

DeepONet: Learning nonlinear operators

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Conference on the Numerical Solution of Differential and
Differential-Algebraic Equations
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From function to operator

- Function: $\mathbb{R}^{d_1} \rightarrow \mathbb{R}^{d_2}$

e.g., image classification:

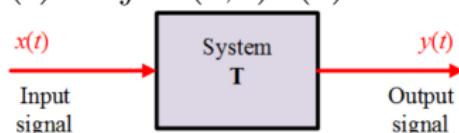
 $\mapsto 5$

- Operator: function (∞ -dim) \mapsto function (∞ -dim)

e.g., derivative (local): $x(t) \mapsto x'(t)$

e.g., integral (global): $x(t) \mapsto \int K(s, t)x(s)ds$

e.g., dynamic system:



e.g., biological system

e.g., social system



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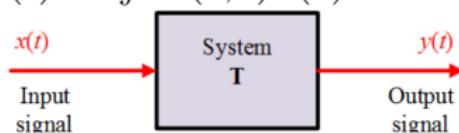
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⇒ Can we learn operators via neural networks?

⇒ How?



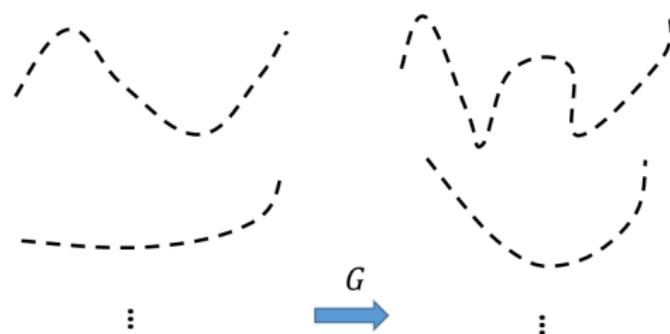
Problem setup

$$G : u \in V \subset C(K_1) \mapsto G(u) \in C(K_2)$$

$$G(u) : y \in \mathbb{R}^d \mapsto G(u)(y) \in \mathbb{R}$$

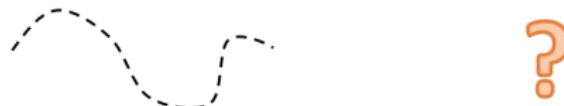
Input function u

Data:



Output function $G(u)$

Question:



Universal Approximation Theorem for Operator

$G : \textcolor{blue}{u} \in V \subset C(K_1) \mapsto \textcolor{teal}{G}(u) \in C(K_2)$

$G(u) : \textcolor{red}{y} \in \mathbb{R}^d \mapsto \textcolor{magenta}{G}(u)(y) \in \mathbb{R}$

Theorem (Chen & Chen, 1995)

Suppose that σ is a continuous non-polynomial function, X is a Banach Space, $K_1 \subset X$, $K_2 \subset \mathbb{R}^d$ are two compact sets in X and \mathbb{R}^d , respectively, V is a compact set in $C(K_1)$, G is a continuous operator, which maps V into $C(K_2)$.

Then for any $\epsilon > 0$, there are positive integers n, p, m , constants $c_i^k, \xi_{ij}^k, \theta_i^k, \zeta_k \in \mathbb{R}$, $w_k \in \mathbb{R}^d$, $x_j \in K_1$, $i = 1, \dots, n$, $k = 1, \dots, p$, $j = 1, \dots, m$, such that

$$\left| G(u)(y) - \sum_{k=1}^p \sum_{i=1}^n c_i^k \sigma \left(\sum_{j=1}^m \xi_{ij}^k u(x_j) + \theta_i^k \right) \sigma(w_k \cdot \textcolor{red}{y} + \zeta_k) \right| < \epsilon$$

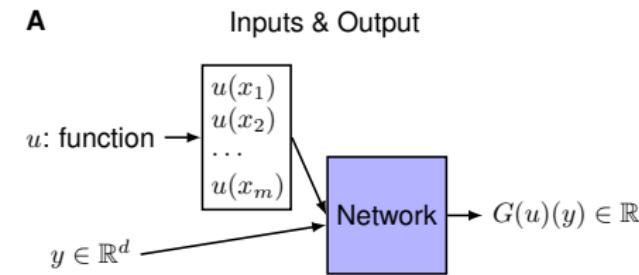
holds for all $u \in V$ and $y \in K_2$.

Problem setup

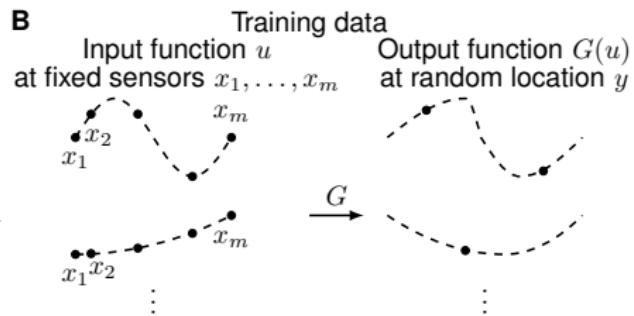
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$$G(u) : y \in \mathbb{R}^d \mapsto G(u)(y) \in \mathbb{R}$$

A



B



- Inputs: u at sensors $\{x_1, x_2, \dots, x_m\} \in \mathbb{R}^m$, $y \in \mathbb{R}^d$
- Output: $G(u)(y) \in \mathbb{R}$

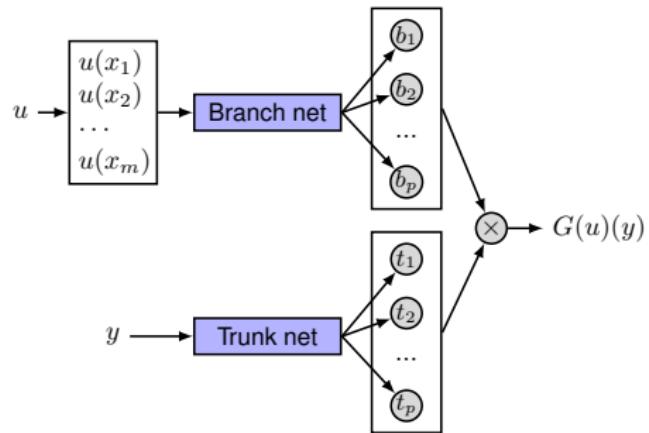


Deep operator network (DeepONet)

Lu et al., *Nature Mach Intell*, 2021

$$G(u)(y) \approx \sum_{k=1}^p \underbrace{b_k(u)}_{\text{branch}} \underbrace{t_k(y)}_{\text{trunk}}$$

D Unstacked DeepONet



Idea: $G(u)(y)$: a function of y conditioning on u

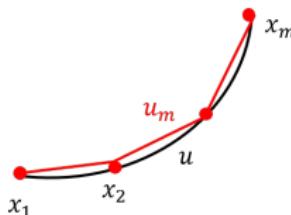
- $t_k(y)$: basis function of y
- $b_k(u)$: u -dependent coefficient, i.e., functional of u



Error analysis: the number of sensors

Consider $G : u(x) \mapsto s(x)$ ($x \in [0, 1]$) by ODE system

$$\frac{d}{dx} s(x) = g(s(x), u(x), x), \quad s(0) = s_0$$



$$\forall u \in V \Rightarrow u_m \in V_m$$

$$\text{Let } \kappa(m, V) := \sup_{u \in V} \max_{x \in [0, 1]} |u(x) - u_m(x)|$$

e.g., Gaussian process with kernel $e^{-\frac{\|x_1 - x_2\|^2}{2l^2}}$: $\kappa(m, V) \sim \frac{1}{m^2 l^2}$

Theorem (Lu et al., Nature Mach Intell, 2021)

Assume g is Lipschitz continuous (c).

