



# Approximation algorithms 3

## Vertex cover, TSP, k-center

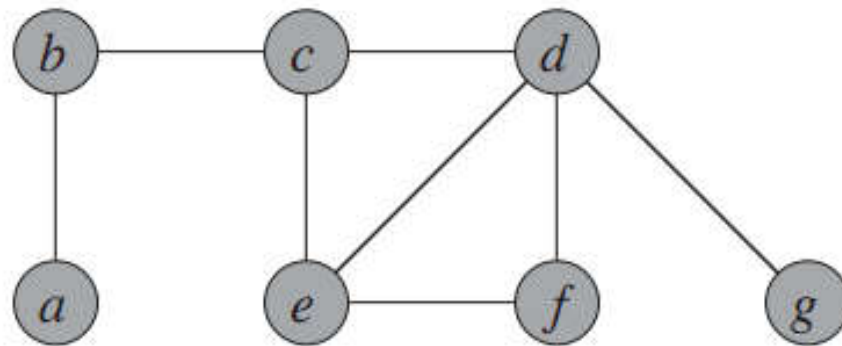
CS240

Spring 2020

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# Vertex cover

- **Input** A graph with vertices  $V$  and edges  $E$ .
- **Output** A subset  $V'$  of the vertices, so that every edge in  $E$  touches some vertex in  $V'$ .
- **Goal** Make  $|V'|$  as small as possible.



source: *Introduction to Algorithms*, Cormen et al.

- Finding the minimum vertex cover is NP-complete.
- Vertex cover is a special case of (unweighted) set cover, where each element (edge) can be covered by at most two sets (vertices).
- We'll see a simple 2 approximation for this problem.

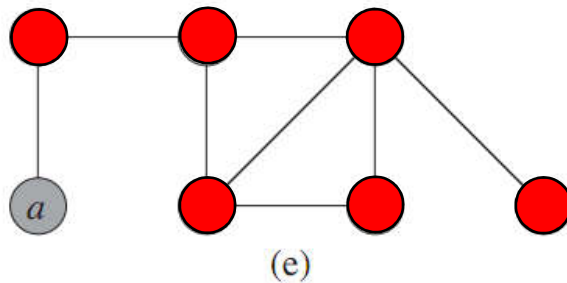
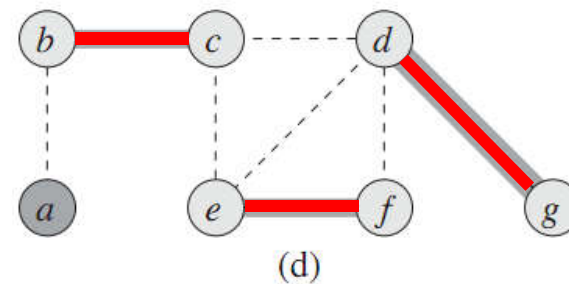
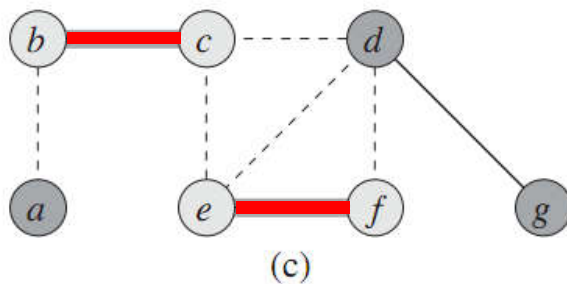
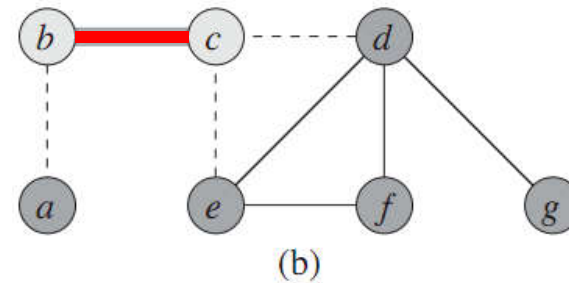
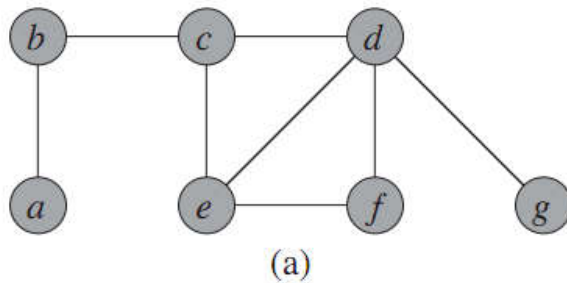


