LA HW2

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(a) $V = \begin{bmatrix} 1 & -4 \\ 1 & 3 \end{bmatrix}, D = \begin{bmatrix} 5 & 0 \\ 0 & -2 \end{bmatrix}$

(b) $Av_1 = v_1 \lambda_1, Av_2 = v_2 \lambda_2 \implies A[v_1, v_2] = \begin{bmatrix} v_2, v_2 \end{bmatrix} \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}$

(c)

$$A = VDV^{-1}$$

$$\begin{bmatrix} 1 & 4 \\ 3 & 2 \end{bmatrix} = \begin{bmatrix} 1 & -4 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} 5 & 0 \\ 0 & -2 \end{bmatrix} \begin{bmatrix} 1 & -4 \\ 1 & 3 \end{bmatrix}^{-1}$$

$$\begin{bmatrix} 1 & 4 \\ 3 & 2 \end{bmatrix} \begin{bmatrix} 1 & -4 \\ 1 & 3 \end{bmatrix} = \begin{bmatrix} 1 & -4 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} 5 & 0 \\ 0 & -2 \end{bmatrix}$$

$$\begin{bmatrix} 5 & 8 \\ 5 & -6 \end{bmatrix} = \begin{bmatrix} 5 & 8 \\ 5 & -6 \end{bmatrix}$$

(d) The transformation matrix applied to one of it's eigenvectors is the same as multiplying the eigenvector by its respective eigenvalue.

(e)

$$A^{33} = VD^{33}V^{-1}$$

$$= \begin{bmatrix} 1 & -4 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} 5 & 0 \\ 0 & -2 \end{bmatrix}^{33} \begin{bmatrix} 1 & -4 \\ 1 & 3 \end{bmatrix}^{-1}$$

$$= \begin{bmatrix} 1 & -4 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} 5^{33} & 0 \\ 0 & (-2)^{33} \end{bmatrix} \begin{bmatrix} 1 & -4 \\ 1 & 3 \end{bmatrix}^{-1}$$

$$= \begin{bmatrix} 1 & -4 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} 5 & 0 \\ 0 & -2 \end{bmatrix}^{33} \begin{bmatrix} 1 & -4 \\ 1 & 3 \end{bmatrix}^{-1}$$

$$= \frac{1}{7} \left(5^{33} \begin{bmatrix} 3 & 4 \\ 3 & 4 \end{bmatrix} + (-2)^{33} \begin{bmatrix} 4 & -4 \\ -3 & 3 \end{bmatrix} \right)$$

(a) Distance preserving means that the length before and after the transformation are the same, or ||v|| = ||Vv||, which is also the same as $\langle v, v \rangle = \langle Vv, Vv \rangle$.

Angle preserving means that the angle before and after the transformation are the same. One way to express this is that the angle between v and Vv is 0, indicating no change. This is the same as the cosine of the angle being 1.

$$\frac{\langle v, Vv \rangle}{\|v\| \|Vv\|} = \frac{\langle v, Vv \rangle}{\|v\|^2}$$
 Distance preserving
$$= \frac{\|v\|^2}{\|v\|^2}$$
$$= 1$$

(b)

$$VV^t = Id$$

$$det(VV^t) = det(Id)$$

$$det(V)det(V^t) = det(Id)$$

$$det(V)det(V) = det(Id)$$

$$det(V)^2 = det(Id)$$

$$det(V)^2 = det(Id)$$

$$det(V)^2 = 1$$

$$det(V) = \pm 1$$

$$det(V) = det(Id)$$

- (c) The eigenvector(s) would be on the specific axis, such as (1,0,0) for the x-axis. This is because a rotation around an axis wouldn't affect the orientation of something that is on the axis, which makes sense because the transformation of an eigenvector is just a scalar multiple of itself.
- (d) The Identity matrix has values of 1 on the diagonal and 0 elsewhere. This means $j = k \implies 1 \land j \neq k \implies 0$. The jth row of V^t is just the jth column of V, so we would get 1 when j = k and 0 when $j \neq k$.

(a)
$$V = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \rightarrow \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}, D = \begin{bmatrix} 5 & 0 \\ 0 & -3 \end{bmatrix}$$

The lengths of the eigenvectors don't matter since we can just scale them. $\langle (1,1), (1,-1) \rangle = 0$, so our eigenvectors are orthogonal.