Then there exists a DeepONet \mathcal{N} , such that

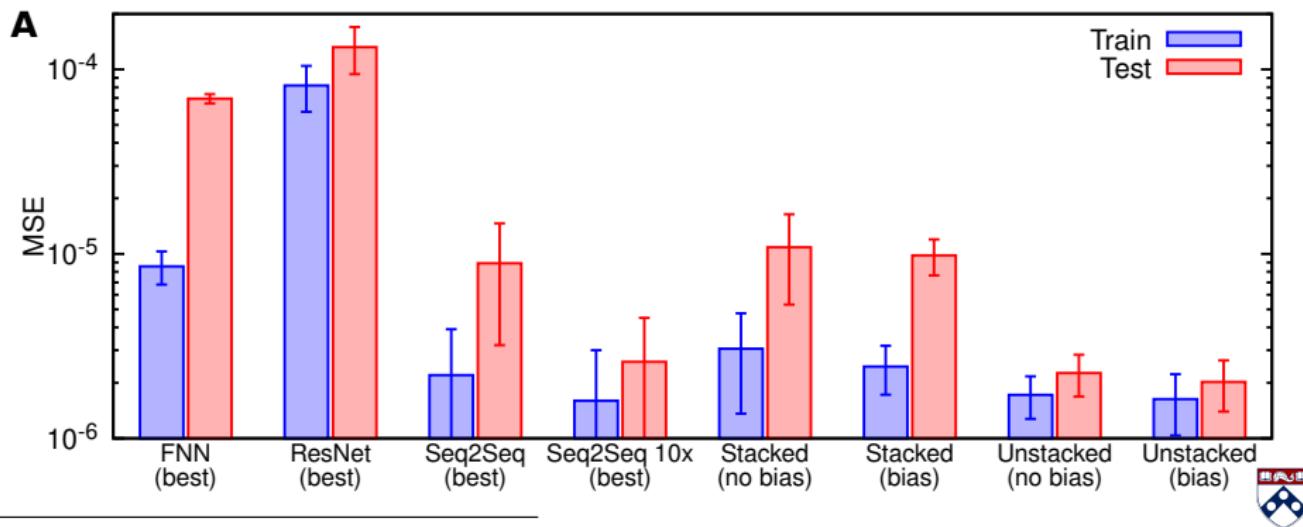
$$\sup_{u \in V} \max_{x \in [0, 1]} \|G(u)(x) - \mathcal{N}([u(x_1), \dots, u(x_m)], x)\|_2 < ce^c \kappa(m, V).$$

Explicit operator: A simple ODE case

$$\frac{ds(x)}{dx} = u(x), \quad x \in [0, 1], \quad s(0) = 0$$

$$G : u(x) \mapsto s(y) = s(0) + \int_0^y u(\tau) d\tau$$

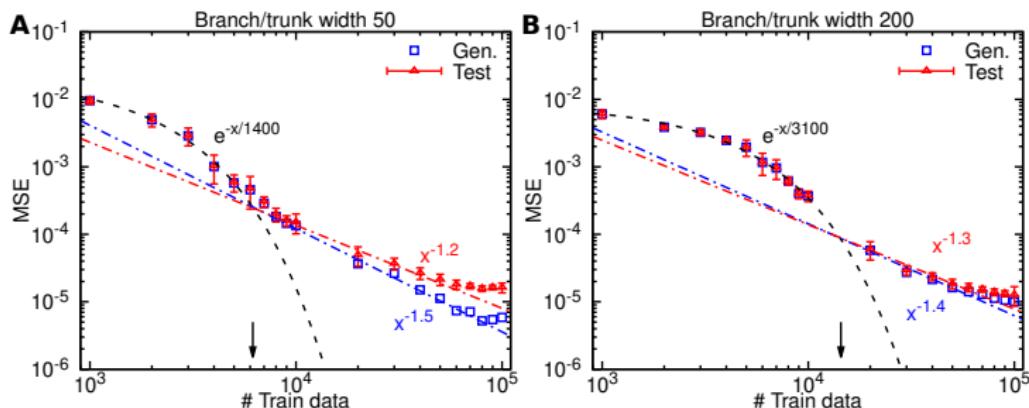
Very small generalization error!



Implicit operator: Gravity pendulum with an external force

$$\frac{ds_1}{dt} = s_2, \quad \frac{ds_2}{dt} = -k \sin s_1 + u(t)$$

$G : u(t) \mapsto \mathbf{s}(t)$



Test/generalization error:

- small dataset: exponential convergence
- large dataset: polynomial rates
- larger network has later transition point

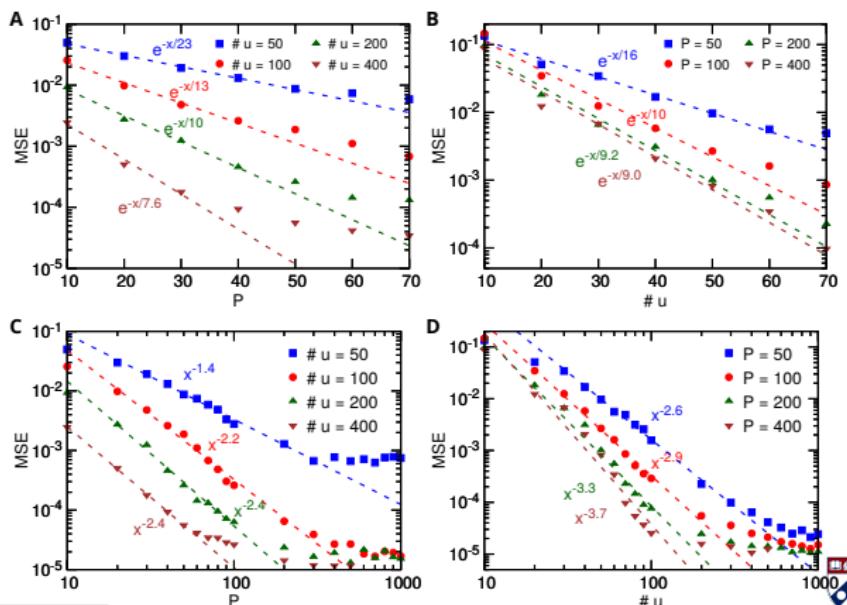


Implicit operator: Diffusion-reaction system

$$\frac{\partial s}{\partial t} = D \frac{\partial^2 s}{\partial x^2} + ks^2 + u(x), \quad x \in [0, 1], t \in [0, 1]$$

