heuristics strongly rely on 3-opt (local search)

Our anytime Branch-and-Bound

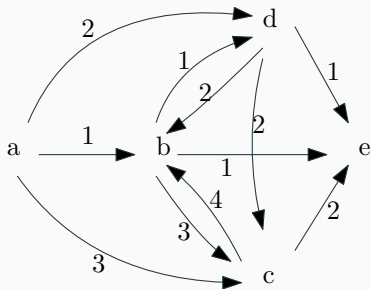
Two parts:

Implicit tree: how to branch, bounds ...

Search strategy: DFS, best-first, Beam Search ...

Implicit tree - Branching

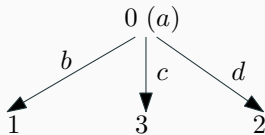
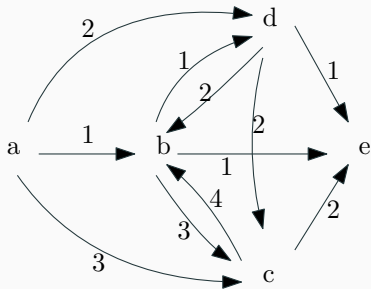
Forward branching + Prefix bounds



0 (a)

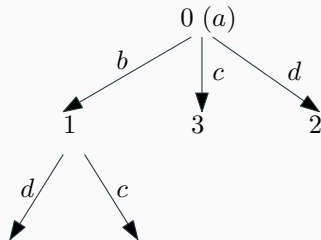
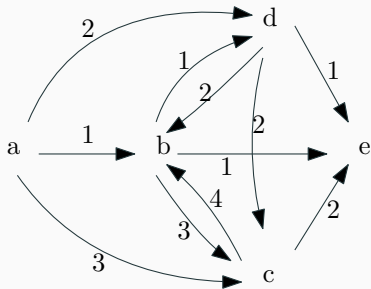
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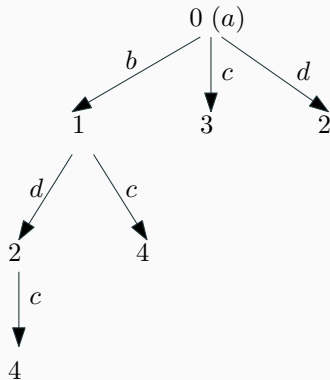
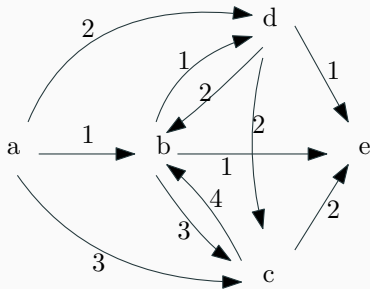
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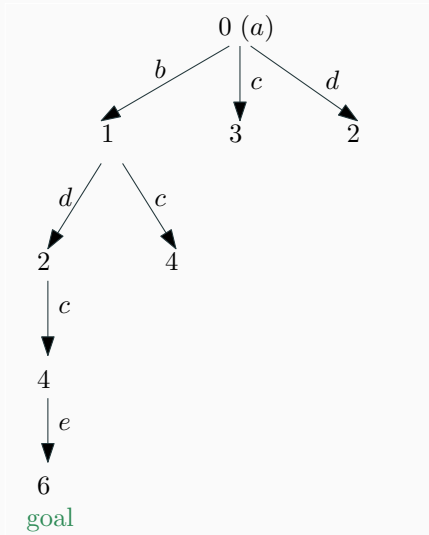
