# Chapter 5. Lighting and Shading

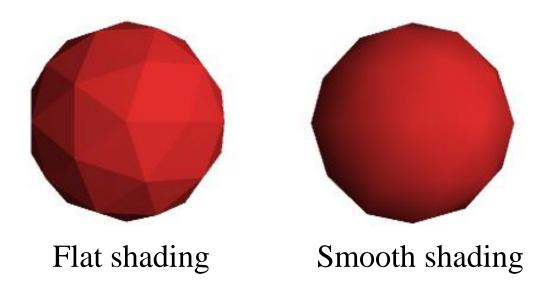
# **Shading Implementation** with **GLSL**

# Review: OpenGL shading

- Need
  - Normals
  - material properties
  - Lights
- State-based shading functions have been deprecated (glNormal, glMaterial, glLight)
- send attributes or uniforms to shaders

# **Review: Polygon Rendering Methods**

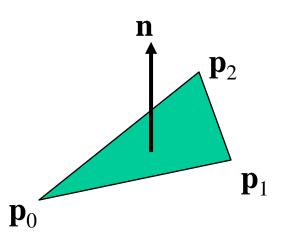
- Curved surfaces are often approximated by polygonal surfaces
- So, polygonal (piecewise planar) surfaces often need to be rendered as if they are smooth



### **Review: Flat Shading**

We set a single normal for each triangle

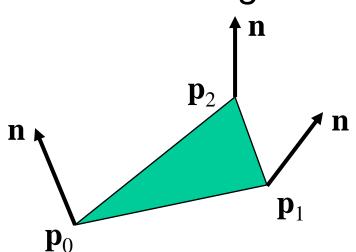
 Because three vertices of a triangle has the same normal, shades computed by the Phong model can be almost same

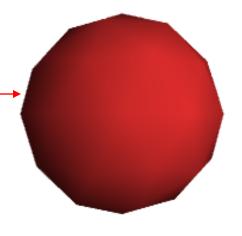




# **Review: Smooth Shading**

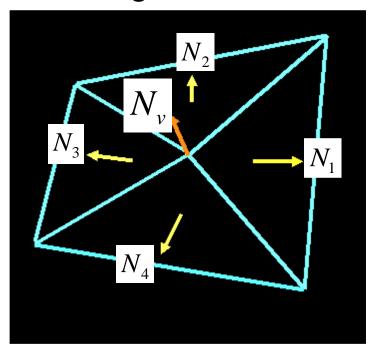
- We set <u>a new normal at each vertex</u> as if the polygon is the approximation of a smooth surface
- For a sphere model, it is easy
  - If centered at origin  $\mathbf{n} = \mathbf{p}$
- Note silhouette edge





#### **Review: Vertex Normal Vector**

- Normal vectors at vertices
  - Averaging the normal vectors for each polygon sharing that vertex



$$N_{v} = \frac{(N_{1} + N_{2} + N_{3} + N_{4})}{\|N_{1} + N_{2} + N_{3} + N_{4}\|}$$

# Applying Phong Model in two different ways

- Applying Phong model <u>at each vertex</u>
  - Gouraud Shading

- Applying Phong model <u>at each fragment</u>
  - Phong Shading

# Intensity-Interpolation Surface Rendering

#### Gouraud shading

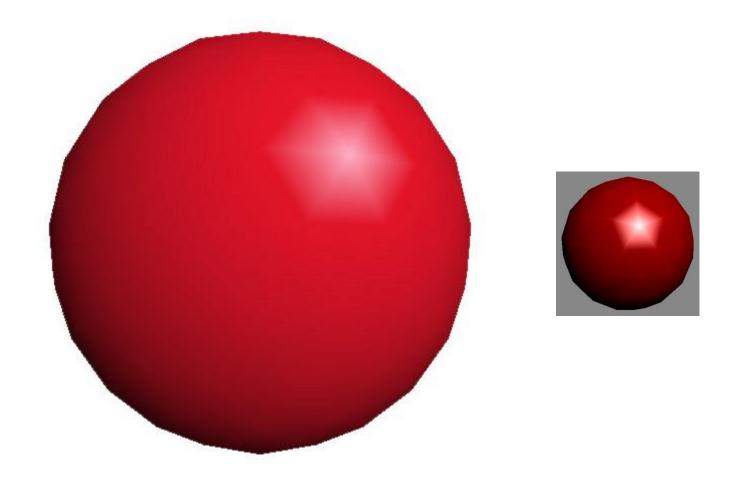
- Rendering a curved surface that is approximated with a polygon mesh
- Interpolate intensities at polygon vertices