# A vertex cover algorithm

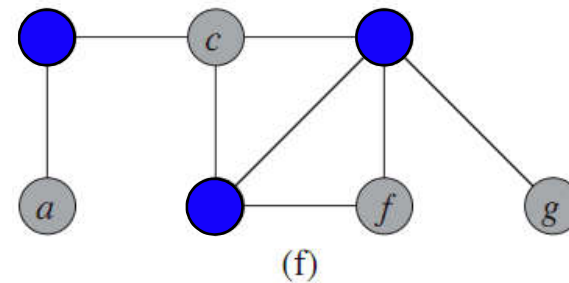
- Initially, let  $D$  be all the edges in the graph, and  $C$  be the empty set.
  - $C$  is our eventual vertex cover.
- Repeat as long as there are edge left in  $D$ .
  - Take any edge  $(u,v)$  in  $D$ .
  - Add  $\{u,v\}$  to  $C$ .
  - Remove all the edges adjacent to  $u$  or  $v$  from  $D$ .
- Output  $C$  as the vertex cover.

# Example

source: CLRS



Algorithm's vertex cover



Optimal vertex cover

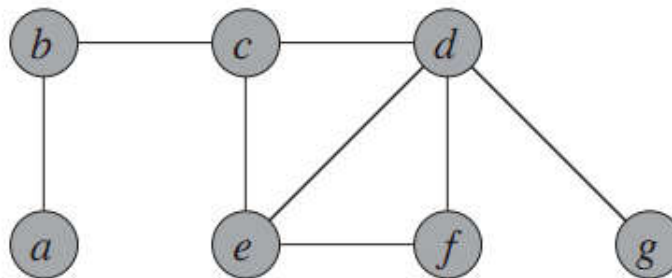


# Proof of correctness

- The output is certainly a vertex cover.
  - In each iteration, we only take out edges that get covered.
  - We keep adding vertices till all edges are covered.
- Now, we show it's a 2 approximation.
- Let  $C^*$  be an optimal vertex cover.
- Let  $A$  be the set of edges the algorithm picked.

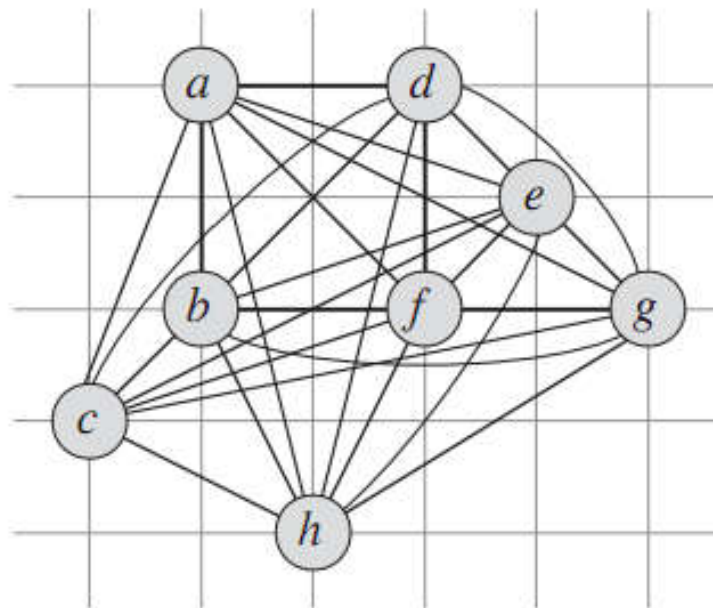
# Proof of Correctness

- None of the edges in  $A$  touch each other.
  - Each time we pick an edge, we remove all adjacent edges.
- So each vertex in  $C^*$  covers at most one edge in  $A$ .
  - The edges covered by a vertex all touch each other.
- Every edge in  $A$  is covered by a vertex in  $C^*$ .
  - Because  $C^*$  is a vertex cover.
- So  $|C^*| \geq |A|$ .
- The number of vertices the algorithm uses is  $2|A|$ .
  - If alg picks edge  $(u,v)$ , it uses  $\{u,v\}$  in the cover.
- So  $(\# \text{ vertices alg uses}) / (\# \text{ vertices in opt cover}) = 2|A| / |C^*| \leq 2|A| / |A| = 2$ .



