

# 数值公式表 V4(最终版)

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## 说明

- 该版为最终版
- 排版工具：Microsoft® Word 2019 MSO (16.0.11629.20238)

## 版本

- V0
  - 收集、编写、校对公式
- V1
  - 联合排版
- V2
  - 微调了公式
- V3
  - 缩排
  - 删除了章标题，横线分割与章号取而代之
  - 加粗了公式标题
  - 微调了公式
  - 会产生歧义的地方添加了逗号或分号
  - 调整了部分公式顺序
- V4
  - 删除了页眉
  - 微调了公式

## 编写组

	收集&编写	校对
Chapter 1 Preliminaries	计 1 白晓瞳	计 2 冯戴鹏
Chapter 2 Solution of Nonlinear Equations	计 1 白晓瞳	计 2 冯戴鹏
Chapter 3 Solution of Linear Systems	计 4 林正青	计 5 汤禹
Chapter 4 Interpolation and Polynomial Approximation	计 4 梁萍佳	计 5 汤禹
Chapter 5 Curve Fitting	计 1 曾天宇	计 5 施晴
Chapter 6 Numerical Differentiation	计 2 贾丰帆	计 4 刘斯宇
Chapter 7 Numerical Integration	计 6 王程钥	计 4 林楠
Chapter 9 Solution of Differential Equations	计 1 陈泓璇 计 2 符尧	计 4 卢鹏

排版：计 4 梁济凡

**Absolute Error**  $E_p = |p - \hat{p}|$

**Relative Error**  $E_r = \left| \frac{p - \hat{p}}{p} \right|$

**Significant Digits**  $\left| \frac{p - \hat{p}}{p} \right| < \frac{10^{1-d}}{2}$

**Horner's Method**

$$P_n(x) := \sum_{i=0}^n a_i x^i, b_n := a_n, b_k := a_k + c b_{k+1} \Rightarrow b_0 = P(c)$$

**Fixed Point Iteration**  $p_{i+1} = g(p_i)$

**Fixed Point Theorem**

$g \in C^2[a, b], p_0 \in (a, b), g(x) \in [a, b];$   
 $\exists K > 0 \text{ s.t. } |g'(x)| \leq K < 1 \Rightarrow \text{converge to } p;$   
 $|g'(x)| > 1 \Rightarrow \text{not converge to } p$

**Bisection Theorem**  $|r - c_n| \leq \frac{b-a}{2^{n+1}}$

**False Position Method**  $c = b - \frac{f(b)(b-a)}{f(b)-f(a)}$

**Newton-Raphson Theorem**

$p_k = g(p_{k-1}) = p_{k-1} - \frac{f(p_{k-1})}{f'(p_{k-1})};$   
 $f \in C^2[a, b], p \in [a, b], f(p) = 0;$   
 $f'(p) \neq 0 \Rightarrow \exists \delta > 0 \forall p_0 \in [p_0 - \delta, p_0 + \delta] \text{ converge to } p$

**Acceleration of Newton-Raphson Iteration**

$$p_k = p_{k-1} - \frac{M f(p_{k-1})}{f'(p_{k-1})}, M \text{ is the order of root } p$$

$$|E_{k+1}| \approx |E_k|^{1.618} \left| \frac{f''(p)}{2f'(p)} \right|^{0.618}$$

**Back Substitution**

$$x_k = \frac{b_k - \sum_{j=k+1}^N a_{kj} x_j}{a_{kk}}, k = N, N-1, \dots, 1$$

**LU Factorization**

$$\begin{bmatrix} 1 & 2 & 4 \\ 2 & 8 & 6 \\ 3 & 10 & 8 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 3 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 4 \\ 0 & 4 & -2 \\ 0 & 0 & -2 \end{bmatrix}$$

**Jacobi Iteration**

$$x_i^{(k+1)} = \frac{b_i - \sum_{j=1}^{i-1} a_{ij} x_j^{(k)} - \sum_{j=i+1}^n a_{ij} x_j^{(k)}}{a_{ii}}, i = 1, 2, \dots, N$$