#### Procedure

- 1. Determine the average unit normal vector at each vertex
- 2. Apply an illumination model at each polygon vertex to obtain the light intensity at that position
- 3. Linearly interpolate the vertex intensities over the projected area of the polygon

# **Gouraud Shading Problems**

Lighting in the polygon interior is inaccurate



# Normal-Vector Interpolation Surface Rendering

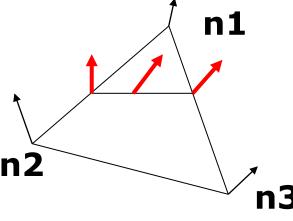
#### Phong shading

- Interpolate normal vectors at polygon vertices

#### Procedure

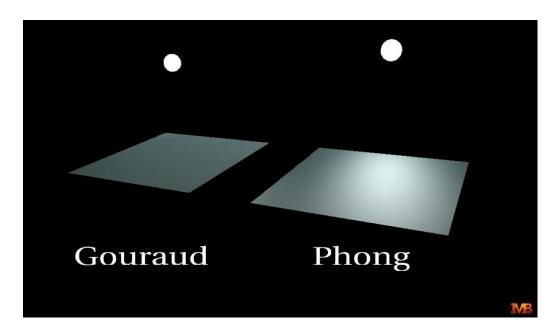
- 1.Determine the average unit normal vector at each vertex
- 2.Linearly interpolate the vertex normals over the projected area of the polygon

3. Apply an illumination model at positions along scan lines to calculate pixel intensities



# Gouraud versus Phong Shading

- Gouraud shading is faster than Phong shading
  - OLD OpenGL supports Gouraud shading
- Phong shading is more accurate.
  - Can be implemented using Fragment shader



# **Gouraud and Phong Shading**

#### Gouraud Shading

- Find average normal at each vertex (vertex normals)
- Apply Phong model at each vertex
- Interpolate vertex shades across each polygon

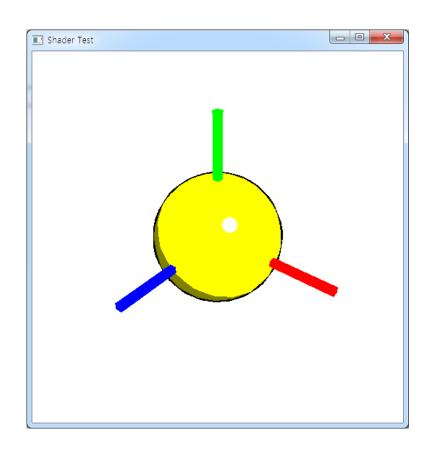
#### Phong shading

- Find vertex normals
- Interpolate vertex normals across edges
- Interpolate edge normals across polygon
- Apply **Phong model at each fragment**

# Comparison

- If the polygon mesh approximates surfaces with a high curvatures, Phong shading may look smooth while Gouraud shading may show edges
- Phong shading requires much more work than Gouraud shading
  - Until recently not available in real time systems
  - Now can be done using fragment shaders
- Both need data structures to represent meshes so we can obtain vertex normals

