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遗传算法运行程序(python)
# -*- encoding: utf-8 -*-
import random
import math
import pos_data
import sys
if sys.version_info.major < 3:
      import Tkinter
else:
      import tkinter as Tkinter
from GA import GA
pos_list = pos_data.pos_list
class TSP_WIN(object):
    def init (self, aRoot, aLifeCount = 100, aWidth = 560, aHeight = 330):
           self.root = aRoot
           self.lifeCount = aLifeCount
           self.width = aWidth
           self.height = aHeight
           self.canvas = Tkinter.Canvas(
                         self.root,
                         width = self.width,
                         height = self.height,
           self.canvas.pack(expand = Tkinter.YES, fill = Tkinter.BOTH)
           self.bindEvents()
           self.initCitys()
           self.new()
           self.title("TSP")
    def initCitys(self):
      self.citys = pos_data.pos_list
      #坐标变换
      minX, minY = self.citys[0][0], self.citys[0][1]
      maxX, maxY = minX, minY
      for city in self.citys[1:]:
           if minX > city[0]:
               minX = city[0]
           if minY > city[1]:
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minY = city[1]
       if maxX < city[0]:
            maxX = city[0]
       if maxY < city[1]:
            maxY = city[1]
  w = maxX - minX
  h = maxY - minY
  xoffset = 30
  yoffset = 30
  ww = self.width - 2 * xoffset
  hh = self.height - 2 * yoffset
  xx = ww / float(w)
  yy = hh / float(h)
  r = 5
  self.nodes = []
  self.nodes2 = []
  for city in self.citys:
       x = (city[0] - minX) * xx + xoffset
       y = hh - (city[1] - minY) * yy + yoffset
       self.nodes.append((x, y))
       node = self.canvas.create\_oval(x - r, y - r, x + r, y + r,
            fill = "#ff0000",
            outline = "#000000",
            tags = "node",)
       self.nodes2.append(node)
def distance(self, order):
       distance = 0.0
       for i in range(-1, len(self.citys) - 1):
              index1, index2 = order[i], order[i + 1]
              city1, city2 = self.citys[index1], self.citys[index2]
              distance += math.sqrt((city1[0] - city2[0]) ** 2 + (city1[1] - city2[1]) ** 2)
       return distance
def matchFun(self):
       return lambda life: 1.0 / self.distance(life.gene)
def title(self, text):
       self.root.title(text)
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def line(self, order):
       self.canvas.delete("line")
       for i in range(-1, len(order) -1):
              p1 = self.nodes[order[i]]
              p2 = self.nodes[order[i + 1]]
              self.canvas.create_line(p1, p2, fill = "#000000", tags = "line")
def bindEvents(self):
       self.root.bind("n", self.new)
       self.root.bind("g", self.start)
       self.root.bind("s", self.stop)
def get distance(self,p1,p2):
     return math.sqrt(math.pow(p1[0]-p2[0],2)+math.pow(p1[1]-p2[1],2))
def get list(self):
    tdm()
     D = []
     for j in range(280):
         dis = []
         for i in range(280):
              if i==j:
                   dis.append(9e9)
              else:
                   dis.append(self.get_distance(pos_list[j],pos_list[i]))
         D.append(dis)
     return D
def new(self, evt = None):
       self.isRunning = False
       order = range(len(self.citys))
       self.line(order)
       self.ga = GA(aCrossRate = 0.8,
              aMutationRage = 0.02,
              aLifeCount = self.lifeCount,
              aGeneLenght = len(self.citys),
              aD = self.get list(),
              aMatchFun = self.matchFun())
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def start(self, evt = None):
          self.isRunning = True
          while self.isRunning:
                 self.ga.next()
                 distance = self.distance(self.ga.best.gene)
                 self.line(self.ga.best.gene)
                 self.title("TSP-gen: %d" % self.ga.generation)
                 print("%d : %f"%(self.ga.generation,distance))
                 self.canvas.update()
    def stop(self, evt = None):
          self.isRunning = False
    def mainloop(self):
          self.root.mainloop()
           print(self.ga.best.gene)
def main():
      \#tsp = TSP()
      #tsp.run(10000)