Training points = # $u \times P$

Small dataset:
Exponential convergence



Large dataset:
Polynomial convergence

Stochastic ODE

Consider the population growth model

$$dy(t; \omega) = k(t; \omega)y(t; \omega)dt, \quad y(0) = 1$$

Stochastic process $k(t; \omega) \sim \mathcal{GP}(0, \sigma^2 \exp(-\|t_1 - t_2\|^2/2l^2))$

$$G : k(t; \omega) \mapsto y(t; \omega)$$

Ideas:

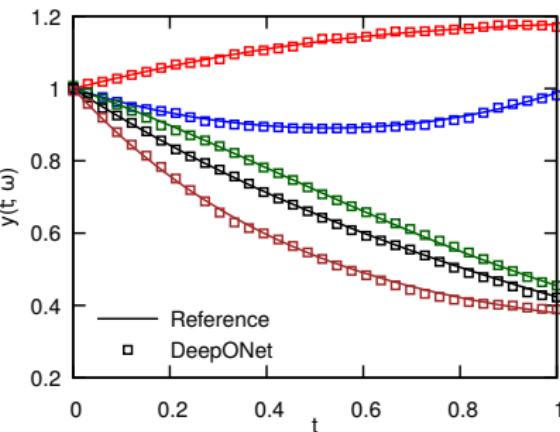
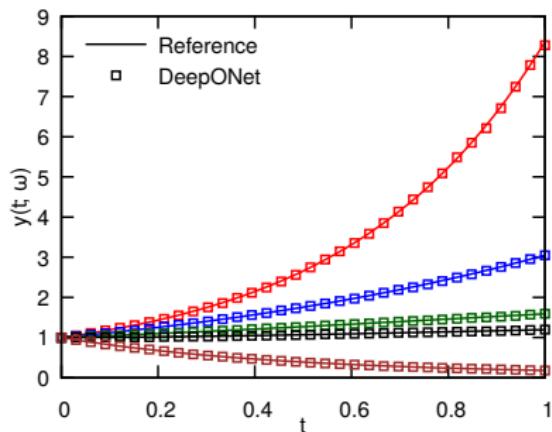
- Karhunen-Loève (KL) expansion: $k(t; \omega) \approx \sum_{i=1}^N \sqrt{\lambda_i} e_i(t) \xi_i(\omega)$
- branch net inputs: $[\sqrt{\lambda_1} e_1(t), \sqrt{\lambda_2} e_2(t), \dots, \sqrt{\lambda_N} e_N(t)] \in \mathbb{R}^{N \times m}$,
where $\sqrt{\lambda_i} e_i(t) = \sqrt{\lambda_i} [(e_i(t_1), e_i(t_2)), \dots, e_i(t_m)] \in \mathbb{R}^m$
- trunk net inputs: $[t, \xi_1, \xi_2, \dots, \xi_N] \in \mathbb{R}^{N+1}$



Stochastic ODE

- Choose $N = 5$ to conserve 99.9% stochastic energy
- Train with 10000 different $k(t; \omega)$ with l randomly sampled in $[1, 2]$, and for each $k(t; \omega)$ we use only one realization
- Test MSE is $8.0 \times 10^{-5} \pm 3.4 \times 10^{-5}$

Example: 10 different random samples of $y(t; \omega)$ for $k(t; \omega)$ with $l = 1.5$



Stochastic PDE

Consider the elliptic problem with multiplicative noise

$$-\operatorname{div}(e^{b(x;\omega)} \nabla u(x;\omega)) = f(x), \quad x \in (0,1)$$

with zero boundary conditions, $f(x) = 10$.

Stochastic process $b(x; \omega) \sim \mathcal{GP}(0, \sigma^2 \exp(-\|x_1 - x_2\|^2 / 2l^2))$

$$G : b(x; \omega) \mapsto u(x; \omega)$$

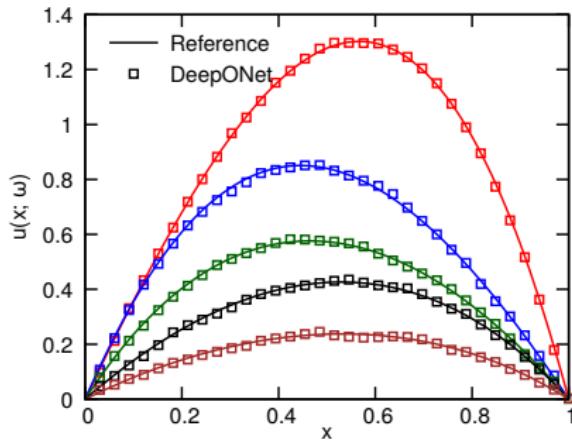
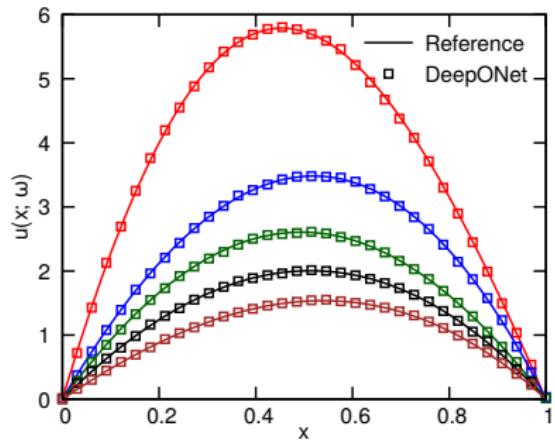
Ideas:

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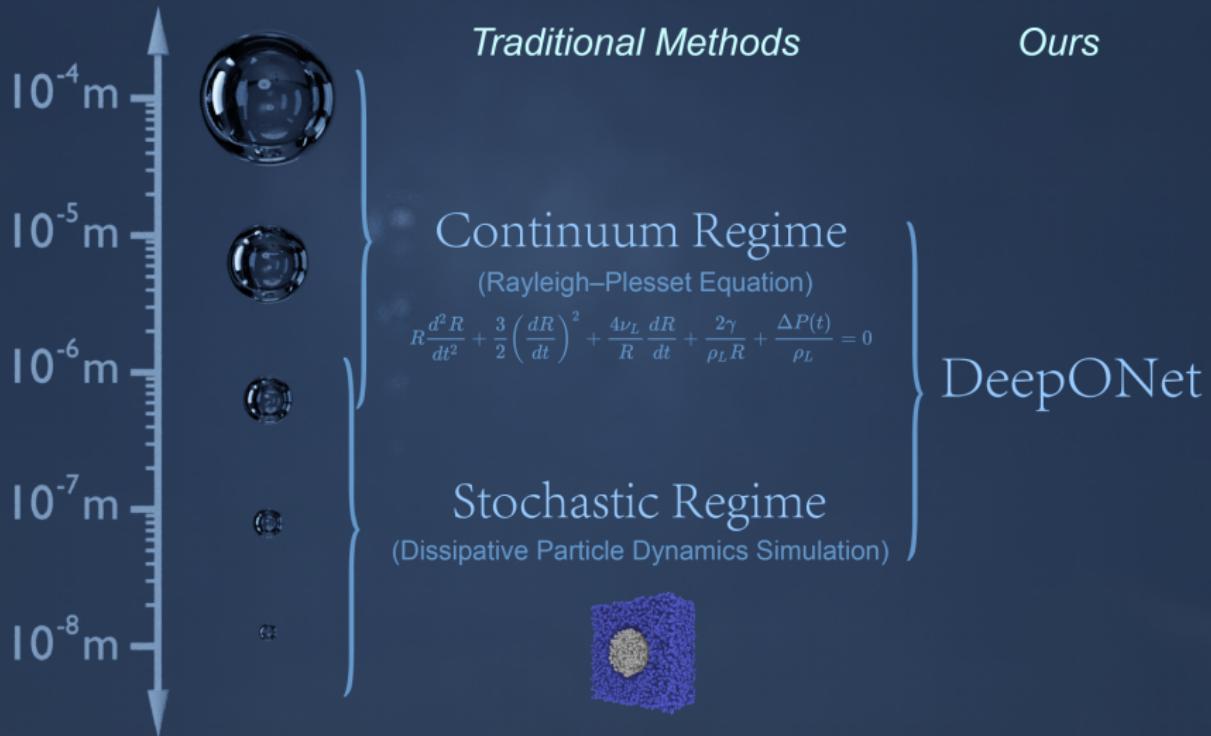