# Simple Non-Photorealistic Rendering



#### Observation:

- Only Two Colors for diffuse
- One Color for Highlights

#### At Silhouette:

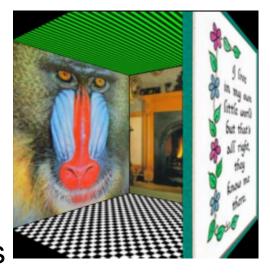
Black line

# Chapter 7. Discrete Techniques: Texture Mapping

# **Texture Mapping**

A way of adding surface details

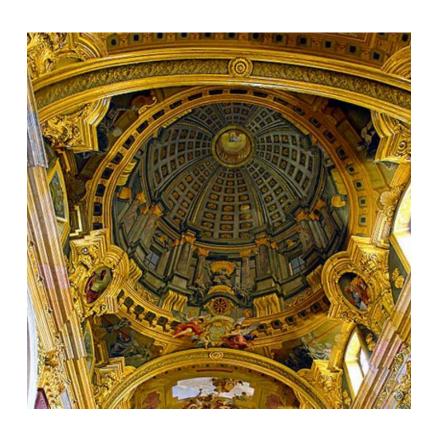
- Two ways can achieve the goal:
  - Model the surface with more polygons
    - Slows down rendering speed
    - Hard to model fine features
  - Map a texture to the surface
    - This lecture
    - Image complexity does not affect complexity of processing





Efficiently supported in hardware

# Trompe L'Oeil ("Deceive the Eye")



Jesuit Church, Vienna, Austria

- Windows and columns in the dome are painted, not a real 3D object
- Similar idea with texture mapping:
- Rather than modeling the intricate 3D geometry, replace it with an image!

# Map textures to surfaces



An image

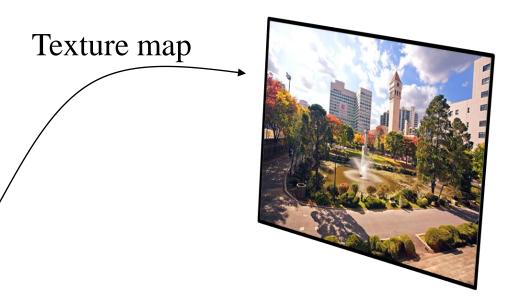
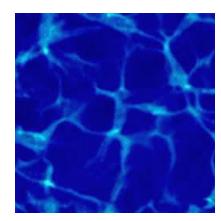


Image mapped to a 3D polygon: The polygon can have arbitrary size, Shape, and 3D position.

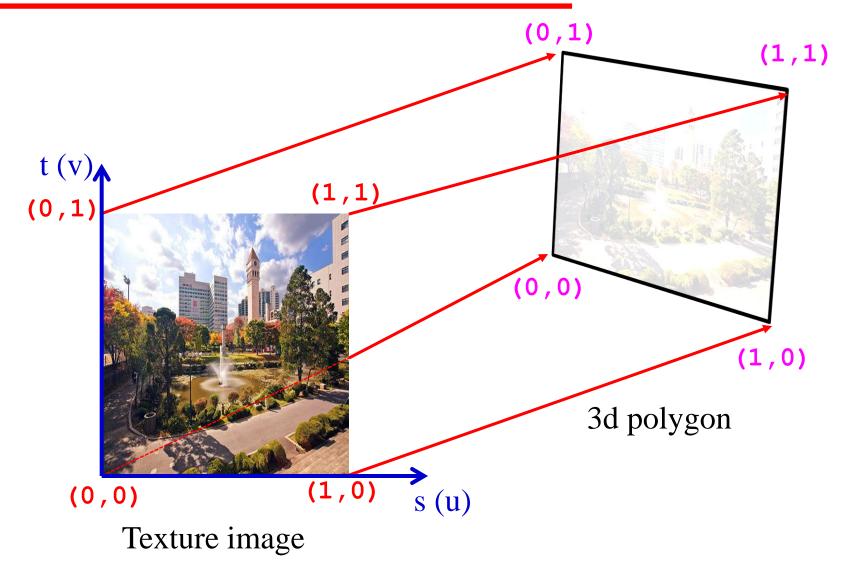
#### The texture

- Texture is a bitmap image
  - Can use an image library to load image into memory
  - Or can create images yourself within the program
- 2D array: unsigned char texture[height][width][4]
- Or unrolled into 1D array: unsigned char texture[4\*height\*width]
- Pixels of the texture are called texels
- Texel coordinates (s,t) scaled to [0,1] range or also called (u,v) coordinate