      tsp = TSP_WIN(Tkinter.Tk())
      tsp.mainloop()
if __name__ == '__main__':
      main()
遗传算法主程序
# -*- coding: utf-8 -*-
import random
import math
import pos_data
from Life import Life
pos_list=pos_data.pos_list
class GA(object):
    """遗传算法类"""
    def __init__(self, aCrossRate, aMutationRage, aLifeCount, aGeneLenght, aD,
aMatchFun = lambda life : 1):
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self.croessRate = aCrossRate
    self.mutationRate = aMutationRage
    self.lifeCount = aLifeCount
    self.geneLenght = aGeneLenght
                                                   # 适配函数
    self.matchFun = aMatchFun
    self.lives = []
                                              # 种群
                                                 # 保存这一代中最好的个体
    self.best = None
    self.generation = 1
    self.D = aD
    self.crossCount = 0
    self.mutationCount = 0
    self.bounds = 0.0
                                                  # 适配值之和,用于选择是计算概
    dis min = []
    for i in range(self.geneLenght):
         temp = self.D[i][0]
        for j in range(self.geneLenght):
             if temp > self.D[i][j]:
                  _temp = self.D[i][j]
                 temp = j
         dis_min.append(temp)
    self.Min = dis min
    self.initPopulation()
def initPopulation(self):
    """初始化种群"""
    path_solve = pos_data.path_solve
    path greddy = pos data.path greddy
    self.lives = []
    for i in range(self.lifeCount):
         gene = [x \text{ for } x \text{ in range}(0,\text{self.geneLenght})]
         # gene = []
        # rate =random.randint(1,100)
         # if rate > 55:
             # gene.extend(path greddy)
         # else:
             # gene.extend(path_solve)
        # rate =random.randint(1,100)
         # if rate > 50:
             # random.shuffle(gene)
         random.shuffle(gene)
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# gene.insert(0,0)
         # gene.append(0)
         life = Life(gene)
         self.lives.append(life)
def judge(self):
    """评估, 计算每一个个体的适配值"""
    self.bounds = 0.0
    self.best = self.lives[0]
    for life in self.lives:
         life.score = self.matchFun(life)
         self.bounds += life.score
         if self.best.score < life.score:
             self.best = life
def get_distance(self,c1,c2):
    p1=pos list[c1]
    p2=pos list[c2]
    return math.sqrt(math.pow(p1[0]-p2[0],2)+math.pow(p1[1]-p2[1],2))
def miner_one(self,index,lis):
    num = int(index)
    if num==0:
         num = len(lis) - 1
    else:
         num -= 1
    return num
def plus one(self,index,lis):
    num = int(index)
    if num==(len(lis) - 1):
         num = 0
    else:
         num += 1
    return num
def cross(self, parent1, parent2):
    index = random.randint(0, self.geneLenght - 1)
    rp1,rp2=list(parent1.gene),list(parent2.gene)
    lp1,lp2=list(parent1.gene),list(parent2.gene)
    index2 = int(index)
    node = rp1[index]
    newGene1,newGene2 = [node],[node]
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rp1.remove(node)
    rp2.remove(node)
    lp1.remove(node)
    lp2.remove(node)
    while(len(rp1)>=1):
        temp_index = self.miner_one(index,rp1)
        d1 = self.D[rp1[temp index]][node]
        d2 = self.D[rp2[temp_index]][node]
        if d1<d2:
            node = rp1[temp_index]
        else:
            node = rp2[temp_index]
        index = temp_index
        newGene1.append(node)
        rp1.remove(node)
        rp2.remove(node)
    while(len(lp1)>=1):
        temp_index = self.plus_one(index,lp1)
        d1 = self.D[lp1[temp_index]][node]
        d2 = self.D[lp2[temp_index]][node]
        if d1<d2:
            node = lp1[temp_index]
        else:
            node = lp2[temp_index]
        index2 = temp_index
        newGene2.append(node)
        lp1.remove(node)
        lp2.remove(node)
    self.crossCount += 1
    return newGene1,newGene2
def cross bk(self, parent1, parent2):
    """交叉"""
    index1 = random.randint(0, self.geneLenght - 1)
    index2 = random.randint(index1, self.geneLenght - 1)
    tempGene = parent2.gene[index1:index2] # 交叉的基因片段
    newGene = []
    p1len = 0
    for g in parent1.gene:
        if p1len == index1:
            newGene.extend(tempGene)
                                            # 插入基因片段
