

June 12, 2019

- TA tutorial sessions tomorrow and next Tuesday @ LM158, 6-9pm
- Final exam questions (topics taught after midterm):
 - 1) Forecast (Ch 5)
 - 2) Transfer function noise model
 - 3) Multivariate time series—VAR & cointegration...
 - 4) GARCH model
 - 5) Modeling appraisal returns...
 - 6) Bootstrap time series

Generalized autoregressive conditional heteroskedastic (GARCH) model:

The first order of autoregressive conditional heteroskedastic (ARCH(1)) process:

$$a_t \sim NID(0, \sigma_t^2)$$

$$\sigma_t^2 = \alpha_0 + \alpha_1 a_{t-1}^2$$

On defining $v_t = a_t^2 - \sigma_t^2$, the model can also be written as

$$a_t^2 = \alpha_0 + \alpha_1 a_{t-1}^2 + v_t.$$

Since $E(v_t | x_{t-1}, x_{t-2}, \dots) = 0$, the model corresponds directly to an AR(1) model for the squared error a_t^2 .

ARCH(q) process:

$$\sigma_t^2 = \alpha_0 + \sum_{i=1}^q \alpha_i a_{t-i}^2,$$

with

$$\alpha_0 \geq 0, \alpha_i > 0, \sum_{i=1}^q \alpha_i < 1.$$

Or equivalently,

$$a_t^2 = \alpha_0 + \sum_{i=1}^q \alpha_i a_{t-i}^2 + v_t = \alpha_0 + \alpha(B) a_{t-1}^2 + v_t,$$

where

$$\alpha(B) = \alpha_1 + \alpha_2 B + \dots + \alpha_q B^{q-1}.$$

The (generalized) ARCH(GARCH) process:

Consider a GARCH(p,q) model

$$\sigma_t^2 = \alpha_0 + \sum_{i=1}^p \beta_i \sigma_{t-i}^2 + \sum_{i=1}^q \alpha_i a_{t-i}^2 = \alpha_0 + \alpha(B) a_{t-1}^2 + \beta(B) \sigma_{t-1}^2.$$

Provided that $\alpha_0 \geq 0$, $\alpha(B)$ and $\beta(B)$ have no common roots and that the roots of $1 - \beta(B)$ all less than unity.

Review of forecast:

$$y_t = 0.5y_{t-1} + a_t, \quad a_t \sim NID(0,1).$$

1. Optimal l -step ahead forecast (conditional expectation):

$$E_t(y_{t+1}) = 0.5E_t(y_t) + E_t(a_{t+1})$$

$$\rightarrow \hat{y}_t(1) = 0.5y_t$$

$$y_{t+l} = 0.5y_{t+l-1} + a_{t+l}$$

$$\rightarrow \hat{y}_t(l) = 0.5\hat{y}_t(l-1), \quad l > 1$$

2. Optimal l -step ahead forecast in terms of a_t :

- 1) Express y_{t+l} as a causal process:

$$y_{t+l} = \sum_{i=0}^{\infty} 0.5^i a_{t+l-i}. \quad (1)$$

- 2) Optimal MSE forecast a time t is

$$\hat{y}_t(l) = \sum_{i=0}^{\infty} \tilde{\phi}_i a_{t-i}. \quad (2)$$

Finding $\tilde{\phi}_i$:

$$\begin{aligned} \min_{\tilde{\phi}_j} E[y_{t+l} - \hat{y}_t(l)]^2 &= E \left[\sum_{i=0}^{l-1} 0.5^i a_{t+l-i} + \sum_{j=0}^{\infty} (0.5^{j+l} - \tilde{\phi}_j) a_{t-j} \right]^2 \\ &= \underbrace{\sigma_a^2}_1 \sum_{i=0}^{l-1} 0.25^i + \sum_{j=0}^{\infty} (0.5^{j+l} - \tilde{\phi}_j)^2 \end{aligned}$$

That is, the optimal $\tilde{\phi}_j$'s are found as $\tilde{\phi}_j = 0.5^{j+l}$, $j = 0, 1, 2, \dots$

3. The variance of the forecast error:

$$\text{var}(y_{t+l} - \hat{y}_t(l)) = \sum_{i=0}^{l-1} 0.25^i$$

4. The forecast error for a transfer function noise model

$$z_t = \beta f_t + y_t, \quad f_t = 0.6f_{t-1} + e_t, \quad \text{cov}(e_t, a_s) = 0$$

l -step ahead forecast error of z_t is the sum of:

$$\beta^2 \text{var}(f_{t+l} - \hat{f}_t(l)) + \text{var}(y_{t+l} - \hat{y}_t(l))$$

$$f_t = \sum_{i=0}^m v_i x_{t-i} \quad (\text{temporal aggregation})$$

Modeling appraisal returns:

Consider appraisal returns satisfying:

$$y_t = a_t + \theta a_{t-1}, \quad a_t \sim NID(0,1).$$

According to Getmansky et al. (2005), we can define

$$y_t = \frac{\overbrace{1}^{w_0}}{(1+\theta)} \underbrace{[(1+\theta)a_t]}_{r_t} + \frac{\overbrace{\theta}^{w_1}}{(1+\theta)} \underbrace{[(1+\theta)a_{t-1}]}_{r_{t-1}}$$

$$r_t = (1+\theta)a_t$$

Suppose $\theta = 0.5$

$$\text{var}(y_t) = (1 + .25)\sigma_a^2 = 1.25$$

$$\text{var}(r_t) = (1 + 0.5)^2 \sigma^2 = 2.25$$

$$\frac{\text{var}(r_t)}{\text{var}(y_t)} = \frac{2.25}{1.25} = 1.8$$