**Gauss-Seidel Iteration**

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$$x_i^{(k+1)} = \frac{b_i - \sum_{j=1}^{i-1} a_{ij} x_j^{(k+1)} - \sum_{j=i+1}^n a_{ij} x_j^{(k)}}{a_{ii}}, i = 1, 2, \dots, N$$

**Taylor Series Expansions**

$$\sin x = \sum_{i=1}^{\infty} \frac{(-1)^{i+1} x^{2i-1}}{(2i-1)!}, \cos x = \sum_{i=0}^{\infty} \frac{(-1)^i x^{2i}}{(2i)!},$$

$$\exp x = \sum_{i=0}^{\infty} \frac{x^i}{i!}, \ln(1+x) = \sum_{i=1}^{\infty} \frac{(-1)^{i-1} x^i}{i}$$

**Taylor Polynomial Approximation**

$$f(x) \approx P_N(x) = \sum_{k=0}^N \frac{f^{(k)}(x_0)}{k!} (x - x_0)^k;$$

$$E_N(x) = \frac{f^{(N+1)}(c)}{(N+1)!} (x - x_0)^{N+1}$$

**Lagrange Polynomial**

$$P_N(x) = \sum_{i=0}^N \left( y_i \prod_{j=0, j \neq i}^N \frac{(x - x_j)}{(x_i - x_j)} \right)$$

**Divided Differences**

$$f[x_k, x_{k-1}, \dots, x_j] = \frac{f[x_k, x_{k-1}, \dots, x_{j+1}] - f[x_{k-1}, x_{k-2}, \dots, x_j]}{x_k - x_j}, k > j$$

**Newton Polynomial**

$$P_N(x) = a_0 + \sum_{i=0}^{N-1} (a_{i+1} \prod_{j=0}^i (x - x_j)),$$
$$a_i := f[x_i, x_{i-1}, \dots, x_0]$$

**Lagrange / Newton Polynomial Error Term**

$$E_N(x) = \frac{(\prod_{i=0}^N (x - x_i)) f^{(N+1)}(c)}{(N+1)!}$$

**Least-Squares Line**

$$y = Ax + B$$

$$\begin{cases} (\sum_{k=1}^N x_k^2)A + (\sum_{k=1}^N x_k)B = \sum_{k=1}^N x_k y_k \\ (\sum_{k=1}^N x_k)A + NB = \sum_{k=1}^N y_k \end{cases}$$

$$E(A, B) = \sum_{k=1}^N (Ax_k + B - y_k)^2 = \sum_{k=1}^N d_k^2$$

**Least-Squares Parabola**

$$y = f(x) = Ax^2 + Bx + C$$

$$\begin{cases} (\sum_{k=1}^N x_k^4)A + (\sum_{k=1}^N x_k^3)B + (\sum_{k=1}^N x_k^2)C = \sum_{k=1}^N y_k x_k^2 \\ (\sum_{k=1}^N x_k^3)A + (\sum_{k=1}^N x_k^2)B + (\sum_{k=1}^N x_k)C = \sum_{k=1}^N y_k x_k \\ (\sum_{k=1}^N x_k^2)A + (\sum_{k=1}^N x_k)B + NC = \sum_{k=1}^N y_k \end{cases}$$

**Root-Mean-Square Error**

$$E_2(f) = \sqrt{\frac{1}{N} \sum_{k=1}^N |f(x_k) - y_k|^2}$$

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**Linearization**

$$y = Cx^A \Rightarrow \ln(y) = A \ln(x) + \ln(C)$$

$$\Rightarrow X = \ln(x), Y = \ln(y), C = e^B;$$

$$y = C e^{Ax} \Rightarrow \ln(y) = Ax + \ln(C)$$

$$\Rightarrow X = x, Y = \ln(y), C = e^B$$

**Cubic Spline**

$$S(x) = S_k(x)$$

$$= S_{k,0} + S_{k,1}(x - x_k) + S_{k,2}(x - x_k)^2 + S_{k,3}(x - x_k)^3,$$
$$x \in [x_k, x_{k+1}], k = 0, 1, \dots, N-1$$