# Traveling Salesman Problem

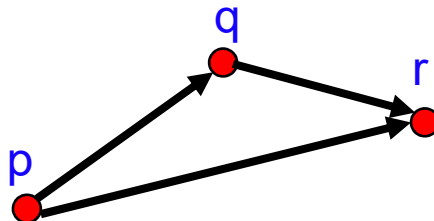
- **Input** A complete graph with weights on the edges.
- **Output** A cycle that visits each city once.
- **Goal** Find a cycle with minimum total weight.



source: CLRS

# Metric TSP

- TSP is NP-hard. In fact, it's even NP-hard to approximate when weights can be arbitrary.
- However, TSP is approximable for special types of weights.
- A weighted graph satisfies the triangle inequality if for any 3 vertices  $p, q, r$ , we have  $d_{pq} + d_{qr} \geq d_{pr}$ .
  - I.e., direct path is always no worse than a roundabout path.
  - This is called a metric TSP.
- There is a 1.5-approx algorithm for TSP in graphs with the triangle inequality.
  - Let's look at a simpler 2-approx first.





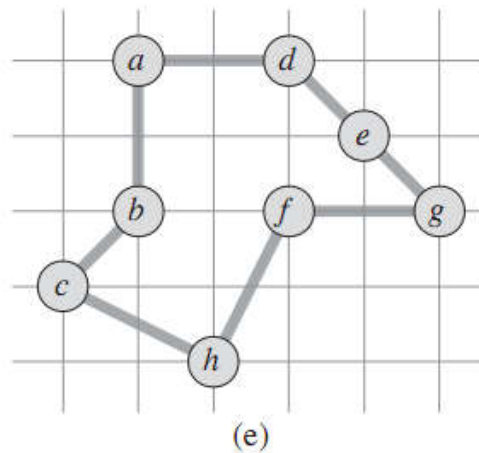
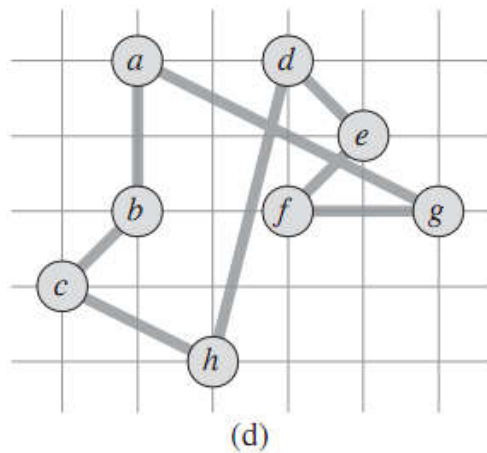
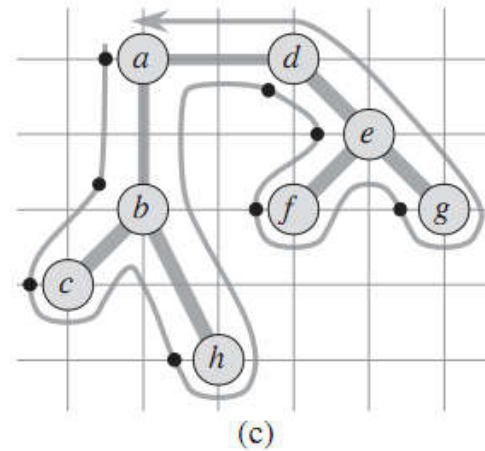
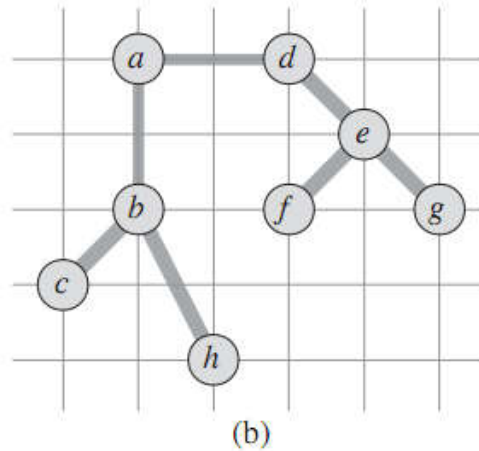
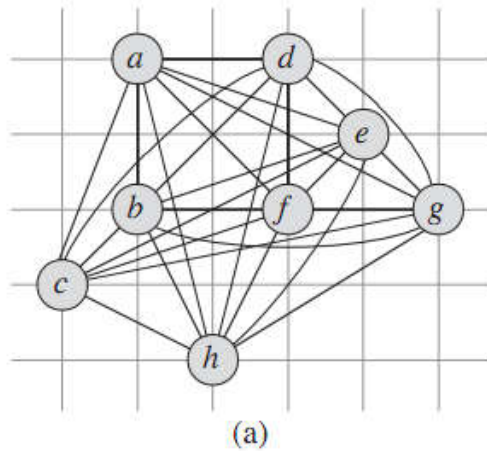