            p1len += 1
        if g not in tempGene:
            newGene.append(g)
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p1len += 1
        self.crossCount += 1
        return newGene
   def mutation bk(self, gene):
        index = random.randint(1, self.geneLenght - 1)
        min to = self.Min[gene[index]]
        index2 = gene.index(min_to)
        if index < index2:
            part1 = gene[0:index+1]
            part2 = gene[index+1:index2+1][::-1]
            part2.reverse()
            part3 = gene[index2+1:]
        else:
            part1 = gene[0:index2]
            part2 = gene[index2:index][::-1]
            part3 = gene[index:]
        newGene = []
        newGene.extend(part1)
        newGene.extend(part2)
        newGene.extend(part3)
        self.mutationCount += 1
        return newGene
   def mutation(self, gene):
          """突变"""
          index1 = random.randint(1, self.geneLenght - 2)
          index2 = random.randint(1, self.geneLenght - 2)
                                   # 产生一个新的基因序列,以免变异的时候影响父种
          newGene = gene[:]
群
          newGene[index1], newGene[index2] = newGene[index2], newGene[index1]
          self.mutationCount += 1
          return newGene
   def getOne(self):
          """选择一个个体"""
          r = random.uniform(0, self.bounds)
          for life in self.lives:
                r -= life.score
                if r <= 0:
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return life

raise Exception("选择错误", self.bounds)

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def newChild(self):
        """产生新后的"""
        parent1 = self.getOne()
        parent2 = self.getOne()
        rate = random.random()
        # 按概率交叉
        if rate < self.croessRate:
            # 交叉
            gene1,gene2 = self.cross(parent1, parent2)
        else:
            gene1,gene2 = parent1.gene,parent2.gene
        # 按概率突变
        rate = random.random()
        if rate < self.mutationRate:
            gene1,gene2 = self.mutation(gene1),self.mutation_bk(gene2)
        return Life(gene1),Life(gene2)
    def next(self):
        """产生下一代"""
        self.judge()
        newLives = ∏
        newLives.append(self.best)
                                               #把最好的个体加入下一代
        while len(newLives) < self.lifeCount-1:
            child1,child2=self.newChild()
            newLives.append(child1)
            newLives.append(child2)
        if len(newLives) < self.lifeCount:
            newLives.append(child1)
        self.lives = newLives
        self.generation += 1
class Life(object):
      """个体类"""
      def __init__(self, aGene = None):
            self.gene = aGene
```

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贪婪算法
from __future__ import print_function, division
from itertools import islice
from array import array as pyarray
##########
# A simple algorithm for solving the Travelling Salesman Problem
# Finds a suboptimal solution
##########
if "xrange" not in globals():
   #py3
   xrange = range
else:
   #py2
   pass
def optimize solution( distances, connections ):
   """Tries to optimize solution, found by the greedy algorithm"""
   N = len(connections)
   path = restore_path( connections )
   def ds(i,j): #distance between ith and jth points of path
       return distances[path[i]][path[j]]
   d_total = 0.0
   optimizations = 0
   for a in xrange(N-1):
       b = a+1
       for c in xrange(b+2, N-1):
           d = c+1
           delta_d = ds(a,b)+ds(c,d) - (ds(a,c)+ds(b,d))
           if delta d > 0:
               d total += delta d
               optimizations += 1
               connections[path[a]].remove(path[b])
               connections[path[a]].append(path[c])
               connections[path[b]].remove(path[a])
               connections[path[b]].append(path[d])
               connections[path[c]].remove(path[d])
               connections[path[c]].append(path[a])
               connections[path[d]].remove(path[c])
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connections[path[d]].append(path[b])
                  path[:] = restore_path( connections )
    return optimizations, d total
def restore_path( connections ):
    """Takes array of connections and returns a path.