$$m_k = S''(x_k), h_k = x_{k+1} - x_k, d_k = \frac{y_{k+1} - y_k}{h_k},$$

$$h_{k-1} m_{k-1} + 2(h_{k-1} + h_k) m_k + h_k m_{k+1} = 6(d_k - d_{k-1})$$
$$\text{for } k = 1, 2, \dots, N-1$$

$$S_{k,0} = y_k, S_{k,1} = d_k - \frac{h_k(2m_k + m_{k+1})}{6},$$

$$S_{k,2} = \frac{m_k}{2}, S_{k,3} = \frac{m_{k+1} - m_k}{6h_k}$$

**Natural Runout**  $m_0 = 0, m_N = 0$

**Parabolic Runout**  $m_0 = m_1, m_N = m_{N-1}$

**Cubic Runout**

$$m_0 = m_1 - \frac{h_0(m_2 - m_1)}{h_1}, m_N = m_{N-1} + \frac{h_{N-1}(m_{N-1} - m_{N-2})}{h_{N-2}}$$

**Central-Difference Formulas**

$$f'(x_i) = \frac{f_1 - f_{-1}}{2h} - \frac{h^2 f^{(3)}(c)}{6};$$

$$f'(x_i) = \frac{-f_2 + 8f_1 - 8f_{-1} + f_{-2}}{12h} + \frac{h^4 f^{(5)}(c)}{30};$$

$$f''(x_i) = \frac{f_1 - 2f_0 + f_{-1}}{h^2} - \frac{h^2 f^{(4)}(c)}{12};$$

$$f''(x_i) = \frac{-f_2 + 16f_1 - 30f_0 + 16f_{-1} - f_{-2}}{12h^2} + O(h^4);$$

$$f^{(3)}(x_i) = \frac{f_2 - 2f_1 + 2f_{-1} - f_{-2}}{2h^3} + O(h^2);$$

$$f^{(3)}(x_i) = \frac{-f_3 + 8f_2 - 13f_1 + 13f_{-1} - 8f_{-2} + f_{-3}}{8h^3} + O(h^4);$$

$$f^{(4)}(x_i) = \frac{f_2 - 4f_1 + 6f_0 - 4f_{-1} + f_{-2}}{h^4} + O(h^2);$$

$$f^{(4)}(x_i) = \frac{-f_3 + 12f_2 - 39f_1 + 56f_0 - 39f_{-1} + 12f_{-2} - f_{-3}}{6h^4} + O(h^4)$$

**Forward-Difference Formulas**

$$f'(x_i) = \frac{f_1 - f_0}{h} - \frac{h}{2} f''(c);$$

$$f'(x_i) = \frac{-3f_0 + 4f_1 - f_2}{2h} + O(h^2);$$

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$$f''(x_i) = \frac{f_0 - 2f_1 + f_2}{h^2} + O(h);$$

$$f''(x_i) = \frac{2f_0 - 5f_1 + 4f_2 - f_3}{h^2} + O(h^2);$$

$$f^{(3)}(x_i) = \frac{-f_0 + 3f_1 - 3f_2 + f_3}{h^3} + O(h);$$

$$f^{(3)}(x_i) = \frac{-5f_0 + 18f_1 - 24f_2 + 14f_3 - 3f_4}{2h^3} + O(h^2);$$

$$f^{(4)}(x_i) = \frac{f_0 - 4f_1 + 6f_2 - 4f_3 + f_4}{h^4} + O(h);$$

$$f^{(4)}(x_i) = \frac{3f_0 - 14f_1 + 26f_2 - 24f_3 + 11f_4 - 2f_5}{h^4} + O(h^2)$$