# A 2-approximation for TSP

- Construct a minimum spanning tree  $T$  on  $G$ .
- Use depth-first traversal to visit all the vertices in  $T$ , starting from an arbitrary vertex.
- Convert this depth-first traversal  $T'$  to a cycle  $H$  that doesn't revisit any vertex.
- Return  $H$  as the TSP tour.

# Example

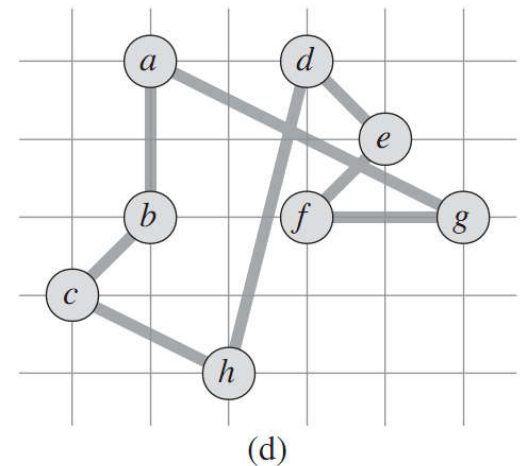
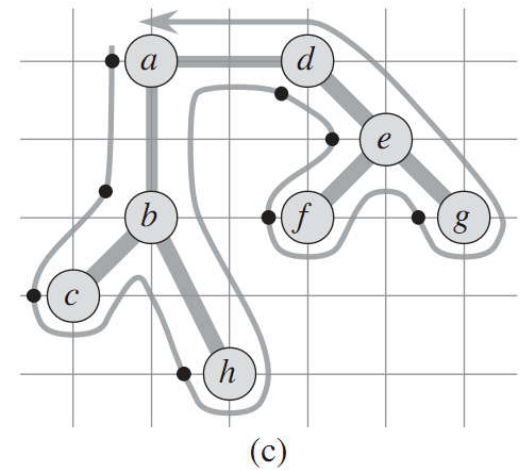
source: CLRS



- (b) The MST T.
- (c) visit T in order abcbhbadefegeda.
- (d) converts the tour from (c) to a Hamiltonian cycle, that doesn't revisit any vertices.
- (e) is the optimal TSP.

# Making the tour Hamiltonian

- To go from (c) to (d), we need to make a tour  $T'$  that revisits vertices into a cycle  $H$  that doesn't revisit vertices.
- We use shortcutting.
  - If we revisit a vertex in  $T'$ , we directly jump to the next vertex in  $T'$  we haven't visited.
    - We allow revisiting the first vertex.
  - The sequence of vertices we now visit is  $H$ .
  - Ex  $abc**h**ba**de**fed**a** \rightarrow abchdefga$ .





# Making the tour Hamiltonian

- **Lemma** If  $H$  is the shortcut of  $T'$ , then  $c(H) \leq c(T')$ .
- **Proof** We formed  $H$  from  $T'$  by skipping over some vertices. E.g. we directly went from  $c$  to  $h$ , skipping over  $b$ .
  - But by the triangle inequality,  $d_{cb} + d_{bh} \geq d_{ch}$ .
    - So shortcutting from  $c$  to  $h$  didn't increase the distance.
  - The same thing applies to all our shortcuts.
  - So  $H$  is no longer than  $T'$ .

