

# Spatially Aware Dictionary Learning and Coding for Fossil Pollen Identification

## Design and research of WiFi intelligent car based on computer vision technology

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### Abstract

*In order to realize the work of some dangerous and complex areas, such as the places where the human can not be close to the fire and explosion scene, a kind of intelligent control car with two-way communication ability has put forward in this paper. Based on the machine vision technology and WiFi wireless communication technology, the car can transmit the environmental information of the working area in real time. At the same time, the control terminal can send control commands to the car to realize remote control. The overall framework of the intelligent car is designed, the whole system is composed of six parts, including power supply, control terminal, WiFi communication module, microcontroller, motor and camera. Finally, the performance of the intelligent car is tested by experiment, and the PCB board of the car control system is made. The experimental results show that the communication distance of communication, WiFi communication over Zigbee and Bluetooth has farther and faster communication speed, can meet the demand of intelligent vehicle two-way real-time communication, which provides a feasible communication scheme for the design of the intelligent car.*

### 1. Introduction

The full name of Wifi is wireless fidelity, is one of the most widely used wireless network transmission technology [3]. If there is a mobile phone WiFi Internet function, the WiFi signal can not connect to the Internet through places Unicom mobile data, this application has been very extensive, but the application of WiFi in signal control based on little. In the place where there is a WiFi signal, you can not use mobile or Unicom's data connection to the Internet, the application has been very extensive, But the application of WiFi signal in control is still very few. However, compared to the Zigbee wireless transmission and Bluetooth signals with transmission distance, transmission speed and so many

advantages, it is used in the design of remote image transmission and control command transmission system, has important significance for improving the transmission rate and transmission distance.

### 2. Design of WiFi intelligent car system based on computer vision technology

The whole system of WiFi intelligent car based on computer vision technology is based on MCU and WiFi module as the core, mainly divided into six parts, including power supply, control terminal, WiFi communication module, microcontroller, motor and camera, the structure of the whole system as shown in Fig 1.

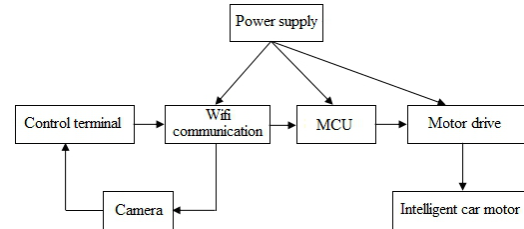


Figure 1. The overall design of the system structure.

As shown in Fig 1, the control terminal of WiFi intelligent car control based on computer vision technology can be a computer terminal, and it can also be a mobile phone, the main function of WiFi communication module is responsible for the communication between the control terminal and the lower computer, it can be transmitted back to the realtime image collected by the intelligent car terminal, and can also send control commands to the intelligent car terminal. The system uses intelligent car camera to collect environmental information, then through the MCU and WiFi control module, the real-time image is transmitted back to the host computer, according to the environment information, the host computer can send out the control commands,

### 2.1. Design of Wifi intelligent car motor drive module

[illegible]

shown in Fig 2, L298N chip can simultaneously drive two DC motors, assuming that the two motors were M1 and M2, The AB pin is mainly for the motor speed control, speed control using PWM pulse width modulation method [1]. Taking M1 motor as an example, when the IN1 is connected to a low level, IN2 is connected to a high level, you can specify the level when the motor is transferred, instead, the motor rotate reversely, reversing motor can effectively control the car forward backward, the speed and the forward backward control level as shown in table 1.

Moto	Rotation mode	IN1 port	IN2 por
M1	Corotation	Low	Hjgh
M1	Reversal	Hjgh	Low
M1	Stop	Low	Low

## References

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