

Finite-Sample Properties of OLS

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Research Module in Econometrics and Statistics

November 4, 2019

Overview

- 1 Introduction to the Theorem
- 2 Proof of Theorem
- 3 Conclusions

Introduction to the Theorem

Notation

- ① y_i dependent variable,
- ② x_{ik} k th independent variable (or regressor) with $k = 1, \dots, K$,
- ③ ϵ_i stochastic error term,
- ④ i indexes the i th individual with $i = 1, \dots, n$, where n is the sample size.

Assumptions

- ➊ Assumption 1.1 Linearity:

$$y_i = \sum_{k=1}^K \beta_k x_{ik} + \epsilon_i, i = 1, \dots, n$$

- ➋ Assumption 1.2 Strict Exogeneity:

$$\mathbb{E}(\epsilon_i | \mathbf{X}) = 0$$

- ➌ Assumption 1.3 Rank Condition:

$$\text{rank}(\mathbf{X}) = K$$

- ➍ Assumption 1.4 Spherical Error:

$$\mathbb{E}(\epsilon_i^2 | \mathbf{X}) = \sigma^2$$

$$\mathbb{E}(\epsilon_i \epsilon_j | \mathbf{X}) = 0, i \neq j$$

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Theorem 4.1: Finite Sample Properties

The OLS estimator b

- 1 is an unbiased estimator: $\mathbb{E}(b|X) = \beta$
- 2 has variance: $\mathbb{V}(b|X) = \sigma^2(X'X)^{-1}$
- 3 has the lowest variance in the class of all linear unbiased estimators.

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Explanation of (3)

For any unbiased estimator $\tilde{\mathbf{b}}$ that is linear in \mathbf{y} , we have:

$\mathbb{V}(\tilde{\mathbf{b}}|\mathbf{X}) \geq \mathbb{V}(\mathbf{b}|\mathbf{X})$ in the matrix sense,

meaning that

$\mathbb{V}(\tilde{\mathbf{b}}|\mathbf{X}) - \mathbb{V}(\mathbf{b}|\mathbf{X}) = \mathbf{D}$, where \mathbf{D} is a positive semidefinite $K \times K$ matrix, i.e., $\mathbf{a}'\mathbf{D}\mathbf{a} \geq 0$ for any K -dimensional vector \mathbf{a} .

$\Rightarrow \mathbb{V}(\tilde{b}_k|\mathbf{X}) \geq \mathbb{V}(b_k|\mathbf{X})$ for any $k = 1, \dots, K$.

Proof of (1)

$$\begin{aligned}\mathbb{E}(b|X) &= \mathbb{E}((X'X)^{-1}X'y|X) \\ &= \mathbb{E}((X'X)^{-1}X'(X\beta + \varepsilon)|X) \\ &= \mathbb{E}((X'X)^{-1}X'X\beta + (X'X)^{-1}X'\varepsilon|X) \\ &= \beta + (X'X)^{-1}X' \underbrace{\mathbb{E}(\varepsilon|X)}_{\substack{= 0 \\ \text{(A1.2)}}} = \beta\end{aligned}$$

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Proof of (2)

$$\begin{aligned}
 \mathbb{V}(b|X) &= \mathbb{V}(b - \beta|X) && (\beta \text{ is not random}) \\
 &= \mathbb{V}((X'X)^{-1}X'\varepsilon|X) && (b = \beta + (X'X)^{-1}X'\varepsilon) \\
 &= (X'X)^{-1}X' \underbrace{\mathbb{V}(\varepsilon|X)}_{= \sigma^2 I_n} X (X'X)^{-1} && (\text{A1.4: Spherical Error}) \\
 &= \sigma^2 (X'X)^{-1}
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Proof (3)

Assumptions

Let \tilde{b} be an unbiased estimator and linear in y with

$$\tilde{b} = Cy$$

where $C \in \mathbb{R}^{K \times n}$, which is a function of X and/or nonrandom components (e.g. $C = (X'X)^{-1}X'$ as in OLS Model).

Proof of (3)

Decomposition

With $D := C - (X'X)^{-1}X'$, \tilde{b} can be decomposed to:

$$\begin{aligned}\tilde{b} &= Cy = (C \overbrace{-(X'X)^{-1}X' + (X'X)^{-1}X'}^{=0})y \\ &= Dy + \underbrace{(X'X)^{-1}X'y}_{=b} \\ &= D(X\beta + \varepsilon) + b \\ &= DX\beta + D\varepsilon + b\end{aligned}$$

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 \tilde{b} unbiased

Due to \tilde{b} being unbiased, it follows that $\mathbb{E}(\tilde{b}|X) = \beta$. Therefore,

$$\begin{aligned}\mathbb{E}(\tilde{b}|X) &= \mathbb{E}(DX\beta|X) + \mathbb{E}(D\varepsilon|X) + \mathbb{E}(b|X) \\ &= DX\beta + 0 + \beta = \beta \\ &\implies DX = 0 \\ &\implies \tilde{b} = D\varepsilon + b \\ \iff \tilde{b} - \beta &= D\varepsilon + (b - \beta) \\ &= D\varepsilon + (X'X)^{-1}X'\varepsilon \\ &= (D + (X'X)^{-1}X')\varepsilon \quad (*)\end{aligned}$$

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Rearrangement

By using (*), $\mathbb{V}(\tilde{b}|X)$ can now be rearranged such that:

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since $D'D$ is positive semidefinite. □

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Conclusions

- Under stated assumptions OLS estimator has very nice properties
- Assumptions in the real life examples are very difficult to satisfy. Example: model with lagged dependent variable
- Team work: communication is more important than you think.