

Analysis of Algorithms

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CSCI 570

Lecture 11

University of Southern California

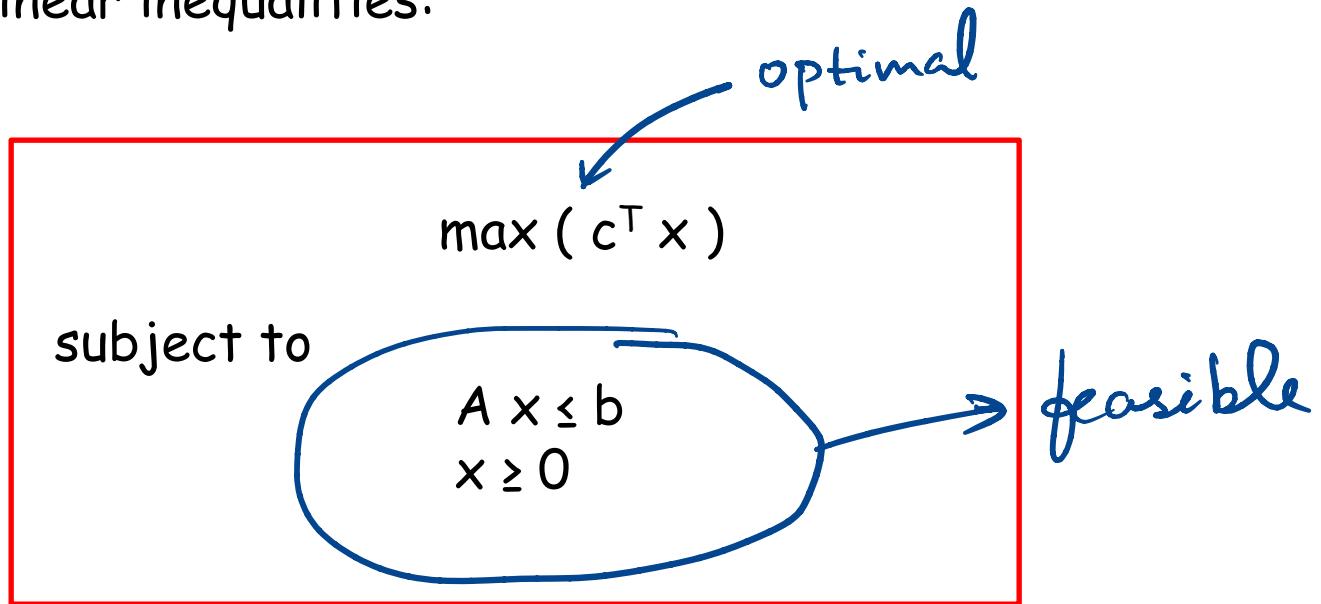
Spring 2023

Linear Programming NP-Completeness

Reading: chapter 8 and 9

Linear Programming

We say that a maximization linear program with n variables is in standard form if for every variable x_k we have the inequality $x_k \geq 0$ and other m linear inequalities:



The LP can be solved in polynomial time for real variables x_k . In case of integer variables, we do not have a polynomial solver.

Dual LP

To every linear program there is a dual linear program

Similar to reduction but not really reduction .



Duality

Definition. The dual of the standard (primal) maximum problem

$$\begin{aligned} \max_x & c^T x \\ Ax &\leq b \text{ and } x \geq 0 \end{aligned}$$

is defined to be the standard minimum problem

$$\begin{aligned} \min_y & b^T y \\ A^T y &\geq c \text{ and } y \geq 0 \end{aligned}$$

Weak Duality

$$\max (c^T x)$$

$$\begin{aligned} Ax &\leq b \\ x &\geq 0 \end{aligned}$$

primal linear
program

$$\min (b^T y)$$

$$\begin{aligned} A^T y &\geq c \\ y &\geq 0 \end{aligned}$$

dual linear program



Weak Duality. The optimum of the dual is an upper bound to the optimum of the primal. ~~•~~

$$\text{opt(primal)} \leq \text{opt(dual)}$$

Theorem (The weak duality).

Let P and D be primal and dual LP correspondingly.

If x is a feasible solution for P and y is a feasible solution for D, then

$$c^T x \leq b^T y$$

Strong Duality

$$\max (c^T x)$$

$$\begin{aligned} A x &\leq b \\ x &\geq 0 \end{aligned}$$

$$\min (b^T y)$$

$$\begin{aligned} A^T y &\geq c \\ y &\geq 0 \end{aligned}$$



Theorem (The strong duality).

Let P and D be primal and dual LP correspondingly.

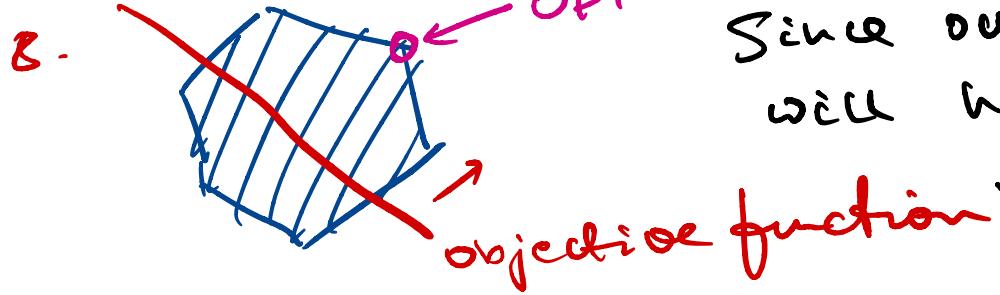
If P and D are feasible, then

$$\underbrace{c^T x}_{\in \mathbb{R}} = b^T y$$

Review Questions

6. (T/F) Every LP has an optimal solution.
7. (T/F) If an LP has an optimal solution it occurs at an extreme point.
8. (T/F) If an LP is feasible and bounded, then it must have an optimal solution.
9. (T/F) An LP allows strict inequalities in the constraints.
10. (T/F) An LP for which the feasible region is unbounded has the finite optimal solution.
11. (T/F) The weak duality theorem does not always hold for an integer linear program. [If the question asks for strong duality then it might be false because here we have integers & not real nos]
12. (T/F) An LP must be infeasible if its dual problem is unbounded.
13. (T/F) Both the primal and the dual can be infeasible.
14. (T/F) There is no duality gap in linear programming.

↳ Since the problem is linear we take that
primal = dual



Since our polygon is bounded we will have an optimal solⁿ at the extreme. If not bounded no guarantee

10. $\max(x) \quad x \geq 0$
 ↳ counter example

11. $C^T x \leq b^T y$

12. $C^T x \leq b^T y \quad \xrightarrow{-\infty} ?$
 because it is $\min(b^T y)$
 \downarrow
 $C^T x \leq -\infty \Rightarrow$ This doesn't make any sense
 hence TRUE

13. TRUE -?
 by Example - In the textbook
 (it is found in the end of his annotated notes)

NP-Completeness



23 Problems of Hilbert



In 1900 Hilbert presented a list of 23 challenging (unsolved) problems in math

#1 The Continuum Hypothesis

impossible, 1963

#8 The Riemann Hypothesis

unproved yet

#10 On solving a Diophantine equations

impossible, 1970

#18 The Kepler Conjecture

proved, 1998

Hilbert's 10th problem

Given a multivariate polynomial with integer coeffs,
e.g. $4x^2y^3 - 2x^4z^5 + x^8$, "devise a process according
to which it can be determined in a finite number of
operations" whether it has an integer root.

Mathematicians: we should try to formalize what
counts as a 'process' and an 'operation'.

?

Hilbert's 10th problem

In 1928 Hilbert rephrased it as follows:

Given a statement in first-order logic,
devise an "effectively calculable procedure"
for determining if it's provable.

Mathematicians: we should try to formalize what counts as an
'calculable procedure' (aka algorithm) and an '**efficient calculable**
procedure'.

Hilbert's conjecture

Hilbert conjectured that any mathematical proposition can be decided (proved true or false) by mechanistic logical methods.

In 1931 it was unexpectedly disproven by Gödel.

Gödel showed that for any formal theory, there will always be undecidable propositions.

Mathematicians started to look for practical techniques (computation) for proving undecidability.

Gödel (1934):

Discusses some ideas for definitions of what functions/languages are “computable”, but isn’t confident what’s a good definition.



Church (1936):

Invents lambda calculus, claims it should be the definition of “computable”.



Gödel and Post (1936):

Argue that Church’s definition isn’t justified.



Meanwhile... a certain British grad. student in Princeton, unaware of all these debates...

In 1935 Alan Turing described a model of computation, known today as the Turing Machine (TM).

A problem P is *computable* (or *decidable*) if it can be solved by a Turing machine that halts on every input.



Alan Turing
(1936, age 22)

We say that P has an *algorithm*.

Turing Machines were adopted in the 1960's, years after his death.

Turing's Inspiration

Human writes symbols on paper

The paper is a sequence of squares

No upper bound on the number of squares

At most finitely many kinds of symbols

Human observes one square at a time

Human has only finitely many mental states

Human can change symbols and change

focus to a neighboring square, but only

based on its state and the symbol it observes

Human acts deterministically

High Level Example of a Turing Machine

The machine that takes a binary string and appends 0 to the left side of the string.