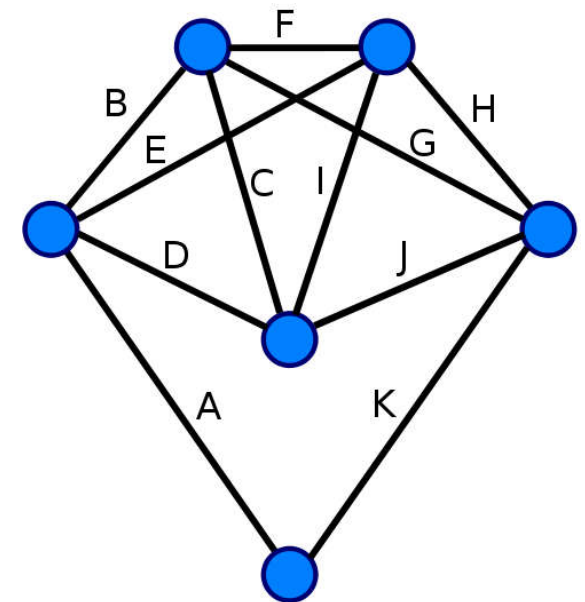
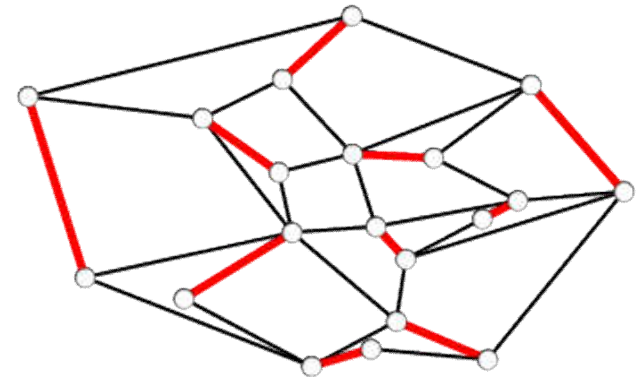


# Proof of 2-approximation

- Let  $H^*$  be an optimum TSP.
- If we delete an edge from  $H^*$ , we get a spanning tree.
- Since  $T$  is an MST,  $c(T) \leq c(H^*)$ .
- Call the path from the depth-first traversal  $T'$ .
  - $T'$  crosses each edge in  $T$  twice.
  - So  $c(T') = 2 c(T)$ .
- Let  $H$  be the outcome of shortcutting  $T'$ .
  - $H$  is a Hamiltonian cycle. It visits all the vertices, and ends where it started.
  - $c(H) \leq c(T')$ , by the lemma.
  - $c(H) \leq c(T') = 2 c(T) \leq 2 c(H^*)$ .
- So  $H$  is a 2-approximation.

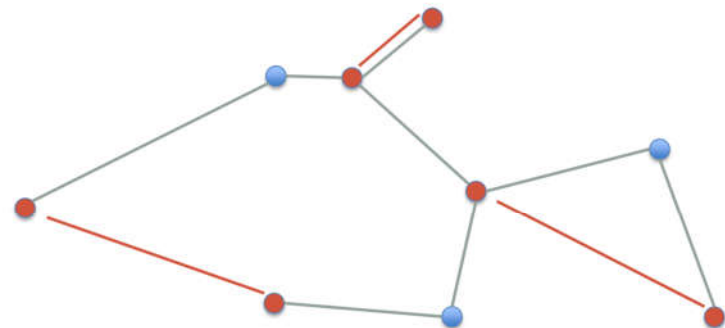
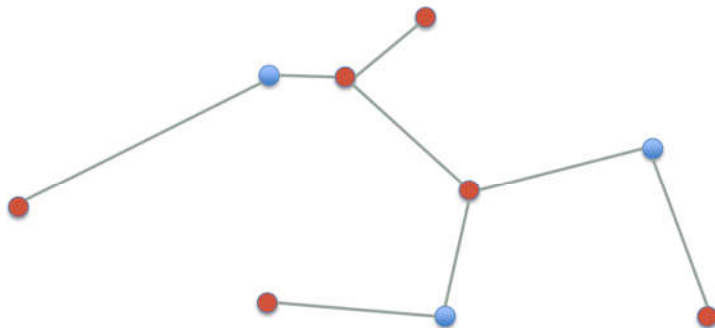
# Matchings and Euler cycles

- A matching in a graph is a set of nonintersecting edges.
  - A perfect matching is a matching that includes every vertex.
- An Euler tour of a graph is a path that starts and ends at the same vertex, and visits every edge once.
  - Hamiltonian tour visits every vertex once.
- Thm (Euler) A graph has an Euler tour if and only if all vertices have even degree.
- Note how deciding if graph has Euler tour is trivial, but deciding if it has Hamiltonian tour is NPC!



