

# An MPI-based 3D FFT Implementation on CPU+GPU Heterogeneous Clusters

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## **Abstract**

FFT(Fast Fourier Transform) is a fast algorithm to compute DFT, and it is also an important algorithm of data processing in SKA project. In the poster, the Auto-tuning FFT Framework on GPU and the FFT parallel library based on MPI are both introduced, and different FFT algorithms are evaluated on different platforms including TianHe-2.

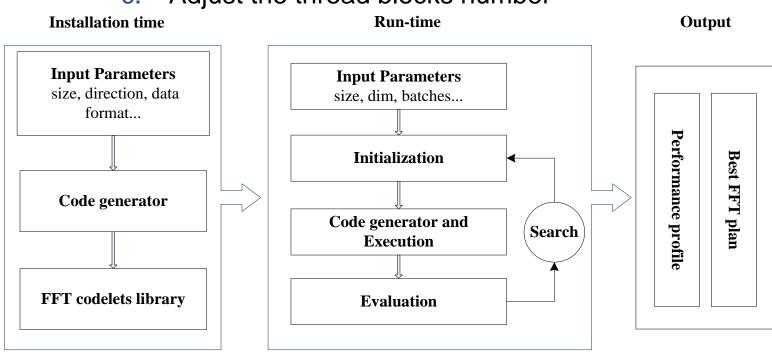
# 1. Introduction

FFT is one of the key algorithm in SDP image processing. CPU+GPU heterogeneous clusters (such as Tianhe-IA and Dawning Nebulae) is a promising hardware platform for SKA project. So in our work, we prototyped an auto-tuning FFT Framework on GPU, and based on that, the parallel 3D FFT algorithm on CPU+GPU clusters through 2D grid decomposition are introduced. We will first introduce 1D decomposition and its deficiencies, and then focus on 2D decomposition and our implementation results.

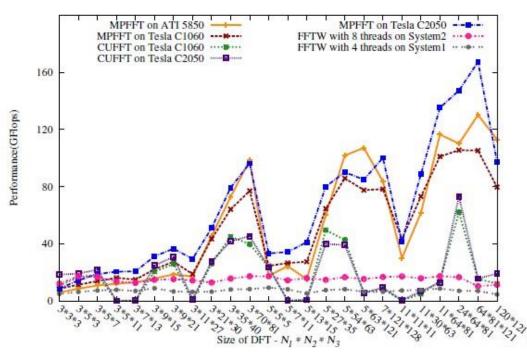
# 2. Auto-tuning FFT Framework on GPU

Currently, the general GPU FFT library is mostly NVIDIA CUFFT, and it couldn't be portable on different platforms. The optimization work for Auto-tuning of Fast Fourier Transform based on CUDA is mainly on the following points:

- (1) Support the run-time optimization partly by cutting the thread blocks of heuristic search strategy.
- (2) Combining with the characteristics of the GPU storage level to highly optimize one-dimensional small-scale FFT, the YZ dimensions of 3D are treated as one dimension to optimize respectively, and the main optimization work is focus on solving the access conflicts on shared memory of GPU. The Auto-tuning strategies are as follows:
  - a. Choose different decomposition bases and sequence
  - b. Memory-access optimizations
  - c. Adjust the thread blocks number



#### (a) Auto-tuning FFT Framework



(b) The comparison result on different platforms

# 3. The FFT parallel library based on MPI

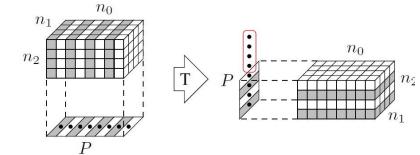
The research of 3D FFT on clusters is mainly based on 1D and 2D decomposition. We assume that the input size is  $n_0 \times n_1 \times n_2$  ( $n_0 \ge n_1 \ge n_2$ ), and the computing sequence will be  $n_2$ ,  $n_1$ ,  $n_0$ .

#### (1) 1D decomposition

- a. Strategy
  - Along  $n_0$  dimension, divide data into  $P(P \le n)$  processes.
  - Secondly, P processes computes 2D FFT (size=  $n_1 \times n_2$  ) of  $n_0/p$  batches parallelly.
  - Because the data needed for the  $n_0$  dimension are distributed in all processes, We need to do a full exchange of data on all processes to complete the computation of  $n_0$  dimension.

#### b. bottleneck

• The scale of parallel computing is limited to  $n_1$  or  $n_2$ .

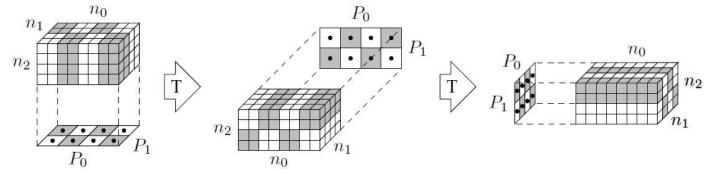


(c) 1D decomposition

#### (2) 2D decomposition

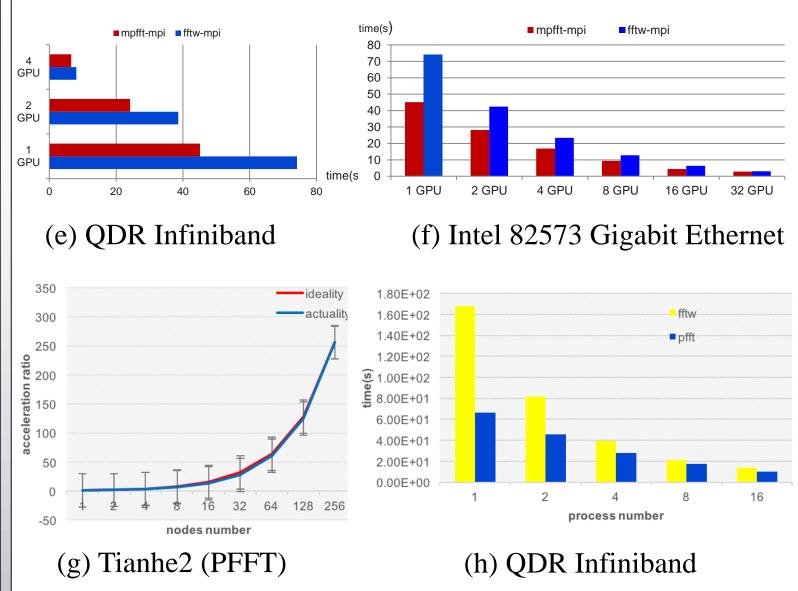
#### a. Strategy

As Figure (d) shows, the decomposition is firstly along n<sub>1</sub> and n<sub>0</sub> to compute the data along n<sub>2</sub> parallelly. Then the decomposition is along n<sub>0</sub> and n2 to compute n<sub>1</sub>. Finally the compute will be along n<sub>0</sub>.



(d) 2D decomposition

The parallel algorithm is evaluated in different environments, including TianHe-2. The comparison results are as follows:



#### 4. Conclusions and Future Work

The FFT parallel algorithms have been successfully evaluated in different platforms compared with FFTW. In the future, we will continue to enhance the scalability of FFT parallel algorithms to satisfy the higher requirement for data processing.

## 5. Reference

- [1] Li Y, Zhang Y, Jia H, etal. Automatic FFT Performance Tuning on OpenCL GPUs.
- [2] Li Y, Zhang Y. Auto-tuning FFT Optimization Framework on GPU and Virtualization Technology Research.