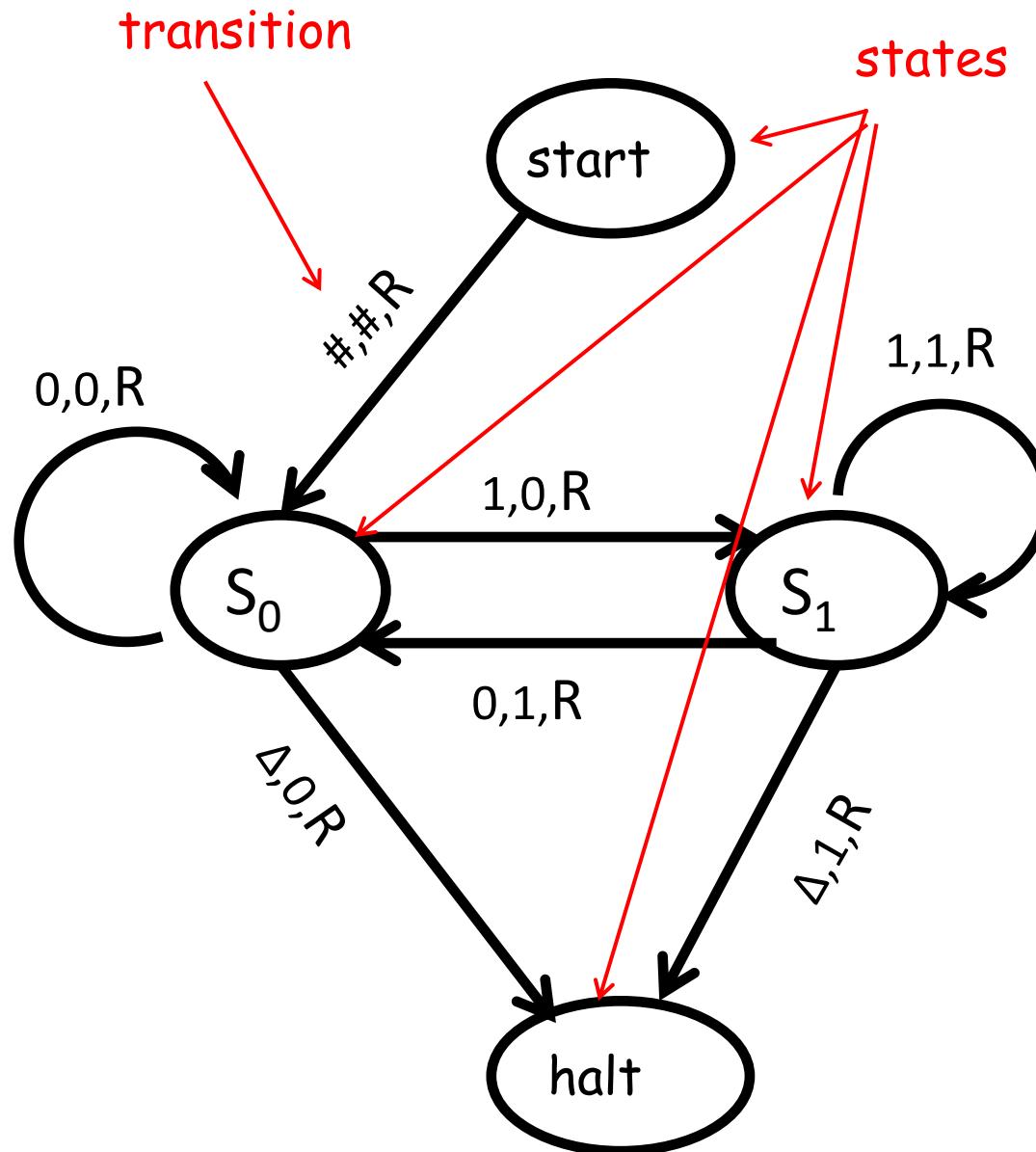
Input: #10010Δ

Output: #010010Δ

- leftmost char

Δ - rightmost char

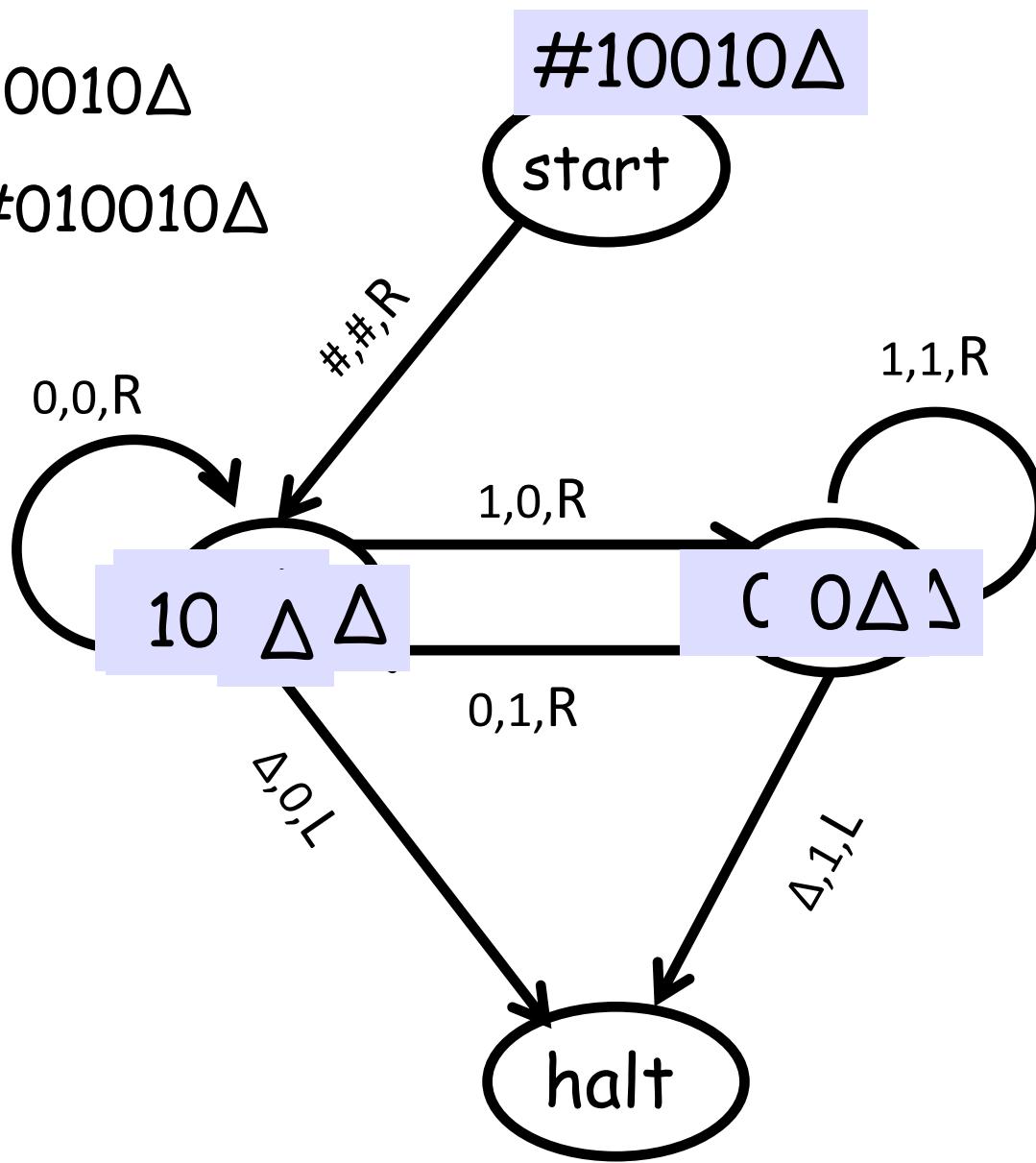
Transition on each edge
read,write,move (L or R)



Deterministic Turing Machine

Input: #10010Δ

Output: #010010Δ



The Church-Turing Thesis

"Any natural / reasonable notion of computation can be simulated by a TM."

This is not a theorem.

Is it... ...an observation?
 ...a definition?
 ...a hypothesis?
 ...a law of nature?
 ...a philosophical statement?

Everyone believes it.

No counterexample yet.

Super-Turing computation

In 1995 Prof. Hava Siegelmann proposed Artificial Recurrent Neural Networks (ARNN).

She proved mathematically that ARNNs have computational powers that extend the TM.

She claims that ARNNs can “compute” Turing non-computable functions.

As of today, the statement is not proven nor disproven.

Runtime Complexity

A problem P is *decidable* if it can be solved by a Turing machine that always halts.

Let M be a Turing Machine that halts on all inputs.

Assume we compute the running time purely as a function of the length of the input string.

Definition: The running complexity is the function $f : N \rightarrow N$ such that $f(n)$ is the maximum number of steps that M uses on any input of length n .

Complexity Classes



A fundamental complexity class P (or PTIME) is a class of decision problems that can be solved by a deterministic Turing machine in polynomial time.

A fundamental complexity class EXPTIME is a class of decision problems that can be solved by a deterministic Turing machine in $O(2^{p(n)})$ time, where $p(n)$ is a polynomial.

Undecidable Problems

Undecidable means that there is no computer program that always gives the correct answer: it may give the wrong answer or run forever without giving any answer.

The halting problem is the problem of deciding whether a given Turing machine halts when presented with a given input.

Turing's Theorem: The Halting Problem is not decidable.

Why is the Halting Problem so important?

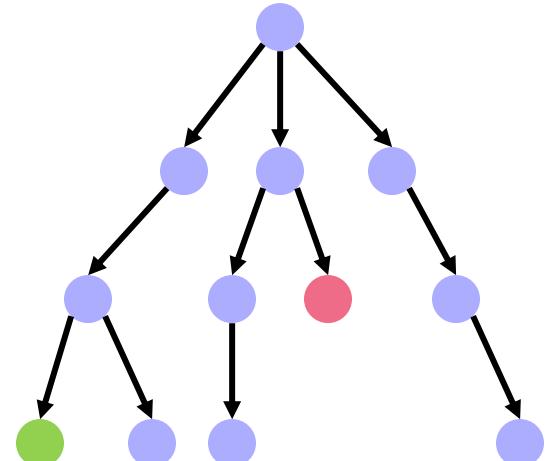
Because a lot of really practical problems are the halting problem in disguise.

Nondeterministic Turing Machine

The deterministic Turing machine means that there is only one valid computation starting from any given input. A computation path is like a linked list.

Nondeterministic Turing machine (NDTM) defined in the same way as deterministic, except that a computation is like a tree, where at any state, it's allowed to have a number of choices.

One way to visualize NDTM is that it makes an exact copy of itself for each available transition, and each machine continues the computation.



Complexity Class: NP



A fundamental complexity class NP is a class of decision problems that can be solved by a nondeterministic Turing machine in polynomial time.

Equivalently, the NP decision problem has a certificate that can be checked by a polynomial time deterministic Turing machine.

We will be using the last definition for proving NP completeness.

P versus NP

It has been proven that Nondeterministic TM can be simulated by Deterministic TM. Rabin & Scott in 1959 shown that adding nondeterminism does not result in more powerful machine.

But how fast we can do that simulation?

The famous **P \neq NP conjecture**, would answer that we cannot hope to simulate nondeterministic Turing machines very fast (in polynomial time).

P and NP complexity classes

P = set of problems that can be solved in polynomial time by a deterministic TM.

NP = set of problems for which solution can be verified in polynomial time by a deterministic TM.

Polynomial Reduction: $Y \leq_p X$

To reduce a decision problem Y to a decision problem X (we write $Y \leq_p X$) we want a function f that maps Y to X such that:

- 1) f is a polynomial time computable
- 2) $\forall y \in Y$ (y is instance of Y) is YES if and only if $f(y) \in X$ is YES.

We use this to prove NP completeness:

knowing that Y is hard, we prove that X is at least as hard as Y .

$$Y \leq_p X$$

If we can solve X in polynomial time,
we can solve Y in polynomial time.

Examples:

Bipartite Matching \leq_p Max-Flow

Circulation \leq_p Max-Flow

known to be hard ← Y \leq_p X

If we can solve X, we can solve Y.

The contrapositive of the statement "if A, then B"
is "if not B, then not A."

If we cannot solve Y, we cannot solve X.

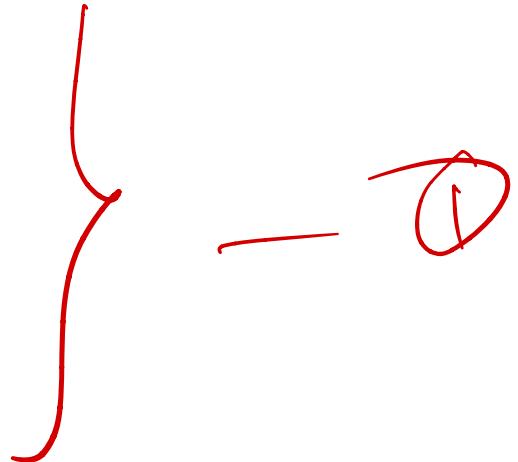
Knowing that Y is hard, we prove that X is harder.

In plain form: X is at least as hard as Y.

Two ways of using $Y \leq_p X$

1) Knowing that X is easy

If we can solve X in polynomial time,
we can solve Y in polynomial time.



2) Knowing that Y is hard

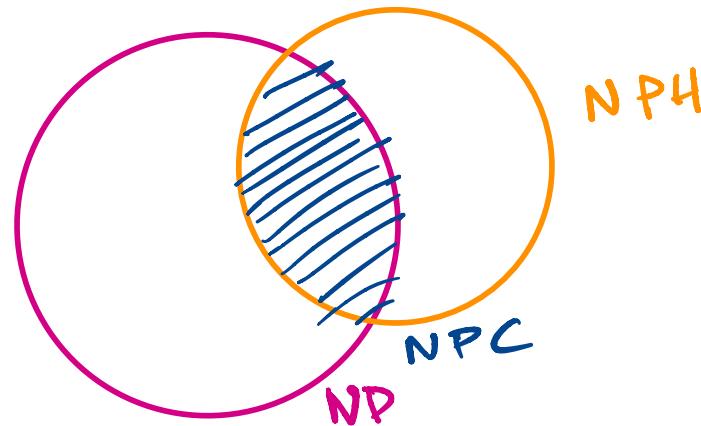
Then we can prove that X is at least as hard as Y



NP-Hard and NP-Complete

X is *NP-Hard*, if $\forall Y \in \text{NP}$ and $Y \leq_p X$.