    Connections is array of lists with 1 or 2 elements.
    These elements are indices of teh vertices, connected to this vertex
    Guarantees that first index < last index
    #there are 2 nodes with valency 1 - start and end. Get them.
    start, end = [idx]
                     for idx, conn in enumerate(connections)
                     if len(conn)==1]
    path = [start]
    prev_point = None
    cur point = start
    while True:
         next_points = [pnt for pnt in connections[cur_point]
                          if pnt != prev point ]
         if not next_points: break
         next point = next points[0]
         path.append(next_point)
         prev point, cur point = cur point, next point
    return path
def pairs by dist(N, distances):
    #Sort coordinate pairs by distance
    indices = [None] * (N*(N-1)//2)
    idx = 0
    for i in xrange(N):
         for j in xrange(i+1,N):
             indices[idx] = (i,j)
             idx += 1
    indices.sort(key = lambda ij: distances[ij[0]][ij[1]])
    return indices
def solve tsp( distances, optim steps=3, pairs by dist=pairs by dist):
    """Given a distance matrix, finds a solution for the TSP problem.
    Returns list of vertex indices.
    Guarantees that the first index is lower than the last"""
    N = len(distances)
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if N == 0: return []
if N == 1: return [0]
for row in distances:
     if len(row) != N: raise ValueError( "Matrix is not square")
#State of the TSP solver algorithm.
node_valency = pyarray('i', [2])*N #Initially, each node has 2 sticky ends
#for each node, stores 1 or 2 connected nodes
connections = [[] for i in xrange(N)]
def join segments(sorted pairs):
     #segments of nodes. Initially, each segment contains only 1 node
     segments = [ [i] for i in xrange(N) ]
     def filtered pairs():
         #Generate sequence of
         for ij in sorted pairs:
              i,j = ij
              if not node_valency[i] or\
                       not node_valency[j] or\
                       (segments[i] is segments[j]):
                   continue
              yield ij
     for i,j in islice(filtered_pairs(), N-1):
         node_valency[i] -= 1
         node valency[j] -= 1
         connections[i].append(j)
         connections[j].append(i)
         #Merge segment J into segment I.
