$A_{(n\times n)}$ ,  $\exists B_{(n\times n)}$ ,  $AB = I \rightarrow A$  is invertible (non-singular)  $B = A^{-1}$ 

Fundamental properties:  $xAA^{-1} = x$ 

Not every matrix has inverse (ex.  $A = \vec{0}$ )

If a homogeneous system Ax = 0 has non-trivial solution, A's not invertible

Ax = 0 not imply  $x \neq 0$ 

$$ex. A = \begin{pmatrix} 2 & 5 \\ 4 & 10 \end{pmatrix} \begin{pmatrix} 2 & 5 \\ 4 & 10 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \end{pmatrix} \gg \begin{pmatrix} 5t \\ -2t \end{pmatrix}$$

i) Equivalently Ax = 0 has only trivial solution, A is invertible.

A has an inverse 
$$\rightarrow \exists ! A^{-1}$$
 (uniqueness)

Proof: assume B & C are inverse of A, show B = C

B, C are inverse of A, means 
$$BA = I = AB$$
,  $CA = I = AC$ 

$$B = BI = B(AC) = (BA)C = IC = C$$

- ii)  $(A^{-1})^{-1} = A$
- iii)  $A_{(n\times n)}$ ,  $\exists B_{(n\times n)}$ , s. t.  $AB=I\to BA=I \land A=B^{-1} \land B=A^{-1}$
- iv) A one-sided inverse is automatically a two-sided inverse

Proof:  $Bx = 0 \rightarrow A(Bx) = 0$ , A(0), (AB)x = 0, Ix = 0, x = 0, B is invertible

Show A's inverse of B, given AB = 1

$$AI = A(BB^{-1}) = IB^{-1} = B^{-1}$$

Finding  $A^{-1}$  if exists

A is invertible  $\leftrightarrow \forall b \in \mathbb{R}^n, Ax = b, \rightarrow x = A^{-1}b$ 

$$Ax = b = A(A^{-1}b), \exists x \in R^n, s. t. Ax = b$$

Multiple by A expresses in term of  $AA^{-1}b = Ib = b$ , multiple  $A^{-1}$  expresses x in terms of b.

e.x. find 
$$A^{-1}$$
 of  $A = \begin{pmatrix} 1 & 2 & 1 \\ 1 & 3 & 4 \\ 2 & 4 & 1 \end{pmatrix}$  if exists (using  $AA^{-1} = I$ )

$$\begin{pmatrix} 1 & 2 & 1 & 1 & 0 & 0 \\ 1 & 3 & 4 & 0 & 1 & 0 \\ 2 & 4 & 1 & 0 & 0 & 1 \end{pmatrix} \gg \begin{pmatrix} R2 - R1 \\ R3 - 2R1 \end{pmatrix} \gg \begin{pmatrix} 1 & 2 & 1 & 1 & 0 & 0 \\ 0 & 1 & 3 & -1 & 1 & 0 \\ 0 & 0 & -1 & -2 & 0 & 1 \end{pmatrix}$$

$$\gg \begin{pmatrix} 1 & 0 & 0 & | & 13 & -2 & 5 \\ 0 & 1 & 0 & | & -7 & 1 & 3 \\ 0 & 0 & 1 & | & 2 & 0 & -1 \end{pmatrix}$$

Process fails iff A can't convert to I (if # of pivots in A < n)

A is invetible if f # pivots in A is n

$$e. x. A = \begin{pmatrix} 1 & 2 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}$$
 show  $(I - A)^3 = 0$  and use this to find  $A^{-1}$  without using row reduction

$$I - A = \begin{pmatrix} 0 & -2 & 0 \\ 0 & 0 & -1 \\ 0 & 0 & 0 \end{pmatrix} (I - A)^2 = \begin{pmatrix} 0 & 0 & 2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} (I - A)^3 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$0 = I^3 - 3I^2A + 3IA^2 - A^3$$

$$I = 3A - 3A^2 + A^3 = A(A^2 - A + 3I)$$

$$A^{-1} = A^2 - A + 3I = \begin{pmatrix} 1 & -2 & 2 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{pmatrix}$$