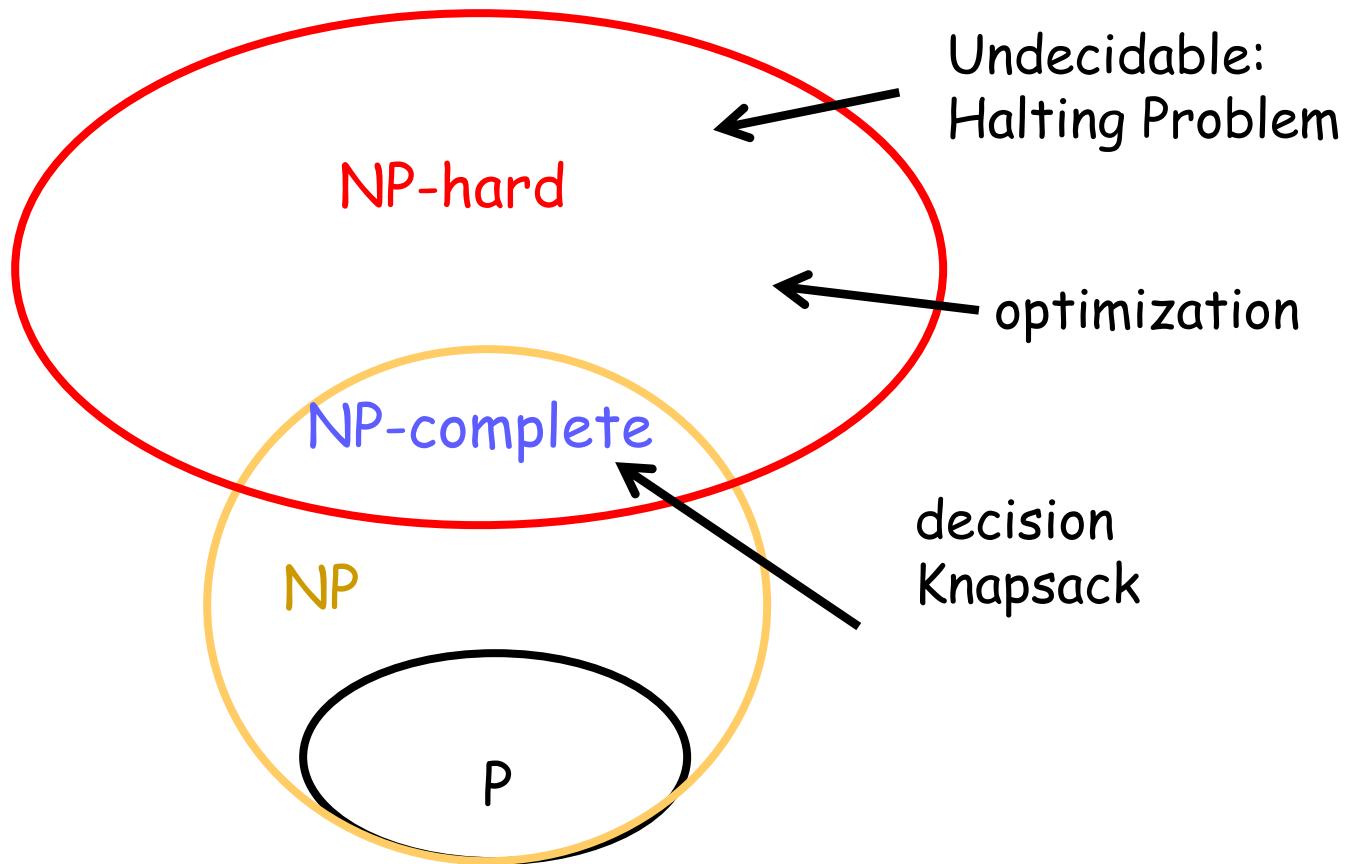
X is *NP-Complete*, if X is NP-Hard and $X \in \text{NP}$.



Venn Diagram ($P \neq NP$)

NPH problems
do not have to be
in NP.

NPC problems are
the most
difficult NP
problems.



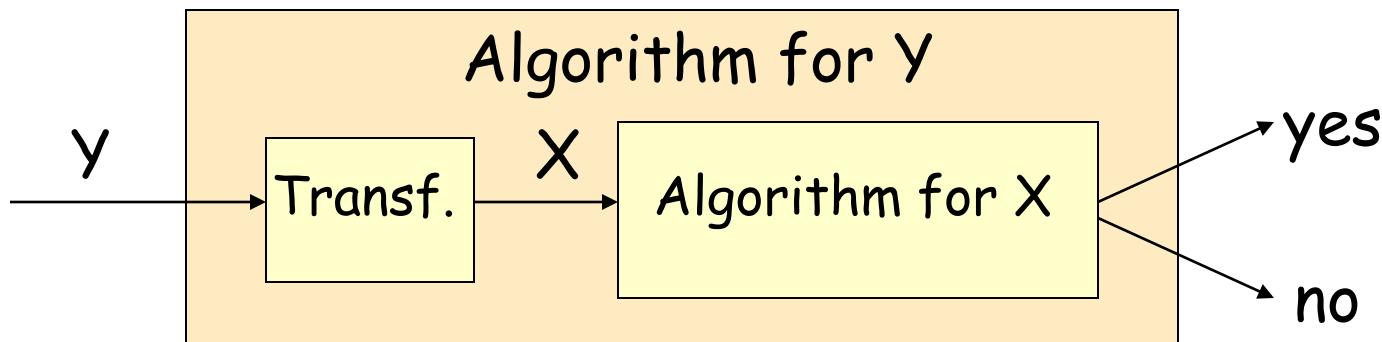
It's not known if NPC problems can be solved by a deterministic TM in polynomial time.

Imagine $P = NP \rightarrow NPC = P$
 $NPH = NPH$

NP-Completeness Proof Method

To show that X is NP-Complete:

- 1) Show that X is in NP
- 2) Pick a problem Y , known to be an NP-Complete
- 3) Prove $Y \leq_p X$ (reduce Y to X)



Boolean Satisfiability Problem (SAT)

A propositional logic formula is built from variables, operators AND (conjunction, \wedge), OR (disjunction, \vee), NOT (negation, \neg), and parentheses:

$$(X_1 \vee \neg X_3) \wedge (X_1 \vee \neg X_2 \vee X_4 \vee X_5) \wedge \dots \rightarrow \text{True}$$

A formula is said to be satisfiable if it can be made TRUE by assigning appropriate logical values (TRUE, FALSE) to its variables.

A formula is in conjunctive normal form (**CNF**) if it is a conjunction of clauses.

A **literal** is a variable or its negation.

A **clause** is a disjunction of literals.

What does each thing mean here?

Cook-Levin Theorem (1971)

Theorem. CNF SAT is NP-complete.

The proof of this theorem is outside of the scope of this course.

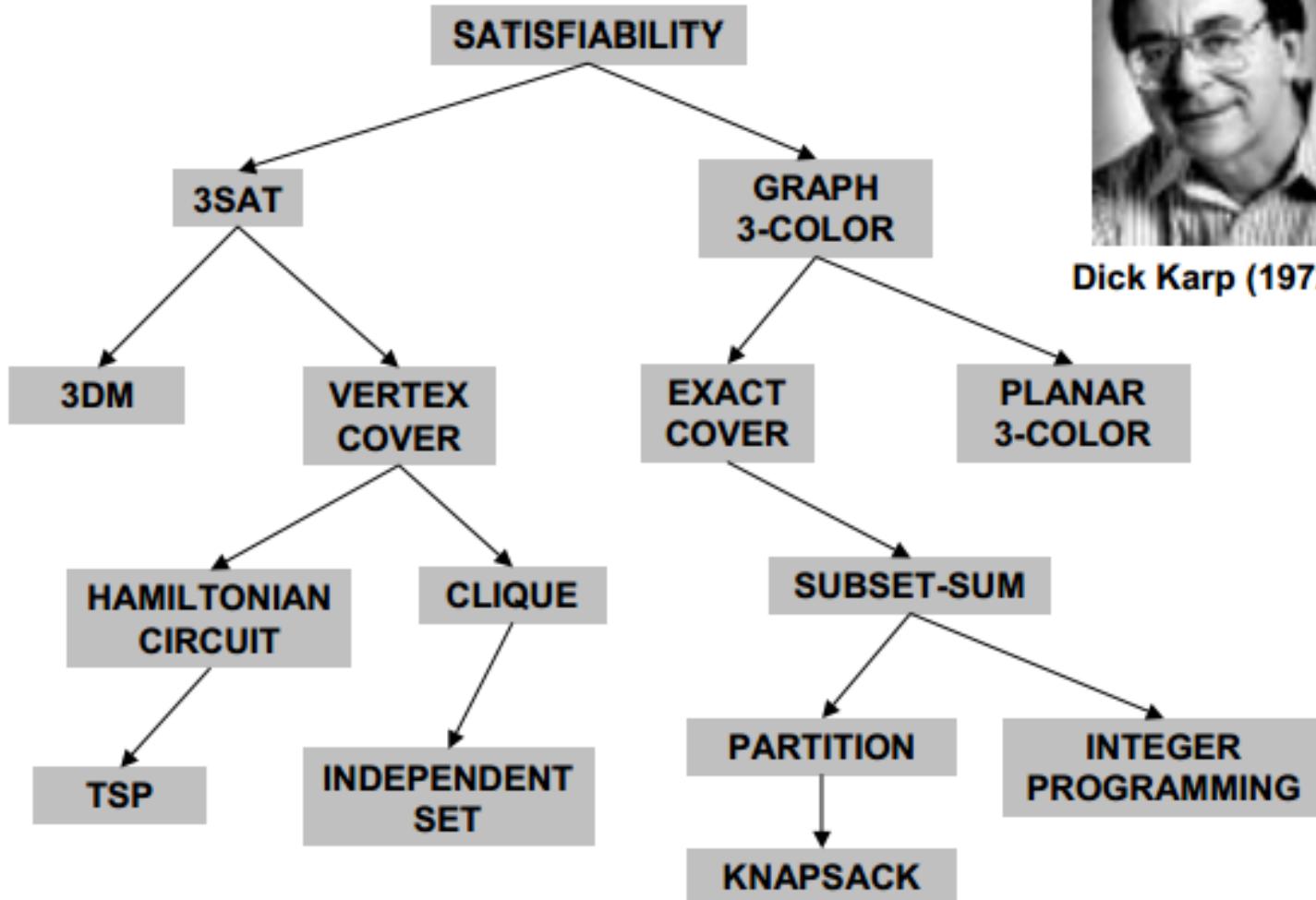
Cook received a Turing Award for his work.

You are not responsible for knowing the proof.

Reduction



Dick Karp (1972)



Karp introduced the now standard methodology for proving problems to be NP-Complete.

He received a Turing Award for his work (1985).

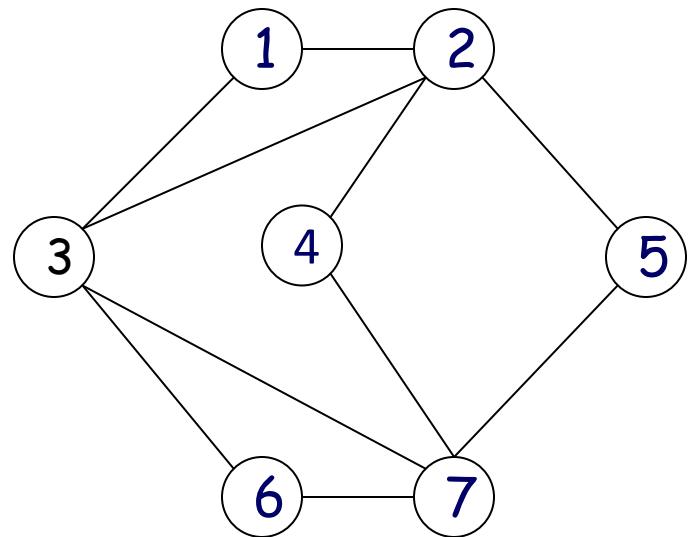
Independent Set



Given a graph, we say that a subset of vertices is "independent" if no two of them are joined by an edge.

$$\begin{aligned}IS &= \{1\} \\&= \{3, 4\} \\&= \{1, 4, 5\}\end{aligned}$$

The maximum independent set problem, **MaxIndSet**, asks for the size of the largest independent set in a given graph.



Independent Set

Optimization Version (**MaxIndSet**):

Given a graph, find the largest independent set. \Rightarrow NP-Hard

Decision Version (**IndSet**):

\Rightarrow NP-Complete

Given a graph and a number **k**, does the graph contains an independent set of size **k**?

Optimization vs. Decision

Optimization vs. Decision Problems

$\text{OPT} \rightarrow \text{decision}$

If one can solve an optimization problem (in polynomial time), then one can answer the decision version (in polynomial time)

$\text{decision} \rightarrow \text{OPT}$

Conversely, by doing binary search on the bound b , one can transform a polynomial time answer to a decision version into a polynomial time algorithm for the corresponding optimization problem

In that sense, these are essentially equivalent.
However, they belong to two different complexity classes.

Independent Set is NP Complete

Given a graph and a number k , does the graph contains an independent set of size k ?

Is it in NP?

We need to show we can verify a solution in polynomial time.

Given a set of vertices, we can easily count them and then verify that any two of them are not joined by an edge.

Independent Set is NP Complete

Given a graph and a number k , does the graph contains an independent set of size k ?

Is it in NP-hard?

We need to pick Y such that $Y \leq_p \text{IndSet}$ for $\forall Y \in \text{NP}$

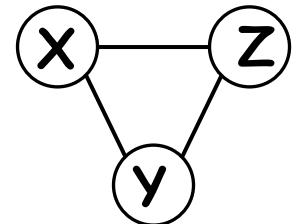
Reduce from 3-SAT.

3-SAT is SAT where each clause has at most 3 literals.

$3SAT \leq_p IndSet$

We construct a graph G that will have an independent set of size k iff the 3-SAT instance with k clauses is satisfiable.