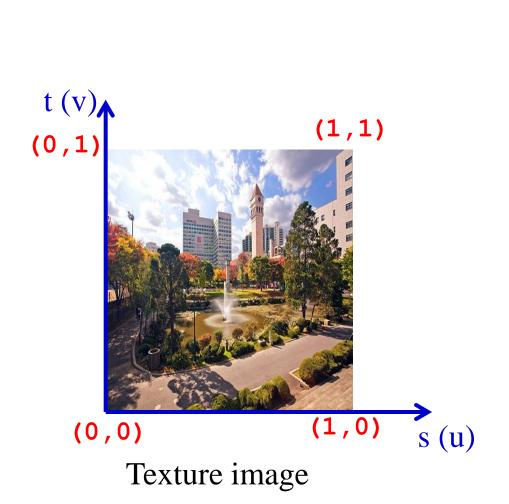


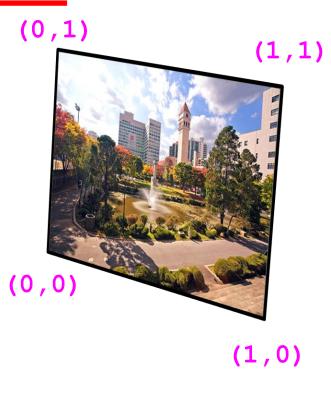


### **Texture map**



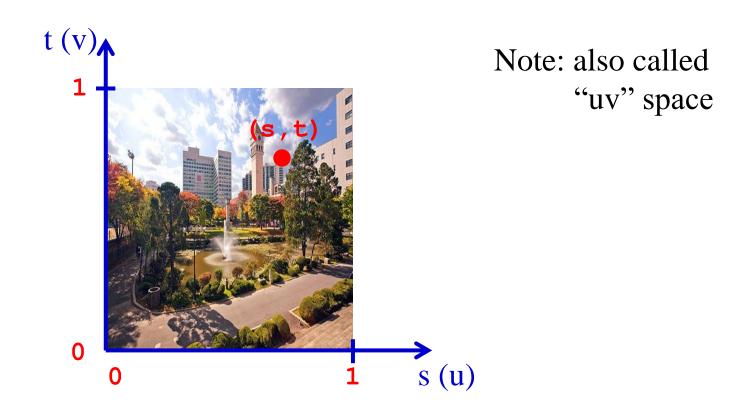
### **Texture map**



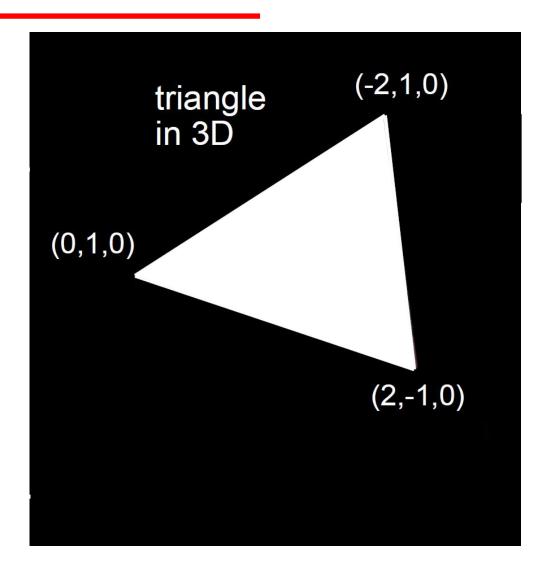


3d polygon

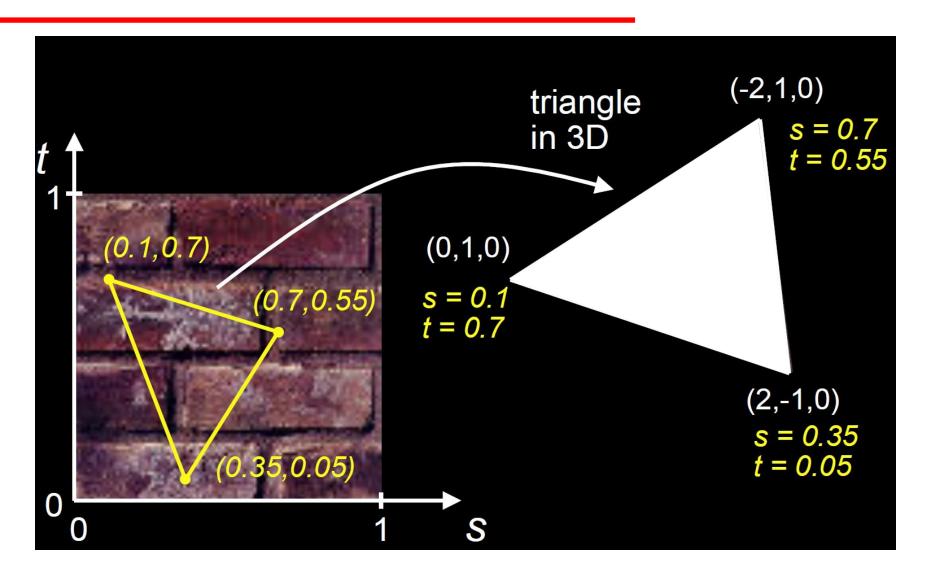
# The "st" coordinate system



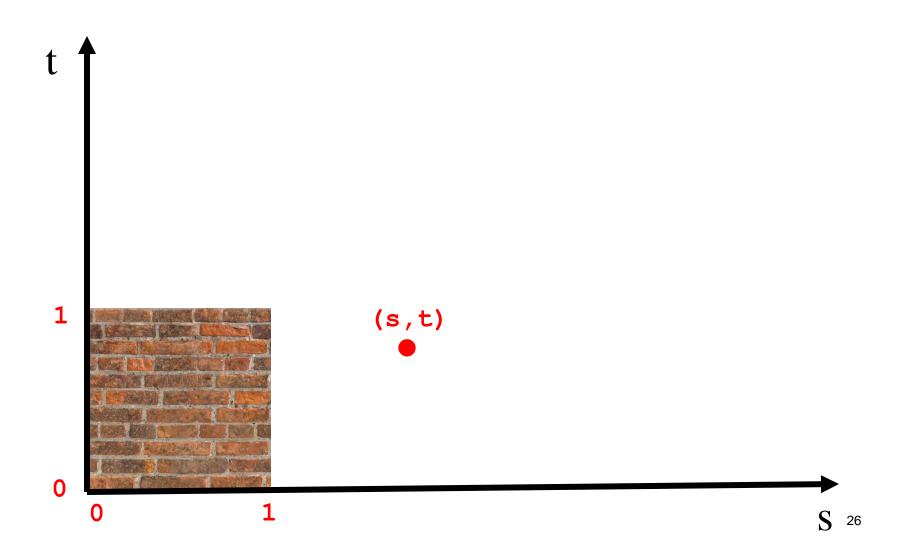