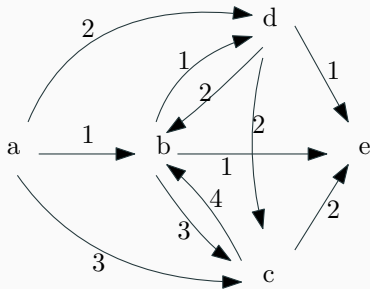
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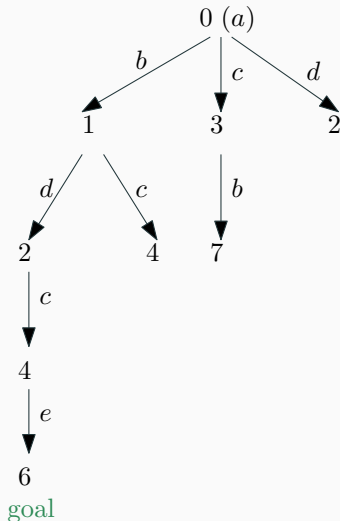
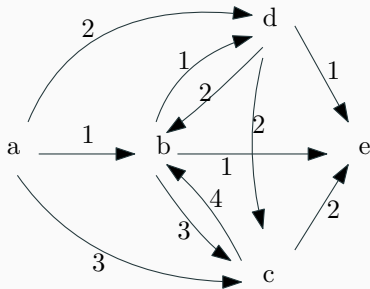
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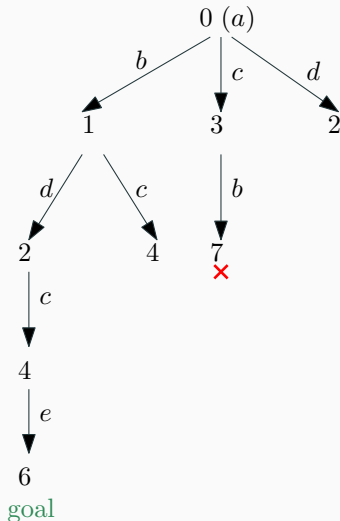
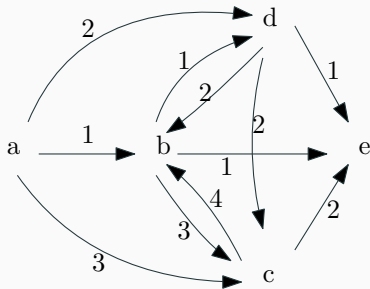
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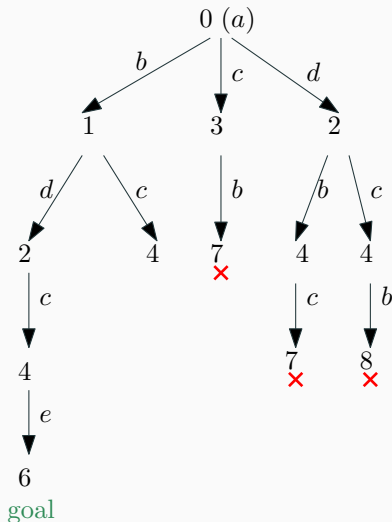
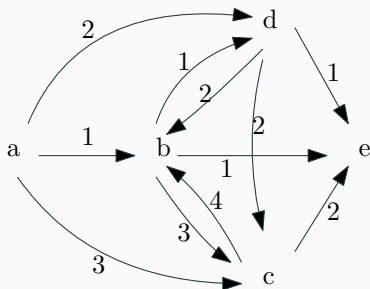
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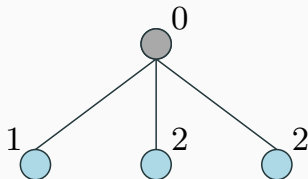
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- **Iterative Beam Search** (next slide)

Beam Search ($D = 3$)