(b)

$$B = VDV^{t}$$

$$\begin{bmatrix} 1 & 4 \\ 4 & 1 \end{bmatrix} = \frac{1}{\sqrt{2}} \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 5 & 0 \\ 0 & -3 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}^{t}$$

$$= \frac{1}{2} \begin{bmatrix} 5 & 3 \\ 5 & -3 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}^{t}$$

$$= \frac{1}{2} \begin{bmatrix} 2 & 8 \\ 8 & 2 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 4 \\ 4 & 1 \end{bmatrix}$$

$$Id = VV^{t}$$

$$= \frac{1}{\sqrt{2}} \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}^{t}$$

$$= \frac{1}{2} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix}$$

$$= \frac{1}{2} \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}$$

$$= Id$$

$$VV^{-1} = Id = VV^t \implies V^{-1} = V^t$$

(c) An orthogonal vector A has the property that $AA^t = Id$.

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I did both parts in Jupyter Notebook (Python). Here is the code snippet.
import numpy as np
import matplotlib.pyplot as plt
%matplotlib inline
def rrq(v, B): # Ritz-Rayleight Quotient
        \# @ is matrix multiplication
        return np. dot(v, B@v)/(np. dot(v, v))
\# generate 100 random vectors of size 2 in range (-10,\ 10)
v = np.random.uniform(-10,10,[100,2])
# our matrix
B = np. array([1, 4, 4, 1]). reshape((2, 2))
rrqs = [] \# Ritz - Rayleigh Quotients
for i in range(v.shape[0]):
        rrqs.append(rrq(v[i], B))
plt.plot(rrqs)
plt.axhline(y = 5, color = 'b', linestyle = '-') # large eigenvalue
plt.axhline(y = -3, color = 'r', linestyle = '-') # small eigenvalue
plt.show()
for i in range (10):
        # output 10 vectors and their RRQs
        print(v[i], rrqs[i])
```

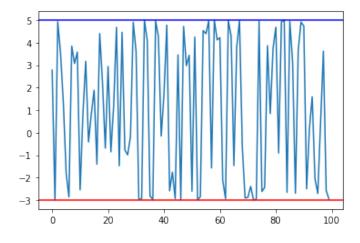
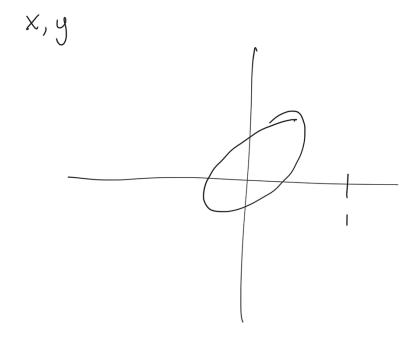


Figure 1: RRQ

10 vectors and their RRQs are :

```
\begin{array}{c} [8.79546278, 2.06447912] \rightarrow 2.779715855809442 \\ [9.5063905, -8.90054609] \rightarrow -2.9913427706469595 \\ [7.76486343, 6.4787083] \rightarrow 4.935298822710415 \\ [8.980074, 3.18657326] \rightarrow 3.521315522110756 \\ [-3.16092004, -0.13259838] \rightarrow 1.3350048755291104 \\ [-6.54872245, 2.68558311] \rightarrow -1.8084307457639526 \\ [-9.18640328, 7.06257587] \rightarrow -2.8656246827096234 \\ [8.16544874, 3.41700323] \rightarrow 3.8488780492756383 \\ [9.74184802, 2.73129675] \rightarrow 3.079479954078956 \\ [8.5244294, 3.12348018] \rightarrow 3.584346724232756 \end{array}
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$$\begin{bmatrix} 3 & -2 \\ -2 & 6 \end{bmatrix} \longrightarrow \frac{1}{\sqrt{5}} \begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 0 & 7 \end{bmatrix} \begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix}^t \frac{1}{\sqrt{5}}$$
$$2X^2 + 7Y^2 = 1$$