### Backward-Difference Formulas

$$f'(x_i) = \frac{f_0 - f_{-1}}{h} + \frac{h}{2} f''(c);$$

$$f'(x_i) = \frac{3f_0 - 4f_{-1} + f_{-2}}{2h} + O(h^2);$$

$$f''(x_i) = \frac{f_0 - 2f_{-1} + f_{-2}}{h^2} + O(h);$$

$$f''(x_i) = \frac{2f_0 - 5f_{-1} + 4f_{-2} - f_{-3}}{h^2} + O(h^2);$$

$$f^{(3)}(x_i) = \frac{f_0 - 3f_{-1} + 3f_{-2} - f_{-3}}{h^3} + O(h);$$

$$f^{(3)}(x_i) = \frac{5f_0 - 18f_{-1} + 24f_{-2} - 14f_{-3} + 3f_{-4}}{2h^3} + O(h^2);$$

$$f^{(4)}(x_i) = \frac{f_0 - 4f_{-1} + 6f_{-2} - 4f_{-3} + f_{-4}}{h^4} + O(h);$$

$$f^{(4)}(x_i) = \frac{3f_0 - 14f_{-1} + 26f_{-2} - 24f_{-3} + 11f_{-4} - 2f_{-5}}{h^4} + O(h^2)$$

### Trapezoidal Rule

$$\int_{x_0}^{x_1} f(x) dx = \frac{h}{2} (f_0 + f_1) - \frac{h^3}{12} f^{(2)}(c)$$

### Simpson's 1/3 Rule

$$\int_{x_0}^{x_2} f(x) dx = \frac{h}{3} (f_0 + 4f_1 + f_2) - \frac{h^5}{90} f^{(4)}(c)$$

### Simpson's 3/8 Rule

$$\int_{x_0}^{x_3} f(x) dx = \frac{3h}{8} (f_0 + 3f_1 + 3f_2 + f_3) - \frac{3h^5}{80} f^{(4)}(c)$$

### Boole's Rule

$$\int_{x_0}^{x_4} f(x) dx = \frac{2h}{45} (7f_0 + 32f_1 + 12f_2 + 32f_3 + 7f_4) - \frac{8h^7}{945} f^{(6)}(c)$$

### Newton-Cotes Open Formula

$$\int_a^b f(x) dx = (b-a)f\left(\frac{a+b}{2}\right) + \frac{(b-a)^3}{24} f^{(2)}(c)$$

### Two-point Newton-Cotes Open Formula

$$\int_a^b f(x) dx = \frac{b-a}{2} [f(x_1) + f(x_2)] + \frac{(b-a)^3}{108} f^{(2)}(c)$$

### Three-point Newton-Cotes Open Formula

$$\int_a^b f(x) dx = \frac{b-a}{3} [2f(x_1) - f(x_2) + 2f(x_3)] + \frac{7(b-a)^5}{23040} f^{(4)}(c)$$

### Composite Trapezoidal Rule $h = \frac{b-a}{M}$ ;

$$\int_a^b f(x) dx \approx \sum_{k=1}^M \frac{h}{2} (f(x_{k-1}) + f(x_k))$$

$$= \frac{h}{2} (f_0 + 2f_1 + 2f_2 + \dots + 2f_{M-2} + 2f_{M-1} + f_2 M);$$

$$E_T(f, h) = \frac{-(b-a)f^{(2)}(c)h^2}{12}$$

### Composite Simpson's 1/3 Rule $h = \frac{b-a}{2M}$ ;

$$\int_a^b f(x) dx \approx \sum_{k=1}^M \frac{h}{3} (f(x_{2k-2}) + 4f(x_{2k-1}) + f(x_{2k}))$$