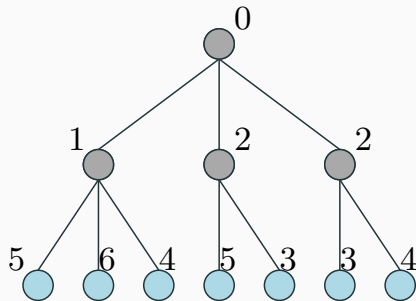


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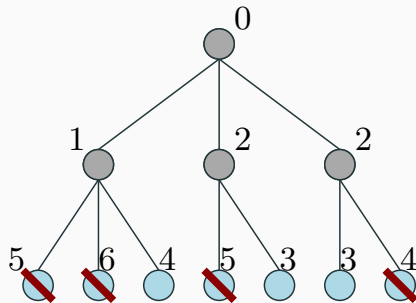
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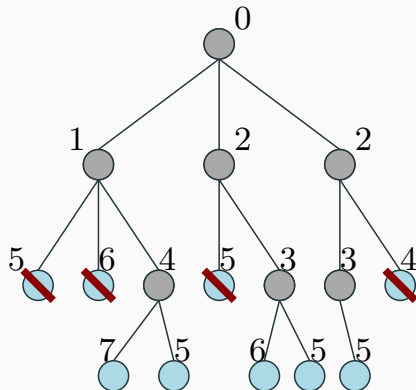
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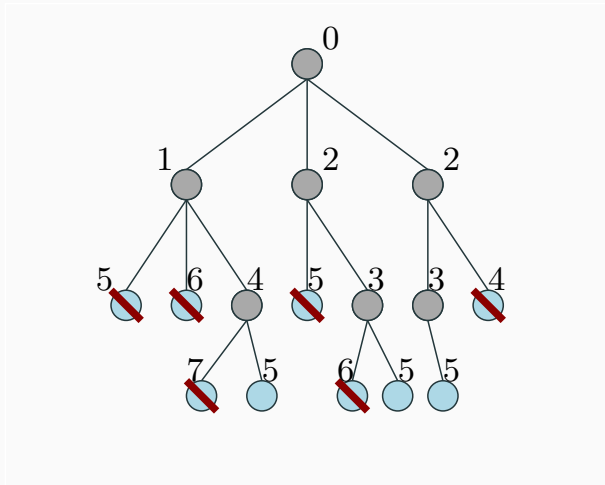
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Iterative Beam Search

- Runs a beam of size 1 (greedy)
- Then runs a beam of size 2, then 4, then 8 ...

Stops when no heuristic fathoming is done (proves optimality)

Dominance fathomings. Inspired from dynamic programming

Example, two partial equivalent solutions:

1. **a,b,c,d** cost 10
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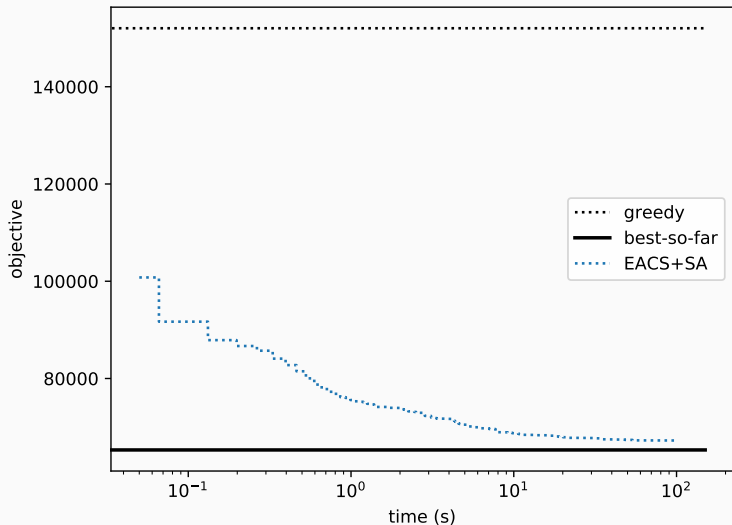
Discard (2) as it is “dominated” by (1).

Maintain each entry in a *Hash table*

Numerical Results

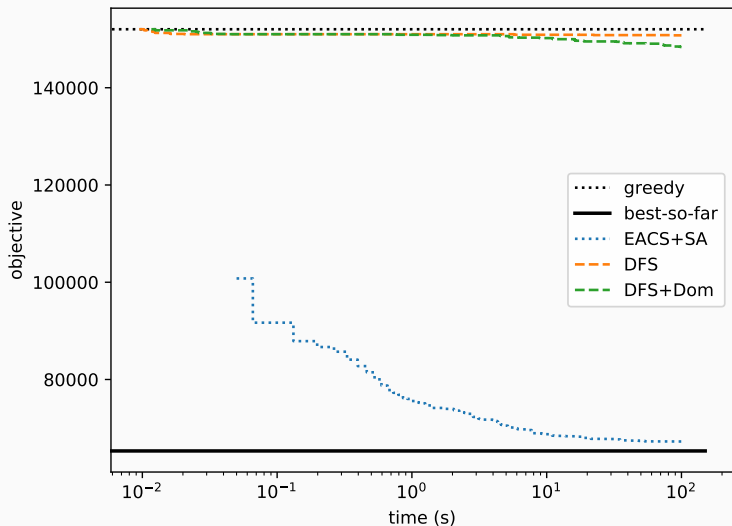
Results - Performance profiles on R.700.1000.15

best-so-far LKH3 with 100.000 seconds run ($\approx 27\text{h}$)