For each clause $(X \vee Y \vee Z)$ we will be using a special gadget:



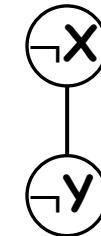
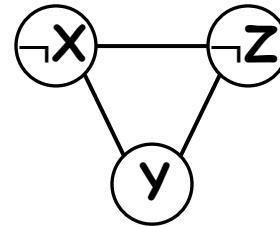
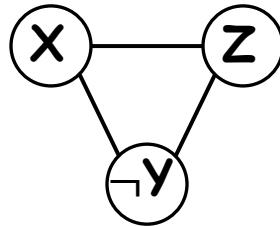
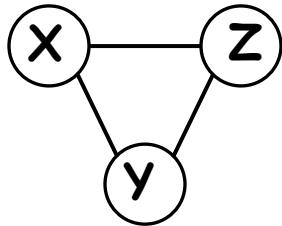
Next, we need to connect gadgets.

As an example, consider the following instance:

$$(X \vee Y \vee Z) \wedge (X \vee \neg Y \vee Z) \wedge (\neg X \vee Y \vee \neg Z) \wedge (\neg X \vee \neg Y)$$

$3SAT \leq_p IndSet$

$$(X \vee Y \vee Z) \wedge (X \vee \neg Y \vee Z) \wedge (\neg X \vee Y \vee \neg Z) \wedge (\neg X \vee \neg Y \vee \neg Z)$$

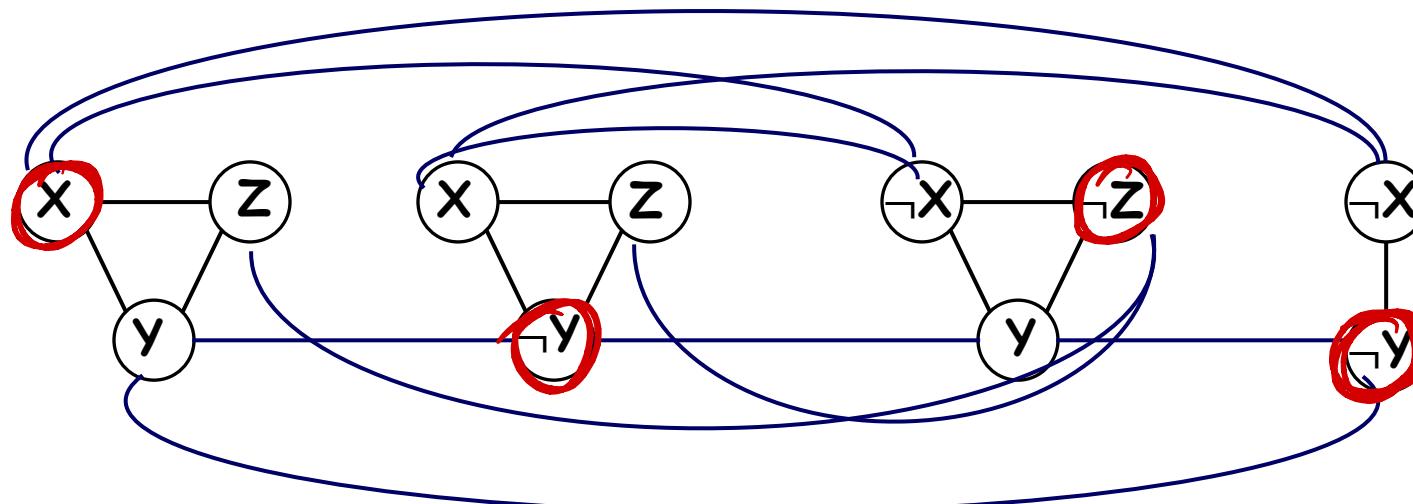


How do we connect gadgets?

Claim:

$3SAT \leq_p IndSet$

$$(X \vee Y \vee Z) \wedge (X \vee \neg Y \vee Z) \wedge (\neg X \vee Y \vee \neg Z) \wedge (\neg X \vee \neg Y)$$



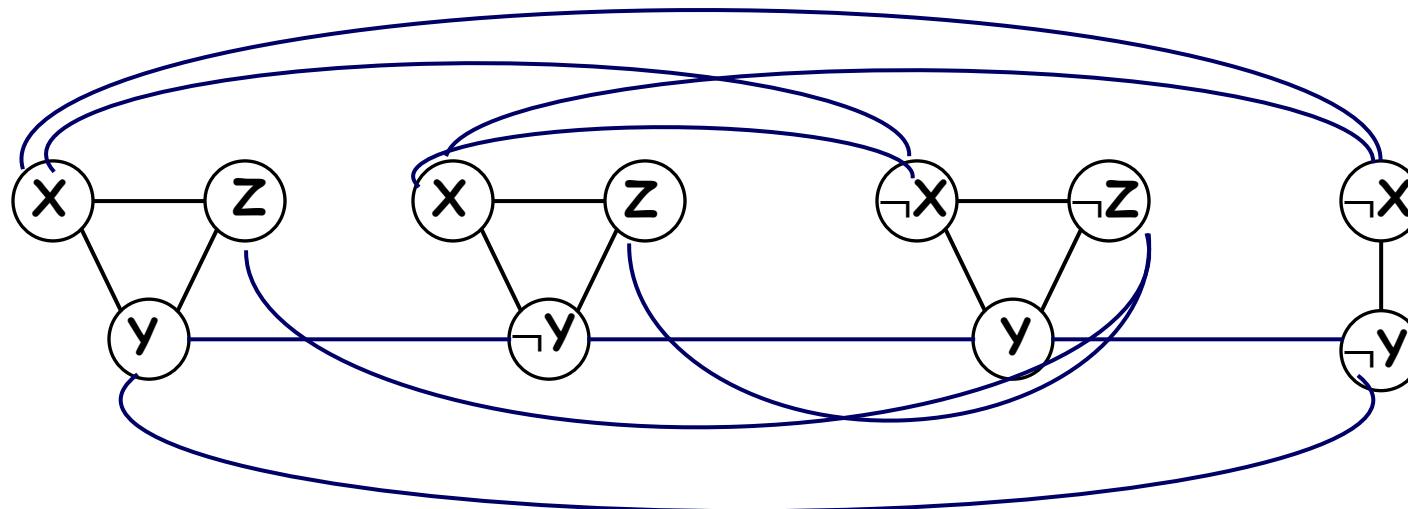
Proof. \Rightarrow Given 3SAT satisfiable

For example , $X = T$
 $\neg Y = T$
 $\neg Z = T$

Goal : set an IS. true literals make an IS.

$3SAT \leq_p IndSet$

$$(X \vee Y \vee Z) \wedge (\underline{X} \vee \neg Y \vee Z) \wedge (\neg X \vee Y \vee \neg Z) \wedge (\neg X \vee \neg Y) = \top$$



Proof. \Leftarrow Given a triangular graph G $|IS(G)| = k$
Goal : to get an assignment

$$x = \top, \neg z = \top, \neg y = \top$$

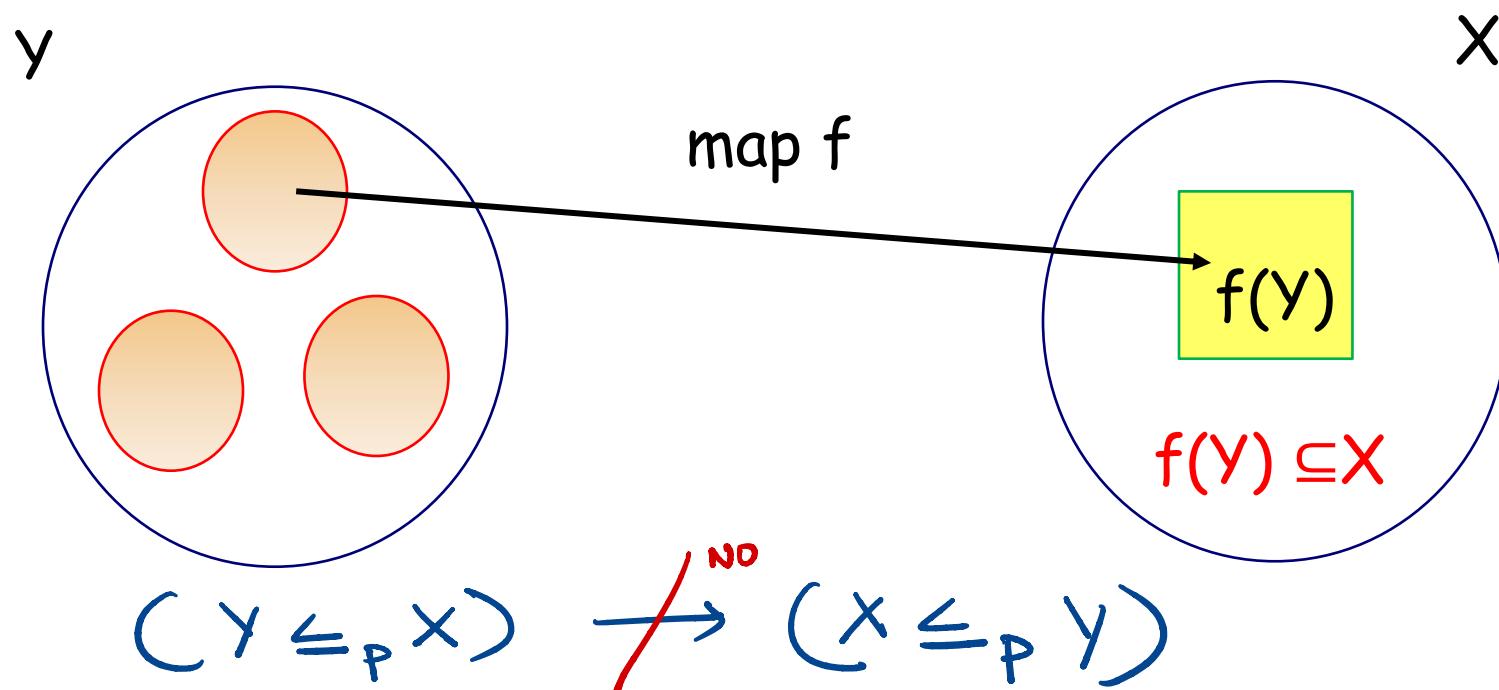
~~-X~~ - $\forall Y \rightarrow \exists X$ ~~-X~~ ~~-X~~ ~~-X~~

The confusing point is that the reduction $Y \leq_p X$ only "works one way", but the correctness proof needs to "work both ways".

The correctness proofs are not actually symmetric.

The proof needs to handle **arbitrary** instances of Y , but only needs to handle the **special** instances of X produced by the reduction.

This asymmetry is the key to understanding reductions.



$3SAT \leq_p IndSet$

Reduction from 3SAT to IndSet consists of three parts:

- we transform an arbitrary CNF formula into a special graph G and a specific integer k , in polynomial time.
- we transform an arbitrary satisfying assignment for 3SAT into an independent set in G of size k .
- we transform an arbitrary independent set (in G) of size k into a satisfying assignment for 3SAT.

The General Pattern $Y \leq_p X$

1. Describe a polynomial-time algorithm to transform an arbitrary instance of Y into a special instance of X .
2. Prove that if an instance of Y is True, then an instance of X is True.
3. Prove that if an instance of X is True, then an instance of Y is True. (This part causes the most trouble.)



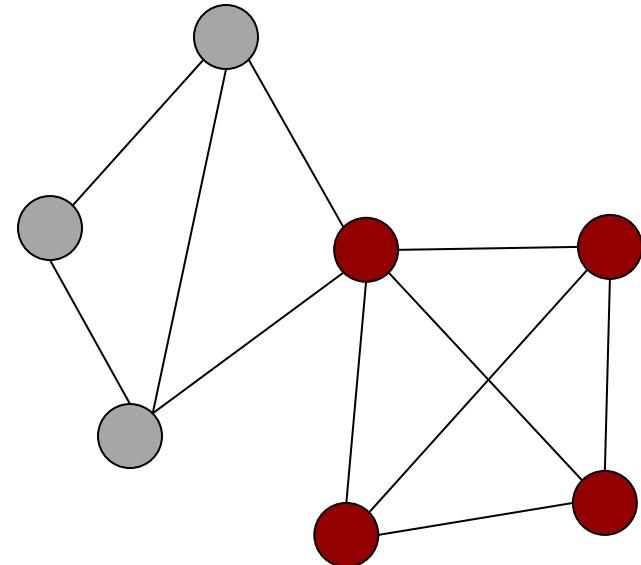
Clique

A clique is another name for a complete graph, that is, a graph where every pair of vertices is connected by an edge.

The MaxClique problem asks for the number of vertices in its largest complete subgraph in a given graph

We can prove that MaxClique is NP-hard using the following easy reduction from IndSet.