# Texture mapping: key slide



# Texture mapping: key slide

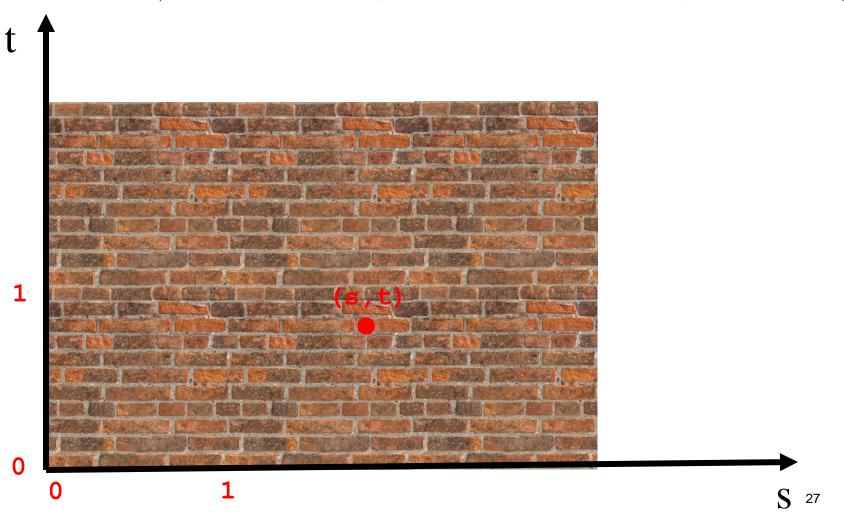


# What if texture coordinates are outside of [0,1]



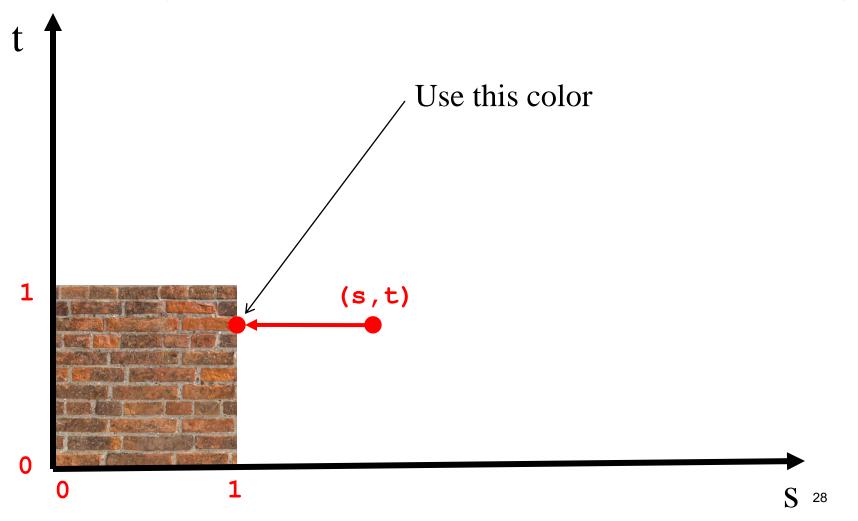
# Solution 1: Repeat texture

glTexParameteri(GL\_TEXTURE\_2D, GL\_TEXTURE\_WRAP\_S, GL\_REPEAT) glTexParameteri(GL\_TEXTURE\_2D, GL\_TEXTURE\_WRAP\_T, GL\_REPEAT)



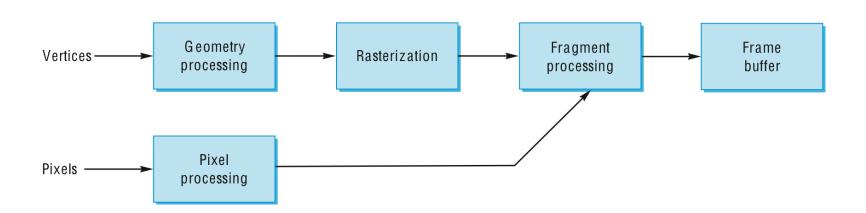
# Solution 2: Clamp to [0,1]

glTexParameteri(GL\_TEXTURE\_2D, GL\_TEXTURE\_WRAP\_S, GL\_CLAMP) glTexParameteri(GL\_TEXTURE\_2D, GL\_TEXTURE\_WRAP\_T, GL\_CLAMP)



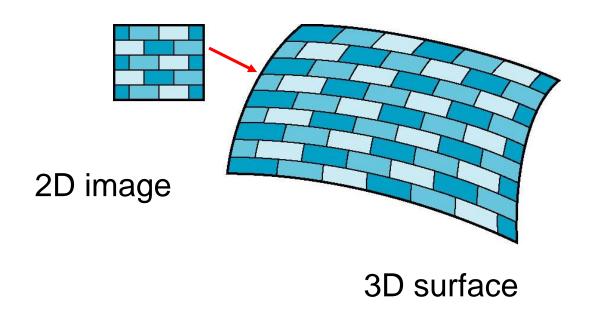
# Where does mapping take place?

 Mapping techniques are implemented at the end of the rendering pipeline



# How to compute the map?

• Is it simple?