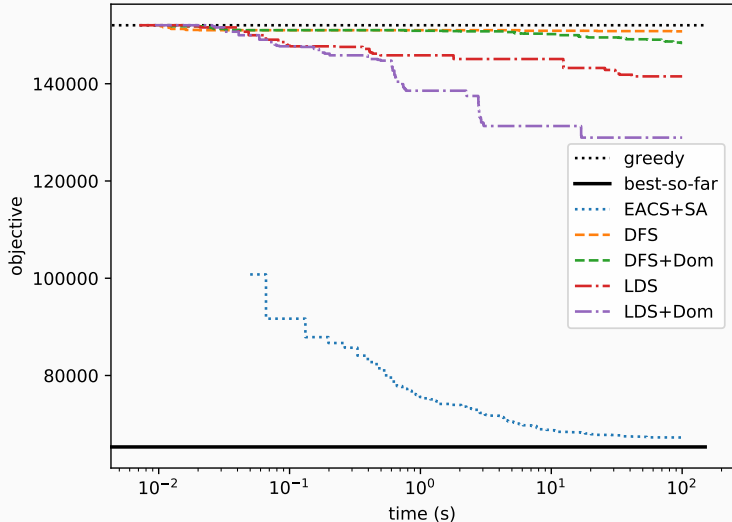
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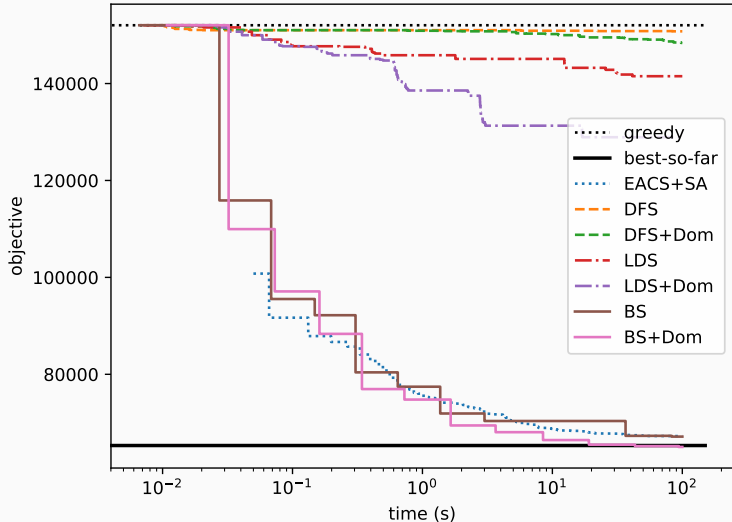
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Results - New best-so-far solutions

6 out of 7 new-best-so-far solutions
(the best known solution for the 7th is maybe already optimal)

| Instance | best known | BS+Dom (600s) |
|---------------|------------|---------------|
| R.500.100.15 | 5.284 | 5.261 |
| R.500.1000.15 | 49.504 | 49.366 |
| R.600.100.15 | 5.472 | 5.469 |
| R.600.1000.15 | 55.213 | 54.994 |
| R.700.100.15 | 7.021 | 7.020 |
| R.700.1000.15 | 65.305 | 64.777 |

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Wrapping-up

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- The search-strategy choice is crucial

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- Generic tree search framework

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References

- [1] Frédéric Gardi, Thierry Benoist, Julien Darlay, Bertrand Estellon, and Romain Megel. *Mathematical programming solver based on local search*. Wiley Online Library, 2014.
- [2] Luc Libralesso, Abdel-Malik Bouhassoun, Hadrien Cambazard, and Vincent Jost. Tree searches for the Sequential Ordering Problem. working paper or preprint, January 2020. URL <https://hal.archives-ouvertes.fr/hal-02374896>.