

# Less than a Single Pass: Stochastically Controlled Stochastic Gradient Lihua Lei & Michael I. Jordan

# Problem Setup

### **Composite Objectives**

$$\min_{x \in \mathbb{R}^d} f(x) = \min_{x \in \mathbb{R}^d} \frac{1}{n} \sum_{i=1}^n f_i(x)$$

#### Assumptions

A1  $f_i$  are smooth with L-Lipschitz gradients;

A2  $f_i$  are strongly convex with modulus  $\mu \ge 0$ . ( $\mu = 0$  is allowed.)

 $f_i(x)$  can be deterministic/dependent/not identically distributed!

## Measure of Intrinsic Difficulty

### Question: how difficult is the problem?

Initialization	$\Delta_0 = L   x_0 - x^*  ^2, D_0 = f(x_0) - f(x^*)$
Curvature	$\kappa = L/\mu$ (when $\mu > 0$ )
Gradient Regularity	$G^2 = \max_i \sup_x \ \nabla f_i(x)\ ^2$
Heterogeneity	$\mathcal{H}^* = \sup_{x \to L} \frac{1}{nL} \sum_{i=1}^n \ \nabla f_i(x) - \nabla f(x)\ ^2$

A toy example:  $f_i(x) = (x - b_i)^2$  with

1. 
$$b = (b_1, \ldots, b_n) \in \mathcal{B}_0 = \{b : b_1 = b_2 = \ldots = b_n \in [-1, 1]\};$$

2. 
$$b = (b_1, \ldots, b_n) \in \mathcal{B}_1 = \{b : b_1, b_2, \ldots, b_n \in [-1, 1]\}.$$

 $\mathcal{B}_1$  is strictly harder than  $\mathcal{B}_0$ : heterogeneity matters!

 $\mathcal{H}^*$  is too conservative:  $\mathcal{H}^* = \infty$  in *various* realistic situations with unbounded domain! In our work, we define

$$\mathcal{H} = \inf_{x^* \in \arg\min f(x)} \frac{1}{nL} \sum_{i=1}^n \|\nabla f_i(x^*)\|^2.$$

- (i)  $\mathcal{H} \leq \min\{\mathcal{H}^*, G^2/L\};$
- (ii)  $\mathcal{H} = O_p(1)$  if  $f_i(x)$  are i.i.d. (under standard conditions);
- (iii) H can be efficiently estimated for Generalized Linear Models;
- (iv) When  $\mathcal{H} \ll n$  and  $\epsilon$  is moderate, optimizing f(x) with less than a single pass of data is possible!

## SCSG

#### Outer-Loop Update

**Inputs:** Initial value  $\tilde{x}_0$ , block size B, stepsize  $\eta$ , number of epochs T, other parameter  $\gamma$  (non-strongly convex) or m (strongly convex)

#### **Procedure:**

- 1: **for** t = 1, 2, ..., T **do**
- $\tilde{x}_{i} \leftarrow \text{SCSGepoch}(\tilde{x}_{i-1}; B, \eta, \gamma, m)$
- 3: end for

**Output:** (non-strongly convex)  $\bar{x}_T = \frac{1}{T} \sum_{t=1}^T \tilde{x}_t$ ; (strongly convex)  $\tilde{x}_T$ .

#### Inner-Loop/Within-Epoch Update

#### **SVRGepoch**

#### SCSGepoch

- 1: Input:  $x_0, \eta$ 1: Input:  $x_0, \eta, B, \gamma$  (or m)
- 2:  $\mathcal{I} \leftarrow [n]$ 2: Randomly pick  $\mathcal{I}$  with size B
- 3:  $g \leftarrow \frac{1}{|\mathcal{I}|} \sum_{i \in \mathcal{I}} f_i'(x_0)$ 3:  $g \leftarrow \frac{1}{|\mathcal{I}|} \sum_{i \in \mathcal{I}} f_i'(x_0)$
- 4: Generate  $N \sim \text{Geo}(\gamma)/U([m])$ 4: Generate  $N \sim U([n])$
- 5: **for**  $k = 1, 2, \dots, N$  **do** 
  - Randomly pick  $i \in [n]$
- 7:  $\nu \leftarrow f_i'(x) f_i'(x_0) + g$ 7:  $\nu \leftarrow f_i'(x) - f_i'(x_0) + g$ 
  - $x \leftarrow x \eta \nu$
- 9: end for
- 10: Output:  $x_N$

- 5: **for**  $k = 1, 2, \cdots, N$  **do**
- Randomly pick  $i \in \mathcal{I}$
- 8:  $x \leftarrow x \eta \nu$
- 9: end for
- 10: Output:  $x_N$

