Multipath Routing for Network Functions Virtualization

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Algorithm 1 AlphaBeta Multipath
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Input: NFVI G = (V, E, B, C), D, \alpha, \beta, n_p
Output: Optimal rate allocation and routing paths
 1: Initialization: G^r = (V, E, B^r, C^r);
          B^{r} = \{b_{e}^{r} : b_{e}^{r} = b_{e}, \forall e\}; C^{r} = \{c_{v}^{r} : c_{v}^{r} = c_{v}, \forall v\};
          y_d \leftarrow y_d^l, \, \forall d; \, U^* \leftarrow 0;
          lb \leftarrow \min_d y_d; \ ub \leftarrow f_{\max}/|D|;
 2: while lb \leq ub do
          Sort D in descending order of y_d
 3:
          for all d \in D do
 4:
                (Q_d^n, Q_d^m, \delta_d^n, \delta_d^m) = \text{PATHRATE}(G^r, d, n_p)
 5:
                N_d^n = \text{NODE}(Q_d^n, \delta_d^n)
  6:
                N_d^m = \text{Node}(Q_d^m, \delta_d^m)
 7:
 8:
          Compute F_n = F(Q_d^n, \delta_d^n, N_d^n) and
 9:
                F_m = F\left(Q_d^m, \delta_d^m, N_d^m\right) according to the
                objective function
          if F^* \leq F_n or F^* \leq F_m then
10:
                Update F^* and the better solution
11:
12:
                lb \leftarrow \min_{d \in D} y_d
                y_d \leftarrow \max\{y_{dl}, (ub+lb)/2\}, \forall d
13:
          else
14:
                ub \leftarrow \min_{d \in D} y_d
15:
                y_d \leftarrow \min\{y_d^u, (ub+lb)/2\}, \forall d
16:
          end if
18: end while
```

 ${\it Abstract} \color{red} - {\it Multipath Routing for Network Functions Virtualization...}}$

I. INTRODUCTION

II. PROBLEM FORMULATION

III. HEURISTIC

Graph:

IV. EVALUATION

A. Dataset and setup

Generated topologies: use the Georgia Tech [?] and BRITE [?] topology generators

Actual ISP topology: Abilene (Internet2) dataset [?] and Geant dataset [?]

Algorithm 2 Find the best candidates for path and rate allocation to a demand

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1: function PATHRATE(G^r, d, n_p)
          Initialization: Let Q denote the set of all shortest
                paths from s_d to t_d; Path q \in Q consists of a
                sequence of nodes V_q, and a sequence of links
                E_q; b_q^r \leftarrow \min_{e \in E_q} b_e^r; c_q^r \leftarrow \min_{v \in V_q} c_v^r;
                Q_d^m \leftarrow \emptyset;
          a_q^r \leftarrow \min\left\{b_q^r, c_q^r\right\}
                                                                    ▶ Path capacity
 3:
          Q_d^n \leftarrow n_p largest paths in Q
          \pi = y_d / \sum_{q \in Q_d^n} a_q^r
 5:
          if \pi \leq 1 then
 6:
                \delta_n(q) \leftarrow \pi a_q^r, \, \forall q \in Q_d^n
 7:
 8:
 9:
          end if
10:
11:
          while |Q_d^m| \le n_p and y_d \ge 0 and Q \ne \emptyset do
                Scan Q for smallest path q with a_q^r \ge y_d
12:
                if <path not found> then
13:
                      Find the largest path q in Q
14:
                      Update path and rate allocation:
15:
                           Q_d^m \leftarrow Q_d^m \cup \{q\}; \ \delta_d^m(q) \leftarrow a_q^r;
                      Update remaining resources and demand:
16:
                           \begin{array}{l} b_e^r \leftarrow b_e^r - a_q^r, \forall e \in E_q; \ Q \leftarrow Q \backslash \left\{q\right\}; \\ y_d \leftarrow y_d - a_q^r \end{array}
                else
17:
18:
                      Update path and rate allocation:
                           Q_d^m \leftarrow Q_d^m \cup \{q\}; \ \delta_d^m(q) \leftarrow y_d;
19:
                      Update remaining resources and demand:
                           b_e^r \leftarrow b_e^r - y_d, \forall e \in E_q; y_d \leftarrow 0;
20:
          end while
21:
          return Q_d^n, Q_d^m, \delta_d^n(q), \delta_d^m(q)
22:
23: end function
```

- B. Convergence speed
- C. Throughput
- D. End-to-end latency
- E. Routing overhead

V. DISCUSSION

A. Implementation

VI. CONCLUSION

Algorithm 3 Find the assignment of nodes for a SFC on a path allocated to demand

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1: function Node(G^r, d, q, \delta)
           for all f_i \in F_d, i = 1 \dots |F_d| do
 2:
                \begin{array}{l} v_i \leftarrow \text{ the first node } v \text{ on path } q \text{ with } c_v^r \geq r_{vf_i}(\delta) \\ N_d^n \leftarrow N_d^n \cup \{v_i\} \end{array}
 3:
 4:
 5:
           Return failure if solution not found
 6:
           v_{|F_d|+1} \leftarrow t_d; \ N_d^n \leftarrow v_{|F_d|+1}; while node found do
 7:
 8:
                for all f_i \in F_d, i = 1 \dots |F_d| do
 9:
                      Find the smallest node v with c_v^r \ge r_{vf_i}(\delta)
10:
                            along path q from v_i to v_{i+1}
                      Update v_i if node found
11:
                end for
12:
           end while
13:
           return N_d^n
14:
15: end function
```