T03 Planning and Uncertainty

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November 27, 2019

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1 Q1
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(a) Volume (p_i) = 5 \wedge Volume (p_r) = 2 \wedge Contains (p_i, s_i, s_i) \wedge Contains (p_i, s_i, s_i) \wedge Contains (p_i, w_i, s_i) \wedge W>O \longrightarrow Contains (p_i, w_i, s_i) \wedge W>O \wedge Contains (p_i, w_i, s_i) \wedge W<sub>1</sub> > O \wedge Contains (p_i, w_i, s_i) \wedge W<sub>2</sub> \wedge Volume (p_i) \wedge Contains (p_i, w_i - w_{min}, do(tansfer(p_i, p_i), s_i)) \wedge Contains (p_i, w_i + w_{min}, do(tansfer(p_i, p_i), s_i)) \wedge Contains (p_i, w_i + w_{min}, do(tansfer(p_i, p_i), s_i)) \wedge Contains (p_i, w_i + w_{min}, do(tansfer(p_i, p_i), s_i)) \wedge Contains (p_i, w_i + w_{min}, do(tansfer(p_i, p_i), s_i)) \wedge Contains (p_i, q_i, q_i) \wedge Contai
```

2 Q2

```
(a) move (x, y, z)
      Pre: { clear(x), clear(z), on(x,y)}
      Add: { clearly), on(x, z)}
      Dels: {clear(z), on(x,y)}
      move From Table (x, y)
      Pre: { clear(x), clear(y), onTable(x)}
      Add: fonlx, y)}
                                               initial KB = { clear(a),
      Dels: { clearly), on Table (x)}
                                                             on(a,b),
                                                             onlb,c),
      move To Table (x, y)
                                                             onTable (c) }
      Pre: {clear(x),on(x,y)}
                                                 goal = clear(a) ~ clear(c)
      Add: { clearly), on Table (x) }
                                                       1 Onla, b) 1 on Table(b)
                                                      nonTable(c)
     Pels: {on(x,y)}
```

```
(b)
                                 S.
                                               Α,
                                                                S_{\nu}
  clearla) move(a,b,a)
                             clearla)
                                          move(a,a,a)
                                                              clearla)
            move To Table (a, b) clear (b)
                                         move (a,a,b)
  on(a,b)
                                                              clearlb)
                                          move (a,b,b)
                              on(a,b)
  on (b, c)
                                                              clear(c)
                                          move (b, c, a)
                              on (b,c)
  onTable(c)
                                                              on(a,a)
                                         move (b, c, b)
                              on (a,a)
                                                              onlab)
                                          move From Table (a,a)
                              onTable(a)
                                                              onlb,a)
                                          muve From Table (a,b)
                              onTable (c) mareToTable (a,a)
                                                              υn(b,b)
                                                             on(b,c)
                                         moveToTable(b,c)
                                                              onTable(a)
                                                             unTable(b)
                                                             on Table (c)
   Count Actions (G, S2):
   G={clearla), clearle), onla,b), onTable(b), onTable(c)}
   Gp={clearla), onla, b), onTable(c)}
   Cw={clear(c), onTable(b)}
   A = {moveToTable(b,c)}
   Pre(A) = \{ clear(b), on(b,c) \}
   G. = Cp U Pre(A) = { clearla), clearlb), onla,b), onlb,c), onTable(c)}
   Count Actions ( G., S.):
   C.= { clearla), clearlb), onla, b), onlb,c), onTable(c)}
   Gp = { clear(a), on(a,b), on(b,c), on Table (c)}
   Con= { clear (b) }
   A = {move To Table (a, b)}
   Count Actions ( a., So): return 0
: heuristic value = CountActims (G, S2) = 2
```

(b) of and e are independent given c

(c) P(AB, c, 7d, e) = P(A).P(B|A).P(clA).P(7d|B,c).P(elc)

 $P(a,b,c,7d,e) = 0.2 \times 0.8 \times 0.2 \times 0.3 \times 0.2 \times 0.6 = 0.00512$ $P(a,b,7c,7d,e) = 0.2 \times 0.8 \times 0.2 \times 0.6 = 0.01536$ $P(a,7b,c,7d,e) = 0.2 \times 0.2 \times 0.2 \times 0.3 \times 0.8 = 0.00128$ $P(a,7b,7c,7d,e) = 0.2 \times 0.2 \times 0.8 \times 0.95 \times 0.6 = 0.01824$ $P(7a,b,c,7d,e) = 0.8 \times 0.2 \times 0.95 \times 0.2 \times 0.8 = 0.00128$ $P(7a,b,c,7d,e) = 0.8 \times 0.2 \times 0.95 \times 0.2 \times 0.6 = 0.00128$ $P(7a,b,7c,7d,e) = 0.8 \times 0.8 \times 0.95 \times 0.2 \times 0.6 = 0.001824$ $P(7a,7b,c,7d,e) = 0.8 \times 0.8 \times 0.05 \times 0.2 \times 0.8 = 0.001824$ $P(7a,7b,7c,7d,e) = 0.8 \times 0.8 \times 0.05 \times 0.2 \times 0.8 = 0.00512$ $P(7a,7b,7c,7d,e) = 0.8 \times 0.8 \times 0.95 \times 0.95 \times 0.95 \times 0.8 = 0.34656$

P(7d,e) = \(\Sigma_{abc}\)P(A,B,C,7d,e) = 0.4112

P(A,B,C/7d,e):

(1)10,011,01,07						
ABC	l P_					
abc	0.01245136					
a b 76	0.03735409					
a ob c	0.00311284					
a 7b 7c	0.04435798					
та в с	0.00311284					
7a b 7c	0.04435798					
7a ob c	0.01245136					
7a 7b 7C	0.84280156					

(d) p(a,7d,e) = \(\Sigma_{bc}\) p(a,B,C,7d,e)
= 0.04

P(a|7d,e) = \(\frac{p(a,7d,e)}{p(2,7d,e)} = 0.09727626

图子p(a|7d,e) < p(a) = 0.2

· 患 concer 的可能性不降了.

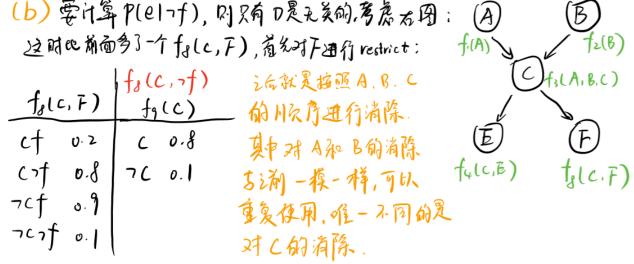
4 Q4

(a) 变量 D和F 是 孔 美的, 所以只需考虑右图; 消除顺序: A, B, C

f, (A)	filB)	+3(A,B,C)	f41C, E)
a 0.9	b 0.2	abc o.1	ce 0.7
7a 0.1	7b 0.8	ab70 0.9	L7e 0.3
	(a7bc 0.8	7CE 0.2
		arb76 0.2	7676 0.8
		Tabe 0.7	
		7ab7c 0.3	
		7a7bc 0.4	
		7a-b-c 0.6	

(B)
) 13(A,B.C)
) f ₄ (c,E)

清除A	海際B	消除C
E af;(A,B,c)f;(A)	SBfs(B,C)f(B)	Sct+(CiE)to(c)
f;(B,C)	fb(C)	to(E)
bc 0.16 b7C 0.84 7bC 0.7b 7b7C 0.24	C 0.64 7C 0.36	e 0.52 7e 0.48



$$\int_{0.3836+0.1824}^{0.3836} = 0.67773852$$