Stochastic PDE

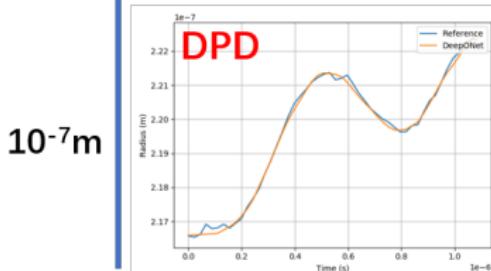
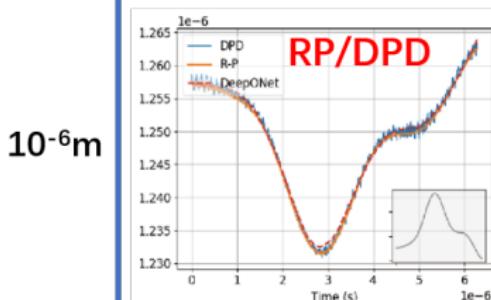
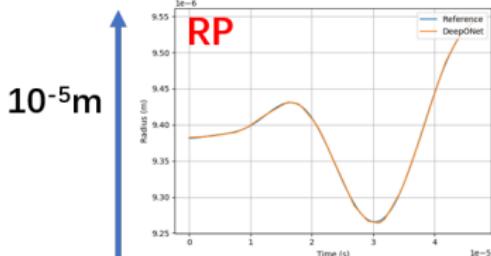
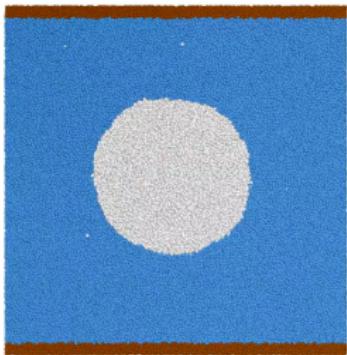
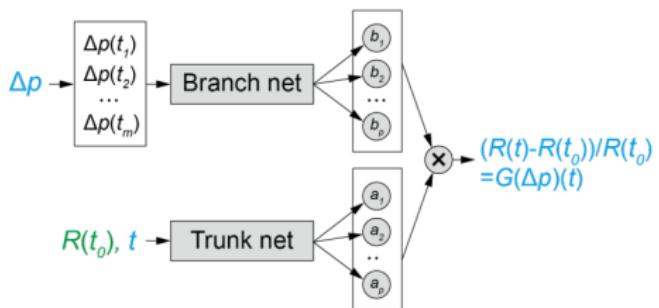
Example: 10 different random samples of $u(x; \omega)$ for $b(x; \omega)$ with $l = 1.5$



