

RBFAR-OLS

This repository contains code for my research on a modified method of OLS (orthogonal least squares), applied to RBF-AR (radial basis function - autoregressive) models.

Relevant Papers

- Original OLS algorithm for RBF networks
- One of the articles that introduced RBF-AR
- RBF-AR parameter optimization
- RBF-AR applications
- Adaptive learning for RBF-AR methods

Formulation of the problem

$$\begin{aligned} X &\in \mathbb{R}^{l \times n} \\ d &\in \mathbb{R}^{l \times 1} \\ \Psi : \mathbb{R}^n &\rightarrow [0, 1]^m, \\ \Phi_i &= \Psi(X_i) \\ N &\in \mathbb{R}^{m \times n} \end{aligned}$$

Note: the target variable d should be normalized, so it has a mean of 0. These models only work well for stationary data, but for data with a trend, this normalization should be done via a trend removal method.

First approach (locally pre-trained coefficients)

$$\begin{aligned} y_i &= \Psi(X_i) \cdot (X_i \cdot N^T) \\ \Rightarrow d &\approx y = (\Phi \odot (X \cdot N^T)) \cdot \underline{1} \\ \Rightarrow N &= ? \end{aligned}$$

Solution: first fit an AR model to each candidate centre, and then select from them and assign weights to each selected one.

Let Ξ_i be the set of training sample indices associated with the i th candidate centre. We define Ξ_i as follows:

$$\Xi_i = \{j \in [1, l] \mid \Psi_i(X_j) \geq \rho\},$$

where ρ is a threshold for the candidate centre selection, and

$\Psi_i(X_j)$ is the i th element of $\Psi(X_j)$

Let ν_i be the coefficient-vector associated with the i th candidate centre.

We fit each linear AR model separately, using a standard least squares approach:

$$\hat{\nu}_i = \arg \min_{\nu_i} \sum_{j \in \Xi_i} (d_j - X_j \cdot \nu_i)^2$$

Let N be the matrix of these coefficients:

$$N = \begin{bmatrix} \hat{\nu}_1^T \\ \hat{\nu}_2^T \\ \vdots \\ \hat{\nu}_m^T \end{bmatrix}$$

Now we can calculate the activation matrix Σ . This matrix represents the output for each training point i and each linear AR model, associated with the j th candidate centre:

$$\begin{aligned} \Sigma &= \Phi \odot (X \cdot N^T) \\ \Sigma_{i,j} &= \Psi_j(X_i) \cdot (X_i \cdot \hat{\nu}_j^T) \\ \Sigma &= \begin{bmatrix} \Psi_1(X_1) \cdot (X_1 \cdot \hat{\nu}_1^T) & \Psi_2(X_1) \cdot (X_1 \cdot \hat{\nu}_2^T) & \dots & \Psi_m(X_1) \cdot (X_1 \cdot \hat{\nu}_m^T) \\ \Psi_1(X_2) \cdot (X_2 \cdot \hat{\nu}_1^T) & \Psi_2(X_2) \cdot (X_2 \cdot \hat{\nu}_2^T) & \dots & \Psi_m(X_2) \cdot (X_2 \cdot \hat{\nu}_m^T) \\ \vdots & \vdots & \ddots & \vdots \\ \Psi_1(X_l) \cdot (X_l \cdot \hat{\nu}_1^T) & \Psi_2(X_l) \cdot (X_l \cdot \hat{\nu}_2^T) & \dots & \Psi_m(X_l) \cdot (X_l \cdot \hat{\nu}_m^T) \end{bmatrix} \end{aligned}$$

From now, we can continue with the OLS approach, such that the activations, normally denoted by P are given by the Σ matrix ($P = \Sigma$).

We then select the centres and assign coefficients (θ_i) to each selected centre using the OLS approach.

$$d = \Sigma \cdot \theta + e$$

The details are left out here, as they are similar to the OLS approach described below.

