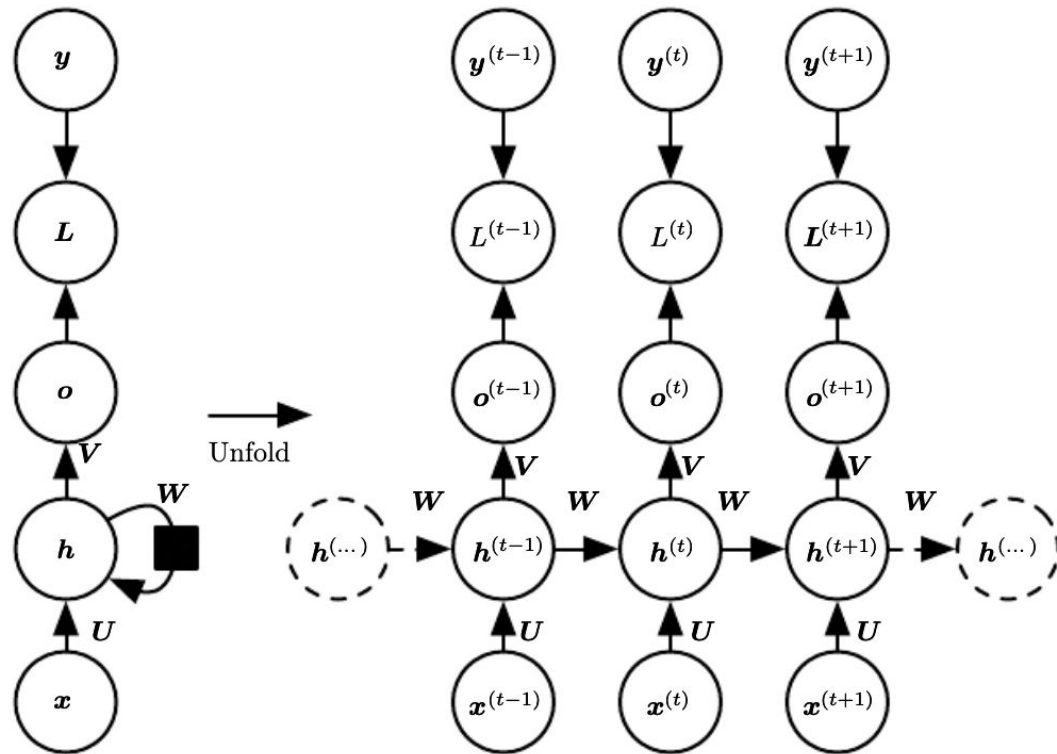


Advanced Machine Learning

Likhith Nayak

Sequence modelling



Backpropagation through time (BPTT)

$$\begin{cases} h_t = Ux_t + Wh_{t-1} \\ o_t = Vh_t \end{cases}$$

where :

h_t : is the hidden state

o_t : is the output at time step t

x_t : is the input at time step t

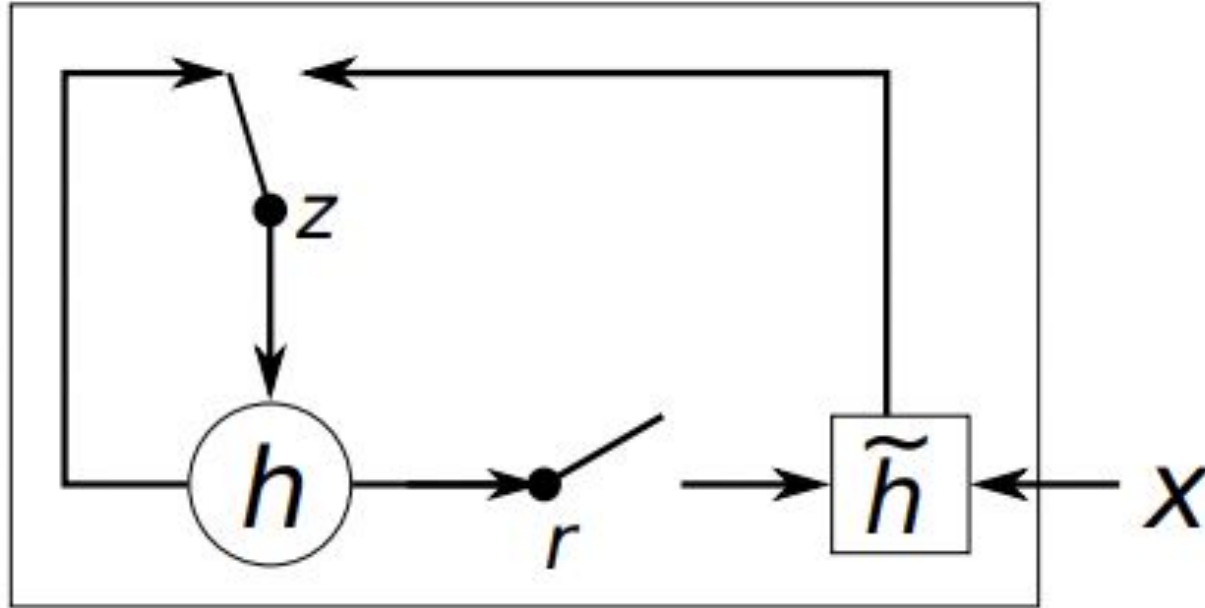
Backpropagation through time (BPTT)

$$\frac{\partial L}{\partial V} = \sum_{t=1}^T \frac{\partial l}{\partial o_t} \cdot h_t^\top$$

$$\frac{\partial L}{\partial W} = \sum_t^T \sum_{k=1}^{t+1} \frac{\partial L_{t+1}}{\partial o_{t+1}} \cdot \frac{\partial o_{t+1}}{\partial h_{t+1}} \cdot \frac{\partial h_{t+1}}{\partial h_k} \cdot \frac{\partial h_k}{\partial W}$$

$$\frac{\partial L}{\partial U} = \sum_t^T \sum_{k=1}^{t+1} \frac{\partial L_{t+1}}{\partial o_{t+1}} \cdot \frac{\partial o_{t+1}}{\partial h_{t+1}} \cdot \frac{\partial h_{t+1}}{\partial h_k} \cdot \frac{\partial h_k}{\partial U}$$

Gated Recurrent Unit (GRU)



Gated Recurrent Unit (GRU)

$$r_j = \sigma \left([\mathbf{W}_r \mathbf{x}]_j + [\mathbf{U}_r \mathbf{h}_{\langle t-1 \rangle}]_j \right)$$

$$z_j = \sigma \left([\mathbf{W}_z \mathbf{x}]_j + [\mathbf{U}_z \mathbf{h}_{\langle t-1 \rangle}]_j \right)$$

$$h_j^{\langle t \rangle} = z_j h_j^{\langle t-1 \rangle} + (1 - z_j) \tilde{h}_j^{\langle t \rangle}$$

$$\tilde{h}_j^{\langle t \rangle} = \phi \left([\mathbf{W} \mathbf{x}]_j + [\mathbf{U} (\mathbf{r} \odot \mathbf{h}_{\langle t-1 \rangle})]_j \right)$$