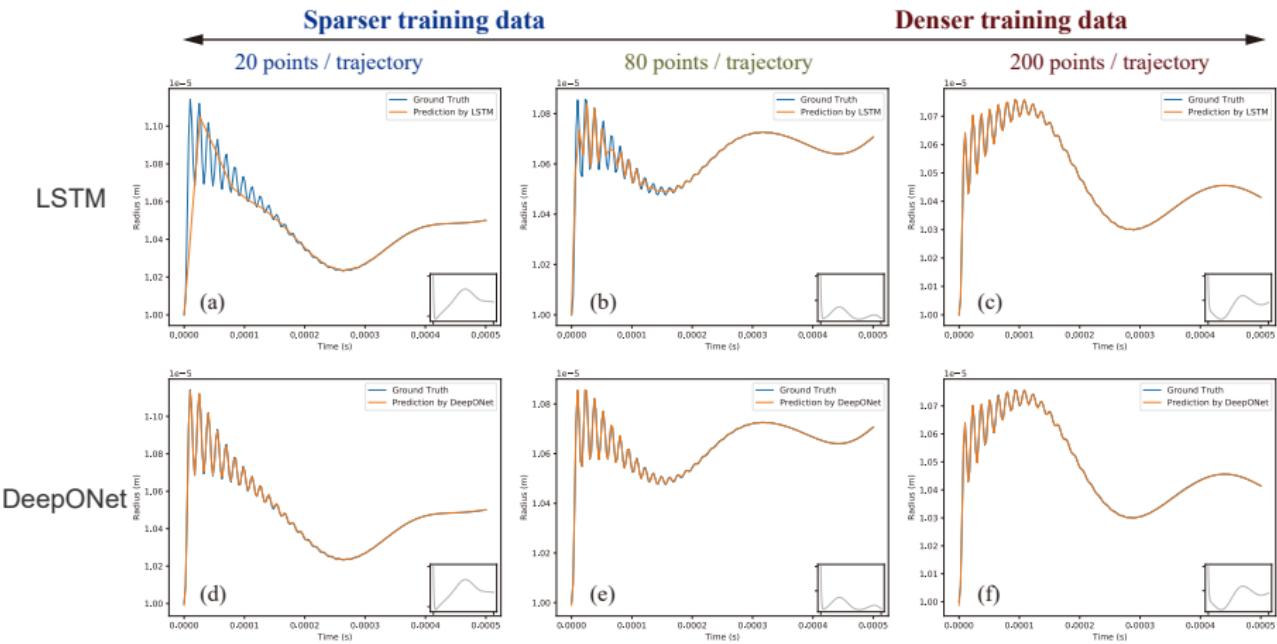
DeepONet for bubble growth dynamics



DeepONet for bubble growth dynamics



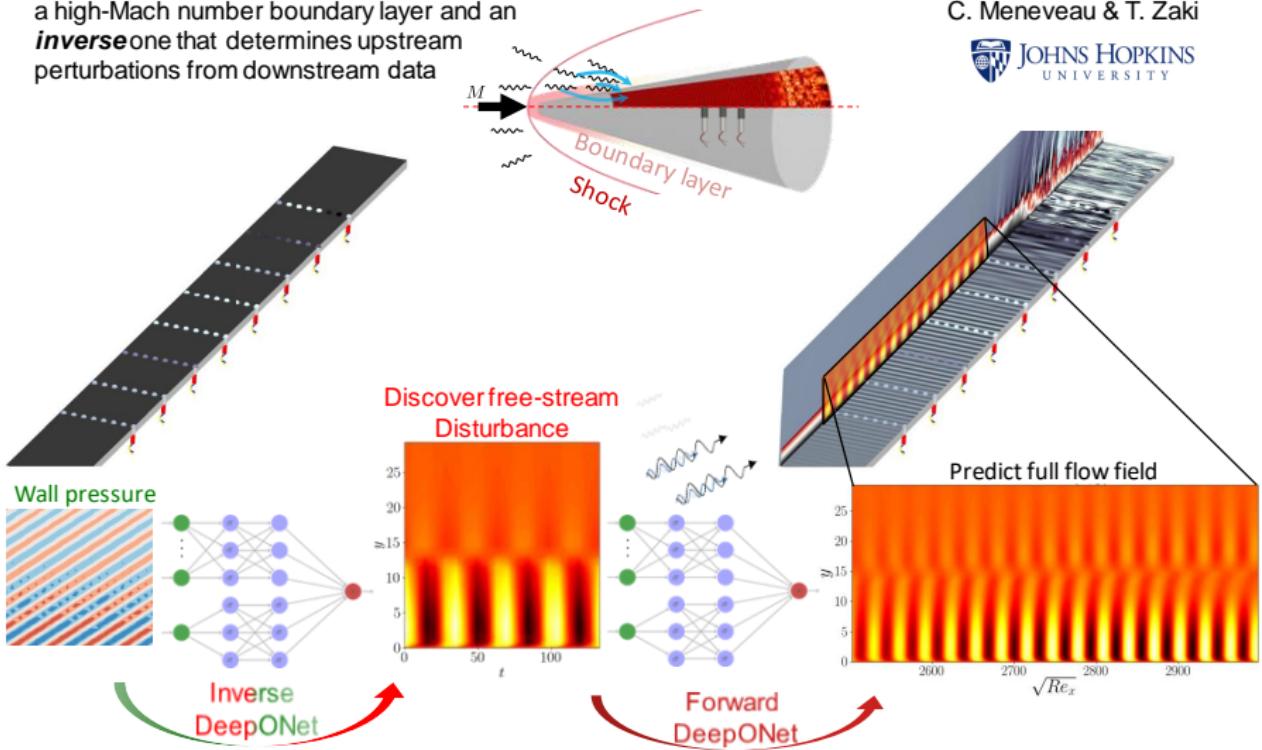
DeepONet vs. LSTM



Data assimilation in high-Mach boundary layers

We trained a **forward** DeepONet that predicts the evolution of instability waves in a high-Mach number boundary layer and an **inverse** one that determines upstream perturbations from downstream data

In collaboration with
P. Clark Di Leoni, Y. Hao,
C. Meneveau & T. Zaki



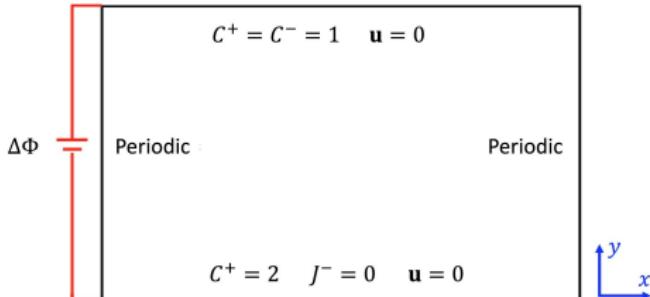
Multiphysics & Multiscale problems

Electroconvection problem

- Stokes equation

$$\frac{\partial \mathbf{u}}{\partial t} = -\nabla p + \nabla^2 \mathbf{u} - \frac{\kappa}{2\epsilon^2} \rho_e \nabla \phi$$

$$\nabla \cdot \mathbf{u} = 0$$



- Electric potential

$$\Delta\phi \in [5, 75]$$

$$-2\epsilon^2 \nabla^2 \phi = \rho_e = z(c^+ - c^-)$$

- Ion transport equation

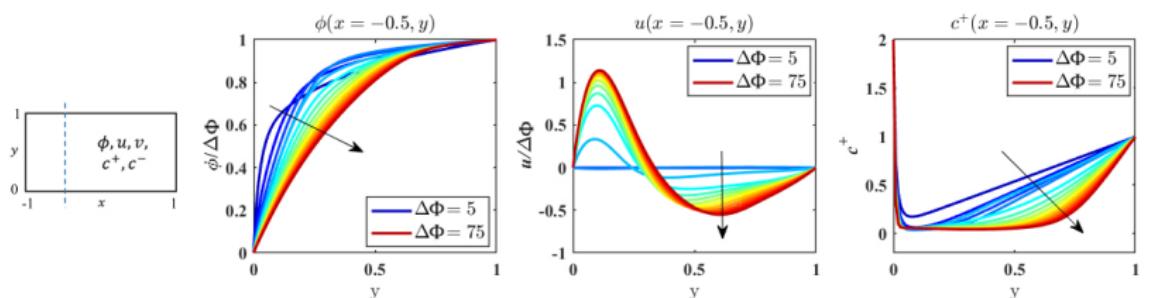
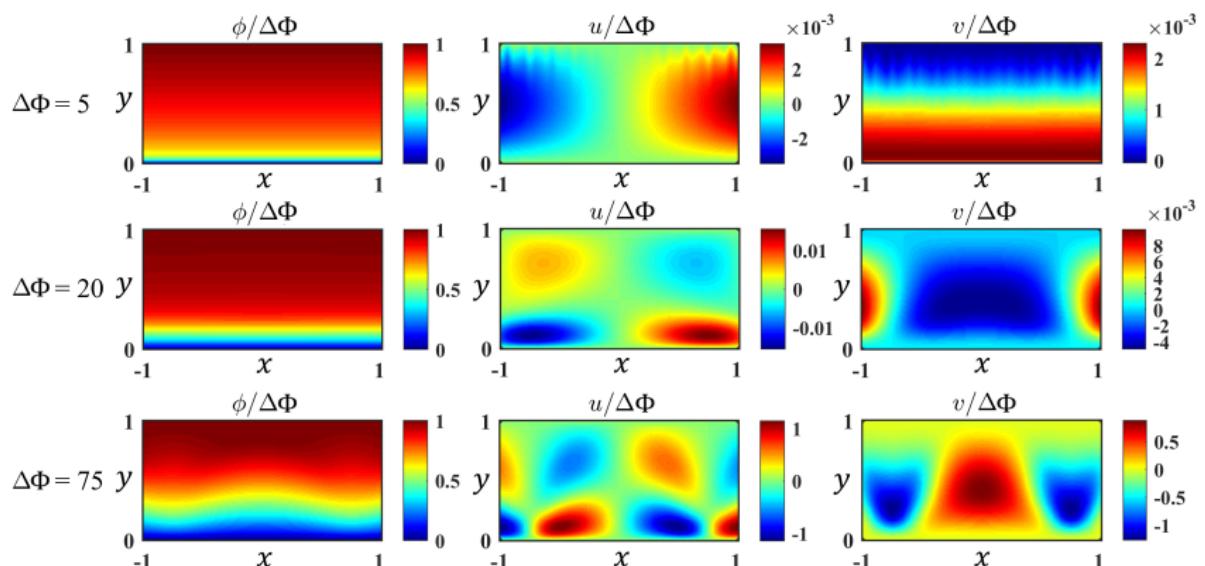
$$\frac{\partial c^\pm}{\partial t} = -\nabla \cdot \mathbf{J}^\pm$$

$$\mathbf{J}^\pm = c^\pm \mathbf{u} - \nabla c^\pm \mp c^\pm \nabla \phi$$

- \mathbf{u} : velocity
- p : pressure
- ϕ : electric potential
- ρ_e : free charge density
- c^\pm : cation/anion concentrations
- \mathbf{J}^\pm : flux