Having completed this step, we get:

$$y = (\Phi \odot (X \cdot N^T)) \cdot \theta$$

This can be rewritten as the original equation, with the weights modified:

$$y = (\Phi \odot (X \cdot \tilde{N}^T)) \cdot \underline{1},$$

$$\text{where } \tilde{N} = N \odot \theta$$

Second approach (no pre-training)

We flatten the N matrix into a vector ν and rewrite the equation as follows:

$$P \in \mathbb{R}^{l \times (n \cdot m)}$$

$$P_{i,(j-1) \cdot m + k} = \Phi_{i,j} \cdot X_{i,k}$$

$$P = \begin{bmatrix} \Phi_{1,1}X_{1,1} & \Phi_{1,2}X_{1,1} & \dots & \Phi_{1,m}X_{1,n} \\ \Phi_{2,1}X_{2,1} & \Phi_{2,2}X_{2,1} & \dots & \Phi_{2,m}X_{2,n} \\ \vdots & \vdots & \ddots & \vdots \\ \Phi_{l,1}X_{l,1} & \Phi_{l,2}X_{l,1} & \dots & \Phi_{l,m}X_{l,n} \end{bmatrix}$$

let p_i be the i th column of P

$$\nu = [N_{1,1}, N_{1,2}, \dots, N_{1,n}, N_{2,1}, \dots, N_{m,n}]^T$$

$$\Rightarrow d \approx y = P \cdot \nu$$

$$A \in \mathbb{R}^{M_S \times M_S},$$

where M_S is the number of selected centres

$$A = \begin{bmatrix} 1 & \alpha_{1,1} & \dots & \alpha_{1,M_S} \\ 0 & 1 & \dots & \alpha_{2,M_S} \\ \vdots & \ddots & \ddots & \vdots \\ 0 & 0 & \dots & 1 \end{bmatrix}$$

OLS criteria:

- $P = W \cdot A$, where A is an upper triangular matrix, W has orthogonal columns
- $d = W \cdot g + e$

Thus:

$$d \approx W \cdot g = P \cdot \nu = W \cdot A \cdot \nu$$

Centre selection

Initialization:

- define candidate centres C , and calculate Φ accordingly

- calculate P as defined above
- initialize the residuals: $d^{(0)} = d$
- initialize the selected centres: $C^{(0)} = \emptyset$
- initialize W to an empty matrix: $W^{(0)} = \emptyset$
- initialize g to an empty vector: $g^{(0)} = \emptyset$
- initialize the selected indices $I_{\text{selected}}^{(0)} = \emptyset$

At each iteration ($k \in [1, |C_{\text{candidates}}|]$):

$\forall i \in [1, |C_{\text{candidates}}|] \setminus I_{\text{selected}}^{(k-1)}$:

$$w_i = p_i - \sum_{j=1}^{k-1} \alpha_{i,j} w_j,$$

$$\text{where } \alpha_{i,j} = \frac{p_i^T \cdot w_j}{||w_j||^2}$$

$$g_i = \frac{w_i^T \cdot d^{(k-1)}}{||w_i||^2}$$

$$err_i = g_i^2 \cdot \frac{||w_i||^2}{||d^{(k-1)}||^2} = \frac{(w_i^T \cdot d^{(k-1)})^2}{||w_i||^2 \cdot ||d^{(k-1)}||^2}$$

Select the centre c_i with the highest err_i .

$$I_{\text{selected}}^{(k)} = I_{\text{selected}}^{(k-1)} \cup \{i\}$$

$$C^{(k)} = C^{(k-1)} \cup \{c_i\}$$

$$W^{(k)} = W^{(k-1)} \oplus w_i$$

$$g^{(k)} = g^{(k-1)} \oplus g_i$$

$$d^{(k)} = d^{(k-1)} - w_i \cdot g_i$$

Stopping criteria:

1. Maximum number of iterations reached: $k = K_{\text{max}}$
2. Convergence: $||d^{(k)}||^2 < \epsilon$
3. No significant improvement: $\frac{||d^{(k)}||^2}{||d^{(k-1)}||^2} < \delta$

If any of the stopping criteria is met, the algorithm terminates with $M_S = k$.

Finding the coefficients

$$d = W \cdot g + e = P \cdot \nu = W \cdot A \cdot \nu + e \approx W \cdot \hat{g}$$

$$W \text{ has orthogonal columns} \implies W^T \cdot W = H,$$

where H is a diagonal matrix, and thus invertible

$$\text{We can calculate } \hat{g} \text{ by } H^{-1} \cdot W^T \cdot d = \hat{g}$$

$$\implies A \cdot \hat{\nu} = H^{-1} \cdot W^T \cdot d$$

$$A \cdot \hat{\nu} = \hat{g}$$

which is easily and efficiently solvable, due to A being an upper triangular matrix.

