

## Calibration results

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### Camera-system parameters:

cam0 (/cam2/image\_raw):

type: <class 'aslam\_cv.libaslam\_cv\_python.DistortedPinholeCameraGeometry'>

distortion: [ 0.04372654 -0.12619885 0.00210549 -0.0013338 ] +- [0.01376338 0.04911932 0.00118091 0.00117132]

projection: [1394.62333699 1394.72200111 945.89412879 610.52587426] +- [ 0.52368001 0.52076137 8.93897922 10.49159778]

reprojection error: [-0.000157, -0.000145] +- [0.805297, 0.810678]

## Target configuration

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Type: aprilgrid

Tags:

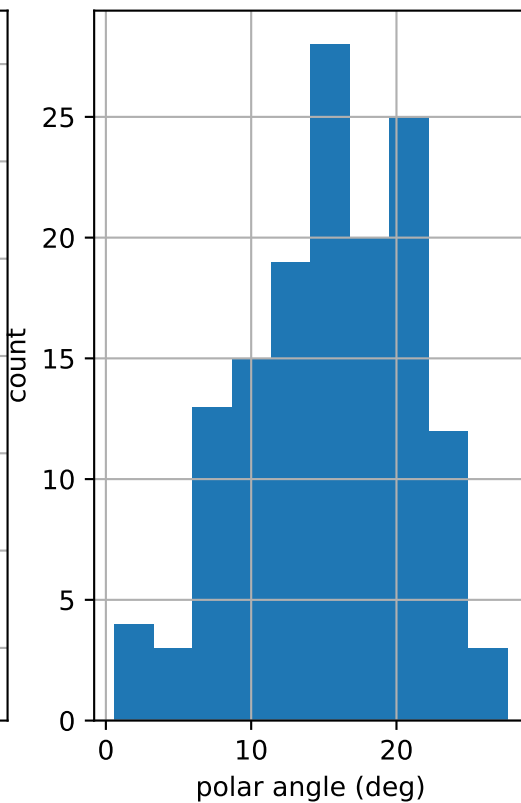
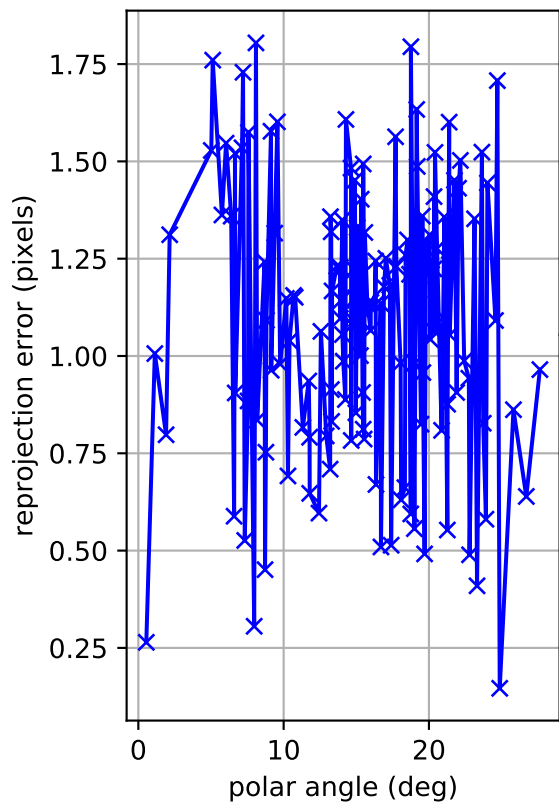
Rows: 6

Cols: 6

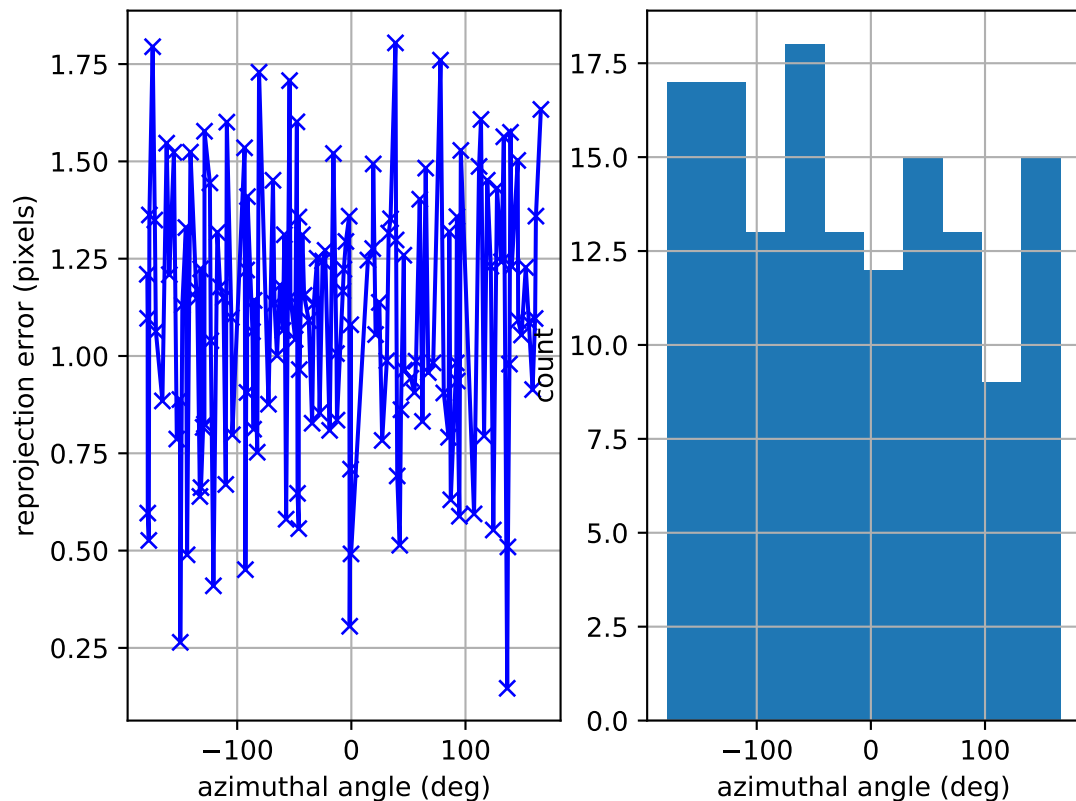
Size: 0.021 [m]

Spacing 0.005999910000000001 [m]

cam0: polar error



cam0: azimuthal error



cam0: reprojection errors