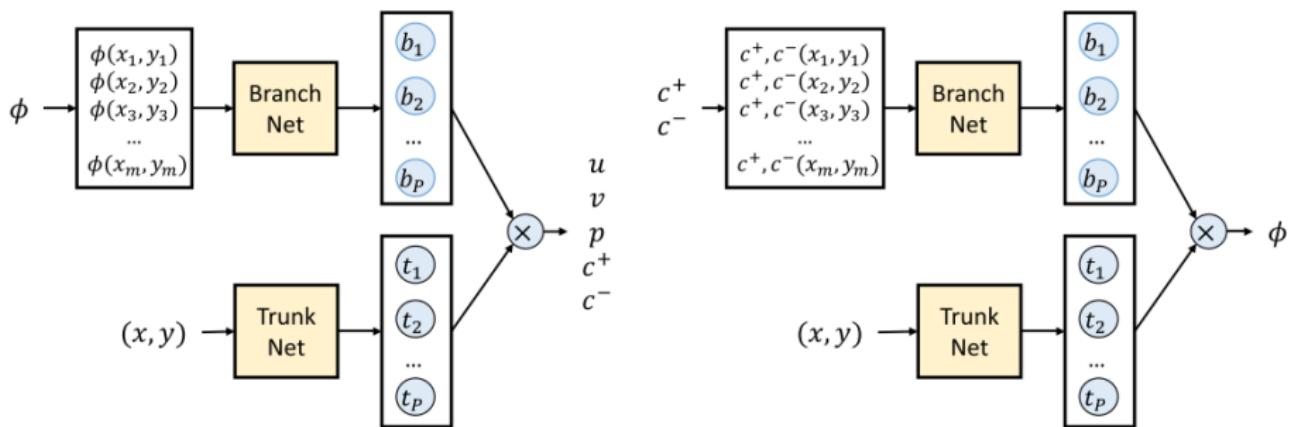


Data examples (steady state)

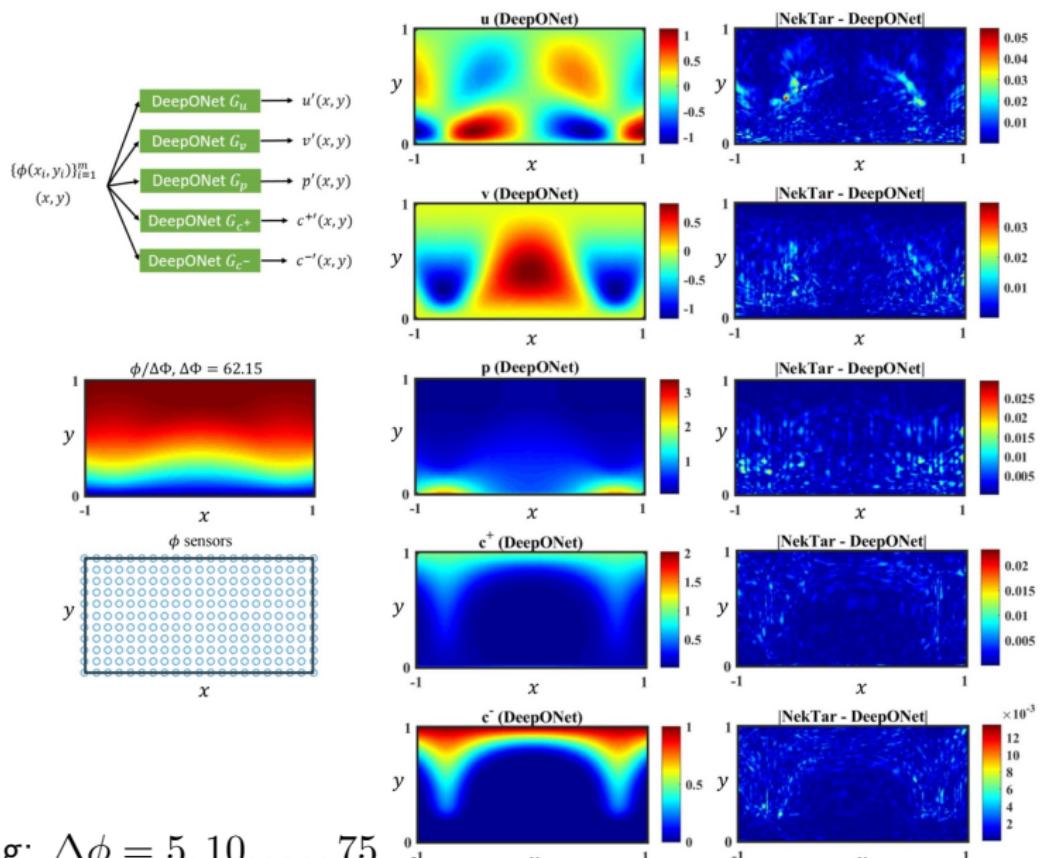


Physics decomposition via 6 DeepONets

DeepONets	Input function	Output function
G_ϕ	$c^+(x, y), c^-(x, y)$	$\phi(x, y)$
G_u	$\phi(x, y)$	$u(x, y)$
G_v	$\phi(x, y)$	$v(x, y)$
G_p	$\phi(x, y)$	$p(x, y)$
G_{c^+}	$\phi(x, y)$	$c^+(x, y)$
G_{c^-}	$\phi(x, y)$	$c^-(x, y)$