SVD-based center selection

Let us assume, we have calculated the activation matrix P , using either approach. Let us then compute its SVD:

$$P = Q \cdot \Sigma \cdot V^T,$$

where Q and V are orthogonal matrices, and Σ is a diagonal matrix containing the singular values of P .

We then get the following equation for the optimal weights:

$$\hat{\nu} = \operatorname{argmin}_{\nu} \{\|d - P \cdot \nu\|_2^2 + \alpha \|\nu\|_2^2\},$$

where α is a regularization parameter.

We can transform this as follows:

$$\begin{aligned}
\hat{\nu} &= \operatorname{argmin}_{\nu} \{ \|d - P \cdot \nu\|_2^2 + \alpha \|\nu\|_2^2 \} \\
&= \operatorname{argmin}_{\nu} \{ d^T d - 2\nu^T P^T d + \nu^T P^T P \nu + \alpha \nu^T \nu \} \\
\Rightarrow \frac{\delta}{\delta \nu} &= -2P^T d + 2P^T P \nu + 2\alpha \nu = 0 \\
\Rightarrow \hat{\nu} &= (P^T P + \alpha I)^{-1} P^T d \\
&= (V \Sigma^T Q^T Q \Sigma V^T + \alpha V V^T)^{-1} V \Sigma^T Q^T d \\
Q \text{ is orthonormal} \Rightarrow Q^T Q &= I \Rightarrow \hat{\nu} = (V \Sigma^T I \Sigma V^T + \alpha V V^T)^{-1} V \Sigma^T Q^T d \\
&= (V \Sigma^T \Sigma V^T + \alpha V V^T)^{-1} V \Sigma^T Q^T d \\
&= (V (\Sigma^T \Sigma + \alpha I) V^T)^{-1} V \Sigma^T Q^T d \\
V \text{ is orthogonal} \Rightarrow V^{-1} &= V^T \Rightarrow \hat{\nu} = V (\Sigma^T \Sigma + \alpha I)^{-1} V^T V \Sigma^T Q^T d \\
V \text{ is orthogonal} \Rightarrow V^T V &= I \Rightarrow \hat{\nu} = V (\Sigma^T \Sigma + \alpha I)^{-1} \Sigma^T Q^T d \\
&= V \begin{bmatrix} \frac{\sigma_1}{\sigma_1^2 + \alpha} & 0 & \cdots & 0 \\ 0 & \frac{\sigma_2}{\sigma_2^2 + \alpha} & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \frac{\sigma_n}{\sigma_n^2 + \alpha} \end{bmatrix} Q^T d
\end{aligned}$$

$$\hat{\nu} = V \begin{bmatrix} \frac{\sigma_1}{\sigma_1^2 + \alpha} & 0 \\ 0 & \frac{\sigma_2}{\sigma_2^2 + \alpha} \\ \vdots & \vdots \\ 0 & 0 \end{bmatrix}$$

This means that:

$$\begin{aligned}
y &= P \hat{\nu} \\
&= Q \Sigma V^T \hat{\nu} \\
&= Q \Sigma V^T V \begin{bmatrix} \frac{\sigma_1}{\sigma_1^2 + \alpha} & 0 & \cdots & 0 \\ 0 & \frac{\sigma_2}{\sigma_2^2 + \alpha} & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \frac{\sigma_n}{\sigma_n^2 + \alpha} \end{bmatrix} Q^T d \\
&= Q \Sigma \begin{bmatrix} \frac{\sigma_1}{\sigma_1^2 + \alpha} & 0 & \cdots & 0 \\ 0 & \frac{\sigma_2}{\sigma_2^2 + \alpha} & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \frac{\sigma_n}{\sigma_n^2 + \alpha} \end{bmatrix} Q^T d \\
&= Q \begin{bmatrix} \frac{\sigma_1^2}{\sigma_1^2 + \alpha} & 0 & \cdots & 0 \\ 0 & \frac{\sigma_2^2}{\sigma_2^2 + \alpha} & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \frac{\sigma_n^2}{\sigma_n^2 + \alpha} \end{bmatrix} Q^T d
\end{aligned}$$