Inverse of a product:

If A, B are invertible, then AB is invertible:  $(AB)^{-1} = B^{-1}A^{-1}$ 

Check 
$$(AB)(B^{-1}A^{-1}) = A(BB^{-1})A^{-1} = AA^{-1} = I$$

Inverse of transpose A is invertible  $\rightarrow A^{T}$  is invertible:  $(A^{T})^{-1} = (A^{-1})^{T}$ 

Check 
$$A^{T}(A^{-1})^{T} = (AA^{-1})^{T} = I^{T} = I$$

Inverse of scalar multiple:  $c \in R$ ,  $(cA)^{-1} = \frac{A^{-1}}{c}$ 

 $A n \times n$  invertible iff:

- 1) Ax = b has unique solution for all b
- 2) Ax = 0 has only trivial solution
- 3)  $A \rightarrow I$  by row reduction
- 4) A has n pivots
- 5) Columns of A span  $R^n$
- 6) Columns of A are linear independent
- 7) Matrix transformation  $T: \mathbb{R}^n \to \mathbb{R}^2$  defined by T(x) = Ax is onto and 1-1

Elementary Matrices and inverses

An elementary matrix operation is a single elementary row operation on I

There are 3 types of elementary row operations hence 3 types of elementary matrices

Thrm: Any elementary row operations on matrix A can be done by multiply A on the left by elementary matrix E. (EA is A after an elementary row operation)

Proof: 
$$A m \times n, B = EA$$
, WTS:  $B = Rj + kRi \ of \ A, Rj(B) = Rj(A) + kRi(A)$ 

$$Rj(B) = Rj(EA) = Rj(E)A = (Rj(1) + kRi(1))A = Rj(I)A + kRi(I)A = Rj(A) + kRi(A)$$

Since elementary row operations are reversible, every elementary matrix is invertible

Swap: 
$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}^{-1} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

Multiply a row by 
$$x \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & x \end{pmatrix}^{-1} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & \frac{1}{x} \end{pmatrix}$$

Add a multiple of a row to another 
$$\begin{pmatrix} 1 & 0 & x \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}^{-1} = \begin{pmatrix} 1 & 0 & -x \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Elementary matrices and invertibility

Thrm:  $A n \times n$  is invertible iff A can be written as a product of elementary matrices Proof:

i)  $A n \times n$  is invertible  $\leftarrow A$  can be written as a product of elementary matrices

$$A = E_1 E_2 E_3 \dots E_k \to \exists E_1^{-1} E_2^{-1} E_3^{-1} \dots E_k^{-1} \to A^{-1}$$

ii)  $A n \times n$  is invertible  $\rightarrow A$  can be written as a product of elementary matrices

$$\begin{split} E_k E_{k-1} E_{k-2} \dots E_1 A &= I \\ A^{-1} &= E_k E_{k-1} E_{k-2} \dots E_1 \\ A &= E_1^{-1} E_2^{-1} E_3^{-1} \dots E_k^{-1} \end{split}$$

$$e. x. A = \begin{pmatrix} 1 & 0 & 2 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$
 shown A is invertible through the product of elementary matrices

$$\begin{pmatrix} 1 & 0 & 2 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \gg (R2 + 2R1) \gg \begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & 4 \\ 0 & 0 & 1 \end{pmatrix} \gg \begin{pmatrix} R1 - 2R3 \\ R2 - 4R3 \end{pmatrix} \gg I$$

$$E1 = \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}, E2 = \begin{pmatrix} 1 & 0 & -2 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}, E3 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & -3 \\ 0 & 0 & 1 \end{pmatrix}$$

$$A^{-1} = E3E2E1$$

$$A = E_1^{-1} E_2^{-1} E_3^{-1}$$

LU decomposition: In  $n \times n$  matrix A is upper or lower triangular if all entries below or above diagonals are zero, (ref is an upper triangular matrix, I is both)