# Magic of The Geometric Distribution

$$N \sim \text{Geo}(\gamma) \Longrightarrow \mathbb{E}(W_N - W_{N+1}) = \frac{1 - \gamma}{\gamma}(W_1 - \mathbb{E}W_N), \quad \forall W_1, W_2, \dots$$

## Computation Cost

#### Parameter Defaults of SCSG

- 1. Non-strongly Convex:  $\eta < \frac{1}{5L}$ ,  $B \ge n \land \frac{2\mathcal{H}}{\epsilon}$ ,  $\gamma = \frac{B-1}{B}$
- 2. Strongly Convex:  $\eta < \frac{1}{5(L+\mu)}$ ,  $B \ge n \land \frac{8\mathcal{H}}{\epsilon}$ ,  $m \ge \frac{1}{2L\mu n^2}$

	Non-strongly Convex	Strongly Convex	
SGD	$O\left(\frac{\mathcal{H}^*}{\epsilon^2}\right)$	$O\left(\frac{\mathcal{H}^*\kappa}{\epsilon}\log\frac{1}{\epsilon}\right)$	
AGD	$O\left(\frac{n}{\sqrt{\epsilon}}\right)$	$O\left(n\sqrt{\kappa}\log\frac{1}{\epsilon}\right)$	
SVRG	_	$O\left((n+\kappa)\log\frac{1}{\epsilon}\right)$	
Katyush	a $O\left(n\log\frac{1}{\epsilon} + \sqrt{\frac{n}{\epsilon}}\right)$	$O\left((n+\sqrt{n\kappa})\log\frac{1}{\epsilon}\right)$	
SCSG	$O\left(\frac{\mathcal{H}}{\epsilon^2} \wedge \frac{n}{\epsilon}\right)$	$O\left(\left[\frac{\mathcal{H}}{\epsilon} \wedge n + \kappa\right] \log \frac{1}{\epsilon}\right)$	
SCSG+	$O\left(\frac{1}{\epsilon}\log\left(\frac{\mathcal{H}}{\epsilon}\wedge n\right) + \sqrt{\frac{\mathcal{H}\log n}{n\epsilon^3}}\right)$	$ ) O \left( \kappa e^{\sqrt{\log \frac{1}{\epsilon}}} + \sqrt{\frac{\kappa}{\epsilon}} \right) $	

### Communication Cost

- When  $B \leq$  memory limit  $\ll n$ , communication matters!
- Even sampling a data is costly (SVRG/its variants are inefficient);
- SCSG is efficient since SCSGepoch is implemented in memory.

	General Convex	Strongly Convex	Dimension
SCSG	$O\left(\left(n \wedge \frac{\mathcal{H}}{\epsilon}\right) \log \frac{1}{\epsilon}\right)$	$O\left(\left(n \wedge \frac{\mathcal{H}}{\epsilon}\right) \log \frac{1}{\epsilon}\right)$	O(d)
CoCoA	-	$O\left(m^2 \cdot \frac{n+\kappa}{n \wedge \frac{\mathcal{H}}{\epsilon} + \kappa} \log \frac{1}{\epsilon}\right)$	O(d)
DANE	_	$O\left(m\kappa\log\frac{1}{\epsilon}\right)$	$O(d^2)$
DiSCO	_	$O\left(m\sqrt{\kappa}\log\kappa\log\frac{1}{\epsilon}\right)$	$O(d^2)$

## More Details on H

Generalized Linear Models:  $f_i(x) = \rho(y_i, a_i^T x)$ :

$$L\mathcal{H} \le \sup_{z,w} \rho_2^2(z,w) \cdot \frac{1}{n} \sum_i ||a_i||^2, \quad L \le \sup_{z,w} \rho_{22}(z,w) \cdot \max_i ||a_i||^2.$$

- 1. Multi-class logistic regression:  $L\mathcal{H} \leq \frac{2}{n} \sum_{i} ||a_i||^2, L \leq \max_{i} ||a_i||^2$ ;
- 2. Linear regression:  $L\mathcal{H} \leq \frac{\|y\|^2}{n} \cdot \max_i \|a_i\|^2, L \leq \max_i \|a_i\|^2$ .

#### Experiments

- Multi-class logistic regression on MNIST ( $L = 292.82, \mathcal{H} = 0.6$ );
- Default parameters:  $B = 2220, \eta_0 = 0.0017;$
- A 2.6M memory with 8 accesses of the disk is sufficient ( $\epsilon = 10^{-3}$ ).