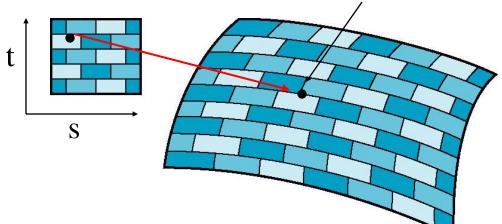
# **Mapping Functions**

- Basic problem is how to find the maps
- Consider mapping from texture coordinates to a point a surface

• Appear to need three functions (x,y,z)

$$x = x(s,t)$$
$$y = y(s,t)$$

$$z = z(s,t)$$



But we really want to go the other way

# **Backward Mapping**

- We really want to go backwards
  - Given a pixel, we want to know to which point on an object it corresponds
  - Given a point on an object, we want to know to which point in the texture it corresponds
- Need a map of the form

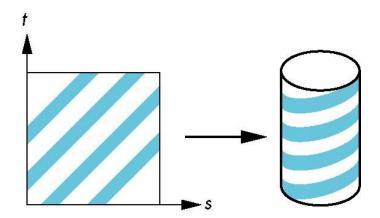
$$\bullet$$
s = s(x,y,z)

$$\bullet t = t(x,y,z)$$

Such functions are difficult to find in general

### **Two-part mapping**

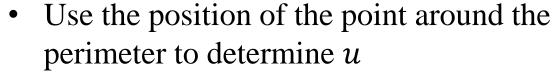
- One solution to the mapping problem is to first map the texture to a simple intermediate surface
- Example: map to cylinder



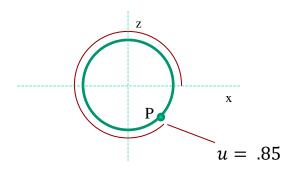
# **Cylindrical Mapping**

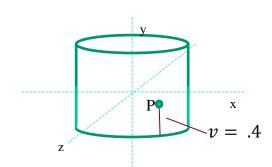
- How to texture map cylinders and cones:
- Given a point P on the surface:
  - If it's on one of the caps, map as though the cap is a plane

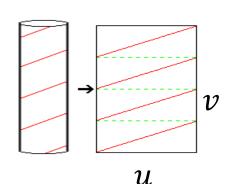




• Use the height of the point to determine v



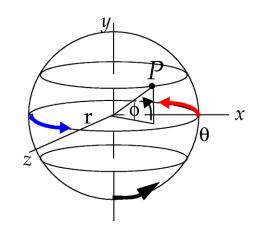




# **Spherical Map**

#### Texture mapping spheres:

- Find (u, v) coordinates for P
- We compute *u* the same we do for cylinders and cones
- If v = 0 or v = 1, there is a singularity. Set u to some predefined value. (0.5 is good)



- v is a function of the latitude of P

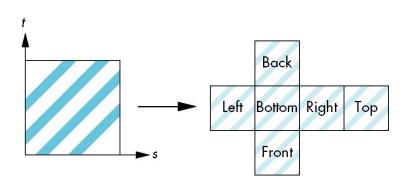
$$\phi = \sin^{-1}\frac{P_y}{r} \qquad -\frac{\pi}{2} \le \phi < \frac{\pi}{2}$$

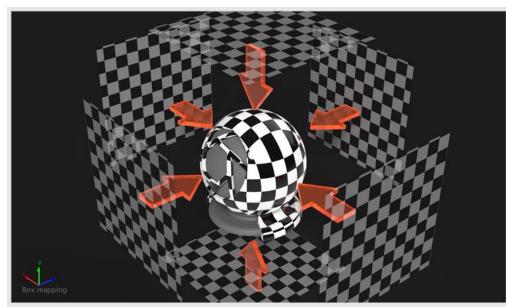
$$v = \frac{\phi}{\pi} + \frac{1}{2}$$

$$r = \text{radius}$$

# **Box Mapping**

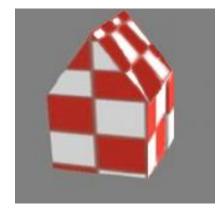
- Easy to use with simple orthographic projection
- Also used in environment maps





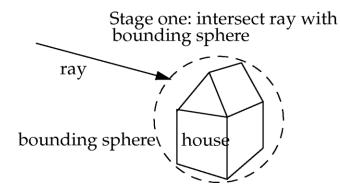
- Sometimes, reducing objects to primitives for texture mapping doesn't achieve the right result.
  - Consider a simple house shape as an example
  - If we texture map it using polygons, we get discontinuities at some edges.