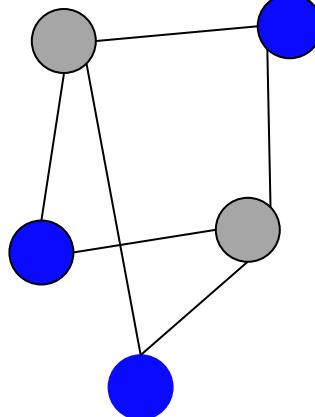
$\text{MaxClique} \leq_p \text{MaxIndSet}$



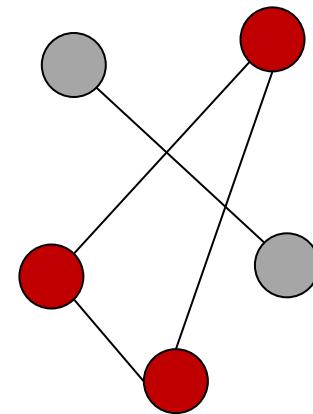
$\text{MaxClique} \leq_p \text{MaxIndSet}$

Any graph $G=(V, E)$ has a **complement** graph $G'=(V, E')$, where edge $(u, v) \in E'$ if and only if $(u, v) \notin E$. In other words, $G \cup G'$ is a complete graph.

Consider the largest Independent Set in G .



Consider the largest Clique in G' .



The largest independent in G has the same vertices (and thus the same size) as the largest clique in the complement of G .

Analysis of Algorithms

V. Adamchik

CSCI 570

Lecture 12

University of Southern California

Fall 2023

NP-Completeness - II

Reading: chapter 9

In 1936 Alan Turing described:

- A simple formal model of computation now known as Turing machines.
- A proof that TM can NOT solve the halting problem.
- A proof that NO Turing machine can determine whether a given proposition is provable from the axioms of first-order logic.
- Compelling arguments that a problem not computable by a Turing machine is not "computable" in the absolute (human) sense.
- A non-deterministic Turing machine: for each state it makes an arbitrary choice between a finite of possible transitions.

Non-Deterministic Turing Machine

- NDTM is a choice machine: for each state it makes an arbitrary choice between a finite (possibly zero) number of states.
- The computation of a NDTM is a tree of possible configuration paths.
- One way to visualize NDTM is that it makes an exact copy of itself for each available transition, and each machine continues the computation.
- Rabin & Scott in 1959 shown that adding non-determinism does not result in more powerful machine.
- For any NDTM, there is a DTM that accepts and rejects exactly the same strings as NDTM.
- P vs. NP is about whether we can simulate NDTM in **polynomial time**.

Complexity Classes

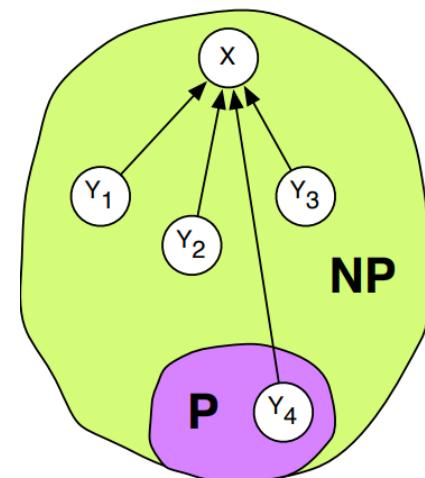
P = set of problems that can be solved in polynomial time by a DTM.

NP = set of problems that can be solved in polynomial time by a NDTM.

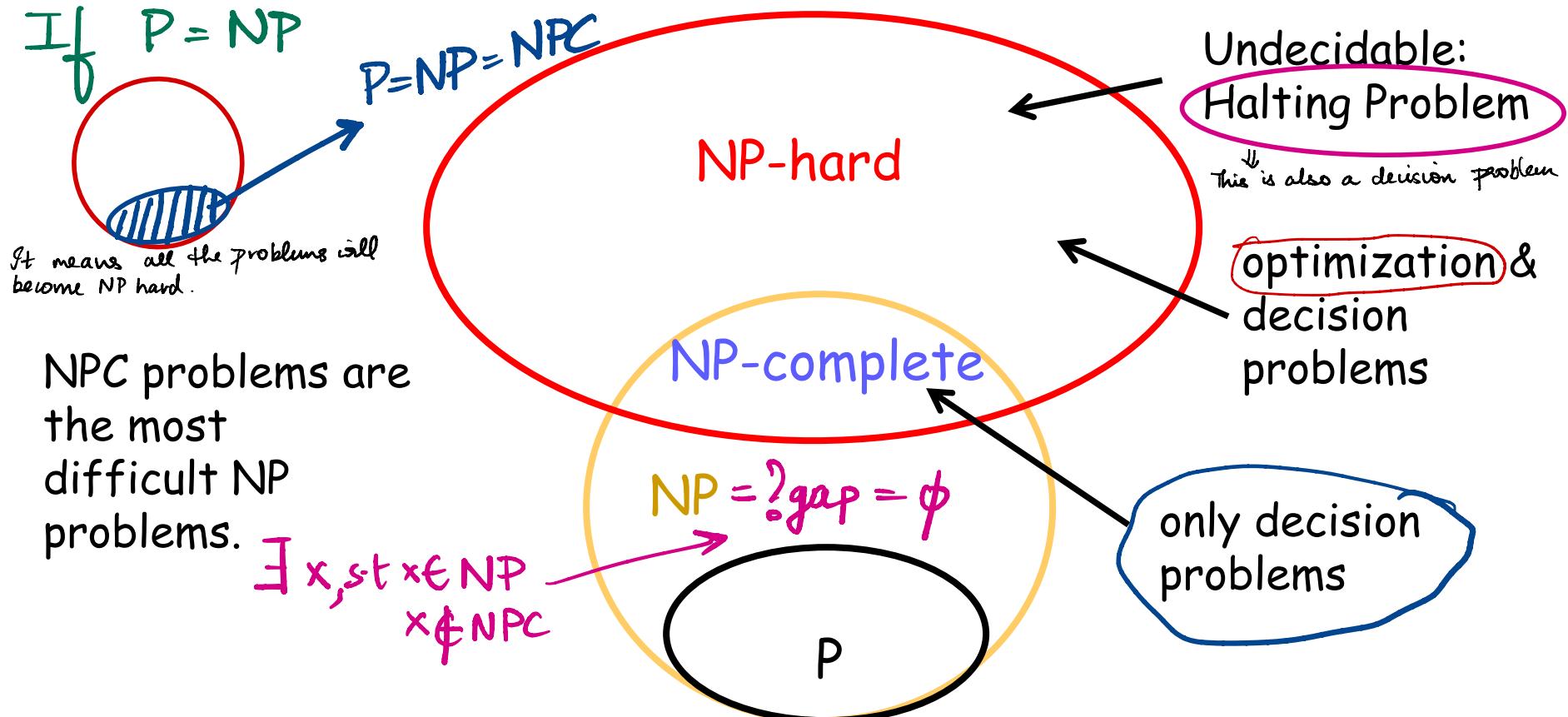
NP = set of problems for which solution can be verified in polynomial time by a deterministic TM.

X is **NP-Hard**, if $\forall Y \in NP$ and $Y \leq_p X$.

X is **NP-Complete**,
if X is NP-Hard and $X \in NP$.



Venn Diagram ($P \neq NP$)



It's not known if NPC problems can be solved by a deterministic TM in polynomial time.

NPC problems can be solved by a **non-deterministic** TM in polynomial time.

Victor's Additional True / False Questions:

① NP complete has all decision problems
⇒ TRUE !!

② All decision problems belong to NP complete
⇒ FALSE !!!

NP-Complete Problems

Cook-Levin Theorem: CNF SAT is NP-complete.



Independent Set:

Given graph G and a number k , does G contain a set of at least k independent vertices?

Vertex Cover:

Given a graph G and a number k , does G contain a vertex cover of size at most k .

A Hamiltonian cycle:

Given a graph G , does G contain a cycle that visits each vertex exactly once.

NP-Completeness Proof Method

To show that X is NP-Complete:

- 1) Show that X is in NP
- 2) Pick a problem Y, known to be an NP-Complete
- 3) Prove $Y \leq_p X$ (reduce Y to X)

Step to follow
in exam

In lecture 11 we have proved that **Independent Set** is NP-Complete by reduction from 3-SAT ($3SAT \leq_p IndSet$)

Reduction from 3SAT to IndSet consists of three parts:

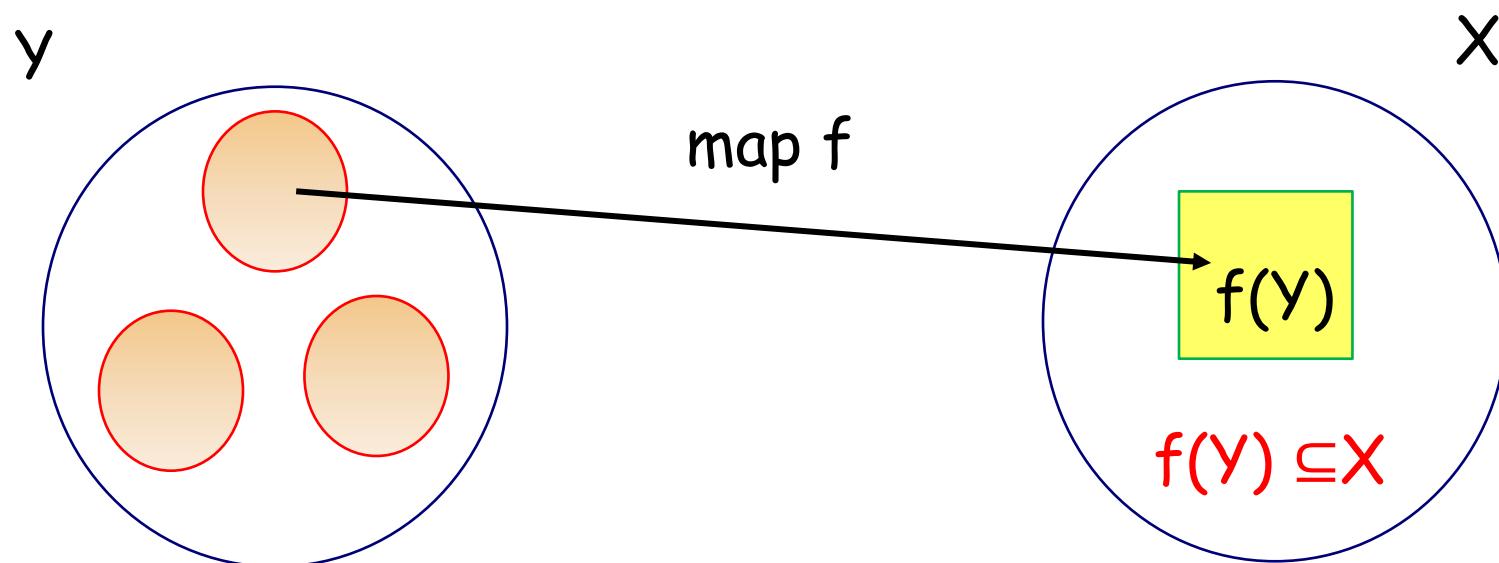
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- we transform an arbitrary satisfying assignment for 3SAT into an independent set in G of size k.
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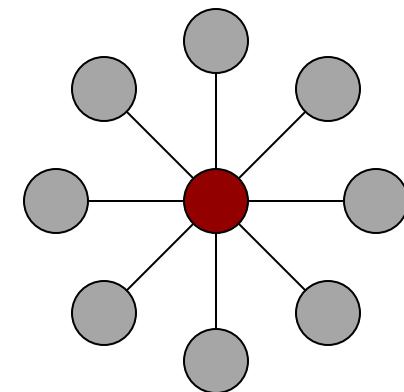




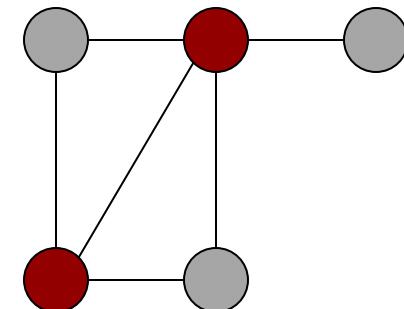
Vertex Cover

Given $G=(V,E)$, find the smallest $S \subset V$ s.t. every edge is incident to vertices in S .

$$VC \cup IS = V$$



The minimum vertex cover problem, **MinVC**, asks for the size of the smallest vertex cover in a given graph.