Physics decomposition via 6 DeepONets

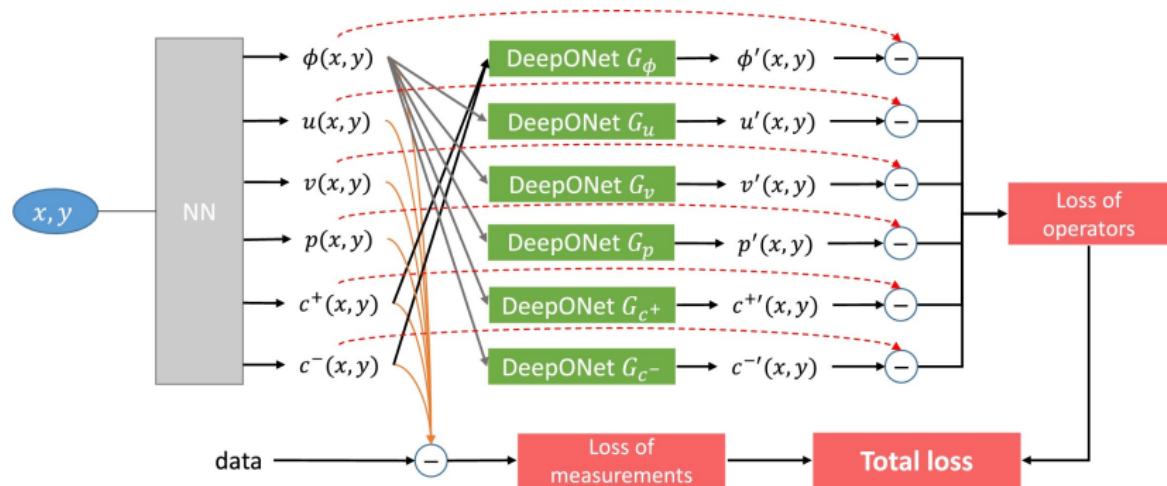


Training: $\Delta\phi = 5, 10, \dots, 75$



DeepM&Mnet: DeepONets coupling

Parallel DeepONets



Loss function:

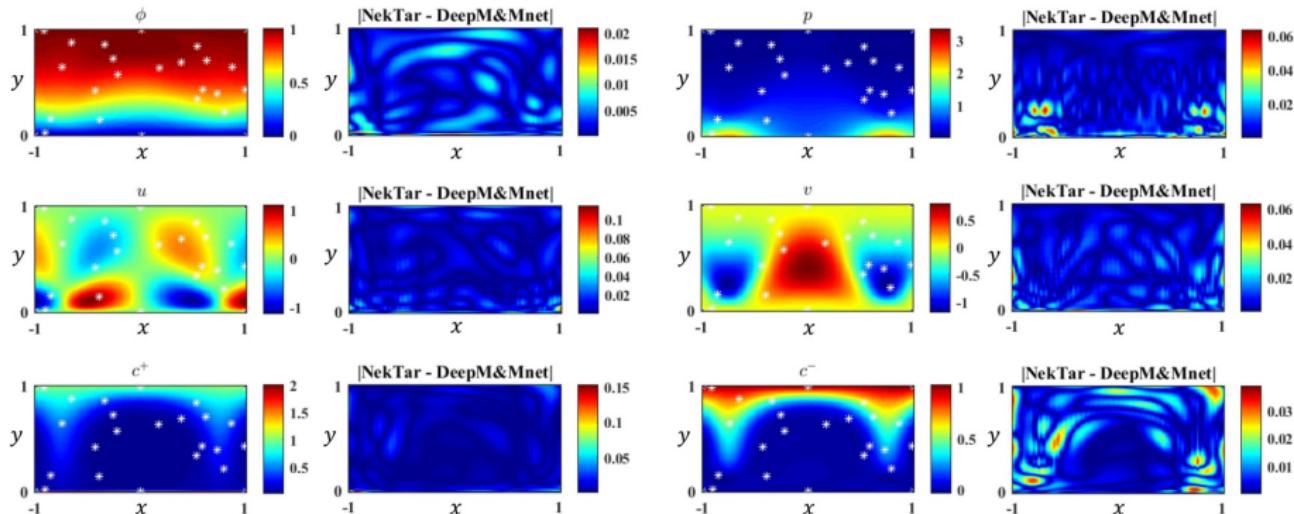
$$\mathcal{L} = \lambda_d \mathcal{L}_{data} + \lambda_o \mathcal{L}_{op} + \lambda_r \mathcal{L}_2(\theta)$$

$$\mathcal{L}_{op} = \sum_{V \in \{\phi, u, v, p, c^+, c^-\}} \frac{1}{N_{op}} \sum_{i=1}^{N_{op}} \left(V(x^i, y^i) - V'(x^i, y^i) \right)^2$$



Testing example

$$\Delta\phi = 62.15$$



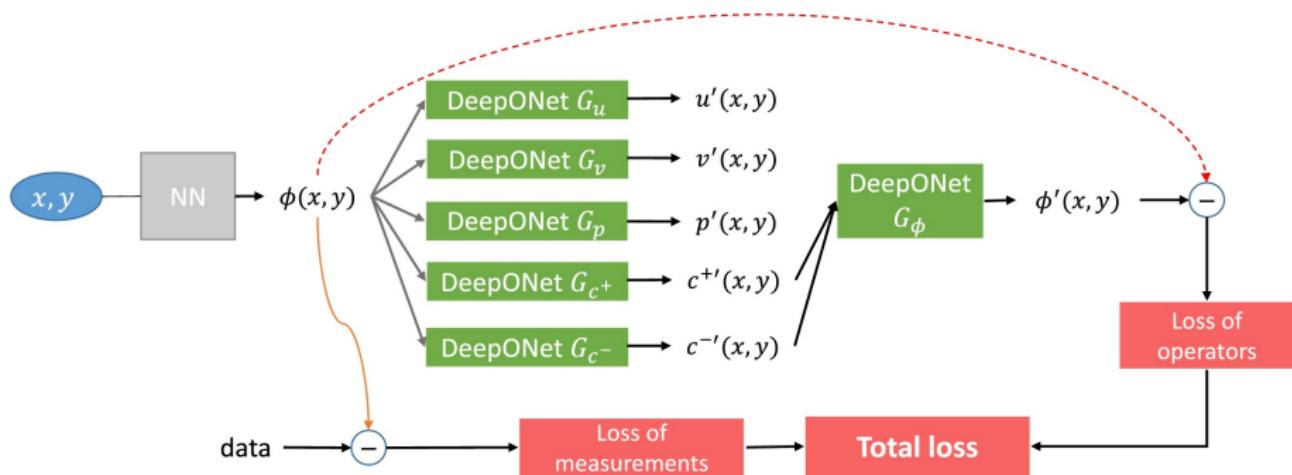
Relative error $\sim 1\%$

ϕ : 0.54%, u : 1.26%, v : 0.54%, p : 0.93%, c^+ : 0.67%, c^- : 0.48%



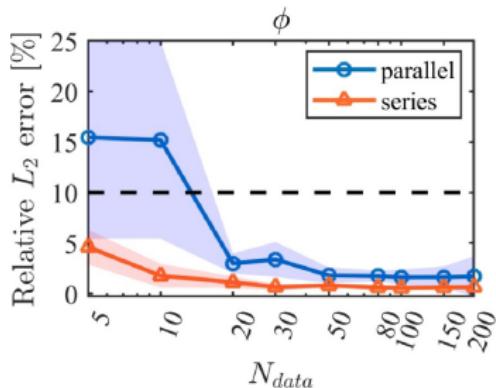
DeepM&Mnet: DeepONets coupling

Serial DeepONets

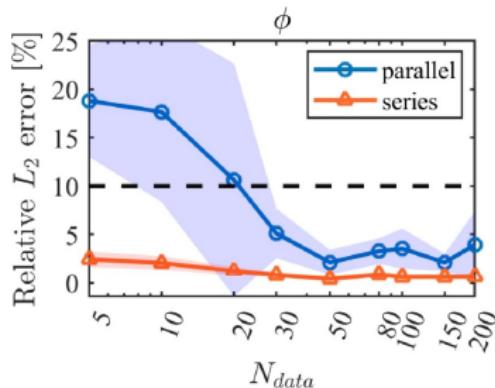


DeepM&Mnet: Parallel vs. Serial

Only have data of ϕ :



