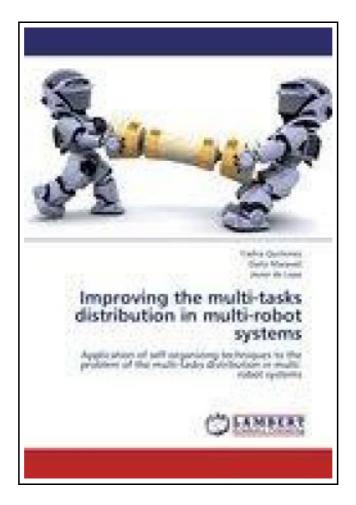
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## IMPROVING THE MULTI-TASKS DISTRIBUTION IN MULTI-ROBOT **SYSTEMS**



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