Let $\sigma'_i = \frac{\sigma_i^2}{\sigma_i^2 + \alpha}$, and let Σ' be defined as follows:

$$\begin{aligned}\Sigma' &= \begin{bmatrix} \frac{\sigma_1^2}{\sigma_1^2 + \alpha} & 0 & \cdots & 0 \\ 0 & \frac{\sigma_2^2}{\sigma_2^2 + \alpha} & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \frac{\sigma_n^2}{\sigma_n^2 + \alpha} \end{bmatrix} \\ &= \begin{bmatrix} \sigma'_1 & 0 & \cdots & 0 \\ 0 & \sigma'_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \sigma'_n \end{bmatrix}\end{aligned}$$

Thus we get:

$$y = Q\Sigma'Q^Td$$

The selection algorithm

We iteratively select the first k columns of Q and Σ' , which correspond to the k largest singular values. This gives us a reduced representation of the data, focusing on the most important features. We then calculate the corresponding error and stop when the error is below a certain threshold.

$$\begin{aligned}\text{Error} &= \|d - P\hat{v}\|_2^2 \\ &= \|d - Q\Sigma'Q^Td\|_2^2\end{aligned}$$

Let us define $Q^{(k)}$ as the matrix formed by the first k columns of Q and zeros elsewhere, and $\Sigma^{(k)}$ as the matrix formed by the first k rows and columns of Σ' and zeros in the rest. Then we can rewrite the error as follows:

$$\text{Error}_k = \|d - Q^{(k)}\Sigma^{(k)}Q^{(k)T}d\|_2^2$$

Our stopping criterion is based on the error:

$$\text{Error}_k < \epsilon$$

where ϵ is a predefined threshold. When this condition is met, we stop the selection process and use the current $Q^{(k)}$ and $\Sigma^{(k)}$ for our reduced representation.

We can refine this process by optimizing the calculation of Error_k . We can achieve this by only calculating the differences of the errors.

$$\begin{aligned}
\text{Error}_0 &= \|d\|_2^2 \\
\text{Error}_k - \text{Error}_{k-1} &= \|d - Q^{(k)} \Sigma'^{(k)} Q^{(k)T} d\|_2^2 - \|d - Q^{(k-1)} \Sigma'^{(k-1)} Q^{(k-1)T} d\|_2^2 \\
&= \left(\|d\|_2^2 - 2 \sum_{i=1}^k d^T q_i \sigma'_i q_i^T d + \sum_{i=1}^k d^T q_i^T \sigma'_i q_i q_i \sigma'_i q_i^T d \right) \\
&\quad - \left(\|d\|_2^2 - 2 \sum_{i=1}^{k-1} d^T q_i \sigma'_i q_i^T d + \sum_{i=1}^{k-1} d^T q_i^T \sigma'_i q_i q_i \sigma'_i q_i^T d \right) \\
&= \left(\|d\|_2^2 - 2 \sum_{i=1}^k \sigma'_i (q_i^T d)^2 + \sum_{i=1}^k \sigma_i'^2 (q_i^T d)^2 \right) \\
&\quad - \left(\|d\|_2^2 - 2 \sum_{i=1}^{k-1} \sigma'_i (q_i^T d)^2 + \sum_{i=1}^{k-1} \sigma_i'^2 (q_i^T d)^2 \right) \\
&= \left(\|d\|_2^2 + \sum_{i=1}^k \sigma'_i (\sigma'_i - 2) (q_i^T d)^2 \right) \\
&\quad - \left(\|d\|_2^2 + \sum_{i=1}^{k-1} \sigma'_i (\sigma'_i - 2) (q_i^T d)^2 \right) \\
&= \sigma'_k (\sigma'_k - 2) (q_k^T d)^2 \\
&\boxed{\text{Error}_k - \text{Error}_{k-1} = \sigma'_k (\sigma'_k - 2) (q_k^T d)^2}
\end{aligned}$$

To be able to consistently use the same sort of ϵ values, we can normalize the error by dividing it by the initial error:

$$\text{Normalized Error}_k = \frac{\text{Error}_k}{\text{Error}_0} = \frac{\text{Error}_k}{\|d\|_2^2}$$

Thus, we get our optimized centre-selection algorithm:

1. Normalized Error₀ := 1
2. While $k < |C_{\text{candidates}}|$:
 1. Normalized Error_k := Normalized Error_{k-1} + $\sigma'_k (\sigma'_k - 2) \frac{(q_k^T d)^2}{\|d\|_2^2}$
 2. If Normalized Error_k < ϵ then:
 1. Stop

TODO

- regularizations
 - L1 regularization
- non global sigma estimation
- multistep forecast