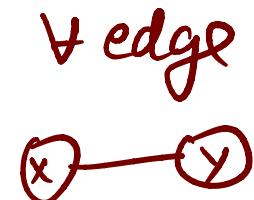


Vertex Cover

Theorem: for a graph $G=(V,E)$, S is an independent set if and only if $V-S$ is a vertex cover

Proof. \Rightarrow S is an IS

① $x \in S$, then $y \notin S$
then $y \in V-S$



② $y \in S$, $\Rightarrow x \in S \Rightarrow x \in V-S$

③ $x, y \notin S \Rightarrow x, y \in V-S$

Vertex Cover

Theorem: for a graph $G=(V,E)$, S is a independent set if and only if $V-S$ is a vertex cover

Proof. \Leftarrow) Given a VC

Pick $\forall x, y$ s.t. $x \notin \text{VC}$, $y \notin \text{VC}$

such that

is it possible? \Rightarrow Ask yourself

$\text{edge}(x,y) - ?$ \Rightarrow This means that there is no edge between
 x & y

It follows, $x, y \in \text{IS}$

\Downarrow
This is because there is no edge between x & y

I THINK VICTOR MADE A MISTAKE ON HIS VIDEO

Min Vertex Cover in NP-Hard

$$\text{MaxIndSet} \leq_p \text{MinVC}$$

By the previous theorem.

Vertex Cover in NP-Complete

Claim: a graph $G=(V,E)$ has an independent set of size at least k if and only if G has a vertex cover of size at most $V-k$.

!!!

$$\text{Ind. Set} \leq_p \text{Vertex Cover}$$

By the previous theorem.

Discussion Problem 1

Show that vertex cover remains NP-Complete even if the instances are restricted to graphs with only even degree vertices. Let us call this problem VC-even.

Prove: $VC \leq_p VC\text{-even}$

$VC\text{-even}$: Given graph G_s with even degrees and number K

① $VC\text{-even} \in NP$, prove it!! \Rightarrow Given a solution for the $VC\text{-even}$ problem, the solution can be verified & validated in polynomial time. Hence, $VC \in NP$

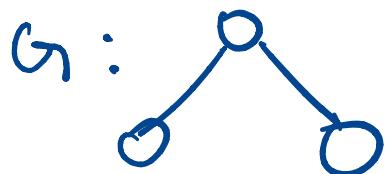
② $VC\text{-even} \in NP\text{-Hard}$:

P.T.O

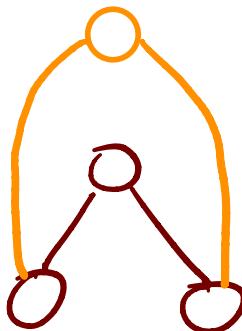
Given a graph with even degree,
there are even no of vertices
with odd degrees.

$$VC \leq_p VC\text{-even}$$

Let graph G_1 be the following :



$$G'_1 :$$



Construct G'_1 with all vertices having even degrees.

claim : $VC(G_1) = k$ iff $VC(G'_1) = k+1$

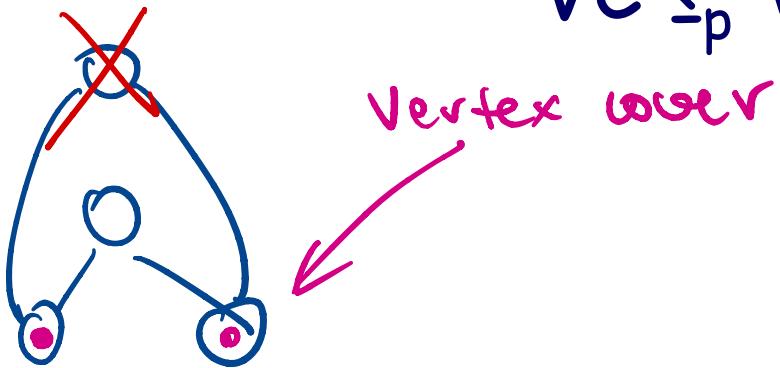


Proof:

\Rightarrow by construction, $VC(G'_1) = VC(G_1) + 1$
 $= k + 1$

\Leftarrow Given $VC(G'_1) = k+1$

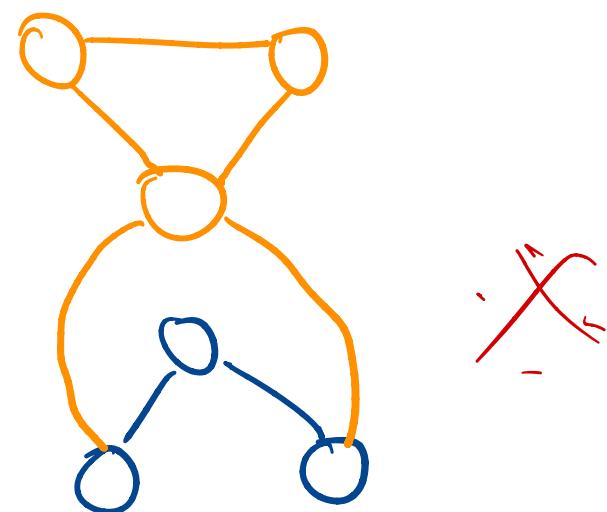
remove a vertex!

$$VC \leq_p VC\text{-even}$$


so, removing a vertex does not mean that the VC changes.

Our construction is wrong!!

New construction


$$G'$$


$VC \leq_p VC\text{-even}$

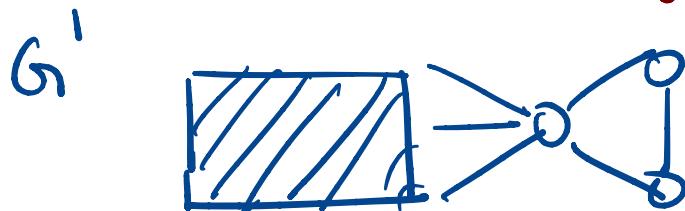
Claim: $VC(G) = k \iff VC(G') = k+2$

Proof

\Rightarrow By construction

\Leftarrow Given a $VC(G') = k+2$

Remove a triangle



In such a case removing a triangle from G' will give you $VC(G) = k$

Hamiltonian Cycle Problem

A Hamiltonian cycle (HC) in a graph is a cycle that visits each vertex exactly once.



Problem Statement:

Given a directed or undirected graph $G = (V,E)$. Find if the graph contains a Hamiltonian cycle.

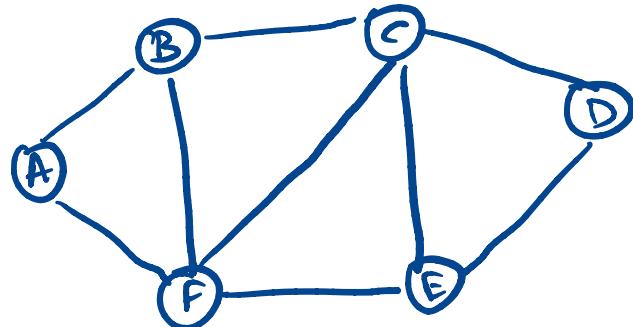
We can prove it that HC problem is NP-complete by reduction from SAT, but we won't.

Discussion Problem 2

Assuming that finding a Hamiltonian Cycle (HC) in a graph is NP-complete, prove that finding a Hamiltonian Path is also NP-complete. HP is a path that visits each vertex exactly once and isn't required to return to its starting point.

- ① $HP \in NP$, given a hamiltonian path we can verify its validity in polynomial time by traversing that path.
- ② $HP \in NPH$ ($HC \leq_p HP$)
 - a) construct a polynomial mapping
 - b) make a claim
 - c) prove the claim in both directions

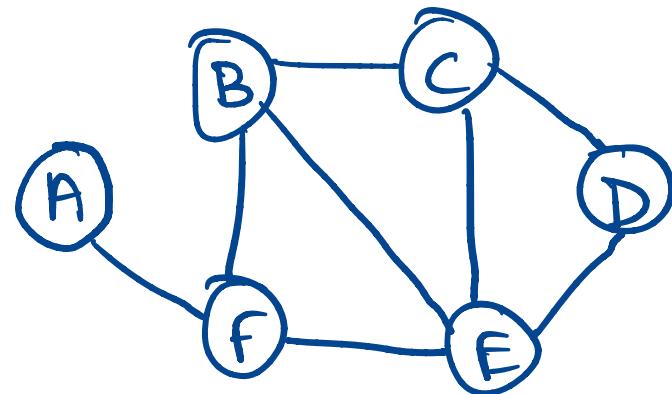
$G:$



$$HC(G) = AFEDCBA$$

Construct G'

G'

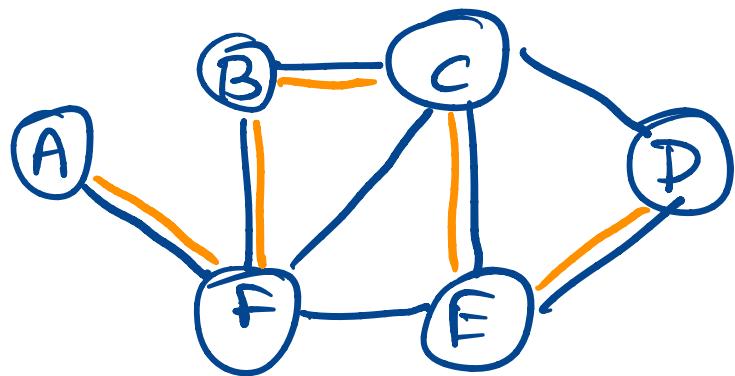


Claim : G has a HC $\iff G'$ has a HP

Proof:

⇒ By construction, if there is a given hamiltonian cycle then there should exist a hamiltonian path.

← Given a hamiltonian path $HC(G')$
Goal: get a HC in G

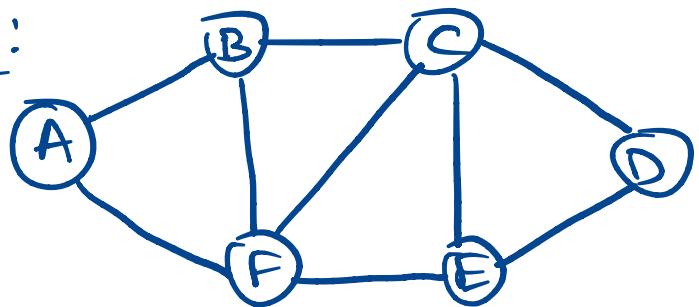


We cannot do anything
to this to get a
Hamiltonian cycle,

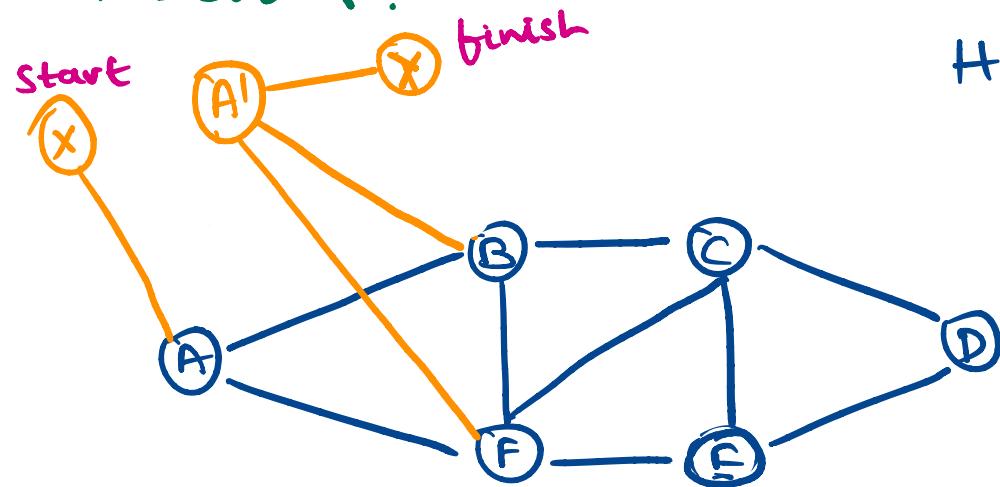


WRONG CONSTRUCTION!