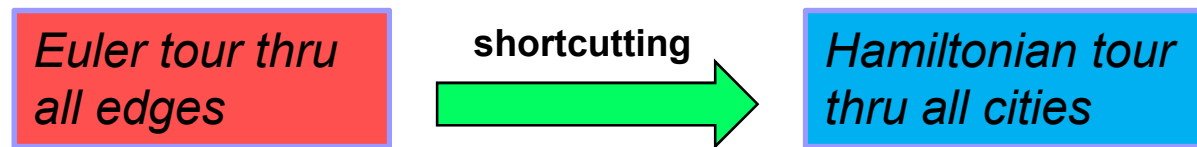
# Christofides 3/2-approx algorithm

- ❖ A 3/2-approximation for TSP with triangle inequality.
- Construct a minimum spanning tree  $T$  on  $G$ .
- Find the set  $V'$  of odd degree vertices in  $T$ .
- Construct a minimum cost perfect matching  $M$  on  $V'$ .
- Add  $M$  to  $T$  to obtain  $T'$ .
- Find an Euler tour  $T''$  in  $T'$ .
- Shortcut  $T''$  to obtain a Hamiltonian cycle  $H$ . Output as the TSP.



# Why Christofides works well

- In the 2-approx, we found a TSP by “doubling” the MST to an Euler tour, then shortcutting.
  - We need to start with Euler tour before shortcutting to ensure we visit all cities.



- Key to Christofides is to find a shorter Euler tour, without doubling the MST.
  - A graph with only even degree vertices always has Euler tour.
  - So we want to modify the MST to have all even degrees, by adding a matching.



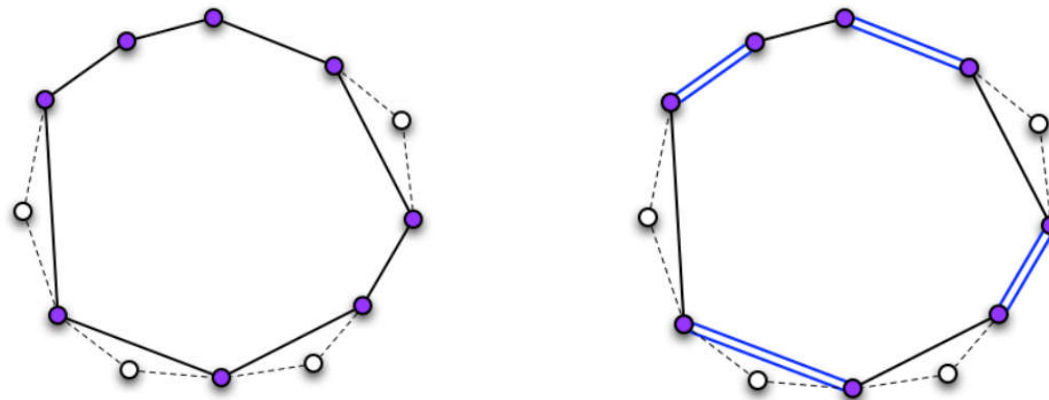


# Proof of correctness

- **Lemma**  $T'$  has an Euler tour.
- **Proof** There are an even number of vertices in  $V'$ , because the total degree of  $T$  is even.
  - Since  $G$  is a complete graph and  $|V'|$  is even, there's a perfect matching on  $V'$ .
    - The min cost perfect matching can be found in  $O(n^2)$  time using the blossom algorithm.
  - The degree of every node in  $M$  is odd. Since  $V'$  are the odd degree nodes in  $T$ , adding  $M$  to  $T$  makes all nodes in  $T'$  have even degree.
  - $T'$  has Euler tour by Euler's theorem.

# Proof of correctness

- **Lemma** Let  $H^*$  be an optimal TSP on  $G$ , and let  $m$  be the cost of  $M$ . Then  $m \leq c(H^*)/2$ .
- **Proof** Let  $H'$  be the optimal TSP on  $V'$ .
  - $c(H') \leq c(H^*)$  because  $H'$  is an optimal TSP on fewer vertices.
  - $H'$  is a cycle on  $V'$ , so it consists of two matchings on  $V'$ . The cheaper one has cost  $m' \leq c(H')/2 \leq c(H^*)/2$ .
  - $m \leq m'$  because  $M$  has min cost.



# Proof of 3/2-approximation

- **Thm** Let  $H$  be the TSP output by Christofides and let  $H^*$  be an optimal TSP. Then  $c(H) \leq 3/2 \cdot c(H^*)$ .