$$e.x.\begin{pmatrix} 1 & 2 & 1 & b1 \\ 1 & 3 & 4 & b2 \\ 1 & 7 & 8 & b3 \end{pmatrix}\begin{pmatrix} 1 & 2 & 1 & 1 & 0 & 0 \\ 1 & 3 & 4 & 0 & 1 & 0 \\ 1 & 7 & 8 & 0 & 0 & 1 \end{pmatrix} \gg \begin{pmatrix} 1 & 2 & 1 & 1 & 0 & 0 \\ 0 & 1 & 3 & -1 & 1 & 0 \\ 0 & 0 & -3 & 1 & -3 & 1 \end{pmatrix}$$

$$L = \begin{pmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 1 & -3 & 1 \end{pmatrix}, Y = \begin{pmatrix} 1 & 2 & 0 \\ 0 & 1 & 3 \\ 0 & 0 & -3 \end{pmatrix}$$

Solving Ax = b is equivalent to solving Yx = Lb

To solve 
$$b = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$$
,  $Lb = \begin{pmatrix} 1 & 0 & 0 & 1 \\ -1 & 1 & 0 & 2 \\ 1 & -3 & 1 & 3 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix}$ , then solve  $\begin{pmatrix} 1 & 2 & 0 & 1 \\ 0 & 1 & 3 & 1 \\ 0 & 0 & -3 & -2 \end{pmatrix}$ 

In general  $(A \mid I) \rightarrow (Y \mid L)$ ,  $Ax = Ib \rightarrow Yx = Lb \rightarrow Yx = LAx \rightarrow Y = LA \rightarrow A = L^{-1}Y$ 

$$E1E2E3 A = Y$$

$$A = (E_3^{-1}E_2^{-1}E_1^{-1})Y$$

e. x. find LU factorization of  $A = \begin{pmatrix} 1 & 2 & 1 \\ 2 & 1 & 1 \\ 1 & 3 & 2 \end{pmatrix}$ 

$$\begin{pmatrix} 1 & 2 & 1 \\ 2 & 1 & 1 \\ 1 & 3 & 2 \end{pmatrix} \gg \begin{pmatrix} R2 - 2R1 \\ R3 - R1 \\ R3 + 3R2 \end{pmatrix} \gg \begin{pmatrix} 1 & 2 & 0 \\ 0 & -3 & -1 \\ 0 & 0 & -3 \end{pmatrix}$$

$$A = (E_1^{-1} E_2^{-1} E_3^{-1}) U$$

$$L = (E_1^{-1} E_2^{-1} E_3^{-1}) = \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -\frac{1}{3} & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 1 & -\frac{1}{3} & 1 \end{pmatrix}$$

$$A = \begin{pmatrix} 1 & 2 & 1 \\ 2 & 1 & 1 \\ 1 & 3 & 2 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 0 \\ 0 & -3 & -1 \\ 0 & 0 & -3 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 1 & -\frac{1}{3} & 1 \end{pmatrix}$$

In term of solving systems: solve Ax = b, since A = LU, LU x = b

Solve in 2 steps: find w, s.t. Lw = b, then solve Ux = w

$$e. x. solve \begin{pmatrix} 1 & 2 & 1 \\ 2 & 1 & 1 \\ 1 & 3 & 2 \end{pmatrix} x = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} given U = \begin{pmatrix} 1 & 2 & 0 \\ 0 & -3 & -1 \\ 0 & 0 & -3 \end{pmatrix}, L = \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 1 & -\frac{1}{3} & 1 \end{pmatrix}$$
$$Lw = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}, \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 1 & -\frac{1}{3} & 1 \end{pmatrix} w = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}, w = \begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix}$$

$$Ux = w, \begin{pmatrix} 1 & 2 & 0 \\ 0 & -3 & -1 \\ 0 & 0 & -3 \end{pmatrix} x = \begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix}, x = \begin{pmatrix} 0 \\ 1 \\ -3 \end{pmatrix}$$