$$= \frac{h}{3} (f_0 + 4f_1 + 2f_2 + \dots + 2f_{2M-2} + 4f_{2M-1} + f_2 M);$$

$$E_S(f, h) = \frac{-(b-a)f^{(4)}(c)h^4}{180}$$

### Romberg Integration

$$h = \frac{b-a}{2^J}, K = 0, 1, 2, \dots, J \geq K$$

$$R(J, 0) = T(J) \text{ (Trapezoidal Rule)}$$

$$R(J, 1) = S(J) \text{ (Simpson's 1/3 Rule)}$$

$$R(J, 2) = B(J) \text{ (Boole's Rule)}$$

$$R(J, K) = \frac{4^K R(J, K-1) - R(J-1, K-1)}{4^K - 1}$$

### Precision of Romberg Integration

$$\int_a^b f(x) dx = R(J, K) + c_1 h^{2K+2} + c_2 h^{2K+4} + \dots$$

$$= R(J, K) + b_K h^{2K+2} f^{(2K+2)}(c_{J,K}), c_{J,K} \in [a, b]$$

$$= R(J, K) + O(h^{2K+2})$$

### Euler's Method

$$y_{i+1} = y_i + hf(t_i, y_i), E_a = \frac{f'(t_i, y_i)}{2!} h^2 = O(h^2)$$

### Heun's Method

$$y_{i+1}^0 = y_i + f(t_i, y_i)h, y_{i+1} = y_i + \frac{f(t_i, y_i) + f(t_{i+1}, y_{i+1}^0)}{2} h$$

### RK2

$$k_1 = f(t_i, y_i), k_2 = f(t_i + p_1 h, y_i + q_{11} k_1 h),$$

$$y_{i+1} = y_i + (a_1 k_1 + a_2 k_2)h,$$

$$a_1 + a_2 = 1, a_2 p_1 = \frac{1}{2}, a_2 q_{11} = \frac{1}{2}$$

$$\text{Mid-Point } a_1 = 0, p_1 = \frac{1}{2}, q_{11} = \frac{1}{2}$$

$$\text{Ralston's Method } a_2 = \frac{2}{3}, p_1 = q_{11} = \frac{3}{4}$$

### Classical RK3

$$k_1 = f(t_i, y_i), k_2 = f\left(t_i + \frac{h}{2}, y_i + \frac{k_1 h}{2}\right),$$

$$k_3 = f(t_i + h, y_i - k_1 h + 2k_2 h),$$

$$y_{i+1} = y_i + \frac{1}{6} (k_1 + 4k_2 + k_3)h$$

### 3rd-Order Heun

$$k_1 = f(t_i, y_i), k_2 = f\left(t_i + \frac{1}{3}h, y_i + \frac{1}{3}k_1 h\right),$$

$$k_3 = f\left(t_i + \frac{2}{3}h, y_i + \frac{2}{3}k_2 h\right), y_{i+1} = y_i + \frac{1}{4} (k_1 + 3k_3)h$$

### Classical RK4

$$k_1 = f(t_i, y_i), k_2 = f\left(t_i + \frac{1}{2}h, y_i + \frac{1}{2}k_1 h\right),$$

$$k_3 = f\left(t_i + \frac{1}{2}h, y_i + \frac{1}{2}k_2 h\right),$$

$$k_4 = f(t_i + h, y_i + k_3 h),$$

$$y_{i+1} = y_i + \frac{1}{6} (k_1 + 2k_2 + 2k_3 + k_4)h$$

### Two ODE-IVPs

$$y_{1,i+1} = y_{1,i} + hf_1(t_i, y_{1,i}, y_{2,i}),$$

$$y_{2,i+1} = y_{2,i} + hf_2(t_i, y_{1,i}, y_{2,i})$$

### Linear Shooting Method

$$x'' = p(t)x'(t) + q(t)x(t) + r(t), x(a) = \alpha, x(b) = \beta;$$

$$u'' = p(t)u'(t) + q(t)u(t) + r(t), u(a) = \alpha, u'(a) = 0;$$

$$v'' = p(t)v'(t) + q(t)v(t), v(a) = 0, v'(a) = 1;$$

$$x(t) = u(t) + \frac{\beta - u(b)}{v(b)} v(t)$$

### Finite-Difference Method

$$\left(-\frac{h}{2}p_j - 1\right)x_{j-1} + (2 + h^2 q_j)x_j + \left(\frac{h}{2}p_j - 1\right)x_{j+1} = -h^2 r_j$$

$$\text{for } j = 1, 2, \dots, N-1 \text{ where } x_0 = \alpha, x_N = \beta$$