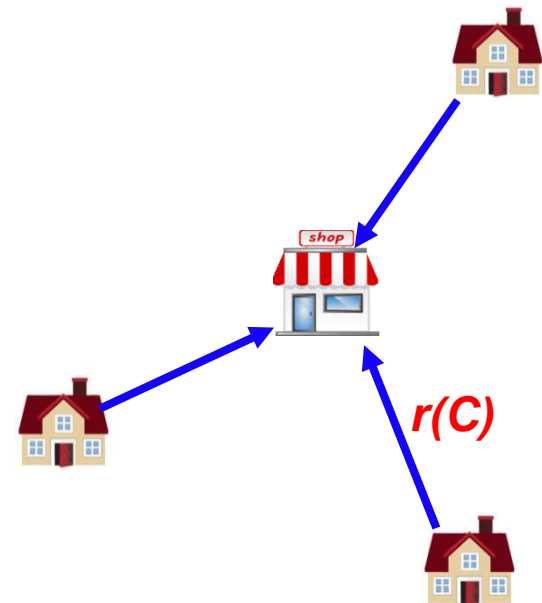
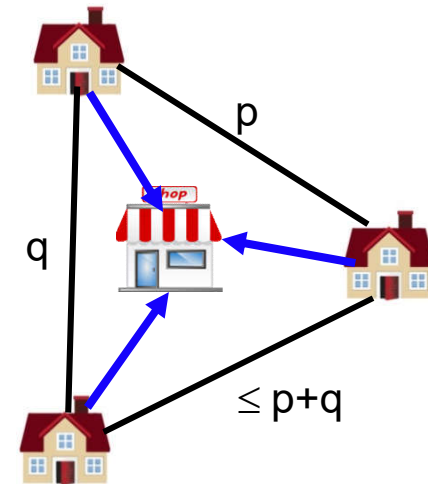
- **Proof**

- $c(T) \leq c(H^*)$  because  $T$  is an MST.
- $c(T') = c(M) + c(T) \leq c(H^*)/2 + c(H^*) = 3/2 \cdot c(H^*)$ .
- $c(H) \leq c(T')$  because  $H$  is the shortcut of  $T'$ .

- Construct a minimum spanning tree  $T$  on  $G$ .
- Find set  $V'$  of odd-degree vertices in  $T$ .
- Construct a minimum cost perfect matching  $M$  on  $V'$ .
- Add  $M$  to  $T$  to obtain  $T'$ .
- Shortcut  $T'$  to obtain a Hamiltonian cycle. Output as the TSP.

# k-Center problem

- Given a city with  $n$  sites, we want to build  $k$  centers to serve them.
  - Let  $S$  be set of sites,  $C$  be set of centers.
- Each site uses the center closest to it.
  - Distance of site  $s$  from the nearest center is  $d(s, C) = \min_{c \in C} d(s, c)$ .
- Goal is to make sure no site is too far from its center.
  - We want to minimize the max distance that any site is from its closest center.
    - Minimize  $r(C) = \max_{s \in S} \min_{c \in C} d(s, c)$ .
  - $C$  is called a cover of  $S$ , and  $r$  is called  $C$ 's radius.
  - Where should we put centers to minimize the radius?
- Assume distances satisfy triangle inequality.



# Gonzalez's algorithm

- k-Center is NP-complete.
- We'll give a simple 2-approximation for it.
- **Idea** Say there's one site that's farthest away from all centers. Then it makes the radius large. We'll put a center at that site, to reduce the radius.
  - Note we allow putting center at same location as site.



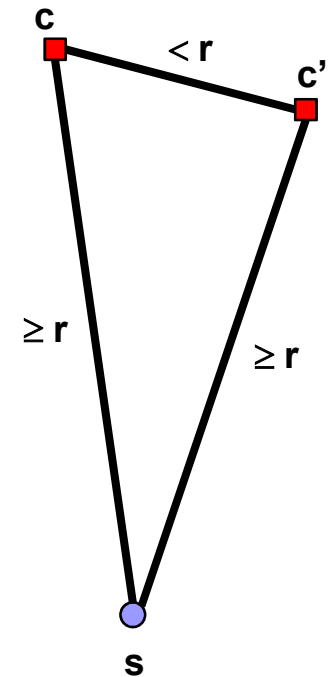


# Gonzalez's algorithm

- C is set of centers, initially empty.
- repeat k times
  - choose site s with maximum  $d(s, C)$
  - add s to C
- return C
- **Note** The centers are located at the sites.