(a) NN size: 6×100

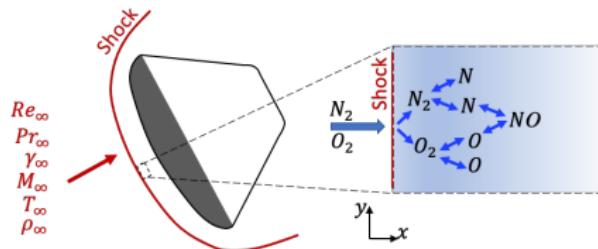


(b) NN size: 3×50

- Serial: Better accuracy
 - especially when the data is small
- Parallel: More flexible

DeepM&Mnet: Multiphysics & Multiscale problems

Hypersonics with chemical reaction: fluid flow & chemical reaction



$$\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x_j} (\rho u_j) = 0$$

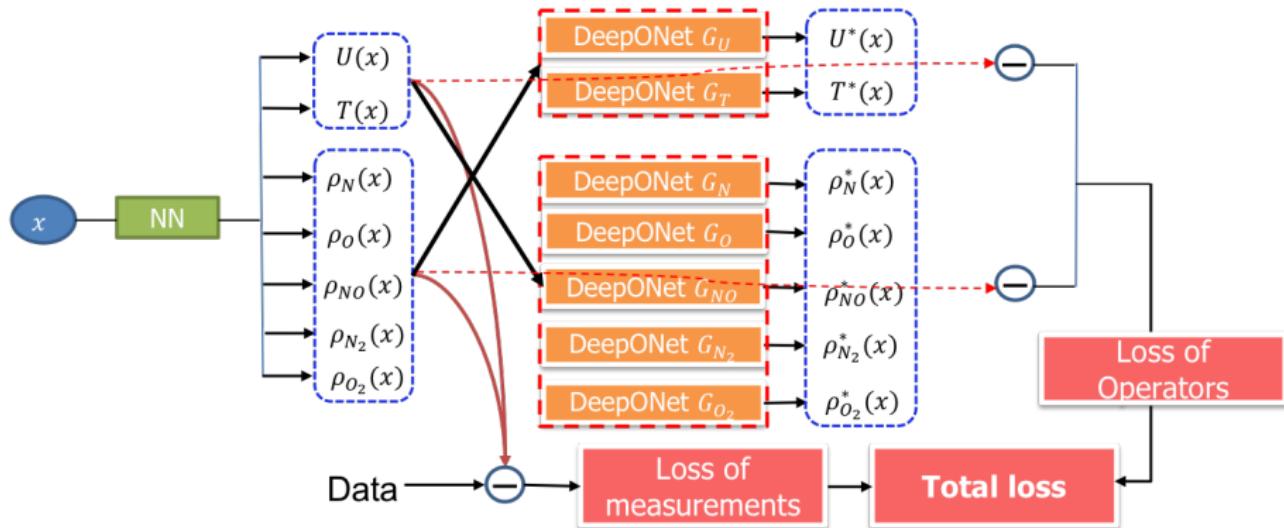
$$\frac{\partial \rho^s}{\partial t} + \frac{\partial}{\partial x_j} (\rho^s u_j) = \dot{w}^s, \quad s = 1, \dots, 5$$

$$\frac{\partial u_i}{\partial t} + \frac{\partial}{\partial x_j} (\rho u_i u_j + p \delta_{ij}) = \frac{\partial \sigma_{ij}}{\partial x_j}, \quad i = 1, 2$$

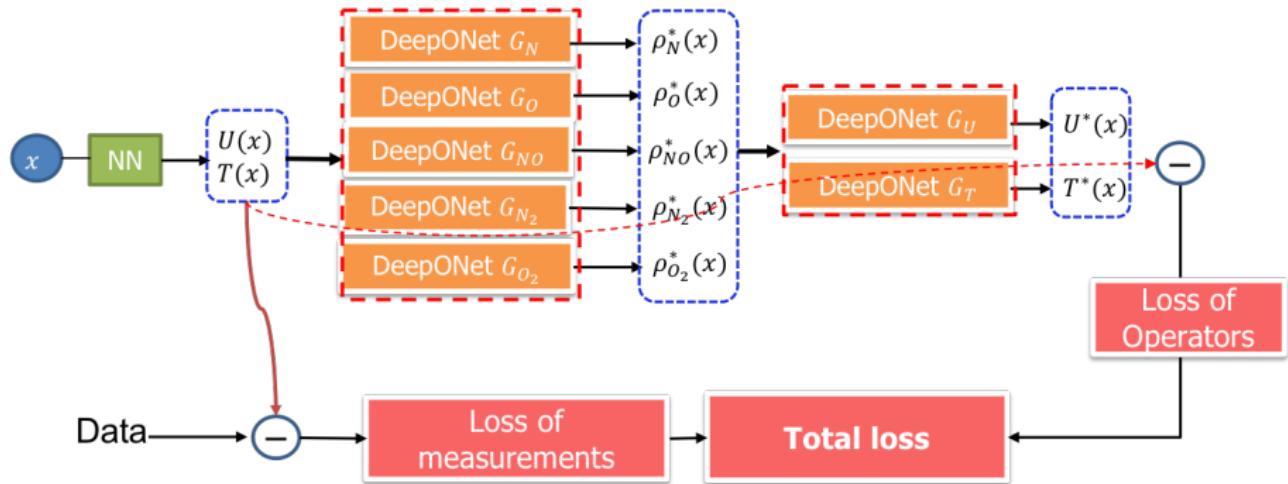
$$\frac{\partial E}{\partial t} + \frac{\partial}{\partial x_j} [(E + p) u_j] = -\frac{\partial q_j}{\partial x_j} + \frac{\partial}{\partial x_k} (u_j \sigma_{jk})$$



Parallel DeepM&Mnet



Serial DeepM&Mnet



DeepONet for learning operators

DeepONet (Lu et al., *Nature Mach Intell*, 2021)

- **Algorithms & Applications**

- ▶ 16 ODEs/PDEs (nonlinear, fractional & stochastic)
- ▶ Multiphysics & Multiscale problems
 - ★ Bubble growth dynamics from nm to mm (Lin et al., *J Chem Phys*, 2021)
 - ★ Linear instability waves in high-speed boundary layers (Clark Di Leoni et al., arXiv:2105.08697)
 - ★ Electroconvection (Cai et al., *J Comput Phys*, 2021)
 - ★ Hypersonics (Mao et al., arXiv:2011.03349)

- **Observation:** Good performance

- ▶ Small generalization error
- ▶ Exponential/polynomial error convergence

- **Theory**

- ▶ Convergence rate for advection-diffusion equations (Deng et al., arXiv:2102.10621)