         seg i = segments[i]
         seg_j = segments[j]
         if len(seg_j) > len(seg_j):
              seg i, seg j = seg j, seg i
              i, j = j, i
         for node idx in seg j:
              segments[node_idx] = seg_i
         seg i.extend(seg j)
join segments(pairs by dist(N, distances))
for passn in range(optim_steps):
     nopt, dtotal = optimize solution( distances, connections )
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if nopt == 0:
              break
    path = restore_path( connections )
    return path
贪婪算法运行程序
from greedy import solve_tsp
import math
import numpy as np
import matplotlib.pyplot as plt
import pos_data
pos_list = pos_data.pos_list
D = \Pi
T = []
X = \Pi
Y = \Pi
def get list():
    tdm()
    for j in range(280):
         dis = []
         for i in range(280):
              if i==j:
                  dis.append(9e9)
              else:
                  dis.append((get_distance(pos_list[j],pos_list[i])-T[i]-T[j])*0.001)
                  # dis.append(get_distance(pos_list[j],pos_list[i]))
         D.append(dis)
def get_distance(p1,p2):
    return math.sqrt(math.pow(p1[0]-p2[0],2)+math.pow(p1[1]-p2[1],2))
def tdm():
    x bar = reduce(lambda x,y:x+y, X)/280
    y_bar = reduce(lambda x, y:x+y, Y)/280
    dis = []
    for i in range(280):
         dis.append(get distance([x bar,y bar],pos list[i]))
    dis_bar = reduce(lambda x,y:x+y, dis)/280
    for i in range(280):
         T.append(get_distance([x_bar,y_bar],pos_list[i])-dis_bar)
def init():
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for i in range(280):
         X.append(pos list[i][0])
         Y.append(pos_list[i][1])
def get fit(path):
    fit = 0 #functools.reduce(get_distance,target)
    for i in range(279):
         dis = get distance(pos list[path[i]],pos list[path[i+1]])
         # print('dis btw %d %d is %f'%(target[i],target[i+1],dis))
         fit = fit + dis
    return fit
init()
get list()
# path = solve_tsp(D,12)
path= [40, 27, 14, 3, 2, 1, 0, 9, 12, 11, 10, 25, 24, 23, 32, 41, 56, 49, 57, 48, 64, 81, 82,
98, 112, 127, 146, 160, 159, 178, 177, 187, 198, 197, 188, 164, 165, 158, 145, 144, 128,
133, 134, 115, 114, 113, 99, 96, 83, 65, 71, 72, 67, 84, 97, 100, 116, 129, 147, 161, 175,
189, 196, 207, 214, 231, 215, 208, 209, 216, 233, 232, 247, 248, 259, 279, 278, 258, 246,
257, 277, 261, 252, 251, 260, 276, 256, 245, 234, 217, 210, 199, 190, 176, 162, 148, 131,
117, 101, 85, 75, 90, 106, 89, 102, 137, 132, 121, 138, 150, 167, 180, 192, 201, 218, 219,
220, 221, 228, 229, 230, 237, 236, 235, 255, 275, 274, 273, 269, 272, 270, 271, 268, 254,
267, 266, 265, 264, 253, 263, 262, 250, 249, 223, 211, 212, 213, 244, 206, 181, 182, 169,
168, 151, 139, 126, 125, 140, 152, 163, 183, 205, 224, 243, 242, 241, 240, 239, 238, 225,
226, 227, 222, 200, 204, 195, 191, 179, 186, 166, 174, 156, 173, 185, 194, 203, 202, 193,
184, 172, 154, 143, 142, 155, 171, 170, 153, 141, 124, 109, 93, 94, 110, 111, 95, 80, 79,
78, 63, 47, 38, 22, 36, 21, 20, 37, 45, 62, 46, 61, 77, 76, 92, 91, 108, 123, 122, 107, 118,
103, 86, 70, 55, 60, 73, 87, 104, 119, 136, 157, 149, 135, 130, 120, 105, 88, 74, 59, 43,
44, 34, 19, 18, 35, 31, 8, 7, 6, 5, 4, 16, 17, 33, 42, 58, 53, 68, 69, 54, 52, 66, 51, 50, 39,
26, 13, 15, 28, 30, 29]
# path.append(path[0])
print(get fit(path))
# print(path)
plt.figure()
plt.plot(X,Y,'bo')
plt.plot(X[40],Y[40],'ro')
plt.plot(X[29],Y[29],'go')
a = ∏
for i in range(279):
    xp = X[path[i]]
    yp = Y[path[i]]
    xI = X[path[i+1]] - xp
    yl = Y[path[i+1]] - yp
    temp = [xp, yp, xl, yl]
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a.append(temp)

# plt.setp(lines, color='r', linewidth=2.0)
soa = np.array(a)
px,py,u,v = zip(*soa)
ax = plt.gca()
ax.quiver(px,py,u,v,color='b',angles='xy',scale_units='xy',scale=1)
plt.draw()
# plt.plot(px,py)
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plt.show()