

Lila Smith

Email

lsmith2@olin.edu

Portfolio

lila.engineer

Hardware

Altium
KiCAD
SystemVerilog
LTSpice
SolidWorks
Fusion 360 CAM
Onshape

Software

Python
MATLAB
Git
C++
ROS

Machining

CNC
3D-printing
Pick-and-place
Laser cutting
Band saw

Education

Olin College of Engineering — Needham, MA

B.S. in Electrical and Computer Engineering (GPA: 3.92)

Awards: Olin Half-Tuition Merit Scholarship

Relevant Courses: Microelectronic Circuits; Computer Architecture; Analog and Digital Communications; Signals and Systems; Principles of Integrated Engineering

May 2024

Technical Experience

Shaper Tools

Electrical Engineering Intern

- Designed and tested PCBs for factory line calibration and quality assurance
- Developed embedded MicroPython for PCBs to interface with factory software and sensors
- Troubleshooting using root cause analysis for both hardware and software bugs
- Developed embedded C++ for lifetime cycle testing rig

Summer
2022

Olin Baja SAE Team

Electrical Lead

- Designed microcontroller PCBs for Hall effect and ride height sensors communicating via CAN Bus
- Developed embedded C++ code to record Hall effect sensor and ride height sensor input for data collection
- Redesigned file system with standardized components and version control using Git for Electrical Subteam

Sept 2020 to
present

Oshkosh Corporation: Global Product Development

Electrification Engineering Intern

- Developed CAN J1939 architecture and DBC files for battery-electric prototype vehicle
- Automated datalogger downloads, reducing work time needed to receive CSVs by 75%
- Standardized wiring for charging inlets on plug-in vehicles
- Communicated with suppliers to evaluate team's potential purchases and receive technical help

Summer
2021

Academic Projects

Ferrofluid Display: Designed, assembled, and tested electro-magnet array controller PCB in under four weeks.

Low-Level Reinforcement Learning (RL): Implemented RL snake game in Python using only pandas, pygame, and numpy.

Line-Following Robot: Wrote embedded C++ for PID control of DC-motor robot with phototransistors to follow curved tape track.