# Proof of correctness

- Let  $C$  be the algorithm's output, and  $r$  be  $C$ 's radius.
  - $r = \max_{s \in S} \min_{c \in C} d(s, c)$
- **Lemma 1** For any  $c, c' \in C$ ,  $d(c, c') \geq r$ .
- **Proof** Since  $r$  is the radius, there exists a point  $s \in S$  at distance  $\geq r$  from all the centers.
  - If there's no such  $s$ , then  $C$ 's radius  $< r$ .
  - So  $s$  is distance  $\geq r$  from  $c$  and  $c'$ .
  - Suppose WLOG  $c'$  is added to  $C$  after  $c$ .
  - If  $d(c, c') < r$ , then algorithm would add  $s$  to  $C$  instead of  $c'$ , since  $s$  is farther.





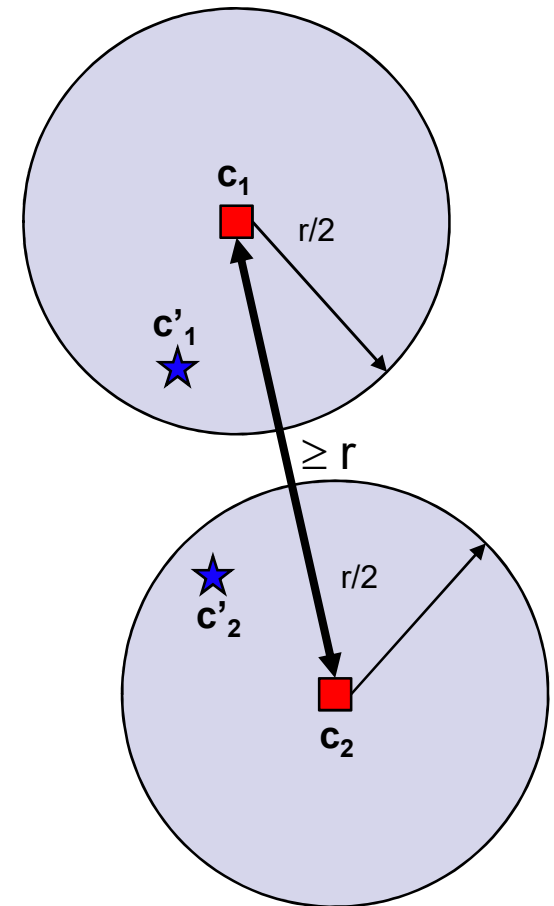
# Proof of correctness

- **Cor** There exist  $k+1$  points mutually at distance  $\geq r$  from each other.
  - By the lemma, the  $k$  centers are mutually  $\geq r$  distance apart.
  - Also, there's an  $s \in S$  at distance  $\geq r$  from all the centers.
    - Otherwise  $C$ 's covering radius is  $< r$ .
  - So the  $k$  centers plus  $s$  are the  $k+1$  points.
- Call these  $k+1$  points  $D$ .



# Proof of correctness

- Let  $C^*$  be an optimal cover with radius  $r^*$ .
- **Lemma 2** Suppose  $r > 2r^*$ . Then for every  $c \in D$ , there exists a corresponding  $c' \in C^*$ . Furthermore, all these  $c'$  are unique.
- **Proof** Draw a circle of radius  $r/2$  around each  $c \in D$ .
  - There must be a  $c' \in C^*$  inside the circle, because
    - $c$  is at most distance  $r^*$  away from its nearest center, since  $r^*$  is  $C^*$ 's radius.
    - $r/2 > r^*$ .
  - Given  $c_1, c_2 \in D$ , let  $c'_1, c'_2 \in C^*$  be inside  $c_1$  and  $c_2$ 's circle, resp.
  - $c_1$  and  $c_2$ 's circles don't touch, because  $d(c_1, c_2) \geq r$ .
  - So  $c'_1 \neq c'_2$ .





# Proof of correctness

- **Thm** Let  $C$  be the output of Gonzalez's algorithm, and let  $C^*$  be an optimal  $k$ -center. Then  $r(C) \leq 2r(C^*)$ .
- **Proof** By Lemma 2, if  $r(C) > 2r(C^*)$ , then for every  $c \in D$ , there is a unique  $c' \in C^*$ .
  - But there are  $k+1$  points in  $D$ , by the corollary.
  - So there are  $k+1$  points in  $C^*$ . This is a contradiction because  $C^*$  is a  $k$ -center.