

Homogeneous System: $Ax = 0$.

- The vector equation will always have a solution $x=0$, which is the trivial solution
- Look for non-trivial solution

$$\begin{aligned}
 \text{e. x. } \left[\begin{array}{ccccc|c} 1 & 2 & 0 & 0 & 1 & 0 \\ -1 & 0 & 1 & 0 & 1 & 0 \\ 1 & 0 & -3 & 1 & 0 & 0 \end{array} \right] &\gg \left[\begin{array}{ccccc|c} 1 & 0 & 0 & -\frac{1}{2} & -\frac{3}{2} & 0 \\ 0 & 1 & 0 & \frac{1}{4} & \frac{5}{4} & 0 \\ 0 & 0 & 1 & -\frac{1}{2} & -\frac{1}{2} & 0 \end{array} \right] &\gg \begin{pmatrix} x_1 = -\frac{s}{2} - \frac{3t}{2} \\ x_2 = \frac{s}{4} + \frac{5t}{4} \\ x_3 = -\frac{s}{2} - \frac{t}{2} \\ x_4 = s \\ x_5 = t \end{pmatrix} \\
 &\gg s \begin{pmatrix} \frac{1}{2} \\ \frac{1}{4} \\ -\frac{1}{2} \\ 1 \\ 0 \end{pmatrix} + t \begin{pmatrix} -\frac{3}{2} \\ \frac{5}{4} \\ -\frac{1}{2} \\ 0 \\ 1 \end{pmatrix} &\gg \text{span} \left\{ \begin{pmatrix} \frac{1}{2} \\ \frac{1}{4} \\ -\frac{1}{2} \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -\frac{3}{2} \\ \frac{5}{4} \\ -\frac{1}{2} \\ 0 \\ 1 \end{pmatrix} \right\}
 \end{aligned}$$

Theorem: Homogenous system with more variables than equations always have infinitely many non-trivial solutions.

$$\text{e. x. } \left(\begin{array}{cccc|c} 1 & 0 & 2 & 1 & 14 \\ 1 & 0 & 3 & 3 & 19 \end{array} \right) \text{ gives solution } \begin{pmatrix} 4+3t \\ s \\ 5-2t \\ t \end{pmatrix} \gg \begin{pmatrix} 4 \\ 0 \\ 5 \\ 0 \end{pmatrix} + \left(s \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} + t \begin{pmatrix} 3 \\ 0 \\ -2 \\ 1 \end{pmatrix} \right)$$

$$\text{consider } \left(\begin{array}{cccc|c} 1 & 0 & 2 & 1 & 0 \\ 1 & 0 & 3 & 3 & 0 \end{array} \right) \gg \left(s \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} + t \begin{pmatrix} 3 \\ 0 \\ -2 \\ 1 \end{pmatrix} \right)$$

Theorem: every solution to $Ax = b$ is of form $x = xp + x_0$, where xp is a particular solution to $Ax=b$ and x_0 is a solution to the associated homogeneous equation

Proof:

$$\begin{aligned}
 Ax &= A(xp + x_0) \\
 &= Axp + Ax_0 \\
 &= b + 0 \\
 &= b \\
 Ax_0 &= A(x - xp) \\
 &= Ax - Axp \\
 &= b - b \\
 &= 0
 \end{aligned}$$

Definition 1.1) vector $v_1, v_2, \dots, v_k \in R^n$ are linear dependent if

\exists scalar $c_1, c_2, \dots, c_k \in R$, are not all 0, s.t. $c_1v_1 + c_2v_2 + \dots + c_kv_k = 0$

Definition 1.2) $v_1, v_2, \dots, v_k \in R^n$ are linear dependent iff homogenous solution $(v_1, v_2, \dots, v_k | 0)$ has non-trivial solutions

$$\begin{aligned} \text{e.x. } \left\{ \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix} \right\} \text{ are lin. dep. } \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} - \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix} &= \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \\ c_1 = 1, c_2 = 1, c_3 &= -1 \\ \text{also } \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} &= \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix} \end{aligned}$$

Definition 1.3) $v_1, v_2, \dots, v_k \in R^n$ are linear dependent iff at least one of v_1, v_2, \dots, v_k can be written as a linear combination of remaining $(k-1)$ vectors.

$$\text{e.x. } \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \begin{pmatrix} 2 \\ 0 \\ 0 \end{pmatrix} \right\} \text{ are lin. dep. } \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = 0 \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + 0 \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} + \frac{1}{2} \begin{pmatrix} 2 \\ 0 \\ 0 \end{pmatrix}$$

Definition 2) $v_1, v_2, \dots, v_k \in R^n$ are linear independent if they are not lin. dep., which

2.1) $c_1 = c_2 = \dots = c_k = 0$

2.2) $(v_1, v_2, \dots, v_k | 0)$ only have trivial solutions

e.x. For what value of c is the set of vectors lin.in.

$$\left\{ \begin{pmatrix} 1 \\ -1 \\ 0 \\ 0 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \\ 1 \\ 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 0 \\ 1 \end{pmatrix} \begin{pmatrix} c \\ 1 \\ 1 \\ 2c \end{pmatrix} \right\} \gg \begin{pmatrix} 1 & 1 & 1 & c \\ -1 & 1 & 0 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 2c \end{pmatrix} \gg \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & c-1 \\ 0 & 0 & 1 & c+1 \end{pmatrix} \gg c \neq -1$$