G:



Construction :



$$HC(G) = AFEDCBA$$

$$HP(G) = XAFEDCBA'Y$$

vertex X : any vertex v

vertex A' : adjacent to v

vertex Y : adjacent to A'

P.T.D

Claim: G has a HC $\iff G'$ has a HP

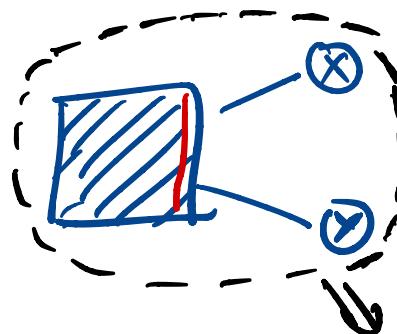
Proof

\Rightarrow By construction, HP

ASK ANANNYA

\Leftarrow Given a hamiltonian path $HPC(G')$

Goal: HC(G)

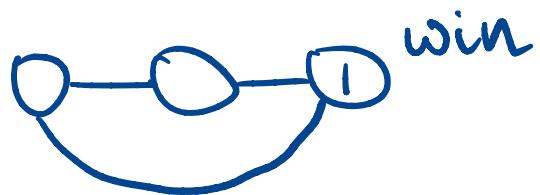
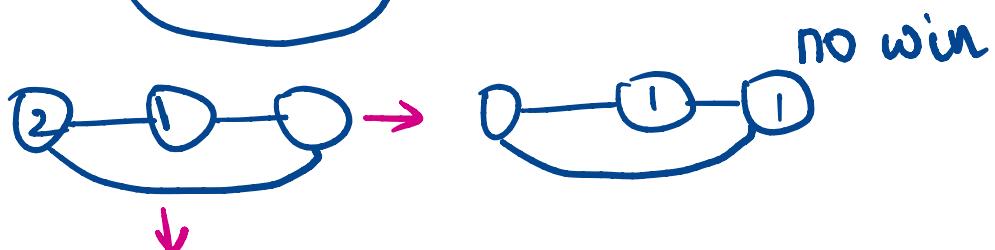
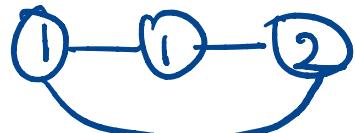
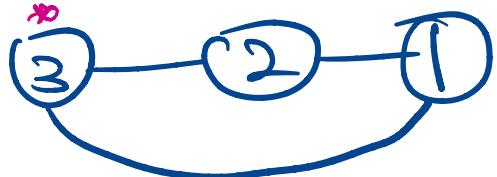


We need to have the A' vertex in the above node to guarantee that given a graph has a hamiltonian path, there exists a path that creates an hc.

Discussion Problem 3

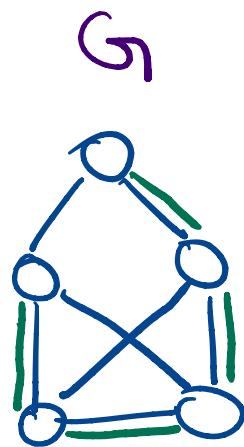
You are given an undirected graph $G = (V, E)$ and for each vertex v , you are given a number $p(v)$ that denotes the number of pebbles placed on v . We will now play a game where the following move is the only move allowed. You can pick a vertex u that contains at least two pebbles, and remove two pebbles from u and add one pebble to **an adjacent** vertex. The objective of the game is to perform a sequence of moves such that we are left with exactly one pebble in the whole graph. Show that the problem of deciding if we can reach the objective is NP-complete. Reduce from the Hamiltonian Path problem.

$HP \leq_p \text{pebbles}$

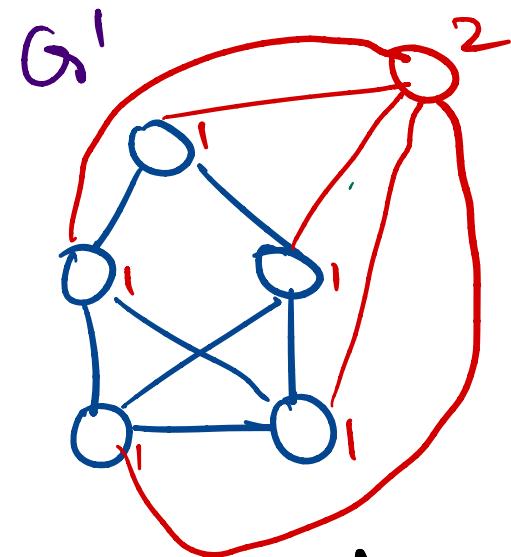


- ① Pebbles \in NP, given the final result based it to polynomial time to check how many pebbles exist in the solution.
- ② HP \leq_p Pebbles

Construction



Convert into pebble game by assigning pebbles to each vertex



We have created this construction intentionally to prove our point. Constructing like this will force us to make a single move & no cycles.

Claim: G_r has a HP $\iff G_r'$ has a winning sequence

\Rightarrow Given : G_r has a HP

Goal : Find a winning sequence

Example

2 1 1 1 1 1

0 2 1 1 1 1

0 0 2 1 1 1

0 0 0 2 1 1

0 0 0 0 2 1

0 0 0 0 0 2

0 0 0 0 1 0

follow the path

\Leftarrow Given : G_r' has a winning sequence

Goal: Find HP in G_r .

We wont visit the same vertex twice, except the last move, hence this proves that there exists a HP. & Hence NP-Hard.

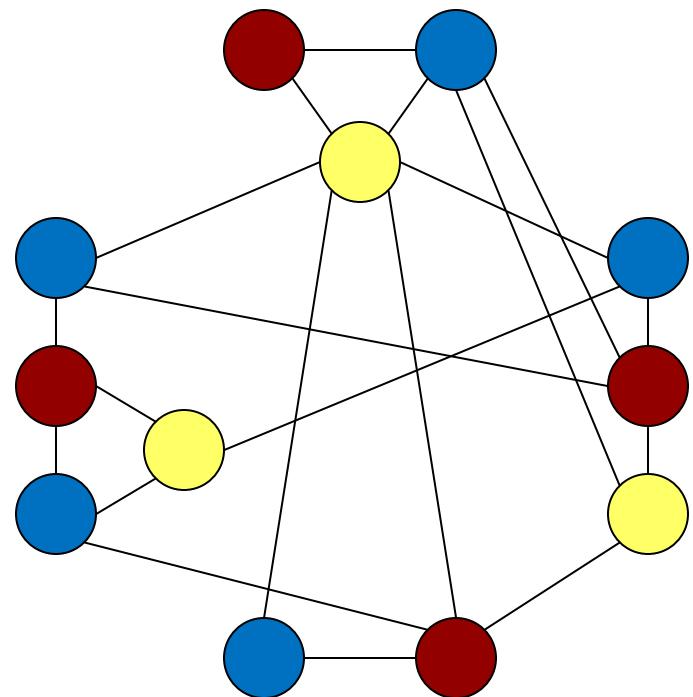
Graph Coloring



Given a graph, can you color the nodes with $\leq k$ colors such that the endpoints of every edge are colored differently?

- ① Planar, $K = 4$
- ② $K = 2$

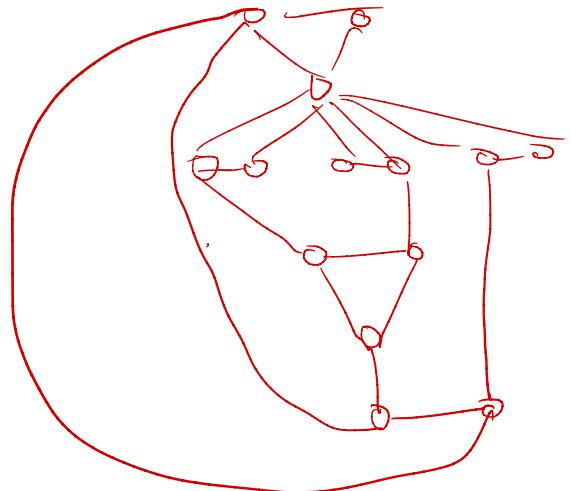
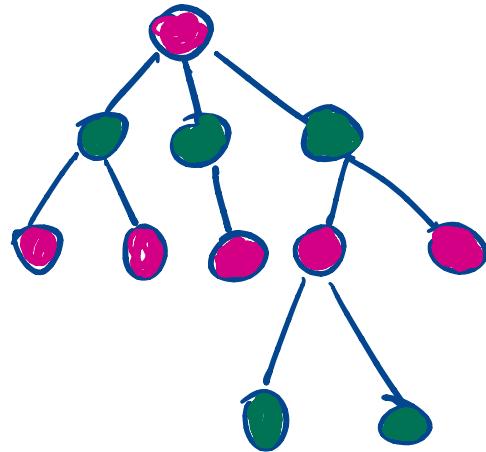
Theorem. ($k > 2$)
 k -Coloring is NP-complete.



Graph Coloring: $k = 2$

How can we test if a graph has a 2-coloring?

BFS

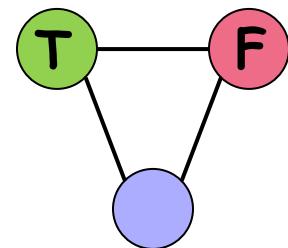


$3\text{-SAT} \leq_p 3\text{-colorable}$

We construct a graph G that will be 3-colorable iff the 3-SAT instance is satisfiable.

Graph G consists of the following gadgets.

A truth gadget:



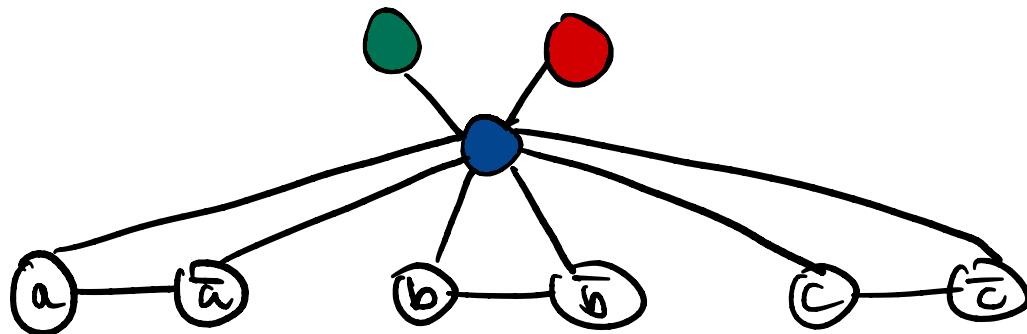
A gadget for each ~~variable~~^{literal}:



$3\text{-SAT} \leq_p 3\text{-colorable}$

Combining those gadgets together (for three literals)

$$(a \vee b \vee c)$$



$3\text{-SAT} \leq_p 3\text{-colorable}$

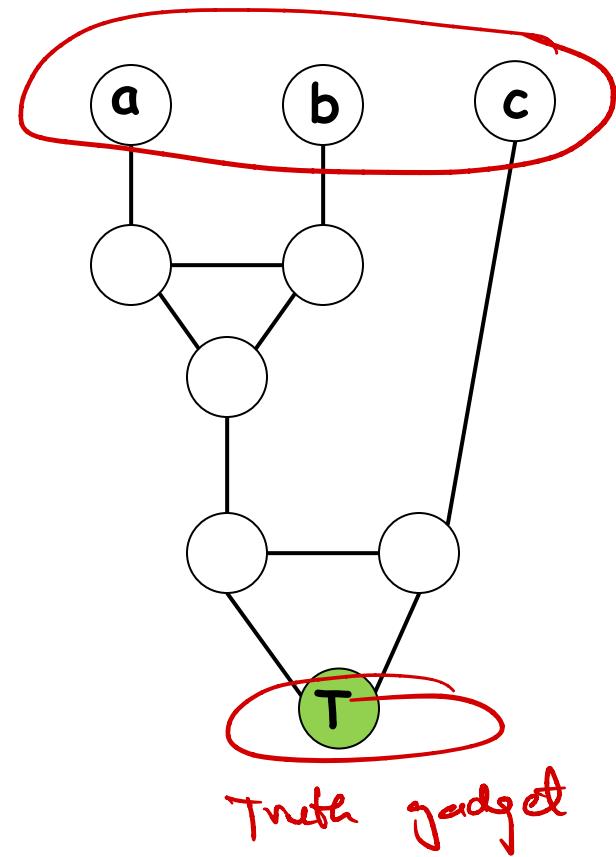
A special gadget for each clause

This gadget connects a truth gadget with variable gadgets.