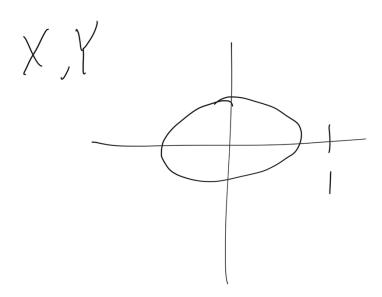


Figure 2: Before and After the transform

(a)
$$\begin{bmatrix} 9 & -4 & 4 \\ -4 & 7 & 0 \\ 4 & 0 & 11 \end{bmatrix} \longrightarrow \frac{1}{3} \begin{bmatrix} 2 & -1 & -2 \\ -1 & 2 & -2 \\ 2 & 2 & 1 \end{bmatrix} \begin{bmatrix} 15 & 0 & 0 \\ 0 & 9 & 0 \\ 0 & 0 & 3 \end{bmatrix} \begin{bmatrix} 2 & -1 & -2 \\ -1 & 2 & -2 \\ 2 & 2 & 1 \end{bmatrix}^{t} \frac{1}{3}$$
$$15X^{2} + 9Y^{2} + 3Z^{2} = 1$$

(b)
$$\frac{1}{3} \begin{bmatrix} 2 & -1 & -2 \\ -1 & 2 & -2 \\ 2 & 2 & 1 \end{bmatrix} \begin{bmatrix} 2 & -1 & -2 \\ -1 & 2 & -2 \\ 2 & 2 & 1 \end{bmatrix}^{t} \frac{1}{3} = 1/9 \begin{bmatrix} 9 & 0 & 0 \\ 0 & 9 & 0 \\ 0 & 0 & 9 \end{bmatrix} = Id$$

(a) Verify that $\sigma_{...}$ is equal to its conjugate transpose.

 σ_x

$$\begin{bmatrix} 0 & 1+0i \\ 1+0i & 0 \end{bmatrix} = \begin{bmatrix} 0 & 1-0i \\ 1-0i & 0 \end{bmatrix}$$

 σ_y

$$\begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix}$$

 σ_z

$$\begin{bmatrix} 1+0i & 0 \\ 0 & -1+0i \end{bmatrix} = \begin{bmatrix} 1-0i & 0 \\ 0 & -1-0i \end{bmatrix}$$

(b) σ_x

$$0+0=0$$
; $0\cdot 0-1\cdot 1=-1$

 σ_y

$$0+0=0$$
; $0\cdot 0-i^2=-1$

 σ_z

$$1 - 1 = 0$$
; $1 \cdot -1 - 0 \cdot 0 = -1$

(c) $(\sigma_x)^2 = Id$

$$\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

 $(\sigma_y)^2 = Id$

$$\begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

 $(\sigma_z)^2 = Id$

$$\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

 $\sigma_x \sigma_y = -\sigma_y \sigma_x = i\sigma_z$

$$\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} = - \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = i \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

$$\sigma_y \sigma_z = -\sigma_z \sigma_y = i\sigma_x$$

$$\begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} = - \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} = i \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$\sigma_z \sigma_x = -\sigma_x \sigma_z = i\sigma_y$$

$$\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = - \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix}$$

(d)

$$a \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} + b \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} + c \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$
$$\begin{bmatrix} 0 & a \\ a & 0 \end{bmatrix} + \begin{bmatrix} 0 & -bi \\ bi & 0 \end{bmatrix} + \begin{bmatrix} c & 0 \\ 0 & -c \end{bmatrix}$$
$$\begin{bmatrix} c & a - bi \\ a + bi & -c \end{bmatrix}$$

The trace is c - c = 0.

$$det \left(\begin{bmatrix} c & a-bi \\ a+bi & c \end{bmatrix} \right) = c^2 - (a-bi)(a+bi)$$

$$= -c^2 - a^2 - b^2$$

$$= -(a^2 + b^2 + c^2)$$

$$= -(1)$$

$$= -1$$

The determinant is -1.

(f) [Note: Looks like you skipped (e)]

Let $A = \begin{bmatrix} a & b+0i \\ b+0i & -a \end{bmatrix}$, where a, b are real. The trace is a-a=0, and it's also a Hermitian matrix because it's symmetric and real. The determinant is $-a^2-b^2=-1$. All Hermitian matrices meeting our requirements will be of this form. The eigenvalues of this matrix are

$$\det\left(\begin{bmatrix} a-\lambda & b \\ b & -a-\lambda \end{bmatrix}\right) = (a-\lambda)(-a-\lambda) - b^2 = 0$$

$$= -a^2 - b^2 + \lambda^2 = 0$$

$$\lambda^2 = a^2 + b^2$$

$$\lambda^2 = 1$$

$$\lambda = \pm 1$$