

view\_frames Result

Recorded at time: 23.001

base\_footprint

base\_link

camera\_link

hokuyo\_link

wheel\_1

wheel\_2

wheel\_3

wheel\_4

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 23.001 sec old)  
Buffer length: 0.000 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 23.001 sec old)  
Buffer length: 0.000 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 23.001 sec old)  
Buffer length: 0.000 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 10.210 Hz  
Most recent transform: 23.000 ( 0.001 sec old)  
Buffer length: 4.799 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 10.210 Hz  
Most recent transform: 23.000 ( 0.001 sec old)  
Buffer length: 4.799 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 10.210 Hz  
Most recent transform: 23.000 ( 0.001 sec old)  
Buffer length: 4.799 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 10.210 Hz  
Most recent transform: 23.000 ( 0.001 sec old)  
Buffer length: 4.799 sec