We can color this graph
with 3 colors \Leftrightarrow one of the
 literals is true

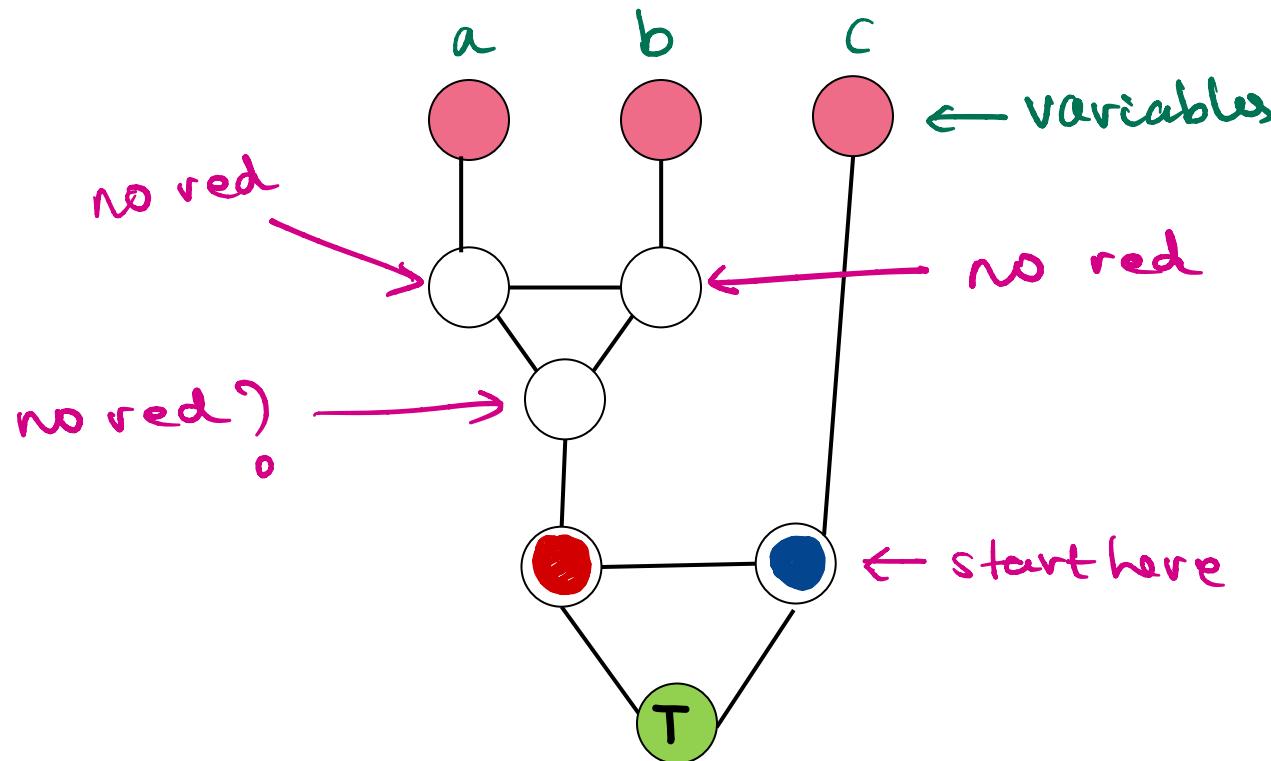
If $a=b=c=F$, then we cannot
color this graph with 3 colors

gadget for variable



$3\text{-SAT} \leq_p 3\text{-colorable}$

Suppose all a, b and c are all False (red).

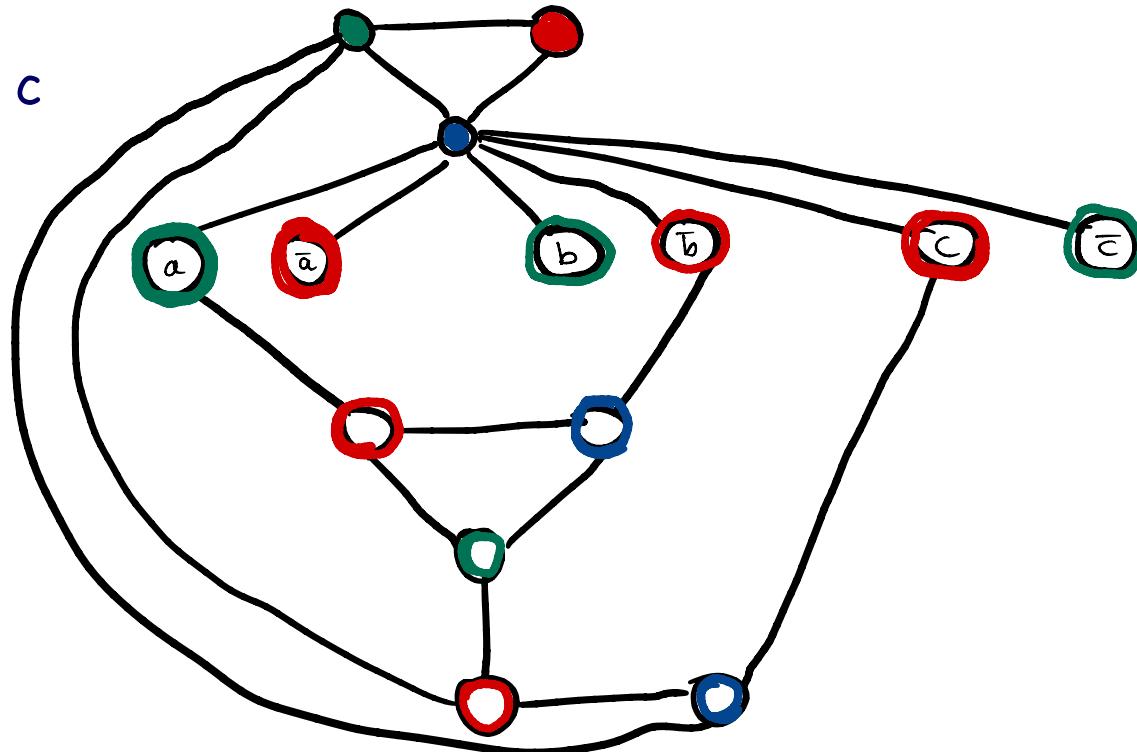


$3\text{-SAT} \leq_p 3\text{-colorable}$

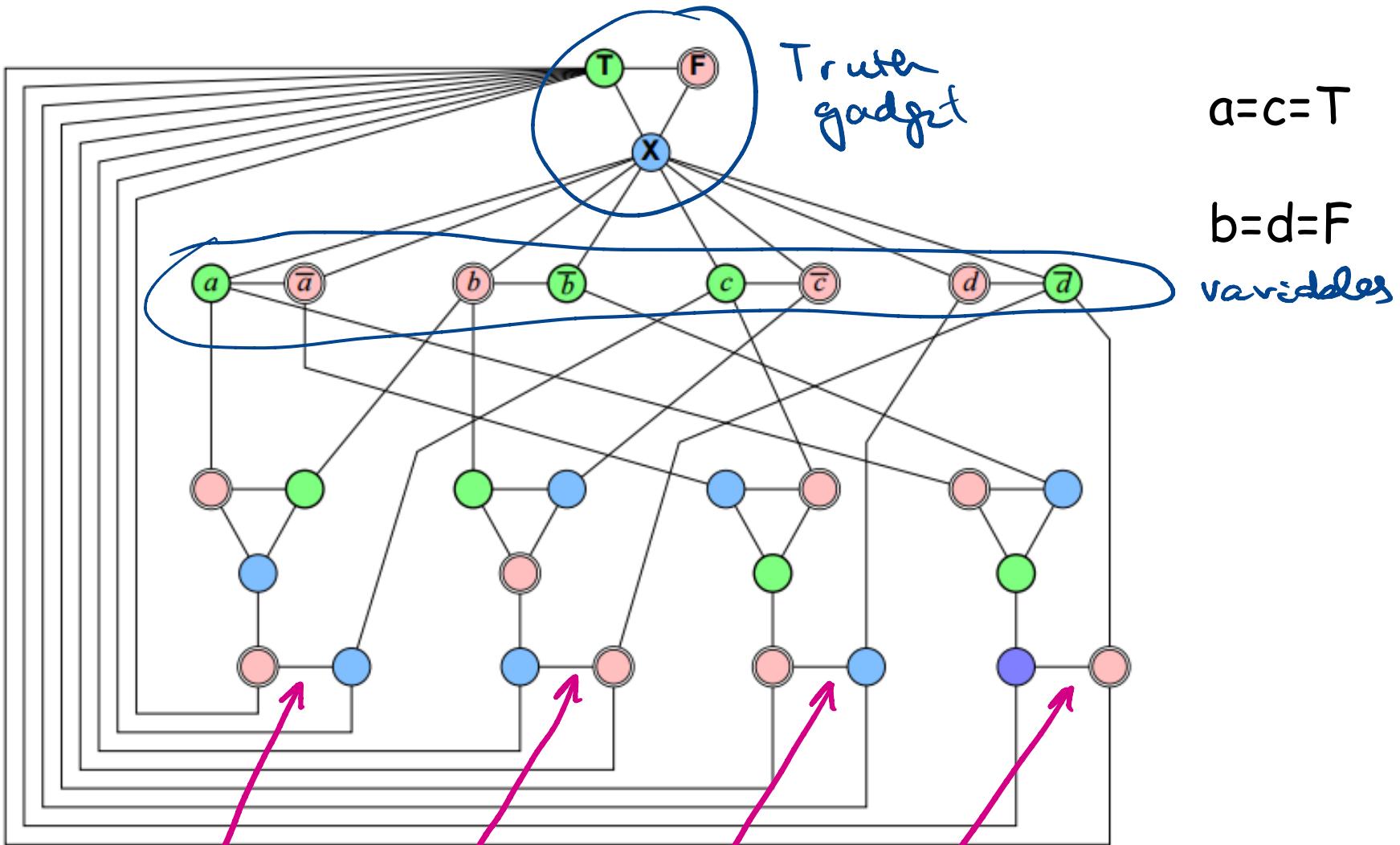
We have showed that if all the variables in a clause are false, the gadget cannot be 3-colored.

let $a = T$, $\bar{b} = c = F$

Example: $a \vee \neg b \vee c$



Example with four clauses



A 3-colorable graph derived from a satisfiable 3CNF formula.

$$(a \vee b \vee c) \wedge (b \vee \bar{c} \vee \bar{d}) \wedge (\bar{a} \vee c \vee d) \wedge (a \vee \bar{b} \vee \bar{d})$$

$$a=c=T$$

$$b=d=F$$

variables

$3\text{-SAT} \leq_p 3\text{-colorable}$

Claim: 3-SAT instance is satisfiable if and only if G is 3-colorable.

Proof: \Rightarrow) By construction

$T = \text{Green}$, $F = \text{red}$

Truth gadget \rightarrow color

Variable gadget \rightarrow color

Clauses gadget \rightarrow coloring is forced

$3\text{-SAT} \leq_p 3\text{-colorable}$

Claim: 3-SAT instance is satisfiable if and only if G is 3-colorable.

Proof: \Leftarrow) Given a special graph which is 3 colorable
Goal: Find a truth assignment

Look at the variable gadget & assign red to False & green to True.

Sudoku: $n^2 \times n^2$



NP-?

NP-hard?

9-colors
sudoku graph

vertex : 81

edges : $81 \cdot \frac{20^{\text{!}}}{2} = 810$

2		3	8		5
	3	4	5	9	8
	8		9	7	3
6	7	9			
9	8			1	7
			5	6	9
3	1	9	7		2
4	6	5	2		8
2		9	3		1

Sudoku Graph

Sudoku \leq_p 9-color

did we prove
sudoku \in NP-hard

No!!

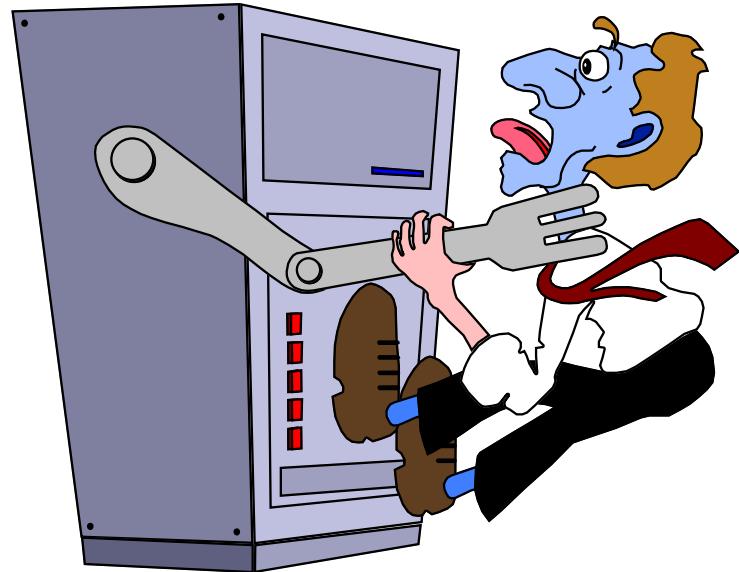
2		3	8	5				
	3	4	5	9	8			
	8		9	7	3	4		
6	7	9						
9	8				1	7		
		5	6		9			
3	1	9	7		2			
4	6	5	2		8			
2		9	3			1		

Sudoku

Constructing a Sudoku graph, we have proved:

Don't be afraid of NP-hard problems.

Many reasonable instances (of practical interest) of problems in class NP can be solved!



The largest solved TSP is an **85,900-vertex** route calculated in 2006. The graph corresponds to the design of a customized computer chip created at Bell Laboratories, and the solution exhibits the shortest path for a laser to follow as it sculpts the chip.