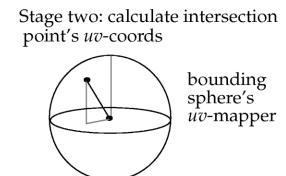




• Solution: Pretend object is a sphere and texture map using the sphere (u, v) map

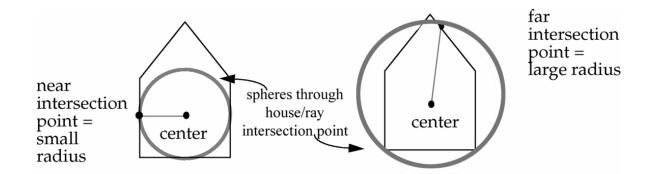
- Intuitive approach: Place a bounding sphere around the complex object
  - Find ray's object space intersection with bounding sphere
  - Convert to (u, v) coordinates





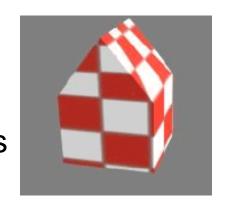
- We actually don't need a bounding sphere!
  - Once we have the intersection point with the object, we just treat it as though it were on a sphere passing through the point. Same results, but different radii.

 When we treat the object intersection point as a point on a sphere passing through the point, our "sphere" won't always have the same radius



- What radius to use?
  - Compute radius as distance from defined or computed center of complex object to the intersection point. Use that as the radius for the (u, v) mapping.

- Results of spherical (u, v) mapping on house:
- You can also use cylindrical or planar mappings when texture mapping complex objects



- Each has drawbacks
  - Spherical: warping at the "poles" of the object (the top of the house)
  - Cylindrical (not shown here): discontinuities at the caps
  - Planar: one axis is ignored

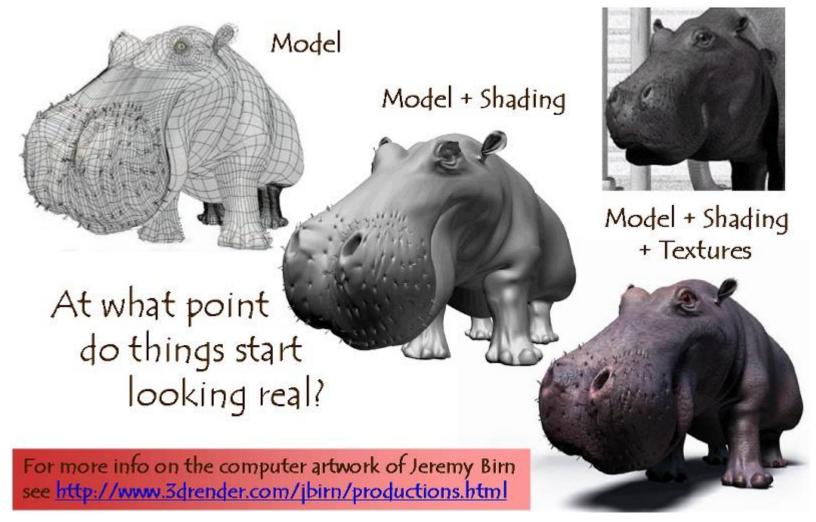
sphere mapped with spherical projection





sphere mapped with planar projection

# Combining texture mapping and shading



# Combining texture mapping and shading

- Final pixel color = a combination of texture color and color under standard OpenGL Phong lighting
- GL\_MODULATE: multiply texture and Phong lighting color
- GL\_BLEND:
   linear combination of texture and Phong lighting color
- GL\_REPLACE: use texture color only (ignore Phong lighting)
- Example: