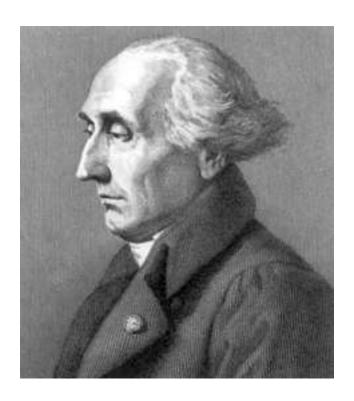
MATH673 - Partial Differential equations I



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1 Homeworks

1.1 Homework1

Problem . 2.5.3 Define

$$\phi(r) := rac{1}{|\partial B(0,r)|} \int_{\partial B(0,r)} u(x) dS + \int_{B(0,r)} \Phi(x) f(x) dx - \Phi(r) \int_{B(0,r)} f(x) dx$$

Where
$$\Phi(x) = \frac{1}{n(n-2)|B(0,1)|} \frac{1}{|x|^{n-2}}$$
, then

$$\begin{split} \phi'(r) &= \frac{r}{n} \frac{1}{|B(0,r)|} \int_{B(0,r)} \Delta u(x) dx + \int_{\partial B(0,r)} \Phi(x) f(x) dS \\ &- \Phi'(r) \int_{B(0,r)} f(x) dx - \Phi(r) \int_{\partial B(0,r)} f(x) dS \\ &= -\frac{r}{n} \frac{1}{|B(0,r)|} \int_{B(0,r)} f(x) dx + \frac{r}{n} \frac{1}{|B(0,r)|} \int_{B(0,r)} f(x) dx \\ &+ \int_{\partial B(0,r)} (\Phi(x) - \Phi(r)) f(x) dS \\ &= 0 \end{split}$$

$$egin{aligned} \phi(s) &= u(0) + rac{1}{|\partial B(0,s)|} \int_{\partial B(0,s)} \left(u(x) - u(0)
ight) dS + \int_{B(0,s)} \Phi(x) f(x) dx - \Phi(s) \int_{B(0,s)} f(x) dx \ &:= u(0) + I_1 + I_2 + I_3 \end{aligned}$$

$$|I_1| \leq rac{1}{|\partial B(0,s)|} \int_{\partial B(0,s)} |u(x)-u(0)| \, dS
ightarrow 0, \ s
ightarrow 0$$

By the continuity of u

$$|I_2| \leq \|f\|_{L^\infty} \int_{B(0,s)} \Phi(x) dx = \|f\|_{L^\infty} \int_{B(0,s)} \Phi(x) dx = rac{s^2 \|f\|_{L^\infty}}{2(n-2)} o 0, \ s o 0$$

$$|I_3| \leq \Phi(s) \, \|f\|_{L^\infty} \int_{B(0,s)} dx = \|f\|_{L^\infty} \int_{B(0,s)} \Phi(x) dx = rac{s^2 \, \|f\|_{L^\infty}}{n(n-2)} o 0, \, s o 0$$

Thus

$$egin{aligned} u(0) &= \lim_{s o 0} \phi(s) = \lim_{s o r} \phi(s) \ &= rac{1}{|\partial B(0,r)|} \int_{\partial B(0,r)} g(x) dS + \int_{B(0,r)} \left(\Phi(x) - \Phi(r)
ight) f(x) dx \end{aligned}$$

Problem . 2.5.4 a)

Since

$$\left\{rac{d}{dr}\left\{rac{1}{|\partial B(x,r)|}\int_{\partial B(x,r)}v(y)dS
ight\}=rac{r}{n}rac{1}{|B(x,r)|}\int_{B(x,r)}\Delta v(y)dy\geq 0$$

Thus

$$v(x) \leq rac{1}{|\partial B(x,r)|} \int_{\partial B(x,r)} v(y) dS$$

and

$$egin{aligned} rac{1}{|B(x,r)|}\int_{B(x,r)}v(y)dy&=rac{1}{|B(x,r)|}\int_0^r\left(\int_{\partial B(x,s)}v(y)dS
ight)ds\ &\geq v(x)rac{1}{|B(x,r)|}\int_0^r|\partial B(x,s)|ds\ &=v(x)\end{aligned}$$

b) Suppose v attains at $x_0 \in U$ its maximum $\max_{\overline{U}} v > \max_{\partial U} v$, consider the connected component U_0 which contains x_0 , then by a) we know that the set $\{x \in U_0 \ v(x) = \max_{\overline{U}} v\}$ is both open and closed, thus $\max_{\partial U_0} v = \max_{\overline{U}} v$ which is a contradiction.

c)

Since ϕ is convex, $\phi''(x) \geq 0$, thus

$$\Delta v(x) = \Delta \phi(u(x)) = \phi'(u(x))\Delta u + \phi''(u(x))|\nabla u|^2 = \phi''(u(x))|\nabla u|^2 \ge 0$$

Hence v is subharmonic.

d)

$$\Delta v = \Delta |\nabla u|^2 = 2 \sum_{i,j} u_{x_i x_j}^2 + 2 \nabla u \cdot \nabla (\Delta u) \geq 0$$

By a) we know v is subharmonic

Problem . 2.5.5 Define $M:=\max_{B(0,1)}|f|$ and $v:=u+\frac{M}{2n}|x|^2$, then we have $\Delta v=\Delta u+M=M-f\geq 0$ in $B^0(0,1)$, thus v is subharmonic, maximum principle still holds, hence

$$\max_{B(0,1)} u \leq \max_{B(0,1)} v = \max_{\partial B(0,1)} v \leq \max_{\partial B(0,1)} |g| + \frac{M}{2n} = \max_{B(0,1)} |v| \leq \max_{\partial B(0,1)} |g| + \frac{1}{2n} \max_{B(0,1)} |f|$$

Similary, we could consider $\begin{cases} -\Delta(-u) = -f \\ -u = -g \end{cases}$, then we would have

$$-\min_{B(0,1)} u = \max_{B(0,1)} (-u) \le \max_{\partial B(0,1)} |g| + rac{1}{2n} \max_{B(0,1)} |f|$$

Therefore, we have

$$\max_{B(0,1)} |u| \le \max_{\partial B(0,1)} |g| + \frac{1}{2n} \max_{B(0,1)} |f| \le \max_{\partial B(0,1)} |g| + \max_{B(0,1)} |f|$$

Problem . 2.5.6 Using Poisson's formula and the fact that u is harmonic, we have

$$\begin{split} u(x) &= \frac{r^2 - |x|^2}{|\partial B(0,1)|r} \int_{\partial B(0,r)} \frac{u(y)}{|x-y|^n} dS \\ &\leq \frac{r^2 - |x|^2}{|\partial B(0,1)|r} \int_{\partial B(0,r)} \frac{u(y)}{(r-|x|)^n} dS \\ &= \frac{r^2 - |x|^2}{|\partial B(0,1)|r} \frac{1}{(r-|x|)^n} \int_{\partial B(0,r)} u(y) dS \\ &= \frac{r^{n-2}(r+|x|)}{(r-|x|)^{n-1}} u(0) \end{split}$$

Similarly, we have

$$\begin{split} u(x) &= \frac{r^2 - |x|^2}{|\partial B(0,1)|r} \int_{\partial B(0,r)} \frac{u(y)}{|x-y|^n} dS \\ &\geq \frac{r^2 - |x|^2}{|\partial B(0,1)|r} \int_{\partial B(0,r)} \frac{u(y)}{(r+|x|)^n} dS \\ &= \frac{r^2 - |x|^2}{|\partial B(0,1)|r} \frac{1}{(r+|x|)^n} \int_{\partial B(0,r)} u(y) dS \\ &= \frac{r^{n-2}(r-|x|)}{(r+|x|)^{n-1}} u(0) \end{split}$$

Thus
$$rac{r^{n-2}(r-|x|)}{(r+|x|)^{n-1}}u(0) \leq u(x) \leq rac{r^{n-2}(r+|x|)}{(r-|x|)^{n-1}}u(0)$$

Problem . 2.5.7 Since $K(x, y) \in C^{\infty}(B^0(0, 1))$, thus

$$u(x):=\int_{\partial B(0,r)}K(x,y)g(y)dS(y)\in C^{\infty}(B^0(0,1))$$

Also.

$$\Delta u(x) = \int_{\partial B(0,r)} \Delta_x K(x,y) g(y) dS(y) = 0$$

Since $\Delta_x K(x,y) = 0$, when $y \in \partial B(0,r)$

By taking $u \equiv 1$ we get $\int_{\partial B(0,r)} K(x,y) dS(y) = 1$ Since $g \in C(\partial B(0,r)), |g| \leq M$ for some M > 0, and $\forall \epsilon > 0, \exists \delta > 0$, such that $|g(y) - g(x^0)| \leq M$ $\epsilon, orall y \in \partial B(0,r) \cap B(x^0,\delta), ext{ hence, when } |x-x^0| < rac{\delta}{2}, ext{ we have } |x-y| \geq |x^0-y| - |x-x^0| > 1$ $\frac{\delta}{2}$, $\forall y \in \partial B(0,r) - B(x^0,\delta)$, hence

$$\begin{split} \left|u(x)-g(x^0)\right| &= \left|\int_{\partial B(0,r)} K(x,y) \left(g(y)-g(x^0)\right) dS(y)\right| \\ &\leq \left|\int_{\partial B(0,r)\cap B(x^0,\delta)} K(x,y) \left(g(y)-g(x^0)\right) dS(y)\right| \\ &+ \left|\int_{\partial B(0,r)-B(x^0,\delta)} K(x,y) \left(g(y)-g(x^0)\right) dS(y)\right| \\ &\leq \epsilon \int_{\partial B(0,r)\cap B(x^0,\delta)} K(x,y) dS(y) + 2M \int_{\partial B(0,r)-B(x^0,\delta)} K(x,y) dS(y) \\ &\leq \epsilon \int_{\partial B(0,r)} K(x,y) dS(y) + \frac{2M \left(r^2-|x|^2\right)}{|\partial B(0,1)|r} \int_{\partial B(0,r)} \frac{2^n}{\delta^n} dS(y) \\ &= \epsilon + \frac{2^{n+1} M r^{n-2} \left(r^2-|x|^2\right)}{\delta^n} \end{split}$$

Thus $\lim_{\substack{x \to x^0 \\ x \in B^0(0,r)}} u(x) = g(x^0)$

Problem . 1[January 2010] a)

Suppose u, u_1 are two bounded solution, then $\forall \epsilon > 0, \exists R > 0$, such that $\forall r > R$

$$|u(x) - \epsilon \ln |x| \le u_1(x) \le u(x) + \epsilon \ln |x|$$

on $\partial B(0,r)$, using maximum principle for $u(x) - \epsilon \ln |x| - u_1(x)$ and $u_1(x) - u(x) - \epsilon \ln |x|$ on $B(0,r)-B^{0}(0,1)$

Thus the inequality above holds for any $\epsilon > 0$ and |x| > 1, let $\epsilon \to 0$, we have $u = u_1$

 $u \equiv 1$ and $u(x) = \frac{1}{|x|}$ are both bounded solutions with $f \equiv 1$

One additional condition that ascertain the uniqueness of the solution could be $\lim_{x\to\infty} u(x) = 0$, in this case we would have

$$u(x) - \epsilon \le u_1(x) \le u(x) + \epsilon$$

On $\partial B(0,r)$ for sufficiently large r

Problem . 1[January 2005] **Lemma:** If $g = \sum_{k=0}^{\infty} a_k z^k$ is a holomorphic function on \mathbb{C} , then

$$\int \int_{B(0,R)} |f'(z)|^2 dx dy = \sum_{k=0}^{\infty} |a_k|^2 rac{\pi R^{2k+2}}{k+1}$$

Proof: Using the fact that

$$\int\int_{B\left(0,R
ight)}z^{k}\overline{z}^{l}dxdy=egin{cases}rac{\pi R^{2k+2}}{k+1},\ k=l\ 0,\ k
eq l \end{cases}$$

Method 1:

Since u is harmonic on \mathbb{R}^2 , there exists a holomorphic function f on \mathbb{C} , such that $\operatorname{Re} f = u$, then $|\nabla u| = |f'|$, hence we have $\int \int_{\mathbb{R}^2} |\nabla u|^2 dx dy = \int \int_{\mathbb{C}} |f'(z)|^2 dx dy < \infty$, according to the lemma above, we have $f' \equiv 0$, hence f is a constant, so is u

Method 2:

According to 2.5.4 d), we know that $|\nabla u|^2$ is subharmonic, thus

$$|
abla u(x)|^2 \leq rac{1}{|B(x,r)|} \int_{B(x,r)} |
abla u(y)|^2 dy \leq rac{1}{|B(x,r)|} \int_{\mathbb{R}^2} |
abla u(y)|^2 dy$$

Which tends to 0 as r tends to 0, thus $\nabla u \equiv 0$, u is a constant

Problem. 1[August 2004] Assume $f \not\equiv 0$, since $f \in C^1(\mathbb{R}^n)$, there is some $B(x, \epsilon)$, such that f is positive(negative) on it, consider $v \equiv 1$, then we have

$$\begin{split} 0 &= \int_{\partial B(x,\epsilon)} v \frac{\partial u}{\partial n} dS = \int_{B(x,\epsilon)} v \Delta u dx + \int_{B(x,\epsilon)} \nabla v \cdot \nabla u dx \\ &= \int_{B(x,\epsilon)} \nabla v \cdot \nabla u dx - \int_{B(x,\epsilon)} v f dx \\ &= -\int_{B(x,\epsilon)} f dx < (>)0 \end{split}$$

Which is a contradiction, Thus $f \equiv 0$

1.2 Homework2

We have $u_t = -\frac{x}{2t^{\frac{3}{2}}}v'$ and $u_{xx} = \frac{1}{t}v''$, thus $u_t - u_{xx} = 0 \Leftrightarrow -\frac{x}{2t^{\frac{3}{2}}}v' - \frac{1}{t}v'' = 0 \Leftrightarrow v'' + \frac{z}{2}v' = 0$ Multiply $e^{\frac{z^2}{4}}$ on both sides, we get $e^{\frac{z^2}{4}}v'' + \frac{ze^{\frac{z^2}{4}}}{2}v' = \left(e^{\frac{z^2}{4}}v'\right)' = 0$, Thus $e^{\frac{z^2}{4}}v' = c$ for some constant c, $v' = ce^{-\frac{z^2}{4}} \Rightarrow v = c \int_{-\infty}^{z} e^{-\frac{s^2}{4}} ds + d$ for some other constant d

According to (a), we have $u(x,t) = c \int_0^{\frac{x}{\sqrt{t}}} e^{-\frac{s^2}{4}} ds + d$, thus $u_x = \frac{c}{\sqrt{t}} e^{-\frac{x^2}{4t}}$, which again solve the heat equation, in order to obtain a fundamental solution, we also need $\lim_{t\downarrow 0} u_x(x,t) =$ $u_x(x,0)=\delta_0$, thus we should have $1=\int_{\mathbb{D}}u_x(x,0)dx=\int_{\mathbb{D}}\lim_{t\downarrow 0}u_x(x,t)dx=\lim_{t\downarrow 0}\int_{\mathbb{D}}u_x(x,t)dx=$ $\lim_{t \to 0} \int_{\mathbb{T}} \frac{c}{\sqrt{t}} e^{-\frac{x^2}{4t}} dx = 2c\sqrt{\pi} \Rightarrow c = \frac{1}{\sqrt{4\pi}}$

Problem. 2.5.14 Consider $v = ue^{ct}$, we have $v_t - \Delta v = e^{ct} (u_t - \Delta u + cu)$, thus the initial value problem becomes

$$\begin{cases} v_t - \Delta v = f e^{ct}, & \text{in } \mathbb{R}^n \times (0, \infty) \\ v = g, & \text{on } \mathbb{R}^n \times \{t = 0\} \end{cases}$$

Solve it to get

$$v(x,t) = \int_{\mathbb{R}^n} \Phi(x-y,t) g(y) dy + \int_0^t \int_{\mathbb{R}^n} \Phi(x-y,t-s) f(y,s) e^{cs} dy ds$$

Thus

$$u(x,t)=\int_{\mathbb{D}^n}\Phi(x-y,t)g(y)e^{-ct}dy+\int_0^t\int_{\mathbb{D}^n}\Phi(x-y,t-s)f(y,s)e^{-c(t-s)}dyds$$

Problem . January 2013, Problem 4 (a)
Since
$$u(x,t) = \int_0^x u_x(y,t)dy + u(0,t) = \int_0^x u_x(y,t)dy$$

$$|u(x,t)|^2 = \left|\int_0^x u_x(y,t)dy
ight|^2 \leq \left(\int_0^1 |u_x(y,t)|dy
ight)^2 \leq \left(\int_0^1 |u_x(y,t)|^2 dy
ight) \left(\int_0^1 1^2 dy
ight) = \int_0^1 |u_x(y,t)|^2 dy$$

Hence $\sup_{x} |u(x,t)|^2 \le \int_0^1 |u_x(y,t)|^2 dy$ Then we have

$$egin{aligned} \int_0^1 u^3 dx & \leq \int_0^1 |u^3| dx \leq \left(\int_0^1 |u_x|^2 dx
ight) \int_0^1 |u| dx \ & \leq \left(\int_0^1 |u_x|^2 dx
ight) \left(\int_0^1 |u|^2 dx
ight)^{rac{1}{2}} \left(\int_0^1 1^2 dy
ight)^{rac{1}{2}} \ & = \left(\int_0^1 |u_x|^2 dx
ight) \left(\int_0^1 |u|^2 dx
ight)^{rac{1}{2}} \end{aligned}$$

Since u is smooth, we have

$$\begin{split} \frac{d}{dt} \int_0^1 |u|^2 dx &= \int_0^1 \frac{d}{dt} u^2 dx = \int_0^1 2u u_t dx = 2 \int_0^1 u (u_{xx} + c u^2) dx \\ &= 2u u_{xx}|_0^1 - 2 \int_0^1 |u_x|^2 dx + 2c \int_0^1 u^3 dx \\ &\leq -2 \int_0^1 |u_x|^2 dx + 2c \left(\int_0^1 |u_x|^2 dx \right) \left(\int_0^1 |u|^2 dx \right)^{\frac{1}{2}} \\ &= -2 \left(\int_0^1 |u_x|^2 dx \right) \left(1 - c \left(\int_0^1 |u|^2 dx \right)^{\frac{1}{2}} \right) \end{split}$$

(b)

Since u is smooth, so is $F(t) := \left(\int_0^1 |u|^2 dx\right)^{\frac{1}{2}}$, suppose $\exists t_0 \in (0, \infty)$ such that $F(t_0) \ge \frac{1}{c^2}$, then $\varnothing \ne S := \left\{t \in [0, t_0] \mid F(t) = \frac{1}{c^2}\right\}$ is closed, let $0 < t_1 = \min_{t \in S} t$, then we have $F(t_1) = \frac{1}{c^2}$ and $F(t) < \frac{1}{c^2}$ for $t \in [0, t_1)$, using intermediate value theorem, we have $0 < F(t_1) - F(0) = F'(\xi)t_1$, where $\xi \in (0, t_1)$, but according to (a), we have $F'(\xi) \le -2\left(\int_0^1 |u_x|^2 dx\right)\left(1 - cF(\xi)^{\frac{1}{2}}\right) \le 0$ which leads to a contradiction

Problem . January 2012, Problem 2 (a)

This is equivalent to solve ODE
$$\begin{cases} w' + w^3 = 0, t > 0 \\ w(0) = c \end{cases}$$
, thus $w(t) = \frac{1}{\sqrt{2t + \frac{1}{c^2}}}$

(b)

Assume otherwise, then $\exists (t_0, x_0) \in (0, \infty) \times (0, 1)$ such that $(w - u)(t_0, x_0) < 0$, suppose w - u must attain the minimum of $[0, t_0] \times [0, 1]$ at (t_1, x_1) , then $(w - u)(t_1, x_1) < 0$, thus $0 \le w(t_1.x_1) < u(t_1.x_1)$, hence $w^3(t_1.x_1) < u^3(t_1.x_1)$, then we would have $0 < u^3(t_1.x_1) - w^3(t_1.x_1) = (\frac{\partial}{\partial t} - \Delta)(w - u)(t_1, x_1) \ge 0$ which is a contradiction, hence $u(t, x) \le \frac{1}{\sqrt{2t + \frac{1}{c^2}}}$ on $[0, \infty) \times [0, 1]$

Problem . August 2011, Problem 3 (a)

Assume $\exists (x_0, t_0) \in \Omega \times (0, \infty)$ such that $u(x_0, t_0) < 0$, suppose $u(x_1, t_1) = \min_{\bar{\Omega}_{t_0}} u < 0$, since $|f'| \leq K$, $f(x) = \int_0^x f' dy \leq \int_0^x K dy = Kx$ if $x \geq 0$, or $f(x) \geq Kx$ if x < 0 let $K_1 > K$, then $0 \geq \left(\frac{\partial}{\partial t} - \Delta\right) \left(ue^{-K_1 t}\right) = e^{-K_1 t} \left[\left(\frac{\partial}{\partial t} - \Delta\right) u - K_1 u\right] = e^{-K_1 t} \left[f(u) - K_1 u\right] = e^{-K_1 t} \int_u^0 \left[K_1 - f'\right] dx > 0$ at (x_1, t_1) which is a contradiction (b)

Assume $\exists (x_0, t_0) \in \Omega \times (0, \infty)$ such that $u(x_0, t_0) > Me^{Kt_0} \Rightarrow u(x_0, t_0)e^{-K_1t_0} > M$ for some $K_1 > K$, suppose $u(x_1, t_1)e^{-K_1t_1} = \max_{\bar{\Omega}_{t_0}} ue^{-K_1t} > 0$

$$0 \le \left(\frac{\partial}{\partial t} - \Delta\right) \left(ue^{-K_1t}\right) = e^{-K_1t} \left[f(u) - K_1u\right] = e^{-K_1t} \int_0^u \left[f' - K_1\right] dx < 0 \text{ at } (x_1, t_1) \text{ which is a contradiction}$$

Problem. August 2005, Problem 6 Suppose |f'| < K, u, w are both solutions, then $(u-w)e^{Kt} = 0$ on $\Omega \times \{0\} \cup \partial\Omega \times (0,\infty)$, Assume $\exists (x_0,t_0) \in \Omega \times (0,\infty)$ such that $(u-w)(x_0,t_0)e^{Kt_0} < 0$, suppose $(u-w)(x_1,t_1)e^{-Kt_1} = \min_{\Omega_{t_0}}(u-w)e^{Kt} < 0$, the we have $0 \ge \left(\frac{\partial}{\partial t} - \Delta\right) \left((u-w)e^{Kt}\right) = e^{-Kt} \left[\left(f(w) - f(u)\right) + K(u-w)\right] = e^{-Kt} \int_u^w \left[f' + K\right] dx > 0$ at (x_1,t_1) , which is a contradiction

Problem. 2.5.15 Define v(x,t) = u(x,t) - g(t) on $x \ge 0$, extend v to $\{x < 0\}$ by odd reflection, then we have v(x,t) = -v(-x,t) on x < 0, thus the initial boundary problem becomes

$$\begin{cases} v_t - v_{xx} = -g'(t), & \text{in } \mathbb{R}_+ \times (0, \infty) \\ v_t - v_{xx} = g'(t), & \text{in } \mathbb{R}_- \times (0, \infty) \\ v = 0, & \text{on } \mathbb{R}_+ \times \{t = 0\} \\ v = 0, & \text{on } \{x = 0\} \times [0, \infty) \end{cases}$$

Define
$$f(x,t) = \begin{cases} -g'(t), & x \ge 0 \\ g'(t), & x < 0 \end{cases}$$
, we have

$$\begin{split} v(x,t) &= \int_0^t \frac{1}{\sqrt{4\pi(t-s)}} \int_{\mathbb{R}} e^{-\frac{(x-y)^2}{4(t-s)}} f(y,s) dy ds \\ &= \int_0^t \frac{1}{\sqrt{4\pi(t-s)}} \left(\int_{-\infty}^0 e^{-\frac{(x-y)^2}{4(t-s)}} g'(s) dy - \int_0^\infty e^{-\frac{(x-y)^2}{4(t-s)}} g'(s) dy \right) ds \\ &= \frac{1}{\sqrt{\pi}} \int_0^t \left(\int_{-\infty}^{-\frac{x}{\sqrt{4(t-s)}}} e^{-y^2} dy - \int_{-\frac{x}{\sqrt{4(t-s)}}}^\infty e^{-y^2} dy \right) g'(s) ds \\ &= \frac{1}{\sqrt{\pi}} g(s) \left(\int_{-\infty}^{-\frac{x}{\sqrt{4(t-s)}}} e^{-y^2} dy - \int_{-\frac{x}{\sqrt{4(t-s)}}}^\infty e^{-y^2} dy \right) \Big|_0^t + \frac{x}{\sqrt{4\pi}} \int_0^t \frac{1}{((t-s))^{\frac{3}{2}}} e^{-\frac{x^2}{4(t-s)}} g(s) ds \\ &= -\mathrm{sgn}(x) \frac{1}{\sqrt{\pi}} g(t) \int_{-\infty}^\infty e^{-y^2} dy - \frac{x}{\sqrt{4\pi}} \int_0^t \frac{1}{((t-s))^{\frac{3}{2}}} e^{-\frac{x^2}{4(t-s)}} g(s) ds \\ &= -\mathrm{sgn}(x) g(t) - \frac{x}{\sqrt{4\pi}} \int_0^t \frac{1}{((t-s))^{\frac{3}{2}}} e^{-\frac{x^2}{4(t-s)}} g(s) ds \end{split}$$

Where
$$\operatorname{sgn}(x) = \begin{cases} -1, \ x < 0 \\ 0, \ x = 0 \\ 1, \ x > 0 \end{cases}$$
, thus $u(x,t) = \frac{x}{\sqrt{4\pi}} \int_0^t \frac{1}{((t-s))^{\frac{3}{2}}} e^{-\frac{x^2}{4(t-s)}} g(s) ds$ is the solution

Problem . 2.5.17 a)

Define
$$\phi(r):=rac{1}{4r^n}\int\int_{E(0,0;r)}v(y,s)rac{|y|^2}{s^2}dyds$$
, then

$$egin{align} \phi'(r) &= rac{1}{r^{n+1}} \int \int_{E(0,0;r)} -n v_s \psi - rac{n}{2s} \sum_{i=1}^n v_{y_i} y_i dy ds \ &\geq rac{1}{r^{n+1}} \int \int_{E(0,0;r)} -n \Delta v \psi - rac{n}{2s} \sum_{i=1}^n v_{y_i} y_i dy ds \ &= 0 \end{aligned}$$

Since
$$\phi(r) = v(0,0) + \frac{1}{4r^n} \int \int_{E(0,0;r)} (v(y,s) - v(0,0)) \frac{|y|^2}{s^2} dy ds \rightarrow v(0,0), r \rightarrow 0, v(0,0) = \lim_{s \rightarrow 0} \phi(r) \leq \lim_{s \rightarrow r} \phi(s) = \phi(r)$$

Thus
$$v(x,t) \leq rac{1}{4r^n} \int \int_{E(x,t;r)} v(y,s) rac{|x-y|^2}{(t-s)^2} dy ds$$

Define
$$v_{\epsilon}(x,t) = v(x,t) + \epsilon |x|^2$$
, then $\left(\frac{\partial}{\partial t} - \Delta\right) v_{\epsilon} = \left(\frac{\partial}{\partial t} - \Delta\right) v - 2n\epsilon < 0$, v_{ϵ} can't attain its maximum at $(x_0,t_0) \in \overline{U_T} \setminus \Gamma_T$, otherwise $\frac{\partial}{\partial t} v_{\epsilon}(x_0,t_0) \ge 0$, $\Delta v_{\epsilon}(x_0,t_0) \le 0$, then $\Delta v_{\epsilon}(x_0,t_0) \ge 0$,

thus $\max_{\overline{U_T}} \left(v + \epsilon |x|^2 \right) \le \max_{\Gamma_T} \left(v + \epsilon |x|^2 \right) \le \max_{\Gamma_T} v + C\epsilon$ since U is bounded, hence $\max_{\overline{U_T}} v = \max_{\Gamma_T} v$ c)

Since ϕ is convex, $\phi''(x) \ge 0$

$$\left(rac{\partial}{\partial t}-\Delta
ight)v(x)=\left(rac{\partial}{\partial t}-\Delta
ight)\phi\left(v(x,t)
ight)=\phi'(v)\left(rac{\partial v}{\partial t}-\Delta
ight)v-\phi''(v)|
abla v|^2\leq 0$$

Thus v is a subsolution

d)

$$\left(\frac{\partial}{\partial t} - \Delta\right) v = \left(\frac{\partial}{\partial t} - \Delta\right) \left(|\nabla u|^2 + u_t^2\right)
= 2\nabla u \cdot \nabla u_t + 2u_t u_{tt} - 2\sum_{i,j} u_{x_i x_j}^2 - 2\nabla u \cdot \nabla(\Delta u) - 2|\nabla u_t|^2 - 2u_t(\Delta u)_t
= 2\nabla u \cdot \nabla(u_t - \Delta u) + 2u_t (u_t - \Delta u)_t - 2\sum_{i,j} u_{x_i x_j}^2 - 2|\nabla u_t|^2
< 0$$

Thus v is a subsolution

1.3 Homework3

Problem . 2.5.24 Since the solution is given by d'Alembert's formula

$$u(x,t) = rac{1}{2}[g(x+t) - g(x-t)] + rac{1}{2}\int_{x-t}^{x+t} h(y) dy$$

and g, h are compactly supported, u(x,t) is also compactly supported for any fixed t, hence k(t), p(t) make sense (a)

$$rac{d}{dt}(p(t)+k(t))=\int_{-\infty}^{+\infty}u_{t}u_{tt}+u_{x}u_{xt}dx=\int_{-\infty}^{+\infty}u_{t}u_{xx}+u_{x}u_{xt}dx=\int_{-\infty}^{+\infty}rac{\partial}{\partial x}\left(u_{t}u_{x}
ight)dx=u_{t}u_{x}\left|_{-\infty}^{+\infty}
ight.=0$$

Thus k(t) + p(t) is a constant in t (b)

$$u_t(x,t) = rac{1}{2}[g'(x+t) - g'(x-t)] + rac{1}{2}[h(x+t) + h(x-t)]$$
 $u_x(x,t) = rac{1}{2}[g'(x+t) + g'(x-t)] + rac{1}{2}[h(x+t) - h(x-t)]$

Suppose supp $g \cup \text{supp } h \subset D(0,T)$, then consider t > T, one of g'(x+t), g'(x-t) must be zero and one of h(x+t), h(x-t) must be zero, thus $u_t^2 = u_x^2, p(t) = k(t)$

Additional Problem

$$\begin{aligned} |u(x,t)| &= \left| \frac{1}{4\pi t} \int_{\partial B(x,t)} f(y) dS_y \right| \\ &= \left| \frac{t}{4\pi} \int_{S^2} f(x+t\omega) dS_\omega \right| \\ &= \left| -\frac{t}{4\pi} \int_{S^2} \int_t^{-\infty} \frac{d}{d\lambda} f(x+\lambda\omega) d\lambda dS_\omega \right| \\ &= \left| -\frac{t}{4\pi} \int_{S^2} \int_t^{-\infty} (\nabla f \cdot \omega)(x+\lambda\omega) d\lambda dS_\omega \right| \\ &\leq \frac{t}{4\pi} \int_{S^2} \int_t^{-\infty} |\nabla f| \left| \omega \right| (x+\lambda\omega) d\lambda dS_\omega \\ &= \frac{t}{4\pi} \int_{S^2} \int_t^{-\infty} |\nabla f| \left(x+\lambda\omega \right) d\lambda dS_\omega \\ &= \frac{t}{4\pi} \int_{\partial B(x,\lambda)} \int_t^{-\infty} |\nabla f| \left(y \right) d\lambda dS_y \\ &\leq \frac{1}{4\pi t} \int_{\mathbb{R}^3} |\nabla f| dy \end{aligned}$$

Problem . January 2007, Problem 2 (a)

Define

$$E(t)=rac{1}{2}\int_{\partial\Omega}u^2dS+rac{1}{2}\int_{\Omega}\left\{u_t^2+|
abla u|^2+V(x)u^2
ight\}dx$$

Then we have

$$\begin{split} E'(t) &= \int_{\partial\Omega} u u_t dS + \int_{\Omega} \left\{ u_t u_{tt} + \nabla u \cdot \nabla u_t + V(x) u u_t \right\} dx \\ &= \int_{\partial\Omega} u u_t dS + \int_{\Omega} \left\{ u_t \left(\Delta u - V(x) u \right) + \nabla u \cdot \nabla u_t + V(x) u u_t \right\} dx \\ &= \int_{\partial\Omega} u u_t dS + \int_{\Omega} \left\{ u_t \Delta u + \nabla u \cdot \nabla u_t \right\} dx \\ &= \int_{\partial\Omega} u u_t dS + \int_{\partial\Omega} u_t \frac{\partial u}{\partial n} dS \\ &= \int_{\partial\Omega} u_t \left(u + \frac{\partial u}{\partial n} \right) dS \\ &= 0 \end{split}$$

(b)

Uniqueness theorem: Suppose u, v are two solutions to the equation, then u = vConsider w = u - v which satisfies equation $w_{tt} - \Delta w + V(x)w = 0, x \in \Omega, t > 0$, with initial conditions $w(x,0) = 0, w_t(x,0) = 0$ and boundary conditions $w + \frac{\partial w}{\partial n} = 0$ Since $E(0) = \frac{1}{2} \int_{\mathbb{R}^2} w^2(x,0) dS + \frac{1}{2} \int_{\mathbb{R}^2} \left\{ w_t^2(x,0) + |\nabla w|^2(x,0) + V(x)w^2(x,0) \right\} dx = 0$ and

Since $E(0) = \frac{1}{2} \int_{\partial \Omega} w^2(x,0) dS + \frac{1}{2} \int_{\Omega} \left\{ w_t^2(x,0) + |\nabla w|^2(x,0) + V(x) w^2(x,0) \right\} dx = 0$ and E'(t) = 0, hence E(t) = 0, since $V(x) \ge 0$, u = 0 (c)

As for $h \neq 0$, the result is the same as (b)

Problem. August 2003, Problem 4 Suppose there are two solutions u, v, define w = u - v, which would satisfies equation

$$\begin{split} w_{tt} - w_{xx} - w_{yyt} &= 0, \, (x,y) \in \Omega, \, t > 0 \\ w(x,y,0) &= 0, \, w_t(x,y,0) = 0 \\ w(0,y,t) &= w(1,y,t) = 0, \, w_y(x,0,t) = w_y(x,1,t) = 0 \end{split}$$
 Consider $E(t) = \frac{1}{2} \int_{\Omega} (w_t^2 + w_x^2) dx dy$, since
$$w(0,y,t) = w(1,y,t) = 0 \Rightarrow w_t(0,y,t) = w_t(1,y,t) = 0 \\ w_y(x,0,t) &= w_y(x,1,t) = 0 \Rightarrow w_{yt}(x,0,t) = w_{yt}(x,1,t) = 0 \end{split}$$

Thus we have

$$\begin{split} E'(t) &= \int_{\Omega} (w_t w_{tt} + w_x w_{xt}) dx dy \\ &= \int_{\Omega} (w_t w_{xx} + w_t w_{yyt} + w_x w_{xt}) dx dy \\ &= \int_0^1 \int_0^1 (w_t w_x)_x dx dy + \int_0^1 \int_0^1 (w_t w_{yt})_y dy dx - \int_{\Omega} w_{yt}^2 dx dy \\ &\leq \int_0^1 [w_t w_x (1, y, t) - w_t w_x (0, y, t)] dy + \int_0^1 [w_t w_{yt} (x, 1, t) - w_t w_{yt} (x, 0, t)] dx \\ &= 0 \end{split}$$

Thus $u_x = 0$, but u(0, y, t) = 0, hence u = 0

Problem . August 2003, Problem 5 Since

$$egin{align} u(0,t)^2 &= \left(rac{1}{4\pi t}\int_{\partial B(0,t)} g(y) dS_y
ight)^2 \ &\leq rac{1}{8\pi^2 t^2} \left(\int_{\partial B(0,t)} g(y)^2 dS_y
ight) \left(\int_{\partial B(0,t)} 1^2 dS_y
ight) \ &= rac{1}{4\pi} \int_{S^2} g(y)^2 dS_y \ \end{aligned}$$

Thus

$$\int_0^\infty u(0,t)^2 dt \leq \int_0^\infty \frac{1}{4\pi} \int_{\partial B(0,t)} g(y)^2 dS_y dt = \frac{1}{4\pi} \int_{\mathbb{R}^3} g(x)^2 dx$$

Problem . August 2006, Problem 3 (a)

Direct check to find $u_{tt} - \Delta u = 0$ when $r \neq 0$, if t < 1, then $\psi(t + r) = 0$ on a neighborhood of r = 0, thus u(x,t) = 0 on this neighborhood, hence $u_{tt} - \Delta u = 0$, if t < 1

The extended formula should be given by $u(x,t)=rac{\psi(t+r)-\psi(t-r)}{r}=\int_{-1}^1 \psi'(t+\lambda r)d\lambda$

(c)

Since $\psi \in C^k$ by the formula of ψ we showed that $u \in C^{k-1}$

(d)

Since ψ is compactly supported, so is u

Define Energy to be $E(t) = \frac{1}{2} \int_{\mathbb{R}^3} \left(u_t^2 + |\nabla u|^2 \right) dx$, then

$$egin{aligned} E'(t) &= \int_{\mathbb{R}^3} \left(u_t u_{tt} +
abla u \cdot
abla u_t
ight) dx \ &= \int_{\mathbb{R}^3} \left(u_t \Delta u +
abla u \cdot
abla u_t
ight) dx \ &= \int_{B(0,R)} \left(u_t \Delta u +
abla u \cdot
abla u_t
ight) dx \ &= \int_{\partial B(0,R)} u_t rac{\partial u}{\partial n} dS \ &= 0 \end{aligned}$$

Hence the energy is conserved

Problem . August 2001, Problem 1 (a)

$$u(x,t) = rac{1}{4\pi t} \int_{\partial B\left(x,t
ight)} g(y) dS_y = rac{t}{4\pi} \int_{S^2} g(x+t\omega) dS_\omega$$

but $|x+t\omega| \ge t|\omega|-|x|=t-|x| \ge a$, $g(x+t\omega)=0$, hence u(x,t)=0

First we prove g = 0, assume $g(x_1) > 0$, then $u(x_0, |x_1 - x_0|) = \frac{|x_1 - x_0|}{4\pi} \int_{S^2} g(x_0 + |x_1 - x_0|) dS_{\omega} > 0$, since $g \in C(\mathbb{R}^3)$, $g \ge 0$, that is a contradiction, thus g = 0, u(x, t) = 0

1.4 Homework4

Problem. August 2006, Problem 1 Define $F(x, t, p, q, z) = q + xp - z^2$ The characteristics are

$$\left\{ egin{array}{l} \dot{x}=x \ \dot{t}=1 \ \dot{z}=xp+q=z^2 \end{array}
ight.$$

With initial condition

$$\left\{ egin{array}{l} x(0) = x^0 \ t(0) = 0 \ z(0) = f(x^0) \end{array}
ight.$$

Thus we get

$$\begin{cases} x = x^0 e^s \\ t = s \end{cases}$$
$$z(0) = \frac{f(x^0)}{1 - sf(x^0)}$$

which is defined on $\{tf(xe^{-t}) \neq 1\}$, thus $u(x,t) = \frac{f(xe^{-t})}{1 - tf(xe^{-t})}$

Problem. January 2005, Problem 2(b) Define F(x, t, p, q, z) = q + (2z + 1)pThe characteristics are

$$\begin{cases} \dot{x} = 2z + 1 \\ \dot{t} = 1 \\ \dot{z} = 0 \end{cases}$$

With initial condition

$$\begin{cases} x(0) = x^{0} \\ t(0) = 0 \\ z(0) = u(x^{0}, 0) \end{cases}$$

Thus we get

$$\begin{cases} x = x^{0} + (2u(x^{0}, 0) + 1) s \\ t = s \\ z(0) = u(x^{0}, 0) \end{cases}$$

By Rankine-Hugoniot condition, we have $0 = F(u_l) - F(u_r) = \dot{s}(t)(u_l - u_r) = 3\dot{s}(t)$ Thus we have a piecewise smooth solution

$$u(x,t)=\left\{egin{array}{ll} 1,\,x<0\ -2,\,x>0 \end{array}
ight.$$

Problem . January 2000, Problem 2 Consider the initial condition to be

$$g(x) = \left\{ egin{array}{ll} 0, \ x < 0 \ 1, \ 0 < x < 1 \ 0, \ x > 1 \end{array}
ight.$$

Then

$$X(t) = \left\{ \begin{array}{l} 1 + \frac{t}{3}, \ 0 < t < \frac{3}{2} \\ \sqrt[3]{\frac{9}{4}t}, \ t > \frac{3}{2} \end{array} \right. \quad f\left(\frac{x}{t}\right) = \left\{ \begin{array}{l} \sqrt{\frac{x}{t}}, \ 0 < x < X(t), \frac{x}{t} < 1 \\ 1, \ 0 < x < X(t), \frac{x}{t} > 1 \end{array} \right.$$

$$\forall t \in \left[0, \tfrac{3}{2}\right], \int_0^\infty u(x,t) dx = \int_0^t \sqrt{\frac{x}{t}} dx + \int_t^{1+\frac{t}{3}} 1 dx = \frac{2}{3}t + \left(1-\frac{2}{3}t\right) = 1$$

$$orall t \in \left(rac{3}{2},\infty
ight), \, \int_0^\infty u(x,t) dx = \int_0^{\sqrt[3]{rac{9}{4}t}} \sqrt{rac{x}{t}} dx = 1$$

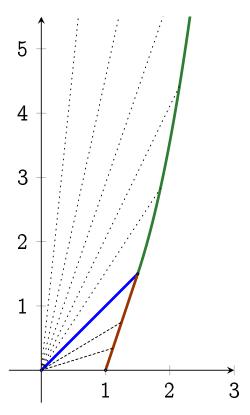
Along
$$x = t, 0 \le t \le \frac{3}{2}, u_l = 1 = u_r$$

Along
$$x = t, 0 \le t \le \frac{3}{2}, u_l = 1 = u_r$$

Along $x = 1 + \frac{t}{3}, 0 \le t \le \frac{3}{2}, 1 = u_l > \frac{1}{3} = \dot{X}(t) > 0 = u_r$

Along $x=\sqrt[3]{\frac{9}{4}t}, t>\frac{3}{2},\ u_l=t^{-\frac{1}{3}}\sqrt[3]{\frac{3}{2}}>\frac{1}{3}t^{-\frac{2}{3}}\sqrt[3]{\frac{9}{4}}=\dot{X}(t)>0=u_r$

Which shows that u satisfies the entropy condition, and along $x = t, 0 \le t \le \frac{3}{2}$, u is a rarefaction wave, along X(t), u is a shock wave



Problem. August 1998, Problem 5 0 = $u_t + uu_x = u_t + \left(\frac{1}{2}u^2\right)_x$, since u and $\xi(t)$ are both continuous, so is $u(\xi(t),t)$, there is a C^1 function u_L in a neighborhood of C_l which agrees with u on C_l and curve C, and there is a C^1 function u_R in a neighborhood of C_r which agrees with u on C_r and curve C, $\frac{d}{dt}u(\xi(t),t) = \frac{d}{dt}u_L(\xi(t),t)$ is continuous since u_L and ξ are both C^1 function, then we have $\frac{d}{dt}u_L(\xi(t),t) = \frac{d}{dt}u_R(\xi(t),t) \Rightarrow 0 = \frac{d}{dt}u_L(\xi(t),t) - \frac{d}{dt}u_R(\xi(t),t) = (u_x^- - u_x^+)\xi' + (u_t^- - u_t^+)$ On the other hand, since u is continuous, $0 = u_t^- + u^-u_x^- = u_t^- + uu_x^- = u_t^+ + u^+u_x^+ = u_t^+ + uu_x^+ \Rightarrow 0 = (u_t^- + uu_x^-) - (u_t^+ + uu_x^+) = (u_x^- - u_x^+)u + (u_t^- - u_t^+)$ But u_x has jump discontinuity on the curve, hence $u_x^- - u_x^+ \neq 0$, compare to get $\xi'(t) = u$

1.5 Homework5

Problem . August 1996, Problem 1a Assume u attains its maximum $\max_{\partial\Omega}u$ at $x^0\in\partial\Omega,$ since $f \geq 0$, U is a domain which is bounded, maximum principle applies. Suppose $u(x) < u(x^0), \forall x \in$ Ω , then according to Hopf lemma, $\frac{\partial u}{\partial n}(x^0) > 0$ since Ω has a smooth boundary, which contradicts $\frac{\partial u}{\partial n}=0$ on $\partial\Omega$. Thus $\exists y\in\Omega$, such that $u(y)=u(x^0)$, by strong maximum principle, u is a

Since f is bounded, assume |f| < C, consider v := u - Cw, we have $v(x^0) = 0$, $v \le 0$ on ∂U and Live $Lu - CLw \le Lu - C < 0$, by maximum principle, we know $v(x) < v(x^0)$, $\forall x \in U$, by Hopf lemma, $\frac{\partial u}{\partial \nu}(x^0) - C\frac{\partial w}{\partial \nu}(x^0) = \frac{\partial v}{\partial \nu}(x^0) > 0$, similarly, if we consider -u - Cw and -w, we have $-\frac{\partial u}{\partial \nu}(x^0) - C\frac{\partial w}{\partial \nu}(x^0) > 0$ and $-\frac{\partial w}{\partial \nu}(x^0) > 0$. Also, since u = 0 on ∂U , $|Du(x^0)| = \left|\frac{\partial u}{\partial \nu}(x^0)\right|$,

$$\left\{egin{aligned} -Crac{\partial w}{\partial
u}(x^0) > -rac{\partial u}{\partial
u}(x^0) \ -Crac{\partial w}{\partial
u}(x^0) > rac{\partial u}{\partial
u}(x^0) \end{aligned}
ight. \Rightarrow -Crac{\partial w}{\partial
u}(x^0) > \left|rac{\partial u}{\partial
u}(x^0)
ight| \Rightarrow C\left|rac{\partial w}{\partial
u}(x^0)
ight| > \left|Du(x^0)
ight|$$

Problem . 7. (a)

$$0 = \int_{U} u \Delta u = \frac{1}{2} \int_{\partial U} u \frac{\partial u}{\partial \nu} - \frac{1}{2} \int_{U} |\nabla u|^{2} \Rightarrow \int_{U} |\nabla u|^{2} = 0 \Rightarrow |\nabla u| \equiv 0 \Rightarrow u \equiv \text{const}$$

(b)

Using maximum principle, let $x^0 \in \partial U$ be a maximizer of u, suppose $u(x) < u(x^0), \forall x \in U$, by Hopf lemma, $\frac{\partial u}{\partial \nu}(x^0) > 0$ which contradicts $\frac{\partial u}{\partial \nu} = 0$ on ∂U , thus $\exists y \in U$, such that $u(y) = u(x^0)$, hence u is a constant by strong maximum principle

References

 $[1]\ Partial\ Differential\ Equations$ - Lawrence C. Evans